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Forecasting Stock Market Indices Using the Recurrent Neural Network Based Hybrid Models: CNN-LSTM, GRU-CNN, and Ensemble Models

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Abstract: Various deep learning techniques have recently been developed in many fields due to the rapid advancement of technology and computing power. These techniques have been widely applied in finance for stock market prediction, portfolio optimization, risk management, and trading strategies. Forecasting stock indices with noisy data is a complex and challenging task, but it plays an important role in the appropriate timing of buying or selling stocks, which is one of the most popular and valuable areas in finance. In this work, we propose novel hybrid models for forecasting the one-time-step and multi-time-step close prices of DAX, DOW, and S&P500 indices by utilizing recurrent neural network (RNN)-based models; convolutional neural network-long short-term memory (CNN-LSTM), gated recurrent unit (GRU)-CNN, and ensemble models. We propose the averaging of the high and low prices of stock market indices as a novel feature. The experimental results confirmed that our models outperformed the traditional machine-learning models in 48.1% and 40.7% of the cases in terms of the mean squared error (MSE) and mean absolute error (MAE), respectively, in the case of one-time-step forecasting and 81.5% of the cases in terms of the MSE and MAE in the case of multi-time-step forecasting.



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Keywords: deep learning; convolutional neural networks; recurrent neural networks; long short-term memory; gated recurrent unit; ensemble model; feature engineering

1. Introduction

Forecasting stock market indices is one of the most critical yet challenging areas in finance, as a key task in investment management. The stock market indices are used to formulate and implement economic policy, and they are also used to inform decisions about the timing and size of various investments, such as stocks and real estate for investors.

In finance, stock market forecasting is one of the most challenging tasks due to the inherently volatile, noisy, dynamic, nonlinear, complex, non-parametric, non-stationary, and chaotic nature of stock markets, making any prediction model subject to large errors [1,2]. Additionally, price fluctuations are influenced not only by historical stock trading data, but also by nonlinear factors, such as political factors, investor behavior, and unexpected events [3–6].

To overcome these difficulties, numerous studies have been conducted over the past decades to predict various types of financial time-series data.

Linear models, such as the autoregressive and moving average (ARMA) and autoregressive integrated moving average (ARIMA) models have achieved high predictive accuracy in predicting stock market trends. However, traditional statistical models assume that financial time series are linear, which is not the case in real-world scenarios. Meanwhile, as many machine learning techniques capture nonlinear relationships from the data [7], they might be very useful for decision-making with respect to financial market investments [8].

A variety of deep learning models has been shown to significantly improve upon previous machine learning models in tasks, such as speech recognition, image captioning, question answering, natural language processing, autonomous self-driving cars, sports, arts, and regression tasks [9–11]. Deep-learning-based models have also been widely used in financial areas, such as forecasting stock price and index, portfolio optimization, risk management, financial information processing, and trade execution strategies.

In particular, RNNs, LSTMs, and GRUs have been designed to deal with time-series data and have been shown to perform better than traditional time-series models when a series of previous events is essential to predict future events. Thus, they have been actively applied to tasks, such as stock market index prediction and language translation [12,13].

RNNs have many advantages when processing short sequences. However, when the distance between the relevant information and the point using the information increases, the learning ability of the network is significantly reduced. The reason for this problem is that the back-propagation algorithm has difficulty in long-term dependency learning. In the process of updating the weights, the gradient disappears as values smaller than one are continuously multiplied, which is called the vanishing gradient problem. To solve the long-term dependency problem of RNNs, the LSTM and GRU models have been proposed, which represent the transformation algorithms of RNNs. In the LSTM model, a structure called the cell state is added to resolve long-term dependencies. Additionally, three additional input, forget, and output gates are added where the data are computed, which partially solves the problem of long-term dependencies by storing each state value in a memory space cell. The GRU is similar to LSTM; however, it has only update and reset gates and no output gate, thus being a simpler model with fewer parameters than LSTM. Recently, the LSTM model has shown great success in various domains, including speech recognition and machine translation, outperforming vanilla RNNs and conventional machine learning algorithms.

In this study, we propose hybrid models based on a variation of RNN models, such as LSTMs and GRUs, to improve stock market index prediction performance. The proposed models are divided into three types: a CNN-LSTM model that stacks a one-dimensional CNN and LSTM, a GRU-CNN model that stacks GRU and a one-dimensional CNN, and an ensemble model that takes the average value of each output result by placing RNN, LSTM, and GRU in parallel. The experiments were conducted on various daily stock market indices (i.e., Deutscher Aktienindex (DAX), Dow Jones Industrial Average (DOW), and Standard and Poor's 500 (S&P500)) for the periods from 1 January 2017 through 31 December 2019 and from 1 January 2019 through 31 December 2021 for three years before and after the COVID-19 pandemic, respectively. Additionally, we considered a long period of time from 1 January 2000 through 31 December 2019 for the DOW and S&P500 and from 24 October 2014 through 31 December 2019 for DAX because the DAX data were only available from 24 October 2014 in the pandas *DataReader* module.

We considered the look-back periods of 5, 21, and 42 days and look-ahead periods of one day for one-time-step and five days for multi-time-step prediction. To verify the robustness of our results, we compared our models with conventional deep-learning models such as RNN, LSTM, GRU, and WaveNet.

The main contributions of this study include the following:

- Novel RNN-based hybrid models are proposed to forecast one-time-step and multi-time-step closing prices of the DAX, DOW, and S&P500 indices by utilizing neural network structures: CNN-LSTM, GRU-CNN, and ensemble models.
- The novel feature, which is the average of the high and low prices of stock market indices, is used as an input feature.
- Comparisons between the proposed and traditional benchmark models with various look-back periods and features are presented.
- The experimental results indicate that the proposed models outperform the benchmark models in 48.1% and 40.7% of the cases in terms of the mean squared error (MSE) and mean absolute error (MAE), respectively, in the case of one-time-step forecasting

and 81.5% of the cases in terms of the MSE and MAE in the case of multi-time-step forecasting.

- Further, compared with previous studies that involved using open, high, and low prices, and trading volume of stock market indices as features, in this study, we evaluate the performance of our models by adding a novel feature to reduce the influence of the highest and lowest prices. The results confirm that the newly proposed feature contributes to improving the performance of the models in forecasting stock market indices.
- In particular, the ensemble model provides significant results for one-time-step forecasting.

The remainder of this paper is organized as follows. Section 2 presents an overview of deep learning models and reviews the relevant existing literature on stock market forecasting. Section 3 describes the proposed models designed using RNN-based hybrid architectures and provides the implementation details of the experiment, including the data and experimental setting. In Section 4, we present the experimental results, where we evaluate the proposed models on three stock market indices, compare them with benchmark models, and analyze the effect of the novel feature. Section 5 discusses the implications and advantages of the proposed models. Finally, Section 6 summarizes the conclusions of the study.

2. Background and Related Work

2.1. Deep-Learning Background

In this subsection, we review the artificial neural network (ANN), multilayer perceptron (MLP), CNN, RNN, LSTM, and GRU.

2.1.1. ANN

ANNs, also known as feedforward neural networks, are computing systems inspired by the biological human brain and consist of input, hidden, and output layers with connected neurons, wherein connections between neurons do not form a cycle. An ANN is capable of learning nonlinear functions and processing information in parallel [14]. Each neuron computes the weighted sum of all of its inputs, and a nonlinear activation function is applied to this sum to produce the output result of each neuron. The weights are adjusted to minimize a metric of the difference between the actual and predicted values of the data using the back-propagation algorithm [15].

2.1.2. MLP

The perceptron was proposed by [16] in 1943, representing an algorithm for the supervised learning of binary classifiers. As a linear classifier, a single-layer perceptron is the simplest feedforward neural network. Minsky and Papert [17] showed that a single-layer perceptron is incapable of learning the exclusive or (XOR) problem, whereas an MLP is capable of solving the XOR problem.

An MLP is a fully connected class of ANN. Attempts to solve linearly inseparable problems, such as the XOR problem, have led to different variations in the number of layers and neurons as well as nonlinear activation functions, such as a logistic sigmoid function or a hyperbolic tangent function [18].

2.1.3. CNN

The CNN was proposed to automatically learn spatial hierarchies of features in tasks, such as image recognition and speech recognition [19], by exploiting the spatial relationships among the pixels in an image. In [20], a CNN is composed of convolutional layers, pooling layers, and fully connected layers, and is trained with the adaptive moment estimation (Adam) optimizer on mini batches [21]. The convolutional layers extract the useful features, while the pooling layers reduce the dimensions of the feature maps. The rectified linear unit (ReLU) is applied as a nonlinear activation function [22], and a dropout layer is

used as a regularization method in which the output of each hidden neuron is set to zero with a given probability [23].

2.1.4. RNN

The assumption of a traditional neural network is that all the inputs are independent of each other, which makes them ineffective when dealing with sequential data and varied sizes of inputs and outputs [24]. The RNN is an extension of the conventional feedforward neural network and is well suited to sequential data, such as time series, gene sequences, and weather data.

An RNN has memory loops and handles a variable length of input sequence by having a recurrent hidden state [25]. It is known to have a shortcoming of a significant decrease in learning ability as the gradient gradually decreases during back-propagation when the distance between the relevant information and the point is long, which is called the vanishing gradient problem [26]. Errors from later time steps are difficult to propagate back to previous time steps, which results in difficulty in training deep RNNs to preserve information over multiple time steps because the gradients tend to either vanish or explode as they cycle through feedback loops [27]. To address this problem, Hochreiter and Schmidhuber [26] proposed the LSTM, which is capable of solving the vanishing gradient problem using memory cells.

2.1.5. LSTM

The LSTM was proposed by [26] as a variant of the vanilla RNN to overcome the vanishing or exploding gradient problem by adding the cell state to the hidden state of an RNN. The LSTM is composed of a cell state and three gates: input, output, and forget gates. The following equations describe the LSTM architecture.

The forget gate f_t determines which information is input to forget or keep from the previous cell state C_{t-1} and is computed as

$$f_t = \sigma(W_f \cdot [h_{t-1}, x_t] + b_f), \quad (1)$$

where x_t is the input vector at time t the function σ is a logistic sigmoid function.

The input gate i_t determines which information is updated to the cell state C_t and is computed by

$$i_t = \sigma(W_i \cdot [h_{t-1}, x_t] + b_i). \quad (2)$$

The candidate value \tilde{C}_t that can be added to the state is created by a tanh activation function and is computed by

$$\tilde{C}_t = \tanh(W_C \cdot [h_{t-1}, x_t] + b_C). \quad (3)$$

The cell state C_t can store information over long periods of time by updating the internal state and is computed by

$$C_t = f_t \odot C_{t-1} + i_t \odot \tilde{C}_t, \quad (4)$$

where the operator \odot represents the element-wise Hadamard product.

The output gate o_t determines what information from the cell state to be used as an output by taking the logistic sigmoid activation function, and is computed by

$$o_t = \sigma(W_o \cdot [h_{t-1}, x_t] + b_o), \quad (5)$$

and the output h_t is computed as

$$h_t = o_t \odot \tanh(C_t), \quad (6)$$

where W_* and b_* represent weight matrices and bias vectors, respectively.

RNN-based models have been used to predict time-series data. Fischer and Krauss [43] showed that LSTM outperformed memory-free classification methods, such as random forests, deep ANNs, and logistic regression classifiers, in prediction tasks. Dutta et al. [44] proposed the GRU model with recurrent dropout to predict the daily cryptocurrency prices.

Other deep learning models have been applied for time series forecasting. Heaton et al. [45] stacked autoencoders to predict and classify stock prices and their movements. Abrishami et al. [7] used a variational autoencoder to remove noise from the data and stacked LSTM to predict the close price of stocks. Wang et al. [2] used wavelet transform to forecast time-series data.

Moreover, various architectures combining deep learning-based models have been proposed in the literature. Ilyas et al. [46] combined technical and content features via learning time series and textual data, Livieris et al. [47] introduced the CNN-LSTM model to predict gold prices and movements, while Daradkeh [6] integrated a CNN and a bidirectional LSTM to predict stock trends. Zhang et al. [4] combined attention and LSTM models for financial time series prediction. Livieris and Pintelas [48] proposed ensemble learning strategies with advanced deep learning models for forecasting cryptocurrency prices and movements. Bao et al. [24] combined wavelet transforms, stacked autoencoders, and LSTM to forecast the closing stock prices for the next day by eliminating noise from the data and generating deep high-level features. Meanwhile, Zhang et al. [49] proposed a novel architecture of a generative adversarial network (GAN) with an MLP as the discriminator and an LSTM as the generator for forecasting the closing price of stocks.

Further, Leung et al. [50] proposed a two-timescale duplex neurodynamic approach for solving the portfolio optimization problem, and several studies have applied an LSTM to construct a portfolio [36,51–55].

This study proposes three models by combining CNN and RNN-based models for predicting the stock market index. Additionally, in contrast to existing studies, which employed open, high, and low prices, trading volume, and change in stock market indices, we introduce a novel input feature: the average of high and low prices. Furthermore, the three proposed models are evaluated on three daily stock market indices with two different optimizers and four different features. Finally, we compare the performance of the proposed models with conventional benchmark models with respect to forecasting the closing prices of the stock market indices.

3. Materials and Methods

3.1. Proposed Models

Following Livieris and Pintelas [48], by combining prediction models, a bias is added, which in turn reduces the variance, resulting in a better performance than that of single models. Therefore, we propose three RNN-based hybrid models that predict the stock market indices for one-time-step and multi-time-step at a time.

3.1.1. Proposed CNN-LSTM Model

CNNs can effectively learn the internal representations of time-series data [47]. The one-dimensional convolutional layer filters out the noise, extracts spatial features, and reduces the number of parameters. The causal convolution ensures that the output at time t derives only inputs from time $t - 1$. RNNs are considered the best sequential deep-learning models for forecasting time-series data. To this end, we combine a one-dimensional CNN and an LSTM in a new model: CNN-LSTM. The CNN-LSTM model consists of (1) a one-dimensional convolutional layer, (2) an LSTM layer, (3) a batch-normalization layer, (4) a dropout layer, and (5) a dense layer.

To determine the best-performing parameters, we examined different variants of the model: the number of hidden layers (1 and 2), the number of neurons (64 and 128), the batch size (32 and 64), and the dropout rate (0.2 and 0.5).

The best-performing CNN-LSTM model comprised a one-dimensional convolutional layer with 32 filters of size 3 with a stride of 1, causal padding, and the ReLU activation

function; an LSTM layer with 128 units and tanh activation function; a batch-normalization layer; a dropout layer with a rate of 0.2; and a dense layer with a prediction window size of units and the ReLU activation function. Figure 1 illustrates the architecture of the proposed CNN-LSTM model, while Table 1 summarizes the configuration.

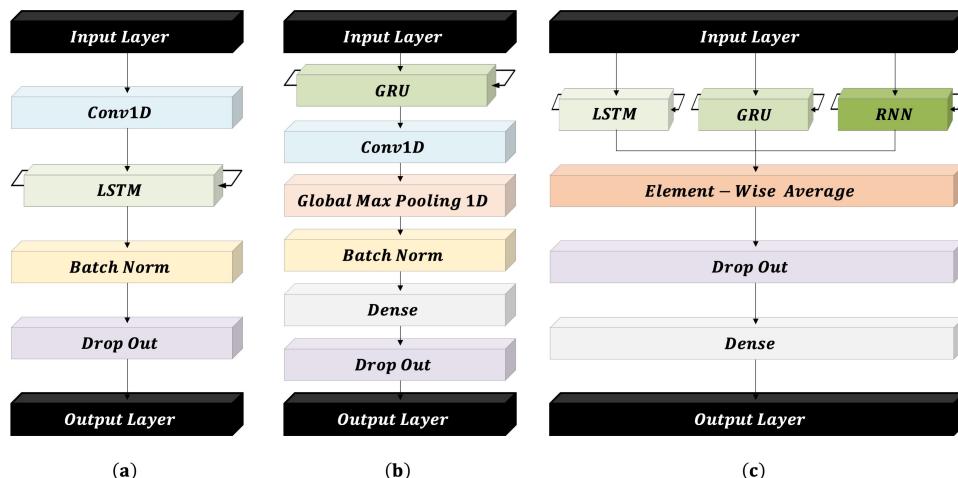


Figure 1. (a) Architecture of the CNN-LSTM model. (b) Architecture of the GRU-CNN model. (c) Architecture of the ensemble model.

Table 1. Model configuration of the proposed models.

Model	Description
CNN-LSTM	One-dimensional convolutional layer with 32 filters of size 3 with a stride of 1 LSTM layer with 128 units and tanh activation function Batch-normalization layer Dropout layer with a rate of 0.2 Dense layer with a prediction window size of units
GRU-CNN	GRU layer with 128 units and the tanh activation One-dimensional convolutional layer with 32 filters of size 3 with a stride of 1 One-dimensional global max-pooling layer Batch-normalization layer Dense layer with 10 units and the ReLU activation Dropout layer with a rate of 0.2 Dense layer with a prediction window size of units
Ensemble	RNN layer with 128 units and the tanh activation function LSTM layer with 128 units and the tanh activation function GRU layer with 128 units and the tanh activation function Average of all the hidden states from RNN, LSTM, and GRU Dropout layer with a rate of 0.2 Dense layer with 32 units and the ReLU activation function Dense layer with a prediction window size of units

3.1.2. Proposed GRU-CNN Model

The GRU is simpler than LSTM, has the ability to train sequential patterns, and takes less time to train the model with improved network performance. To utilize both GRU and one-dimensional CNN, we propose a stacked architecture where a GRU and a one-dimensional CNN are combined, namely the GRU-CNN model. The parameters used for the GRU-CNN model were similar to those of the CNN-LSTM model, as described in Section 3.1.1. The difference between the CNN-LSTM and GRU-CNN models is in the order of stacking the RNN and CNN layers.

The GRU-CNN model consists of a GRU layer with 128 units and the tanh activation function; a one-dimensional convolutional layer with 32 filters of size 3 with a stride of 1,

causal padding, and the ReLU activation function; a one-dimensional global max-pooling layer; a batch-normalization layer; a dense layer with 10 units and the ReLU activation function; a dropout layer with a rate of 0.2; and a dense layer with a prediction window size of units and the ReLU activation function. In the GRU-CNN model, the GRU layer returns a sequence, and the one-dimensional global max-pooling layer takes only important features and reduces the dimension of the feature map. The architecture of the proposed GRU-CNN model is illustrated in Figure 1, while the configuration is listed in Table 1.

3.1.3. Proposed Ensemble Model

While evaluating the performance of the benchmark models, various RNN models, such as RNN, LSTM, and GRU, exhibited high predictive performance on different types of datasets. There are three types of widely employed ensemble learning strategies: ensemble averaging, bagging, and stacking. Based on the results of the benchmarks, the CNN-LSTM, and the GRU-CNN as implemented above, we propose an average ensemble of three RNN-based models to achieve averaged high performance for various datasets. The proposed ensemble model can utilize the representations of the RNN, LSTM, and GRU models. The parameters used for the ensemble model were similar to those of the CNN-LSTM and GRU-CNN models, as described in Section 3.1.1.

The ensemble model consists of an RNN layer with 128 units and the tanh activation function; an LSTM layer with 128 units and the tanh activation function; a GRU layer with 128 units and the tanh activation function; followed by taking the average of all the hidden states from RNN, LSTM, and GRU; a dropout layer with a rate of 0.2; a dense layer with 32 units and the ReLU activation function; and a dense layer with a prediction window size of units and the ReLU activation function. Figure 1 illustrates the details of each layer of the proposed ensemble model, while Table 1 presents the configuration.

3.2. Implementation Details

In this subsection, we present an extensive empirical analysis of the proposed models on three datasets. First, we describe the datasets and the experimental setting used to demonstrate the validity of our financial time-series prediction models. Next, we evaluate the performance of our models on several datasets and compare them with those of conventional deep learning models.

3.2.1. Dataset

We evaluated the performance of the proposed models on daily stock market indices to verify the robustness of our models. We considered three stock market indices from major stock markets listed below.

- (1) DAX: Deutscher Aktienindex, which is a stock market index consisting of the 40 (expanded from 30 in 2021) major German blue-chip companies trading on the Frankfurt stock exchange.
- (2) DOW: Dow Jones Industrial Average, which is a stock market index of 30 prominent companies in the United States.
- (3) S&P500: Standard and Poor's 500, which is a stock market index of 500 large companies in the United States.

The DOW is the most influential and widely used stock market index in the literature. We considered three types of periods for all three indices: the period from 1 January 2000 through 31 December 2019 for DOW and S&P500 and from 24 October 2014 through 31 December 2019 for DAX as long periods; from 1 January 2017 through 31 December 2019 and from 1 January 2019 through 31 December 2021 as short periods before and after the COVID-19 pandemic, respectively.

The historical prices of each stock market index were obtained using the FinanceDataReader open-source library available in the pandas *DataReader* module of the Python programming language [56]. The raw data included six features: open, high, low, and close prices, trading volume, and change. The incomplete data were removed.

Before feeding the raw data into our models, we pre-processed the data. We normalized the raw data using Scikit-learn's *MinMaxScaler* tool, as follows:

$$x = \frac{x - x_{max}}{x_{max} - x_{min}}, \quad (11)$$

where x is the input feature of the stock market index and x_{max} and x_{min} are the maximum and minimum values of each input feature, respectively. Granger [57] suggested holding approximately 20% of the data for out-of-sample testing. Following this suggestion, the first 80% of the data were used as the training set for in-sample training, while the remaining 20% were used as the test set, to ensure that our models were evaluated on unseen out-of-sample data. The first 90% of the training set was used to train the network and to iteratively adjust its parameters such that the loss function was minimized. The trained network predicted the remaining 10% for validation, and the validation loss was computed after each epoch.

3.2.2. Generation of the Inputs and Outputs Using the Sliding Window Technique

This subsection describes the generation of the inputs and outputs. The daily open, high, and low prices, trading volume, and change were commonly used as input features in other studies. However, in the current study, we introduce a novel feature named medium, which is the average of high and low prices, to reduce the influence of the unusually extreme highest and lowest prices and to ensure generalizability.

For each stock market index, the partial features of daily open, high, low, and medium prices, trading volume, and change (OHLMVC) were used as the input to train the model, and the daily close prices were used as the output to predict one-time-step and multi-time-step ahead.

For the input and output generation, the normalized data were segmented using the sliding window technique, by which a fixed window size of time-series data was chosen as the input and a fixed number of the following observations was chosen as the output. This process was repeated for the entire dataset by sliding the window in intervals of one time step to obtain the next input and output. We trained the proposed models to look at m consecutive past data of features. The input at time t was denoted by

$$\mathbf{X}_t = (\mathbf{x}_t^O, \mathbf{x}_t^H, \mathbf{x}_t^L, \mathbf{x}_t^M, \mathbf{x}_t^V, \mathbf{x}_t^{Ch}) \in \mathbb{R}^{m \times 6}, \quad (12)$$

where for each $k \in \{O, H, L, M, V, Ch\}$,

$$\mathbf{x}_t^k = (x_{t-m+1}^k, \dots, x_{t-1}^k, x_t^k)^T \in \mathbb{R}^m, \quad (13)$$

$\mathbf{x}^O, \mathbf{x}^H, \mathbf{x}^L, \mathbf{x}^M, \mathbf{x}^V$, and \mathbf{x}^{Ch} are the daily open, high, low, and medium prices, trading volume, and change from time $t - m + 1$ to time t , respectively.

The input \mathbf{X}_t was fed sequentially into the proposed models to predict the following n daily close prices of stock market indices, with the output denoted by

$$\mathbf{y}_{t+1}^C = (y_{t+1}, y_{t+2}, \dots, y_{t+n})^T \in \mathbb{R}^n. \quad (14)$$

The look-back periods of 5, 21, and 42 days were considered as one week, one month, and two months, respectively; while the look-ahead periods of one and five days were considered to predict the future one-time-step or multi-time-step ahead. Figure 2 illustrates the sliding window technique.

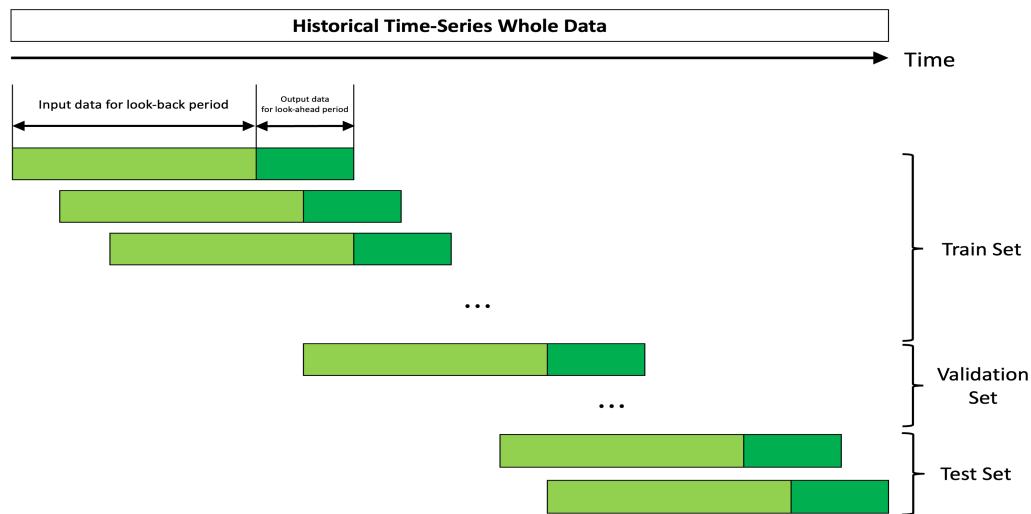


Figure 2. Sliding window technique.

3.2.3. Software and Hardware

The proposed models were implemented, trained, and analyzed in Python 3.7.6 [58] with the Keras library 2.4.3 [59] as a high-level neural network API using TensorFlow 2.3.1 as back-end [60], relying on NumPy 1.19.2 [61], Pandas 0.25.3 [56], and Scikit-learn 1.0.2 [62]. The code used for producing the figures and analysis is available on GitHub at <https://github.com/hyunsunsong/Project>.

All experiments were performed using a workstation equipped with an Intel Xeon Silver 4208 CPU at 2.10 GHz x8, Nvidia GPU TITAN, and 12 GB RAM on each board.

3.2.4. Experimental Setting

The proposed models were trained with the Huber loss function, which combines the characteristics of MSE and MAE and is less susceptible to outliers in the data than the MSE loss function [63]. It behaves quadratically for small residuals and linearly for large residuals [64]. The parameters of the network were learned to minimize the average of the Huber loss function over the entire training dataset.

The network weights and biases were initialized with the Glorot–Xavier uniform method and zeros, respectively. Glorot and Bengio [65] proposed the Glorot–Xavier uniform method to adopt a properly scaled uniform distribution for initialization.

The successful applications of neural networks require regularization [66]. Introduced by [23], the dropout regularization technique randomly drops a fraction of the units with a specified probability, along with connections during training, while all units are presented during testing. We applied the dropout values of 0.2 and 0.5 to reduce overfitting and have observed that higher dropout value result in a decline in performance. Therefore, we settled on the relatively low dropout value of 0.2 as studied in [67].

The batch size and maximum number of epochs were set to 32 and 50, respectively, and an early stopping patience of 10 was applied [68]. That is, once the validation loss no longer decreased for the patience period, the training was stopped, and the weights of the model with the lowest validation loss were restored using ModelCheckpoint callback in the Keras library [59].

The optimization algorithms used for training were the Adam and root mean square propagation (RMSProp) [69], which are adaptive learning rate methods. The RMSProp is usually a viable choice for RNNs [59]. We compared the performance of the proposed models using two different optimizers.

We applied learning rates of 0.001 and 0.0005 and found that a learning rate of 0.0005 resulted in a better performance. Therefore, the learning rate was set to 0.0005.

The ReLU activation function proposed in [22] was used for the dense layers, and the data shuffling technique was not used during training.

3.2.5. Predictive Performance Metrics

In this study, we adopted the MSE and MAE as evaluation metrics to compare the performance of the proposed models with that of conventional benchmark models for forecasting time-series data, which are calculated as follows:

$$\text{MSE} = \frac{1}{T} \sum_{t=1}^T (y_t - \hat{y}_t)^2, \quad (15)$$

$$\text{MAE} = \frac{1}{T} \sum_{t=1}^T |y_t - \hat{y}_t|, \quad (16)$$

where T is the number of prediction time horizons; y_t and \hat{y}_t are the true and predicted values, respectively, during one-time-step prediction. During multi-time-step prediction, we only used the value of the last time step; thus, y_t and \hat{y}_t represent the true and predicted values of the last time step, respectively.

4. Experimental Results

In this section, we present the experimental results of the proposed models using historical time-series data for three stock market indices: DAX, DOW, and S&P500. We first describe the details of the benchmark models used for comparison. Second, we compare the results for the proposed models and conventional benchmarks with respect to one-time-step and multi-time-step predictions on three datasets over three different periods. Third, we present the results of the impact of different features and optimizers on the performance of the proposed models.

4.1. Benchmark Models

For benchmark comparison, we deploy several conventional deep learning models, such as RNN, LSTM, and GRU, to examine whether the proposed models outperform the benchmarks. In addition, we utilize WaveNet, which combines causal filters with dilated convolutions, so that the model learns long-range temporal dependencies in time-series data [70]. The benchmark models and corresponding architectures are listed below.

1. RNN: Two RNN layers with 128 units and a dense layer with a look-ahead period of units;
2. LSTM: An LSTM layer with 128 units and a dense layer with a look-ahead period of units;
3. GRU: A GRU layer with 128 units and a dense layer with a look-ahead period of units;
4. WaveNet: A simpler architecture of an audio generative model based on Pixel-CNN [71], as described in [70].

Table 2 lists the training setting for the benchmark models. All benchmark models were trained with 50 epochs, an early stopping patience of 10, a learning rate of 0.0005, a batch size of 32, the MSE loss function, the Adam optimizer, and the ReLU activation function.

Table 2. Hyperparameter setting for the benchmark models.

Hyperparameter	Value
Number of epochs	50
Early stopping patience	10
Learning rate	0.0005
Batch size	32
Loss function	MSE
Optimizer	Adam
Activation function	ReLU

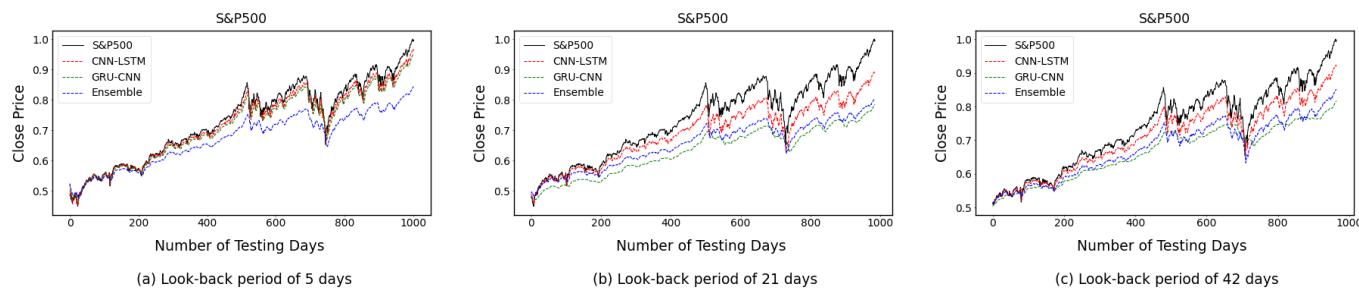


Figure 5. Comparison of true and predicted close prices of the S&P500 index between different look-back periods for one-time-step prediction over the period from 1 January 2000 through 31 December 2019.

Moreover, the proposed models were trained for 1500 epochs with the Adam optimizer and a look-back period of 5 days. The comparisons of true and predicted close prices of the DAX, DOW, and S&P500 indices between different input features for one-time-step prediction are provided in Figures 6–8, respectively.

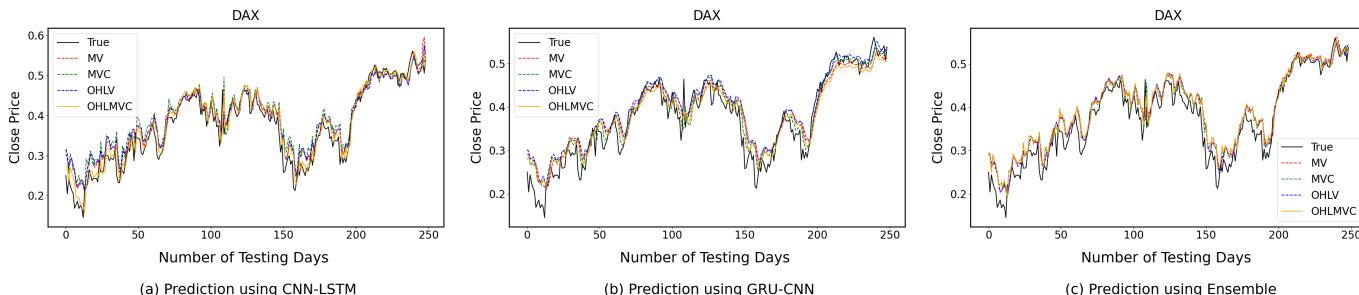


Figure 6. Comparison of true and predicted close prices of the DAX index between different input features for one-time-step prediction over the period from 24 October 2014 through 31 December 2019.

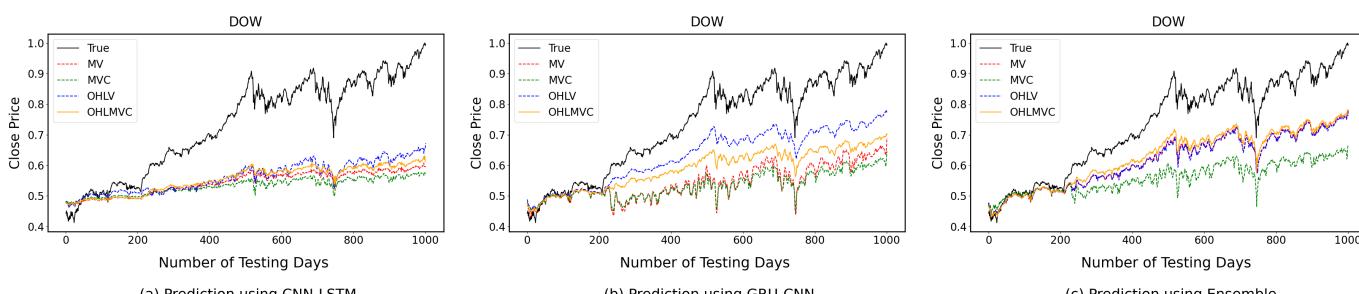


Figure 7. Comparison of true and predicted close prices of the DOW index between different input features for one-time-step prediction over the period from 1 January 2000 through 31 December 2019.

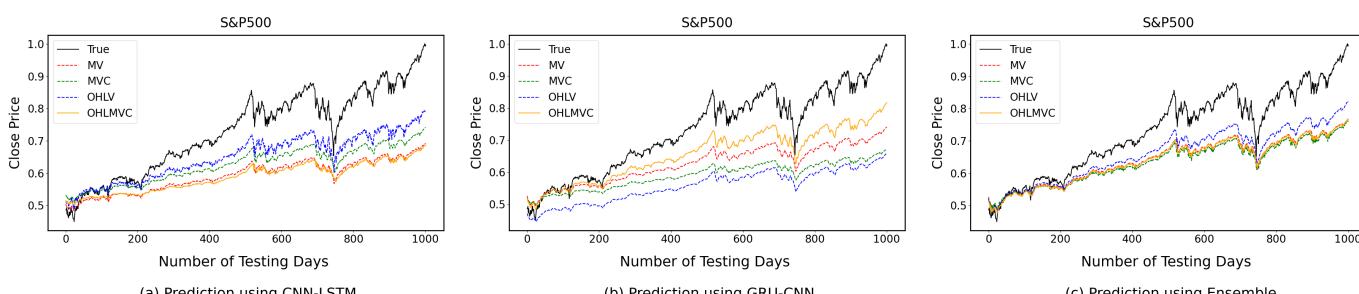


Figure 8. Comparison of true and predicted close prices of the S&P500 index between different input features for one-time-step prediction over the period from 1 January 2000 through 31 December 2019.

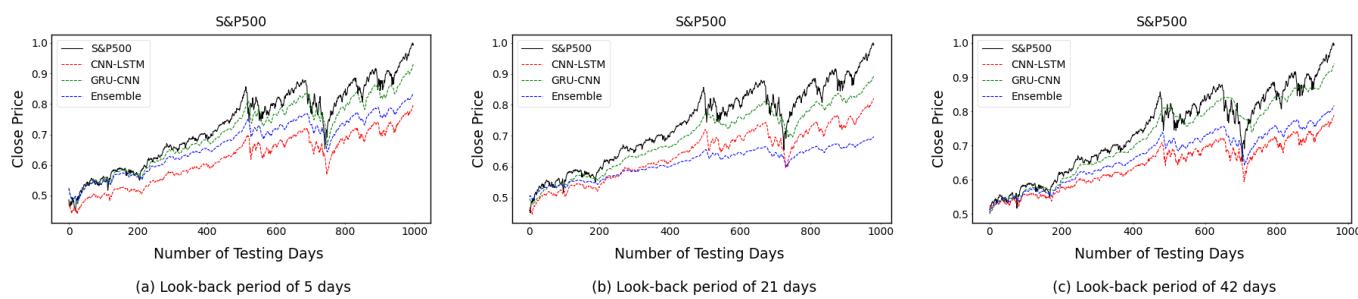


Figure 11. Comparison of true and predicted close prices of the S&P500 index between different look-back periods for five-time-step prediction over the period from 1 January 2000 through 31 December 2019.

Moreover, the proposed models were trained for 1500 epochs with the Adam optimizer and a look-back period of 5 days. The comparisons of true and predicted close prices of the DAX, DOW, and S&P500 indices between different input features for five-time-step prediction are provided in Figures 12–14, respectively.

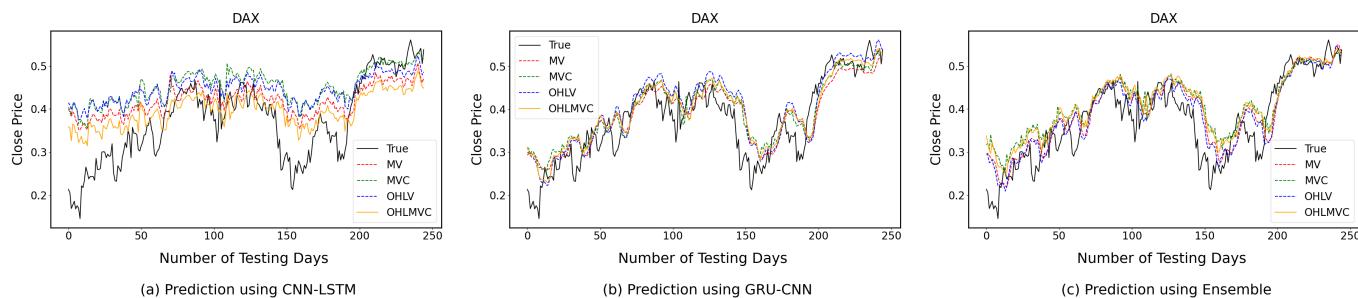


Figure 12. Comparison of true and predicted close prices of the DAX index between different input features for five-time-step prediction over the period from 24 October 2014 through 31 December 2019.

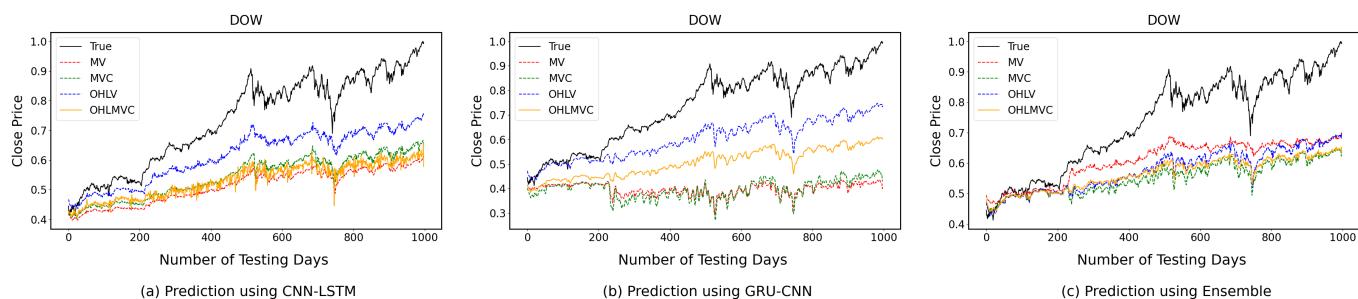


Figure 13. Comparison of true and predicted close prices of the DOW index between different input features for five-time-step prediction over the period from 1 January 2000 through 31 December 2019.

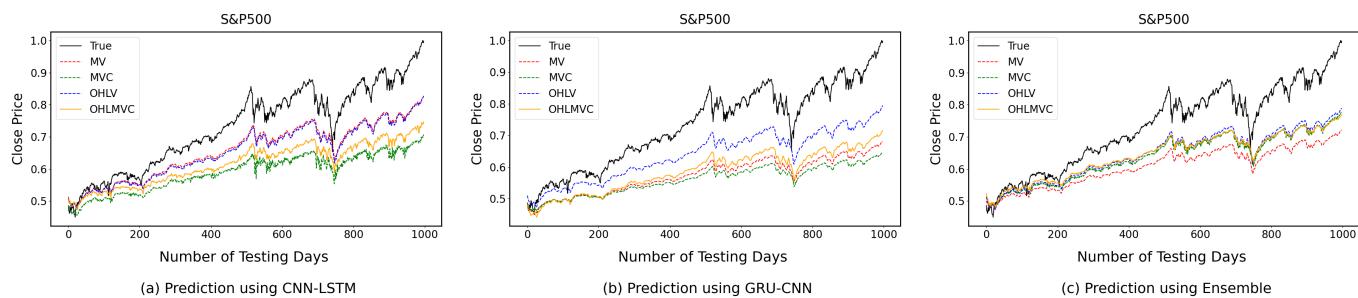


Figure 14. Comparison of true and predicted close prices of the S&P500 index between different input features for five-time-step prediction over the period from 1 January 2000 through 31 December 2019.

5. Discussion

Various deep-learning techniques have been applied extensively in the field of finance for stock market prediction, portfolio optimization, risk management, and trading strategies. Although forecasting stock market indices with noisy data is a complex and challenging process, it significantly affects the appropriate timing of buying or selling investment assets for investors as they reduce the risk, which is one of the most valuable areas in finance.

Combining multiple deep-learning models results in a better performance [48]. We proposed to integrate RNNs, namely, CNN-LSTM, GRU-CNN, and ensemble models. The proposed models were evaluated to forecast the one-time-step and multi-time-step closing prices of stock market indices using various stock market indices, look-back periods, optimizers, features, and the learning rate.

The experimental results revealed that the proposed models that combine variants of RNNs outperformed the traditional machine learning models, such as RNN, LSTM, GRU, and WaveNet in most cases. In particular, the ensemble model produced significant results for one-time-step forecasting. Moreover, compared with the performance of previous studies that used open, high, and low prices and trading volume of stock market indices as features, that of our models improved by incorporating the proposed novel feature, which is the average of the high and low prices. Furthermore, our models with MV features provided favorable results in numerous cases. Notably, reducing the number of features could be interpreted as circumventing the overfitting.

The performance of the proposed and benchmark models with the Adam optimizer and OHLV features over three periods were evaluated to predict one-time-step and five-time-step using look-back periods of 5, 21, and 42 days as provided in Tables 3 and 6, respectively. The comparisons of the average MSE and MAE over three periods for different look-back and look-ahead periods are provided in Figures 15 and 16, respectively. An overall comparison between the ensemble model and other models in Figures 15 and 16 indicates that the ensemble model significantly outperformed the other models.

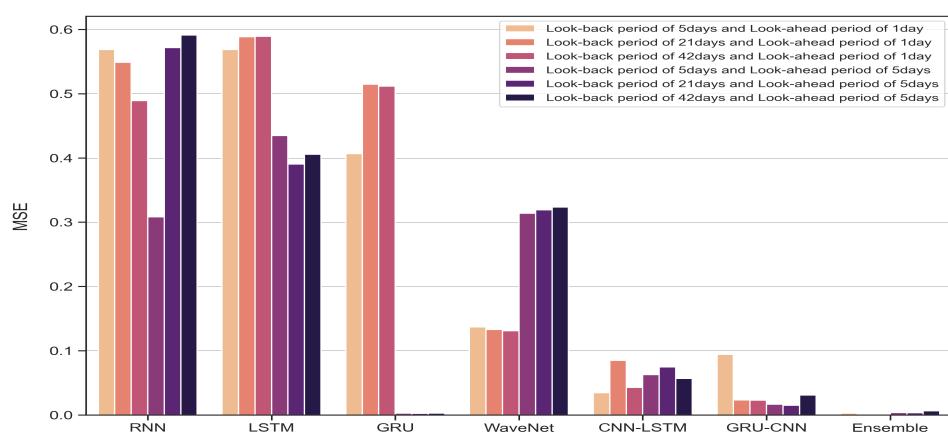


Figure 15. Comparison of the average MSE over three periods for different look-back and look-ahead periods using RNN, LSTM, GRU, WaveNet, CNN-LSTM, GRU-CNN, and ensemble with OHLV features.

In addition, the performance of the proposed and benchmark models over three periods were evaluated to compare the impact of four different input features (i.e., MV, MVC, OHLV, and OHLMVC) for one-time-step and five-time-step predictions with three look-back periods and two optimizers as described in Section 3.2. The comparisons of the average MSE and MAE of the proposed and benchmark models over all periods, optimizers, look-back, and look-ahead periods are provided in Figures 17 and 18, respectively. The proposed models outperform the benchmark models and the performance of our models improves by incorporating the proposed medium feature.

Further, compared with other forecasting methods in other fields, the proposed framework herein can be applied to forecasting time-series data, such as energy consumption, oil price, gas concentration, air quality, and river flow. Moreover, the performance of forecasting can be improved by combining different types of RNN-based models and constructing a portfolio using predicted stock market prices in future studies.

6. Conclusions

In this paper, we proposed three RNN-based hybrid models, namely CNN-LSTM, GRU-CNN, and ensemble models, to make one-time-step and multi-time-step predictions of the closing price of three stock market indices in different financial markets. We evaluated and compared the performance of the proposed models with conventional benchmarks (i.e., RNN, LSTM, GRU, and WaveNet) over three different periods: a long period of more than 15 years and two short periods of three years before and after the COVID-19 pandemic. The proposed models significantly outperformed the benchmark models by achieving high predictive performance for various sizes of look-back and look-ahead periods in terms of MSE and MAE. Moreover, we found that the proposed ensemble model was comparable to the GRU, which performed well among benchmarks and outperformed the benchmarks in many cases.

Additionally, we introduced a novel feature, medium, which is the average of high and low prices, and evaluated the performance of the proposed models with four different features and two different optimizers. The results indicated that incorporating the novel feature improved model performance. Overall, our experiments verified that the proposed models outperformed the benchmark models in many cases and that incorporating the medium feature improved their performance.

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Abbreviations

The following abbreviations are used in this manuscript:

Adam	Adaptive Moment Estimation
ANN	Artificial Neural Network
ARIMA	Autoregressive Integrated Moving Average
ARMA	Autoregressive and Moving Average
CNN	Convolutional Neural Network
DAX	Deutscher Aktienindex
DOW	Dow Jones Industrial Average
GAN	Generative Adversarial Network
GRU	Gated Recurrent Unit
LSTM	Long Short Term Memory
MAE	Mean Absolute Error
MLP	Multilayer Perceptron

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