# AD156B Datasheet

# Zhuhai Jieli Technology Co.,LTD

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## **AD156B Features**

#### **CPU Core**

- 32-bit CPU,Built-in ICACH, can be connected to Flash for expansion of code
- The main frequency is up to 120MHz

#### Memory

Built-in 20Kbytes of SRAM

#### **Clock Source**

- RC Clock frequency about 16MHz
- LRC( low power RC) clock frequency about 200KHz

#### Digital I/O

- Up to 28 programmable digital I/O pins
- General the IO supports
  pull-up(10k),pull-down(60k),
  strong,weak output,input and high
  impedance
- Up to 12 external interrupt/wake-up source(low power available, can be multiplexed to any I/O, with hardware filter)
- Input channel and Output channel, provide arbitrary IO input and output options for some modules

#### Digital peripherals

- Two UART Controllers(UART0/1) supports DMA and Flow Control
- Two SPI Controllers with DMA(SPI0/1)

support master mode and slave mode,SPI0 support 4bit,SPI1support 2bit

- Built-in Flash for code
- One SD host controller
- Three 32-bit Asynchronous Divider Timers
- One IIC Controller
- Four channel PWM output
- Infrared remote control decoder
- Watchdog

#### **Analog Peripherals**

- 0.5 watt Class-D audio amplifier output
- 14 channel 10-bit high precision ADC
- Low voltage protection
- Power on reset

### **Operating Conditions**

- Working voltage
  - VBAT: 2.0v 5.5v
  - VDDIO: 2.0v 3.4v
- Operating Temperature: -40°C to +85°C

#### Package

QFN32(4mm\*4mm)

#### **Application**

- Sound Toy
- Universal Microcontroller
- Bluetooth TWS charging Box
- Audio player

## 1. Pin Definition

### 1.1 Pin Assignment

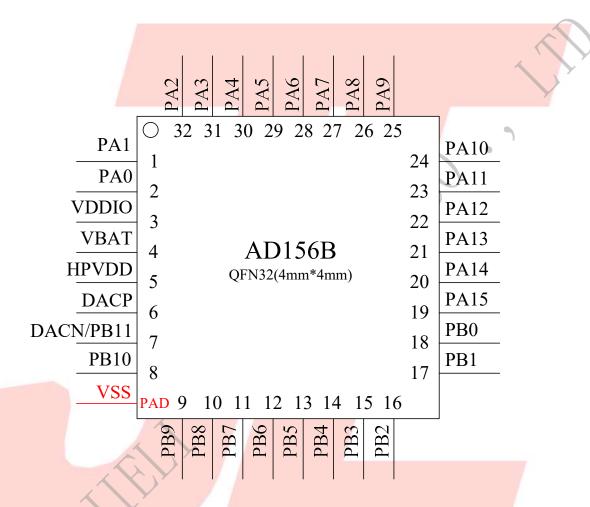


Figure 1-1 AD156B QFN32 Package Diagram

## 1.2 Pin Description

Table 1-1 AD156B\_QFN32 Pin Description

PIN	Name	Туре	Drive	Function	Description
NO.	1,02110	1717	(mA)	1 0/110 11	Storiputer
1	PA1	I/O	8/64	GPIO	ADC1:ADC Input Channel 1; SPI0CLKB:SPI0 Clock(B); SD0CLKA:SD0 Clock(A); UART0RXB:Uart0 Data In(B); I2C_SCL(B); CAP2:Timer2 Capture;
2	PA0	I/O	8/64	GPIO (pull up)	Long Press Reset; ADC0:ADC Input Channel 0; UART0TXB:Uart0 Data Out(B);
3	VDDIO	P	/		Digital Power; (Internal linear regulator output)
4	VBAT	P	/		Battery Power Supply;
5	HPVDD	Р	/		Class-D APA Power Supply;
6	DACP	О	/	47	Class-D APA Positive Output;
	DACN	О	/		Class-D APA Negative Output;
7	PB11	I/O	8	GPIO (High Voltage Resistance)	OSCIB:Crystal Oscillator Input(B);
8	PB10	I/O	8	GPIO (pull up) (High Voltage Resistance)	MCLR(0 effective);
9	PB9	I/O	8	GPIO (High Voltage Resistance)	SPI1DOD:SPI1 Data Out(D); UART1TRXB:Uart1 Data In/Out(B); I2C_SDA(D); CAP1:Timer1 Capture;
10	PB8	I/O	8	GPIO (High Voltage Resistance)	SPI1CLKD:SPI1 Clock(D); I2C_SCL(D); OSCIA:Crystal Oscillator Input(A);
11	PB7	I/O	8/64	GPIO	SPI1DID:SPI1 Data In(D);
12	PB6	I/O	8/64	GPIO	SD0DATC:SD0 Data(C);
13	PB5	I/O	8/64	GPIO	ADC13:ADC Input Channel 13; SD0CMDC:SD0 Command(C);
14	PB4	I/O	8/64	GPIO	ADC12:ADC Input Channel 12; SD0CLKC:SD0 Clock(C);

15	PB3	I/O	8/64	GPIO	TDM_MCLK;		
					SPI1DIA:SPI1 Data In(A);		
16	PB2	I/O	8/64	GPIO	SD0DATB:SD0 Data(B);		
					TDM DAT;		
					ADC11:ADC Input Channel 11;		
					SPI1DOA:SPI1 Data Out(A);		
17	PB1	I/O	8/64	GPIO	SD0CMDB:SD0 Command(B);		
				(pull down)	I2C SDA(A);		
					TDM SYN;		
					ADC10:ADC Input Channel 10;		
					SPI1CLKA:SPI1 Clock(A);		
18	PB0	I/O	8/64	GPIO	SD0CLKB:SD0 Clock(B);		
				(pull down)	I2C SCL(A);		
				/	TDM_CLK;		
				/	ADC9:ADC Input Channel 9;		
19	PA15	I/O	8/64	GPIO	SPI1DOB:SPI1 Data Out(B);		
					MCAP3:Motor Timer3 Capture;		
	PA14	I/O	8/64	GPIO	ADC8:ADC Input Channel 8;		
20					SPI1CLKB:SPI1 Clock(B);		
20					CAP0:Timer0 Capture;		
					MCAP2:Motor Timer2 Capture;		
			1		SPI1DIB:SPI1 Data In(B);		
21	PA13	I/O	8/64	GPIO )	TMR1:Timer1 Clock In;		
					MCAP1:Motor Timer1 Capture;		
22	PA12	I/O	8/64	GPIO	MPWM3:PWM Channel3 Output;		
22	DA 11	1/0	0/64	CDIO	TMR0:Timer0 Clock In;		
23	PA11	I/O	8/64	GPIO	MPWM2:PWM Channel2 Output;		
24	PA10	I/O	8/64	GPIO	7		
25	PA9	I/O	8/64	GPIO			
	D. ( )	1/2	0/51	anua.	SPI1DIC:SPI1 Data In(C);		
26	PA8	I/O	8/64	GPIO	SD0DATD:SD0 Data(D);		
4					ADC7:ADC Input Channel 7;		
	PA7	( )	I/O 8/64	GPIO	SPI1DOC:SPI1 Data Out(C);		
27		I/O			SD0CMDD:SD0 Command(D);		
		I/O			UART0RXA:Uart0 Data In(A);		
					I2C_SDA(C);		
					MPWM1:PWM Channell Output;		

28	PA6	I/O	8/64	GPIO	ADC6:ADC Input Channel 6; SPI1CLKC:SPI1 Clock(C); SD0CLKD:SD0 Clock(D); UART0TXA:Uart0 Data Out(A); I2C SCL(C);
					TMR2:Timer2 Clock In; MPWM0:PWM Channel0 Output;
29	PA5	I/O	8/64	GPIO	ADC5:ADC Input Channel 5; SPI0DAT3:SPI0 Data 3 UART1RXA:Uart1 Data In(A);
30	PA4	I/O	8/64	GPIO	ADC4:ADC Input Channel 4; SPI0DAT2:SPI0 Data 2; UART1TXA:Uart1 Data Out(A); LVD:Low Voltage Detect;
31	PA3	I/O	8/64	GPIO	ADC3:ADC Input Channel 3; SPI0DIB(1):SPI0 Data1 In(B); SD0DATA:SD0 Data(A); CLKOUT; PWM2(A); MCAP0:Motor Timer0 Capture;
32	PA2	I/O	8/64	GPIO	ADC2:ADC Input Channel 2; SPI0DOB(0):SPI0 Data0 Out(B); SD0CMDA:SD0 Command(A); I2C_SDA(B); PWM2(B);
PAD	VSS	G			Ground;

## 2, Electrical Characteristics

## 2.1 Absolute Maximum Ratings

Table 2-1

Symbol	Parameter	Min	Max	Unit
Tamb	Ambient Temperature	-40	+85	°C
Tstg	Storage temperature	-65	+150	°C
VBAT	Supply Voltage	-0.3	5.5	V
HPVDD	Class D Audio Power Amplifier	-0.3	5.5	V
V <sub>VDDIO33</sub>	3.3V IO Input Voltage	-0.3	3.6	V

Note: The chip can be damaged by any stress in excess of the absolute maximum ratings listed below

### 2.2 PMU Characteristics

Table 2-2

Symbol	Parameter	Min	Тур	Max	Unit	Test Conditions
VBAT	Voltage Input	2.0	3.7	5.5	V	_
$V_{\mathrm{VDDIO}}$	Voltage output	2.0	3.0	3.4	V	VBAT = 3.7V, 100mA loading
I <sub>VDDIO</sub>	Loading current	- /	· //	100	mA	VBAT=3.7V

## 2.3 IO Input/Output Electrical Logical Characteristics

Table 2-3

IO input characteristics									
Symbol	ymbol Parameter		Тур	Max	Unit	Test Conditions			
V <sub>IL</sub>	Low-Level Input Voltage	-0.3	I	0.3* VDDIO	V	VDDIO = 3.3V			
$V_{ m IH}$	High-Level Input Voltage	0.7* VDDIO	I	VDDIO+0.3	V	VDDIO = 3.3V			
IO output c	IO output characteristics								
V <sub>OL</sub>	Low-Level Output Voltage	_	_	0.33	V	VDDIO = 3.3V			
$V_{\mathrm{OH}}$	High-Level Output Voltage	2.7	ı	-	V	VDDIO = 3.3V			

## 2.4 Internal Resistor Characteristics

Table 2-4

Port	General Output	High Drive	Internal Pull-Up Resistor	Internal Pull-Down Resistor	Comment
PA0~PA15 PB0~PB7	8mA	64mA	10K	60K	1、PA0&PB10 default pull up 2、PB0 & PB1 default pull down
PB8~PB11	8mA	-	10K	60K	3 internal pull-up/pull-down resistance   accuracy ±20%



## 3. Package Information

### 3.1 QFN32

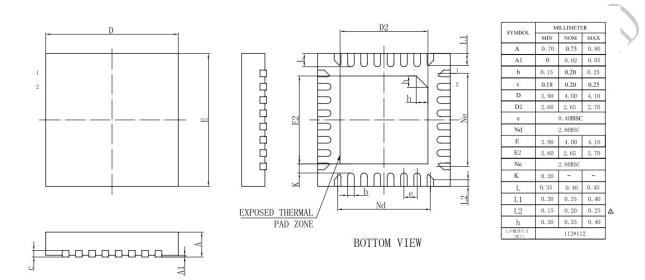
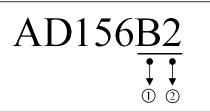


Figure 3-1. AD156B\_QFN32 Package

## 4. Package Type Specification



- ①Represents different packages
- ②Represents different memory sizes
  - 0: No memory
  - 2: 2Mbit Flash
  - 4: 4Mbit Flash
  - 8: 8Mbit Flash

# 5. Revision History

Date	Revision	<b>Y</b>	<b>Des</b> cription	
2021.05.18	V1.0	Initial Release		/
		7.1		