MATH 759: PROBLEM SET 2 SOLUTIONS ARE IN CLASS ON MON. SEP. 30.

1. Show that the sl(n) and so(n) are Lie algebras associated to Lie groups SL(n) and SO(n), respectively.

On a Lie algebra one can define the exponential map (exp : $\mathfrak{g} \to G$ in the following way. Given $X_e \in \mathfrak{g}$, let X be the left-invariant vector field as in the notes. Let $\gamma(t)$ be the solution of

$$\gamma'(t) = X(\gamma(t)), \qquad \gamma(0) = e.$$

Define $\exp(X_e) = \gamma(1)$. Compute the exponential map on sl(n).

Then show that the bracket in the Lie algebra sl(n) can be represented as a commutator of matrices.

2. Let $L_2(V \otimes W)$ be the set of all bilinear functions from $V \times W \to \mathbb{R}$. Show that

$$(V \otimes W)^* \cong L_2(V, W) \cong V^* \otimes W^*.$$

- 3. Show that a manifold is orientable if and only if there exists a volume form on the manifold. A volume form on an n-dimensional manifold \mathcal{M} an n-form which is not equal to zero at any point of the manifold.
- 4. Pull-back of a (0,s) tensor. Let $\Phi: \mathcal{M} \to \mathcal{N}$ be a differentiable mapping and S a (0,s) tensor on \mathcal{N} . The pull back of S is the (0,s) tensor Φ^*S on \mathcal{M} defined as follows:

$$\Phi^*S|_p(v_1,\ldots,v_s) = S|_{\Phi(p)}(D\Phi v_1,\ldots D\Phi v_s) \quad \text{ for all } v_1,\ldots,v_s \in T_p\mathcal{M}.$$

Pullback of differential forms is defined analogously. Show that

- (i) $\Phi^*(S_1 \otimes S_2) = \Phi^*(S_1) \otimes \Phi^*(S_2)$
- (ii) For any two differential forms ω_1 and ω_2 on \mathcal{M} , $\Phi^*(\omega_1 \wedge \omega_2) = \Phi^*(\omega_1) \wedge \Phi^*(\omega_2)$
- (iii) Exterior derivative and pullback commute; that is for any from ω

$$\Phi^*(d\omega) = d\Phi^*(\omega).$$

5. Let ω be a 1-form on S^2 . Think of S^2 as embedded in \mathbb{R}^3 . Assume that for any $\phi \in SO(3)$, $\phi^*\omega = \omega$. Show that $\omega = 0$.