













«Interface»



motor_control.h

-  + open_port()
-  + close_port()
-  + enable_torque()
-  + disable_torque()
-  + set_goal_position()
-  + set_goal_speed()
-  + read_current_position()
-  + read_current_speed()
-  + read_load()
-  + read_error()
-  + read_temperature()
-  + read_supply_voltage()



«Interface»



dynamixel_sdk.h