```
1 function[PC, diameters] = reposition(Points, nslices)
 2 %Repositioning algorithm for capillary bridges: Places the Origin [0 0 0]
 3 %in the center of the CB (z being the axis of rotational "symmetry" and z=0
 4 %being where the diameter of the CB is smallest, which is called the neck.
  5 %This proved difficult because rotational symmetry is not perfect, circular
 6 %circumference is not perfect and often times the CB is tilted in respect
 7 %to z. The origin is generally placed too high, the neck is almost always
 8 % at z < -100. However, in the figures made from the "perfect" Surface
 9 %Evolver these mistakes did not occur, the center was always at the neck...
10 %The result of "reposition" is the Pointcloud (nx3 matrix containing x y z
11 %coordinates) and diameters, which is a nx4 matrix with center coordinates
12 % of the circular sections and the radius value in the 4th column
14 %This step is dependent on the previous steps in Amira, Matlab and during
15 %LSFM Imaging. The data is turned such that z is the rotational axis of the
16 %Capillary Bridge.
17 \times 0 = Points(:,1);
18 y0 = Points(:,3);
19 z0 = -Points(:,2);
20
21 %The Pointcloud is translated so that all values are positive.
22 PC unsorted = [x0-min(x0), y0-min(y0), z0-min(z0)];
23 %1:n column added to keep original order of the Points.
24 PC unsorted = [PC unsorted, (1:size(PC unsorted, 1)).'];
25
26 %Sorting after z value
27 PC_sorted = sortrows(PC unsorted,3);
28 %Storing the "sorted" 1:n column. When sorting after this later, the
29 %original Point order is mainained.
30 fourth column = PC sorted(:,4);
31 %PC sorted remains, it contains x y z Points sorted in z value.
32 PC sorted = PC sorted(:,1:3);
34 %Loop to get the diameters dataset, which slices the Pointcloud in nslices
35 % of equal height and calculates the crossection of each slice and their
36 % center and stores it
37
38 % Define the top and bottom of the point cloud
39 PCtop = max(PC sorted(:,3));
40 PCbot = min(PC sorted(:,3));
41
42 %Make a matrix (nslices+1)x1 with values of equal distance between the top
43 %and bottom z-value
44 Slicematrix = linspace(PCbot, PCtop, nslices+1);
45
46 % Initialize diameters matrix
47 diameters = zeros(nslices, 4);
49 % Loop over each slice with Iterator h
50 \text{ for } h = 1:nslices
51
      %For each slice, define the max and min z value with the Slicematrix
      lowerheight = Slicematrix(h);
52
53
      upperheight = Slicematrix(h+1);
      %Find all Points that lie in this z region and store their indices
       sliceindices = PC sorted(:,3) >= lowerheight & PC sorted(:,3) <= \(\mu\)
upperheight;
 56
 57
      % Get all Points' coordinates at this z-level
```

```
58
        cross section = PC sorted(sliceindices, :);
 59
 60
        if isempty(cross section)
 61
            % Skip if no points in this slice
 62
            continue;
 63
 64
 65
        %With differences, all distances in each dimension between all points in
        %the crosssection are calculated. So all delta x delta y and delta z
 66
        %values. Then, in distances, the euclidian sum is calculated to get the
 67
 68
        %Point distances
 69
        differences = permute(cross_section, [1 3 2]) - cross_section;
        distances = sqrt(sum(differences(:, :, 1:2).^2, 3)); % 2D distances
 70
 71
 72
       % Find the maximum distance. This is the "diameter" of this
 73
       % crosssection.
 74
       max distance = max(distances(:));
 75
 76
        % Store the diameter and center coordinates (which are the center of
 77
        % mass of all crosssection points)
 78
        diameters(h, 1) = max distance;
 79
        diameters(h, 2:4) = mean(cross section, 1);
 80 end
 81
 82 %In the next step, the crosssection with the smallest diameter is found.
 83 %First, a lower and upper index from the diameters matrix are defined. This
 84 %is needed because the CB often has the lowest diameter value at the top or
 85 %bottom, where the sample ends because of the acupuncture needle being
 86 %(obviously) thinner than the neck of the sample. By only looking at the
 87 %50% in the middle, these regions are ignored. If there are 50 slices, the
 88 %first 13 and last 13 slices are ignored.
 89 lowerind = round(0.25*size(diameters,1));
 90 upperind = round(0.75*size(diameters,1));
 91 %The smallest diameter within the defined region lowerind:upperind is
 92 %found.
 93 centerdiam = min(diameters(lowerind:upperind, 1));
 94 %The slice with this diameter is found by identifying the index using
 95 %find()
 96 centerind0 = find(diameters(lowerind:upperind,1) == centerdiam);
 97 %If there are more slices with the same smallest diameter for some reason,
 98 %centerind is defined to be a single number.
 99 centerind = centerind0(1,1);
100 %The center coordinates of the slice with the smallest diameter are stored.
101 center = diameters (centerind, 2:4);
102 disp('center diameter: ');
103 disp(centerdiam);
104
        %Many changes were made in this function specifically, for transparency
105
106
        %i leave it here:
            % topdiams = diameters(centerind:size(diameters,1),:);
107
108
            % botdiams = diameters(1:centerind,:);
            % topind = topdiams(:,1) == max(topdiams(:,1));
109
110
            % botind = botdiams(:,1) == max(botdiams(:,1));
111
            % pneck = usedneckpercentage/100;
112
            % topval = pneck*topdiams(topind,4);
113
114
           % botval = pneck*botdiams(botind,4);
            % neckind = diameters(:,4) >= botval & diameters(:,4) <= topval;</pre>
115
```

```
116
117
            % neck = diameters(neckind,:);
118
            %Finding the center (The coordinates of the center of the smallest {m 	extbf{arepsilon}}
119
diameter)
120
            % center = neck(find(neck(:,1)) == min(neck(:,1))), 2:4);
121
122
            %Translated diameters dataset
            % neck = [neck(:,1) (neck(:,2:4)-center)];
124
125 %The coordinates of the center are subtracted from other coordinates to
126 %reposition them. Now, the center is at [0 0 0]. This is a function output.
127 diameters = [diameters(:,1) (diameters(:,2:4)-center)];
128
129
                %Visualization for testing
130
                % figure;
131
                % plot(neck(:,4),neck(:,1));
132
                % title('diameters along CBridge height, neck region');
133
                응
                     xlabel('z');
134
                용
                     ylabel('diameter');
135
                용
                       ylim ([0 max(neck(:,1))]);
136
                응
137
                % figure;
138
                % plot(diameters(:,4), diameters(:,1));
                % title('diameters along CBridge height');
139
140
                용
                     xlabel('z');
141
                용
                      ylabel('diameter');
142
                응
                      ylim ([0 max(diameters(:,1))]);
143
144 %PC centered is used to store the Rotated and Translated Point Cloud with
145 %original indexing in 4th column, center at the origin now.
146 PC centered = [PC sorted - center, fourth column];
147
148 %Resorting by the fourth column for original order which is needed for
149 %curvature data gives PC_shuffled, and the function output PC are only
150 %coordinates.
151 PC shuffled = sortrows(PC centered, 4);
152 PC = PC shuffled(:,1:3);
153
154
155
```