Connected space

In topology and related branches of mathematics, a **connected space** is a topological space that cannot be represented as the union of two or more disjoint non-empty open subsets. Connectedness is one of the principal topological properties that are used to distinguish topological spaces.

A subset of a topological space *X* is a **connected set** if it is a connected space when viewed as a subspace of *X*.

Some related but stronger conditions are path connected, simply connected, and n-connected. Another related notion is locally connected, which neither implies nor follows from connectedness.

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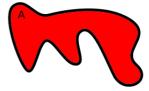
References

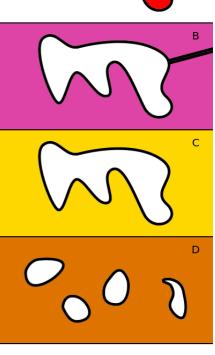
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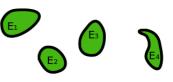
Formal definition

A <u>topological space</u> X is said to be **disconnected** if it is the union of two disjoint non-empty open sets. Otherwise, X is said to be **connected**. A <u>subset</u> of a topological space is said to be connected if it is connected under its subspace topology. Some authors exclude the <u>empty set</u> (with its unique topology) as a connected space, but this article does not follow that practice.

Connected and disconnected subspaces of R²







From top to bottom: red space *A*, pink space *B*, yellow space *C* and orange space *D* are all **connected**, whereas green space *E* (made of subsets E1, E2, E3, and E4) is **not connected**. Furthermore, *A* and *B* are also simply connected (genus 0), while *C* and *D* are not: *C* has genus 1 and *D* has genus 4

For a topological space *X* the following conditions are equivalent:

- 1. X is connected, that is, it cannot be divided into two disjoint non-empty open sets.
- 2. X cannot be divided into two disjoint non-empty closed sets.
- 3. The only subsets of *X* which are both open and closed (clopen sets) are *X* and the empty set.
- 4. The only subsets of X with empty boundary are X and the empty set.
- 5. *X* cannot be written as the union of two non-empty <u>separated sets</u> (sets for which each is disjoint from the other's closure).
- 6. All continuous functions from X to $\{0,1\}$ are constant, where $\{0,1\}$ is the two-point space endowed with the discrete topology.

Connected components

The <u>maximal</u> connected subsets (ordered by <u>inclusion</u>) of a non-empty topological space are called the **connected components** of the space. The components of any topological space X form a <u>partition</u> of X: they are <u>disjoint</u>, non-empty, and their union is the whole space. Every component is a <u>closed subset</u> of the <u>original</u> space. It follows that, in the case where their number is finite, each component is also an open subset. However, if their number is infinite, this might not be the case; for instance, the connected components of the set of the <u>rational numbers</u> are the one-point sets (singletons), which are not open.

Let Γ_x be the connected component of x in a topological space X, and Γ_x' be the intersection of all <u>clopen</u> sets containing x (called <u>quasi-component</u> of x.) Then $\Gamma_x \subset \Gamma_x'$ where the equality holds if X is compact Hausdorff or locally connected.

Disconnected spaces

A space in which all components are one-point sets is called <u>totally disconnected</u>. Related to this property, a space X is called **totally separated** if, for any two distinct elements x and y of X, there exist disjoint <u>open sets</u> U containing x and V containing y such that X is the union of U and V. Clearly, any totally separated space is totally disconnected, but the converse does not hold. For example take two copies of the rational numbers \mathbf{Q} , and identify them at every point except zero. The resulting space, with the quotient topology, is totally disconnected. However, by considering the two copies of zero, one sees that the space is not totally separated. In fact, it is not even Hausdorff, and the condition of being totally separated is strictly stronger than the condition of being Hausdorff.

Examples

- The closed interval [0, 2] in the <u>standard subspace topology</u> is connected; although it can, for example, be written as the union of [0, 1) and [1, 2], the second set is not open in the chosen topology of [0, 2].
- The union of [0, 1) and (1, 2] is disconnected; both of these intervals are open in the standard topological space $[0, 1) \cup (1, 2]$.
- $(0,1) \cup \{3\}$ is disconnected.
- A convex subset of **R**ⁿ is connected; it is actually simply connected.
- A Euclidean plane excluding the origin, (0, 0), is connected, but is not simply connected. The

three-dimensional Euclidean space without the origin is connected, and even simply connected. In contrast, the one-dimensional Euclidean space without the origin is not connected.

- A Euclidean plane with a straight line removed is not connected since it consists of two halfplanes.
- \blacksquare \mathbb{R} , The space of real numbers with the usual topology, is connected.
- If even a single point is removed from \mathbb{R} , the remainder is disconnected. However, if even a countable infinity of points are removed from \mathbb{R}^n , where $n \ge 2$, the remainder is connected. If $n \ge 3$, then \mathbb{R}^n remains simply connected after removal of countably many points.
- Any topological vector space, e.g. any <u>Hilbert space</u> or <u>Banach space</u>, over a connected field (such as $\mathbb R$ or $\mathbb C$), is simply connected.
- Every <u>discrete topological space</u> with at least two elements is disconnected, in fact such a space is totally disconnected. The simplest example is the discrete two-point space.^[1]
- On the other hand, a finite set might be connected. For example, the spectrum of a <u>discrete</u> valuation ring consists of two points and is connected. It is an example of a Sierpiński space.
- The Cantor set is totally disconnected; since the set contains uncountably many points, it has uncountably many components.
- If a space *X* is homotopy equivalent to a connected space, then *X* is itself connected.
- The topologist's sine curve is an example of a set that is connected but is neither path connected nor locally connected.
- The general linear group $GL(n, \mathbf{R})$ (that is, the group of n-by-n real, invertible matrices) consists of two connected components: the one with matrices of positive determinant and the other of negative determinant. In particular, it is not connected. In contrast, $GL(n, \mathbf{C})$ is connected. More generally, the set of invertible bounded operators on a complex Hilbert space is connected.
- The spectra of commutative <u>local ring</u> and integral domains are connected. More generally, the following are equivalent^[2]
 - 1. The spectrum of a commutative ring R is connected
 - 2. Every finitely generated projective module over *R* has constant rank.
 - 3. R has no idempotent $\neq 0, 1$ (i.e., R is not a product of two rings in a nontrivial way).

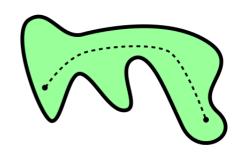
An example of a space that is not connected is a plane with an infinite line deleted from it. Other examples of disconnected spaces (that is, spaces which are not connected) include the plane with an <u>annulus</u> removed, as well as the union of two disjoint closed <u>disks</u>, where all examples of this paragraph bear the <u>subspace topology</u> induced by two-dimensional Euclidean space.

Path connectedness

A **path**-connected space is a stronger notion of connectedness, requiring the structure of a <u>path</u>. A **path** from a point x to a point y in a topological space X is a continuous function f from the <u>unit interval</u> [0,1] to f with f(0) = x and f(1) = y. A **path-component** of f is an <u>equivalence class</u> of f under the <u>equivalence relation</u> which makes f equivalent to f if there is a path from f to f. The space f is said to be **path-connected** (or **pathwise connected** or **o-connected**) if there is exactly one path-component, i.e. if there is a path joining any two points in f. Again, many authors exclude the empty space (note however that by this definition, the empty space is not path-connected because it has zero path-components; there is a unique equivalence relation on the empty set which has zero equivalence classes).

Every path-connected space is connected. The converse is not always true: examples of connected spaces that are not path-connected include the extended $\underline{long line} L^*$ and the topologist's sine curve.

Subsets of the <u>real line</u> \mathbf{R} are connected <u>if and only if they are path-connected</u>; these subsets are the <u>intervals</u> of \mathbf{R} . Also, open subsets of \mathbf{R}^n or \mathbf{C}^n are connected if and only if they are path-connected. Additionally, connectedness and path-connectedness are the same for <u>finite topological spaces</u>.



This subspace of **R**² is pathconnected, because a path can be drawn between any two points in the space.

Arc connectedness

A space X is said to be **arc-connected** or **arcwise connected** if any two distinct points can be joined by an arc, that is a path f which is a <u>homeomorphism</u> between the unit interval [0, 1] and its <u>image</u> f([0, 1]). It can be shown any <u>Hausdorff space</u> which is path-connected is also arc-connected. An example of a space which is path-connected but not arc-connected is provided by adding a second copy o' of o to the nonnegative real numbers $[0, \infty)$. One endows this set with a <u>partial order</u> by specifying that o' < a for any positive number a, but leaving o and o' incomparable. One then endows this set with the <u>order topology</u>. That is, one takes the open intervals $(a, b) = \{x \mid a < x < b\}$ and the half-open intervals $[0, a) = \{x \mid 0 \le x < a\}$, $[0', a) = \{x \mid 0' \le x < a\}$ as a <u>base</u> for the topology. The resulting space is a \underline{T}_1 space but not a <u>Hausdorff space</u>. Clearly o and o' can be connected by a path but not by an arc in this space.

Local connectedness

A topological space is said to be **locally connected at a point** x if every neighbourhood of x contains a connected open neighbourhood. It is **locally connected** if it has a <u>base</u> of connected sets. It can be shown that a space X is locally connected if and only if every component of every open set of X is open.

Similarly, a topological space is said to be **locally path-connected** if it has a base of path-connected sets. An open subset of a locally path-connected space is connected if and only if it is path-connected. This generalizes the earlier statement about \mathbf{R}^n and \mathbf{C}^n , each of which is locally path-connected. More generally, any topological manifold is locally path-connected.

Locally connected does not imply connected, nor does locally path-connected imply path connected. A simple example of a locally connected (and locally path-connected) space that is not connected (or path-connected) is the union of two separated intervals in \mathbb{R} , such as $(0,1) \cup (2,3)$.

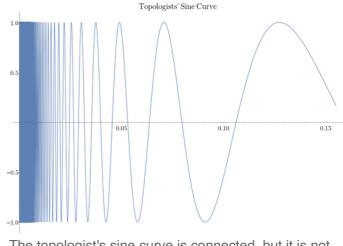
A classical example of a connected space that is not locally connected is the so called <u>topologist's</u> sine curve, defined as $T = \{(0,0)\} \cup \{(x,\sin(\frac{1}{x}): x \in (0,1]\}$, with the <u>Euclidean topology</u> induced by inclusion in \mathbb{R}^2 .

Set operations

The **intersection** of connected sets is not necessarily connected.

The **union** of connected sets is not necessarily connected. Consider a collection $\{X_i\}$ of connected sets whose union is $X = \bigcup_i X_i$. If X is disconnected and $U \cup V$ is a separation of X (with U, V disjoint and open in X), then each X_i must be entirely contained in either U or V, since otherwise, $X_i \cap U$ and $X_i \cap V$ (which are disjoint and open in X_i) would be a separation of X_i , contradicting the assumption that it is connected.

Each ellipse is a connected set, but the union is not connected, since it can be partitioned to two disjoint open sets U and V.

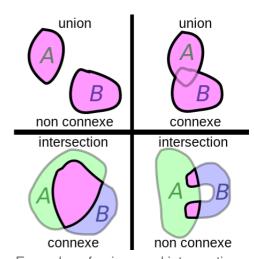


The topologist's sine curve is connected, but it is not locally connected

This means that, if the union X is disconnected, then the collection $\{X_i\}$ can be partitioned to two subcollections, such that the unions of the sub-collections are disjoint and open in X (see picture). This implies that in several cases, a union of connected sets is necessarily connected. In particular:

- 1. If the common intersection of all sets is not empty ($\bigcap X_i \neq \emptyset$), then obviously they cannot be partitioned to collections with <u>disjoint unions</u>. Hence the union of connected sets with non-empty intersection is connected.
- 2. If the intersection of each pair of sets is not empty ($\forall i,j: X_i \cap X_j \neq \emptyset$) then again they cannot be partitioned to collections with disjoint unions, so their union must be connected.
- connected.

 3. If the sets can be ordered as a "linked chain", i.e. indexed by integer indices and $\forall i: X_i \cap X_{i+1} \neq \emptyset$, then again their union must be connected.

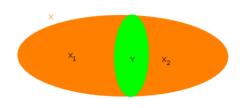


Examples of unions and intersections of connected sets

4. If the sets are pairwise-disjoint and the <u>quotient space</u> $X/\{X_i\}$ is connected, then X must be connected. Otherwise, if $U \cup V$ is a separation of X then $q(U) \cup q(V)$ is a separation of the quotient space (since q(U), q(V) are disjoint and open in the quotient space).^[3]

The <u>set</u> difference of connected sets is not necessarily connected. However, if $X \supseteq Y$ and their difference $X \setminus Y$ is disconnected (and thus can be written as a union of two open sets X_1 and X_2), then the union of Y with each such component is connected (i.e. $Y \cup X_i$ is connected for all i).

Proof:^[4] By contradiction, suppose $Y \cup X_1$ is not connected. So it can be written as the union of two disjoint open sets, e.g. $Y \cup X_1 = Z_1 \cup Z_2$. Because Y is connected, it must be



Two connected sets whose difference is not connected

entirely contained in one of these components, say Z_1 , and thus Z_2 is contained in X_1 . Now we know that:

$$X = (Y \cup X_1) \cup X_2 = (Z_1 \cup Z_2) \cup X_2 = (Z_1 \cup X_2) \cup (Z_2 \cap X_1)$$

The two sets in the last union are disjoint and open in X, so there is a separation of X, contradicting the fact that X is connected.

Theorems

- Main theorem of connectedness: Let X and Y be topological spaces and let $f: X \to Y$ be a continuous function. If X is (path-)connected then the image f(X) is (path-)connected. This result can be considered a generalization of the intermediate value theorem.
- Every path-connected space is connected.
- Every locally path-connected space is locally connected.
- A locally path-connected space is path-connected if and only if it is connected.
- The <u>closure</u> of a connected subset is connected. Furthermore, any subset between a connected subset and its closure is connected.
- The connected components are always closed (but in general not open)
- The connected components of a locally connected space are also open.
- The connected components of a space are disjoint unions of the path-connected components (which in general are neither open nor closed).
- Every <u>quotient</u> of a connected (resp. locally connected, path-connected, locally path-connected) space is connected (resp. locally connected, path-connected, locally path-connected).
- Every <u>product</u> of a family of connected (resp. path-connected) spaces is connected (resp. path-connected).
- Every open subset of a locally connected (resp. locally path-connected) space is locally connected (resp. locally path-connected).
- Every manifold is locally path-connected.
- Arc-wise connected space is path connected, but path-wise connected space may not be arcwise connected
- Continuous image of arc-wise connected set is arc-wise connected.

Graphs

<u>Graphs</u> have path connected subsets, namely those subsets for which every pair of points has a path of edges joining them. But it is not always possible to find a topology on the set of points which induces the same connected sets. The $\underline{5}$ -cycle graph (and any n-cycle with n > 3 odd) is one such example.

As a consequence, a notion of connectedness can be formulated independently of the topology on a space. To wit, there is a category of connective spaces consisting of sets with collections of connected subsets satisfying connectivity axioms; their morphisms are those functions which map connected sets to connected sets (<u>Muscat & Buhagiar 2006</u>). Topological spaces and graphs are special cases of connective spaces; indeed, the finite connective spaces are precisely the finite graphs.

However, every graph can be canonically made into a topological space, by treating vertices as points and edges as copies of the unit interval (see topological graph theory#Graphs as topological spaces). Then one can show that the graph is connected (in the graph theoretical sense) if and only

Stronger forms of connectedness

There are stronger forms of connectedness for topological spaces, for instance:

- If there exist no two disjoint non-empty open sets in a topological space, *X*, *X* must be connected, and thus hyperconnected spaces are also connected.
- Since a <u>simply connected space</u> is, by definition, also required to be path connected, any simply connected space is also connected. Note however, that if the "path connectedness" requirement is dropped from the definition of simple connectivity, a simply connected space does not need to be connected.
- Yet stronger versions of connectivity include the notion of a contractible space. Every contractible space is path connected and thus also connected.

In general, note that any path connected space must be connected but there exist connected spaces that are not path connected. The <u>deleted comb space</u> furnishes such an example, as does the above-mentioned topologist's sine curve.

See also

- Connected component (graph theory)
- Connectedness locus
- Extremally disconnected space
- Locally connected space
- n-connected
- Uniformly connected space
- Pixel connectivity

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