Wildfire Detection with a CNN Ensemble 1INF52 Deep Learning

CPSquad

PUCP

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Introduction and Problem Statement

- The increasing frequency of wildfires has led to a demand for automated monitoring systems.
- Traditional methods (satellites, thermal sensors) suffer from delayed data retrieval.
- Deep learning techniques can be used to improve detection speed and accuracy.



Figure 1: Wildfire in Peru. Source: Daily Sabah

Research Motivation and Goals

Objective of this Study

- Develop an ensemble of CNNs for wildfire detection in aerial images.
- Evaluate the performance of Xception,
 DenseNet121, and ResNet152.
- Improve classification accuracy while keeping computational efficiency.

Traditional Approaches to Wildfire Detection

- Sensor-based methods: Use temperature, smoke, and gas sensors, but have limited coverage.
- Classic Computer Vision methods: Use color-based segmentation, but suffer from high false positives.
- Machine Learning and Deep Learning approaches:
 - CNN-based classification (e.g., Xception, DenseNet, ResNet).
 - Object detection with YOLOv8.
 - Vision Transformers (ViTs) for feature extraction.

Baseline Model: FireSight (Stanford)

- FireSight combines CNNs and ViTs for aerial wildfire detection.
- Achieves 82.28% accuracy and an F1-score of 0.75 using a DenseNet + ResNet + ViT ensemble.
- Our approach:
 - Perform Transfer Learning on Xception, DenseNet, and ResNet using pre-trained weights.
 - Improve each model's performance by unfreezing and training the last layers to refine feature extraction.
 - Ensemble the fine-tuned models using a voting-based strategy to compare against the SOTA baseline.

FLAME Dataset Overview

- The dataset contains drone-captured images of wildfires.
- Designed specifically for binary wildfire classification (Fire vs No Fire).
- Training Set: 39,375 images
- Test Set: 8,617 images.
- Validation Split: 10% of training set.
- Class Distribution:
 - Fire: 25,027 images (63.55%).
 - No-Fire: 14,357 images (36.45%).



Figure 2: Sample FLAME dataset image.

Pipeline for Model Training

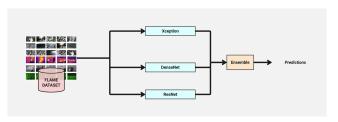


Figure 3: Model Architecture

- Preprocessing: Images resized to 224x224 and augmented.
- **Training Strategy:** Individual CNNs trained separately.
- Evaluation: Models compared based on accuracy, precision, recall, and F1-score.

Keras Tuner for Hyperparameter Search

- Keras Tuner used for optimizing batch size, dropout, L2 regularization, and learning rate.
- Best hyperparameters found:

Model	Batch Size	Dropout	L2 Factor	Learning Rate
Xception	10	0.45	0.001	0.00541
DenseNet121	64	0.35	0.001	0.00147
ResNet152	64	0.4	0.0005	0.00093

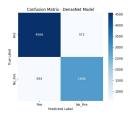
Why Use an Ensemble?

- Goal: Improve model stability and accuracy.
- We experimented with:
 - Majority Voting (Final Selection).
 - Weighted Averaging.
 - Stacking.

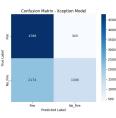
Final Approach: Voting

- Each model votes on the predicted class.
- The most frequent class is the final prediction.

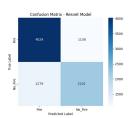
Confusion Matrices



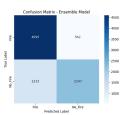
DenseNet



Xception



ResNet



Ensemble

Final Model Performance

Model	Baseline		Our Models	
	F1-score	Accuracy	F1-score	Accuracy
Xception	0.58	49.09%	0.5087	70.72%
DenseNet	0.53	70.35%	0.8324	86.5%
ResNet	0.61	73.2%	0.6484	72.3%
Ensemble (Voting)	0.75	81.94%	0.7169	79.4%

Key Takeaways

- DenseNet121 and Xception models outperformed the ensemble in some metrics.
- The ensemble's advantage might be due to the use of Vision Transformers (ViTs).
- Close-to-SOTA results may be due to this dataset not being used at scale with recent models.
- **Keras Tuner** was crucial for finding the best hyperparameters, improving individual models.
- Future Work:
 - **Pruning** to reduce model size and improve inference speed.
 - Distillation to compress into a lighter architecture like MobileNetV3.

Thank You!



Our code is available at:

github.com/Litusuwu/DeepLearning_Project

Trained models can be found at:

huggingface.co/superflash41/fire-chad-detector-v1.0