

# Proof of Quantized Federated learning

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## 1 Assumption and Theorem

In FedAvg, the distributed optimization model across  $N$  devices is given by  $\min_{\theta} F(\theta) = \sum_{k=1}^N p_k F_k(\theta) = \mathbb{E}_k[F_k(\theta)]$ , where  $p_k$  is the weight of the  $k$ -th device. Suppose device  $k$  holds  $n_k$  training samples,  $p_k = n_k / \sum_{i=1}^N n_i$ . The objective function of device  $k$  can be given by  $F_k(\theta) = \mathbb{E}_{x_k \sim D_k} F_k(\theta; x_k)$ , where  $x_k$  is sampled from the data distribution  $D_k$  at device  $k$ . Since we are considering the non-IID data distribution across devices, we have  $D_i \neq D_j$  when  $i \neq j$ . We apply the same stochastic quantizer  $Q_s$  for weight and gradient under different resolution  $\Delta$ , where  $Q_s(x, \Delta)$  is defined as

$$Q_s(x, \Delta) = \Delta \begin{cases} \left\lfloor \frac{x}{\Delta} \right\rfloor + 1, & p \geq \frac{x}{\Delta} - \left\lfloor \frac{x}{\Delta} \right\rfloor, \\ \left\lfloor \frac{x}{\Delta} \right\rfloor, & p < \frac{x}{\Delta} - \left\lfloor \frac{x}{\Delta} \right\rfloor. \end{cases} \quad (1)$$

Then the  $k$ -th device performs  $E(\geq 1)$  quantized local updates before aggregation, which can be given by

$$\theta_{t+i+1}^k = \theta_{t+i}^k - \alpha_t Q_s(\nabla F_k(\theta_{t+i,q}^k, x_k), \Delta_g^t), i = 0, 1, \dots, E-1, \quad (2)$$

where  $\alpha_t$  is the learning rate,  $\Delta_g^t = 2^{-\delta_g^t}$  is the gradient quantization resolution, and  $\delta_g^t$  is the gradient precision(bit width) in the  $t$  step. Before GEMM, the weight  $\theta_{t+i}^k$  will be quantized into quantized weight  $\theta_{t+i,q}^k = Q_s(\theta_{t+i}^k, \Delta_{\theta}^t)$  with quantization resolution  $\Delta_{\theta}^t = 2^{-\delta_{\theta}^t}$ , where  $\delta_{\theta}^t$  is the weight precision(bit width) in the  $t$  step. The server then aggregates the quantized local models  $\theta_{t+E}^1, \dots, \theta_{t+E}^N$  to generate a new global model  $\theta_{t+E}$ . Assume all devices participate in the global update, and thus we have  $\theta_{t+E} := \sum_{k=1}^N p_k \theta_{t+E}^k$ . To prove the convergence of the proposed neural quantization strategy, we make the following assumptions.

- *Assumption 1.* (L-Smooth)  $F_1, \dots, F_N$  are all L-smooth, that is for all  $\mathbf{v}$  and  $\mathbf{w}$ ,  $F_k(\mathbf{v}) \leq F_k(\mathbf{w}) + (\mathbf{v} - \mathbf{w})^T \nabla F_k(\mathbf{w}) + \frac{L}{2} \|\mathbf{v} - \mathbf{w}\|_2^2$ .
- *Assumption 2.* ( $\mu$ -strongly convex)  $F_1, \dots, F_N$  are all L-smooth, that is for all  $\mathbf{v}$  and  $\mathbf{w}$ ,  $F_k(\mathbf{v}) \geq F_k(\mathbf{w}) + (\mathbf{v} - \mathbf{w})^T \mu F_k(\mathbf{w}) + \frac{L}{2} \|\mathbf{v} - \mathbf{w}\|_2^2$ .
- *Assumption 3.* (bounded local gradient variance)  $\mathbf{E} \|\nabla F_k(\theta_t^k, x_k^t) - \nabla F_k(\theta_t^k)\|^2 \leq \sigma_k^2$ , for  $k = 1, \dots, N$ , where  $x_k^t$  is sampled from the  $k$ -th device's local data uniformly.

- *Assumption 4.* (bounded local gradient) The expected squared norm of stochastic gradients is bounded,  $\mathbf{E} \|\nabla F_k(\theta_t^k, x_k^t)\|^2 \leq G^2$ , for  $k = 1, \dots, N$ .

**Theorem 1** When Assumption 1-4 hold, under static weight precision and resolution  $\delta_\theta^t = \delta_\theta$ ,  $\Delta_\theta^t = \Delta_\theta = 2^{-\delta_\theta}$ , static gradient precision and resolution  $\delta_g^t = \delta_g$ ,  $\Delta_g^t = \Delta_g = 2^{-\delta_g}$  and learning rate  $\alpha_t = \frac{2}{\mu(t+\gamma)}$ , if  $\theta^*$  is optimal,  $\mathbf{E}[F(\theta_t)] - F(\theta^*)$  is bounded by

$$\mathbf{E}[F(\theta_t)] - F(\theta^*) \leq \frac{A_1}{\gamma+t} \Delta_\theta^2 + \frac{A_2}{\gamma+t} \Delta_g + \frac{B}{\gamma+t}, \quad (3)$$

where  $d$  is the dimensions of the  $\theta$ ;  $A_1 = \frac{4L^3d}{\mu^2}$  and  $A_2 = \frac{2(1+16(E-1)^2)\sqrt{d}LG}{\mu^2}$ ;  $B = \frac{2L}{\mu^2} (C + \frac{\mu^2(\gamma+1)}{4} \mathbf{E} \|\theta_1 - \theta^*\|^2)$ ;  $C = \sum_{k=1}^N p_k^2 \sigma_k^2 + 8(E-1)^2 G^2 + 6L\Omega$  is the federated learning term and  $\Omega = F^* - \sum_{k=1}^N p_k F_k^*$  is difference of aggregated local minimized loss  $F_k^*$  and global minimized loss  $F^*$ ;  $\gamma = \max\{\frac{8L}{\mu}, E\}$ , and  $t, L, E, G, \mu, \Delta_\theta, \Delta_g, \sigma_k$  are as defined above.

**Theorem 2** When Assumptions 1-4 hold, under learning rate  $\alpha_t = \frac{4}{\mu(t+\gamma)}$ , dynamic weight precision and resolution,  $\delta_\theta^t = 1 - \lfloor \log_2(\mu\alpha_t) \rfloor$ ,  $\Delta_\theta^t = 2^{-\delta_\theta^t}$  and dynamic gradient precision and resolution,  $\delta_g^t = 2 - 2\lfloor \log_2(\mu\alpha_t) \rfloor$ ,  $\Delta_g^t = 2^{-\delta_g^t}$ , if  $\theta^*$  is optimal,  $\mathbf{E}[F(\theta_t)] - F(\theta^*)$  is bounded by

$$\mathbf{E}[F(\theta_t)] - F(\theta^*) \leq \frac{B}{\gamma+t} + \frac{16(A_1 + A_2)}{(\gamma+t)^3}, \quad (4)$$

where  $\gamma = \max\{16\frac{L}{\mu}, E\}$  and the remaining variables are as defined in Theorem 1.

## 2 Proof of Theorem

### 2.1 Additional Notation

Set  $\theta_t^k$  as the model parameter in the  $k$ -th device at the  $t$ -step and  $\theta_{t,q}^k$  is its quantized version from Equation ???. We rewrite Equation ?? as :

$$\theta_{t,q}^k = \theta_t^k - r_{k,\theta}^t \quad (5)$$

where  $r_{k,\theta}^t = \theta_t^k - Q_s(\theta_t^k, \Delta_\theta^t)$  donates the weight quantization error on the  $t$ -th iteration under weight quantization resolution  $\Delta_\theta^t$ . We also rewrite the update of FedAvg (Equation 2) with full devices active as:

$$v_{t+1}^k = \theta_t^k - \alpha_t \nabla F_k(\theta_{t,q}^k, x_k) + \alpha_t r_{k,g}^t \quad (6)$$

$$\theta_{t+1}^k = \begin{cases} v_{t+1}^k, & t+1 \neq nE, n=1, 2, \dots \\ \sum_{k=1}^N p_k v_{t+1}^k, & t+1 = nE, n=1, 2, \dots \end{cases} \quad (7)$$

where  $r_{k,g}^t = \nabla F_k(\theta_{t,q}^k, x_k) - Q_s(\nabla F_k(\theta_{t,q}^k, x_k), \Delta_g^t)$  donates the gradient quantization error on the  $t$ -th iteration under gradient quantization resolution  $\Delta_g^t$ . we use  $v_{t+1}^k$  as the direct result of SGD from  $\theta_t^k$ . And we define  $\bar{v}_t = \sum_{k=1}^N p_k v_t^k$ ,  $\bar{\theta}_t = \sum_{k=1}^N p_k \theta_t^k$ ,  $\bar{g}_t = \sum_{k=1}^N p_k \nabla F_k(\theta_{t,q}^k, x_k)$  and  $g_t = \sum_{k=1}^N p_k \nabla F_k(\theta_{t,q}^k, x_k)$ . Therefore  $\bar{v}_{t+1} = \bar{\theta}_t - \alpha_t g_t + \alpha_t \sum_{k=1}^N p_k r_{k,g}^t$ ,  $\bar{v}_{t+1} = \bar{\theta}_{t+1}$  and  $\mathbf{E}[g_t] = \bar{g}_t$ .

### 2.2 Key Lemmas

**Lemma 1** Assume Assumption 4, the gradient quantization error  $r_{k,g}^t$  for  $k$ -th device on  $t$ -th iteration can be bounded in expectation as following:

$$\mathbf{E} \left\| \sum_{k=1}^N p_k r_{k,g}^t \right\|^2 \leq \sqrt{d} G \Delta_g^t \quad (8)$$

where  $d$  donates the dimension of  $\theta_t$

**Lemma 2** Assume Assumption 1 and 2. If  $\alpha \leq \frac{1}{4L}$ , we have:

$$\mathbf{E} \|\bar{v}_{t+1} - \theta^*\|^2 \leq (1 - \alpha_t \mu) \mathbf{E} \|\bar{\theta}_t - \theta^*\|^2 + 6L\alpha_t^2 \Omega + 2\mathbf{E} \left[ \sum_{k=1}^N p_k \|\bar{\theta}_t - \theta_t^k\|^2 \right] + \alpha_t^2 \|\bar{g}_t - g_t\|^2 + 2L^2 \alpha_t^2 d(\Delta_\theta^t)^2 + \alpha_t^2 \mathbf{E} \left\| \sum_{k=1}^N p_k r_{k,g}^t \right\|^2 \quad (9)$$

where  $\Omega = F^* - \sum_{k=1}^N p_k F_k^* \geq 0$

**Lemma 3** Assume Assumption 3 holds. It follows that

$$\mathbf{E} \|g_t - \bar{g}_t\|^2 \leq \sum_{k=1}^N p_k^2 \sigma_k^2 \quad (10)$$

**Lemma 4** Assume Assumption 4 holds, and  $\alpha_t$  is non-increasing and  $\alpha_t \leq 2\alpha_{t+E}$ . It follows that

$$\mathbf{E} \sum_{k=1}^N p_k \|\bar{\theta}_t - \theta_t^k\|^2 \leq 4\alpha_t^2 (E-1)^2 (G^2 + 2\mathbf{E} \left\| \sum_{k=1}^N p_k r_{k,g}^t \right\|^2) \quad (11)$$

### 2.3 The proof of Theorem 1

Let  $D_t = \mathbf{E} \|\bar{\theta}_t - \theta^*\|$ . Set static weight resolution  $\Delta_\theta^t = \Delta_\theta$  and static gradient resolution  $\Delta_g^t = \Delta_g$ . From Lemma 1, Lemma 2, Lemma 3 and Lemma 4, it follows that

$$D_{t+1} \leq (1 - \alpha_t \mu) D_t + \alpha_t^2 A \quad (12)$$

where  $A = C + 2L^2 d \Delta_\theta^2 + (1 + 16(E-1)^2) \sqrt{d} G \Delta_g$  and  $C = \sum_{k=1}^N p_k^2 \sigma_k^2 + 8(E-1)^2 G^2 + 6L\Omega$

We set  $\alpha_t = \frac{\beta}{t+\gamma}$  for  $\beta > \frac{1}{\mu}$  and  $\gamma > 0$  such that  $\alpha_t \leq 2\alpha_{t+E}$  and  $\alpha_1 \leq \frac{1}{4L}$ . We Want to prove  $D_t \leq \frac{v}{\gamma+t}$ , where  $v = \max\{\frac{\beta^2 A}{\beta\mu-1}, (\gamma+1)D_1\}$ .

We Prove it by induction. Firstly,  $v$  ensures that it holds for  $t = 1$ . Assume the conclusion holds for some  $t$ , it follows that:

$$\begin{aligned} D_{t+1} &\leq (1 - \alpha_t \mu) D_t + \alpha_t^2 A \\ &\leq \left(1 - \frac{\beta\mu}{t+\gamma}\right) \frac{v}{t+\gamma} + \frac{\beta^2 A}{(t+\gamma)^2} \\ &\leq \frac{t+\gamma-1}{(t+\gamma)^2} v + \frac{\beta^2 A}{(t+\gamma)^2} - \frac{\beta\mu-1}{(t+\gamma)^2} v \\ &\leq \frac{v}{t+\gamma+1} \end{aligned} \quad (13)$$

Then by the Assumption 1,

$$\mathbb{E}[F(\bar{\theta}_t)] - F^* \leq \frac{L}{2} D_t \leq \frac{L}{2} \frac{v}{\gamma+t} \quad (14)$$

Specifically, if we choose  $\beta = \frac{2}{\mu}$ , and  $\gamma = \max\{8\frac{L}{\mu}, E\}$ ,  $\alpha_t = \frac{2}{\mu(\gamma+t)}$ . i.e.  $\alpha_1 = \frac{2}{\mu(\gamma+1)} \leq \frac{2}{\mu\gamma} \leq \frac{1}{4L}$ . And  $2\alpha_{t+E} = \frac{4}{\mu(\gamma+t+E)} \geq \frac{4}{\mu(2\gamma+2t)} \geq \alpha_t$ . In this case, for  $t \geq 1$  we have:

$$v = \max\left\{\frac{\beta^2 A}{\beta\mu-1}, (\gamma+1)D_1\right\} \leq \frac{\beta^2 A}{\beta\mu-1} + (\gamma+1)D_1 \leq \frac{4A}{\mu^2} + (\gamma+1)D_1 \quad (15)$$

and

$$\mathbb{E}[F(\bar{\theta}_t)] - F^* \leq \frac{L}{2} \frac{v}{\gamma+t} \leq \frac{L}{2(\gamma+t)} \left( \frac{4A}{\mu^2} + (\gamma+1)D_1 \right) \quad (16)$$

Thus:

$$\begin{aligned}
\mathbb{E}[F(\bar{\theta}_t)] - F^* &\leq \frac{2L}{\gamma+t} \left( \frac{C + 2L^2 d \Delta_\theta^2 + (1 + 16(E-1)^2) \sqrt{d} G \Delta_g + \frac{(\gamma+1)D_1}{4}}{\mu^2} \right) \\
&\leq \frac{4L^3 d}{\mu^2(\gamma+t)} \Delta_\theta^2 + \frac{2(1 + 16(E-1)^2) \sqrt{d} L G}{\mu^2(\gamma+t)} \Delta_g + \frac{2L}{\mu^2(\gamma+t)} \left( C + \frac{\mu^2(\gamma+1)}{4} D_1 \right) \\
&\leq \frac{A_1}{\gamma+t} \Delta_\theta^2 + \frac{A_2}{\gamma+t} \Delta_g + \frac{B_1}{\gamma+t}
\end{aligned} \tag{17}$$

Where  $A_1 = \frac{4L^3 d}{\mu^2}$  and  $A_2 = \frac{2(1+16(E-1)^2)\sqrt{d}LG}{\mu^2}$ ;  $B_1 = \frac{2L}{\mu^2} \left( C + \frac{\mu^2(\gamma+1)}{4} D_1 \right)$

## 2.4 The proof of Theorem 2

Let  $D_t = \mathbb{E}[\|\bar{\theta}_t - \theta^*\|]$ . dynamic weight precision and resolution,  $\delta_\theta^t = 1 - \lfloor \log_2 \mu \alpha_t \rfloor$ ,  $\Delta_\theta^t = 2^{-\delta_\theta^t}$  and dynamic gradient precision and resolution,  $\delta_g^t = 2 - 2\lfloor \log_2 \mu \alpha_t \rfloor$ ,  $\Delta_g^t = 2^{-\delta_g^t}$ , if  $\theta^*$  is optimal,  $\mathbb{E}[F(\theta_t)] - F(\theta^*)$ . From Lemma 1, Lemma 2, Lemma 3 and Lemma 4, it follows that

$$D_{t+1} \leq (1 - \alpha_t \mu) D_t + \alpha_t^2 H_1 (\Delta_\theta^t)^2 + \alpha_t^2 H_2 \Delta_g^t + \alpha_t^2 C \tag{18}$$

where  $H_1 = 2L^2 d$ ,  $H_2 = (1 + 16(E-1)^2) \sqrt{d} G$  and  $C = \sum_{k=1}^N p_k^2 \sigma_k^2 + 8(E-1)^2 G^2 + 6L\Omega$

Because  $\delta_\theta^t \geq 1 - \log_2(\mu \alpha_t)$  and  $\delta_g^t \geq 2 - 2\log_2(\mu \alpha_t)$ , Thus

$$\begin{aligned}
\Delta_\theta^t &= 2^{-\delta_\theta^t} \leq \frac{\mu \alpha_t}{2} \\
\Delta_g^t &= 2^{-\delta_g^t} \leq \frac{(\mu \alpha_t)^2}{4}
\end{aligned}$$

Thus Equation 18 will be

$$D_{t+1} \leq (1 - \alpha_t \mu) D_t + \alpha_t^4 \frac{\mu^2(H_1 + H_2)}{4} + \alpha_t^2 C \tag{19}$$

We set  $\alpha_t = \frac{\beta}{t+\gamma}$  for  $\beta > \frac{3}{\mu}$  and  $\gamma > 0$  such that  $\alpha_t \leq 2\alpha_{t+E}$  and  $\alpha_1 \leq \frac{1}{4L}$ . We Want to prove  $D_t \leq \frac{v}{\gamma+t} + \frac{w}{(\gamma+t)^3}$ , where  $v = \max\{\frac{\beta^2 C}{\beta\mu-1}, (\gamma+1)D_1\}$ .  $w = \frac{\beta^4 \mu^2(H_1+H_2)}{4(\beta\mu-3)}$ .

We Prove it by induction. Firstly,  $v$  and  $w$  ensures that it holds for  $t = 1$ . Assume the conclusion holds for some  $t$ , it follows that:

$$\begin{aligned}
D_{t+1} &\leq (1 - \alpha_t \mu) D_t + \alpha_t^4 \frac{\mu^2(H_1 + H_2)}{4} + \alpha_t^2 C \\
&\leq \left(1 - \frac{\beta\mu}{t+\gamma}\right) \left(\frac{v}{t+\gamma} + \frac{w}{(\gamma+t)^3}\right) + \frac{\beta^4}{(t+\gamma)^4} \frac{\mu^2(H_1 + H_2)}{4} + \frac{\beta^2}{(t+\gamma)^2} C \\
&\leq \frac{t+\gamma-1}{(t+\gamma)^2} v + \frac{t+\gamma-3}{(t+\gamma)^4} w + \left[ \frac{\beta^2 C}{(t+\gamma)^2} - \frac{\beta\mu-1}{(t+\gamma)^2} v \right] + \left[ \frac{\beta^4 \mu^2(H_1 + H_2)}{4(t+\gamma)^4} - \frac{\beta\mu-3}{(t+\gamma)^4} w \right] \\
&\leq \frac{v}{t+\gamma+1} + \frac{w}{(t+\gamma+1)^3}
\end{aligned} \tag{20}$$

Specifically, if we choose  $\beta = \frac{4}{\mu}$ , and  $\gamma = \max\{16\frac{L}{\mu}, E\}$ ,  $\alpha_t = \frac{4}{\mu(\gamma+t)}$ . i.e.  $\alpha_1 = \frac{4}{\mu(\gamma+1)} \leq \frac{4}{\mu\gamma} \leq \frac{1}{4L}$ . And  $2\alpha_{t+E} = \frac{8}{\mu(\gamma+t+E)} \geq \frac{8}{\mu(2\gamma+2t)} \geq \alpha_t$ . In this case, for  $t \geq 1$  we have:

$$v = \max\left\{\frac{\beta^2 C}{\beta\mu-1}, (\gamma+1)D_1\right\} \leq \frac{\beta^2 C}{\beta\mu-1} + (\gamma+1)D_1 \leq \frac{4C}{\mu^2} + (\gamma+1)D_1 \tag{21}$$

and

$$\mathbb{E}[F(\bar{\theta}_t)] - F^* \leq \frac{L}{2} \left( \frac{v}{\gamma+t} + \frac{w}{(t+\gamma)^3} \right) \leq \frac{1}{\gamma+t} \left( \frac{2LC}{\mu^2} + \frac{(\gamma+1)LD_1}{2} \right) + \frac{1}{(\gamma+t)^3} \frac{32(H_1 + H_2)L}{\mu^2} \tag{22}$$

Thus, if we set  $A_1 = \frac{2LH_1}{\mu^2} = \frac{4L^3d}{\mu^2}$  and  $A_2 = \frac{2LH_2}{\mu^2} = \frac{2(1+16(E-1)^2)\sqrt{d}LG}{\mu^2}$ ;  $B_2 = \frac{2L}{\mu^2} \left( C + \frac{\mu^2(\gamma+1)}{4} D_1 \right)$ ,  
We will have:

$$\mathbb{E}[F(\bar{\theta}_t)] - F^* \leq \frac{B_2}{\gamma + t} + \frac{1}{(\gamma + t)^3} (16(A_1 + A_2)) \quad (23)$$