

# Домашка 1.

# Домашня Евгавена

1. (0.25 point) Prove that the sum of two functions of bounded first-order variation also has bounded first-order variation.

□ Пусть  $f, g$  определены на отрезке  $[a, b]$  и имеют на нем ограниченную вариацию. Выразим:

$$V_a^b(f) = \sup_{\Pi_{a,b}} \sum_{i=1}^N |f(x_i) - f(x_{i-1})| < \infty \quad \text{и} \quad V_a^b(g) = \dots < \infty \quad (1)$$

однозначное  
с нечетким

Возьмем  $\epsilon$  равномере  $\{x_i\}_{i=0}^N$  отрезка  $[a, b]$  и пусть это:

$$\begin{aligned} \sum_{i=1}^N |(f+g)(x_i) - (f+g)(x_{i-1})| &= \sum_{i=1}^N |f(x_i) - f(x_{i-1}) + g(x_i) - g(x_{i-1})| \leq \\ &\leq \sum_{i=1}^N (|f(x_i) - f(x_{i-1})| + |g(x_i) - g(x_{i-1})|) = \\ &= \sum_{i=1}^N |f(x_i) - f(x_{i-1})| + \sum_{i=1}^N |g(x_i) - g(x_{i-1})| < \infty \quad \text{из (1)} \end{aligned}$$

т.к. это было записано для  $f$  и  $g$  на  $[a, b]$ ,  
также суммируя по всем равномерным, получим:

$$V_a^b(f+g) \leq V_a^b(f) + V_a^b(g) < \infty \quad \text{т.т.д.}$$



2. (0.75 point) Prove that the product of two functions of bounded first-order variation also has bounded first-order variation.

□ Пусть  $f, g$  имеют ограниченную вариацию на отрезке  $[a, b]$ .

Заметим, что функциональное выражение вариации ограничено (на конечном отрезке).

△ Если  $V_a^b(f) < \infty$  то  $\forall$  фикср.  $x_0 \in [a, b], \forall x \in [a, b]$ :

$$|f(x) - f(x_0)| \leq V_{x_0}^x(f) \leq V_a^b(f)$$

$$\Leftrightarrow |f(x)| \leq |f(x_0)| + V_a^b(f) < \infty$$



т.е. для функций  $f, g$   $\exists \text{const } M_f, M_g : |f(x)| \leq M_f, |g(x)| \leq M_g \forall x \in [a, b]$

Возьмем  $\epsilon$  равномере  $\{x_i\}_{i=0}^N$  отрезка  $[a, b]$  и пусть это:

$$\begin{aligned} \Delta(fg)_i &= f(x_i)g(x_i) - f(x_{i-1})g(x_{i-1}) = f(x_i) \cdot (g(x_i) - g(x_{i-1})) + g(x_{i-1})(f(x_i) - f(x_{i-1})) = \\ &= f(x_i) \cdot \Delta g_i + g(x_{i-1}) \Delta f_i \end{aligned}$$

$$|\Delta(fg)| = |f(x_i) \Delta g_i + g(x_{i-1}) \Delta f_i| \leq |f(x_i)| |\Delta g_i| + |g(x_{i-1})| |\Delta f_i| \leq M_f \cdot |\Delta g_i| + Mg \cdot |\Delta f_i|$$

Суммируем по  $i$  и возвращаем  $\sup$  по всем разбиениям:

$$V_a^B(fg) \leq M_f \cdot V_a^B(g) + Mg \cdot V_a^B(f) < \infty$$

$\Rightarrow fg$  имеет ограниченную вариацию

□

3. (1 point) Is it true that the quadratic variation of function

$$f(x) = \begin{cases} x \sin(\frac{1}{x}), & x \in (0, 1], \\ 0, & x = 0. \end{cases}$$

is bounded?

$$V_{0,1}^2(f) = \sup_{\Pi_{a,b}} \sum_{i=0}^n |f(x_{i+1}) - f(x_i)|^2 < \infty$$

$$f'(x) = \sin \frac{1}{x} - x \cdot \cos \frac{1}{x} \cdot \frac{1}{x^2} = \sin \frac{1}{x} - \frac{1}{x} \cos \frac{1}{x} \quad (x \in (0, 1])$$

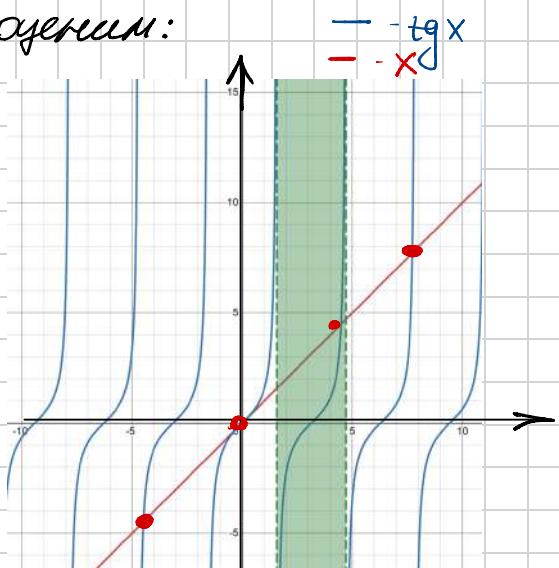
$f'(x) = 0 \Rightarrow \sin \frac{1}{x} - \frac{1}{x} \cos \frac{1}{x} = 0 \Leftrightarrow \tan \frac{1}{x} = \frac{1}{x}$ . Наиболее  $\{x_k\}_{k \in \mathbb{N}}$ -рекуррентное уравнение  $\tan \frac{1}{x} = \frac{1}{x}$  (т.е. экстремумы нашей функции)

Подбираем соответствующие  $x_k$  из  $\Pi_{a,b}$

Т.к. наименшую наклонность не имеют, берём:

$$\text{т.к. } \forall k \in \mathbb{N} \exists! x_k : x_k \in \left( \frac{1}{2\pi + \pi k}; \frac{1}{-\pi + \pi k} \right),$$

этот факт  
запись в  
 $\pi$ -форме.  $\tan x = x$   
имеет  
одинаковую  
наклонность



$$\text{но } \sum_{k \in \mathbb{N}} |x_{k+1} \sin(\frac{1}{x_{k+1}}) - x_k \sin(\frac{1}{x_k})|^2 \leq$$

$$\leq \sum_{k \in \mathbb{N}} |x_{k+1} + x_k|^2 \quad \text{④}$$

$$x_{k+1} + x_k \leq \frac{1}{-\frac{\pi}{2} + \pi(k+1)} + \frac{1}{-\frac{\pi}{2} + \pi k} = \frac{1}{\pi} \left( \frac{1}{k+\frac{1}{2}} + \frac{1}{k-\frac{1}{2}} \right) = \frac{1}{\pi} \frac{2k}{k^2 - \frac{1}{4}} \leq \frac{1}{\pi} \cdot \frac{2}{k}$$

$$\therefore \frac{2k}{k^2 - \frac{1}{4}} \leq \frac{4}{k} ? \text{ Проверка: } \frac{k}{k^2 - \frac{1}{4}} \leq \frac{2}{k} \Leftrightarrow k \geq 1 \quad k^2 \leq 2k^2 - \frac{1}{2} \quad \checkmark$$

$$\left( \sum_{k \in \mathbb{N}} \frac{1}{\pi^2} \cdot \frac{2^2}{k^2} \right) = \frac{4}{\pi^2} \sum_{k \in \mathbb{N}} \frac{1}{k^2} < \infty \quad \text{т.е. } f(x) \text{ имеет конечную квадратную вариацию.} \quad \square$$

4. (2 points) Verify that the explicit call option price formula

$$C_t = S_t N(d_1) - K e^{-r(T-t)} N(d_2),$$

$$d_1 = \frac{\ln \frac{S_t}{K} + (r + \frac{\sigma^2}{2})(T-t)}{\sigma \sqrt{T-t}}, \quad d_2 = d_1 - \sigma \sqrt{T-t}$$

satisfies the Black-Scholes-Merton equation

$$\frac{\partial C}{\partial t} + \frac{1}{2} \sigma^2 S^2 \frac{\partial^2 C}{\partial S^2} + rS \frac{\partial C}{\partial S} - rC = 0.$$

□ 1) Наидені рахунки підтверджують правильність формул:

$$\frac{\partial C}{\partial S} = N(d_1) + S n(d_1) \frac{\partial d_1}{\partial S} - K e^{-r(T-t)} n(d_2) \cdot \frac{\partial d_2}{\partial S}$$

$$\frac{\partial d_1}{\partial S} = \frac{1}{S \sigma \sqrt{T-t}} ; \quad \frac{\partial d_2}{\partial S} = \frac{\partial d_1}{\partial S} = \frac{1}{S \sigma \sqrt{T-t}}$$

$$\Rightarrow \frac{\partial C}{\partial S} = N(d_1) + S n(d_1) \cdot \frac{1}{S \sigma \sqrt{T-t}} - K e^{-r(T-t)} n(d_2) \cdot \frac{1}{S \sigma \sqrt{T-t}} \quad (=)$$

$$\left. \begin{aligned} n(d_1) &= \frac{1}{\sqrt{2\pi}} e^{-\frac{d_1^2}{2}} = \frac{1}{\sqrt{2\pi}} \exp \left\{ -\frac{1}{2} (d_2 + \sigma \sqrt{T-t})^2 \right\} = \\ &= \frac{1}{\sqrt{2\pi}} \exp \left\{ -\frac{1}{2} d_2^2 - \frac{1}{2} \sigma^2 (T-t) - d_2 \sigma \sqrt{T-t} \right\} = \frac{1}{\sqrt{2\pi}} e^{-\frac{d_2^2}{2}} \exp \left\{ -\frac{1}{2} \sigma^2 (T-t) - \right. \\ &\quad \left. - d_2 \sigma \sqrt{T-t} \right\} = n(d_2) \cdot \exp \left\{ -\frac{1}{2} \sigma^2 (T-t) - \frac{\ln(S/K) + (r - \frac{\sigma^2}{2})(T-t)}{\sigma \sqrt{T-t}} \sigma \sqrt{T-t} \right\} = \\ &= n(d_2) \cdot \exp \left\{ -\frac{1}{2} \sigma^2 (T-t) - \ln(S/K) - (r - \frac{\sigma^2}{2})(T-t) \right\} = \\ &= n(d_2) \cdot \exp \left\{ -\ln(S/K) - r(T-t) \right\} = n(d_2) \cdot \frac{K}{S} \cdot e^{-r(T-t)} \end{aligned} \right\}$$

$$(=) N(d_1) + n(d_2) \frac{K}{S} \cdot e^{-r(T-t)} \frac{1}{\sigma \sqrt{T-t}} - K e^{-r(T-t)} n(d_2) \frac{1}{S \sigma \sqrt{T-t}} = N(d_1)$$

To check  $\frac{\partial C}{\partial S} = N(d_1)$

$$\frac{\partial^2 C}{\partial S^2} = \frac{\partial}{\partial S} N(d_1) = n(d_1) \frac{\partial d_1}{\partial S} = n(d_1) \cdot \frac{1}{S \sigma \sqrt{T-t}}$$

2) Наидені рахунки підтверджують правильність формули для  $t$ :

$$\frac{\partial C}{\partial t} = S n(d_1) \frac{\partial d_1}{\partial t} - r K e^{-r(T-t)} n(d_2) - K e^{-r(T-t)} n(d_2) \frac{\partial d_2}{\partial t} \quad (=)$$

$$\frac{\partial d_1}{\partial t} = \frac{\ln(S/K) + (r + \frac{\sigma^2}{2})(T-t)}{2 \sigma (T-t)^{3/2}} - \frac{r + \frac{\sigma^2}{2}}{\sigma \sqrt{T-t}}$$

$$\frac{\partial d_2}{\partial t} = \frac{\partial d_1}{\partial t} + \frac{6}{2\sqrt{T-t}}$$

$$\Rightarrow S \cdot n(d_2) \underbrace{\frac{K}{S} e^{-r(T-t)} \frac{\partial d_1}{\partial t}}_{-\cancel{r} K e^{-r(T-t)} N(d_2)} - \cancel{r} K e^{-r(T-t)} N(d_2) - \cancel{K e^{-r(T-t)} n(d_2)} \left( \frac{\partial d_1}{\partial t} + \frac{6}{2\sqrt{T-t}} \right) = \\ = -r K e^{-r(T-t)} N(d_2) - K e^{-r(T-t)} n(d_2) \frac{6}{2\sqrt{T-t}}$$

3) nowsmachen & CQY:

$$\frac{\partial C}{\partial t} + \frac{1}{2} \sigma^2 S^2 \frac{\partial^2 C}{\partial S^2} + rS \frac{\partial C}{\partial S} - rC = 0$$

$$\left[ -r K e^{-r(T-t)} N(d_2) - K e^{-r(T-t)} n(d_2) \frac{6}{2\sqrt{T-t}} \right] + \frac{1}{2} \sigma^2 S^2 \cdot n(d_1) \cdot \frac{1}{S \sqrt{T-t}} + \\ + r S N(d_1) - r C = \\ = -r K e^{-r(T-t)} N(d_2) - K e^{-r(T-t)} n(d_2) \frac{6}{2\sqrt{T-t}} + \frac{1}{2} \sigma^2 S^2 n(d_1) \frac{K}{S} \frac{e^{-r(T-t)}}{\sqrt{T-t}} + \\ + r S N(d_1) - r C = \\ = -r K e^{-r(T-t)} N(d_2) + r S N(d_1) - r C = \quad \text{3-е уравнение CQY} \\ = r(S N(d_1) - K e^{-r(T-t)} N(d_2)) - r C = 0 \quad \text{второе!}$$

z.m.d.



## Домашка 2

## Домашка Евгения

1. (1 point) Find the variance of the sample third-order variation

$$\sum_{i=1}^n |W_{t_i} - W_{t_{i-1}}|^3$$

of Brownian motion on  $[0, T]$ .

1) Рассмотрим схему  $0 = t_0 < t_1 < \dots < t_n = T$  с  $\Delta t_i = t_i - t_{i-1}$

т.к.  $W_{t_i} - W_{t_{i-1}} = \sqrt{\Delta t_i} Z_i$ , где  $\Delta t_i = t_i - t_{i-1}$ ,  $Z_i \sim N(0, 1)$

и между  $Z_i$  независимы

$$\Rightarrow |W_{t_i} - W_{t_{i-1}}|^3 = (\Delta t_i)^{3/2} |Z_i|^3$$

$$\begin{aligned} \Rightarrow \mathbb{D}\left(\sum_{i=1}^n |W_{t_i} - W_{t_{i-1}}|^3\right) &= \mathbb{D}\left(\sum_{i=1}^n (\Delta t_i)^{3/2} |Z_i|^3\right) = \sum_{i=1}^n \mathbb{D}\left[(\Delta t_i)^{3/2} |Z_i|^3\right] = \\ &= \sum_{i=1}^n (\Delta t_i)^3 \cdot \mathbb{D}[|Z_i|^3] = \{ \text{где погрешность схемы} \} = n \cdot (\Delta t)^3 \cdot \mathbb{D}[|Z_i|^3] \end{aligned}$$

2) Используя  $\mathbb{D}|Z|^3 = \mathbb{E}|Z|^6 - (\mathbb{E}|Z|^3)^2$ , где  $Z \sim N(0, 1)$

$$\mathbb{D}|Z|^3 = \mathbb{E}|Z|^6 - (\mathbb{E}|Z|^3)^2$$

$$\varphi(x) = \frac{1}{\sqrt{2\pi}} e^{-x^2/2}$$

$$\mathbb{E}|Z|^3 = \int_{-\infty}^{+\infty} |x|^3 \varphi(x) dx = 2 \int_0^{+\infty} \frac{1}{\sqrt{2\pi}} x^3 e^{-x^2/2} dx = \frac{2}{\sqrt{2\pi}} \int_0^{+\infty} x^3 e^{-x^2/2} dx$$

$$\text{Заметка } u = \frac{x^2}{2}. \text{ Тогда } du = x dx \quad \text{и } x^2 = 2u$$

$$\Rightarrow x^3 dx = x^2 \cdot x dx = 2u \cdot du$$

$$I = \int_0^{+\infty} x^3 e^{-x^2/2} dx = \int_0^{+\infty} 2u e^{-u} du = 2 \int_0^{+\infty} u e^{-u} du = 2 \Gamma(2) = 2$$

$$\Rightarrow \mathbb{E}|Z|^3 = \frac{2}{\sqrt{2\pi}} \cdot 2 = \frac{2\sqrt{2}}{\sqrt{\pi}}$$

$$\text{Аналогично, } \mathbb{E}|Z|^6 = \frac{2}{\sqrt{2\pi}} \cdot 2^{5/2} \cdot \frac{15}{8} \sqrt{\pi} = \frac{2}{\sqrt{2\pi}} \cdot 4\sqrt{2} \cdot \frac{15}{8} \sqrt{\pi} = 15$$

$$I = \int_0^{+\infty} x^6 e^{-x^2/2} dx = \int_0^{+\infty} (2u)^{5/2} e^{-u} du = 2^{5/2} \int_0^{+\infty} u^{5/2} e^{-u} du = 2^{5/2} \Gamma\left(\frac{7}{2}\right)$$

$$\Gamma\left(\frac{7}{2}\right) = \frac{5}{2} \cdot \frac{3}{2} \cdot \frac{1}{2} \cdot \Gamma\left(\frac{1}{2}\right) = \frac{15}{8} \sqrt{\pi}$$

3)  $B$  amore,

$$\mathbb{D}|z|^3 = \mathbb{E}|z|^6 - (\mathbb{E}|z|^3)^2 = 15 - \left(\frac{2\sqrt{2}}{\sqrt{\pi}}\right)^2 = 15 - \frac{8}{\pi}$$

$$\begin{aligned}\mathbb{D}\left(\sum_{i=1}^n |W_{t_i} - W_{t_{i-1}}|^3\right) &= \sum_{i=1}^n (\Delta t_i)^3 \cdot \mathbb{D}[|z_i|^3] = \mathbb{D}[|z|^3] \sum_{i=1}^n (\Delta t_i)^3 = \\ &= \left(15 - \frac{8}{\pi}\right) \cdot \sum_{i=1}^n (\Delta t_i)^3\end{aligned}$$

Dne равномерной сетки:  $\mathbb{D}\left(\sum_{i=1}^n |W_{t_i} - W_{t_{i-1}}|^3\right) = \left(15 - \frac{8}{\pi}\right) \cdot \frac{T^3}{h^2}$

Ошибкa:  $\mathbb{D}\left(\sum_{i=1}^n |W_{t_i} - W_{t_{i-1}}|^3\right) = \left(15 - \frac{8}{\pi}\right) \sum_{i=1}^n (\Delta t_i)^3$

две равномерные сетки:  $\mathbb{D}\left(\sum_{i=1}^n |W_{t_i} - W_{t_{i-1}}|^3\right) = \frac{T^3}{h^2} \left(15 - \frac{8}{\pi}\right)$   $\square$

2. (1 point) The Ornstein-Uhlenbeck process is defined by

$$dX_t = -\kappa X_t dt + \sigma dW_t.$$

Find the quadratic variation of  $\sin(X_t)$ .

□ Применим формулу для  $f(x) = \sin(x)$ :

$$d\sin(X_t) = \cos(X_t) dX_t - \frac{1}{2} \sin(X_t) \underbrace{d[X]}_{= \sigma^2 dt}$$

$$d\sin(X_t) = \left(-\kappa X_t \cos(X_t) - \frac{\sigma^2}{2} \sin(X_t)\right) dt + \underbrace{\sigma \cos(X_t)}_{\text{Безуопаска!}} dW_t$$

На конечна обсчудование:

$$d[X]_t = (dX_t)^2 = (\sigma \cos(X_t))^2 dt = \sigma^2 \cos^2(X_t) dt$$

т.е. бывало в монитор.

$$[\sin(X)]_t = \int_0^t \sigma^2 \cos^2(X_s) ds$$

Ошибка:  $[\sin(X)]_t = \int_0^t \sigma^2 \cos^2(X_s) ds$   $\square$

3. (a) (0.5 point) Show that the process defined as

$$(T-t)W_t$$

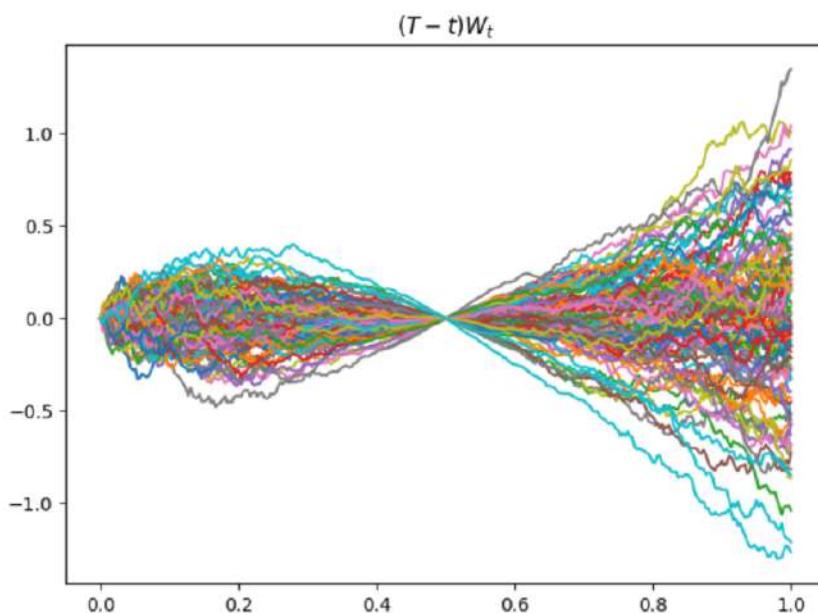
is differentiable at point  $T$  almost surely.

a) nowokum  $X_t = (T-t)W_t$

$$\begin{aligned} ((T-t)W_t)'|_{t=T} &= \lim_{h \rightarrow 0} \frac{X_{T+h} - X_{T-h}}{2h} = \lim_{h \rightarrow 0} \frac{(T-(T+h))W_{T+h} - (T-(T-h))W_{T-h}}{2h} = \\ &= \lim_{h \rightarrow 0} \frac{-hW_{T+h} - hW_{T-h}}{2h} = \frac{1}{2} \lim_{h \rightarrow 0} (-W_{T+h} - W_{T-h}) \stackrel{\text{Skewer.}}{\underset{\text{неприменим.}}{=}} = -W_T \end{aligned}$$

$\Rightarrow$  т.е. б. мове  $t=T$  процесс  $X_t = (T-t)W_t$  дифф. н.н.  
 $\& (X_t)'|_{t=T} = -W_T$

- (b) (0.5 point) Are there other points at which the process is differentiable almost surely?



Рассмотрим  $t_0 \in [0, T]$  в предположении, что  $X_t$  дифф. в т.  $t_0$  н.н.

Если  $X_t$  дифф. н.н.  $\Rightarrow \exists$  правое и левое производные н.н.  $\Rightarrow$

$$\begin{aligned} \lim_{h \rightarrow 0+} \frac{X_{t_0+h} - X_{t_0}}{h} &= \lim_{h \rightarrow 0+} \frac{(T-(t_0+h))W_{t_0+h} - (T-t_0)W_{t_0}}{h} = \\ &= \lim_{h \rightarrow 0+} (T-t_0) \frac{W_{t_0+h} - W_{t_0}}{h} - W_{t_0+h} \end{aligned}$$

$W_{t_0+h} \rightarrow W_{t_0}$  при  $h \rightarrow 0+$  (условие н.н. гладкости)

но  $\nexists \lim_{h \rightarrow 0+} \frac{W_{t_0+h} - W_{t_0}}{h}$  н.н., т.к. траектории  $B(t)$  не глад. н.н.

$\Rightarrow$  доказано

□

1. Consider a structured deposit - a financial product that offers fixed income and additional yield in the form of a call option. The underlying asset of the call option is asset  $S$ . The guaranteed income pays an amount  $S_0$  at maturity of the deposit. Assume the funding rate is higher than the model rate.

- (a) (0.5 point) Is it true that the funding component is always positive?  
 (b) (0.5 point) Is it true that the funding component is always negative?

□

**Theorem 3**

Under the assumptions above, the hedging error for a European option in the Black-Scholes-Merton model can be decomposed into the next components:

$$Z_t = \underbrace{\frac{Z_0}{D_t}}_{\text{Premium component}} + \underbrace{\int_0^t \frac{D_u}{D_t} (r_u^f - r) \left( V_u - \frac{\partial V}{\partial S} S_u \right) du}_{\text{Funding component}} + \underbrace{\int_0^t \frac{1}{D_t} \left( \Delta_u^h - \frac{\partial V}{\partial S} \right) dD_u S_u}_{\text{Delta component}} + \underbrace{\frac{1}{2} \int_0^t \frac{D_u}{D_t} \frac{\partial^2 V}{\partial S^2} (\sigma^2 S_u^2 du - (dS_u)^2)}_{\text{Gamma component}},$$

where the derivatives are taken at  $(u, S_u)$ .

Видимо мояссыңыз салынуда.

Из-за funding component  
мы ожидаем -1.

$$\int_0^t \frac{D_u}{D_t} (r_u^f - r) \left( V_u - \frac{\partial V}{\partial S} S_u \right) du \\ := F(u, S_u)$$

На салынуда жеке калыптаған call-онуқорға:

$$V(t, S_t) - \frac{\partial V}{\partial S}(t, S_t) S_t = V(t, S_t) \left( 1 - \frac{S_t}{S_t - x} \right) < 0.$$

Үрненесе, шоноң негізгіші  $r_u^f > r$ , т.е.  $(r_u^f - r) > 0$ , и

Оребугре,  $\frac{D_u}{D_t} > 0 \Rightarrow$  жиғ call-онуқорға

$$\int_0^t \underbrace{\frac{D_u}{D_t}}_{>0} (r_u^f - r) \underbrace{\left( V_u - \frac{\partial V}{\partial S} S_u \right) du}_{=: F(u, S_u)} < 0$$

Шоңаң енбектің үлкемелілігінде  $G = S_0$  баремдай  $T$

Дене кел:  $\tilde{V}_t = S_0 e^{-r(T-t)}$ ;  $\Delta_t = \frac{\partial \tilde{V}_t}{\partial S} = 0 \Rightarrow \tilde{F}(u, S_u) = \tilde{V}_u > 0$

Б үмірде, шоңаң забаремдай соғынаның  $F$  үр  $\tilde{F}$ :

- енбек  $S_0 e^{-r(T-t)} = \tilde{F} > |F|$ , шоңаң fund. comp.  $> 0$

- енбек  $S_0 e^{-r(T-t)} = \tilde{F} = |F|$ , шоңаң fund. comp.  $= 0$

- енбек  $S_0 e^{-r(T-t)} = \tilde{F} < |F|$ , шоңаң fund. comp.  $< 0$

$\Rightarrow$  Омбем: а) нәрм; ж) нәрм



2. (1 point) Describe a hedging strategy that replicates the payoff of a call option under a non-zero constant interest rate, for continuous paths crossing the strike price finitely many times.  $=:\gamma$

□ Вспоминаем конт-опциона в момент времени  $T$ :  $X_T = (S_T - K)^+$

Положим  $\Delta_t := \mathbb{I}\{S_t > K\}$   $\leftarrow$  имеет конечную вариацию!

$\leftarrow$  у-за  $\Rightarrow$  можно применить ф. уро

При условии, что  $S_t$  непрерывна и пересекает конечное число раз  $K$  кривую буде  $C^{\infty}$

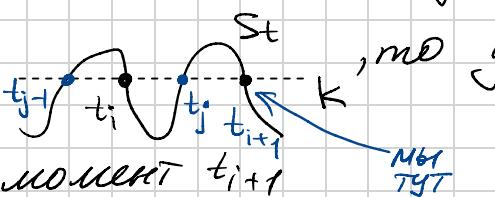
Стратегия:

- 1) В начальный момент времени капитал  $V_0 = (S_0 - K)^+ e^{-rT}$
- 2) В каждый момент времени  $t$  поддерживается портфель из  $\Delta_t$  единиц рискового актива и  $[-K \cdot \Delta_t e^{-r(T-t)}]$  — из  $\Delta_t$  единиц безрискового актива

Составляем портфель в момент времени  $t$ :

$$V_t = S_t \cdot \Delta_t + [-K \cdot \Delta_t \cdot e^{-r(T-t)}] = S_t \Delta_t - K \Delta_t e^{r(t-T)} = \Delta_t (S_t - K e^{r(t-T)})$$

Пусть мы пересекаем уровень  $K$  во времени  $t_1, t_2, \dots, t_m$   
(их конечное число по условию)

- Если  , то у нас имеется 1 акция (продаем) ценой  $K e^{r(t-t_j)}$

- Если нет в  $t_j$  (т.е.  $S_t \geq K$ ), то у нас одна 1 акция ( покупаем) ценой  $K e^{-r(T-t)}$

В таком случае составление портфеля непрерывно

В конечный момент времени  $T$ :

- Если  $S_T \leq K$ , то рискового актива  $\Delta_T = 0$   
безрискового 0  
 $V_T = 0 = (S_T - K)^+$

- Если  $S_T > K$ , то рискового актива  $\Delta_T = 1$   
безрискового  $-K \cdot \Delta_T e^{-r(T-T)} = -K$   
 $V_T = S_T - K = (S_T - K)^+$



3. (1 point) Consider a naive hedging strategy for an option with a certain strike price, assuming the underlying asset price follows a Brownian motion. Compute the ratio of the standard deviation of the hedging error to the premium of a zero-strike option. Assume zero interest rates.

□ В наивной стратегии хеджирования  $\Delta_t = \mathbb{1}\{S_t \geq K\}$  с  $dS_t = dW_t$   
Следовательно, при попытке Танака для баланса ожидаем  
 $f(x) = (x - K)^+$ , имеем:

According to Theorem 1 with  $X = S$  and  $f(x) = (x - K)^+$ ,

$$(S_t - K)^+ = (S_0 - K)^+ + \int_0^t \mathbb{1}\{S_u \geq K\} dS_u + \frac{1}{2} L_t^K.$$

Thus, the 'naive' hedging strategy gives the next slippage in continuous time when the underlying price is a geometric Brownian motion:

$$Z_T = -\frac{1}{2} L_T^K.$$

т.е.

$$L_t^x = \lim_{\varepsilon \rightarrow 0^+} \frac{1}{2\varepsilon} \int_0^t \mathbb{1}\{x - \varepsilon < X_u < x + \varepsilon\} d[X]_u$$

is the local time of  $X$  at point  $x$ .

Что при  $K=0$ , то имеем

$$\begin{aligned} X_T &= (S_T - 0)^+ = (S_0 - 0)^+ + \int_0^T \mathbb{1}\{S_u \geq 0\} dS_u + \frac{1}{2} L_T^0 = \{dS_t = dW_t\} = \\ &= (S_0)^+ + \int_0^T \mathbb{1}\{W_u \geq 0\} dW_u + \frac{1}{2} L_T^0 \end{aligned}$$

Одна из хеджирований:

$$Z_T = \left[ (S_0)^+ + \int_0^T \mathbb{1}\{W_u \geq 0\} dW_u \right] - (W_T)^+ = -\frac{1}{2} L_T^0 \quad (1)$$

$$\mathbb{E}[S_T^+] = \mathbb{E}[\max(W_T, 0)] = \frac{1}{\sqrt{2\pi}}$$

Следовательно 3 зная, что  $L_T^0 \stackrel{d}{=} N_T \stackrel{d}{=} |W_T|$ , где  $N_T = \sup_{s \leq t} W_s$

$$\mathbb{E}[|W_T|] = \sqrt{\frac{2T}{\pi}}, \quad \mathbb{E}[|W_T|^2] = T$$

$$\Rightarrow D[L_T^0] = D[|W_T|] = \mathbb{E}[|W_T|^2] - (\mathbb{E}[|W_T|])^2 = T - \frac{2T}{\pi} = T(1 - \frac{2}{\pi})$$

из (1)  $D[Z_T] = \frac{1}{4} D[L_T^0] = \frac{T}{4} \cdot (1 - \frac{2}{\pi}) \Rightarrow$

$$\text{std}(Z_T) = \frac{1}{2} \sqrt{T(1 - \frac{2}{\pi})}$$

$$T \text{ erga } k = \frac{\text{std}(Z_T)}{E[S_T^+]} = \frac{\frac{1}{\sqrt{2}} \sqrt{T(1 - \frac{2}{\pi})}}{\frac{1}{\sqrt{2\pi}}} = \frac{1}{2} \sqrt{T(2\pi - 4)} = \sqrt{T(\frac{\pi}{2} - 1)}$$

$$\text{Dnlem: } k = \sqrt{T(\frac{\pi}{2} - 1)}$$

□

## Домашка 4

## Домашка Евгебема

1. (0.25 point) Derive the expression for  $\frac{\partial V}{\partial r}$  for a call option within the Black-Scholes-Merton model. **Rho**

$V = C_t = S_t N(d_1) - K e^{-r(T-t)} N(d_2),$

$$d_1 = \frac{\ln \frac{S_t}{K} + (r + \frac{\sigma^2}{2})(T-t)}{\sigma \sqrt{T-t}}, \quad d_2 = d_1 - \sigma \sqrt{T-t}$$

$$\frac{\partial V}{\partial r} = S N'(d_1) \frac{\partial d_1}{\partial r} - K e^{-r(T-t)} \left( -(T-t) N(d_2) + N'(d_2) \frac{\partial d_2}{\partial r} \right)$$

$$\frac{\partial d_1}{\partial r} = \frac{T-t}{6\sqrt{T-t}} = \frac{\sqrt{T-t}}{6}, \quad \frac{\partial d_2}{\partial r} = \frac{T-t}{6\sqrt{T-t}} = \frac{\sqrt{T-t}}{6}$$

В первом гомеоморфном рабочем

$$N'(d_1) = n(d_1) = n(d_2) \cdot \underbrace{\frac{K}{S} e^{-r(T-t)}}_{= N'(d_2)}$$

$$\Rightarrow \frac{\partial V}{\partial r} = S \cancel{N'(d_2)} \frac{K}{S} e^{-r(T-t)} \cdot \frac{\sqrt{T-t}}{6} + K e^{-r(T-t)} (T-t) N(d_2) - \\ - K e^{-r(T-t)} N'(d_2) \cdot \frac{\sqrt{T-t}}{6} = \\ = K e^{-r(T-t)} (T-t) N(d_2)$$

**Ошибки:**  $\frac{\partial V}{\partial r} = K e^{-r(T-t)} (T-t) N(d_2)$



2. (0.25 point) Derive the expression for  $\frac{\partial^2 V}{\partial S \partial \sigma}$  for a call option within the Black-Scholes-Merton model. **Vanna**

В первом гомеоморфном находим  $\Delta = \frac{\partial V}{\partial S} = N(d_1)$ .

Затем,  $\frac{\partial^2 V}{\partial S \partial \sigma} = \frac{\partial \Delta}{\partial \sigma} = N'(d_1) \frac{\partial d_1}{\partial \sigma}$

$$\frac{\partial d_1}{\partial \sigma} = - \frac{\ln \frac{S}{K} + r(T-t)}{S^2 \sqrt{T-t}} + \frac{1}{2} \frac{(T-t)}{\sqrt{T-t}} = - \frac{d_1}{6} + \sqrt{T-t}$$

$$\Rightarrow \frac{\partial^2 V}{\partial S \partial \sigma} = N'(d_1) \cdot \left( \sqrt{T-t} - \frac{d_1}{6} \right), \text{ где } N'(d_1) = \frac{1}{\sqrt{2\pi}} e^{-\frac{d_1^2}{2}}$$

**Ошибки:**  $\frac{\partial^2 V}{\partial S \partial \sigma} = N'(d_1) \cdot \left( \sqrt{T-t} - \frac{d_1}{6} \right) = -N'(d_1) \frac{d_2}{6}$



3. (0.25 point) Derive the expression for  $\frac{\partial^2 V}{\partial \sigma^2}$  for a call option within the Black-Scholes-Merton model.

Volga

$$\square \quad J = \frac{\partial V}{\partial \sigma} = S N'(d_1) \cdot \frac{\partial d_1}{\partial \sigma} - K e^{-r(T-t)} N'(d_2) \frac{\partial d_2}{\partial \sigma}$$

$$\frac{\partial d_1}{\partial \sigma} = -\frac{d_1}{6} + \sqrt{T-t}; \quad \frac{\partial d_2}{\partial \sigma} = -\frac{d_2}{6} + \sqrt{T-t} - \sqrt{T-t} = -\frac{d_2}{6}$$

$$N'(d_1) = n(d_1) = \underbrace{n(d_2)}_{= N'(d_2)} \cdot \frac{K}{S} e^{-r(T-t)}$$

$$\Rightarrow J = \frac{\partial V}{\partial \sigma} = S N'(d_1) \cdot \left( \sqrt{T-t} - \frac{d_1}{6} \right) - S N'(d_2) \cdot \left( -\frac{d_2}{6} \right) = S N'(d_1) \cdot \sqrt{T-t}$$

$$\left\{ \begin{array}{l} \frac{\partial^2 V}{\partial \sigma^2} = \frac{\partial J}{\partial \sigma} = S \sqrt{T-t} \cdot N''(d_1) \cdot \frac{\partial d_1}{\partial \sigma} \\ N''(d_1) = -d_1 N'(d_1) \end{array} \right.$$

$$\hookrightarrow \frac{\partial^2 V}{\partial \sigma^2} = -S \sqrt{T-t} d_1 N'(d_1) \cdot \left( \sqrt{T-t} - \frac{d_1}{6} \right)$$

$$\text{Ombem: } \frac{\partial^2 V}{\partial \sigma^2} = S \sqrt{T-t} d_1 N'(d_1) \left( \frac{d_1}{6} - \sqrt{T-t} \right) = \frac{S \sqrt{T-t} N'(d_1) d_1 d_2}{6} \quad \square$$

4. (0.25 point) Derive the expression for  $\frac{\partial V}{\partial t}$  for a call option within the Black-Scholes-Merton model.

Theta

$$\square \quad \frac{\partial V}{\partial t} = S N'(d_1) \frac{\partial d_1}{\partial t} - K e^{-r(T-t)} \left( r N(d_2) + N'(d_2) \frac{\partial d_2}{\partial t} \right)$$

$$\left\{ \begin{array}{l} \frac{\partial d_1}{\partial t} = +\frac{1}{2} \cdot \frac{\ln \frac{S}{K}}{(T-t)^{3/2}} - \left( r + \frac{\sigma^2}{2} \right) \cdot \frac{1}{\lambda} \frac{1}{6 \sqrt{T-t}} = \frac{d_1}{2 \sqrt{T-t}} - \frac{r + \frac{\sigma^2}{2}}{6 \sqrt{T-t}} \\ \frac{\partial d_2}{\partial t} = \frac{\partial d_1}{\partial t} + \frac{1}{2} \frac{\sigma}{\sqrt{T-t}} = \frac{d_1}{2 \sqrt{T-t}} - \frac{r}{6 \sqrt{T-t}} \end{array} \right.$$

$$N'(d_1) = n(d_1) = \underbrace{n(d_2)}_{= N'(d_2)} \cdot \frac{K}{S} e^{-r(T-t)}$$

$$\begin{aligned} \hookrightarrow \frac{\partial V}{\partial t} &= S N'(d_1) \left( \frac{d_1}{2 \sqrt{T-t}} - \frac{r + \frac{\sigma^2}{2}}{6 \sqrt{T-t}} \right) - r K e^{-r(T-t)} N(d_2) - \\ &\quad - S N'(d_1) \cdot \left( \frac{d_1}{2 \sqrt{T-t}} - \frac{r}{6 \sqrt{T-t}} \right) = \end{aligned}$$

$$= -S N'(d_1) \frac{6}{2 \sqrt{T-t}} - r K e^{-r(T-t)} N(d_2)$$

$$\text{Ombem: } \frac{\partial V}{\partial t} = -S N'(d_1) \frac{6}{2 \sqrt{T-t}} - r K e^{-r(T-t)} N(d_2) \quad \square$$

5. (0.5 point) Consider two Brownian motions  $W_t^1$  and  $W_t^2$  such that  $[W^1, W^2]_t = \rho t$ . Show that  $\text{cov}(W_t^1, W_t^2) = \rho t$ .

□ no фокусне умо, где мы доказали:

$$d(W_t^1 W_t^2) = W_t^1 dW_t^2 + W_t^2 dW_t^1 + d[W^1, W^2]_t$$

$$W_t^1 W_t^2 = \int_0^t W_t^1 dW_t^2 + \int_0^t W_t^2 dW_t^1 + [W^1, W^2]_t$$

$$\mathbb{E}[W_t^1 W_t^2] = 0 + 0 + \mathbb{E}[W^1, W^2]_t$$

$$\Rightarrow \mathbb{E}[W_t^1 W_t^2] = \mathbb{E}[W^1, W^2]_t = \rho t$$

$$\left\{ \begin{array}{l} \text{т.к. } \mathbb{E} W_t^1 = \mathbb{E} W_t^2 = 0 \end{array} \right.$$

$$\Rightarrow \text{cov}(W_t^1, W_t^2) = \mathbb{E}[W_t^1 W_t^2] - \mathbb{E}[W_t^1] \cdot \mathbb{E}[W_t^2] = \rho t$$

$$\text{т.е. } \text{cov}(W_t^1, W_t^2) = \rho t \quad \text{з.р.д.}$$

□

6. (0.5 point) Let  $Y_t$  follow a Geometric brownian motion, and define  $Z_t = \frac{1}{Y_t}$ . Find the quadratic covariation  $[Y, Z]_t$ .

□ Рассмотрим  $dY_t = \mu Y_t dt + \sigma Y_t dW_t$ . Найдем квадратичную ф. умо к  $f(y) = \frac{1}{y}$

$$f'(y) = -\frac{1}{y^2}; \quad f''(y) = \frac{2}{y^3}$$

$$\Rightarrow d(Z_t) = df(Y_t) = -\frac{1}{y_t^2} dY_t + \frac{1}{2} \cdot \frac{2}{y_t^3} (dY_t)^2 =$$

$$= -\frac{1}{y_t^2} (\mu Y_t dt + \sigma Y_t dW_t) + \frac{1}{y_t^3} (\sigma^2 Y_t^2 dt) =$$

$$= (\sigma^2 - \mu) \cdot \frac{1}{y_t} dt - \sigma \cdot \frac{1}{y_t} dW_t = (\sigma^2 - \mu) Z_t dt - \sigma Z_t dW_t$$

$$\text{т.е. } dZ_t = (\sigma^2 - \mu) Z_t dt - \sigma Z_t dW_t$$

$$d[Y, Z]_t = dY_t \cdot dZ_t = (\mu Y_t dt + \sigma Y_t dW_t) \cdot ((\sigma^2 - \mu) Z_t dt - \sigma Z_t dW_t) =$$

$$= \sigma Y_t \cdot (-\sigma Z_t) dt = -\sigma^2 dt$$

$$\Rightarrow [Y, Z]_t = -\sigma^2 t$$

$$\text{Окончание: } [Y, Z]_t = -\sigma^2 t$$

□