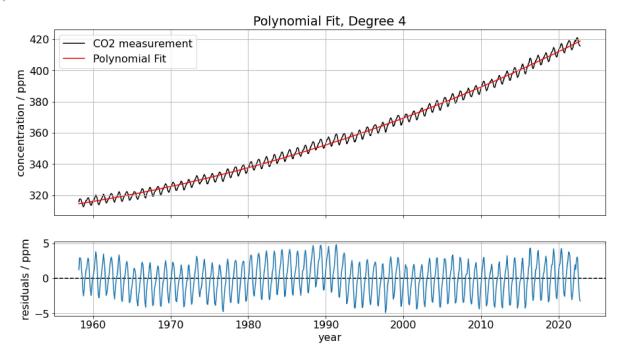
```
In [159... import os
            import numpy as np
            import matplotlib.pyplot as plt
            from mpl_toolkits.axes_grid1.inset_locator import zoomed_inset_axes
            from mpl_toolkits.axes_grid1.inset_locator import mark_inset
In [160... | fs = 20 # fontsize
            lw = 2 # Line width
            width = 15 # figure width
            height = 8 # figure height
            plt.rcParams["axes.formatter.useoffset"] = False # No tick Label offset
            plt.rcParams.update({'font.size': fs-4}) # Standard font size
In [161... path = "Data\co2_mm_mlo.csv"
            t, co2, co2_av = np.loadtxt(path, skiprows = 53,delimiter = ',',comments='#',useco
            Given: Time series of measurements of concentration ec{c}=(c_1,c_2,\ldots,c_m) According to
            time \vec{t}=(t_1,t_2,\ldots,t).
            Forward model: Polynome of order 4
                           c(t) = a_0 + a_1 \cdot t + a_2 \cdot t^2 + a_3 \cdot t^3 + a_4 \cdot t^4 = \sum_{i=0}^4 a_i \cdot t^i
                                                                                                        (1)
            Matrix notation:
                                                     c(\vec{t}) = K\vec{a}
                                                                                                        (2)
           with \vec{a}=egin{pmatrix} a_0\\a_1\\a_2\\a_3 \end{pmatrix} and K=egin{pmatrix} t_1^{\circ} & t_1 & t_1^{\circ} & t_1^{\circ} & t_1^{\circ}\\t_2^{0} & t_2 & t_2^{2} & t_2^{3} & t_2^{4}\\t_3^{0} & t_3 & t_3^{2} & t_3^{3} & t_3^{4} \end{pmatrix}
In [162... def forward_model(timeseries, n):
                 K_T= np.zeros([n,len(timeseries)])
                 for j in range(n):
                      K_T[j]= timeseries**j
                 K model=np.transpose(K T)
                 return K_model
In [163...] orderp1 = 5
            K = forward_model(t, orderp1)
            a_fit, r, rank, sv = np.linalg.lstsq(K,co2, rcond=1)
            c_fit= np.matmul(K,a_fit)
            print("K is an (mxn) matrix with m= "+ str(len(t))+ " and n=" + str(orderp1)+ ". T
            K is an (mxn) matrix with m= 776 and n=5. The rank of K is 3.
```

As K is no square matrix, there is no inverse of K, thus there is no exact solution of the problem.

Out[164]: <matplotlib.legend.Legend at 0x20384bc8820>



Residuals show systematic deviation from fit curve (Oscillation around zero). --> polynomial fit does not describe underlying measurement very well --> Oscillating term should be introduced.

Advanced forward model: polynome of order 4, overlaid with fourier series of order 4

$$c(t) = \sum_{i=0}^{4} a_i \cdot t^i + b_i \cos(2\pi \cdot i \cdot t) + c_i \sin(2\pi \cdot i \cdot t)$$
(3)

Matrix notation:

$$\vec{c(t)} = K\vec{a} \tag{4}$$

```
with ec{a}=\left(egin{array}{c} a_4 \ b_0 \ \dots \ b_4 \ c_0 \ \dots \end{array}
ight) and
                     \begin{pmatrix} t_1^0 & \dots & t_1^4 & \cos(2\pi \cdot 0 \cdot t_1) & \dots & \cos(2\pi \cdot 0 \cdot t_1) & \sin(2\pi \cdot 0 \cdot t_1) & \dots & \sin(t_1^2 & \dots & t_2^4 & \cos(2\pi \cdot 0 \cdot t_2) & \dots & \cos(2\pi \cdot 4 \cdot t_2) & \sin(2\pi \cdot 0 \cdot t_2) & \dots & \sin(t_3^2 & \dots & t_3^4 & \cos(2\pi \cdot 0 \cdot t_3) & \dots & \cos(2\pi \cdot 4 \cdot t_3) & \sin(2\pi \cdot 0 \cdot t_3) & \dots & \sin(t_3^2 & \dots & \dots & \dots \\ & \dots & \dots & \dots & \dots & \dots & \dots \\ \end{pmatrix} 
In [165... def advanced forward model(timeseries, order poly, order fourier):
                  K T= np.zeros([2*order fourier+order poly,len(timeseries)])
                  for j in range(order poly):
                       K_T[j]= timeseries**j
                  for j in range(order_fourier):
                        K_T[j+order_poly]= np.cos(2*np.pi*j*timeseries)
                        K_T[j+order_poly+order_fourier]= np.sin(2*np.pi*j*timeseries)
                  K=np.transpose(K T)
                  return K
In [166... n_poly = 5
             n_fourier= 5
             K 2 = advanced forward model(t, n poly, n fourier)
             x_fit_2, r_2, rank_2, sv_2 = np.linalg.lstsq(K_2,co2, rcond=1)
             y fit 2= np.matmul(K 2,x fit 2)
             print("K is an (mxn) matrix with m= "+ str(len(t))+ " and n=" + str(5)+ ". The rank
             K is an (mxn) matrix with m= 776 and n=5. The rank of K is 3.
In [168... | fig, (ax, res) = plt.subplots(2, 1, sharex=True, gridspec_kw={"height_ratios": [5,
             axins = zoomed_inset_axes(ax, 2.5, loc=4)
             axins.plot(t,co2,color="black" )
             axins.plot(t,y_fit,color="red" )
             axins.plot(t,y_fit_2,color="green" )
             x1, x2, y1, y2 = 1960, 1970, 310, 330 # specify the limits
             axins.set_xlim(x1, x2) # apply the x-limits
             axins.set_ylim(y1, y2)
             mark_inset(ax, axins, loc1=2, loc2=4, fc="none", ec="0.05")
             ax.plot(t,co2,label="CO2 measurement",color="black",zorder=1)
             ax.plot(t,y_fit,label="Polynomial Fit",color="red",zorder=1)
             ax.plot(t,y_fit_2,label="Fourier Fit",color="green",zorder=1)
             res.errorbar( t, co2 - y_fit,label="Polynomial Residuals",color="red", capsize=3)
             res.errorbar( t, co2 - y_fit_2,label="Fourier Residuals",color="green", capsize=3)
```

```
res.axhline(0, linestyle="--", color="black")
res.grid()
ax.grid()
res.set_xlabel("year")
res.set_ylabel('residuals / ppm')
ax.set_ylabel("concentration / ppm")
ax.set_title("Polynomial-Fourier Fit, Degree 4")
ax.legend(loc=2)
```

Out[168]: <matplotlib.legend.Legend at 0x2038522ca90>

