

## Solutions



# Chapter 2 Foundations of Probability

**2.1 (COMPOSING RANDOM ELEMENTS)** Show that if  $f$  is  $\mathcal{F}/\mathcal{G}$ -measurable and  $g$  is  $\mathcal{G}/\mathcal{H}$ -measurable for sigma algebras  $\mathcal{F}, \mathcal{G}$  and  $\mathcal{H}$  over appropriate spaces, then their composition,  $g \circ f$  (defined the usual way:  $(g \circ f)(\omega) = g(f(\omega)), \omega \in \Omega$ ), is  $\mathcal{F}/\mathcal{H}$ -measurable.

*Proof.* Since  $g$  is  $\mathcal{G}/\mathcal{H}$ -measurable, therefore  $\forall C \in \mathcal{H}, \exists B = g^{-1}(C) \in \mathcal{G}$ . Similarly, since  $f$  is  $\mathcal{F}/\mathcal{G}$ -measurable,  $\forall B \in \mathcal{G}, \exists A = f^{-1}(B) \in \mathcal{F}$ . Thus  $\forall C \in \mathcal{H}, \exists A = f^{-1}(g^{-1}(C)) = (g \circ f)^{-1}(C) \in \mathcal{F}$  and the proof is complete. □

**2.2** Let  $X_1, \dots, X_n$  be random variables on  $(\Omega, \mathcal{F})$ . Prove that  $X = (X_1, \dots, X_n)$  is a random vector.

*Proof.* Since  $X_i$  is a random variable ( $\forall i = 1, 2, \dots, n$ ), it holds that  $X_i$  is  $\mathcal{F}/\mathcal{B}(\mathbb{R})$ -measurable, which means that  $\forall B \in \mathcal{B}(\mathbb{R}), X_i^{-1}(B) \in \mathcal{F}$ . We first prove that  $X$  is  $\mathcal{F}/(\mathcal{B}(\mathbb{R}) \times \mathcal{B}(\mathbb{R}) \times \dots \times \mathcal{B}(\mathbb{R}))$ -measurable (totally  $n$   $\mathcal{B}(\mathbb{R})$ s).  $\forall A = A_1 \times A_2 \times \dots \times A_n \in \mathcal{B}(\mathbb{R}) \times \mathcal{B}(\mathbb{R}) \times \dots \times \mathcal{B}(\mathbb{R}), X^{-1}(A) = X_1^{-1}(A_1) \cap X_2^{-1}(A_2) \cap \dots \cap X_n^{-1}(A_n) \in \mathcal{F}$ , which holds since  $X_i^{-1}(A_i) \in \mathcal{F}, \forall i = 1, 2, \dots, n$  and  $\mathcal{F}$  is a  $\sigma$ -algebra. Thus we conclude that  $X$  is  $\mathcal{F}/(\mathcal{B}(\mathbb{R}) \times \mathcal{B}(\mathbb{R}) \times \dots \times \mathcal{B}(\mathbb{R}))$ -measurable.

By definition  $\mathcal{B}(\mathbb{R}^n) = \sigma(\mathcal{B}(\mathbb{R}) \times \mathcal{B}(\mathbb{R}) \times \dots \times \mathcal{B}(\mathbb{R}))$  (totally  $n$   $\mathcal{B}(\mathbb{R})$ s). And according to the property in 2.5(b), we can get that  $X$  is  $\mathcal{F}/\mathcal{B}(\mathbb{R}^n)$ -measurable, thus it is a random vector. □

**2.3 (RANDOM VARIABLE INDUCED  $\sigma$ -ALGEBRA)** Let  $\mathcal{U}$  be an arbitrary set and  $(\mathcal{V}, \Sigma)$  a measurable space and  $X : \mathcal{U} \rightarrow \mathcal{V}$  an arbitrary function. Show that  $\Sigma_X = \{X^{-1}(A) : A \in \Sigma\}$  is a  $\sigma$ -algebra over  $\mathcal{U}$ .

*Proof.* (i) We need to show that  $\Sigma_X$  is closed under countable union. Let  $U_i = X^{-1}(A_i), A_i \in \Sigma, i \in \mathbb{N}$ .

It follows that  $\bigcup_{i=1}^{\infty} U_i = \bigcup_{i=1}^{\infty} X^{-1}(A_i) = X^{-1}(\bigcup_{i=1}^{\infty} A_i)$ . Since  $\bigcup_{i=1}^{\infty} A_i \in \Sigma, \bigcup_{i=1}^{\infty} U_i \in \Sigma_X$ .

(ii) We need to show that  $\Sigma_X$  is closed under set subtraction  $-$ .  $\forall U_1, U_2 \in \Sigma_X, U_1 - U_2 = X^{-1}(A_1) - X^{-1}(A_2) = X^{-1}(A_1 - A_2)$ . Since  $A_1 - A_2 \in \Sigma, U_1 - U_2 \in \Sigma_X$ .

(iii) We need to show that  $\Sigma_X$  is closed to  $\mathcal{U}$  itself. Since  $\mathcal{U} = X^{-1}(\mathcal{V})$  and  $\mathcal{V} \in \Sigma$ , it follows that  $\mathcal{U} \in \Sigma_X$ . □

**2.4** Let  $(\Omega, \mathcal{F})$  be a measurable space and  $A \subseteq \Omega$  and  $\mathcal{F}|_A = \{A \cap B : B \in \mathcal{F}\}$ .

*Proof.* (a) (i) We need to show that  $\mathcal{F}|_A$  is closed under countable union. Let  $X_1 = A \cap B_1, X_2 = A \cap B_2, \dots$  and  $X' = \bigcup_{i=1}^{\infty} X_i$  and  $B' = \bigcup_{i=1}^{\infty} B_i$  where  $B_1, B_2, \dots \in \mathcal{F}$ . Since  $\mathcal{F}$  is sigma algebra,  $B' \in \mathcal{F}$ . Furthermore, since  $X' = \bigcup_{i=1}^{\infty} X_i = \bigcup_{i=1}^{\infty} A \cap B_i = A \cap \left( \bigcup_{i=1}^{\infty} B_i \right) = A \cap B'$ , we can see that  $X' \in \mathcal{F}|_A$ .

(ii) We need to show that  $\mathcal{F}|_A$  is closed under set subtraction  $-$ .  $\forall X_1, X_2 \in \mathcal{F}|_A, X_1 - X_2 = (A \cap B_1) - (A \cap B_2) = A \cap (B_1 - B_2)$ . Since  $B_1 - B_2 \in \mathcal{F}$ , it follows that  $X_1 - X_2 \in \mathcal{F}|_A$ .

- (iii) We need to show that  $\mathcal{F}|_A$  is closed to  $A$  itself. Since  $\emptyset \in \mathcal{F}$ , we have  $\emptyset = A \cap \emptyset \in \mathcal{F}|_A$  and  $A = \emptyset^C \in \mathcal{F}|_A$ .
- (b) Let  $P = \{A \cap B : B \in \mathcal{F}\}, Q = \{B : B \subset A, B \in \mathcal{F}\}$ .
- (i) We claim that  $P \subset Q$ . Let  $X = A \cap B, B \in \mathcal{F}$ . Since  $A \in \mathcal{F}, X = A \cap B \in \mathcal{F}$ . Furthermore,  $X \in Q = \{B : B \subset A, B \in \mathcal{F}\}$ .
- (ii) We claim that  $Q \subset P$ .  $\forall X \in Q$ , we have  $X \subset A$  and  $X \in \mathcal{F}$ , which means that  $X = X \cap A$  and  $X \in \mathcal{F}$ . It follows that  $X \in P$ .
- (iii) Take both (i)(ii) into consideration, we can see that  $P = Q$ .

□

**2.5** Let  $\mathcal{G} \subseteq 2^\Omega$  be a non-empty collection of sets and define  $\sigma(\mathcal{G})$  as the smallest  $\sigma$ -algebra that contains  $\mathcal{G}$ . By ‘smallest’ we mean that  $\mathcal{F} \in 2^\Omega$  is smaller than  $\mathcal{F}' \in 2^\Omega$  if  $\mathcal{F} \subset \mathcal{F}'$ .

- (a) Show that  $\sigma(\mathcal{G})$  exists and contains exactly those sets  $A$  that are in every  $\sigma$ -algebra that contains  $\mathcal{G}$ .
- (b) Suppose  $(\Omega', \mathcal{F})$  is a measurable space and  $X : \Omega' \rightarrow \Omega$  be  $\mathcal{F}/\mathcal{G}$ -measurable. Show that  $X$  is also  $\mathcal{F}/\sigma(\mathcal{G})$ -measurable. (We often use this result to simplify the job of checking whether a random variable satisfies some measurability property).
- (c) Prove that if  $A \in \mathcal{F}$  where  $\mathcal{F}$  is a  $\sigma$ -algebra, then  $\mathbb{I}\{A\}$  is  $\mathcal{F}$ -measurable.

*Proof.* (a) Let  $\mathcal{K} = \{\mathcal{F} | \mathcal{F} \text{ is a } \sigma\text{-algebra and contains } \mathcal{G}\}$ , It holds obviously that  $\mathcal{K}$  is not an empty set since it contains  $2^\Omega$ .

Then  $\bigcap_{\mathcal{F} \in \mathcal{K}} \mathcal{F}$  contains exactly those sets that are in every  $\sigma$ -algebra that contains  $\mathcal{G}$ . Given its existence, we only need to prove that  $\bigcap_{\mathcal{F} \in \mathcal{K}} \mathcal{F}$  is the smallest  $\sigma$ -algebra that contains  $\mathcal{G}$ .

First we show  $\bigcap_{\mathcal{F} \in \mathcal{K}} \mathcal{F}$  is a  $\sigma$ -algebra. Since  $\mathcal{F}$  is a  $\sigma$ -algebra and therefore  $\Omega \in \mathcal{F}$  for all  $\mathcal{F} \in \mathcal{K}$ , it follows that  $\Omega \in \bigcap_{\mathcal{F} \in \mathcal{K}} \mathcal{F}$ . Next, for any  $A \in \bigcap_{\mathcal{F} \in \mathcal{K}} \mathcal{F}$ ,  $A^c \in \mathcal{F}$  for all  $\mathcal{F} \in \mathcal{K}$ . Since they are all  $\sigma$ -algebras,  $A^c \in \bigcap_{\mathcal{F} \in \mathcal{K}} \mathcal{F}$ . Hence  $A^c \in \bigcap_{\mathcal{F} \in \mathcal{K}} \mathcal{F}$ . Finally, for any  $\{A_i\}_i \subset \bigcap_{\mathcal{F} \in \mathcal{K}} \mathcal{F}$ ,  $\{A_i\}_i \subset \mathcal{F}$  for all  $\mathcal{F} \in \mathcal{K}$ . Since they are all  $\sigma$ -algebras,  $\bigcup_i A_i \in \mathcal{F}$  for all  $\mathcal{F} \in \mathcal{K}$ . Hence  $\bigcup_i A_i \in \bigcap_{\mathcal{F} \in \mathcal{K}} \mathcal{F}$ .

Next we want to prove  $\bigcap_{\mathcal{F} \in \mathcal{K}} \mathcal{F}$  is the smallest  $\sigma$ -algebra that contains  $\mathcal{G}$ . It is quite obvious that  $\bigcap_{\mathcal{F} \in \mathcal{K}} \mathcal{F} \subseteq \mathcal{F}'$  for all  $\mathcal{F}' \in \mathcal{K}$ .

Above all, we have  $\sigma(\mathcal{G}) = \bigcap_{\mathcal{F} \in \mathcal{K}} \mathcal{F}$ .

- (b) Define  $\mathcal{H} = \{A : X^{-1}(A) \in \mathcal{F}\}$ . To show  $X$  is  $\mathcal{F}/\sigma(\mathcal{G})$ -measurable, it is sufficient to prove  $\sigma(\mathcal{G}) \subseteq \mathcal{H}$ .

First we prove that  $\mathcal{H}$  is a  $\sigma$ -algebra. It holds that  $\Omega \in \mathcal{H}$  since  $X^{-1}(\Omega) = \Omega' \in \mathcal{F}$ . For any  $A \in \mathcal{H}$ , we have  $X^{-1}(A) \in \mathcal{F}$ , thus  $X^{-1}(A^c) = X^{-1}(A)^c \in \mathcal{F}$ , which holds since  $\mathcal{F}$  is a  $\sigma$ -algebra. Thus  $A^c \in \mathcal{H}$ . For any  $A_i \in \mathcal{H}$ ,  $i = 1, 2, \dots$ ,  $X^{-1}(A_i) \in \mathcal{F}$ ,  $X^{-1}(\bigcup_i A_i) = \bigcup_i X^{-1}(A_i) \in \mathcal{F}$ . We can then conclude  $\bigcup_i A_i \in \mathcal{H}$  and  $\mathcal{H}$  is a  $\sigma$ -algebra.

Also, since  $X$  is  $\mathcal{F}/\mathcal{G}$ -measurable, we have  $\mathcal{G} \subseteq \mathcal{H}$ . Thus  $\mathcal{H}$  is  $\sigma$ -algebra that contains  $\mathcal{G}$ . By applying the result of (a), we have  $\sigma(\mathcal{G}) \subseteq \mathcal{H}$ , which completes the proof.

- (c) The idea is to show  $\forall B \in \mathfrak{B}(\mathbb{R}), \mathbb{I}\{A\}^{-1}(B) \in \mathcal{F}$ .

If  $\{0, 1\} \in B$ ,  $\mathbb{I}\{A\}^{-1}(B) = \Omega \in \mathcal{F}$ . If  $\{0\} \in B$ ,  $\mathbb{I}\{A\}^{-1}(B) = A^c \in \mathcal{F}$ . If  $\{1\} \in B$ ,  $\mathbb{I}\{A\}^{-1}(B) = A \in \mathcal{F}$ . If  $\{0, 1\} \cap B = \emptyset$ ,  $\mathbb{I}\{A\}^{-1}(B) = \emptyset \in \mathcal{F}$ .

□

**2.6** (KNOWLEDGE AND  $\sigma$ -ALGEBRAS: A PATHOLOGICAL EXAMPLE) In the context of Lemma 2.5, show an example where  $Y = X$  and yet  $Y$  is not  $\sigma(X)$  measurable.

**HINT** As suggested after the lemma, this can be arranged by choosing  $\Omega = \mathcal{Y} = \mathcal{X} = \mathbb{R}, X(\omega) = Y(\omega) = \omega, \mathcal{F} = \mathcal{H} = \mathfrak{B}(\mathbb{R})$  and  $\mathcal{G} = \{\emptyset, \mathbb{R}\}$  to be the trivial  $\sigma$ -algebra.

*Proof.* As the hint suggests, Let  $\Omega = \mathcal{Y} = \mathcal{X} = \mathbb{R}$ ,  $X(\omega) = Y(\omega) = \omega$ ,  $\mathcal{F} = \mathcal{H} = \mathfrak{B}(\mathbb{R})$ . In this case,  $\sigma(X) = \{X^{-1}(A) : A \in \mathcal{G}\} = \{\emptyset, \mathbb{R}\}$ , we can find that  $Y^{-1}((0, 1)) = (0, 1) \notin \sigma(X)$ , thus  $Y$  is not  $\sigma(X)$ -measurable.  $\square$

**2.7** Let  $(\Omega, \mathcal{F}, \mathbb{P})$  be a probability space,  $B \in \mathcal{F}$  be such that  $\mathbb{P}(B) > 0$ . Prove that  $A \mapsto \mathbb{P}(A|B)$  is a probability measure over  $(\Omega, \mathcal{F})$ .

*Proof.* First we have  $\mathbb{P}(\Omega | B) = \frac{\mathbb{P}(\Omega \cap B)}{\mathbb{P}(B)} = \frac{\mathbb{P}(B)}{\mathbb{P}(B)} = 1$ . Then, for any  $A \in \mathcal{F}$ ,  $\mathbb{P}(A | B) = \frac{\mathbb{P}(A \cap B)}{\mathbb{P}(B)} \geq 0$ . Next, for any  $A \in \mathcal{F}$ ,  $\mathbb{P}(A^c | B) = \frac{\mathbb{P}(A^c \cap B)}{\mathbb{P}(B)} = \frac{\mathbb{P}((\Omega - A) \cap B)}{\mathbb{P}(B)} = \frac{\mathbb{P}(B) - \mathbb{P}(A \cap B)}{\mathbb{P}(B)} = 1 - \mathbb{P}(A | B)$ . Finally, for all countable collections of disjoint sets  $\{A_i\}_i$  with  $A_i \in \mathcal{F}$  for all  $i$ , we have  $\mathbb{P}(\bigcup_i A_i | B) = \frac{\mathbb{P}((\bigcup_i A_i) \cap B)}{\mathbb{P}(B)} = \frac{\mathbb{P}(\bigcup_i (A_i \cap B))}{\mathbb{P}(B)} = \sum_i \frac{\mathbb{P}(A_i \cap B)}{\mathbb{P}(B)} = \sum_i \mathbb{P}(A_i | B)$ .  $\square$

**2.8** (BAYES LAW) Verify (2.2).

*Proof.* With the definition of conditional probability, we have  $\mathbb{P}(A | B) = \frac{\mathbb{P}(A \cap B)}{\mathbb{P}(B)} = \frac{\mathbb{P}(B|A)\mathbb{P}(A)}{\mathbb{P}(B)}$ .  $\square$

**2.9** Consider the standard probability space  $(\Omega, \mathcal{F}, \mathbb{P})$  generated by two standard, unbiased, six-sided dice that are thrown independently of each other. Thus,  $\Omega = \{1, \dots, 6\}^2$ ,  $\mathcal{F} = 2^\Omega$  and  $\mathbb{P}(A) = |A|/6^2$  for any  $A \in \mathcal{F}$  so that  $X_i(\omega) = \omega_i$  represents the outcome of throwing dice  $i \in \{1, 2\}$ .

- (a) Show that the events ' $X_1 < 2$ ' and ' $X_2$  is even' are independent of each other.
- (b) More generally, show that for any two events,  $A \in \sigma(X_1)$  and  $B \in \sigma(X_2)$ , are independent of each other.

*Proof.* (a) The event  $\{X_1 < 2\} = \{1\} \times \{1, 2, 3, 4, 5, 6\}$ ,  $\{X_2 \text{ is even}\} = \{1, 2, 3, 4, 5, 6\} \times \{2, 4, 6\}$ ,  $\{X_1 < 2, X_2 \text{ is even}\} = \{(1, 2), (1, 4), (1, 6)\}$ .

Thus  $\mathbb{P}(X_1 < 2) = \frac{6}{36} = \frac{1}{6}$ ,  $\mathbb{P}(X_2 \text{ is even}) = \frac{18}{36} = \frac{1}{2}$ ,  $\mathbb{P}(X_1 < 2, X_2 \text{ is even}) = \frac{3}{36} = \frac{1}{12}$ , which satisfies  $\mathbb{P}(X_1 < 2, X_2 \text{ is even}) = \mathbb{P}(X_1 < 2) \times \mathbb{P}(X_2 \text{ is even})$ . These two events are independent of each other.

- (b)  $\sigma(X_1) = \{X_1^{-1}(A'), A' \subseteq [6]\} = \{A' \times [6] : A' \subseteq [6]\}$ ,  $\sigma(X_2) = \{X_2^{-1}(B'), B' \subseteq [6]\} = \{[6] \times B' : B' \subseteq [6]\}$ . Thus  $\forall A \in \sigma(X_1), B \in \sigma(X_2)$ ,  $\mathbb{P}(A) = \frac{|A'| \times 6}{36} = \frac{|A'|}{6}$ ,  $\mathbb{P}(B) = \frac{6 \times |B'|}{36} = \frac{|B'|}{6}$  and  $\mathbb{P}(A \cap B) = \frac{|A'| \times |B'|}{36} = \mathbb{P}(A) \times \mathbb{P}(B)$ . So  $A$  and  $B$  are independent of each other.  $\square$

**2.10** (SERENDIPITOUS INDEPENDENCE) The point of this exercise is to understand independence more deeply. Solve the following problems:

- (a) Let  $(\Omega, \mathcal{F}, \mathbb{P})$  be a probability space. Show that  $\emptyset$  and  $\Omega$  (which are events) are independent of any other event. What is the intuitive meaning of this?
- (b) Continuing the previous part, show that any event  $A \in \mathcal{F}$  with  $\mathbb{P}(A) \in \{0, 1\}$  is independent of any other event.
- (c) What can we conclude about an event  $A \in \mathcal{F}$  that is independent of its complement,  $A^c = \Omega \setminus A$ ? Does your conclusion make intuitive sense?
- (d) What can we conclude about an event  $A \in \mathcal{F}$  that is independent of itself? Does your conclusion make intuitive sense?
- (e) Consider the probability space generated by two independent flips of unbiased coins with the smallest possible  $\sigma$ -algebra. Enumerate all pairs of events  $A, B$  such that  $A$  and  $B$  are independent of each other.

- (f) Consider the probability space generated by the independent rolls of two unbiased three-sided dice. Call the possible outcomes of the individual dice rolls 1, 2 and 3. Let  $X_i$  be the random variable that corresponds to the outcome of the  $i$ th dice roll ( $i \in \{1, 2\}$ ). Show that the events  $\{X_1 \leq 2\}$  and  $\{X_1 = X_2\}$  are independent of each other.
- (g) The probability space of the previous example is an example when the probability measure is uniform on a finite outcome space (which happens to have a product structure). Now consider any  $n$ -element, finite outcome space with the uniform measure. Show that  $A$  and  $B$  are independent of each other if and only if the cardinalities  $|A|$ ,  $|B|$ ,  $|A \cap B|$  satisfy  $n|A \cap B| = |A| \cdot |B|$ .
- (h) Continuing with the previous problem, show that if  $n$  is prime, then no non-trivial events are independent (an event  $A$  is **trivial** if  $\mathbb{P}(A) \in \{0, 1\}$ ).
- (i) Construct an example showing that pairwise independence does not imply mutual independence.
- (j) Is it true or not that  $A, B, C$  are mutually independent if and only if  $\mathbb{P}(A \cap B \cap C) = \mathbb{P}(A)\mathbb{P}(B)\mathbb{P}(C)$ ? Prove your claim.

*Proof.* (a) Empty sets and complete sets are independent of any event:

$$P(A \cap \Omega) = P(A) = 1 \times P(A) = P(\Omega) \times P(A)$$

$$P(A \cap \emptyset) = P(\emptyset) = 0 = P(\emptyset) \times P(A)$$

- (b) For any  $B \in \Omega$  and  $P(A) \in \{0, 1\}$ :  
 when  $P(A) = 1, P(A^c \cap B) \leq P(A^c) = 1 - P(A) = 0$ , we have  $P(A \cap B) = P(A \cap B) + P(A^c \cap B) = P(B) = P(A)P(B)$ ; when  $P(A) = 0$ , we have  $P(A \cap B) \leq P(A) = 0 = P(A)P(B)$
- (c)  $P(A^c \cap A) = P(A)P(A^c)$ , we have  $0 = P(A)(1 - P(A)) \Rightarrow P(A) \in \{0, 1\}$
- (d)  $P(A \cap A) = P(A)P(A)$ , we have  $P(A) = \{0, 1\}$
- (e)  $\Omega = \{(1, 1), (1, 0), (0, 1), (0, 0)\}$ .  $A, B \subseteq \Omega$  denote the events.

First of all, if either  $A$  or  $B$  is trivial, then  $A$  and  $B$  are independent of each other.

Then, we only need to enumerate  $A, B \notin \Omega, \emptyset$  satisfied that  $P(A \cap B) = P(A)P(B)$ . Since  $P(A \cap B) = \frac{|A \cap B|}{|\Omega|} = \frac{|A \cap B|}{4}$  and  $P(A)P(B) = \frac{|A||B|}{16}$ , we can conclude that  $|A| = 2$ ,  $|B| = 2$  and  $|A \cap B| = 1$  is the only situation satisfying the condition.

Thus, besides trivial  $A$  or  $B$ , all  $A, B$  satisfying  $|A| = 2$ ,  $|B| = 2$  and  $|A \cap B| = 1$  are the solution.

- (f)  $P(X_1 \leq 2) = 2/3$   
 $P(X_1 = X_2) = 3/9 = 1/3$   
 $P(X_1 \leq 2, X_1 = X_2) = P(X_1 = X_2 = 1) + P(X_1 = X_2 = 2) = 1/9 + 1/9 = 2/9$   
 So,  $P(X_1 \leq 2, X_1 = X_2) = P(X_1 = X_2)P(X_1 \leq 2)$
- (g) Necessity :  $\frac{|A \cap B|}{n} = P(A \cap B) = P(A)P(B) = \frac{|A|}{n} \frac{|B|}{n}$   
 $\Rightarrow |A \cap B| \times n = |A||B|$   
 Sufficiency :  $|A \cap B| \times n = |A||B| \Rightarrow \frac{|A|}{n} \frac{|B|}{n} = \frac{|A \cap B|}{n}$   
 $\Rightarrow P(A \cap B) = P(A)P(B)$
- (h) If  $A, B$  are two non-trivial events independent to each other,  $|A \cap B| \times n = |A||B| \Rightarrow n \mid (|A||B|) \Rightarrow n \mid (|A|)$  or  $n \mid (|B|) \Rightarrow |A| = n$  or  $|B| = n$ , contradictory to non-trivial assumption.
- (i) Let  $\Omega = \{1, 2, 3, 4\}$ ,  $A = \{1, 2\}$ ,  $B = \{1, 3\}$ ,  $C = \{1, 4\}$ .  $A, B, C$  are pairwise independent but  $P(A \cap B \cap C) = \frac{1}{4} \neq P(A)P(B)P(C) = \frac{1}{8}$ .

- (j) Consider rolling a dice and set  $A = \{1, 2, 3\}$ ,  $B = \{1, 2, 4\}$ ,  $C = \{1, 4, 5, 6\}$ . Then  $P(A \cap B \cap C) = \frac{1}{6} = (1/2) * (1/2) * (2/3) = P(A)P(B)P(C)$ , however  $P(A \cap B) = 1/3 \neq \frac{1}{2} * \frac{1}{2} = P(A)P(B)$ . Thus  $P(A \cap B \cap C) = P(A)P(B)P(C)$  does not mean mutual independence.  $\square$

**2.11** (INDEPENDENCE AND RANDOM ELEMENTS) Solve the following problems:

- Let  $X$  be a constant random element (that is,  $X(\omega) = x$  for any  $\omega \in \Omega$  over the outcome space over which  $X$  is defined). Show that  $X$  is independent of any other random variable.
- Show that the above continues to hold if  $X$  is almost surely constant (that is,  $\mathbb{P}(X = x) = 1$  for an appropriate value  $x$ ).
- Show that two events are independent if and only if their indicator random variables are independent (that is,  $A, B$  are independent if and only if  $X(\omega) = \mathbb{1}\{\omega \in A\}$  and  $Y(\omega) = \mathbb{1}\{\omega \in B\}$  are independent of each other).
- Generalise the result of the previous item to pairwise and mutual independence for collections of events and their indicator random variables.

*Proof.* (a) To prove  $X$  is independent of another random variable  $Y$ , we can equivalently show that  $\sigma(X)$  and  $\sigma(Y)$  are independent. And notice  $\sigma(X) = \{\emptyset, \Omega\}$  for constant random element  $X$ . Therefore, for all  $A \in \sigma(X)$  and  $B \in \sigma(Y)$  it trivially holds that  $\mathbb{P}(A \cap B) = \mathbb{P}(A)\mathbb{P}(B)$ .

- Given that  $\mathbb{P}(X = x) = 1$ , we can infer the generated sigma-algebra  $\sigma(X) = \{\emptyset, \Omega, G_1, G_2, \dots\}$ , where  $\mathbb{P}(G_1) = \mathbb{P}(G_2) = \dots = 0$ . Therefore, for any  $A \in \sigma(X)$ , we have  $\mathbb{P}(A) = 0$  or  $\mathbb{P}(A) = 1$ . By the result of 2.10(b),  $X$  is independent of any other random variable.

- Notice that  $\sigma(X) = \{\emptyset, \Omega, A, A^c\}$ ,  $\sigma(Y) = \{\emptyset, \Omega, B, B^c\}$ .

- 'only if': Given that  $A, B$  are independent, we have  $\mathbb{P}(A \cap B) = \mathbb{P}(A)\mathbb{P}(B)$ . Consequently  $\mathbb{P}(A \cap B^c) = \mathbb{P}(A) - \mathbb{P}(A \cap B) = \mathbb{P}(A) - \mathbb{P}(A)\mathbb{P}(B) = \mathbb{P}(A)\mathbb{P}(B^c)$ , which implies that  $A$  and  $B^c$  are also independent. Given that  $\emptyset$  and  $\Omega$  are trivially independent of any other event, we have  $A$  and  $B$  are independent for all  $A \in \sigma(X)$  and  $B \in \sigma(Y)$ .

- 'if': If  $X$  and  $Y$  are independent,  $A \in \sigma(X)$  and  $B \in \sigma(Y)$  are trivially independent.

- Notice that  $\sigma(X) = \{\emptyset, \Omega, A, A^c\}$ ,  $\sigma(Y) = \{\emptyset, \Omega, B, B^c\}$ .

- Pairwise independence: The result can be generalized as we go through all pair of events.

- Mutual independence: 'if' case is again trivial. For 'only if' case, suppose that  $(A_i)_i$  are mutually independent. The mutual independence suggests that for any finite subset  $K \subset \mathbb{N}$  we have  $\mathbb{P}(\bigcap_{i \in K} A_i) = \prod_{i \in K} \mathbb{P}(A_i)$ .

Similar to the previous part, for any disjoint finite sets  $J, K$  we have

$$\mathbb{P}\left(\bigcap_{i \in K} A_i \cap \bigcap_{i \in J} A_i^c\right) = \prod_{i \in K} \mathbb{P}(A_i) \prod_{i \in J} \mathbb{P}(A_i^c).$$

This leads to the conclusion that for any finite set  $K \subset \mathbb{N}$  and  $(V_i)_{i \in K}$  with  $V_i \in \sigma(X_i) = \{\Omega, \emptyset, A_i, A_i^c\}$ , we have

$$\mathbb{P}\left(\bigcap_{i \in K} V_i\right) = \prod_{i \in K} \mathbb{P}(V_i),$$

which implies that  $(X_i)_i$  are mutually independent.  $\square$

**2.12** Our goal in this exercise is to show that  $X$  is integrable if and only if  $|X|$  is integrable. This is broken down into multiple steps. The first issue is to deal with the measurability of  $|X|$ . While a direct calculation can also show this, it may be worthwhile to follow a more general path:

- (a) Any  $f : \mathbb{R} \rightarrow \mathbb{R}$  continuous function is Borel measurable.
- (b) Conclude that for any random variable  $X$ ,  $|X|$  is also a random variable.
- (c) Prove that for any random variable  $X$ ,  $X$  is integrable if and only if  $|X|$  is integrable. (The statement makes sense since  $|X|$  is a random variable whenever  $X$  is).

*Proof.* (a) Let  $\mathcal{G} = \{(a, b) : a < b \text{ with } a, b \in \mathbb{R}\}$ , then  $\mathcal{B}(\mathbb{R}) = \sigma(\mathcal{G})$ . According to Exercise 2.5(b), to show that  $f$  is  $\mathcal{B}(\mathbb{R})/\mathcal{B}(\mathbb{R})$ -measurable, we just need to show  $f$  is  $\mathcal{B}(\mathbb{R})/\mathcal{G}$ -measurable. Recall the definition of continuous function,  $\forall x_0 \in \mathbb{R}, \varepsilon > 0, \exists \delta > 0$  such that when  $x \in (x_0 - \delta, x_0 + \delta)$ , there is  $f(x) \in (f(x_0) - \varepsilon, f(x_0) + \varepsilon)$ . Thus  $\forall (a, b) \in \mathcal{G}, y_0 \in (a, b), y \in (y_0 - \varepsilon, y_0 + \varepsilon) : f^{-1}(y) \in (f^{-1}(y_0) - \delta, f^{-1}(y_0) + \delta)$ , which means  $f^{-1}(a, b) = \cup(a', b') \in \mathcal{B}(\mathbb{R})$ . We have then shown that  $f$  is  $\mathcal{B}(\mathbb{R})/\mathcal{B}(\mathbb{R})$ -measurable.

- (b) By definition,  $X$  is a random variable means that  $X$  is  $\mathcal{F}/\mathcal{B}(\mathbb{R})$ -measurable. According to Exercise 2.12 (a),  $|X|$  is continuous, thus it is  $\mathcal{B}(\mathbb{R})/\mathcal{B}(\mathbb{R})$ -measurable. Further apply the result of Exercise 2.1, let  $f(X) = |X|$ , then  $f$  is  $\mathcal{F}/\mathcal{B}(\mathbb{R})$ -measurable, thus  $|X|$  is also a random variable.

- (c) Define  $X^+(\omega) = X(\omega)\mathbf{1}\{X(\omega) > 0\}$ ,  $X^-(\omega) = -X(\omega)\mathbf{1}\{X(\omega) < 0\}$ . If  $X$  is integrable,  $\int_{\Omega} X d\mathbb{P} = \int_{\Omega} X^+ d\mathbb{P} - \int_{\Omega} X^- d\mathbb{P}$ , which means  $X^+$  and  $X^-$  are integrable, and by definition  $\int_{\Omega} |X| d\mathbb{P} = \int_{\Omega} X^+ d\mathbb{P} + \int_{\Omega} X^- d\mathbb{P}$  is also integrable, vice versa.

□

**2.13** (Infinite-valued integrals) Can we consistently extend the definition of integrals so that for non-negative random variables, the integral is always defined (it may be infinite)? Defend your view by either constructing an example (if you are arguing against) or by proving that your definition is consistent with the requirements we have for integrals.

*Proof.* We can extend the definition by letting at least one of  $\int_{\Omega} X^+ d\mathbb{P}$  and  $\int_{\Omega} X^- d\mathbb{P}$  be finite. □

**2.14** Prove Proposition 2.6 (Let  $(X_i)_i$  be a (possibly infinite) sequence of random variables on the same probability space and assume that  $\mathbb{E}[X_i]$  exists for all  $i$  and furthermore that  $X = \sum_i X_i$  and  $\mathbb{E}[X]$  also exists. Then  $\mathbb{E}[X] = \sum_i \mathbb{E}[X_i]$ )

*Proof.* We only consider the infinite condition, as when the sum is finite, we can use the property of integration to draw the conclusion. We should add a condition first, which is

$$\sum_i \mathbb{E}|X_i| < \infty \tag{1}$$

First, we need to prove

$$\mathbb{E}[\sum_i |X_i|] = \sum_i \mathbb{E}[|X_i|] \tag{2}$$

Consider  $Y_n = \sum_{i=1}^n |X_i|$ . As  $Y_{n=1}^{\infty}$  is an ascent sequence and  $Y_n \forall n$  is integrable. According to the monotone convergence theorem, we have

$$\mathbb{E}[\lim_{n \rightarrow \infty} Y_n] = \lim_{n \rightarrow \infty} \mathbb{E}[Y_n] \tag{3}$$

which is equivalent to (2).

Then we consider  $Z_n = \sum_{i=1}^n X_i$ , as  $|Z_n| \leq \sum_{i=1}^n |X_i| \leq \sum_{i=1}^{\infty} |X_i|$ . According to (1),  $\sum_{i=1}^{\infty} |X_i|$  is integrable. Then, using dominated convergence theorem, we have

$$\mathbb{E}[\lim_{n \rightarrow \infty} Z_n] = \lim_{n \rightarrow \infty} \mathbb{E}[Z_n] \iff \mathbb{E}[X] = \sum_i \mathbb{E}[X_i] \tag{4}$$

□

## 2.15



(a) Assume  $X$  is simple function.

$$\begin{aligned}
 \mathbb{E}[cX] &= \mathbb{E}\left[c \sum_{i=1}^n \alpha_i \mathbb{I}_{A_i}\{\omega\}\right] \\
 &= \int_{\Omega} c \sum_{i=1}^n \alpha_i \mathbb{I}_{A_i}\{\omega\} d\mathbb{P}(\omega) \\
 &= c \int_{\Omega} \sum_{i=1}^n \alpha_i \mathbb{I}_{A_i}\{\omega\} d\mathbb{P}(\omega) \\
 &= c\mathbb{E}[X]
 \end{aligned}$$

(b) Assume  $X$  is non-negative random variable.

$$\begin{aligned}
 \mathbb{E}[cX] &= \sup \left\{ \int_{\Omega} h d\mathbb{P} : h \text{ is simple and } 0 \leq h \leq cX \right\} \\
 &= c \sup \left\{ \int_{\Omega} h' d\mathbb{P} : h' \text{ is simple and } 0 \leq h' \leq X \right\} \\
 &= c\mathbb{E}[X]
 \end{aligned}$$

(c) Assume  $X$  is arbitrary random variable.

(i)  $c \geq 0$

$$\begin{aligned}
 \mathbb{E}[cX] &= \mathbb{E}[(cX)^+] - \mathbb{E}[(cX)^-] \\
 &= \mathbb{E}[c(X)^+] - \mathbb{E}[c(X)^-] \\
 &= c\mathbb{E}[(X)^+] - c\mathbb{E}[(X)^-] \\
 &= c\mathbb{E}[X]
 \end{aligned}$$

(ii)  $c < 0$

By definition, we have

$$\begin{aligned}
 (cX)^+ &= cX \mathbb{I}\{cX > 0\} \\
 &= cX \mathbb{I}\{X < 0\} \text{ (since } c < 0\text{)} \\
 &= (-c)(-X) \mathbb{I}\{X < 0\} \\
 &= (-c)(X)^-
 \end{aligned}$$

Along the similar line, we have

$$\begin{aligned}
 (cX)^- &= -cX \mathbb{I}\{cX < 0\} \\
 &= -cX \mathbb{I}\{X > 0\} \\
 &= -c(X)^+
 \end{aligned}$$

Now we can see that

$$\begin{aligned}
 \mathbb{E}[cX] &= \mathbb{E}[(cX)^+] - \mathbb{E}[(cX)^-] \\
 &= \mathbb{E}[(-c)(X)^-] - \mathbb{E}[-c(X)^+] \\
 &= -c\mathbb{E}[(X)^-] + c\mathbb{E}[(X)^+] \\
 &= c\mathbb{E}[X]
 \end{aligned}$$

(a) Assume  $X = \sum_{i=1}^n \alpha_i \mathbb{I}_{A_i}\{\omega\}$ ,  $Y = \sum_{j=1}^m \beta_j \mathbb{I}_{B_j}\{\omega\}$  are simple functions.

$$\begin{aligned}
\mathbb{E}[XY] &= \mathbb{E}\left[\sum_{i=1}^n \sum_{j=1}^m \alpha_i \beta_j \mathbb{I}_{A_i}\{\omega\} \mathbb{I}_{B_j}\{\omega\}\right] \\
&= \int_{\Omega} \sum_{i=1}^n \sum_{j=1}^m \alpha_i \beta_j \mathbb{I}_{A_i}\{\omega\} \mathbb{I}_{B_j}\{\omega\} d\mathbb{P}(\omega) \\
&= \sum_{i=1}^n \sum_{j=1}^m \alpha_i \beta_j \mathbb{P}(A_i \cap B_j) \\
&= \sum_{i=1}^n \sum_{j=1}^m \alpha_i \beta_j \mathbb{P}(A_i) \mathbb{P}(B_j) \text{ (by the definition of independence)} \\
&= \left(\sum_{i=1}^n \alpha_i \mathbb{P}(A_i)\right) \left(\sum_{j=1}^m \beta_j \mathbb{P}(B_j)\right) \\
&= \mathbb{E}[X] \mathbb{E}[Y]
\end{aligned}$$

(b) Assume  $X, Y$  are non-negative random variables.

$$\begin{aligned}
\mathbb{E}[XY] &= \sup \{ \mathbb{E}[h] : h \text{ is simple and } 0 \leq h \leq XY \} \\
&= \sup \{ \mathbb{E}[h_1 h_2] : h_1, h_2 \text{ are simple and } 0 \leq h_1 \leq X, 0 \leq h_2 \leq Y \} \\
&= \sup \{ \mathbb{E}[h_1] \mathbb{E}[h_2] : h_1, h_2 \text{ are simple and } 0 \leq h_1 \leq X, 0 \leq h_2 \leq Y \} \\
&= \sup \{ \mathbb{E}[h_1] : h_1 \text{ is simple and } 0 \leq h_1 \leq X \} \cdot \sup \{ \mathbb{E}[h_2] : h_2 \text{ is simple and } 0 \leq h_2 \leq Y \} \\
&= \mathbb{E}[X] \mathbb{E}[Y]
\end{aligned}$$

(c) Assume  $X, Y$  are arbitrary random variables.

$$\begin{aligned}
\mathbb{E}[XY] &= \mathbb{E}[(X^+ - X^-)(Y^+ - Y^-)] \\
&= \mathbb{E}[X^+ Y^+ - X^+ Y^- - X^- Y^+ + X^- Y^-] \\
&= \mathbb{E}[X^+] \mathbb{E}[Y^+] - \mathbb{E}[X^+] \mathbb{E}[Y^-] - \mathbb{E}[X^-] \mathbb{E}[Y^+] + \mathbb{E}[X^-] \mathbb{E}[Y^-] \\
&= (\mathbb{E}[X^+] - \mathbb{E}[X^-])(\mathbb{E}[Y^+] - \mathbb{E}[Y^-]) \\
&= \mathbb{E}[X] \mathbb{E}[Y]
\end{aligned}$$

**2.17** Before proving Ex.2.17, we need to make minor changes to the definition of conditional expectation and give a small lemma.

**Definition 1.** Assume  $(\Omega, \mathcal{F}, \mathbb{P})$  is a probability space.  $\mathcal{G} \subset \mathcal{F}$  is a sub- $\sigma$ -algebra of  $\mathcal{F}$ .  $X : \Omega \rightarrow \mathbb{R}$  is a random variable. The conditional expectation of  $X$  given  $\mathcal{G}$  is denoted by any random variable  $Y$  which satisfies the following 2 properties:

- $Y$  is  $\mathcal{G}$ -measurable
- $\forall A \in \mathcal{G}$ ,

$$\int_A Y d\mathbb{P} = \int_A X d\mathbb{P}$$

Formally, we denote  $Y$  by notation  $\mathbb{E}[X|\mathcal{G}]$ .

**Lemma 1.** If  $X$  is  $\mathcal{G}$ -measurable, then  $\mathbb{E}[X|\mathcal{G}] = X$  holds a.s.

*Proof.* Since  $X$  is  $\mathcal{G}$ -measurable, property1 holds. And property2 holds trivially.  $\square$

We can now handily prove Ex.2.17. Since  $\mathbb{E}[X|\mathcal{G}_1]$  is  $\mathcal{G}_1$ -measurable and  $\mathcal{G}_1 \subset \mathcal{G}_2$ , we can see that  $\mathbb{E}[X|\mathcal{G}_1]$  is  $\mathcal{G}_2$ -measurable. By Lemma 1,  $\mathbb{E}[\mathbb{E}[X|\mathcal{G}_1]|\mathcal{G}_2] = \mathbb{E}[X|\mathcal{G}_1]$  holds almost surely.

**2.18** Suppose  $X = Y$  with  $\mathbb{V}[X] \neq 0$ . Then, we have  $\mathbb{E}[XY] = \mathbb{E}[X^2] = \mathbb{V}[X] + \mathbb{E}[X]^2 \neq \mathbb{E}[X]^2 = \mathbb{E}[X]\mathbb{E}[Y]$ .

**2.19** As the hint suggests,  $X(\omega) = \int_{[0,\infty)} \mathbb{I}\{[0, X(\omega)]\}(x)dx$ . Hence, we have

$$\begin{aligned} \mathbb{E}[X(\omega)] &= \mathbb{E}\left[\int_{[0,\infty)} \mathbb{I}\{[0, X(\omega)]\}(x)dx\right] \\ &= \int_{[0,\infty)} \mathbb{E}[\mathbb{I}\{[0, X(\omega)]\}(x)]dx \\ &= \int_{[0,\infty)} P(X(\omega) > x)dx \end{aligned} \tag{5}$$

where the second equality is given by Fubini–Tonell theorem.

**2.20** We prove the following properties all by contradiction (for the sake of rigor).

- (1) Let  $G = \{\omega : \mathbb{E}[X | \mathcal{G}](\omega) < 0\}$ . Then  $G \in \mathcal{G}$  since  $\mathbb{E}[X | \mathcal{G}]$  is  $\mathcal{G}$ -measurable by definition. Now suppose  $\mathbb{P}(G) > 0$ , then

$$\begin{aligned} \int_G X d\mathbb{P} &= \int_G \mathbb{E}(X | \mathcal{G}) d\mathbb{P} \\ &< 0 \end{aligned} \tag{6}$$

where the equality holds by the definition of conditional expectation. Now we can find it contradictory as  $X \geq 0$ . Therefore  $\mathbb{P}(G) = 0$ , and  $\mathbb{E}[X | \mathcal{G}] \geq 0$  a.s.

- (2) Let  $G = \{\omega : \mathbb{E}[1 | \mathcal{G}](\omega) \neq 1\}$ . Then  $G \in \mathcal{G}$  since  $\mathbb{E}[1 | \mathcal{G}]$  is  $\mathcal{G}$ -measurable by definition. Now suppose  $\mathbb{P}(G) > 0$ , then

$$\begin{aligned} \int_G 1 d\mathbb{P} &= \int_G \mathbb{E}(1 | \mathcal{G}) d\mathbb{P} \\ &\neq 1 \end{aligned} \tag{7}$$

where the equality holds by the definition of conditional expectation. Now we can find it contradictory as  $\int_G 1 d\mathbb{P} = 1$ . Therefore  $\mathbb{P}(G) = 0$ , and  $\mathbb{E}[1 | \mathcal{G}] = 1$  a.s.

- (3) Let  $G = \{\omega : \mathbb{E}[X + Y | \mathcal{G}](\omega) \neq \mathbb{E}[X | \mathcal{G}](\omega) + \mathbb{E}[Y | \mathcal{G}](\omega)\}$ . Then  $G \in \mathcal{G}$  since  $\mathbb{E}[X + Y | \mathcal{G}]$ ,  $\mathbb{E}[X | \mathcal{G}]$ , and  $\mathbb{E}[Y | \mathcal{G}]$  are all  $\mathcal{G}$ -measurable by definition. Now suppose  $\mathbb{P}(G) > 0$ , then

$$\begin{aligned} \int_G (X + Y) d\mathbb{P} &= \int_G \mathbb{E}(X + Y | \mathcal{G}) d\mathbb{P} \\ &\neq \int_G [\mathbb{E}(X | \mathcal{G}) + \mathbb{E}(Y | \mathcal{G})] d\mathbb{P} \\ &= \int_G \mathbb{E}(X | \mathcal{G}) d\mathbb{P} + \int_G \mathbb{E}(Y | \mathcal{G}) d\mathbb{P} \\ &= \int_G X d\mathbb{P} + \int_G Y d\mathbb{P} \end{aligned} \tag{8}$$

where the first equality and the last one hold by the definition of conditional expectation. It contradicts the linearity of expectation in that  $\int_G (X + Y) d\mathbb{P} \neq \int_G X d\mathbb{P} + \int_G Y d\mathbb{P}$ . Therefore  $\mathbb{P}(G) = 0$ , and  $\mathbb{E}(X + Y | \mathcal{G}) = \mathbb{E}(X | \mathcal{G}) + \mathbb{E}(Y | \mathcal{G})$  a.s.

- (4) Let  $G = \{\omega : \mathbb{E}[XY \mid \mathcal{G}](\omega) \neq Y(\omega)\mathbb{E}[X \mid \mathcal{G}](\omega)\}$ . Then  $G \in \mathcal{G}$  since  $\mathbb{E}[XY \mid \mathcal{G}]$ ,  $Y$ , and  $\mathbb{E}[X \mid \mathcal{G}]$  are all  $\mathcal{G}$ -measurable by definition. Now suppose  $\mathbb{P}(G) > 0$ , then

$$\begin{aligned} \int_G XY d\mathbb{P} &= \int_G \mathbb{E}(XY \mid \mathcal{G}) d\mathbb{P} \\ &\neq \int_G Y \mathbb{E}[X \mid \mathcal{G}] d\mathbb{P} \end{aligned} \tag{9}$$

Now our target is to show it is contradictory. This is a bit tricky, so we start from the simplest case and then generalize it step by step.

- a. Suppose  $Y = \mathbb{I}_A$  for some  $A \in \mathcal{G}$ . Then

$$\int_G XY d\mathbb{P} = \int_{G \cap A} X d\mathbb{P} \tag{10}$$

and

$$\begin{aligned} \int_G Y \mathbb{E}[X \mid \mathcal{G}] d\mathbb{P} &= \int_{G \cap A} \mathbb{E}[X \mid \mathcal{G}] d\mathbb{P} \\ &= \int_{G \cap A} X d\mathbb{P} \end{aligned} \tag{11}$$

Hence it holds that  $\int_G XY d\mathbb{P} = \int_G Y \mathbb{E}[X \mid \mathcal{G}] d\mathbb{P}$ .

- b. Suppose  $Y$  is non-negative and let  $\{Y_n\}$  be sequence of non-negative simple functions converging to  $Y$  from below. Then by linearity, it holds that

$$\int_G X^+ Y_n d\mathbb{P} = \int_G Y_n \mathbb{E}[X^+ \mid \mathcal{G}] d\mathbb{P} \tag{12}$$

and

$$\int_G X^- Y_n d\mathbb{P} = \int_G Y_n \mathbb{E}[X^- \mid \mathcal{G}] d\mathbb{P} \tag{13}$$

Applying the monotone convergence we end up with

$$\int_G X^+ Y d\mathbb{P} = \int_G Y \mathbb{E}[X^+ \mid \mathcal{G}] d\mathbb{P} \tag{14}$$

and

$$\int_G X^- Y d\mathbb{P} = \int_G Y \mathbb{E}[X^- \mid \mathcal{G}] d\mathbb{P} \tag{15}$$

Hence,

$$\begin{aligned} \int_G XY d\mathbb{P} &= \int_G X^+ Y d\mathbb{P} - \int_G X^- Y d\mathbb{P} \\ &= \int_G Y (\mathbb{E}[X^+ \mid \mathcal{G}] - \mathbb{E}[X^- \mid \mathcal{G}]) d\mathbb{P} \\ &= \int_G Y \mathbb{E}[X^+ - X^- \mid \mathcal{G}] d\mathbb{P} \\ &= \int_G Y \mathbb{E}[X \mid \mathcal{G}] d\mathbb{P} \end{aligned} \tag{16}$$

- c. Finally, for arbitrary  $Y$ , we can separate  $Y = Y^+ - Y^-$  and the contradiction still holds by linearity of expectation.

Therefore, in any case Eq.9 is contradictory. So  $\mathbb{P}(G) = 0$ , and  $\mathbb{E}[XY | \mathcal{G}] = Y\mathbb{E}[X | \mathcal{G}]$  a.s.

- (5) Let  $G = \{\omega : \mathbb{E}[X | \mathcal{G}_1](\omega) \neq \mathbb{E}[\mathbb{E}[X | \mathcal{G}_2] | \mathcal{G}_1](\omega)\}$ . Then  $G \in \mathcal{G}_1$  since both  $\mathbb{E}[X | \mathcal{G}_1]$  and  $\mathbb{E}[\mathbb{E}[X | \mathcal{G}_2] | \mathcal{G}_1]$  are  $\mathcal{G}_1$ -measurable by definition. Now suppose  $\mathbb{P}(G) > 0$ , then

$$\begin{aligned} \int_G X d\mathbb{P} &= \int_G \mathbb{E}(X | \mathcal{G}_1) d\mathbb{P} \\ &\neq \int_G \mathbb{E}[\mathbb{E}[X | \mathcal{G}_2] | \mathcal{G}_1] d\mathbb{P} \\ &= \int_G \mathbb{E}(X | \mathcal{G}_2) d\mathbb{P} \\ &= \int_G X d\mathbb{P} \end{aligned} \tag{17}$$

The last equality stands since  $G \in \mathcal{G}_1$  and  $\mathcal{G}_1 \subset \mathcal{G}_2$ , which suggests  $G \in \mathcal{G}_2$ . Now we can find it contradictory. Therefore  $\mathbb{P}(G) = 0$ , and  $\mathbb{E}[X | \mathcal{G}_1] = \mathbb{E}[\mathbb{E}[X | \mathcal{G}_2] | \mathcal{G}_1]$  a.s.

$$\begin{aligned} \int_G X d\mathbb{P} &= \int_G \mathbb{E}(X | \mathcal{G}_1) d\mathbb{P} \\ &\neq \int_G \mathbb{E}[\mathbb{E}[X | \mathcal{G}_2] | \mathcal{G}_1] d\mathbb{P} \\ &= \int_G \mathbb{E}(X | \mathcal{G}_2) d\mathbb{P} \\ &= \int_G X d\mathbb{P} \end{aligned} \tag{18}$$

- (6) Let  $G = \{\omega : \mathbb{E}[X | \sigma(\mathcal{G}_1 \cup \mathcal{G}_2)](\omega) \neq \mathbb{E}[X | \mathcal{G}_1](\omega)\}$ . Notice that  $\mathbb{E}[X | \mathcal{G}_1]$  is not only  $\mathcal{G}_1$ -measurable but also  $\sigma(\mathcal{G}_1 \cup \mathcal{G}_2)$ -measurable. Thus we have  $G \in \sigma(\mathcal{G}_1 \cup \mathcal{G}_2)$ . Now suppose  $\mathbb{P}(G) > 0$ , then

$$\begin{aligned} \int_G X d\mathbb{P} &= \int_G \mathbb{E}[X | \sigma(\mathcal{G}_1 \cup \mathcal{G}_2)] d\mathbb{P} \\ &\neq \int_G \mathbb{E}[X | \mathcal{G}_1] d\mathbb{P} \end{aligned} \tag{19}$$

To show it is contradictory, we want to prove that  $\forall G \in \sigma(\mathcal{G}_1 \cup \mathcal{G}_2)$ ,

$$\int_G X d\mathbb{P} = \int_G \mathbb{E}[X | \mathcal{G}_1] d\mathbb{P} \tag{20}$$

The following techniques are closely related to ‘Dynkin system’, which is beyond my knowledge. The main idea is that if we assume  $X$  is non-negative, which can be generalized by linearity, it is enough to establish Eq.20 for some  $\pi$ -system that generates  $\sigma(\mathcal{G}_1 \cup \mathcal{G}_2)$ .

One possibility is  $\mathcal{H} = \{G_1 \cap G_2 : G_1 \in \mathcal{G}_1, G_2 \in \mathcal{G}_2\}$ . Then,  $\forall G_1 \cap G_2 \in \mathcal{H}$ ,

$$\begin{aligned} \int_{G_1 \cap G_2} \mathbb{E}[X | \mathcal{G}_1] d\mathbb{P} &= \int_{\Omega} \mathbb{E}[X | \mathcal{G}_1] \mathbb{I}_{G_1} \mathbb{I}_{G_2} d\mathbb{P} \\ &= \int_{\Omega} \mathbb{E}[X | \mathcal{G}_1] \mathbb{I}_{G_1} d\mathbb{P} \int_{\Omega} \mathbb{I}_{G_2} d\mathbb{P} \\ &= \int_{\Omega} X \mathbb{I}_{G_1} d\mathbb{P} \int_{\Omega} \mathbb{I}_{G_2} d\mathbb{P} \\ &= \int_{\Omega} X \mathbb{I}_{G_1} \mathbb{I}_{G_2} d\mathbb{P} \\ &= \int_{G_1 \cap G_2} X d\mathbb{P} \end{aligned} \tag{21}$$

where the second and fourth equality holds due to independence between  $\sigma(X)$  and  $\mathcal{G}_2$  given  $\mathcal{G}_1$ .

Hence, we find it contradictory. So  $\mathbb{P}(G) = 0$  and  $\mathbb{E}[X | \sigma(\mathcal{G}_1 \cup \mathcal{G}_2)] = \mathbb{E}[X | \mathcal{G}_1]$  a.s.

(7) Let  $G = \{\omega : \mathbb{E}[X \mid \mathcal{G}](\omega) \neq \mathbb{E}[X]\}$ . Then  $G \in \mathcal{G}$  since  $\mathbb{E}[X \mid \mathcal{G}]$  is  $\mathcal{G}$ -measurable by definition. And because  $\mathcal{G}$  is trivial,  $G = \emptyset$  or  $G = \Omega$ .

- a. If  $G = \emptyset$ ,  $P(G) = 0$  for sure.
- b. If  $G = \Omega$ , which suggests  $\mathbb{E}[X \mid \mathcal{G}] \neq \mathbb{E}[X]$  always holds, we have

$$\begin{aligned}
 \int_G X d\mathbb{P} &= \int_G \mathbb{E}[X \mid \mathcal{G}] d\mathbb{P} \\
 &\neq \int_G \mathbb{E}[X] d\mathbb{P} \\
 &= \int_\Omega \mathbb{E}[X] d\mathbb{P} \\
 &= \mathbb{E}[X]
 \end{aligned} \tag{22}$$

which is obviously contradictory since  $\int_G X d\mathbb{P} = \int_\Omega X d\mathbb{P} = \mathbb{E}[X]$ .

Therefore,  $P(G) = 0$  and hence  $\mathbb{E}[X \mid \mathcal{G}] = \mathbb{E}[X]$  a.s.

# Chapter 3 Stochastic Processes and Markov Chains

## 3.1

- (a) On  $([0, 1], \mathcal{B}, \lambda)$ , for any  $x \in [0, 1]$

Let  $F_1(x), F_2(x), F_3(x), \dots$  be the binary expansion of  $x$ .

$$F_t(x) = \begin{cases} 1, & A \\ 0, & \bar{A} \end{cases} \quad (\bar{A} \text{ is the opposite case of } A)$$

$F_t(x)$  is Bernoulli random variable.

$$(b) \begin{cases} F_1 = 0 : 0 \leq x < 0.5 \\ F_1 = 1 : 0.5 \leq x < 1 \\ \dots \\ \begin{cases} F_2 = 0 : 0 \leq x' < 0.5 \\ F_2 = 1 : 0.5 \leq x' < 1 \end{cases} \quad x' = 2x - 1 \\ \dots \\ \begin{cases} F_t = 0 : 0 \leq x^t < 0.5 \Rightarrow \mathbb{P}(F_t = 0) = \frac{1}{2} \\ F_t = 1 : 0.5 \leq x^t < 1 \Rightarrow \mathbb{P}(F_t = 1) = \frac{1}{2} \end{cases} \end{cases}$$

- (c) It is obviously that  $(F_t)_{t=1}^\infty$  are independent. It satisfies independent equation:  $\mathbb{P}(A \cap B) = \mathbb{P}(A)\mathbb{P}(B)$ .

- (d)  $(X_{m,t})_{t=1}^\infty$  is a subsequence of  $(F_t)_{t=1}^\infty$  and  $(X_{m,t})_{t=1}^\infty$  are mutually exclusive.

- (e) Such as (d).

- (f) Such as (d).

## 3.2

- (a)  $S_t = \sum_{s=1}^t X_s 2^{s-1}$

$X_t$  is a  $\mathcal{F}$ -adapted martingale.

$$(1) \mathbb{E}[X_t | \mathcal{F}_{t-1}] = X_{t-1}.$$

$$(2) X_t \text{ is integrable} \Rightarrow S_t \text{ is integrable.}$$

$$\begin{aligned} \mathbb{E}[S_t | \mathcal{F}_{t-1}] &= \mathbb{E}[S_{t-1} + X_t 2^{t-1} | \mathcal{F}_{t-1}] \\ &= S_{t-1} + \mathbb{E}[X_t 2^{t-1} | \mathcal{F}_{t-1}] \\ &= S_{t-1} + 2^t \times (1) \times \frac{1}{2} + 2^t \times (-1) \times \frac{1}{2} \\ &= S_{t-1} \end{aligned}$$

$$\Rightarrow (S_t)_{t=1}^\infty$$

- (b)  $t=1$  , if  $S_t \neq 1 \Rightarrow X_1 = -1, S_t = -1$   
 $t=2$  , if  $S_t \neq 1 \Rightarrow X_1 = -1, S_t = -3$   
 $t=3$  , if  $S_t \neq 1 \Rightarrow X_1 = -1, S_t = -7$

...

If avoid  $S_t = 1$  , the  $X_s$  sequence must be  $-1$ .

$$\tau = \min\{t : S_t = 1\} = \min\{t : X_T = 1\}$$

$$\Rightarrow \mathbb{P}(\tau < n) = 1 - \mathbb{P}(\tau \geq n) = 1 - \frac{1}{2^n}$$

$$\Rightarrow \mathbb{P}(\tau < \infty) = 1 - \lim_{n \rightarrow \infty} \mathbb{P}(\tau \geq n) = 1 - \frac{1}{2^n} = 1 - \lim_{n \rightarrow \infty} \frac{1}{2^n}$$

- (c) If  $t = \tau$  , then  $S_t = 1$  , so  $S_\tau \equiv 1$

$$\Rightarrow \mathbb{E}[S_\tau] = 1$$

- (d) Doob's(a) can be proved by 3.2(b)

$$\tau = 1 \Rightarrow X_1 = 1 \Rightarrow \mathbb{P}(\tau = 1) = \frac{1}{2}$$

$$\tau = 2 \Rightarrow X_1 = -1, X_2 = 1 \Rightarrow \mathbb{P}(\tau = 1) = \frac{1}{4}$$

$$\tau = 3 \Rightarrow X_1 = -1, X_2 = -1, X_3 = 1 \Rightarrow \mathbb{P}(\tau = 1) = \frac{1}{8}$$

...

$$\mathbb{P}(\tau < \infty) = \mathbb{P}(\tau = 1) + \mathbb{P}(\tau = 2) + \mathbb{P}(\tau = 3) + \dots = \frac{1}{2} + \frac{1}{4} + \frac{1}{8} + \dots = 1$$

because of  $n \neq \infty$ ,  $\mathbb{P}(\tau = n) = \frac{1}{n^2} \neq 0$ .

Doob's(b)(c) can also be proved by 3.2(b)

$$t=1 \text{ , if } S_t \neq 1 \Rightarrow X_1 = -1, S_t = -1$$

$$t=2 \text{ , if } S_t \neq 1 \Rightarrow X_1 = -1, S_t = -3$$

$$t=3 \text{ , if } S_t \neq 1 \Rightarrow X_1 = -1, S_t = -7$$

...

It can be concluded that  $-S_t-$  and  $-S_{t-1}-$  can not be bounded, so  $\mathbb{E}[|X_{t+1}| \mathcal{F}]$  and  $|4X_{t \wedge \tau}|$  can not be bounded neither.

**3.4** If  $X_t \geq 0$  is dropped,  $\mathbb{E}[X_\tau | \{\tau \leq n\}] \geq \mathbb{E}[\varepsilon | \{\tau \leq n\}]$  not always true.



# Chapter 4 Stochastic Bandits

4.1 By definition

$$\begin{aligned}
 R_n(\pi, v) &= n\mu^*(v) - \mathbb{E}\left[\sum_{t=1}^n X_t\right] \\
 &= \sum_{t=1}^n \mu^*(v) - \sum_{t=1}^n \mathbb{E}[X_t] \\
 &= \sum_{t=1}^n [\mu^* - \mu_{A_t}]
 \end{aligned}$$

(a)  $\mu^* = \max_a \mu_a \geq \mu_{A_t} \Rightarrow R_n(\pi, v) = \sum_{t=1}^n [\mu^* - \mu_{A_t}] \geq 0.$

(b) If  $\pi$  choose  $A_t \in \arg \max_a \mu_a$  for all  $t \in [n] \Rightarrow \sum_{t=1}^n [\mu^* - \mu_{A_t}] = 0.$

(c) If  $R_n(\pi, v) = 0$  for some policy  $\pi$ , then  $A_t \in \arg \max_a \mu_a \Rightarrow \mathbb{P}(\mu_{A_t} = \mu^*) = 1.$

4.3 Denote  $h_t = a_1, x_1, \dots, a_t, x_t.$

(a) According to the definition of conditional probability and marginal distribution, we have

$$\begin{aligned}
 p_{v\pi}(a_n \mid h_{n-1}) &= \frac{p_{v\pi}(h_{n-1}, a_n)}{p_{v\pi}(h_{n-1})} \\
 &= \frac{\int_{\mathbb{R}} p_{v\pi}(h_n) dx_n}{p_{v\pi}(h_{n-1})} \\
 &= \frac{\int_{\mathbb{R}} \prod_{t=1}^n \pi(a_t \mid h_{t-1}) p_{a_t}(x_t) dx_n}{p_{v\pi}(h_{n-1})} \\
 &= \frac{\prod_{t=1}^{n-1} \pi(a_t \mid h_{t-1}) p_{a_t}(x_t)}{p_{v\pi}(h_{n-1})} \int_{\mathbb{R}} \pi(a_n \mid h_{n-1}) p_{a_n}(x_n) dx_n \\
 &= \pi(a_n \mid h_{n-1}) \int_{\mathbb{R}} p_{a_n}(x_n) dx_n \\
 &= \pi(a_n \mid h_{n-1})
 \end{aligned}$$

(b) According to the definition of conditional probability and marginal distribution, we have

$$\begin{aligned}
p_{v\pi}(x_n \mid h_{n-1}, a_n) &= \frac{p_{v\pi}(h_n)}{p_{v\pi}(h_{n-1}, a_n)} \\
&= \frac{p_{v\pi}(h_n)}{\int_{\mathbb{R}} p_{v\pi}(h_n) dx_n} \\
&= \frac{p_{v\pi}(h_n)}{\int_{\mathbb{R}} [\prod_{t=1}^n \pi(a_t \mid h_{t-1}) p_{a_t}(x_t)] dx_n} \\
&= \frac{p_{v\pi}(h_n)}{\prod_{t=1}^{n-1} \pi(a_t \mid h_{t-1}) p_{a_t}(x_t)} \frac{1}{\int_{\mathbb{R}} \pi(a_n \mid h_{n-1}) p_{a_n}(x_n) dx_n} \\
&= \pi(a_n \mid h_{n-1}) p_{a_n}(x_n) \frac{1}{\pi(a_n \mid h_{n-1})} \\
&= p_{a_n}(x_n)
\end{aligned}$$

**4.4** Denote  $h_t = a_1, x_1, \dots, a_t, x_t$ . The policy that mixes the policies can be defined as

$$\pi_t^\circ(a_t \mid h_{t-1}) = \frac{\sum_{\pi \in \Pi} p(\pi) \prod_{s=1}^t \pi_s(a_s \mid h_{s-1})}{\sum_{\pi \in \Pi} p(\pi) \prod_{s=1}^{t-1} \pi_s(a_s \mid h_{s-1})}$$

By the definition of the canonical probability space and the product of probability kernels,

$$\begin{aligned}
\mathbb{P}_{v\pi^\circ}(B) &= \sum_{a_1=1}^k \int_{\mathbb{R}} \cdots \sum_{a_n=1}^k \int_{\mathbb{R}} \mathbb{I}_B(h_n) v_{a_n}(dx_n) \pi_n^\circ(a_n \mid h_{n-1}) \cdots v_{a_1}(dx_1) \pi_1^\circ(a_1) \\
&= \sum_{\pi \in \Pi} p(\pi) \sum_{a_1=1}^k \int_{\mathbb{R}} \cdots \sum_{a_n=1}^k \int_{\mathbb{R}} \mathbb{I}_B(h_n) v_{a_n}(dx_n) \pi_n(a_n \mid h_{n-1}) \cdots v_{a_1}(dx_1) \pi_1(a_1) \\
&= \sum_{\pi \in \Pi} p(\pi) \mathbb{P}_{v\pi}(B),
\end{aligned}$$

where the second equality follows by substituting the definition of  $\pi_n^\circ$  and induction.

# Chapter 5 Concentration of Measure

## 5.1

$$V(\hat{\mu}) = E((\hat{\mu} - \mu)^2) = E\left(\left(\frac{1}{n} \sum_{t=1}^n X_t - \mu\right)^2\right) = E\left(\frac{1}{n^2} \sum_{t=1}^n (X_t - \mu)^2\right) = \frac{1}{n^2} \sum_{t=1}^n E(X_t - \mu)^2 = \frac{1}{n^2} \sum_{t=1}^n \sigma^2 = \frac{\sigma^2}{n} \quad (23)$$

## 5.4

(a)

$$P(|X| \geq \varepsilon) = P(X \geq \varepsilon)I\{X \geq 0\} + P(X \leq -\varepsilon)I\{X < 0\} = \int_{\varepsilon}^{\infty} \frac{x}{2} \exp\left\{-\frac{x^2}{2}\right\} dx + \int_{-\infty}^{-\varepsilon} \frac{-x}{2} \exp\left\{-\frac{x^2}{2}\right\} dx \quad (24)$$

Calculate the above formula and get the result ,

$$P(|X| \geq \varepsilon) = \frac{1}{2} \exp\left\{-\frac{\varepsilon^2}{2}\right\} + \frac{1}{2} \exp\left\{-\frac{\varepsilon^2}{2}\right\} \\ = \exp\left\{-\frac{\varepsilon^2}{2}\right\}$$

(b)

Let's start with a lemma:

If  $X$  is  $\sigma$ -subgaussian, then  $P(|X| > t) \leq \exp\{-b\varepsilon^2\}$  , where  $b = \exp\{-\sigma^2\}$

The proof of lemma is omitted.

It can be seen from the first question ,  $P(|X| \geq \varepsilon) = \exp\left\{-\frac{\varepsilon^2}{2}\right\}$

The comparison of the two formulas shows that ,  $0 < b \leq 1/2$  . That is,  $\sigma \geq \sqrt{\ln 2}$

By topic condition ,  $\sigma = \sqrt{2 - \varepsilon}$

Hence ,  $\varepsilon \leq 2 - \ln 2$  , this is in contradiction with the arbitrariness of  $\varepsilon$

## 5.7

(a) If  $X$  is  $\sigma$ -subgaussian , then  $E(X) = 0, E(X^2) \leq \sigma^2$

proof:

$$E(e^{\lambda X}) = \sum_{n=0}^{\infty} \frac{\lambda^n E(X^n)}{n!} = 1 + \lambda E(X) + \frac{\lambda^2 E(X^2)}{2} + O(\lambda^2) \quad (25)$$

By definition ,

$$E(e^{\lambda X}) \leq e^{\frac{\lambda^2 \sigma^2}{2}} = 1 + \frac{\lambda^2 \sigma^2}{2} + O(\lambda^2) \quad (26)$$

By comparing the above two formulas and discussing the case that  $\lambda$  approaches to 0 from above and below 0, we get the conclusion that ,

$$E(X) = 0, E(X^2) \leq \sigma^2$$

(b)

If  $X$  is  $\sigma$ -subgaussian, then  $E(X) = 0, E(X^2) \leq \sigma^2$ .

$$\begin{aligned} E(e^{c\lambda x}) &= 1 + \lambda E(cx) + \frac{\lambda^2 E(c^2 x^2)}{2} + O(\lambda^2) \\ &\leq 1 + c\lambda E(x) + \frac{\lambda^2 c^2}{2} E(x^2) + O(\lambda^2) \\ &\leq 1 + \frac{\lambda^2 c^2 \sigma^2}{2} + O(\lambda^2) \\ &\leq e^{\frac{\lambda^2 c^2 \sigma^2}{2}} \end{aligned}$$

Hence,  $cX$  is  $|c|\sigma$ -subgaussian.

(c)

If  $X_1$  is  $\sigma_1$ -subgaussian,  $X_2$  is  $\sigma_2$ -subgaussian

$$\begin{aligned} \text{then } E(X_1) &= 0, E(X_1^2) \leq \sigma_1^2, E(X_2) = 0, E(X_2^2) \leq \sigma_2^2 \\ E(e^{\lambda(x_1+x_2)}) &= 1 + \lambda E(x_1+x_2) + \frac{\lambda^2 E((x_1+x_2)^2)}{2} + O(\lambda^2) \\ &= 1 + \frac{\lambda^2}{2} \text{Var}(x_1+x_2) + O(\lambda^2) \\ &= 1 + \frac{\lambda^2}{2} (\text{var}(x_1) + \text{var}(x_2) + 2\text{cov}(x_1, x_2)) + O(\lambda^2) \\ \text{Because } x_1, x_2 &\text{ are independent,} \\ &= 1 + \frac{\lambda^2}{2} (E(x_1^2) + E(x_2^2)) + O(\lambda^2) \\ &\leq 1 + \frac{\lambda^2}{2} (\sigma_1^2 + \sigma_2^2) + O(\lambda^2) \\ &\leq e^{\frac{\lambda^2(\sigma_1^2 + \sigma_2^2)}{2}} \end{aligned}$$

Hence,  $X_1 + X_2$  is  $\sqrt{\sigma_1^2 + \sigma_2^2}$ -subgaussian.

### 5.11

(a)

$$E(e^{\lambda X}) = 1 + \lambda E(X) + \frac{\lambda^2 E(X^2)}{2} + O(\lambda^2) = 1 + \frac{\lambda^2 E(X^2)}{2} + O(\lambda^2) \quad (27)$$

If the conclusion is true, then the above formula satisfies

$$\leq 1 + \frac{\lambda^2}{2} \left( \frac{(b-a)^2}{4} \right) + O(\lambda^2)$$

So just prove:

$$E(x^2) \leq \left( \frac{b-a}{2} \right)^2$$

$$E(x^2) = \text{var}(x) = E(x - \bar{x})^2$$

However,  $(x - \bar{x})^2 \leq \left( \frac{b-a}{2} \right)^2$ . The conclusion is proved.

(b)

The proof of Hoeffding's Inequality:

Let  $X_i = Z_i - E(Z_i)$ ,  $\bar{X} = \frac{1}{m} \sum_{i=1}^m X_i$

By Markov inequality, for all  $\lambda > 0$ ,  $\varepsilon > 0$ ,

$$P(\bar{X} \geq \varepsilon) = P(e^{\lambda \bar{X}} \geq e^{\lambda \varepsilon}) \leq \frac{E(e^{\lambda \bar{X}})}{e^{\lambda \varepsilon}}$$

$Z_1, \dots, Z_m$  iid.r.v.

$$\text{So, } E(e^{\lambda \bar{X}}) = \prod_{i=1}^m E(e^{\frac{\lambda X_i}{m}})$$

By Hoeffding's lemma,

$$E(e^{\frac{\lambda X_i}{m}}) \leq e^{\frac{\lambda^2 (b-a)^2}{8m^2}}$$

$$\text{So, } P(\bar{X} \geq \varepsilon) \leq e^{-\lambda \varepsilon} \prod_{i=1}^m E(e^{\frac{\lambda X_i}{m}})$$

$$\leq e^{-\lambda \varepsilon} e^{\frac{\lambda^2 (b-a)^2}{8m}}$$

$$\leq e^{-\lambda \varepsilon + \frac{\lambda^2 (b-a)^2}{8m}}$$

$$\text{Let } \lambda = \frac{4m\varepsilon}{(b-a)^2}, \text{ then } P(\bar{X} \geq \varepsilon) \leq e^{\frac{-2m\varepsilon^2}{(b-a)^2}}$$

Similarly, we can prove the other side of the inequality.

**5.16** By assumption  $Pr(X_t \leq x) \leq x$ , which means that for  $\lambda < 1$ ,

$$\mathbb{E} \left[ \exp(\lambda \log(\frac{1}{x_t})) \right] = \int_0^\infty P(\exp(\lambda \log(\frac{1}{x_t})) \geq x) dx = 1 + \int_1^\infty P(X_t \leq x^{-\frac{1}{\lambda}}) dx \quad (28)$$

Applying the Cramer-Chernoff method,

$$P \left( \sum_{t=1}^n \log(\frac{1}{X_t}) \geq \epsilon \right) = P \left( \exp(\lambda \sum_{t=1}^n \log(\frac{1}{X_t})) \geq \exp(\lambda \epsilon) \right) \leq \left( \frac{1}{1-\lambda} \right)^n \exp(-\lambda \epsilon)$$

choosing  $\lambda = \frac{\epsilon - n}{\epsilon}$  completes the claim.

**5.18(a)** Let  $\lambda > 0$ . Then,

$$\exp(\lambda \mathbb{E}[Z]) \leq \mathbb{E}[\exp(\lambda Z)] \leq \sum_{t=1}^n \mathbb{E}[\exp(\lambda X_t)] \leq n \exp\left(\frac{\lambda^2 \sigma^2}{2}\right)$$

Rearranging shows that,

$$\mathbb{E}(Z) \leq \frac{\log(n)}{\lambda} + \frac{\lambda \sigma^2}{2}$$

Choosing  $\lambda = \frac{1}{\sigma} \sqrt{2 \log(n)}$  shows that  $\mathbb{E}(Z) \leq \sqrt{2 \sigma^2 \log(n)}$



# Chapter 6 The Explore-Then-Commit Algorithm

**6.2** We proceed by comparing the values of  $n\Delta$  and  $\Delta + \frac{4}{\Delta} \left(1 + \max \left\{0, \log \left(\frac{n\Delta^2}{4}\right)\right\}\right)$ .

- (a) If  $n\Delta > \Delta + \frac{4}{\Delta} \left(1 + \max \left\{0, \log \left(\frac{n\Delta^2}{4}\right)\right\}\right)$ , we have  $(n-1)\Delta^2 > 4(1 + \max \left\{0, \log \left(\frac{n\Delta^2}{4}\right)\right\}) \geq 4$ , which suggests that  $\Delta \geq \frac{2}{\sqrt{n}}$ . Therefore,

$$\begin{aligned} R_n &= \Delta + \frac{4}{\Delta} \left(1 + \max \left\{0, \log \left(\frac{n\Delta^2}{4}\right)\right\}\right) \\ &= \Delta + \frac{4}{\Delta} \left(1 + \log \left(\frac{n\Delta^2}{4}\right)\right) \\ &= \Delta + \frac{4}{\Delta} + \frac{4}{\Delta} \log \left(\frac{n\Delta^2}{4}\right) \\ &\leq \Delta + 2\sqrt{n} + \frac{16}{e^4} \sqrt{n} \\ &= \Delta + C\sqrt{n}, \end{aligned}$$

where the inequality follows from taking  $x^* = \frac{2e^4}{\sqrt{n}}$  to maximize  $f(x) = \frac{4}{x} \log \left(\frac{nx^2}{4}\right)$ .

- (a) If  $n\Delta \leq \Delta + \frac{4}{\Delta} \left(1 + \max \left\{0, \log \left(\frac{n\Delta^2}{4}\right)\right\}\right)$ , we consider another two cases:

- (i) If  $\Delta \geq \frac{2}{\sqrt{n}}$ , by (1) we still have  $R_n = n\Delta \leq \Delta + \frac{4}{\Delta} \left(1 + \max \left\{0, \log \left(\frac{n\Delta^2}{4}\right)\right\}\right) \leq \Delta + C\sqrt{n}$ .  
(ii) If  $\Delta < \frac{2}{\sqrt{n}}$ ,  $R_n \leq n\Delta \leq 2\sqrt{n} \leq \Delta + C\sqrt{n}$ , where the first inequality is trivial.

**6.3** Suppose  $\Delta_1 = 0$ ,  $\Delta_2 = \Delta > 0$ . Then, the probability that we choose the suboptimal arm (i.e., the second arm) after commitment is

$$\begin{aligned} \mathbb{P}(T_2(n) > m) &= \mathbb{P}(\hat{\mu}_2(2m) > \hat{\mu}_1(2m)) \\ &= \mathbb{P}([\hat{\mu}_2(2m) - \mu_2] - [\hat{\mu}_1(2m) - \mu_1] > \Delta) \\ &\leq \exp\left(-\frac{m\Delta^2}{4}\right), \end{aligned}$$

where the inequality follows from Theorem 5.3. By letting  $\exp\left(-\frac{m\Delta^2}{4}\right) = \delta$ , we have  $m = -\frac{4\log \delta}{\Delta^2}$ . Hence, if we take  $m = \min\{\lfloor \frac{n}{2} \rfloor, -\frac{4\log \delta}{\Delta^2}\}$ , with high probability we have

$$\begin{aligned} \bar{R}_n &= \Delta T_2(n) \\ &\leq \Delta m \\ &= \min\{\lfloor \frac{n}{2} \rfloor \Delta, -\frac{4\log \delta}{\Delta}\} \end{aligned}$$

**6.4** Denote the reward received in the  $t$ -th interaction with arm  $i$  as  $X_{i,t}$ . From 6.3 we have that with probability  $1 - \delta$ ,

$$\begin{aligned}\hat{R}_n &\leq \sum_{t=1}^{n-m} (\mu_1 - X_{1,t}) + \sum_{t=1}^m (\mu_1 - X_{2,t}) \\ &= \sum_{t=1}^{n-m} (\mu_1 - X_{1,t}) + \sum_{t=1}^m (\mu_2 - X_{2,t}) + m\Delta\end{aligned}$$

Notice that the sum of the first two terms is  $(\sqrt{(n-m)^2 + m^2})$ -subgaussian. Therefore, with probability  $(1-\delta)^2$ , we have  $\hat{R}_n \leq \sqrt{-2[(n-m)^2 + m^2] \log \delta} + m\Delta$ . This suggests that compared to that derived for the pseudo-regret, the bound on the random regret is less tight with a smaller probability as more randomness is considered.

**6.5** Suppose  $\Delta_1 = 0$ ,  $\Delta_2 = \Delta > 0$ .

(a) By Theorem 6.1, we have

$$\begin{aligned}R_n(v) &= \Delta \mathcal{E}[T_2(n)] \\ &\leq m\Delta + (n-2m)\Delta \exp\left(-\frac{m\Delta^2}{4}\right) \\ &\leq m\Delta + n\Delta \exp\left(-\frac{m\Delta^2}{4}\right) \\ &\leq m\Delta + n\sqrt{\frac{2}{m}} \exp\left(-\frac{1}{2}\right) \\ &= [\Delta + \sqrt{2} \exp\left(-\frac{1}{2}\right)] n^{\frac{2}{3}},\end{aligned}$$

where the last inequality follows from taking  $x^* = \sqrt{\frac{2}{m}}$  to maximize  $f(x) = x \exp(-\frac{m\Delta^2}{4})$ , and the last equality follows from taking  $m = n^{\frac{2}{3}}$ .

Assume there is such a  $C > 0$  that leads to  $R_n(v) \leq \Delta_v + Cn^{2/3}$  for any problem instance  $v$  and  $n \geq 1$ . Since trivially  $R_n(v) \geq m\Delta$ , we have  $m\Delta \leq \Delta + Cn^{\frac{2}{3}} \Rightarrow m \leq 1 + \frac{Cn^{\frac{2}{3}}}{\Delta}$ . Under this circumstance, we can easily find a problem instance  $v$  with  $\Delta \rightarrow \infty$  such that  $m \leq 1$ . Recalling we only explore  $2m$  rounds, we will eventually pull the suboptimal arm with a high probability, which contradicts our assumption.

(c) We proceed by comparing the values of  $\frac{C \log n}{\Delta}$  and  $C\sqrt{n \log(n)}$ .

- (i) If  $\Delta \geq \sqrt{\frac{\log n}{n}}$ ,  $R_n(v) \leq \Delta + C \frac{\log n}{\Delta} \leq \Delta + C\sqrt{n \log n}$ .
- (ii) If  $\Delta < \sqrt{\frac{\log n}{n}}$ ,  $R_n(v) \leq n\Delta \leq \sqrt{n \log n} \leq \Delta + C\sqrt{n \log n}$ .

(e) We proceed by comparing the values of  $e$  and  $n\Delta^2$ .

- (i) If  $\Delta \geq \sqrt{\frac{e}{n}}$ ,  $R_n(v) \leq \Delta + \frac{C \log(n\Delta^2)}{\Delta} \leq \Delta + \frac{2C}{e} \sqrt{n} = \Delta + C\sqrt{n}$ .
- (ii) If  $\Delta < \sqrt{\frac{e}{n}}$ ,  $R_n(v) \leq n\Delta \leq \sqrt{en} \leq \Delta + C\sqrt{n}$ .



# Chapter 11 The Exp3 Algorithm

**11.2** Let  $\pi$  be a deterministic policy, and we define  $x_{ti} = 0$  if  $A_t = i$  otherwise  $x_{ti} = 1$ . The deterministic policy collects zero rewards all time,

$$\max_{i \in [k]} \sum_{t=1}^n x_{ti} \geq \frac{1}{k} \sum_{t=1}^n \sum_{i=1}^k x_{ti} = \frac{n(k-1)}{k}$$

**11.5** Let  $P$  be a probability vector with nonzero components and let  $A \sim P$ . Suppose  $\hat{X}$  is a function such that for all  $x \in \mathbb{R}^k$ ,

$$\mathbb{E} [\hat{X}(A, x_A)] = \sum_{i=1}^k P_i \hat{X}(i, x_i) = x_1$$

Show that there exists an  $a \in \mathbb{R}^k$  such that  $\langle a, P \rangle = 0$  and for all  $i$  and  $z$  in their respective domains,  $\hat{X}(i, z) = a_i + \frac{\mathbb{I}_{\{i=1\}} z}{P_1}$

*Proof.* Let  $x, x'$  be arbitrary but agree on the first component  $x_1 = x'_1$ . Let  $f(x) = \sum_{i=1}^k P_i \hat{X}(i, x_i)$  Note that,

$$0 = f(x) - f(x') = \sum_{i=j}^k P_j \hat{X}(j, x_j)$$

for all  $j > 1$ . Since  $x, x'$  are arbitrary,  $\hat{X}(j, \cdot) = \text{const.}$  Let  $a_j$  equal to  $\hat{X}(j, \cdot)$ .

Further, let  $a_1 = \hat{X}(1, 0)$  and then given any  $x_1 \in \mathbb{R}$ ,  $\hat{X}(1, x_1) = a_1 + x_1/P_1$ .

Finally, let  $x$  be such that  $x_1 = 0$ . Then  $0 = f(x) = \sum_i P_i a_i$ . □

**11.7** First, note that if  $G = -\log(-\log(U))$  then  $\mathbb{P}(G \leq g) = e^{-\exp(-g)}$ .

$$\begin{aligned} \mathbb{P} \left( \log a_i + G_i \geq \max_{j \in [k]} \log a_j + G_j \right) &= \mathbb{E} \left[ \prod_{j \neq i} \mathbb{P}(\log a_j + G_j \leq \log a_i + G_i \mid G_i) \right] \\ &= \mathbb{E} \left[ \prod_{j \neq i} \exp \left( -\frac{a_j}{a_i} \exp(-G_i) \right) \right] \\ &= \mathbb{E} \left[ U_i^{\sum_{j \neq i} \frac{a_j}{a_i}} \right] \\ &= \frac{1}{1 + \sum_{j \neq i} \frac{a_j}{a_i}} \\ &= \frac{a_i}{\sum_{j=1}^k a_j} \end{aligned}$$

**11.8** Let  $Z_{ti}$  be a standard Gambel. The follow-the-perturbed-leader algorithm chooses

$$A_t = \operatorname{argmax}_{i \in [k]} \left( Z_{ti} - \eta \sum_{s=1}^{t-1} \hat{Y}_{si} \right)$$

is the same as EXP3. Given (11.7)

$$\mathbb{P} \left( \log(a_i) + G_i = \max_{j \in [k]} (\log(a_j) + G_j) \right) = \frac{a_i}{\sum_{j=1}^k a_j}$$

Just simply take  $a_i$  as  $-\eta \sum_{s=1}^{t-1} \hat{Y}_{si}$ , then the form is identical.

# Chapter 18

## 18.1

(a) By Jensen's inequality,

$$\begin{aligned}\sum_{c \in \mathcal{C}} \sqrt{\sum_{t=1}^n \mathcal{I}\{c_t = c\}} &= \|C\| \sum_{c \in \mathcal{C}} \frac{1}{\|C\|} \sqrt{\sum_{t=1}^n \mathcal{I}\{c_t = c\}} \\ &\leq \|C\| \sqrt{\sum_{c \in \mathcal{C}} \frac{1}{\|C\|} \sum_{t=1}^n \mathcal{I}\{c_t = c\}} \\ &= \sqrt{\|C\|n}\end{aligned}$$

(b) When each context occurs  $\frac{n}{\|\mathcal{C}\|}$  times we have

$$\sum_{c \in \mathcal{C}} \sqrt{\sum_{t=1}^n \mathcal{I}\{c_t = c\}} = \sqrt{n\|C\|}$$