# ROBOTIC CONTROL SYSTEM Configuration and operation

# LAYOUT OF OCC FILESYSTEM

```
o/occ
   • /bin
               various startup and utility scripts
   • /common
          o/ngat

NGAT libraries

          o/shared
                    • 3rd party libs (jibx, jdom, xerces...)
          o/lib
                    • c libs (libjslalib.so, libngatfits.so...)
   • /data

data generated by various cron scripts

                    • Eg cloud.dat, dust.dat, ocr.dat...
   • /rcs
          o/config

configuration files

          o/instruments
                    • instrument calib data
          o/tocs

ToO accounting

          o/scripts

Various scripts

   • /logs
                    • The rcs logs for the last day
   • /tmp
                    • Temporary logs eg rcs console, various script logs.
   /backup

Dated backups made using /occ/bin/backup script
```

# PROCESSES ON OCC

### • RCS

- Started via: /etc/init.d/rcw\_init
  - This is a watchdog, it restarts the RCS if it falls over or a restart is requested via the OpsUI.

### Scheduler

- Started via: /etc/init.d/sched\_init
  - The deployed version of this script does not have a stop option there is one in the dev version.
- Synoptic Model -Phase2 cache (level 1)
  - Started via: /etc/init.d/smp\_init
    - There is a level 2 cache but this is still experimental it would probably speed up scheduler execution by a factor of around x5 to x10. Again the deployed script has no stop option but the dev version does.
- Beam Steering System
  - Started via: /etc/init.d/bss\_init
    - This has to be running as the instruments (O at least) talk to it.

## MAIN PROCESS

- The RCS main launcher is contained in the class
  - ngat.rcs.RCS\_Controller
- It configures and starts all the various subsystems and modules:-
  - TCM
    - o configured via telescope.xml
  - ICM
    - o configured via *ireg.xml*
  - EMS
  - ERS
    - o configured via *rules.xml*
  - TMS
    - o configured via task.properties
    - o agent.properties and various mode controllers via
    - ${\tt o}\, soca\_ops.properties \ , \ to\_ops.properties, \ background.properties$
  - Ops
    - configured via tsm\_reactive.properties

# RCS PROCESS STARTUP

- o Initialize logs
- Initialize astrometry
- Setup CIL service and CIL Proxy
- Setup ISS and TOCS
- TCM setup
  - Configuration
  - Start monitoring TCS and AG
- o ICM setup
  - Configuration of Ireg and instrument status providers
  - Start monitoring instruments
- Legacy providers for LiveData feeds
- o EMS setup
  - Configuration
  - Start monitoring WMS, BCS, TNG
- ERS setup
  - Start processing thread
- Monitors setup
  - Tracking, Autoguider lock, Instruments, PMC
- o TMS setup
- Ops setup, statemodel and binding to ERS
- MCA setup
  - Configure BGCA, SOCA, TOCA, CA
- A minute or so after everything is setup the time-of-day (PERIOD) and eng/auto (INTENT) state variables, used by the state model are set according to the actual time of day and command line arg (manual or auto).