AlexNet

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0.1 Loading Files from drive

The command below is to load files from drive

Drive already mounted at /content/drive; to attempt to forcibly remount, call drive.mount("/co

0.2 Importing Libraries

Numpy, Pandas, Torch, PIL, Torchvision, matplotlib and os libraries are imported

```
In [0]: import numpy as np
    import pandas as pd
    import os
    import torch
    import torchvision
    from PIL import Image
    import matplotlib.pyplot as plt
    from torch.utils.data import Dataset
    from torchvision import datasets, models, transforms
```

0.3 Dataset loading

The dataset class is inherited and customized as per the dataset given. RandomResizedCrop, RandomHorizontalFlip are used as data augmentation techniques. The dataset is also normalized to obtain better results.

```
In [0]: class DataSet(Dataset):
    def __init__(self, root_dir, total_no, csv_file, transform=None):
        self.root_dir = root_dir
        self.transform = transform
        self.total_no = total_no
        self.csv_file = np.array(pd.read_csv(csv_file, header=None))[0]

def __len__(self):
    return self.total_no
```

```
def __getitem__(self, image_no):
        img_name = os.path.join(self.root_dir, str(image no+1)+".jpg")
        image = Image.open(img_name)
        sample = {'image': image, 'category': self.csv file[image no]-1}
        if self.transform:
            sample['image'] = self.transform(sample['image'])
        return sample
trainDataset = DataSet('/content/drive/My Drive/HW3_data/train/',
                       1888.
                       '/content/drive/My Drive/HW3_data/train_labels.csv',
                       transforms.Compose([
        transforms.RandomResizedCrop(224),
        transforms.RandomHorizontalFlip(),
        transforms.ToTensor(),
        transforms.Normalize([0.485, 0.456, 0.406], [0.229, 0.224, 0.225])
    ]))
testDataset = DataSet('/content/drive/My Drive/HW3_data/test/', 800,
                      '/content/drive/My Drive/HW3 data/test labels.csv',
                      transforms.Compose([
        transforms.Resize(256),
        transforms.CenterCrop(224),
        transforms.ToTensor(),
        transforms.Normalize([0.485, 0.456, 0.406], [0.229, 0.224, 0.225])
   ]))
```

0.4 Dataloaders for loading the datasets defined

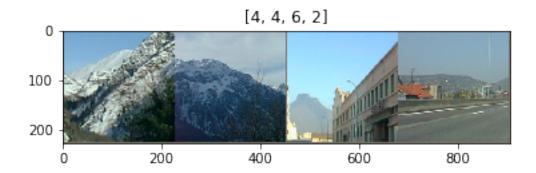
Train and test dataloaders are defined with batch size 4, number of workers 4 and shuffling while loading data has been enabled.

0.5 Displaying the images

The images are displayed along with their classes after loading data

```
In [0]: def imshow(inp, title=None):
    inp = inp.numpy().transpose((1, 2, 0))
    mean = np.array([0.485, 0.456, 0.406])
    std = np.array([0.229, 0.224, 0.225])
    inp = std * inp + mean
    inp = np.clip(inp, 0, 1)
```

```
plt.imshow(inp)
   if title is not None:
       plt.title(title)
inputs = next(iter(trainDataloader))
out = torchvision.utils.make_grid(inputs['image'])
imshow(out, title=[int(x) for x in inputs['category']])
```



0.6 Loading pretrained Alexnet model

In [0]: alexnet = torchvision.models.alexnet(pretrained=True)

Downloading: "https://download.pytorch.org/models/alexnet-owt-4df8aa71.pth" to /root/.torch/models/alexnet-owt-4df8aa71.pth 244418560it [00:08, 27452845.75it/s]

Transfer Learning and Fine-tuning

All the layers are freezed except the final layer and the number of outputs in final layer is changed to 8.

```
In [0]: for param in alexnet.parameters():
          param.requires_grad=False
        alexnet.classifier[6] = torch.nn.Linear(alexnet.classifier[6].in_features, 8)
```

0.8 Final Alexnet model

```
In [0]: alexnet.to(device)
Out[0]: AlexNet(
          (features): Sequential(
            (0): Conv2d(3, 64, kernel_size=(11, 11), stride=(4, 4), padding=(2, 2))
            (1): ReLU(inplace)
            (2): MaxPool2d(kernel_size=3, stride=2, padding=0, dilation=1, ceil_mode=False)
            (3): Conv2d(64, 192, kernel_size=(5, 5), stride=(1, 1), padding=(2, 2))
            (4): ReLU(inplace)
```

```
(5): MaxPool2d(kernel_size=3, stride=2, padding=0, dilation=1, ceil_mode=False)
  (6): Conv2d(192, 384, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
  (7): ReLU(inplace)
  (8): Conv2d(384, 256, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
  (9): ReLU(inplace)
  (10): Conv2d(256, 256, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
  (11): ReLU(inplace)
  (12): MaxPool2d(kernel_size=3, stride=2, padding=0, dilation=1, ceil_mode=False)
(avgpool): AdaptiveAvgPool2d(output_size=(6, 6))
(classifier): Sequential(
  (0): Dropout(p=0.5)
  (1): Linear(in_features=9216, out_features=4096, bias=True)
  (2): ReLU(inplace)
  (3): Dropout(p=0.5)
  (4): Linear(in_features=4096, out_features=4096, bias=True)
  (5): ReLU(inplace)
  (6): Linear(in_features=4096, out_features=8, bias=True)
)
```

0.9 Defining Optimizer, Loss functions and Learning rate scheduler

The optimizer function, loss function and the learning rate scheduler are defined in the following segment of code.

0.10 Function for running the defined model

)

The function is defined for loading the data for each epoch, outputing the output for the batch and performing backpropagation using the defined optimizer.

```
In [0]: def run_model(model, epochs, loss, optimizer, trainDataloader, testDataloader):
    model.to(device)
    for epoch in range(epochs):
        current_loss = 0.0
        exp_lr_scheduler.step()
        for i, data in enumerate(trainDataloader, 0):
        images, labels = data['image'], data['category']
        images, labels = images.to(device), labels.to(device)
        optimizer.zero_grad()
        obtained_outputs = model(images)
        obtained_loss = loss(obtained_outputs, labels)
        obtained_loss.backward()
        optimizer.step()
```

```
current_loss += obtained_loss.item()
   if(i\%100 == 99):
     print("EPOCH:", epoch+1)
     print("BATCH:", i+1)
     print("LOSS:", current loss/100)
     print("----")
     current loss = 0.0
print("Training Done!!!")
model.to(device)
correct = 0
total = 0
with torch.no_grad():
 for data in testDataloader:
   images, labels = data['image'], data['category']
   images, labels = images.to(device), labels.to(device)
   outputs = model(images)
   predicted_output = torch.argmax(outputs, 1)
   correct += (predicted_output == labels).sum().item()
   total += labels.size(0)
print("Accuracy:", correct*100/total, "%")
```

0.11 Running the model

Resnet model is run for 200 epochs with the defined Cross Entropy Loss and Adam Optimizer.

```
In [0]: run model(alexnet, 200, Loss, Optimizer, trainDataloader, testDataloader)
```

0.12 Training Accuracy

The trained model is run on the train dataset. Accuracy of 93.432% is obtained.

```
In [0]: correct = 0
    total = 0
    with torch.no_grad():
        for data in trainDataloader:
            images, labels = data['image'], data['category']
            images, labels = images.to(device), labels.to(device)
            outputs = alexnet(images)
            predicted_output = torch.argmax(outputs, 1)
            correct += (predicted_output == labels).sum().item()
            total += labels.size(0)
            print("Training Accuracy:", correct*100/total, "%")
```

0.13 Testing Accuracy

Training Accuracy: 93.4322033898305 %

The trained model is run on the test dataset. Accuracy of 93.25% is obtained.

```
In [0]: alexnet.to(device)
    correct = 0
    total = 0
    with torch.no_grad():
        for data in testDataloader:
            images, labels = data['image'], data['category']
            images, labels = images.to(device), labels.to(device)
            outputs = alexnet(images)
            predicted_output = torch.argmax(outputs, 1)
            correct += (predicted_output == labels).sum().item()
            total += labels.size(0)
            print("Test Accuracy:", correct*100/total, "%")

Test Accuracy: 93.25 %
In [0]:
```