

Tianlang Liu | Vision Algorithm Engineer | Portfolio

# Portfolio

Computer Vision & Anomaly Detection for Industrial Systems

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# Surface Defect Detection with 2D + 3D Fusion

**Tech Stack:** Mask RCNN, PCL, Python, OpenCV

## **Problem:**

Surface **holes** were often **missed by standard 2D Mask RCNN detection**, leading to false negatives and quality concerns.

## **Solution:**

Developed a detection algorithm based on integration of **point cloud** and 2D images using Mask RCNN, checking suspected areas with **2D features, 3D features and registered areas depth**.

## **Results:**

**Reduced manual inspectors from 12 to 0**; achieved **0% missed defects and <0.4% false alarms** across 200k+ products.

## **My Contribution:**

Independently handled **data preprocessing**, model design and training, **PCL-based postprocessing**, and deployment scripting.

# Die Surface Damage unsupervised Detection

**Tech Stack:** PatchCore, OpenCV, PyTorch

## **Problem:**

Unseen defects on the die surface caused **YOLO to miss detections**. Retraining was not feasible due to the limited defect samples.

## **Solution:**

Applied **unsupervised anomaly detection** using PatchCore and **post-classification** with ResNet, combined with classical image preprocessing in OpenCV to enhance contrast and localization of anomalies.

## **Results:**

Achieved **0% missed defects** and **<0.14% false alarms** on over **200,000 units**, significantly improving early-stage defect detection.

## **My Contribution:**

Designed the **full inspection pipeline**, tuned feature extraction and thresholding, and validated the system in large-scale production environments.

# YOLOv8 Small Object Detection with Self-Attention

Tech Stack: YOLOv8, PyTorch, OpenCV

## Problem:

Standard YOLOv8 models **struggled with detecting small wrinkles in X-ray images**, leading to missed defects and unstable recall.

## Solution:

**Integrated a self-attention mechanism into the YOLOv8** architecture to improve focus on small targets. Enhanced the feature representation for subtle defects while maintaining real-time inference speed in offline batch mode.

## Results:

Achieved **0% missed defects and <0.3% false alarms** on offline inspection batches, significantly improving small-defect recall compared to baseline YOLO.

## My Contribution:

Modified the **YOLOv8 backbone and attention structure**, trained and validated the model on defect datasets, and integrated it into the existing pipeline for batch analysis.

# Electrode Orientation Filtering using YOLO + DBSCAN

Tech Stack: YOLO, OpenCV, Scikit-learn (DBSCAN), Python

## Problem:

Electrodes **misaligned** in orientation were difficult to detect **using angle thresholds alone**, causing **defects to slip through** automated QA filters.

## Solution:

Used **YOLO** to detect electrode **masks** and evaluated their alignment via overlap with its ROI. Applied DBSCAN clustering on overlap scores to **dynamically determine threshold** boundaries and filter out outliers.

## Results:

Enabled reliable detection of orientation anomalies under varying production configurations. **Reduced human checking workload** and stabilized process quality.

## My Contribution:

**Modified the orientation filtering algorithm**, tuned **DBSCAN parameters** for dynamic thresholding, and implemented the full postprocessing logic in Python.