

Definition of the tuning vector θ

The NMPC configuration is parametrized by the column vector

$$\theta^\top = [f, \theta_p, \theta_m, q, r^{(u)}, r^{(\Delta u)}].$$

The components satisfy:

$$\begin{aligned} f &\in (0, 1), \\ \theta_m &\in \mathbb{Z}_{\geq 0}, \quad 0 \leq \theta_m \leq 30, \\ \theta_p &\in \mathbb{Z}_{\geq 0}, \quad 0 \leq \theta_p \leq 60, \\ q &\in [-3, 3]^3, \\ r^{(u)} &\in [-3, 3]^3, \\ r^{(\Delta u)} &\in [-3, 3]^3. \end{aligned}$$

The weighting matrices are given by

$$Q = \text{diag}(10^q), \quad R_u = \text{diag}(10^{r^{(u)}}), \quad R_{\Delta u} = \text{diag}(10^{r^{(\Delta u)}}).$$

The horizons are

$$\begin{aligned} m &= \theta_m + 1, \\ p &= \theta_p + m. \end{aligned}$$

Surrogate for time

Implementation

```
1      function t_hat = time_model(x, m, p, alfa
2          , beta, a)
3      k = 20;
4      softplus = @(z) log1p(exp(k*z)) / k;
5
6      y = a(1) + a(2)*x;
7      t_base = y + softplus(-y);
8
9      scale = (m/10).^alfa .* (p/30).^beta;
10     t_hat = scale .* t_base;
11     end
```

Mathematical form

Let the scalar input be normalised to the interval $[-1, 1]$ as

$$x = 2f - 1.$$

The shape term is modelled as an affine function of x ,

$$y(x) = a_0 + a_1x.$$

Define the smooth rectifier

$$\text{softplus}_k(z) = \frac{1}{k} \log(1 + e^{kz}), \quad k > 0.$$

The base time surrogate is

$$t_{\text{base}}(x) = y(x) + \text{softplus}_{k=20}(-y(x)),$$

which enforces non-negativity while remaining continuously differentiable.

The full surrogate for the computation time **in hours** is

$$\hat{t}(x, m, p) = \left(\frac{m}{10}\right)^\alpha \left(\frac{p}{30}\right)^\beta t_{\text{base}}(x).$$

Fitting is performed in hours to avoid numerical scaling issues during optimisation.

Fitted parameters

Table 1: Estimated parameters of the surrogate time model.

Category	Parameter	Value
Scaling exponents	α	0.33233435
	β	2.3029582
Affine shape coefficients	a_0	8.843454×10^{-1}
	a_1	1.079230
Softplus parameter	k	20
Fit quality	R^2	0.999417