OBJECT RECOGNITION AND TRACKING BY DEEP LEARNING

Liqiang Ding

Department of Electrical and Computer Engineering
McGill University, Montreal

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A thesis submitted to the Faculty of Graduate Studies and Research
in partial fulfilment of the requirements of the degree of
Master of Engineering

A great dedication goes here.

Abstract

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Resume

ACKNOWLEDGEMENTS

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CHAPTER 1

INTRODUCTION

1.1 Motivation

This is a section in Chapter 2.

1.2 Thesis Overview

This is a section in Chapter 2.

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Table 1.1: This is an example Table.

x	f(x)	g(x)
1	6	4
2	6	3
3	6	2
4	6	2

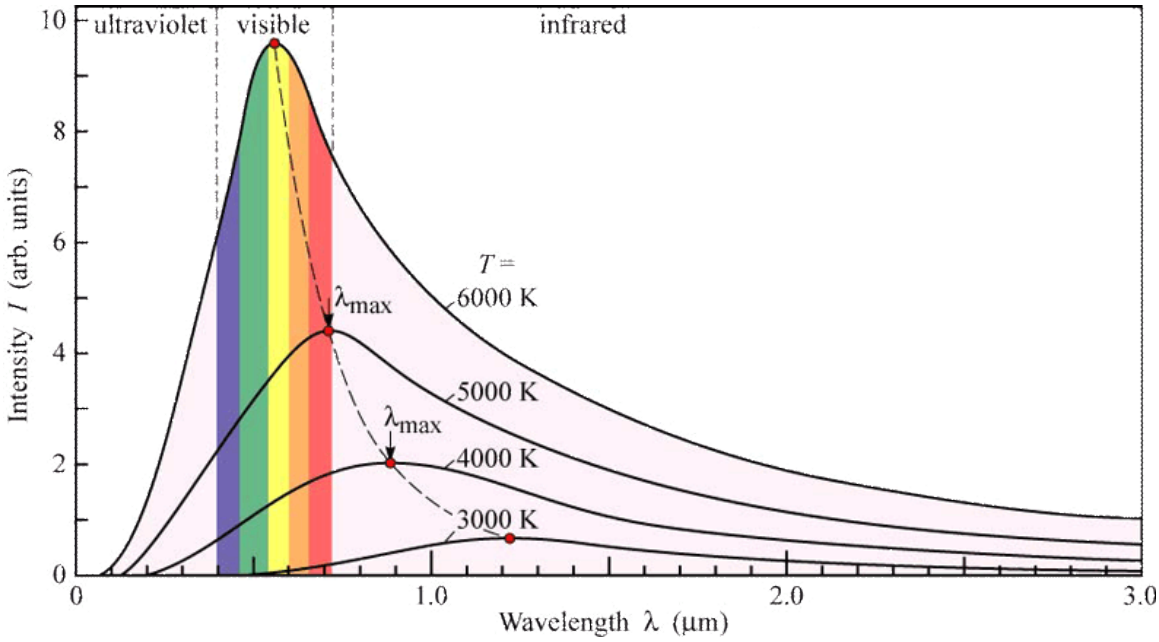

Figure 1.1: This is an example Figure.

CHAPTER 2

PREVIOUS APPROACHES

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2.1 Section

This is a section in Chapter 2.

2.1.1 Example Subsection

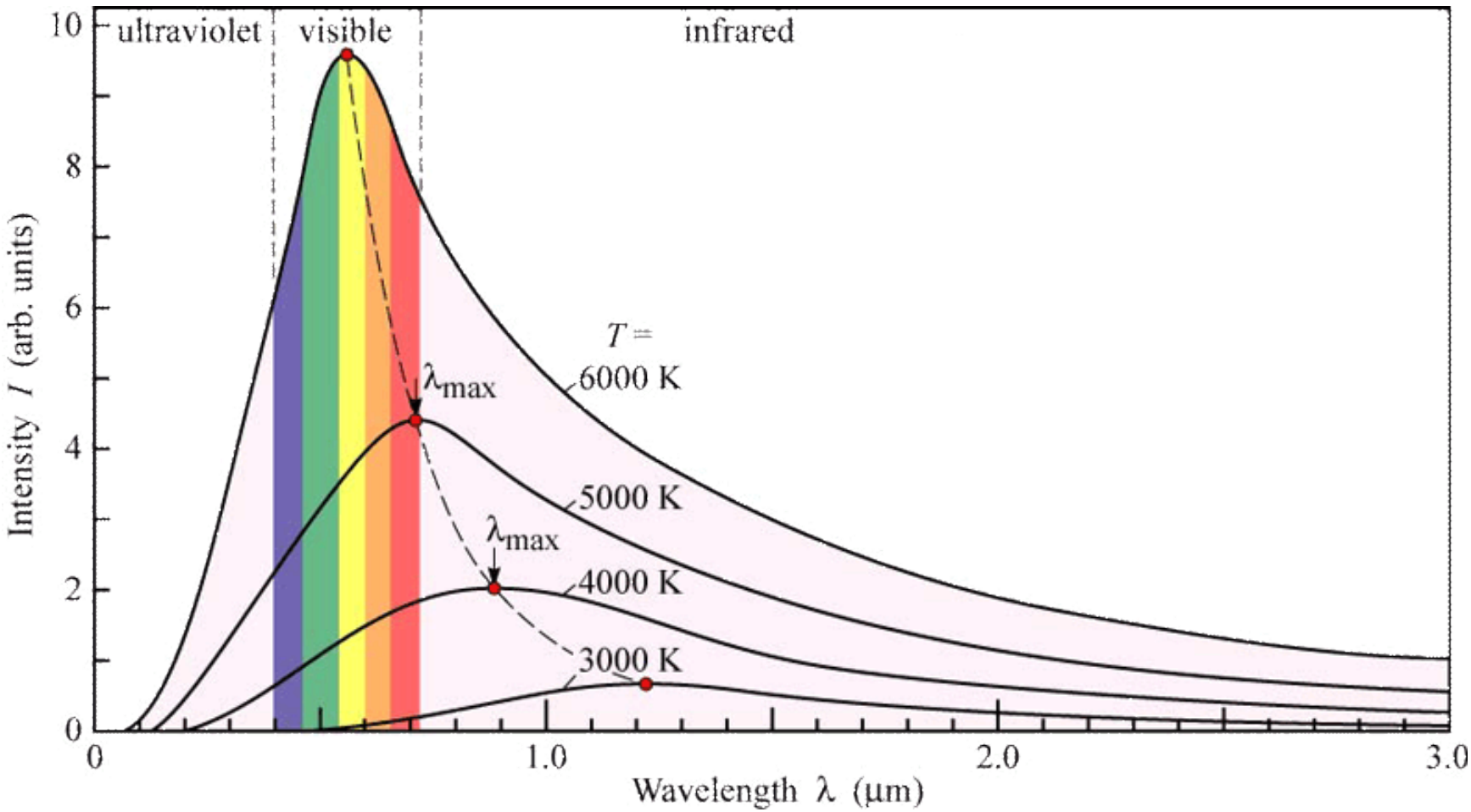

Figure 2.1: This is another example Figure, rotated to landscape orientation.

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MIO-TCD SPID Caltech

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Image clustering

3.2 Neural Network Cascading

Caltech

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4.1.1.1 Lucas Kanade Optical Flow

4.1.1.2 Farnback Optical Flow

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CHAPTER 6

CONCLUSIONS AND FUTURE WORK

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Appendices

APPENDIX A

EXPERIMENTAL EQUIPMENT

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APPENDIX B

DATA PROCESSING

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[1] B. W. Kernighan and D. M. Ritchie, *The C Programming Language Second Edition*. Prentice-Hall, Inc., 1988.

[2] G. P. Burdell, *Myths and Their Origins Plus Some Extra Words to Make the Title Really Long and Extend to the Next Line*. Real Books, Inc., 2017.

[3] A. Einstein, B. Podolsky, and N. Rosen, "Can quantum-mechanical description of physical reality be considered complete?" *Phys. Rev.*, vol. 47, pp. 777–780, 10 1935.

VITA

Vita may be provided by doctoral students only. The length of the vita is preferably one page. It may include the place of birth and should be written in third person. This vita is similar to the author biography found on book jackets.