

## Chapter 17. Markov and hidden Markov models

17.1.

$$l_c(\boldsymbol{\theta}) = \sum_{i=1}^N \log p(\mathbf{x}_i, \mathbf{z}_i | \boldsymbol{\theta}) = \sum_{i=1}^N [\log p(z_{i1}) + \sum_{t=2}^{T_i} \log p(z_{it} | z_{i,t-1}) + \sum_{t=1}^{T_i} \log p(\mathbf{x}_{it} | z_{it})]$$

$$\begin{aligned} Q(\boldsymbol{\theta}, \boldsymbol{\theta}^{\text{old}}) &= \mathbb{E}[l_c(\boldsymbol{\theta}) | \mathcal{D}, \boldsymbol{\theta}^{\text{old}}] = \sum_{i=1}^N \mathbb{E}[\log p(z_{i1})] \\ &+ \sum_{i=1}^N \sum_{t=2}^{T_i} \mathbb{E}[\log p(z_{it} | z_{i,t-1})] + \sum_{i=1}^N \sum_{t=1}^{T_i} \mathbb{E}[\log p(\mathbf{x}_{it} | z_{it})]. \end{aligned}$$

$$\sum_{i=1}^N \mathbb{E}[\log p(z_{i1})] = \sum_{i=1}^N \sum_{k=1}^K p(z_{i1} = k | \mathbf{x}_i, \boldsymbol{\theta}^{\text{old}}) \log p(z_{i1} = k) = \sum_{k=1}^K \mathbb{E}[N_k^1] \log \pi_k.$$

$$\begin{aligned} \sum_{i=1}^N \sum_{t=2}^{T_i} \mathbb{E}[\log p(z_{it} | z_{i,t-1})] &= \sum_{i=1}^N \sum_{t=2}^{T_i} \sum_{j=1}^K \sum_{k=1}^K p(z_{it} = k, z_{i,t-1} = j | \mathbf{x}_i, \boldsymbol{\theta}^{\text{old}}) \log p(z_{it} = k | z_{i,t-1} = j) \\ &= \sum_{j=1}^K \sum_{k=1}^K \mathbb{E}[N_{jk}] \log A_{jk}. \end{aligned}$$

$$\sum_{i=1}^N \sum_{t=1}^{T_i} \mathbb{E}[\log p(\mathbf{x}_{it} | z_{it})] = \sum_{i=1}^N \sum_{t=1}^{T_i} \sum_{k=1}^K p(z_{it} = k | \mathbf{x}_i, \boldsymbol{\theta}^{\text{old}}) \log p(\mathbf{x}_{it} | z_{it} = k).$$

Summing those three term gives:

$$Q(\boldsymbol{\theta}, \boldsymbol{\theta}^{\text{old}}) = \sum_{k=1}^K \mathbb{E}[N_k^1] \log \pi_k + \sum_{j=1}^K \sum_{k=1}^K \mathbb{E}[N_{jk}] \log A_{jk}$$

$$+ \sum_{i=1}^N \sum_{t=1}^{T_i} \sum_{k=1}^K p(z_{it} = k | \mathbf{x}_i, \boldsymbol{\theta}^{\text{old}}) \log p(\mathbf{x}_{it} | \boldsymbol{\phi}_k).$$

17.2.

$$\begin{aligned} r_t(i) &= p(S_t = i | \mathbf{x}_{t+1:T}) = \sum_j p(S_t = i, S_{t+1} = j | \mathbf{x}_{t+1:T}) \\ &= \sum_j p(S_{t+1} = j | \mathbf{x}_{t+1:T}) p(S_t = i | S_{t+1} = j). \\ p(S_{t+1} = j | \mathbf{x}_{t+1:T}) &= p(S_{t+1} = j | \mathbf{x}_{t+1}, \mathbf{x}_{t+2:T}) \\ &\propto p(\mathbf{x}_{t+1} | S_{t+1} = j) p(S_{t+1} = j | \mathbf{x}_{t+2:T}) \propto \phi_{t+1}(j) r_{t+1}(j). \\ &\Rightarrow \mathbf{r}_t \propto \boldsymbol{\phi}_t \odot (\Xi^T \mathbf{r}_{t+1}), \end{aligned}$$

where  $\Xi$  is the time-reversed transition matrix with  $\xi_{ji} = p(S_t = i | S_{t+1} = j)$  with initial state given by  $\Pi_T(i)$ .

Computing  $\gamma_t(i)$  can be done as follows:

$$\begin{aligned} \gamma_t(i) &= p(S_t = i | \mathbf{x}_{1:T}) = p(S_t = i) p(\mathbf{x}_{1:T} | S_t = i) \\ &= p(S_t = i) p(\mathbf{x}_{1:t} | S_t = i) p(\mathbf{x}_{t+1:T} | S_t = i) = \frac{1}{p(S_t = i)} p(S_t = i | \mathbf{x}_{1:t}) p(S_t = i | \mathbf{x}_{t+1:T}) \\ &= \frac{\alpha_t(i) r_t(i)}{\Pi_t(i)}. \end{aligned}$$

17.3.

Recall the result from 17.1:

$$\begin{aligned} Q(\boldsymbol{\theta}, \boldsymbol{\theta}^{\text{old}}) &= \sum_{k=1}^K \mathbb{E}[N_k^1] \log \pi_k + \sum_{j=1}^K \sum_{k=1}^K \mathbb{E}[N_{jk}] \log A_{jk} \\ &+ \sum_{i=1}^N \sum_{t=1}^{T_i} \sum_{k=1}^K p(z_{it} = k | \mathbf{x}_i, \boldsymbol{\theta}^{\text{old}}) \log p(\mathbf{x}_{it} | \boldsymbol{\phi}_k). \end{aligned}$$

Assume that each of the emission distributions

$$p(\mathbf{x}_t | z_t = k, \boldsymbol{\theta}) = \sum_{m=1}^{M_k} w_{km} \mathcal{N}(\mathbf{x}_t | \boldsymbol{\mu}_{km}, \boldsymbol{\Sigma}_{km})$$

is itself a mixture of  $M_k$  Gaussians. Now we introduce a second latent variable  $y_{km}$ , which refers to the component  $m$  with state  $k$ . The latent variable  $y_{km}$  is itself a Markov chain with the transition matrix  $\mathbf{\Omega} = [\omega_{(km), (k'm')}]$ , where  $\omega_{(km), (k'm')} = A_{kk'} w_{k'm'}$ . (Therefore the transition between  $km$  and  $k'm'$  only depends on the hidden state  $z$  at the previous time.)

Let  $\gamma_{i,t}(k)$ ,  $\xi_{i,t}(j, k)$  be smoothed node and edge marginals in Section 17.5.2.1., and  $\delta_{i,t}(k, m) = p(y_t = km | z_t = k, \mathbf{x}_{i,1:T_i}, \boldsymbol{\theta})$  be marginals for mixture component transition. Then the last term becomes:

$$\begin{aligned} & \sum_{i=1}^N \sum_{t=1}^{T_i} \sum_{k=1}^K p(z_{it} = k | \mathbf{x}_i, \boldsymbol{\theta}^{\text{old}}) \log p(\mathbf{x}_{it} | \boldsymbol{\phi}_k) \\ &= \sum_{i=1}^N \sum_{t=1}^{T_i} \sum_{k=1}^K \sum_{m=1}^{M_k} \gamma_{i,t}(k) \delta_{i,t}(k, m) \log w_{km} \\ &+ \sum_{i=1}^N \sum_{t=1}^{T_i} \sum_{k=1}^K \sum_{m=1}^{M_k} \gamma_{i,t}(k) \delta_{i,t}(k, m) \log \mathcal{N}(\mathbf{x}_{it} | \boldsymbol{\mu}_{km}, \boldsymbol{\Sigma}_{km}). \end{aligned}$$

E-step:

The smoothed node and edge marginals can be estimated in the same manner in Section 17.5.2.1, running the forwards-backwards algorithm on each sequence.

The marginals for mixture component transition is computed as:

$$\hat{\delta}_{i,t}(k, m) = \frac{w_{km} \mathcal{N}(\mathbf{x}_{it} | \boldsymbol{\mu}_{km}, \boldsymbol{\Sigma}_{km})}{\sum_{m'=1}^{M_k} w_{km'} \mathcal{N}(\mathbf{x}_{it} | \boldsymbol{\mu}_{km'}, \boldsymbol{\Sigma}_{km'})}$$

M-step:

The M step for  $\mathbf{A}$  and  $\boldsymbol{\pi}$  is already discussed in Section 17.5.2.2. For other variables, we get:

$$\begin{aligned} \hat{w}_{km} &= \frac{\sum_{i=1}^N \sum_{t=1}^{T_i} \sum_{k=1}^K \hat{\gamma}_{i,t}(k) \hat{\delta}_{i,t}(k, m)}{\sum_{i=1}^N \sum_{t=1}^{T_i} \sum_{k=1}^K \hat{\gamma}_{i,t}(k)} \\ \hat{\boldsymbol{\mu}}_{km} &= \frac{\sum_{i=1}^N \sum_{t=1}^{T_i} \sum_{k=1}^K \hat{\gamma}_{i,t}(k) \hat{\delta}_{i,t}(k, m) \mathbf{x}_{it}}{\sum_{i=1}^N \sum_{t=1}^{T_i} \sum_{k=1}^K \hat{\gamma}_{i,t}(k) \hat{\delta}_{i,t}(k, m)} \\ \hat{\boldsymbol{\Sigma}}_{km} &= \frac{\sum_{i=1}^N \sum_{t=1}^{T_i} \sum_{k=1}^K \hat{\gamma}_{i,t}(k) \hat{\delta}_{i,t}(k, m) (\mathbf{x}_{it} - \hat{\boldsymbol{\mu}}_{km})(\mathbf{x}_{it} - \hat{\boldsymbol{\mu}}_{km})^T}{\sum_{i=1}^N \sum_{t=1}^{T_i} \sum_{k=1}^K \hat{\gamma}_{i,t}(k) \hat{\delta}_{i,t}(k, m)}. \end{aligned}$$

17.4.

This time each of the emission distributions becomes:

$$p(\mathbf{x}_t | z_t = k, \boldsymbol{\theta}) = \sum_{m=1}^M w_m \mathcal{N}(\mathbf{x}_t | \boldsymbol{\mu}_m, \boldsymbol{\Sigma}_m).$$

The expected complete data log likelihood is:

$$\begin{aligned} Q(\boldsymbol{\theta}, \boldsymbol{\theta}^{\text{old}}) &= \sum_{k=1}^K \mathbb{E}[N_k^1] \log \pi_k + \sum_{j=1}^K \sum_{k=1}^K \mathbb{E}[N_{jk}] \log A_{jk} \\ &\quad + \sum_{i=1}^N \sum_{t=1}^{T_i} \sum_{k=1}^K \sum_{m=1}^{M_k} \gamma_{i,t}(k) \delta_{i,t}(m) \log w_m \\ &\quad + \sum_{i=1}^N \sum_{t=1}^{T_i} \sum_{k=1}^K \sum_{m=1}^{M_k} \gamma_{i,t}(k) \delta_{i,t}(m) \log \mathcal{N}(\mathbf{x}_{it} | \boldsymbol{\mu}_m, \boldsymbol{\Sigma}_m). \end{aligned}$$

E-step:

$$\hat{\delta}_{i,t}(m) = \frac{w_m \mathcal{N}(\mathbf{x}_{it} | \boldsymbol{\mu}_m, \boldsymbol{\Sigma}_m)}{\sum_{m'=1}^M w_{m'} \mathcal{N}(\mathbf{x}_{it} | \boldsymbol{\mu}_{m'}, \boldsymbol{\Sigma}_{m'})}.$$

M-step:

$$\begin{aligned} \hat{w}_m &= \frac{\sum_{i=1}^N \sum_{t=1}^{T_i} \hat{\delta}_{i,t}(m)}{\sum_{i=1}^N \sum_{t=1}^{T_i} 1}. \\ \hat{\boldsymbol{\mu}}_m &= \frac{\sum_{i=1}^N \sum_{t=1}^{T_i} \hat{\delta}_{i,t}(m) \mathbf{x}_{it}}{\sum_{i=1}^N \sum_{t=1}^{T_i} \hat{\delta}_{i,t}(m)}. \\ \hat{\boldsymbol{\Sigma}}_m &= \frac{\sum_{i=1}^N \sum_{t=1}^{T_i} \hat{\delta}_{i,t}(m) (\mathbf{x}_{it} - \hat{\boldsymbol{\mu}}_m)(\mathbf{x}_{it} - \hat{\boldsymbol{\mu}}_m)^T}{\sum_{i=1}^N \sum_{t=1}^{T_i} \hat{\delta}_{i,t}(m)}. \end{aligned}$$