SHENYUAN GAO

2nd-year Ph.D. student at HKUST

Homepage: github.com/Little-Podi ♦ Email: sygao@connect.ust.hk

EDUCATION

Hong Kong University of Science and Technology

2022 - 2026 (expected)

Ph.D. in Electronic and Computer Engineering Advised by Prof. Jun Zhang (IEEE Fellow)

Huazhong University of Science and Technology

2018 - 2022

B.Eng. in Electronic Information Engineering Advanced Class (Elite Program for Information Science, 30/400) GPA: 3.9/4.0 Rank: 1/30

RESEARCH INTEREST

Embodied AI Autonomous Driving, Generalist Robot, Real-World Decision Making **Generative AI** World Models, Diffusion Models, Vision-Language Foundation Models

PUBLICATION

Vista: A Generalizable Driving World Model with High Fidelity and Versatile Controllability

Shenyuan Gao, Jiazhi Yang, Li Chen, Kashyap Chitta, Yihang Qiu, Andreas Geiger, Jun Zhang, Hongyang Li [Paper] [Demo] [Code] (300+ stars within 2 weeks)

Generalized Predictive Model for Autonomous Driving

Jiazhi Yang*, **Shenyuan Gao***, Yihang Qiu*, Li Chen, Tianyu Li, Bo Dai, Kashyap Chitta, Penghao Wu, Jia Zeng, Ping Luo, Jun Zhang, Andreas Geiger, Yu Qiao, Hongyang Li Accepted by CVPR 2024 as *Highlight* (**Top 2.8%**).

[Paper] [Dataset]

Generalized Relation Modeling for Transformer Tracking

Shenyuan Gao, Chunluan Zhou, Jun Zhang

Accepted by CVPR 2023.

[Paper] [Code]

AiATrack: Attention in Attention for Transformer Visual Tracking

Shenyuan Gao, Chunluan Zhou, Chao Ma, Xinggang Wang, Junsong Yuan

Accepted by ECCV 2022.

[Paper] [Code]

Content-Aware Masked Image Modeling Transformer for Stereo Image Compression

Xinjie Zhang, **Shenyuan Gao**, Zhening Liu, Jiawei Shao, Xingtong Ge, Dailan He, Tongda Xu, Yan Wang, Jun Zhang [Paper]

EXPERIENCE

Shanghai Artificial Intelligence Laboratory, OpenDriveLab

April 2023 - present *Shanghai, China*

Research Intern

- · Leader: Prof. Hongyang Li
- · Worked on foundation models for autonomous driving.
- · Experienced in large-scale training with hundreds of GPUs and thousands of hours of video data.
- · Developed a driving world model with strong generalization to diverse scenarios and applications.

Hong Kong University of Science and Technology

Research Postgraduate Program

September 2022 - present Hong Kong SAR, China

- · Advisor: Prof. Jun Zhang (IEEE Fellow)
- · Worked on object tracking and neural compression.
- · Worked on multi-agent perception system.
- · Proposed a generalized relation modeling formulation for Transformer-based tracking.
- · Proposed a content-aware masked image modeling for bidirectional prior interaction.

Huazhong University of Science and Technology

Final Year Project for Bachelor Degree

March 2022 - June 2022 Wuhan, China

- · Advisor: Prof. Peng Yang
- · Worked on the intersection of tracking and efficient deep learning.
- · Proposed a slimmable tracker with hierarchical weight sharing.
- · Awarded as outstanding graduation thesis.

University at Buffalo

Summer Research Intern

July 2021 - March 2022 New York, United States (Remote)

- · Advisor: Prof. Junsong Yuan (IEEE Fellow)
- · Worked on object tracking.
- · Proposed Attention in Attention to facilitate correspondence learning.

The University of Hong Kong, MMLab

HKU CS Summer Research Internship Programme

July 2021 - Augest 2021 Hong Kong SAR, China (Remote)

- · Advisor: Prof. Ping Luo
- · Worked on the intersection of tracking and visual grounding.
- · Completed the research project successfully with full stipend award.

HONORS AND AWARDS

Full Postgraduate Scholarship	2022-2026
RedBird PhD Scholarship	2022-2023
Outstanding Graduate	2022
Outstanding Graduation Thesis	2022
• Outstanding Undergraduate in Terms of Academic Performance (Top 1%)	2019
• National Scholarship (Top 2%)	2019

ACADEMIC SERVICES

Conference Reviewer

ICLR 2025, NeurIPS 2023/2024, CVPR 2023/2024, ECCV 2024, AAAI 2025, ICPR 2024

Journal Reviewer

TPAMI, TMM, TCSVT, IMAVIS

Teaching Assistant

COMP 5214: Advanced Deep Learning Architectures (for postgraduate/undergraduate)

ELEC 3100: Signal Processing and Communications (for undergraduate)