

# **MAEG4070 Engineering Optimization**

## **Lecture 13 Robust Optimization**

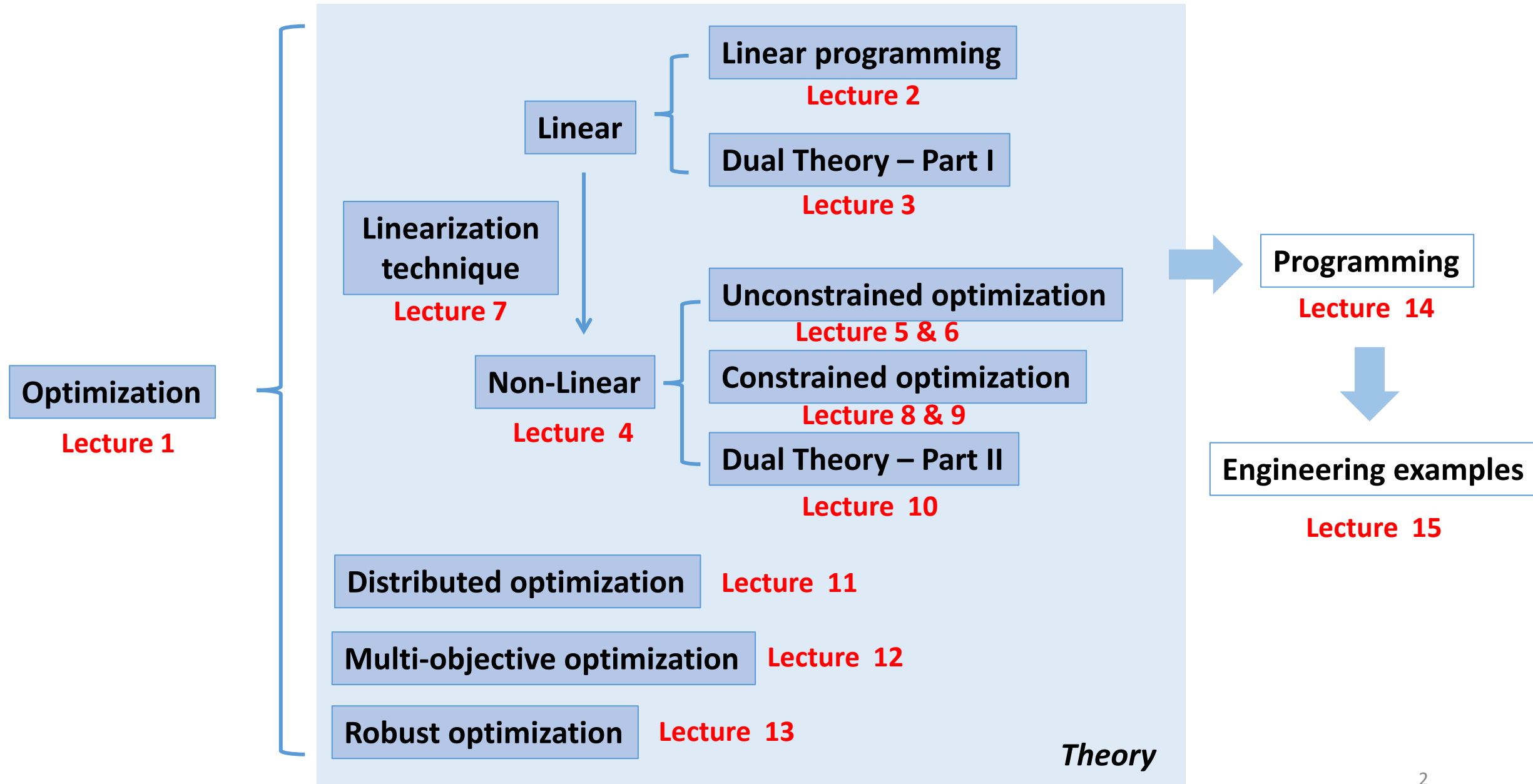
Yue Chen

MAE, CUHK

email: [yuechen@mae.cuhk.edu.hk](mailto:yuechen@mae.cuhk.edu.hk)

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# Content of this course (tentative)



# ***Motivation— Why optimization under uncertainty?***

Deterministic optimization models assume known parameters

Precise data is unavailable in most practical cases:

- Numerical error (data precision)
- Measurement error (cost coefficients)
- Forecast error (wind/solar power prediction)
- Changing environment (the attitudes and ability of the decision maker)

How much will the solution be affected by uncertainty

- In 13 of 90 benchmark LPs, 0.01% perturbations of uncertain data result in severe constraint violations
- 0.1% coefficient perturbation makes 50% optimal solutions infeasible

**Reference:** Arkadi N. Lectures on Robust Convex Optimization. Available at:

<https://www.ims.nus.edu.sg/oldwww/Programs/012opti/files/arkadi1p.pdf>

# *Approaches to handle uncertainty*

**Q:** How to handle uncertainty in an optimal way?

- Stochastic optimization
- Robust optimization

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## Methods

- Generate scenarios to represent possible realizations of uncertain data
- Assign a probability to each scenario

## Advantages

- Various models(LP, MILP, SDP...)
- Less conservative in the sense of statistics

## Challenges

- Scenario generation and reduction (proper scenarios and their probabilities)
- Computationally challenging

# Stochastic optimization

## Expectation

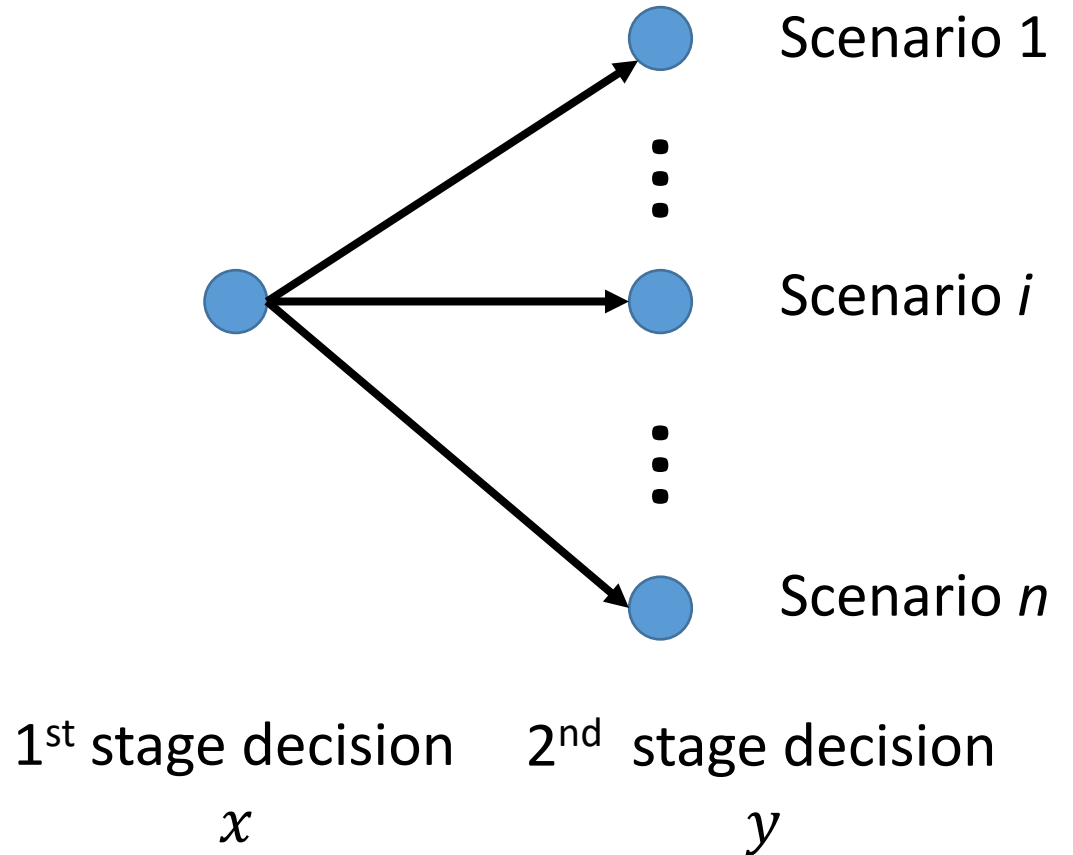
$$\begin{aligned} \min_{x,y} \quad & \mathbb{E}_w f(x, y, w) \\ \text{s.t.} \quad & h(x, y, w) = 0 \\ & g(x, y, w) \leq 0 \end{aligned}$$

$x$  - Here-and-now variables

$w$  - stochastic vector

$y$  - Wait-and-see variables (optional)

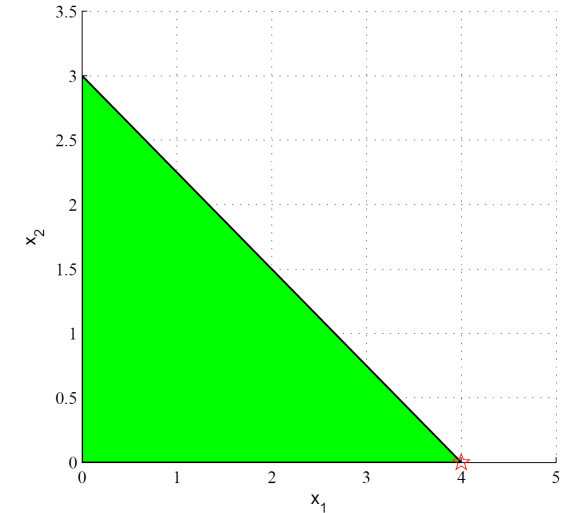
## Decision tree



## An example on uncertain LP

Consider this optimization problem:

$$\begin{aligned} \max_{x_1, x_2} \quad & z = x_1 + x_2 \\ \text{s.t.} \quad & ax_1 + bx_2 \leq 12 \\ & x_1 \geq 0, x_2 \geq 0 \end{aligned}$$



If  $a = 3, b = 4$  are deterministic, then

$$x^* = (4, 0), z^* = 4$$

If parameters  $a, b$  are uncertain may take the values of

$$(a, b) = (2, 6), (3, 5), (5, 3), (6, 2)$$

Each scenario has a probability of 0.25.

Try to formulate a stochastic optimization for this problem?

# *Approaches to handle uncertainty*

**Q:** How to handle uncertainty in an optimal way?

- Stochastic optimization
- Robust optimization

## Methods

- Use a pre-specified set to model uncertain data
- Optimize the outcome in the worst case

## Advantages

- guarantee in the absence of exact input data, provable performance
- More tractable than SO

## Challenges

- Conservativeness
- restrict recourse policy



# Robust optimization

$$\begin{aligned} & \min_x \max_w \min_y f(x, y, w) \\ & \text{s.t. } h^2(x, w, y) = 0 \\ & \quad g^2(x, w, y) \leq 0 \\ & \quad y \in \mathcal{Y} \\ & \text{s.t. } w \in \mathcal{W} \\ & \text{s.t. } h^1(x) = 0 \\ & \quad g^1(x) \leq 0 \\ & \quad x \in \mathcal{X} \end{aligned}$$

Uncertainty set  
(contains all scenarios)

$x$  - Here-and-now variables

$w$  – stochastic vector

$y$  – Wait-and-see variables (optional)

When we do NOT have “wait-and-see variables”, it is called “**static** robust optimization”

When we have “wait-and-see variables”, it is called “**adjustable** robust optimization”

# *Main contributors*



**Aharon Ben-Tal (1946-)**

- Convex optimization
- Robust optimization
- INFORMS Khachiyan Prize, 2016
- INFORMS Fellow, SIAM Fellow
- EURO Gold Medal, 2007



**Dimitris Bertsimas (1962-)**

- Optimization, Applied Probability
- Transportation, Finance
- Farkas Prize
- INFORMS Fellow
- Member of National Academy of Engineering

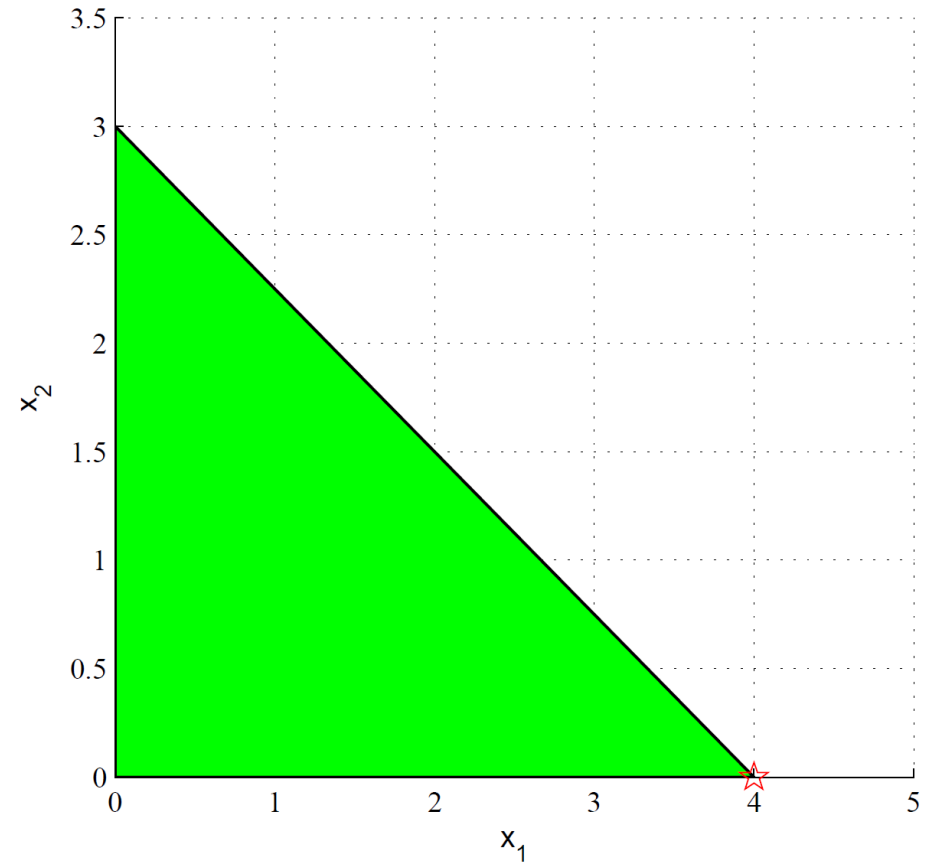
## An example on uncertain LP

Consider this optimization problem:

$$\begin{aligned} \max_{x_1, x_2} \quad & z = x_1 + x_2 \\ \text{s.t.} \quad & ax_1 + bx_2 \leq 12 \\ & x_1 \geq 0, x_2 \geq 0 \end{aligned}$$

If  $a = 3, b = 4$  are deterministic, then  
 $x^* = (4, 0), z^* = 4$

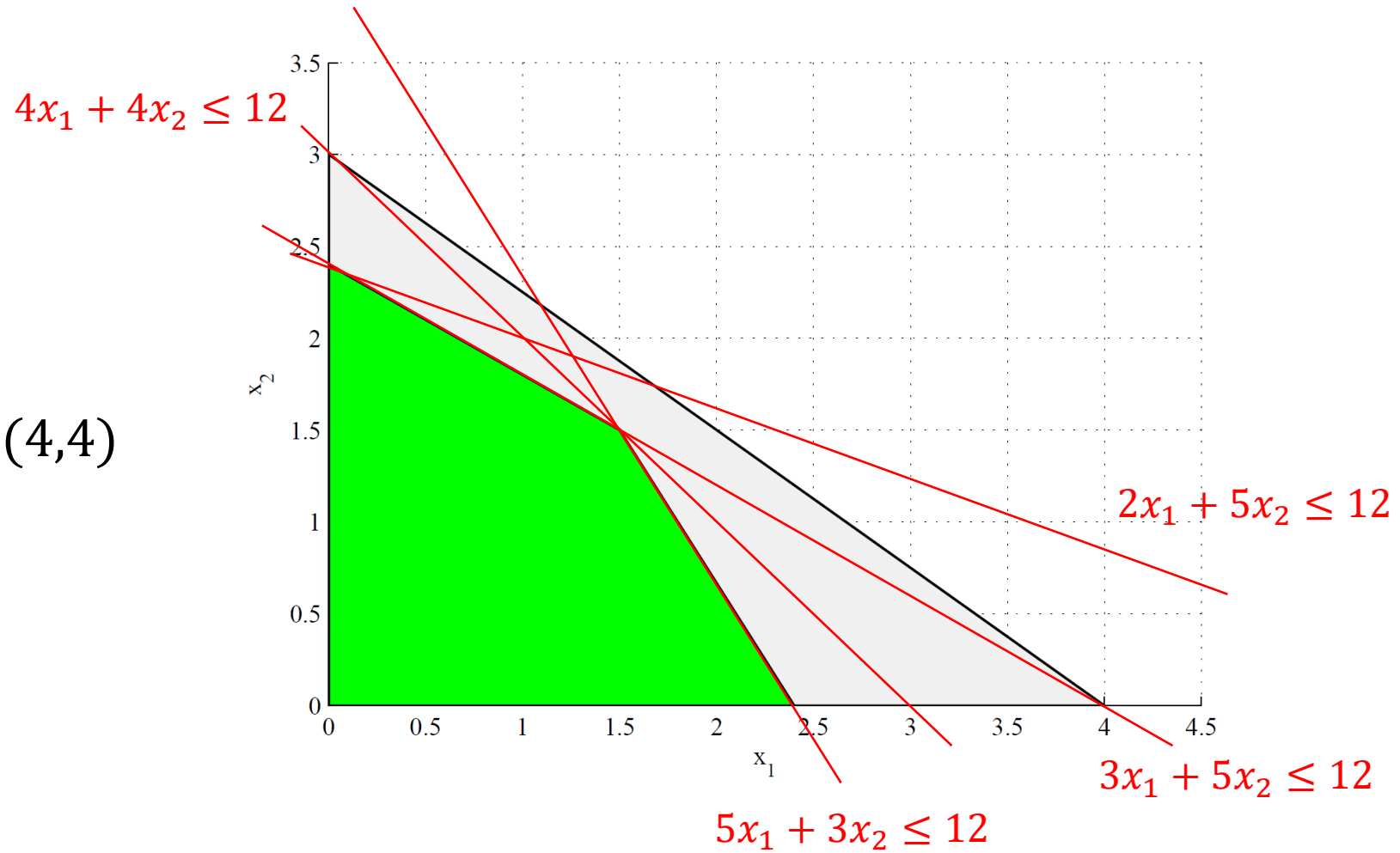
If parameters  $a, b$  are uncertain, and  
 $a \geq 2, b \geq 2, 6 \leq a + b \leq 8$



## An example on uncertain LP

If we let

$$(a, b) = (2, 5), (5, 3), (3, 5), (4, 4)$$



## *An example on uncertain LP*

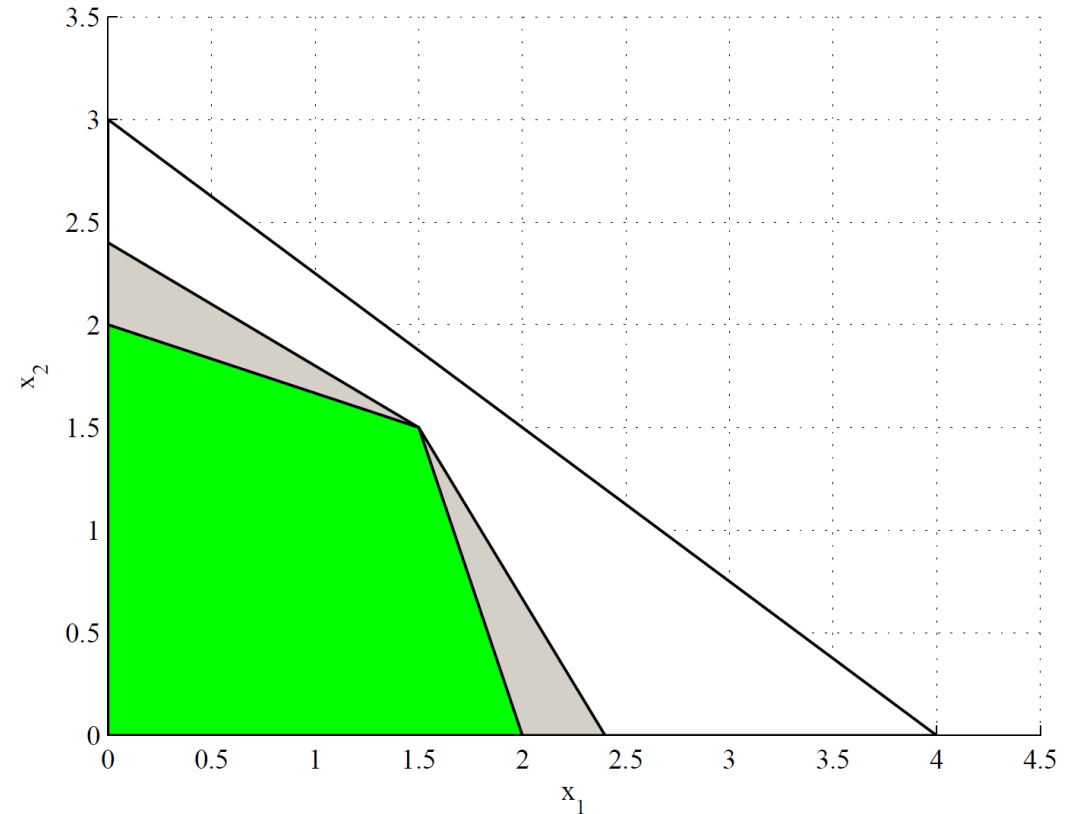
If we let

$$(a, b) = (2, 6), (6, 2)$$

The feasible region further ↓

In fact, the “robust” optimal solution is

$$x^* = (1.5, 1.5), z^* = 3$$



## ***An example on uncertain LP***

Mathematical Analysis:

- The worst data must satisfy  $a + b = 8$ . Why?

- The constraints yields a cluster of lines

$$ax_1 + (8 - a)x_2 \leq 12$$

All the lines in the cluster pass through point (1.5, 1.5)

- The extreme scenarios are  $(a, b) = (2, 6); (6, 2)$
- The robust feasible set is given by (regardless of the objective function)

$$x_1 \geq 0, 6x_1 + 2x_2 \leq 12$$

$$x_2 \geq 0, 2x_1 + 6x_2 \leq 12$$

# Static robust optimization

$$\begin{aligned} \min_x \quad & c^\top x \\ \text{s.t.} \quad & Ax \leq b, \forall A \in W \end{aligned}$$

where  $x$  represent "here-and-now" decisions: they should be specified before the actual data is known.

Constraints are mandatory, i.e., constraint violation is not tolerable when  $A \in W$ .

Without loss of generality, we assume

1. the objective is deterministic
2. the right-hand side of each constraint is deterministic
3.  $W$  is compact and convex
4. the uncertainty is constraint-wise

## Static robust optimization

$$\begin{aligned} \min_x \quad & c^\top x \\ \text{s.t.} \quad & Ax \leq b, \forall A \in W \end{aligned}$$

Suppose  $c$  is uncertain and  $c \in \mathcal{C}$ , we have the equivalent form:

$$\begin{aligned} \min_{x, \sigma} \quad & \sigma \\ \text{s.t.} \quad & c^\top x \leq \sigma : \forall c \in \mathcal{C} \\ & Ax \leq b : \forall A \in W \end{aligned}$$

Suppose  $b$  is uncertain, then we can introduce an additional variable  $y = -1$  and get

$$\begin{aligned} \min_x \quad & c^\top x \\ \text{s.t.} \quad & [A, b] \begin{bmatrix} x \\ -1 \end{bmatrix} \leq 0 : \forall (A, b) \in W \end{aligned}$$

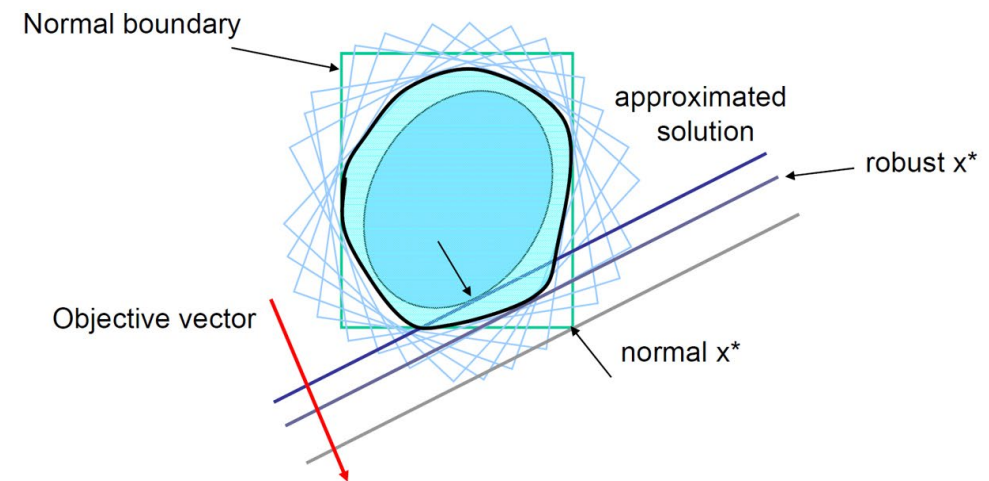


# Static robust optimization

Definition (**Feasibility**): A solution is robust feasible if it stays feasible for all possible realizations of the uncertain data.

Definition (**Optimality**): A robust feasible solution is optimal if it minimizes the objective function for all possible realizations of the uncertain data.

$$\begin{aligned} \min_x \quad & c^\top x \\ \text{s.t.} \quad & Ax \leq b, \forall A \in W \end{aligned}$$



# Static robust optimization

$W$  is called an "uncertainty set".

Different types of uncertainty set:

1. Discrete uncertainty set

How to deal with discrete uncertainty set?

$$a \in [\bar{a}_1, \bar{a}_2, \dots, \bar{a}_N]$$

2. Box uncertainty set

$$a \in \{a \mid \|a_i\| \leq \tau, \forall i = 1, \dots, N\}$$

3. Ellipsoidal uncertainty set

$$a \in \{a \mid (a - \bar{u})^\top R^{-1}(a - \bar{u}) \leq \Omega^2\}$$

4. Polyhedral uncertainty set

$$a \in \{a \mid a = \bar{a} + Pu, Du + q \geq 0\}$$

## ***Adjustable robust optimization\****

Feasible set of static robust optimization:

$$X_S := \{x \mid \forall A \in W: Ax \leq b\}$$

All decisions must be made before  $A$  is known exactly.

Feasible set of adjustable robust optimization:

$$X_A := \{x \mid \forall A \in W, \exists y: Ax + By \leq b\}$$

The choice of  $y$  is a function (feedback, recourse) of  $A$ .

$x$ : here-and-now variable

$y$ : wait-and-see variable

$X_A$  is usually larger than  $X_N$

## ***Static v.s. Adjustable robust optimization\****

$$\begin{aligned} \min_{x_1, x_2} \quad & x_1 \\ \text{s.t.} \quad & x_2 \geq 0.5\xi x_1 + 1, \forall \xi \in \Xi \\ & x_1 \geq (2 - \xi)x_2, \forall \xi \in \Xi \\ & x_1 \geq 0, x_2 \geq 0 \end{aligned}$$

where  $\Xi = \{\xi \mid 0 \leq \xi \leq \rho, \rho \in (0, 1)\}$

**Static case:** both  $x_1$  and  $x_2$  are determined prior to knowing the exact  $\xi$

- When  $\xi = \rho$ ,  $x_2 \geq 0.5\rho x_1 + 1$
- When  $\xi = 0$ ,  $x_1 \geq 2x_2$

Hence  $x_1 \geq \rho x_1 + 2$  or  $x_1 \geq 2/(1 - \rho)$

When  $\rho \rightarrow 1$ ,  $x_1 \rightarrow \infty$

## ***Static v.s. Adjustable robust optimization\****

$$\begin{aligned} \min_{x_1, x_2} \quad & x_1 \\ \text{s.t.} \quad & x_2 \geq 0.5\xi x_1 + 1, \forall \xi \in \Xi \\ & x_1 \geq (2 - \xi)x_2, \forall \xi \in \Xi \\ & x_1 \geq 0, x_2 \geq 0 \end{aligned}$$

where  $\Xi = \{\xi \mid 0 \leq \xi \leq \rho, \rho \in (0, 1)\}$

**Adaptive case:**  $x_2$  is the “wait-and-see” variable

We can let  $x_2 = 0.5\xi x_1 + 1$ , then  $x_1 \geq (2 - \xi)(0.5\xi x_1 + 1), \forall \xi \in [0, \rho]$

Since  $4 \geq (2 - \xi)(2\xi + 1) = -2\xi^2 + 3\xi + 2, \forall \xi \in [0, \rho]$

$x_1 = 4$  is a robust feasible solution

We know that the optimal value of the robust optimization is  $\leq 4$ .

## Example – Robust energy and reserve dispatch\*

With renewable energy...

Traditional Economics Dispatch:

$$\begin{aligned}
 \min F &= \sum_{g=1}^{N_G} (a_g p_g^2 + b_g p_g) \\
 \text{s.t. } P_g^l &\leq p_g \leq P_g^u \quad \forall g \\
 \sum_{g=1}^{N_G} p_g &= \sum_{q=1}^{N_Q} p_q \\
 -F_l &\leq \sum_{g=1}^{N_G} \pi_{gl} p_g - \sum_{q=1}^{N_Q} \pi_{ql} p_q \leq F_l, \quad \forall l
 \end{aligned}$$

$$\min F = \sum_{g=1}^{N_G} (a_g p_g^2 + b_g p_g)$$

$$\text{s.t. } P_g^l + r_g \leq p_g \leq P_g^u - r_g \quad \forall g$$

$$\sum_{g=1}^{N_G} p_g + \sum_{m=1}^{N_W} p_m^{we} = \sum_{q=1}^{N_Q} p_q$$

$$-F_l \leq \sum_{g=1}^{N_G} \pi_{gl} p_g + \sum_{m=1}^{N_W} \pi_{ml} p_m^{we} - \sum_{q=1}^{N_Q} \pi_{ql} p_q \leq F_l,$$

$$W^D = \left\{ \begin{array}{l} p_m^w = p_m^{we} + z_m^+ p_m^{wh} \\ -z_m^- p_m^{wh}, \quad \forall m \end{array} \left| \begin{array}{l} z_m^+, z_m^- \in \{0, 1\}, \quad \forall m \\ z_m^+ + z_m^- \leq 1, \quad \forall m \\ \sum_{m=1}^{N_W} z_m^+ + z_m^- \leq \Gamma^S \end{array} \right. \right\}$$

Uncertainty budget

**Reference:** Wei W, Liu F, Mei S, et al. Robust energy and reserve dispatch under variable renewable generation[J]. IEEE Transactions on Smart Grid, 2014, 6(1): 369-380.

## Example – Robust energy and reserve dispatch\*

### Set-point stage

$$\min_{p_g^f, r_g} F = \sum_{g=1}^{N_G} \left( a_g (p_g^f)^2 + b_g p_g^f + c_g r_g \right) \quad (6a)$$

$$\text{s.t. } p_g^f + r_g \leq P_g^u \quad \forall g \quad (6b)$$

$$P_g^l \leq p_g^f - r_g \quad \forall g \quad (6c)$$

$$\sum_{g=1}^{N_G} p_g^f + \sum_{m=1}^{N_W} p_m^{we} = \sum_{q=1}^{N_Q} p_q \quad (6d)$$

$$-F_l \leq \sum_{g=1}^{N_G} \pi_{gl} p_g^f + \sum_{m=1}^{N_W} \pi_{ml} p_m^{we} - \sum_{q=1}^{N_Q} \pi_{ql} p_q \leq F_l, \quad \forall l \quad (6e)$$

$$0 \leq r_g \leq \min \{ R_g^- \Delta t, R_g^+ \Delta t \} \quad \forall g \quad (6f)$$

### Feasibility check

$$\forall \{p_m^w\} \in W^D, \exists \{\Delta p_g^+, \Delta p_g^-\} \text{ such that} \\ 0 \leq \Delta p_g^+ \leq r_g, 0 \leq \Delta p_g^- \leq r_g \quad \forall g \quad (6g)$$

$$p_g^c = p_g^f + \Delta p_g^+ - \Delta p_g^- \quad \forall g \quad (6h)$$

$$\sum_{g=1}^{N_G} p_g^c + \sum_{m=1}^{N_W} p_m^w = \sum_{q=1}^{N_Q} p_q \quad (6i)$$

$$-F_l \leq \sum_{g=1}^{N_G} \pi_{gl} p_g^c + \sum_{m=1}^{N_W} \pi_{ml} p_m^w - \sum_{q=1}^{N_Q} \pi_{ql} p_q \leq F_l, \quad \forall l \quad (6j)$$

## Example – Robust energy and reserve dispatch\*

Algorithms for solving robust optimization

- Benders decomposition, D Bertsimas, E Litvinov, etc. 2012
- Column & Constraint Generation, B. Zeng, L. Zhao, 2013

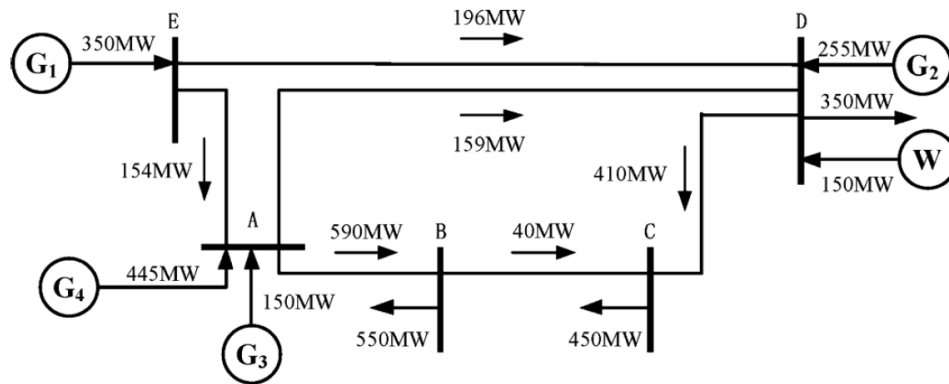


Fig. 4. Power flow for RERD under  $\pm 105$  MW uncertainty.

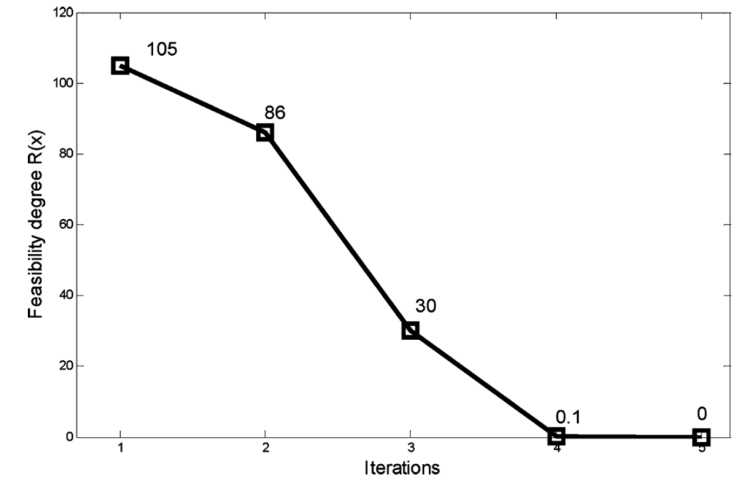
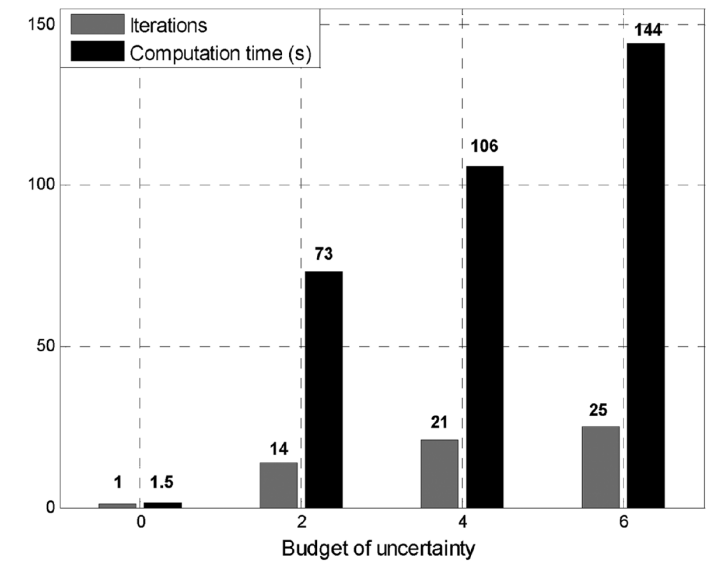


Fig. 5.  $R(x)$  as a feasibility degree in each iteration.



**Reference:** Wei W, Liu F, Mei S, et al. Robust energy and reserve dispatch under variable renewable generation[J]. IEEE Transactions on Smart Grid, 2014, 6(1): 369-380.



Thanks!