云南大学数学与统计学院 上机实践报告

课程名称:数值计算实验	年级: 2015 级	上机实践成绩:
指导教师: 朱娟萍	姓名: 刘鹏	
上机实践名称:插值法	学号: 20151910042	上机实践日期: 2017-11-29
上机实践编号: No.03	组号:	最后修改时间: 15:13

一、实验目的

- 1. 通过对所学的插值法的理论方法进行编程,提升程序编写水平;
- 2. 通过对理论方法的编程实验,进一步掌握理论方法的每一个细节;
- 3. 检验教材知识的理解与掌握程度。

二、实验内容

- 1. 编制用拉格朗日插值方法进行插值的程序;
- 2. 编制用牛顿插值方法进行插值的程序;
- 3. 要求牛顿插值方法在等距与不等距下两种情况下,程序可以进行自行选择,降低计算量。

三、实验平台

Windows 10 1709 Enterprise 中文版;

Python 3.6.0;

Wing IDE Professional 6.0.5-1 集成开发环境;

MATLAB R2017b win64;

AxMath 公式编辑器;

EndNote X8 文献管理。

四、实验记录与实验结果分析

1题

己知正弦函数表:

x_k	0.5	0.7	0.9	1.1	1.3	1.5	1.7	1.9
$\sin(x_k)$	0.4794	0.6442	0.7833	0.8912	0.9636	0.9975	0.9917	0.9463

编写程序,分别用拉格朗日插值和牛顿插值多项式计算 $x_0=0.6,\ 0.8,\ 1.0$ 处的函数值 $\sin(0.6),\ \sin(0.8),\ \sin(1.0)$ 的近似值f $(0.6),\ f(0.8),\ f(1.0)$ 。

解答:

程序代码

```
# -*- coding: utf-8 -*-
2
3
     Created on Thu Dec 7 12:14:49 2017
4
5
     @author: Newton
6
7
8
     """filename: 1.Interpolation Methods.py"""
9
     class Interp:
10
11
         """This class aims to make the interpolation method combined. each method
12
         member of this class represents a method of interpolation.
13
14
15
                       Method
             Name
16
17
         Newton
                           Newton
18
         Lagrange
                       Lagr
19
20
         0.00
21
22
23
         def __init__(self, x_known, y_known, x_unknown):
            """The (x, y) points we have already known is essential to the
24
            interpolation."""
25
26
            self.x = x_known # x_known is a list
27
            self.y = y_known # y_known is a list
28
            self.ux = x_unknown # need to be computed
29
30
            if len(self.x) != len(self.y):
31
                raise ValueError("Bad input, len(x) should equal to len(y)")
32
33
         def getDiffQuotientTab(self):
34
            """Generate a matrix which represents the difference quotient table
35
            of (x_known, y_known).
            0.000
36
37
            n = len(self.x) - 1
38
39
            ans = [[None for i in range(n)] for i in range(n)]
40
            # initialize it with default setting None.
41
42
            for i in range(n): # column
43
                for j in range(i, n): # row
44
                    if i == 0:
45
                       ans[j][i] = (self.y[j+1] - self.y[j]) \setminus
46
                       / (self.x[j+1] - self.x[j])
47
                    else:
48
                       ans[j][i] = (ans[j][i-1] - ans[j-1][i-1]) \setminus
```

```
49
                       / (self.x[j+1] - self.x[j-1])
50
51
            return ans
52
53
         def Newton(self):
            """Need self.getDiffQuotientTab method.
54
55
56
            0.00
57
58
            step0 = self.getDiffQuotientTab()
59
            step1 = list()
60
            for i in range(len(self.x)-1):
61
                step1.append(step0[i][i])
62
63
            ans = [0 for i in range(len(self.ux))]
64
65
            for i in range(len(self.ux)): # generate a list of y we needed
66
                for j in range(len(self.x)): # a long polynomial function
67
                    if j == 0:
68
                       ans[i] += self.y[j]
69
                    else:
70
                       tmp = 1
71
                       for k in range(j):
72
                           tmp *= (self.ux[i] - self.x[k])
73
                       tmp *= step1[j-1]
74
75
                       ans[i] += tmp
76
77
            return ans
78
79
         def Lagr(self):
80
            n = len(self.x)
81
            m = len(self.ux)
82
83
            ans = []
84
85
            for i in range(m): # all the x unknown
86
                s = 0
                for k in range(n):
87
                                       # sum
88
                    p = 1
89
                    for j in range(n): # multi
90
                       if j != k:
91
                           p = p * ((self.ux[i] - self.x[j]) / (self.x[k] - self.x[j]))
92
                    s = s + p * self.y[k]
93
                ans.append(s)
94
            return ans
95
96
     if __name__ == '__main__':
97
```

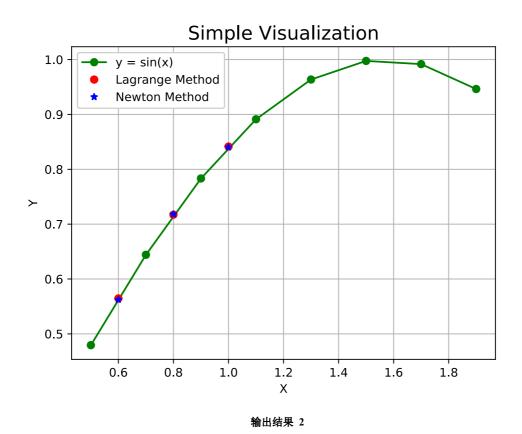
```
98
       x = [0.5, 0.7, 0.9, 1.1, 1.3, 1.5, 1.7, 1.9]
99
       y = [0.4794, 0.6442, 0.7833, 0.8912, 0.9636, 0.9975, 0.9917, 0.9463]
100
       m = [0.6, 0.8, 1.0]
       c = Interp(x, y, m)
101
102
       ans_newton = c.Newton()
103
       ans lagr = c.Lagr()
104
105
       ans_n = list()
106
       for i in ans newton:
107
          ans_n.append(round(i, 4))
108
109
       ans_l = list()
110
       for i in ans_lagr:
111
          ans_1.append(round(i, 4))
112
113
       print('+-----')
114
       print('| Method | x | y |')
115
       print('+-----+')
       print('| Lagr | ',m[0], ' | ', ans_1[0], ' |')
116
117
       | ' )
              | ',m[2], ' | ', ans_1[2],
118
       print('|
                                                | ' )
       print('+-----')
119
       print('| Newton | ',m[0], ' | ', ans_n[0], ' |')
120
121
       | ',m[2], ' | ', ans_n[2], ' |')
122
       print('|
123
       print('+-----')
124
125
       import matplotlib.pyplot as pl
126
127
       pl.grid()
128
       pl.title("Simple Visualization", fontsize=16)
       pl.plot(x, y, 'o-g', label = 'y = sin(x)')
129
       pl.plot(m, ans_l, 'ro', label = 'Lagrange Method')
130
       pl.plot(m, ans_n, 'b*', label = 'Newton Method')
131
       pl.legend()
132
       pl.xlabel('X')
133
       pl.ylabel('Y')
134
       pl.show()
135
```

Code Box 1

输出结果

1. Interpolation Meth ▼	Debug process terminate	ed	
Method	++- x	у	+
Lagr 	0.6 0.8 1.0	0.5646 0.7173 0.8414	
Newton 	0.6 0.8 1.0	0.5624 0.7181 0.8402	

输出结果 1



代码分析

本段代码,是构建了一个简单的封装,可以将已知点作为参数输入,然后输入作为第三个参数的要估计的点的横坐标列表,最终返回一个列表,它储存着根据相应方法得到的插值数值。

2题

已知[1]

\overline{x}	0.4	0.5	0.6	0.7	0.8	0.9
$\ln(x)$	$-0.916\ 291$	$-0.693\ 147$	-0.510826	-0.357765	$-0.223\ 144$	$-0.105\ 361$

用牛顿后插公式求ln(0.78)的近似值,并根据 5 阶差分估计 4 阶公式的误差。

解答:

程序代码

```
# -*- coding: utf-8 -*-
2
3
     Created on Sat Dec 9 19:18:27 2017
4
5
     @author: Newton
6
7
     """filename: 2. Newton left-interp Method.py"""
8
9
10
     class Interp:
        """This class aims to make the interpolation method combined. each method
11
12
        member of this class represents a method of interpolation.
13
14
15
                        Method
16
17
         Newton
                           Newton
18
          Lagrange
                       Lagr
19
20
21
22
23
        def __init__(self, x_known, y_known, x_unknown):
            """The (x, y) points we have already known is essential to the
24
            interpolation."""
25
26
            self.x = x_known # x_known is a list
            self.y = y_known # y_known is a list
27
28
            self.ux = x unknown # need to be computed
29
30
            if len(self.x) != len(self.y):
                raise ValueError("Bad input, len(x) should equal to len(y)")
31
32
33
        def getDiffTab(self):
34
35
            n = len(self.x) - 1
36
            ans = [[None for i in range(n)] for i in range(n)]
37
```

```
38
39
             for i in range(n):
                                         # column
40
                for j in range(i, n): # row
41
                    if i == 0:
42
                        ans[j][i] = self.y[j+1] - self.y[j]
43
                    else:
44
                        ans[j][i] = ans[j][i-1] - ans[j-1][i-1]
45
             return ans
46
47
         def getDiffQuotientTab(self):
             """Generate a matrix which represents the difference quotient table
48
49
             of (x_known, y_known).
50
51
52
             equidistant = False  # equidistant is false by defualt
53
54
             t = self.x[1] - self.x[0]
55
             for i in range(1, len(self.x)-1):
56
                if round(t, 1) == round(self.x[i+1] - self.x[i], 1):
57
                    equidistant = True
58
                else:
59
                    equidistant = False
60
                    break
61
62
             if equidistant == False:
63
                n = len(self.x) - 1
64
                ans = [[None for i in range(n)] for i in range(n)]
65
66
                # initialize it with default setting None.
67
68
                for i in range(n):
                                            # column
69
                    for j in range(i, n): # row
70
                        if i == 0:
71
                            ans[j][i] = (self.y[j+1] - self.y[j]) \
72
                            / (self.x[j+1] - self.x[j])
73
                        else:
74
                            ans[j][i] = (ans[j][i-1] - ans[j-1][i-1]) \setminus
                            / (self.x[j+1] - self.x[j-1])
75
76
                pass
77
                return ans
78
79
             else:
80
                from math import factorial as fc
81
                from math import pow as pow
82
83
                n = len(self.x) - 1
84
85
                ans = [[None for i in range(n)] for i in range(n)]
86
```

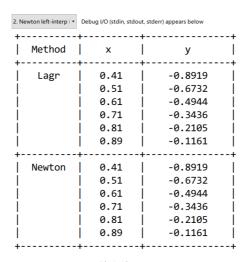
```
87
                diffTab = self.getDiffTab()
88
89
                for i in range(n):
90
                    low = fc(i+1) * pow(t, i+1)
91
                    up = diffTab[i][i]
92
                    ans[i][i] = up/low
93
94
                return ans
95
96
         def Newton(self):
97
             """Need self.getDiffQuotientTab method.
98
99
             0.00
100
101
             step0 = self.getDiffQuotientTab()
102
             step1 = list()
103
             for i in range(len(self.x)-1):
104
                step1.append(step0[i][i])
105
106
            ans = [0 for i in range(len(self.ux))]
107
             for i in range(len(self.ux)):
108
                                              # generate a list of y we needed
109
                for j in range(len(self.x)): # a long polynomial function
110
                    if j == 0:
111
                        ans[i] += self.y[j]
112
                    else:
113
                        tmp = 1
114
                        for k in range(j):
115
                           tmp *= (self.ux[i] - self.x[k])
116
                        tmp *= step1[j-1]
117
118
                        ans[i] += tmp
119
120
             return ans
121
122
         def Lagr(self):
123
             n = len(self.x)
124
             m = len(self.ux)
125
126
             ans = []
127
128
             for i in range(m):
                                       # all the x unknown
129
                s = 0
130
                for k in range(n):
                                        # sum
131
                    p = 1
132
                    for j in range(n): # multi
133
                        if j != k:
                            p = p * ((self.ux[i] - self.x[j]) / (self.x[k] - self.x[j]))
134
135
                    s = s + p * self.y[k]
```

```
136
              ans.append(s)
137
           return ans
138
139
    if __name__ == '__main__':
140
141
        x = [0.4, 0.5, 0.6, 0.7, 0.8, 0.9]
142
        y = [-0.916291, -0.693147, -0.510826, -0.357765, -0.223144, -0.105361]
        m = [0.41, 0.51, 0.61, 0.71, 0.81, 0.89]
143
144
        c = Interp(x, y, m)
145
146
        ans newton = c.Newton()
147
        ans_lagr = c.Lagr()
148
149
        ans n = list()
150
        for i in ans_newton:
151
           ans_n.append(round(i, 4))
152
153
        ans_l = list()
154
        for i in ans_lagr:
155
           ans_1.append(round(i, 4))
156
157
        print('+-----+')
158
        print('| Method | x |
                                             | ' )
159
        print('+-----')
        print('| Lagr | ',m[0], ' | ', ans_l[0], '
160
161
                       | ',m[1], ' | ', ans_l[1], '
        print('|
                                                      | ' )
162
                         ',m[2], ' | ', ans_1[2], '
        print('|
                                                       | ' )
163
                       | ',m[3], ' | ', ans_1[3], '
        print('|
                                                      | ' )
                         ',m[4], ' | ', ans_1[4], '
164
        print('|
                                                      |')
165
                      | ',m[5], ' | ', ans_1[5], ' |')
        print('|
166
        print('+----+')
        print('| Newton | ',m[0], ' | ', ans_n[0], '
167
                                                       | ' )
                       | ',m[1], ' | ', ans_n[1], '
168
        print('|
                                                       |')
169
                       | ',m[2], ' | ', ans_n[2], '
        print('|
                                                     | ' )
                         ',m[3], ' |
                                      ', ans_n[3], '
170
        print('|
                                                      | ' )
171
                         ',m[4], ' | ', ans_n[4], '
        print('|
                                                      | ' )
172
                       | ',m[5], ' | ', ans_n[5], '
                                                     | ' )
        print('|
173
        print('+----+')
174
175
        import matplotlib.pyplot as pl
176
177
        pl.grid()
178
        pl.title("Simple Visualization", fontsize=16)
179
        pl.plot(x, y, 'o-g', label = 'y = sin(x)')
180
        pl.plot(m, ans_l, 'ro', label = 'Lagrange Method')
181
        pl.plot(m, ans_n, 'b-', label = 'Newton Method')
182
        pl.legend()
183
        pl.xlabel('X')
184
        pl.ylabel('Y')
```

185 pl.show()

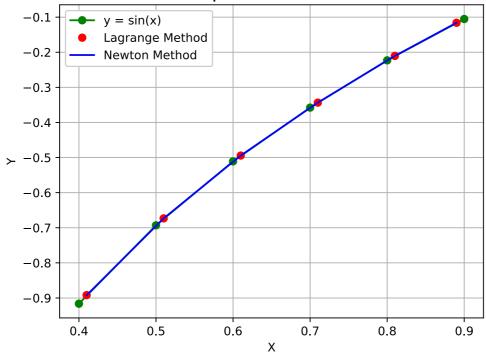
Code Box 2

输出结果



输出结果 3





输出结果 4

代码分析

牛顿后插公式,就是在等距节点的基础上,简化了差商的计算,但是需要计算一个独立的差分表。差分表的构建需要依据前插还是后插,其中前插表得到的是一个上三角矩阵,后插公式得到的是一个下三角矩阵。得到了差分表,就可以根据对角线元素,构建差商表。然后根据题目1的已有代码,即可做出图像。

五、实验体会

本次实验难度较小,代码量不算大。

之前想过用 MATLAB 做 03 号实验,但是后来还是决定继续采用 Python3,首先是平台比较开放,其次是本次基本不涉及矩阵,就算是涉及到矩阵运算,也已经有了一个由我独立设计的比较完善的 Python 包,所以坚持 Python 可能是一个比较好的选择。

插值算法的核心在于解方程组。而在牛顿插值多项式中,引入差商概念,用差商推导出了一般的插值计算公式,同时给出了很明确的算法与误差估计。其形式与泰勒展开式非常相似,余项也和泰勒公式非常像。

六、参考文献

[1] 金一庆, 陈越, 王冬梅. 数值方法[M]. 北京: 机械工业出版社; 2000.2.