

## Natural Language Rules

#1: When visibility is not less than 200 meters, cars are allowed to travel at speeds exceeding 30 km/h.

#2: When visibility is less than 200 meters, cars are not allowed to exceed speeds of 30 km/h.

#3: When visibility is less than 200 meters, cars are allowed to travel.

### Basic Events

a: visibility < 200 meters  
b: cars travel  
c: cars' speeds > 30 km/h  
d: visibility < 200 meters  
e: cars travel  
f: cars' speeds > 30 km/h  
g: visibility < 200 meters  
h: cars travel

### Rules

$$\begin{aligned}r_1 &= \neg a \rightarrow (b \wedge c) \\ &= a \vee (b \wedge c) \\ r_2 &= d \rightarrow \neg(e \wedge f) \\ &= \neg d \vee \neg(e \wedge f) \\ r_3 &= g \rightarrow h \\ &= \neg g \vee h\end{aligned}$$

### Similarity Examination

### Basic Events

$$\begin{aligned}e_1 &= a = d = g \\ e_2 &= b = e = h \\ e_3 &= c = f\end{aligned}$$

### Rules

$$\begin{aligned}r_1 &= e_1 \vee (e_2 \wedge e_3) \\ r_2 &= \neg e_1 \vee \neg e_2 \vee \neg e_3 \\ r_3 &= \neg e_1 \vee e_2\end{aligned}$$

### Consistency Verification

$$CNF = \bigwedge_{i=1}^3 r_i = r_1 \wedge r_2 \wedge r_3$$

$$= (e_1 \vee (e_2 \wedge e_3)) \wedge (\neg e_1 \vee \neg e_2 \vee \neg e_3) \wedge (\neg e_1 \vee e_2)$$

When  $e_1$  is false,  $e_2$  and  $e_3$  are true, the  $CNF$  can be satisfied.  
So this rule library is consistent.