

## Chapter 23. Monte Carlo inference

23.1.

The cdf of a standard Cauchy is given by:

$$F(x) = \frac{1}{\pi} \arctan(x) + \frac{1}{2}.$$

Therefore, we have:

$$F^{-1}(u) = \tan(\pi(u - \frac{1}{2})).$$

Now we sample  $u \sim U(0, 1)$  and get  $x = F^{-1}(u)$ .

23.2.

We have a pdf of a Gamma distribution as:

$$p(x) = Ga(x; a, b) = \frac{b^a}{\Gamma(a)} x^{a-1} e^{-bx}.$$

Now we can derive an unnormalized Gamma distribution by setting  $b = 1$ , to get:

$$\tilde{p}(x) = \frac{1}{\Gamma(a)} x^{a-1} e^{-x}.$$

The Cauchy distribution has density:

$$q(x) = \mathcal{T}(x|\mu, \sigma, 1) = \frac{1}{\pi\sigma(1 + (\frac{x-\mu}{\sigma})^2)}.$$

To get the minimum rejection rate, we have to make two modes the same. We need  $a > 1$  to the mode of  $\tilde{p}(x)$  exist. Now we have:

$$\mu = a - 1$$

Moreover, we should have  $Mq(a-1) = \tilde{p}(a-1)$  to make the bound tightest, to get:

$$M = \frac{1}{\Gamma(a)} \pi \sigma (a-1)^{a-1} e^{-(a-1)}.$$

We should ensure

$$\frac{\tilde{p}(x)}{Mq(x)} = x^{a-1} e^{-x} \left(1 + \left(\frac{x - (a-1)}{\sigma}\right)^2\right) (a-1)^{1-a} e^{a-1} \leq 1.$$

Let

$$r(x) = x^{a-1} e^{-x} \left(1 + \left(\frac{x - (a-1)}{\sigma}\right)^2\right) \propto \frac{\tilde{p}(x)}{Mq(x)}.$$

Then

$$\frac{\partial r(x)}{\partial x} = -\frac{1}{\sigma^2} e^{-x} x^{a-2} (x - (a-1)) ((x-a)^2 + \sigma^2 - (2a-1)).$$

This first derivative must have only one point,  $a-1$ , where it changes its sign, because otherwise it would change its sign at three points, ruining the fact that 1 is the unique global maximum of  $\frac{\tilde{p}(x)}{Mq(x)}$ . Hence we have  $\sigma^2 \geq 2a-1$ .

To maximize  $\frac{\tilde{p}(x)}{Mq(x)}$  with respect to  $\sigma$ , we must minimize  $\sigma$ . Combining these, we can conclude that the optimal value is  $\sigma = \sqrt{2a-1}$ .

23.3.

By equation 4.125 and 4.126,

$$\begin{aligned} p(\mathbf{y}_t | \mathbf{z}_{t-1}) &= \int p(\mathbf{y}_t | \mathbf{z}_t) p(\mathbf{z}_t | \mathbf{z}_{t-1}) d\mathbf{z}_t = \int \mathcal{N}(\mathbf{y}_t | \mathbf{H}_t \mathbf{z}_t, \mathbf{R}_t) \mathcal{N}(\mathbf{z}_t | f_t(\mathbf{z}_{t-1}), \mathbf{Q}_{t-1}) d\mathbf{z}_t \\ &= \mathcal{N}(\mathbf{y}_t | \boldsymbol{\mu}_{\mathbf{y},t}, \boldsymbol{\Sigma}_{\mathbf{y},t}) \\ \boldsymbol{\mu}_{\mathbf{y},t} &= \mathbf{H}_t f_t(\mathbf{z}_{t-1}) \\ \boldsymbol{\Sigma}_{\mathbf{y},t} &= \mathbf{R}_t + \mathbf{H}_t \mathbf{Q}_{t-1} \mathbf{H}_t^T \\ p(\mathbf{z}_t | \mathbf{z}_{t-1}, \mathbf{y}_t) &= \frac{p(\mathbf{y}_t | \mathbf{z}_t) p(\mathbf{z}_t | \mathbf{z}_{t-1})}{p(\mathbf{y}_t | \mathbf{z}_{t-1})} \propto \mathcal{N}(\mathbf{y}_t | \mathbf{H}_t \mathbf{z}_t, \mathbf{R}_t) \mathcal{N}(\mathbf{z}_t | f_t(\mathbf{z}_{t-1}), \mathbf{Q}_{t-1}) \\ &= \mathcal{N}(\mathbf{z}_t | \boldsymbol{\mu}_{\mathbf{z},t}, \boldsymbol{\Sigma}_{\mathbf{z},t}) \\ \boldsymbol{\mu}_{\mathbf{z},t} &= (\mathbf{Q}_t^{-1} + \mathbf{H}_t^T \mathbf{R}_t^{-1} \mathbf{H}_t)^{-1} (\mathbf{H}_t^T \mathbf{R}_t^{-1} \mathbf{y}_t + \mathbf{Q}_t^{-1} f_t(\mathbf{z}_{t-1})) \\ \boldsymbol{\Sigma}_{\mathbf{z},t} &= (\mathbf{Q}_t^{-1} + \mathbf{H}_t^T \mathbf{R}_t^{-1} \mathbf{H}_t)^{-1}. \end{aligned}$$