# AD154 Datasheet

# Zhuhai Jieli Technology Co.,LTD

Version: V1.0

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### **AD154 Features**

#### **CPU Core**

- 32-bit CPU,Built-in ICACH, can be connected to Flash for expansion of code
- The main frequency is up to 120MHz

#### Memory

- Built-in 28Kbytes of SRAM
- 8Kbytes 2-Way Icache

#### Clock Source

- RC Clock frequency about 16MHz
- LRC( low power RC) clock frequency about 200KHz

### Digital I/O

- Up to 28 programmable digital I/O pins
- General the IO supports
  pull-up(10k),pull-down(60k),
  strong,weak output,input and high
  impedance
- Up to 12 external interrupt/wake-up source(low power available, can be multiplexed to any I/O, with hardware filter)
- Input channel and Output channel, provide arbitrary IO input and output options for some modules

#### Digital peripherals

- Two UART Controllers(UART0/1) supports DMA and Flow Control
- Two SPI Controllers with DMA(SPI0/1)

- support master mode and slave mode,SPI0 support 4bit,SPI1support 2bit
- One Spi Flash Controller to run code
- One SD host controller
- Three 32-bit Asynchronous Divider Timers
- One IIC Controller
- Four channel PWM output
- Infrared remote control decoder
- Watchdog
- 64-bit EFUSE

#### **Analog Peripherals**

- 0.5 watt Class-D audio amplifier output
- 14 channel 10-bit high precision ADC
- Low voltage protection
- Power on reset

#### **Operating Conditions**

- Working voltage
  - VBAT: 2.0v 5.5v
  - HPVDD: 2.0v 5.5v
  - VDDIO: 2.0v 3.4v
- Operating Temperature: -40°C to +85°C

### Package

LQFP48(7mm\*7mm)

#### **Application**

- Sound Toy
- Audio player

### 1. Pin Definition

### 1.1 Pin Assignment

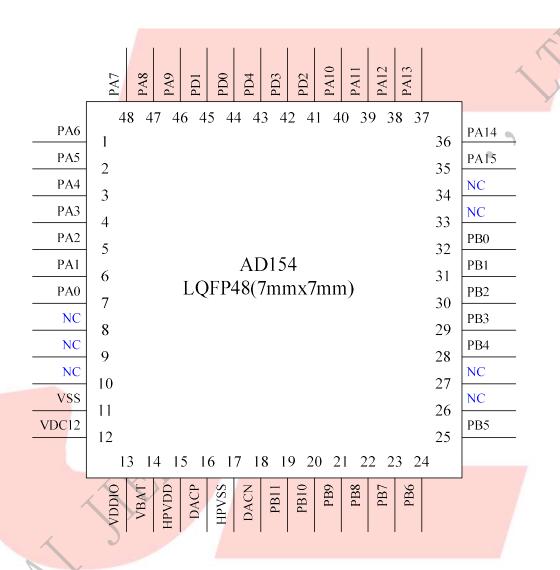


Figure 1-1 AD154\_LQFP48 Package Diagram

### 1.2 Pin Description

Table 1-1 AD154\_LQFP48 Pin Description

PIN NO.	Name	Туре	Drive (mA)	Function	Description
1	PA6	I/O	8/64	GPIO	ADC6:ADC Input Channel 6; SPI1CLKC:SPI1 Clock(C); SD0CLKD:SD0 Clock(D); UART0TXA:Uart0 Data Out(A); I2C_SCL(C); TMR2:Timer2 Clock In; PWM0:PWM Channel0 Output;
2	PA5	I/O	8/64	GPIO	ADC5:ADC Input Channel 5; SPI0DAT3:SPI0 Data 3 UART1RXA:Uart1 Data In(A);
3	PA4	I/O	8/64	GPIO	ADC4:ADC Input Channel 4; SPI0DAT2:SPI0 Data 2; UART1TXA:Uart1 Data Out(A); LVD:Low Voltage Detect;
4	PA3	I/O	8/64	GPIO	ADC3:ADC Input Channel 3; SPI0DIB(1):SPI0 Data1 In(B); SD0DATA:SD0 Data(A); CLKOUT; PWM2L; MCAP0:Motor Timer0 Capture;
5	PA2	I/O	8/64	GPIO	ADC2:ADC Input Channel 2; SPI0DOB(0):SPI0 Data0 Out(B); SD0CMDA:SD0 Command(A); I2C_SDA(B); PWM2H;
6	PA1	I/O	8/64	GPIO	ADC1:ADC Input Channel 1; SPI0CLKB:SPI0 Clock(B); SD0CLKA:SD0 Clock(A); UART0RXB:Uart0 Data In(B); I2C_SCL(B); CAP2:Timer2 Capture;
7	PA0	I/O	8/64	GPIO (pull up)	Long Press Reset; ADC0:ADC Input Channel 0; UART0TXB:Uart0 Data Out(B);
8	NC	_	_		_

10 NC	9	NC				
11			_	_		<u> </u>
12	-					Digital Ground
13	-			,		,
13	12	VDC12	1	/		
14	13	VDDIO	P	/		
15	14	VBAT	P	/		
16    DACP	-					
17						11.0
DACN   O			A	/		•
PB11	-			/		
PB11		Brier		,	GPIO	Class Billittegative curput,
Resistance     GPIO	19	PB11	I/O	8	A	OSCIB:Crystal Oscillator Input(B);
PB10					, ,	
PB10					GPIO	
PB9	20	DD 10	I/O	0	(pull up)	MCI D(0 off otiva)
PB9	20	PB10	1/O	8	(High Voltage	MCLR(0 enective);
PB9					Resistance)	
PB9					GPIO	SPI1DOD:SPI1 Data Out(D);
Resistance   I2C_SDA(D);   CAP1:Timer1 Capture;	21	PR0	I/O	8		UART1TRXB:Uart1 Data In/Out(B);
CAPI: Imer   Capture;   CAPI: Imer   Capture;	21	10)	1/0	Ö		I2C_SDA(D);
22         PB8         I/O         8         (High Voltage Resistance)         I2C_SCL(D); OSCIA:Crystal Oscillator Input(A);           23         PB7         I/O         8/64         GPIO         SPI1DID:SPI1 Data In(D);           24         PB6         I/O         8/64         GPIO         SD0DATC:SD0 Data(C);           25         PB5         I/O         8/64         GPIO         ADC13:ADC Input Channel 13; SD0CMDC:SD0 Command(C);           26         NC         _         _         _           27         NC         _         _           28         PB4         I/O         8/64         GPIO         ADC12:ADC Input Channel 12; SD0CLKC:SD0 Clock(C);           29         PB3         I/O         8/64         GPIO         TDM_MCLK;           30         PB2         I/O         8/64         GPIO         SPI1DIA:SPI1 Data In(A); SD0DATB:SD0 Data(B);					(CSISTATICE)	CAP1:Timer1 Capture;
Resistance)         OSCIA:Crystal Oscillator Input(A);           23         PB7         I/O         8/64         GPIO         SPI1DID:SPI1 Data In(D);           24         PB6         I/O         8/64         GPIO         SD0DATC:SD0 Data(C);           25         PB5         I/O         8/64         GPIO         ADC13:ADC Input Channel 13; SD0CMDC:SD0 Command(C);           26         NC         _         _         _           27         NC         _         _           28         PB4         I/O         8/64         GPIO         ADC12:ADC Input Channel 12; SD0CLKC:SD0 Clock(C);           29         PB3         I/O         8/64         GPIO         TDM_MCLK;           30         PB2         I/O         8/64         GPIO         SD0DATB:SD0 Data(B);					GPIO	SPI1CLKD:SPI1 Clock(D);
23         PB7         I/O         8/64         GPIO         SPI1DID:SPI1 Data In(D);           24         PB6         I/O         8/64         GPIO         SD0DATC:SD0 Data(C);           25         PB5         I/O         8/64         GPIO         ADC13:ADC Input Channel 13; SD0CMDC:SD0 Command(C);           26         NC         _         _         _           27         NC         _         _           28         PB4         I/O         8/64         GPIO         ADC12:ADC Input Channel 12; SD0CLKC:SD0 Clock(C);           29         PB3         I/O         8/64         GPIO         TDM_MCLK;           30         PB2         I/O         8/64         GPIO         SD0DATB:SD0 Data(B);	22	PB8	I/O	8		I2C_SCL(D);
24         PB6         I/O         8/64         GPIO         SD0DATC:SD0 Data(C);           25         PB5         I/O         8/64         GPIO         ADC13:ADC Input Channel 13; SD0CMDC:SD0 Command(C);           26         NC         _         _         _           27         NC         _         _           28         PB4         I/O         8/64         GPIO         ADC12:ADC Input Channel 12; SD0CLKC:SD0 Clock(C);           29         PB3         I/O         8/64         GPIO         TDM_MCLK;           30         PB2         I/O         8/64         GPIO         SD0DATB:SD0 Data(B);	1				Resistance)	OSCIA:Crystal Oscillator Input(A);
25         PB5         I/O         8/64         GPIO         ADC13:ADC Input Channel 13; SD0CMDC:SD0 Command(C);           26         NC	23	PB7	I/O	8/64	GPIO	SPI1DID:SPI1 Data In(D);
25 PB5 I/O 8/64 GPIO SD0CMDC:SD0 Command(C);  26 NC	24	PB6	I/O	8/64	GPIO	SD0DATC:SD0 Data(C);
SD0CMDC:SD0 Command(C);   26	25	PR5	I/O	8/64	GPIO	ADC13:ADC Input Channel 13;
26 NC	23	1 1 1 2 3		0/01	GHO	SD0CMDC:SD0 Command(C);
28         PB4         I/O         8/64         GPIO         ADC12:ADC Input Channel 12; SD0CLKC:SD0 Clock(C);           29         PB3         I/O         8/64         GPIO         TDM_MCLK; SPI1 Data In(A); SPI1DIA:SPI1 Data In(A); SD0DATB:SD0 Data(B);           30         PB2         I/O         8/64         GPIO         SD0DATB:SD0 Data(B);	26	NC	-	_		_
28 PB4 I/O 8/64 GPIO SD0CLKC:SD0 Clock(C);  29 PB3 I/O 8/64 GPIO TDM_MCLK;  SPI1DIA:SPI1 Data In(A);  SD0DATB:SD0 Data(B);	27	NC	_	_		_
SD0CLKC:SD0 Clock(C);  29 PB3 I/O 8/64 GPIO TDM_MCLK;  SPI1DIA:SPI1 Data In(A);  SD0DATB:SD0 Data(B);	28	PR/I	I/O	8/6/	GPIO	ADC12:ADC Input Channel 12;
30 PB2 I/O 8/64 GPIO SD0DATB:SD0 Data(B);	20	I D4	1/0	0/04	GHO	SD0CLKC:SD0 Clock(C);
30 PB2 I/O 8/64 GPIO SD0DATB:SD0 Data(B);	29	PB3	I/O	8/64	GPIO	TDM_MCLK;
	) >					SPI1DIA:SPI1 Data In(A);
TDM_DAT;	30	PB2	I/O	8/64	GPIO	SD0DATB:SD0 Data(B);
<u> </u>						TDM_DAT;

	1			r	
					ADC11:ADC Input Channel 11; SPI1DOA:SPI1 Data Out(A);
31	PB1	I/O	8/64	GPIO	SD0CMDB:SD0 Command(B);
		1, 0	0,01	(pull down)	I2C SDA(A);
					TDM SYN;
					ADC10:ADC Input Channel 10;
					SPI1CLKA:SPI1 Clock(A);
32	PB0	I/O	8/64	GPIO	SD0CLKB:SD0 Clock(B);
32	I Bo		0,01	(pull down)	I2C SCL(A);
					TDM CLK;
33	NC	4		7	
34	NC	_			
		_	_		ADC9:ADC Input Channel 9;
35	PA15	I/O	8/64	GPIO	SPI1DOB:SPI1 Data Out(B);
		1/0	0,0.		MCAP3:Motor Timer3 Capture;
					ADC8:ADC Input Channel 8;
		4 I/O	8/64	GPIO	SPI1CLKB:SPI1 Clock(B);
36	PA14				CAP0:Timer0 Capture;
					MCAP2:Motor Timer2 Capture;
				1	SPI1DIB:SPI1 Data In(B);
37	PA13	I/O	8/64	GPIO	TMR1:Timer1 Clock In;
					MCAP1:Motor Timer1 Capture;
38	PA12	I/O	8/64	GPIO	PWM3:PWM Channel3 Output;
					TMR0:Timer0 Clock In;
39	PA11	I/O	8/64	GPIO	PWM2:PWM Channel2 Output;
40	PA10	I/O	8/64	GPIO	1
				GPIO	SPI0CSA:SPI0 Chip Select(A);
41	PD2	I/O	8/64	(pull up)	SFCCSA:SFC Chip Select(A);
V			Y		SPI0DIA(1):SPI0 Data1 In(A);
42	42 PD3	I/O	8/64	GPIO	SFCDIA(1):SFC Data1 In(A);
43	PD4	I/O	8/64	GPIO	Flash Power Gate;
44.5	200	1/0	0/64	CDIO	SPI0CLKA:SPI0 Clock(A);
44	PD0	I/O	8/64	GPIO	SFCCLKA:SFC Clock(A);
	DD 1	1/0	0/54	CDIO	SPI0DOA(0):SPI0 Data0 Out(A);
45	PD1	I/O	8/64	GPIO	SFCDOA(0):SFC Data0 Out(A);
46	PA9	I/O	8/64	GPIO	
47	DAG	1/0	0/64	CDIC	SPI1DIC:SPI1 Data In(C);
47	PA8	I/O	8/64	GPIO	SD0DATD:SD0 Data(D);
	<u> </u>	l	<u> </u>	l	· //

48	PA7	I/O	8/64	GPIO	ADC7:ADC Input Channel 7; SPI1DOC:SPI1 Data Out(C); SD0CMDD:SD0 Command(D); UART0RXA:Uart0 Data In(A); I2C_SDA(C); PWM1:PWM Channel1 Output;
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### 2, Electrical Characteristics

### 2.1 Absolute Maximum Ratings

Table 2-1

Symbol	Parameter	Min	Max	Unit
Tamb	Ambient Temperature	-40	+85	°C
Tstg	Storage temperature	-65	+150	°C
VBAT	Supply Voltage	-0.3	5.5	V
HPVDD	Class D Audio Power Amplifier	-0.3	5.5	V
V <sub>VDDIO33</sub>	3.3V IO Input Voltage	-0.3	3.6	V

Note: The chip can be damaged by any stress in excess of the absolute maximum ratings listed below

### 2.2 PMU Characteristics

Table 2-2

Symbol	Parameter	Min	Тур	Max	Unit	Test Conditions
VBAT	Voltage Input	2.0	3.7	5.5	V	_
V <sub>HPVDD</sub>	Voltage Input	2.0	3.7	5.5	V	_
V <sub>VDDIO</sub>	Voltage output	2.0	3.0	3.4	V	VBAT = 3.7V, 100mA loading
V <sub>VDC12</sub>	Voltage output	1.05	1.2	1.4	V	VBAT=3.7V
I <sub>VDDIO</sub>	Loading current	<b>\</b> _	_//	100	mA	VBAT=3.7V

### 2.3 IO Input/Output Electrical Logical Characteristics

Table 2-3

IO input ch	aracteristics					
Symbol	Parameter	Min	Тур	Max	Unit	Test Conditions
$V_{IL}$	Low-Level Input Voltage	-0.3	İ	0.3* VDDIO	V	VDDIO = 3.3V
$V_{ m IH}$	High-Level Input Voltage	0.7* VDDIO	ı	VDDIO+0.3	V	VDDIO = 3.3V
IO output c	haracteristics					
Vol	Low-Level Output Voltage	-	_	0.33	V	VDDIO = 3.3V
$V_{\mathrm{OH}}$	High-Level Output Voltage	2.7	_	-	V	VDDIO = 3.3V

### 2.4 Internal Resistor Characteristics

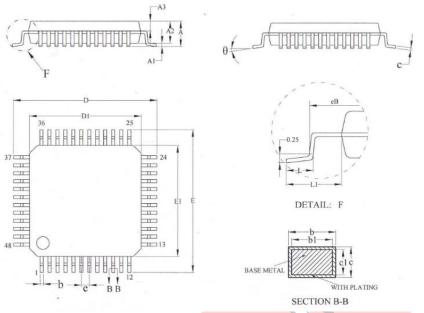
Table 2-4

Port	General Output	High Drive	Internal Pull-Up Resistor	Internal Pull-Down Resistor	Comment
PA0~PA15 PB0~PB7 PD0~PD4	8mA	64mA	10K	60K	1、PA0,PB10,PD2 default pull up 2、PB0 & PB1 default pull down 3、internal pull-up/pull-down
PB8~PB11	8mA	_	10K	60K	resistance   accuracy ±20%



## 3. Package Information

### 3.1 LQFP48(7mm\*7mm)



SYMBOL	M	ILLIMET	ER		
SYMBOL	MIN	NOM	MAX		
Α	_	_	1.60		
A1	0.05		0.15		
A2	1.35	1.40	1.45		
A3	0.59	0.64	0.69		
b	0.18	-	0.26		
b1	0.17	0.20	0.23		
с	0.13	_	0.17		
c1	0.12	0.13	0.14		
D	8.80	9.00	9.20		
D1	6.90	7.00	7.10		
Е	8.80	9.00	9.20		
E1	6.90	7.00	7.10		
eB	8.10	-	8.25		
e	(	).50BS0	2		
L	0.40	-	0.65		
L1	1.00REF				
θ	0	_	7		

Figure 3-1. AD154\_LQFP48 Package

## 4. Revision History

Date	Revision	Description
2021.03.23	V1.0	Initial Release
		<u> </u>

