Solutions

Chapter 2 Foundations of Probability

2.1 (Composing random elements) Show that if f is $\mathcal{F}/\mathcal{G}$-measurable and g is $\mathcal{G}/\mathcal{H}$-measurable for sigma algebras $\mathcal{F}$,$\mathcal{G}$ and $\mathcal{H}$ over appropriate spaces, then their composition, $g \circ f$ (defined the usual way: $(g \circ f)(\omega) = g(f(\omega)), \omega \in \Omega$), is $\mathcal{F}/\mathcal{H}$-measurable.

Proof. Since g is $\mathcal{G}/\mathcal{H}$-measurable, therefore $\forall C \in \mathcal{H}$, $\exists B = g^{-1}(C) \in \mathcal{G}$. Similarly, since f is $\mathcal{F}/\mathcal{G}$-measurable, $\forall B \in \mathcal{G}$, $\exists A = f^{-1}(B) \in \mathcal{F}$. Thus $\forall C \in \mathcal{H}$, $\exists A = f^{-1}(g^{-1}(C)) = (g \circ f)^{-1}(C) \in \mathcal{F}$ and the proof is complete.

$\square$

2.2 Let $X_1, \ldots, X_n$ be random variables on $(\Omega, \mathcal{F})$. Prove that $X = (X_1, \ldots, X_n)$ is a random vector.

Proof. Since X_i is a random variable ($\forall i = 1, 2, ..., n$), it holds that X_i is $\mathcal{F}/\mathcal{B}(\mathbb{R})$-measurable, which means that $\forall B \in \mathcal{B}(\mathbb{R})$, $X_i^{-1}(B) \in \mathcal{F}$. We first prove that X is $\mathcal{F}/(\mathcal{B}(\mathbb{R}) \times \mathcal{B}(\mathbb{R}) \times \cdots \mathcal{B}(\mathbb{R}))$-measurable (totally n $\mathcal{B}(\mathbb{R})$s). $\forall A = A_1 \times A_2 \times \cdots \times A_n \in \mathcal{B}(\mathbb{R}) \times \mathcal{B}(\mathbb{R}) \times \cdots \mathcal{B}(\mathbb{R})$, $X^{-1}(A) = X_1^{-1}(A_1) \cap X_2^{-1}(A_2) \cap \cdots \cap X_n^{-1}(A_n) \in \mathcal{F}$, which holds since $X_i^{-1}(A_i) \in \mathcal{F}, \forall i = 1, 2, ..., n$ and $\mathcal{F}$ is a σ-algebra. Thus we conclude that X is $\mathcal{F}/(\mathcal{B}(\mathbb{R}) \times \mathcal{B}(\mathbb{R}) \times \cdots \mathcal{B}(\mathbb{R}))$-measurable.

By definition $\mathcal{B}(\mathbb{R}^n) = \sigma(\mathcal{B}(\mathbb{R}) \times \mathcal{B}(\mathbb{R}) \times \cdots \mathcal{B}(\mathbb{R}))$ (totally n $\mathcal{B}(\mathbb{R})$s). And according to the property in 2.5(b), we can get that X is $\mathcal{F}/\mathcal{B}(\mathbb{R}^n)$-measurable, thus it is a random vector.

$\square$

2.3 (Random variable induced σ-algebra) Let $\mathcal{U}$ be an arbitrary set and $(\mathcal{V}, \Sigma)$ a measurable space and $X : \mathcal{U} \to \mathcal{V}$ an arbitrary function. Show that $\Sigma_X = \{X^{-1}(A) : A \in \Sigma\}$ is a σ-algebra over $\mathcal{U}$.

Proof. (i) We need to show that Σ_X is closed under countable union. Let $U_i = X^{-1}(A_i), A_i \in \Sigma, i \in \mathbb{N}$. It follows that $\bigcup_{i=1}^{\infty} U_i = \bigcup_{i=1}^{\infty} X^{-1}(A_i) = X^{-1}(\bigcup_{i=1}^{\infty} A_i)$. Since $\bigcup_{i=1}^{\infty} A_i \in \Sigma$, $\bigcup_{i=1}^{\infty} U_i \in \Sigma_X$.

(ii) We need to show that Σ_X is closed under set subtraction $-$. $\forall U_1, U_2 \in \Sigma_X, U_1 - U_2 = X^{-1}(A_1) - X^{-1}(A_2) = X^{-1}(A_1 - A_2)$. Since $A_1 - A_2 \in \Sigma$, $U_1 - U_2 \in \Sigma_X$.

(iii) We need to show that Σ_X is closed to $\mathcal{U}$ itself. Since $\mathcal{U} = X^{-1}(\mathcal{V})$ and $\mathcal{V} \in \Sigma$, it follows that $\mathcal{U} \in \Sigma_X$.

$\square$

2.4 Let $(\Omega, \mathcal{F})$ be a measurable space and $A \subseteq \Omega$ and $\mathcal{F}_{|A} = \{A \cap B : B \in \mathcal{F}\}$.

Proof. (a) (i) We need to show that $\mathcal{F}|_A$ is closed under countable union. Let $X_1 = A \cap B_1, X_2 = A \cap B_2, ...$ and $X' = \bigcup_{i=1}^{\infty} X_i$ and $B' = \bigcup_{i=1}^{\infty} B_i$ where $B_1, B_2, ... \in \mathcal{F}$. Since $\mathcal{F}$ is sigma algebra, $B' \in \mathcal{F}$. Furthermore, since $X' = \bigcup_{i=1}^{\infty} X_i = \bigcup_{i=1}^{\infty} A \cap B_i = A \cap \left(\bigcup_{i=1}^{\infty} B_i \right) = A \cap B'$, we can see that $X' \in \mathcal{F}|_A$.

(ii) We need to show that $\mathcal{F}|_A$ is closed under set subtraction $-$. $\forall X_1, X_2 \in \mathcal{F}|_A$, $X_1 - X_2 = (A \cap B_1) - (A \cap B_2) = A \cap (B_1 - B_2)$. Since $B_1 - B_2 \in \mathcal{F}$, it follows that $X_1 - X_2 \in \mathcal{F}|_A$.

(iii) We need to show that $\mathcal{F}|_A$ is closed to A itself. Since $\varnothing \in \mathcal{F}$, we have $\varnothing = A \bigcap \varnothing \in \mathcal{F}|_A$ and $A = \varnothing^C \in \mathcal{F}|_A$.

(b) Let $P = \{A \bigcap B : B \in \mathcal{F}\}, Q = \{B : B \subset A, B \in \mathcal{F}\}$.

  (i) We claim that $P \subset Q$. Let $X = A \bigcap B, B \in \mathcal{F}$. Since $A \in \mathcal{F}$, $X = A \bigcap B \in \mathcal{F}$. Furthermore, $X \in Q = \{B : B \subset A, B \in \mathcal{F}\}$.

  (ii) We claim that $Q \subset P$. $\forall X \in Q$, we have $X \subset A$ and $X \in \mathcal{F}$, which means that $X = X \bigcap A$ and $X \in \mathcal{F}$. It follows that $X \in P$.

  (iii) Take both (i)(ii) into consideration, we can see that $P = Q$.

$\square$

2.5

(a) Clearly $\sigma(\mathcal{G})$ should be the intersection of all σ-algebras that contain $\mathcal{G}$. Formally speaking, let $\mathcal{K} = \{\mathcal{F}|\mathcal{F}$ is a σ-algebra and contains $\mathcal{G}\}$. Then $\bigcap_{\mathcal{F}\in\mathcal{K}} \mathcal{F}$ contains exactly those sets that are in every σ-algebra that contains $\mathcal{G}$. Given its existence, we only need to prove that $\bigcap_{\mathcal{F}\in\mathcal{K}} \mathcal{F}$ is the smallest σ-algebra that contains $\mathcal{G}$.

First we show $\bigcap_{\mathcal{F}\in\mathcal{K}} \mathcal{F}$ is a σ-algebra. Since $\mathcal{F}$ is a σ-algebra and therefore $\Omega \in \mathcal{F}$ for all $\mathcal{F} \in \mathcal{K}$, it follows that $\Omega \in \bigcap_{\mathcal{F}\in\mathcal{K}} \mathcal{F}$. Next, for any $A \in \bigcap_{\mathcal{F}\in\mathcal{K}} \mathcal{F}$, $A^c \in \mathcal{F}$ for all $\mathcal{F} \in \mathcal{K}$. Since they are all σ-algebras, $A^c \in \mathcal{F}$ for all $\mathcal{F} \in \mathcal{K}$. Hence $A^c \in \bigcap_{\mathcal{F}\in\mathcal{K}} \mathcal{F}$. Finally, for any $\{A_i\}_i \subset \bigcap_{\mathcal{F}\in\mathcal{K}} \mathcal{F}$, $\{A_i\}_i \subset \mathcal{F}$ for all $\mathcal{F} \in \mathcal{K}$. Since they are all σ-algebras, $\bigcup_i A_i \in \mathcal{F}$ for all $\mathcal{F} \in \mathcal{K}$. Hence $\bigcup_i A_i \in \bigcap_{\mathcal{F}\in\mathcal{K}} \mathcal{F}$.

It is quite obvious that $\bigcap_{\mathcal{F}\in\mathcal{K}} \mathcal{F}$ is the smallest one as $\bigcap_{\mathcal{F}\in\mathcal{K}} \mathcal{F} \subseteq \mathcal{F}'$ for all $\mathcal{F}' \in \mathcal{K}$.

(b) We first introduce a useful lemma: the map X is $\mathcal{F}/\mathcal{G}$-measurable if and only $\sigma(X) \subseteq \mathcal{F}$, where $\sigma(X) = \{X^{-1}(A) : A \in \mathcal{G}\}$ is the σ-algebra generated by X. With this lemma, the main idea to prove X is $\mathcal{F}/\sigma(\mathcal{G})$-measurable is to show that $\sigma(X) = \{X^{-1}(A) : A \in \sigma(\mathcal{G})\} \subseteq \mathcal{F}$.

Let $X^{-1}(\mathcal{G}) = \{X^{-1}(A) : A \in \mathcal{G}\}$. Clearly we have $X^{-1}(\mathcal{G}) \subseteq \mathcal{F}$. $\sigma(X^{-1}(\mathcal{G}))$ is the smallest σ-algebra that contains $X^{-1}(\mathcal{G})$. And we know $\mathcal{F}$ is a σ-algebra that contains $X^{-1}(\mathcal{G})$. According to the result of the previous question, $\sigma(X^{-1}(\mathcal{G})) \subseteq \mathcal{F}$. Furthermore, $\sigma(X^{-1}(\mathcal{G})) = X^{-1}(\sigma(\mathcal{G})) = \{X^{-1}(A) : A \in \sigma(\mathcal{G})\} = \sigma(X)$. Hence $\sigma(X) \subseteq \mathcal{F}$.

Readers can further refer to the penultimate paragraph in Page 16, where the author provides a general idea to check whether a map is measurable.

(c) The idea is to show $\forall B \in \mathfrak{B}(\mathbb{R})$, $\mathbb{I}\{A\}^{-1}(B) \in \mathcal{F}$.

If $\{0, 1\} \in B$, $\mathbb{I}\{A\}^{-1}(B) = \Omega \in \mathcal{F}$. If $\{0\} \in B$, $\mathbb{I}\{A\}^{-1}(B) = A^c \in \mathcal{F}$. If $\{1\} \in B$, $\mathbb{I}\{A\}^{-1}(B) = A \in \mathcal{F}$. If $\{0, 1\} \cap B = \emptyset$, $\mathbb{I}\{A\}^{-1}(B) = \emptyset \in \mathcal{F}$.

2.6 As the hint suggests, Y is not $\sigma(X)$-measurable under such conditions since $Y^{-1}((0, 1)) = (0, 1) \notin \sigma(X)$, where $\sigma(X) = \{X^{-1}(A) : A \in \mathcal{G}\} = \{\emptyset, \mathbb{R}\}$.

2.7 First we have $\mathbb{P}(\Omega \mid B) = \frac{\mathbb{P}(\Omega \cap B)}{\mathbb{P}(B)} = \frac{\mathbb{P}(B)}{\mathbb{P}(B)} = 1$. Then, for all $A \in \mathcal{F}$, $\mathbb{P}(A \mid B) = \frac{\mathbb{P}(A \cap B)}{\mathbb{P}(B)} \geq 0$. Next, for all $A \in \mathcal{F}$, $\mathbb{P}(A^c \mid B) = \frac{\mathbb{P}(A^c \cap B)}{\mathbb{P}(B)} = \frac{\mathbb{P}((\Omega - A) \cap B)}{\mathbb{P}(B)} = \frac{\mathbb{P}(B) - \mathbb{P}(A \cap B)}{\mathbb{P}(B)} = 1 - \mathbb{P}(A \mid B)$. Finally, for all countable collections of disjoint sets $\{A_i\}_i$ with $A_i \in \mathcal{F}$ for all i, we have $\mathbb{P}\left(\bigcup_i A_i \mid B\right) = \frac{\mathbb{P}((\bigcup_i A_i) \cap B)}{\mathbb{P}(B)} = \frac{\mathbb{P}(\bigcup_i (A_i \cap B))}{\mathbb{P}(B)} = \sum_i \frac{\mathbb{P}(A_i \cap B)}{\mathbb{P}(B)} = \sum_i \mathbb{P}(A_i \mid B)$.

2.8 With the definition of conditional probability, we have $\mathbb{P}(A \mid B) = \frac{\mathbb{P}(A \cap B)}{\mathbb{P}(B)} = \frac{\mathbb{P}(B|A)\mathbb{P}(A)}{\mathbb{P}(B)}$.

2.9

(a) There are 36 possible events:

1.$X_1 < 2$,$X_2 =$even:

$$X_1 = 1, X_2 = 2$$

$$X_1 = 1, X_2 = 4$$
$$X_1 = 1, X_2 = 6$$

So,P($X_1 < 2$,X_2 =even)= $\frac{3}{36} = \frac{1}{12}$

and $P(X_1 < 2) = \binom{}{1}(6)$,P($X_2$ =even)= $\frac{1}{2}$

So,P($X_1 < 2$,X_2 =even)= $P(X_1 < 2)$*P(X_2 =even).According to the definition of independent event, two events are independent.

(b) Prove$P(A \bigcap B) = P(A)P(B)$

2.10

(a) Empty sets and complete sets are independent of any event:

$$P(A \bigcap \Omega) = P(A) = 1 * P(A) = P(\Omega) * P(A)$$
$$P(A \bigcap \phi) = P(\phi) = 0 = P(\phi) * P(A)$$

(b) Prove when$P(A) = 0 or 1$,A is independent of any event:for any $B \in \Omega$

$P(A) \in \{0, 1\}$

When$P(A) = 1$,$P(A^c \bigcap B) \leq P(A^c) = 1 - P(A) = 0$,

we have $P(A \bigcap B) = P(A \bigcap B) + P(A^c \bigcap B) = P(B) = P(A)P(B)$

When$P(A) = 0$,we have $P(A \bigcap B) \leq P(A) = 0 = P(A)P(B)$

(c) $P(A^c \bigcap A) = P(A)P(A^c)$

we have $0 = P(A)(1 - P(A)) \Rightarrow P(A) \in \{0, 1\}$

(d) $P(A \bigcap A) = P(A)P(A)$,$P(A) = 0, 1$

(e) $\Omega = (1, 1), (1, 0), (0, 1), (0, 0)$

Just verify that each case is independent :$P(A = 1, B = 1) = \frac{1}{4} = \frac{1}{2} * \frac{1}{2} = P(A)P(B)$

$P(A = 1, B = 0) = \frac{1}{4} = \frac{1}{2} * \frac{1}{2} = P(A)P(B)$

$P(A = 0, B = 1) = \frac{1}{4} = \frac{1}{2} * \frac{1}{2} = P(A)P(B)$

$P(A = 0, B = 0) = \frac{1}{4} = \frac{1}{2} * \frac{1}{2} = P(A)P(B)$

(f) $P(X_1 \leq 2) = 2/3$

$P(X_1 = X_2) = 3/9 = 1/3$

$P(X_1 \leq 2, X_1 = X_2) = P(X_1 = X_2 = 1) + P(X_1 = X_2 = 2) = 1/9 + 1/9 = 2/9$

So, $P(X_1 \leq 2, X_1 = X_2) = P(X_1 = X_2)P(X_1 \leq 2)$

(g) Necessity :$\frac{|A \bigcap B|}{n} = P(A \bigcap B) = P(A)P(B) = \frac{|A|}{n} \frac{|B|}{n}$

$\Rightarrow |A \bigcap B| * n = |A||B|$

Sufficiency :$|A \bigcap B| * n = |A||B| \Rightarrow \frac{|A|}{n} \frac{|B|}{n} = \frac{|A \bigcap B|}{n}$

$\Rightarrow P(A \bigcap B) = P(A)P(B)$

(h) $|A \bigcap B| * n = |A||B|, \Rightarrow n \leq |A| \leq n \Rightarrow A \neq \phi or \Omega$

(j) Let's take a counter example: roll a die and set the A event to$\{1, 2, 3\}$,B event is set to$\{1, 2, 4\}$,C event is set to$\{1, 4, 5, 6\}$

$P(X_1 X_2 X_3) = \frac{1}{6}$

$P(X_1)P(X_2)P(X_3) = (1/2) * (1/2) * (2/3) = 1/6$

while$P(X_1 \bigcap X_2) = 1/3 \neq \frac{1}{2} * \frac{1}{2}$

2.11

(a) X:$\Omega \to x$

Because X, Y are independent equivalent to$\sigma(X),\sigma(Y)$ are independent;

For any A$\in \sigma(Y)$,

$$P(\phi \bigcap A) = P(\phi) = 0 = P(\phi)P(A)$$

$$P(\Omega \bigcap A) = P(A) = P(\Omega)P(A)$$

(b) We know that $P(X = x) = 1$

$$P(X = x|Y) = \frac{P((X = x) \bigcap Y)}{P(Y)} = 1 = P(X = x)$$

$$P(X \neq x|Y) = 1 - P(X = x|Y) = 0 = P(X \neq x)$$

(c) Notice the relation:$P(A) = P(X(A) = 1)$

$P(B) = P(X(B) = 1)$

$P(A \bigcap B) = P(X(A \bigcap B) = 1)$

The first two formulas follow the definition. Let's prove the third equation:

$P(X(A \bigcap B) = P(X(A) + X(B) - X(A \bigcup B) = 1)$

Let's discuss$X(A), X(B), X(A \bigcup B)$:

X(A)	X(B)	X(A$\bigcup$ B)	$X(A) + X(B) - X(A \bigcup B)$
1	1	1	1
1	0	1	0
0	1	1	0
0	0	0	0

We can see that,$P(X(A \bigcap B) = P(X(A) + X(B) - X(A \bigcup B) = 1)$, this is only one case of the first row of the table.

that is$P(X(A \bigcap B) = 1) = P(X(A) = 1, X(B) = 1) = P(A \bigcap B)$

that is$P(X(A \bigcap B) = 1) = P(A \bigcap B)$

So,$P(A \bigcap B) = P(A)P(B)$ is equivalent to $P(X(A \bigcap B) = 1) = P(X(A) = 1)P(X(B) = 1)$

(d) A_i pairwise i $\Leftrightarrow I\{A_i\}$ pairwise i

mutual i $\Leftrightarrow P(\bigcap_i A_i) = \prod_i P(A_i)$

$\Leftrightarrow P(\bigcap_{i \in K^I} A_i \bigcap \bigcap_{i \in K^I} A_i^c)$

$= \prod_{i \in K^I} P(A_i) \prod_{i \in K^I} P(A_i^c)$

$\Leftrightarrow \{\phi, \Omega, A_i, A_i^c\}$ mutual independent

$\Leftrightarrow \sigma(I\{w \in A_i\})$mutual i

$\Leftrightarrow I\{w \in A_i\}$ mutual i

2.12 X integrable $|X|$ integrable

(a) For any $A \in B(R) \Rightarrow$A is open,

so,$f^{-1}(A)$is open,so $f^{-1}(A) \in B(R)$

(b) X is known to be a random variable $,f(x) = |x|$ continuous.

    r.v. X is $\mathbf{F}/\mathbf{B}(R)$-measurable

    $\Rightarrow |X|$ is $\mathbf{B}(R)/\mathbf{B}(R)$-measurable

    $\Rightarrow |X|$ is $\mathbf{F}/\mathbf{B}(R)$-measurable

    $\Rightarrow |X|$ is r.v.

    From (a)(b),X integrable $\Leftrightarrow |X|$ integrable.

2.14

(a) Assume $\forall i, X_i$ is simple function.

$$
\begin{aligned}
\mathbb{E}[X] &= \mathbb{E}\left[\sum_{i=1}^{n} X_i\right] \\
&= \mathbb{E}\left[\sum_{i=1}^{n}\sum_{j=1}^{m} \alpha_{i,j}\mathbb{I}_{A_{i,j}}\{\omega\}\right] \\
&= \int_{\Omega}\sum_{i=1}^{n}\sum_{j=1}^{m} \alpha_{i,j}\mathbb{I}_{A_{i,j}}\{\omega\}d\mathbb{P}(\omega) \\
&= \sum_{i=1}^{n}\sum_{j=1}^{m} \alpha_{i,j}\int_{\Omega}\mathbb{I}_{A_{i,j}}\{\omega\}d\mathbb{P}(\omega) \\
&= \sum_{i=1}^{n}\sum_{j=1}^{m} \alpha_{i,j}\mathbb{P}(A_{i,j}) \\
&= \sum_{i=1}^{n} \mathbb{E}[X_i]
\end{aligned}
$$

(b) Assume $\forall i, X_i$ is non-negative random variable.

$$
\begin{aligned}
\mathbb{E}[X] &= \mathbb{E}\left[\sum_{i=1}^{n} X_i\right] \\
&= \sup\left\{\int_{\Omega} h d\mathbb{P} : h \text{ is simple and } 0 \leq h \leq X = \sum_{i=1}^{n} X_i\right\} \\
&= \sum_{i=1}^{n} \sup\left\{\int_{\Omega} h_i d\mathbb{P} : h_i \text{ is simple and } 0 \leq h_i \leq X_i\right\} \\
&= \sum_{i=1}^{n} \mathbb{E}[X_i]
\end{aligned}
$$

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(c) Assume $\forall i, X_i$ is arbitrary random variable.

$$\mathbb{E}[X] = \mathbb{E}\left[\sum_{i=1}^{n} X_i\right]$$

$$= \mathbb{E}\left[\sum_{i=1}^{n}(X_i^+ - X_i^-)\right]$$

$$= \mathbb{E}\left[\sum_{i=1}^{n} X_i^+\right] - \mathbb{E}\left[\sum_{i=1}^{n} X_i^-\right]$$

$$= \sum_{i=1}^{n} \mathbb{E}\left[X_i^+\right] - \sum_{i=1}^{n} \mathbb{E}\left[X_i^-\right]$$

$$= \sum_{i=1}^{n} \left(\mathbb{E}[X_i^+] - \mathbb{E}[X_i^-]\right)$$

$$= \sum_{i=1}^{n} \mathbb{E}[X_i]$$

2.15

(a) Assume X is simple function.

$$\mathbb{E}[cX] = \mathbb{E}\left[c\sum_{i=1}^{n} \alpha_i \mathbb{I}_{A_i}\{\omega\}\right]$$

$$= \int_{\Omega} c\sum_{i=1}^{n} \alpha_i \mathbb{I}_{A_i}\{\omega\}d\mathbb{P}(\omega)$$

$$= c\int_{\Omega} \sum_{i=1}^{n} \alpha_i \mathbb{I}_{A_i}\{\omega\}d\mathbb{P}(\omega)$$

$$= c\mathbb{E}[X]$$

(b) Assume X is non-negative random variable.

$$\mathbb{E}[cX] = \sup\left\{\int_{\Omega} h d\mathbb{P} : h \text{ is simple and } 0 \leq h \leq cX\right\}$$

$$= c\sup\left\{\int_{\Omega} h' d\mathbb{P} : h' \text{ is simple and } 0 \leq h' \leq X\right\}$$

$$= c\mathbb{E}[X]$$

(c) Assume X is arbitrary random variable.

(i) $c \geq 0$

$$\mathbb{E}[cX] = \mathbb{E}[(cX)^+] - \mathbb{E}[(cX)^-]$$

$$= \mathbb{E}[c(X)^+] - \mathbb{E}[c(X)^-]$$

$$= c\mathbb{E}[(X)^+] - c\mathbb{E}[(X)^-]$$

$$= c\mathbb{E}[X]$$

(ii) $c < 0$

By definition, we have

$$
\begin{aligned}
(cX)^+ &= cX\mathbb{I}\{cX > 0\} \\
&= cX\mathbb{I}\{x < 0\} \text{ (since c¡0)} \\
&= (-c)(-X)\mathbb{I}\{X < 0\} \\
&= (-c)(X)^-
\end{aligned}
$$

Along the similar line, we have

$$
\begin{aligned}
(cX)^- &= -cX\mathbb{I}\{cX < 0\} \\
&= -cX\mathbb{I}\{X > 0\} \\
&= -c(X)^+
\end{aligned}
$$

Now we can see that

$$
\begin{aligned}
\mathbb{E}[cX] &= \mathbb{E}[(cX)^+] - \mathbb{E}[(cX)^-] \\
&= \mathbb{E}[(-c)(X)^-] - \mathbb{E}[-c(X)^+] \\
&= -c\mathbb{E}[(X)^-] + c\mathbb{E}[(X)^+] \\
&= c\mathbb{E}[X]
\end{aligned}
$$

2.16

(a) Assume $X = \sum_{i=1}^n \alpha_i \mathbb{I}_{A_i}\{\omega\}, Y = \sum_{j=1}^m \beta_j \mathbb{I}_{B_j}\{\omega\}$ are simple functions.

$$
\begin{aligned}
\mathbb{E}[XY] &= \mathbb{E}[\sum_{i=1}^n \sum_{j=1}^m \alpha_i \beta_j \mathbb{I}_{A_i}\{\omega\}\mathbb{I}_{B_j}\{\omega\}] \\
&= \int_\Omega \sum_{i=1}^n \sum_{j=1}^m \alpha_i \beta_j \mathbb{I}_{A_i}\{\omega\}\mathbb{I}_{B_j}\{\omega\}d\mathbb{P}(\omega) \\
&= \sum_{i=1}^n \sum_{j=1}^m \alpha_i \beta_j \mathbb{P}(A_i \bigcap B_j) \\
&= \sum_{i=1}^n \sum_{j=1}^m \alpha_i \beta_j \mathbb{P}(A_i)\mathbb{P}(B_j) \text{ (by the definition of independence)} \\
&= \left(\sum_{i=1}^n \alpha_i \mathbb{P}(A_i)\right)\left(\sum_{j=1}^m \beta_j \mathbb{P}(B_i)\right) \\
&= \mathbb{E}[X]\mathbb{E}[Y]
\end{aligned}
$$

(b) Assume X, Y are non-negative random variables.

$$
\begin{aligned}
\mathbb{E}[XY] &= \sup\{\mathbb{E}[h] : h \text{ h is simple and } 0 \le h \le XY\} \\
&= \sup\{\mathbb{E}[h_1 h_2] : h_1, h_2 \text{ are simple and } 0 \le h_1 \le X, 0 \le h_2 \le Y\} \\
&= \sup\{\mathbb{E}[h_1]\mathbb{E}[h_2] : h_1, h_2 \text{ are simple and } 0 \le h_1 \le X, 0 \le h_2 \le Y\} \\
&= \sup\{\mathbb{E}[h_1] : h_1 \text{ is simple and } 0 \le h_1 \le X\} \cdot \sup\{\mathbb{E}[h_2] : h_2 \text{ is simple and } 0 \le h_2 \le Y\} \\
&= \mathbb{E}[X]\mathbb{E}[Y]
\end{aligned}
$$

(c) Assume X, Y are arbitrary random variables.

$$\begin{aligned}
\mathbb{E}[XY] &= \mathbb{E}[(X^+ - X^-)(Y^+ - Y^-)] \\
&= \mathbb{E}[X^+Y^+ - X^+Y^- - X^-Y^+ + X^-Y^-] \\
&= \mathbb{E}[X^+]\mathbb{E}[Y^+] - \mathbb{E}[X^+]\mathbb{E}[Y^-] - \mathbb{E}[X^-]\mathbb{E}[Y^+] + \mathbb{E}[X^-]\mathbb{E}[Y^-] \\
&= (\mathbb{E}[X^+] - \mathbb{E}[X^-])(\mathbb{E}[Y^+] - \mathbb{E}[Y^-]) \\
&= \mathbb{E}[X]\mathbb{E}[Y]
\end{aligned}$$

2.17 Before proving Ex.2.17, we need to make minor changes to the definition of conditional expectation and give a small lemma.

Definition 1. *Assume $(\Omega, \mathcal{F}, \mathbb{P})$ is a probability space. $\mathcal{G} \subset \mathcal{F}$ is a sub-σ-algebra of $\mathcal{F}$. $X : \Omega \to \mathbb{R}$ is a random variable. The conditional expectation of X given $\mathcal{G}$ is denoted by any random variable Y which satisfies the following 2 properties:*

- *Y is $\mathcal{G}$-measurable*

- *$\forall A \in \mathcal{G}$,*

$$\int_A Y d\mathbb{P} = \int_A X d\mathbb{P}$$

Formally, we denoted Y by notation $\mathbb{E}[X|\mathcal{G}]$.

Lemma 1. *If X is $\mathcal{G}$-measurable, then $\mathbb{E}[X|\mathcal{G}] = X$ holds a.s.*

Proof. Since X is $\mathcal{G}$-measurable, property1 holds. And property2 holds trivially. $\qquad\square$

We can now handily prove Ex.2.17. Since $\mathbb{E}[X|\mathcal{G}_1]$ is $\mathcal{G}_1$-measurable and $\mathcal{G}_1 \subset \mathcal{G}_2$, we can see that $\mathbb{E}[X|\mathcal{G}_1]$ is $\mathcal{G}_2$-measurable. By Lemma 1, $\mathbb{E}[\mathbb{E}[X|\mathcal{G}_1]|\mathcal{G}_2] = \mathbb{E}[X|\mathcal{G}_1]$ holds almost surely.

2.18 Suppose $X = Y$ with $\mathbb{V}[X] \neq 0$. Then, we have $\mathbb{E}[XY] = \mathbb{E}[X^2] = \mathbb{V}[X] + \mathbb{E}[X]^2 \neq \mathbb{E}[X]^2 = \mathbb{E}[X]\mathbb{E}[Y]$.

2.19 As the hint suggests, $X(\omega) = \int_{[0,\infty)} \mathbb{I}\{[0, X(\omega)]\}(x)dx$. Hence, we have

$$\begin{aligned}
\mathbb{E}[X(\omega)] &= \mathbb{E}\left[\int_{[0,\infty)} \mathbb{I}\{[0, X(\omega)]\}(x)dx\right] \\
&= \int_{[0,\infty)} \mathbb{E}[\mathbb{I}\{[0, X(\omega)]\}(x)]dx \\
&= \int_{[0,\infty)} P(X(\omega) > x)dx
\end{aligned} \tag{1}$$

where the second equality is given by Fubini–Tonell theorem.

2.20 We prove the following properties all by contradiction (for the sake of rigor).

(1) Let $G = \{\omega : \mathbb{E}[X \mid \mathcal{G}](\omega) < 0\}$. Then $G \in \mathcal{G}$ since $\mathbb{E}[X \mid \mathcal{G}]$ is $\mathcal{G}$-measurable by definition. Now suppose $\mathbb{P}(G) > 0$, then

$$\begin{aligned}
\int_G X d\mathbb{P} &= \int_G \mathbb{E}(X \mid \mathcal{G})d\mathbb{P} \\
&< 0
\end{aligned} \tag{2}$$

where the equality holds by the definition of conditional expectation. Now we can find it contradictory as $X \geq 0$. Therefore $\mathbb{P}(G) = 0$, and $\mathbb{E}[X \mid \mathcal{G}] \geq 0$ a.s.

(2) Let $G = \{\omega : \mathbb{E}[1 \mid \mathcal{G}](\omega) \neq 1\}$. Then $G \in \mathcal{G}$ since $\mathbb{E}[1 \mid \mathcal{G}]$ is $\mathcal{G}$-measurable by definition. Now suppose $\mathbb{P}(G) > 0$, then

$$\int_G 1 d\mathbb{P} = \int_G \mathbb{E}(1 \mid \mathcal{G}) d\mathbb{P} \tag{3}$$
$$\neq 1$$

where the equality holds by the definition of conditional expectation. Now we can find it contradictory as $\int_G 1 d\mathbb{P} = 1$. Therefore $\mathbb{P}(G) = 0$, and $\mathbb{E}[1 \mid \mathcal{G}] = 1$ a.s.

(3) Let $G = \{\omega : \mathbb{E}[X + Y \mid \mathcal{G}](\omega) \neq \mathbb{E}[X \mid \mathcal{G}](\omega) + \mathbb{E}[Y \mid \mathcal{G}](\omega)\}$. Then $G \in \mathcal{G}$ since $\mathbb{E}[X + Y \mid \mathcal{G}]$, $\mathbb{E}[X \mid \mathcal{G}]$, and $\mathbb{E}[Y \mid \mathcal{G}]$ are all $\mathcal{G}$-measurable by definition. Now suppose $\mathbb{P}(G) > 0$, then

$$\int_G (X + Y) d\mathbb{P} = \int_G \mathbb{E}(X + Y \mid \mathcal{G}) d\mathbb{P}$$
$$\neq \int_G [\mathbb{E}(X \mid \mathcal{G}) + \mathbb{E}(Y \mid \mathcal{G})] d\mathbb{P}$$
$$= \int_G \mathbb{E}(X \mid \mathcal{G}) d\mathbb{P} + \int_G \mathbb{E}(Y \mid \mathcal{G}) d\mathbb{P} \tag{4}$$
$$= \int_G X d\mathbb{P} + \int_G Y d\mathbb{P}$$

where the first equality and the last one hold by the definition of conditional expectation. It contradicts the linearity of expectation in that $\int_G (X + Y) d\mathbb{P} \neq \int_G X d\mathbb{P} + \int_G Y d\mathbb{P}$. Therefore $\mathbb{P}(G) = 0$, and $\mathbb{E}(X + Y \mid \mathcal{G}) = \mathbb{E}(X \mid \mathcal{G}) + \mathbb{E}(Y \mid \mathcal{G})$ a.s.

(4) Let $G = \{\omega : \mathbb{E}[XY \mid \mathcal{G}](\omega) \neq Y(\omega)\mathbb{E}[X \mid \mathcal{G}](\omega)\}$. Then $G \in \mathcal{G}$ since $\mathbb{E}[XY \mid \mathcal{G}]$, Y, and $\mathbb{E}[X \mid \mathcal{G}]$ are all $\mathcal{G}$-measurable by definition. Now suppose $\mathbb{P}(G) > 0$, then

$$\int_G XY d\mathbb{P} = \int_G \mathbb{E}(XY \mid \mathcal{G}) d\mathbb{P}$$
$$\neq \int_G Y \mathbb{E}[X \mid \mathcal{G}] d\mathbb{P} \tag{5}$$

Now our target is to show it is contradictory. This is a bit tricky, so we start from the simplest case and then generalize it step by step.

   a. Suppose $Y = \mathbb{I}_A$ for some $A \in \mathcal{G}$. Then

$$\int_G XY d\mathbb{P} = \int_{G \cap A} X d\mathbb{P} \tag{6}$$

and

$$\int_G Y \mathbb{E}[X \mid \mathcal{G}] d\mathbb{P} = \int_{G \cap A} \mathbb{E}[X \mid \mathcal{G}] d\mathbb{P}$$
$$= \int_{G \cap A} X d\mathbb{P} \tag{7}$$

   Hence it holds that $\int_G XY d\mathbb{P} = \int_G Y \mathbb{E}[X \mid \mathcal{G}] d\mathbb{P}$.

   b. Suppose Y is non-negative and let $\{Y_n\}$ be sequence of non-negative simple functions converging to Y from below. Then by linearity, it holds that

$$\int_G X^+ Y_n d\mathbb{P} = \int_G Y_n \mathbb{E}[X^+ \mid \mathcal{G}] d\mathbb{P} \tag{8}$$

and

$$\int_G X^- Y_n d\mathbb{P} = \int_G Y_n \mathbb{E}[X^- \mid \mathcal{G}] d\mathbb{P} \qquad (9)$$

Applying the monotone convergence we end up with

$$\int_G X^+ Y d\mathbb{P} = \int_G Y \mathbb{E}[X^+ \mid \mathcal{G}] d\mathbb{P} \qquad (10)$$

and

$$\int_G X^- Y d\mathbb{P} = \int_G Y \mathbb{E}[X^- \mid \mathcal{G}] d\mathbb{P} \qquad (11)$$

Hence,

$$\begin{aligned}
\int_G XY d\mathbb{P} &= \int_G X^+ Y d\mathbb{P} - \int_G X^- Y d\mathbb{P} \\
&= \int_G Y(\mathbb{E}[X^+ \mid \mathcal{G}] - \mathbb{E}[X^- \mid \mathcal{G}]) d\mathbb{P} \\
&= \int_G Y \mathbb{E}[X^+ - X^- \mid \mathcal{G}] d\mathbb{P} \\
&= \int_G Y \mathbb{E}[X \mid \mathcal{G}] d\mathbb{P}
\end{aligned} \qquad (12)$$

    c. Finally, for arbitrary Y, we can separate $Y = Y^+ - Y^-$ and the contradiction still holds by linearity of expectation.

Therefore, in any case Eq.5 is contradictory. So $\mathbb{P}(G) = 0$, and $\mathbb{E}[XY \mid \mathcal{G}] = Y \mathbb{E}[X \mid \mathcal{G}]$ a.s.

(5) Let $G = \{\omega : \mathbb{E}[X \mid \mathcal{G}_1](\omega) \neq \mathbb{E}[\mathbb{E}[X \mid \mathcal{G}_2] \mid \mathcal{G}_1](\omega)\}$. Then $G \in \mathcal{G}_1$ since both $\mathbb{E}[X \mid \mathcal{G}_1]$ and $\mathbb{E}[\mathbb{E}[X \mid \mathcal{G}_2] \mid \mathcal{G}_1]$ are $\mathcal{G}_1$-measurable by definition. Now suppose $\mathbb{P}(G) > 0$, then

$$\begin{aligned}
\int_G X d\mathbb{P} &= \int_G \mathbb{E}(X \mid \mathcal{G}_1) d\mathbb{P} \\
&\neq \int_G \mathbb{E}[\mathbb{E}[X \mid \mathcal{G}_2] \mid \mathcal{G}_1] d\mathbb{P} \\
&= \int_G \mathbb{E}(X \mid \mathcal{G}_2) d\mathbb{P} \\
&= \int_G X d\mathbb{P}
\end{aligned} \qquad (13)$$

The last equality stands since $G \in \mathcal{G}_1$ and $\mathcal{G}_1 \subset \mathcal{G}_2$, which suggests $G \in \mathcal{G}_2$. Now we can find it contradictory. Therefore $\mathbb{P}(G) = 0$, and $\mathbb{E}[X \mid \mathcal{G}_1] = \mathbb{E}[\mathbb{E}[X \mid \mathcal{G}_2] \mid \mathcal{G}_1]$ a.s.

$$\begin{aligned}
\int_G X d\mathbb{P} &= \int_G \mathbb{E}(X \mid \mathcal{G}_1) d\mathbb{P} \\
&\neq \int_G \mathbb{E}[\mathbb{E}[X \mid \mathcal{G}_2] \mid \mathcal{G}_1] d\mathbb{P} \\
&= \int_G \mathbb{E}(X \mid \mathcal{G}_2) d\mathbb{P} \\
&= \int_G X d\mathbb{P}
\end{aligned} \qquad (14)$$

(6) Let $G = \{\omega : \mathbb{E}\left[X \mid \sigma\left(\mathcal{G}_1 \cup \mathcal{G}_2\right)\right](\omega) \neq \mathbb{E}\left[X \mid \mathcal{G}_1\right](\omega)\}$. Notice that $\mathbb{E}\left[X \mid \mathcal{G}_1\right]$ is not only $\mathcal{G}_1$-measurable but also $\sigma\left(\mathcal{G}_1 \cup \mathcal{G}_2\right)$-measurable. Thus we have $G \in \sigma\left(\mathcal{G}_1 \cup \mathcal{G}_2\right)$. Now suppose $\mathbb{P}(G) > 0$, then

$$
\begin{aligned}
\int_G X d\mathbb{P} &= \int_G \mathbb{E}\left[X \mid \sigma\left(\mathcal{G}_1 \cup \mathcal{G}_2\right)\right] d\mathbb{P} \\
&\neq \int_G \mathbb{E}\left[X \mid \mathcal{G}_1\right] d\mathbb{P}
\end{aligned}
\tag{15}
$$

To show it is contradictory, we want to prove that $\forall G \in \sigma\left(\mathcal{G}_1 \cup \mathcal{G}_2\right)$,

$$
\int_G X d\mathbb{P} = \int_G \mathbb{E}\left[X \mid \mathcal{G}_1\right] d\mathbb{P}
\tag{16}
$$

The following techniques are closely related to 'Dynkin system', which is beyond my knowledge. The main idea is that if we assume X is non-negative, which can be generalized by linearity, it is enough to establish Eq.16 for some π-system that generates $\sigma\left(\mathcal{G}_1 \cup \mathcal{G}_2\right)$.

One possibility is $\mathcal{H} = \{G_1 \cap G_2 : G_1 \in \mathcal{G}_1, G_2 \in \mathcal{G}_2\}$. Then, $\forall G_1 \cap G_2 \in \mathcal{H}$,

$$
\begin{aligned}
\int_{G_1 \cap G_2} \mathbb{E}\left[X \mid \mathcal{G}_1\right] d\mathbb{P} &= \int_\Omega \mathbb{E}\left[X \mid \mathcal{G}_1\right] \mathbb{I}_{G_1} \mathbb{I}_{G_2} d\mathbb{P} \\
&= \int_\Omega \mathbb{E}\left[X \mid \mathcal{G}_1\right] \mathbb{I}_{G_1} d\mathbb{P} \int_\Omega \mathbb{I}_{G_2} d\mathbb{P} \\
&= \int_\Omega X \mathbb{I}_{G_1} d\mathbb{P} \int_\Omega \mathbb{I}_{G_2} d\mathbb{P} \\
&= \int_\Omega X \mathbb{I}_{G_1} \mathbb{I}_{G_2} d\mathbb{P} \\
&= \int_{G_1 \cap G_2} X d\mathbb{P}
\end{aligned}
\tag{17}
$$

where the second and fourth equality holds due to independence between $\sigma(X)$ and $\mathcal{G}_2$ given $\mathcal{G}_1$.

Hence, we find it contradictory. So $\mathbb{P}(G) = 0$ and $\mathbb{E}\left[X \mid \sigma\left(\mathcal{G}_1 \cup \mathcal{G}_2\right)\right] = \mathbb{E}\left[X \mid \mathcal{G}_1\right]$ a.s.

(7) Let $G = \{\omega : \mathbb{E}[X \mid \mathcal{G}](\omega) \neq \mathbb{E}[X]\}$. Then $G \in \mathcal{G}$ since $\mathbb{E}[X \mid \mathcal{G}]$ is $\mathcal{G}$-measurable by definition. And because $\mathcal{G}$ is trivial, $G = \emptyset$ or $G = \Omega$.

    a. If $G = \emptyset$, $P(G) = 0$ for sure.

    b. If $G = \Omega$, which suggests $\mathbb{E}[X \mid \mathcal{G}] \neq \mathbb{E}[X]$ always holds, we have

$$
\begin{aligned}
\int_G X d\mathbb{P} &= \int_G \mathbb{E}[X \mid \mathcal{G}] d\mathbb{P} \\
&\neq \int_G \mathbb{E}[X] d\mathbb{P} \\
&= \int_\Omega \mathbb{E}[X] d\mathbb{P} \\
&= \mathbb{E}[X]
\end{aligned}
\tag{18}
$$

    which is obviously contradictory since $\int_G X d\mathbb{P} = \int_\Omega X d\mathbb{P} = \mathbb{E}[X]$.

Therefore, $P(G) = 0$ and hence $\mathbb{E}[X \mid \mathcal{G}] = \mathbb{E}[X]$ a.s.

Chapter 3 Stochastic Processes and Markov Chains

3.1

(a) On$([0,1], \mathcal{B}, \lambda)$,for any $x \in [0,1]$

Let $F_1(x), F_2(x), F_3(x)$,...be the binary expansion of x.

$$F_t(x)= \begin{cases} 1, A \\ 0, \overline{A} \end{cases} \quad (\overline{A} \text{ is the opposite case of } A)$$

$F_t(x)$ is Bernoulli random variable.

(b) $\begin{cases} F_1 = 0 : 0 \leq x < 0.5 \\ F_1 = 1 : 0.5 \leq x < 1 \end{cases}$

$\begin{cases} F_2 = 0 : 0 \leq x' < 0.5 \\ F_2 = 1 : 0.5 \leq x' < 1 \end{cases}$ x'=2x-1

...

$\begin{cases} F_t = 0 : 0 \leq x^t < 0.5 \Rightarrow \mathbb{P}(F_t = 0) = \frac{1}{2} \\ F_t = 1 : 0.5 \leq x^t < 1 \Rightarrow \mathbb{P}(F_t = 1) = \frac{1}{2} \end{cases}$

(c) It is obviously that $(F_t)_{t=1}^{\infty}$ are independent. It satisfies independent equation: $\mathbb{P}(A \cap B) = \mathbb{P}(A)\mathbb{P}(B)$.

(d) $(X_{m,t})_{t=1}^{\infty}$ is a subsequence of $(F_t)_{t=1}^{\infty}$ and $(X_{m,t})_{t=1}^{\infty}$ are mutually exclusive.

(e) Such as(d).

(f) Such as(d).

3.2

(a) $S_t = \sum_{s=1}^{t} X_s 2^{s-1}$

X_t is a F-adapted martingale.

(1)$\mathbb{E}[X_t|\mathcal{F}_{t-1}] = X_{t-1}$.

(2)X_t is integrable $\Rightarrow S_t$ is integrable.

$$\begin{aligned} \mathbb{E}[S_t|\mathcal{F}_{t-1}] &= \mathbb{E}[S_{t-1} + X_t 2^{t-1}|\mathcal{F}_{t-1}] \\ &= S_{t-1} + \mathbb{E}[X_t 2^{t-1}|\mathcal{F}_{t-1}] \\ &= S_{t-1} + 2^t \times (1) \times \frac{1}{2} + 2^t \times (-1) \times \frac{1}{2} \\ &= S_{t-1} \end{aligned}$$

$\Rightarrow (S_t)_{t=1}^{\infty}$

(b) t=1 , if $S_t \neq 1 \Rightarrow X_1 = -1, S_t$=-1

t=2 , if $S_t \neq 1 \Rightarrow X_1 = -1, S_t$=-3

t=3 , if $S_t \neq 1 \Rightarrow X_1 = -1, S_t$=-7

...

If avoid S_t=1 , the X_s sequence must be -1.

$\tau = \min\{t : S_t = 1\} = \min\{t : X_T = 1\}$

$\Rightarrow \mathbb{P}(\tau < n) = 1 - \mathbb{P}(\tau \geq n) = 1 - \frac{1}{2^n}$

$\Rightarrow \mathbb{P}(\tau < \infty) = 1 - \lim_{n \to \infty} \mathbb{P}(\tau \geq n) = 1 - \frac{1}{2^n} = 1 - \lim_{n \to \infty} \frac{1}{2^n}$

(c) If t=τ , then S_t=1 , so $S_\tau \equiv 1$

$\Rightarrow \mathbb{E}[S_\tau] = 1$

(d) Doob's(a)can be proved by 3.2(b)

$\tau = 1 \Rightarrow X_1 = 1 \Rightarrow \mathbb{P}(\tau = 1) = \frac{1}{2}$

$\tau = 2 \Rightarrow X_1 = -1 X_2 = 1 \Rightarrow \mathbb{P}(\tau = 1) = \frac{1}{4}$

$\tau = 3 \Rightarrow X_1 = -1 X_2 = -1 X_3 = 1 \Rightarrow \mathbb{P}(\tau = 1) = \frac{1}{8}$

...

$\mathbb{P}(\tau < \infty) = \mathbb{P}(\tau = 1) + \mathbb{P}(\tau = 2) + \mathbb{P}(\tau = 3) + ... = \frac{1}{2} + \frac{1}{4} + \frac{1}{8} + ... = 1$

because of $n \neq \infty, \mathbb{P}(\tau = n) = \frac{1}{n^2} \neq 0$.

Doob's(b)(c)can also be proved by 3.2(b)

t=1 , if $S_t \neq 1 \Rightarrow X_1 = -1, S_t = -1$

t=2 , if $S_t \neq 1 \Rightarrow X_1 = -1, S_t = -3$

t=3 , if $S_t \neq 1 \Rightarrow X_1 = -1, S_t = -7$

...

It can be concluded that —S_t— and —S_{t-1}— can not be bounded, so $\mathbb{E}[|X_{t+1}|\mathcal{F}]$ and $|4X_{t \wedge \tau}|$ can not be bounded neither.

3.4 If $X_t \geq 0$ is dropped, $\mathbb{E}[X_\tau | \{\tau \leq n\}] \geq \mathbb{E}[\varepsilon | \{\tau \leq n\}]$ not always true.

Chapter 4 Stochastic Bandits

4.1 By definition

$$R_n(\pi, v) = n\mu^*(v) - \mathbb{E}[\sum_{t=1}^{n} X_t]$$

$$= \sum_{t=1}^{n} \mu^*(v) - \sum_{t=1}^{n} \mathbb{E}[X_t]$$

$$= \sum_{t=1}^{n} [\mu^* - \mu_{A_t}]$$

(a) $\mu^* = \max \mu_a \geq \mu_{A_t} \Rightarrow R_n(\pi, v) = \sum_{t=1}^{n} [\mu^* - \mu_{A_t}] \geq 0$.

(b) If π choose $A_t \in \arg\max_a \mu_a$ for all $t \in [n] \Rightarrow \sum_{t=1}^{n} [\mu^* - \mu_{A_t}] = 0$.

(c) If $R_n(\pi, v) = 0$ for some policy π ,then $A_t \in \arg\max_a \mu_a \Rightarrow \mathbb{P}(\mu_{A_t} = \mu^*) = 1$.

4.3 Denote $h_t = a_1, x_1, \ldots, a_t, x_t$.

(a) According to the definition of conditional probability and marginal distribution, we have

$$p_{v\pi}(a_n \mid h_{n-1}) = \frac{p_{v\pi}(h_{n-1}, a_n)}{p_{v\pi}(h_{n-1})}$$

$$= \frac{\int_{\mathbb{R}} p_{v\pi}(h_n) dx_n}{p_{v\pi}(h_{n-1})}$$

$$= \frac{\int_{\mathbb{R}} \prod_{t=1}^{n} \pi(a_t \mid h_{t-1}) p_{a_t}(x_t) dx_n}{p_{v\pi}(h_{n-1})}$$

$$= \frac{\prod_{t=1}^{n-1} \pi(a_t \mid h_{t-1}) p_{a_t}(x_t)}{p_{v\pi}(h_{n-1})} \int_{\mathbb{R}} \pi(a_n \mid h_{n-1}) p_{a_n}(x_n) dx_n$$

$$= \pi(a_n \mid h_{n-1}) \int_{\mathbb{R}} p_{a_n}(x_n) dx_n$$

$$= \pi(a_n \mid h_{n-1})$$

(b) According to the definition of conditional probability and marginal distribution, we have

$$
\begin{aligned}
p_{v\pi}(x_n \mid h_{n-1}, a_n) &= \frac{p_{v\pi}(h_n)}{p_{v\pi}(h_{n-1}, a_n)} \\
&= \frac{p_{v\pi}(h_n)}{\int_{\mathbb{R}} p_{v\pi}(h_n) dx_n} \\
&= \frac{p_{v\pi}(h_n)}{\int_{\mathbb{R}} \left[\prod_{t=1}^{n} \pi\left(a_t \mid h_{t-1}\right) p_{a_t}\left(x_t\right)\right] dx_n} \\
&= \frac{p_{v\pi}(h_n)}{\prod_{t=1}^{n-1} \pi\left(a_t \mid h_{t-1}\right) p_{a_t}\left(x_t\right)} \frac{1}{\int_{\mathbb{R}} \pi\left(a_n \mid h_{n-1}\right) p_{a_n}\left(x_n\right) dx_n} \\
&= \pi\left(a_n \mid h_{n-1}\right) p_{a_n}\left(x_n\right) \frac{1}{\pi\left(a_n \mid h_{n-1}\right)} \\
&= p_{a_n}\left(x_n\right)
\end{aligned}
$$

4.4 Denote $h_t = a_1, x_1, \ldots, a_t, x_t$. The policy that mixes the policies can be defined as

$$
\pi_t^{\circ}\left(a_t \mid h_{t-1}\right) = \frac{\sum_{\pi \in \Pi} p(\pi) \prod_{s=1}^{t} \pi_s\left(a_s \mid h_{s-1}\right)}{\sum_{\pi \in \Pi} p(\pi) \prod_{s=1}^{t-1} \pi_s\left(a_s \mid h_{s-1}\right)}
$$

.

By the definition of the canonical probability space and the product of probability kernels,

$$
\begin{aligned}
\mathbb{P}_{v\pi\circ}(B) &= \sum_{a_1=1}^{k} \int_{\mathbb{R}} \cdots \sum_{a_n=1}^{k} \int_{\mathbb{R}} \mathbb{I}_B\left(h_n\right) v_{a_n}\left(dx_n\right) \pi_n^{\circ}\left(a_n \mid h_{n-1}\right) \cdots v_{a_1}\left(dx_1\right) \pi_1^{\circ}\left(a_1\right) \\
&= \sum_{\pi \in \Pi} p(\pi) \sum_{a_1=1}^{k} \int_{\mathbb{R}} \cdots \sum_{a_n=1}^{k} \int_{\mathbb{R}} \mathbb{I}_B\left(h_n\right) v_{a_n}\left(dx_n\right) \pi_n\left(a_n \mid h_{n-1}\right) \cdots v_{a_1}\left(dx_1\right) \pi_1\left(a_1\right) \\
&= \sum_{\pi \in \Pi} p(\pi) \mathbb{P}_{v\pi}(B),
\end{aligned}
$$

where the second equality follows by substituting the definition of π_n° and induction.

Chapter 5 Concentration of Measure

5.1

$$V(\hat{\mu}) = E((\hat{\mu}-\mu)^2) = E((\frac{1}{n}\sum_{t=1}^{n}X_t - \mu)^2) = E(\frac{1}{n^2}\sum_{t=1}^{n}(X_t-\mu)^2) = \frac{1}{n^2}\sum_{t=1}^{n}E(X_t-\mu)^2 = \frac{1}{n^2}\sum_{t=1}^{n}\sigma^2 = \frac{\sigma^2}{n}$$

(19)

5.4

(a)

$$P(|X| \geq \varepsilon) = P(X \geq \varepsilon)I\{X \geq 0\} + P(X \leq -\varepsilon)I\{X < 0\} = \int_{\varepsilon}^{\infty}\frac{x}{2}exp\{\frac{-x^2}{2}\}dx + \int_{-\infty}^{\varepsilon}\frac{-x}{2}exp\{\frac{-x^2}{2}\}dx$$

(20)

Calculate the above formula and get the result ,
$P(|X| \geq \varepsilon) = \frac{1}{2}exp\{\frac{-\varepsilon^2}{2}\} + \frac{1}{2}exp\{\frac{-\varepsilon^2}{2}\}$
$= exp\{\frac{-\varepsilon^2}{2}\}$
(b)
Let's start with a lemma:
If X is $\sigma-$subgaussian,then $P(|X| > t) \leq exp\{-b\varepsilon^2\}$, where $b = exp\{-\sigma^2\}$
The proof of lemma is omitted.
It can be seen from the first question , $P(|X| \geq \varepsilon) = exp\{\frac{-\varepsilon^2}{2}\}$
The comparison of the two formulas shows that , $0 < b \leq 1/2$. That is, $\sigma \geq \sqrt{ln2}$
By topic condition , $\sigma = \sqrt{2-\varepsilon}$
Hence , $\varepsilon \leq 2 - ln2$, this is in contradiction with the arbitrariness of ε

5.7

(a)If X is $\sigma-$subgaussian , then $E(X) = 0$,$E(X^2) \leq \sigma^2$
proof:

$$E(e^{\lambda X}) = \sum_{n=0}^{\infty}\frac{\lambda^n E(X^n)}{n!} = 1 + \lambda E(X) + \frac{\lambda^2 E(X^2)}{2} + O(\lambda^2)$$

(21)

By definition ,

$$E(e^{\lambda X}) \leq e^{\frac{\lambda^2\sigma^2}{2}} = 1 + \frac{\lambda^2\sigma^2}{2} + O(\lambda^2)$$

(22)

By comparing the above two formulas and discussing the case that a approaches to 0 from above and below 0, we get the conclusion that ,
$E(X) = 0$,$E(X^2) \leq \sigma^2$
(b)

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If X is $\sigma-$subgaussian , then $E(X) = 0, E(X^2) \le \sigma^2$.

$E(e^{c\lambda x}) = 1 + \lambda E(cx) + \frac{\lambda^2 E(c^2 x^2)}{2} + O(\lambda^2)$

$\le 1 + c\lambda E(x) + \frac{\lambda^2 c^2}{2} E(x^2) + O(\lambda^2)$

$\le 1 + \frac{\lambda^2 c^2 \sigma^2}{2} + O(\lambda^2)$

$\le e^{\frac{\lambda^2 c^2 \sigma^2}{2}}$

Hence , cX is $|c|\sigma-$subgaussian .

(c)

If X_1 is σ_1-subgaussian , X_2 is σ_2-subgaussian

then $E(X_1) = 0, E(X_1^2) \le \sigma_1^2$, $E(X_2) = 0, E(X_2^2) \le \sigma_2^2$

$E(e^{\lambda(x_1+x_2)}) = 1 + \lambda E(x_1 + x_2) + \frac{\lambda^2 E((x_1+x_2)^2)}{2} + O(\lambda^2)$

$= 1 + \frac{\lambda^2}{2} Var(x_1 + x_2) + O(\lambda^2)$

$= 1 + \frac{\lambda^2}{2}(var(x_1) + var(x_2) + 2cov(x_1, x_2)) + O(\lambda^2)$

Because x_1, x_2 are independent ,

$= 1 + \frac{\lambda^2}{2}(E(x_1^2) + E(x_2^2))(\lambda^2)$

$\le 1 + \frac{\lambda^2}{2}(\sigma_1^2 + \sigma_2^2) + O(\lambda^2)$

$\le e^{\frac{\lambda^2(\sigma_1^2+\sigma_2^2)}{2}}$

Hence , $X_1 + X_2$ is $\sqrt{\sigma_1^2 + \sigma_2^2}-$subgaussian .

5.11

(a)

$$E(e^{\lambda X}) = 1 + \lambda E(X) + \frac{\lambda^2 E(X^2)}{2} + O(\lambda^2) = 1 + \frac{\lambda^2 E(X^2)}{2} + O(\lambda^2) \tag{23}$$

If the conclusion is true, then the above formula satisfies

$\le 1 + \frac{\lambda^2}{2}(\frac{(b-a)^2}{4}) + O(\lambda^2)$

So just prove:

$E(x^2) \le (\frac{b-a}{2})^2$

$E(x^2) = var(x) = E(x - \bar{x})^2$

However, $(x - \bar{x})^2 \le (\frac{b-a}{2})^2$. The conclusion is proved.

(b)

The proof of Hoeffding's Inequality:

Let $X_i = Z_i - E(Z_i)$, $\bar{X} = \frac{1}{m}\sum_{i=1}^{m} X_i$

By Markov inequality , for all $\lambda > 0$, $\varepsilon > 0$,

$P(\bar{X} \ge \varepsilon) = P(e^{\lambda \bar{X}} \ge e^{\lambda \varepsilon}) \le \frac{E(e^{\lambda \bar{X}})}{e^{\lambda \varepsilon}}$

$Z_1, \cdots, Z_m$ iid.r.v.

So, $E(e^{\lambda \bar{X}}) = \prod_{i=1}^{m} E(e^{\frac{\lambda X_i}{m}})$

By Hoeffding's lamma,

$E(e^{\frac{\lambda X_i}{m}}) \le e^{\frac{\lambda^2 (b-a)^2}{8m^2}}$

So , $P(\bar{X} \ge \varepsilon) \le e^{-\lambda \varepsilon} \prod_{i=1}^{m} E(e^{\frac{\lambda X_i}{m}})$

$\le e^{-\lambda \varepsilon} e^{\frac{\lambda^2 (b-a)^2}{8m}}$

$\le e^{-\lambda \varepsilon + \frac{\lambda^2 (b-a)^2}{8m}}$

Let $\lambda = \frac{4m\varepsilon}{(b-a)^2}$, then $P(\bar{X} \ge \varepsilon) \le e^{\frac{-2m\varepsilon^2}{(b-a)^2}}$

Similarly, we can prove the other side of the inequality.

5.16 By assumption $Pr(X_t \le x) \le x$, which means that for $\lambda < 1$,

$$\mathbb{E}\left[exp(\lambda log(\frac{1}{x_t}))\right] = \int_0^\infty P(exp(\lambda log(\frac{1}{x_t})) \ge x)dx = 1 + \int_1^\infty P(X_t \le x^{-\frac{1}{\lambda}})dx \tag{24}$$

Applying the Cramer-Chernoff method,

$$P\left(\sum_{t=1}^{n} log(\frac{1}{X_t}) \ge \epsilon\right) = P\left(exp(\lambda \sum_{t=1}^{n} log(\frac{1}{X_t})) \ge exp(\lambda \epsilon)\right) \le \left(\frac{1}{1-\lambda}\right)^n exp(-\lambda \epsilon)$$

choosing $\lambda = \frac{\epsilon - n}{\epsilon}$ completes the claim.

5.18(a) Let $\lambda > 0$. Then,

$$exp(\lambda \mathbb{E}[Z]) \leq \mathbb{E}[exp(\lambda Z)] \leq \sum_{t=1}^{n} \mathbb{E}[exp(\lambda X_t)] \leq n exp(\frac{\lambda^2 \sigma^2}{2})$$

Rearranging shows that,

$$\mathbb{E}(Z) \leq \frac{log(n)}{\lambda} + \frac{\lambda \sigma^2}{2}$$

Choosing $\lambda = \frac{1}{\sigma}\sqrt{2 log(n)}$ shows that $\mathbb{E}(Z) \leq \sqrt{2\sigma^2 log(n)}$

Chapter 11 The Exp3 Algorithm

11.2 Let π be a deterministic policy, and we define $x_{ti} = 0$ if $A_t = i$ otherwise $x_{ti} = 1$. The deterministic policy collects zero rewards all time,

$$\max_{i \in [k]} \sum_{t=1}^{n} x_{ti} \geq \frac{1}{k} \sum_{t=1}^{n} \sum_{i=1}^{k} x_{ti} = \frac{n(k-1)}{k}$$

11.5 Let P be a probability vector with nonzero components and let $A \sim P$. Suppose $\hat{X}$ is a function such that for all $x \in \mathbb{R}^k$,

$$\mathbb{E}\left[\hat{X}(A, x_A)\right] = \sum_{i=1}^{k} P_i \hat{X}(i, x_i) = x_1$$

Show that there exists an $a \in \mathbb{R}^k$ such that $< a, P >= 0$ and for all i and z in their respective domains, $\hat{X}(i, z) = a_i + \frac{\mathbb{I}\{i=1\}z}{P_1}$

Proof. Let x, x' be arbitrary but agree on the first component $x_1 = x'_1$. Let $f(x) = \sum_{i=1}^{k} P_i \hat{X}(i, x_i)$ Note that,

$$0 = f(x) - f(x') = \sum_{i=j}^{k} P_j \hat{X}(j, x_j)$$

for all $j > 1$. Since x, x' are arbitrary, $\hat{X}(j,) = const$. Let a_j equal to $\hat{X}(j,)$.
    Further, let $a_1 = \hat{X}(1, 0)$ and then given any $x_1 \in \mathbb{R}$, $\hat{X}(1, x_1) = a_1 + x_1/P_1$.
    Finally, let x be such that $x_1 = 0$. Then $0 = f(x) = \sum_i P_i a_i$. $\qquad\square$

11.7 First, note that if $G = -\log(-\log(U))$ then $\mathbb{P}(G \leq g) = e^{-\exp(-g)}$.

$$\mathbb{P}\left(\log a_i + G_i \geq \max_{j \in [k]} \log a_j + G_j\right) = \mathbb{E}\left[\prod_{j \neq i} \mathbb{P}(\log a_j + G_j \leq \log a_i + G_i \mid G_i)\right]$$

$$= \mathbb{E}\left[\prod_{j \neq i} \exp\left(-\frac{a_j}{a_i} \exp(-G_i)\right)\right]$$

$$= \mathbb{E}\left[U_i^{\sum_{j \neq i} \frac{a_j}{a_i}}\right]$$

$$= \frac{1}{1 + \sum_{j \neq i} \frac{a_j}{a_i}}$$

$$= \frac{a_i}{\sum_{j=1}^{k} a_j}$$

11.8 Let $Z_t i$ be a standard Gambel. The follow-theperturbed-leader algorithm chooses

$$A_t = \operatorname{argmax}_{i \in [k]}\left(Z_{ti} - \eta \sum_{s=1}^{t-1} \hat{Y}_{si}\right)$$

is the same as EXP3. Given (11.7)

$$\mathbb{P}\left(\log\left(a_i\right) + G_i = \max_{j\in[k]}\left(\log\left(a_j\right) + G_j\right)\right) = \frac{a_i}{\sum_{j=1}^{k} a_j}$$

Just simply take a_i as $-\eta \sum_{s=1}^{t-1} \hat{Y}_{si}$, then the form is identical.

Chapter 18

18.1

(a) By Jensen's inequality,

$$\sum_{c \in \mathcal{C}} \sqrt{\sum_{t=1}^{n} \mathcal{I}\{c_t = c\}} = \|C\| \sum_{c \in \mathcal{C}} \frac{1}{\|C\|} \sqrt{\sum_{t=1}^{n} \mathcal{I}\{c_t = c\}}$$

$$\leq \|C\| \sqrt{\sum_{c \in \mathcal{C}} \frac{1}{\|C\|} \sum_{t=1}^{n} \mathcal{I}\{c_t = c\}}$$

$$= \sqrt{\|C\| n}$$

(b) When each context occurs $\frac{n}{\|C\|}$ times we have

$$\sum_{c \in \mathcal{C}} \sqrt{\sum_{t=1}^{n} \mathcal{I}\{c_t = c\}} = \sqrt{n \|C\|}$$