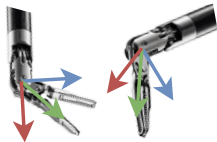
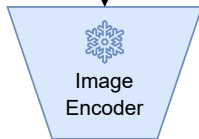


Relative pose trajectory
(pos, rot, gripper \angle)



Images



x^L, g^L

x^R, g^R

concatenate
left and right features

x^L, g^L, x^R, g^R

