AD145A4 Datasheet

Zhuhai Jieli Technology Co.,LTD

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AD145A4 Features

CPU Core

- 32-bit CPU,the highest frequency is 160MHz
- Maximum 16KB 4Way ICache, configurable part Way as a common memory for the CPU use or other Peripheral

Memory

- On-chip 32KB SRAM(not including ICache)
- ICache SRAM: 4KB~12KB configurable

Clock Source

- RC Clock frequency about 16MHz
- LRC(low power RC) clock frequency about 32KHz
- HTC(low drift internal high frequency RC)clock frequency is 5MHz

Digital I/O

- 16 programmable digital I/O pins
- USB DP/DM can be configured to normal I/O pins
- General the IO supports
 pull-up(10k),pull-down(60k),
 strong,weak output,input and high
 impedance
- Up to 8 external interrupt/wake-up source(low power available,can be multiplexed to any I/O, with hardware filter)
- Input channel and Output channel, provide arbitrary IO input and output options for some modules

Digital peripherals

One Full Speed USB 1.1 PHY

- Two UART Controllers(UART0/1)
 UART1 supports DMA and Flow Control
- Two SPI Controllers with DMA(SPI0/1) support master mode and slave mode.
- One Spi Flash Controller to run code
- Built-in SPI flash
- I2S audio interface
- Two 16-bit Asynchronous Divider Timers
- One IIC Controller
- Four channel PWM output
- 0.5 watt Class-D audio amplifier output
- Infrared remote control decoder
- Watchdog
- 64-bit EFUSE

Analog Peripherals

- MIC amplifier circuit
- Two analog audio input channels
- 10-bit high precision ADC
- 16-bit high precision ADC (mainly as recording)
- 16-bit high precision DAC
- Low voltage protection
- Power on reset

Operating Conditions

- Working voltage VBAT: 2.0v - 5.5v
 - VDDIO: 2.0v 3.4v
- Operating Temperature: -40°C to +85°C

Package

QSOP24

Application

- Sound Toy
- Audio player

1. Pin Definition

1.1 Pin Assignment

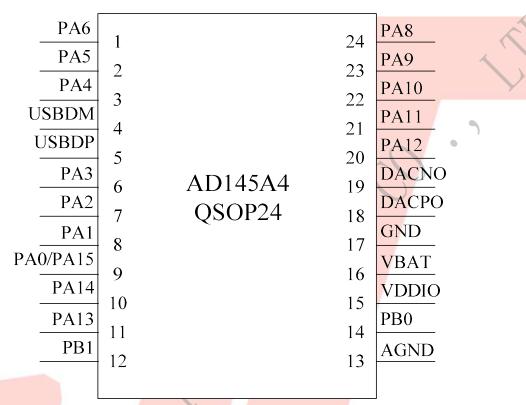


Figure 1-1 AD145A4_QSOP24 Package Diagram

1.2 Pin Description

Table 1-1 AD145A4_QSOP24 Pin Description

PIN NO.	Name	Туре	Drive (mA)	Function	Description
1	PA6	I/O	8/64	GPIO	I2S_MCLK:Audio Link Master Clock; SPI1DIC:SPI1 Data In(C); SD0DATD:SD0 Data(D);
2	PA5	I/O	8/64	GPIO	ADC7:ADC Input Channel 7; SPI0DAT3:SPI0 Data Out3 SPI1DOC:SPI1 Data Out(C); SD0CMDC:SD0 Command(C); SD0CMDD:SD0 Command(D); UART0RXA:Uart0 Data In(A); I2C_SDA(C); PWM1:PWM Channel1 Output;
3	PA4	I/O	8/64	GPIO	ADC6:ADC Input Channel 6; SPI0DAT2:SPI0 Data 2; SPI1CLKC:SPI1 Clock(C); SD0CLKC:SD0 Clock(C); SD0CLKD:SD0 Clock(D); UART0TXA:Uart0 Data Out(A); I2C_SCL(C); TMR2:Timer2 Clock In; PWM0:PWM Channel0 Output;
4	USBDM	I/O	10	USB Negative Data (pull down)	ADC5:ADC Input Channel 5; SPI1DOA:SPI1 Data Out(A); SD0DATC:SD0 Data(C); UART1TXA:Uart1 Data Out(A); I2C_SDA(A);
5	USBDP	I/O	10	USB Positive Data (pull down)	ADC4:ADC Input Channel 4; SPI1CLKA:SPI1 Clock(A); UART1RXA:Uart1 Data In(A); I2C_SCL(A);
6	PA3	I/O	8/64	GPIO	ADC3:ADC Input Channel 3; SPI0DIB(1):SPI0 Data1 In(B); SPI1DIA:SPI1 Data In(A); SD0DATA:SD0 Data(A); PWM2L; MCAP0:Motor Timer0 Capture;

	T		-	T	1
					ADC2:ADC Input Channel 2;
_	D. 0	T/0	0/64	GD10	SPI0DOB(0):SPI0 Data0 Out(B);
7	PA2	I/O	8/64	GPIO	SD0CMDA:SD0 Command(A);
				I2C_SDA(B);	
					PWM2H;
					ADC1:ADC Input Channel 1;
					SPIOCLKB:SPIO Clock(B);
8	PA1	I/O	8/64	GPIO	SD0CLKA:SD0 Clock(A);
			/		UART0RXB:Uart0 Data In(B); I2C SCL(B);
					CAP2:Timer2 Capture;
					Long Press Reset;
	PA0	I/O	8/64	GPIO	ADC0:ADC Input Channel 0;
9	1710		0/01	(pull up)	UARTOTXB: Uart0 Data Out(B);
					ADC12:ADC Input Channel 12;
	PA15	I/O	8/64	GPIO	MIC LDO:Microphone Power Output;
					ADC11:ADC Input Channel 11;
10	PA14	I/O	8/64	GPIO	AUX1:Analog Channel 1 Input;
					ADC10:ADC Input Channel 10;
,,	11 PA13	1/0	0/64	GPIO	AUX0:Analog Channel 0 Input;
11		I/O	8/64		MIC_BIAS:Microphone Bias Output;
			/		CAP0:Timer0 Capture
12	PB1	I/O	8/64	GPIO	MIC_IN: MIC Input Channel;
13	AGND	G	/		Analog Ground;
1			//	Y	DAC:Analog Audio Output;
14	PB0	I/O	8/64	GPIO	ADC13:ADC Input Channel 13;
			Y		LVD:Low Voltage Detect;
15	VDDIO	P	1		GPIO Power;
16	VBAT /	P	/		Battery Power Supply;
17	GND	G	/		Digital Ground;
18	DACPO	O	1		Class-D APA Positive Output;
19, 4	DACNO	О	/		Class-D APA Negative Output;
					I2S_LRCK:Audio Link Word Select:
20	DA 12	I/O	0/61	CDIO	SPI1DOB:SPI1 Data Out(B);
20	20 PA12 I/O 8/64		GPIO	SD0CMDB:SD0 Command(B);	
) ×					MCAP3:Motor Timer3 Capture;
					ADC9:ADC Input Channel 9;
					I2S_SCLK:Audio Link Serial Clock;
21	PA11	I/O	8/64	GPIO	SPI1CLKB:SPI1 Clock(B);
					SD0CLKB:SD0 Clock(B);
					MCAP2:Motor Timer2 Capture;

22	PA10	I/O	8/64	GPIO	ADC8:ADC Input Channel 8; I2S_DAT3:Audio Link Data3; SPI1DIB:SPI1 Data In(B); SD0DATB:SD0 Data(B); TMR1:Timer1 Clock In; MCAP1:Motor Timer1 Capture;
23	PA9	I/O	8	GPIO (High Voltage Resistance)	I2S_DAT2:Audio Link Data2; UART1TXB:Uart1 Data Out(B); UART1RXB:Uart1 Data In(B); I2C_SDA(D); CAP1:Timer1 Capture; PWM3:PWM Channel3 Output;
24	PA8	I/O	8	GPIO (High Voltage Resistance)	I2S_DAT1:Audio Link Data1; I2C_SCL(D); TMR0:Timer0 Clock In; PWM2:PWM Channel2 Output; OSCI:Crystal Oscillator Input;

2, Electrical Characteristics

2.1 Absolute Maximum Ratings

Table 2-1

Symbol	Parameter	Min	Max	Unit
Tamb	Ambient Temperature	-40	+85	°C
Tstg	Storage temperature	-65	+150	°C
VBAT	Supply Voltage	-0.3	5.5	V
V _{VDDIO33}	3.3V IO Input Voltage	-0.3	3.6	V

Note: The chip can be damaged by any stress in excess of the absolute maximum ratings listed below

2.2 PMU Characteristics

Table 2-2

Symbol	Parameter	Min	Тур	Max	Unit	Test Conditions
VBAT	Voltage Input	2.0	3.7	5.5	V	_
V_{VDDIO}	Voltage output	2.0	3.0	3.4	V	VBAT = 3.7V, 100mA loading
I_{VDDIO}	Loading current	_/	<u></u>	100	mA	VBAT=3.7V

2.3 IO Input/Output Electrical Logical Characteristics

Table 2-3

IO input ch	aracteristics					
Symbol	Parameter	Min	Тур	Max	Unit	Test Conditions
V_{IL}	Low-Level Input Voltage	-0.3	_	0.3* VDDIO	V	VDDIO = 3.3V
$V_{ m IH}$	High-Level Input Voltage	0.7* VDDIO	-	VDDIO+0.3	V	VDDIO = 3.3V
IO output c	haracteristics					
V_{OL}	Low-Level Output Voltage	_	_	0.33	V	VDDIO = 3.3V
$ m V_{OH}$	High-Level Output Voltage	2.7	_	_	V	VDDIO = 3.3V

2.4 Internal Resistor Characteristics

Table 2-4

Port	General Output	High Drive	Internal Pull-Up Resistor	Internal Pull-Down Resistor	Comment
PA0~PA6、 PA10~PA15、 PB0、PB1	8mA	64mA	10K	60K	1、PA0 default pull up 2、USBDM & USBDP
PA8、PA9 (high voltage I/O)	8mA	-	10K	60K	default pull down 3 vinternal pull-up/pull-down
USBDP	10mA	-	1.5K	15K	resistance accuracy ±20%
USBDM	10mA	_	180K	15K	

2.5 Analog DAC(PB0) Characteristics

Table 2-5

Parameter	Min	Тур	Max	Unit	Test Conditions
Frequency Response	20	4	16K	Hz	1KHz/0dB
THD+N	4	-65	_	dB	
S/N		95	_	dB	100kohm loading
Output Swing		0.54	_	Vrms	With A-Weighted Filter
		7.1		7	1KHz/-60dB
Dynamic Range	_	92	-	dB	100kohm loading
	<u>)</u>	7			With A-Weighted Filter
Output Resistance	_	8.3	_	K	_

2.6 ADC Characteristics

Table 2-6

Parameter	Min	Тур	Max	Unit	Test Conditions
Dynamic Range	_	75	_	dB	1KHz/210mVrms
S/N	_	79	_	dB	line mode :6dB with cap
THD+N	_	-70	_	dB	PGAIS=2

3. Package Information

3.1 QSOP24

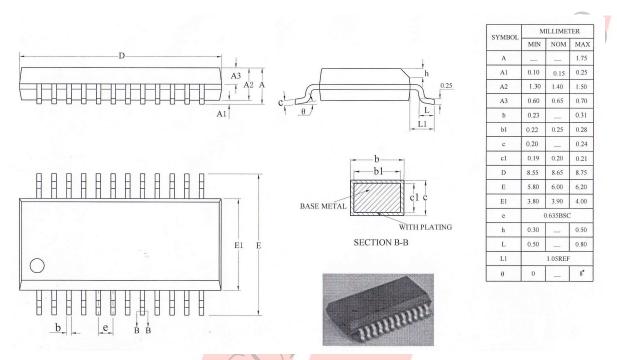


Figure 3-1. AD145A4_QSOP24 Package

4. Revision History

Date	Revision	Description
2021.03.09	V1.0	Initial Release

