

Calibration results

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Camera-system parameters:

cam0 (/usb_cam/image_raw):

type: <class 'aslam_cv.libaslam_cv_python.EquidistantDistortedPinholeCameraGeometry'>

distortion: [-0.04210401 -0.00011969 -0.00474072 0.00134258] +- [0.00473976 0.01075766 0.00942448 0.00281762]

projection: [383.83507219 384.56198569 644.26142898 370.03378743] +- [1.01400758 1.01807956 0.51253877 0.47077146]

reprojection error: [-0.000000, -0.000000] +- [0.170592, 0.195097]

Target configuration

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Type: aprilgrid

Tags:

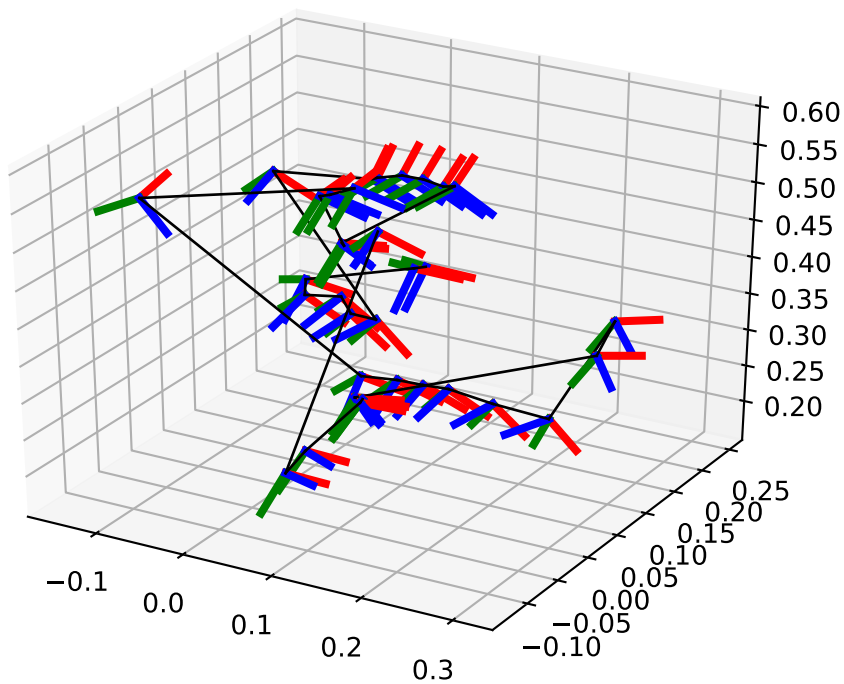
Rows: 8

Cols: 6

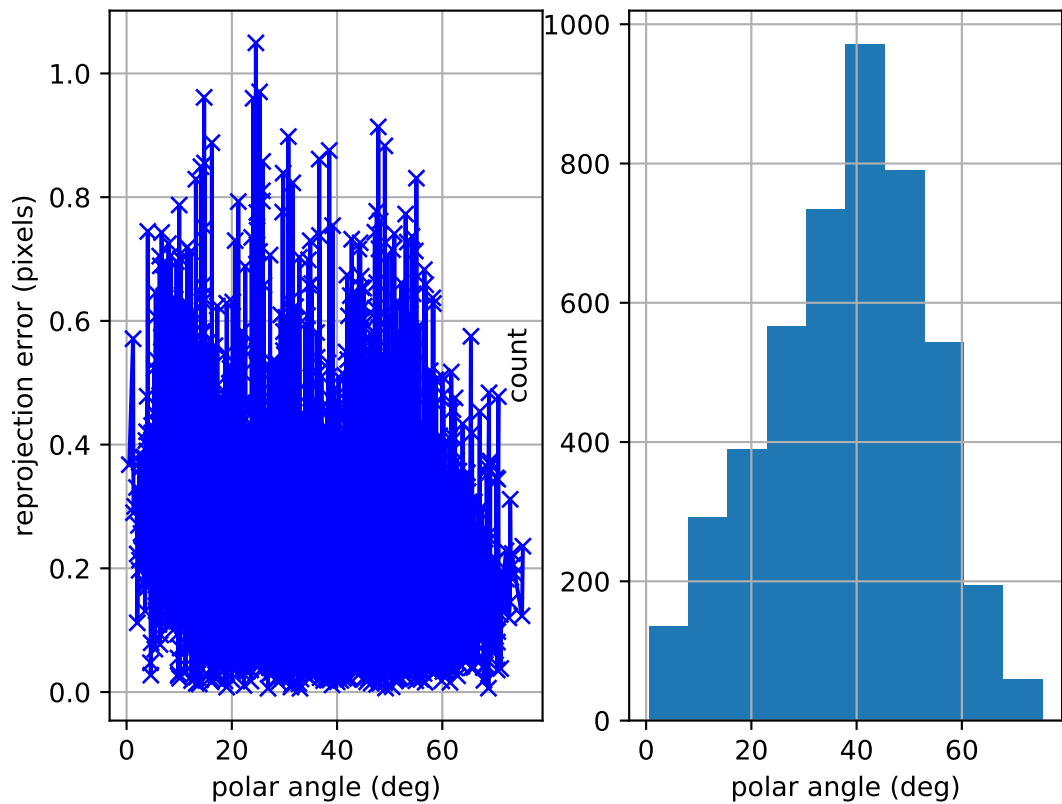
Size: 0.023 [m]

Spacing 0.0069 [m]

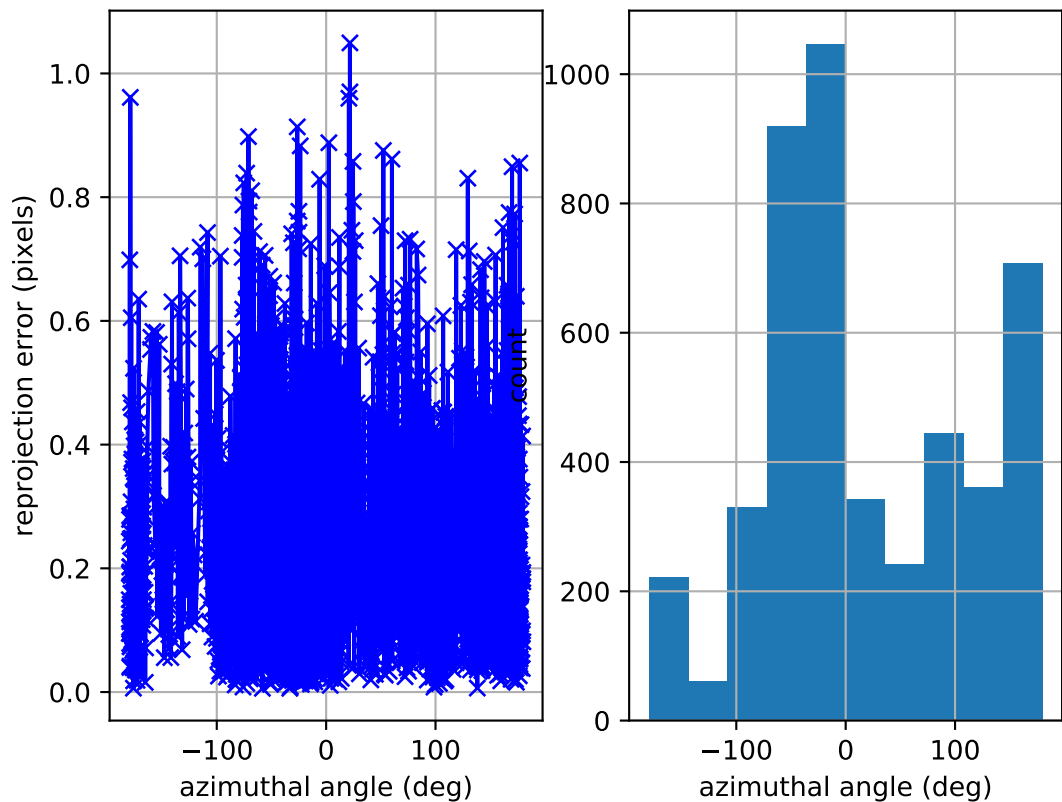
cam0: estimated poses



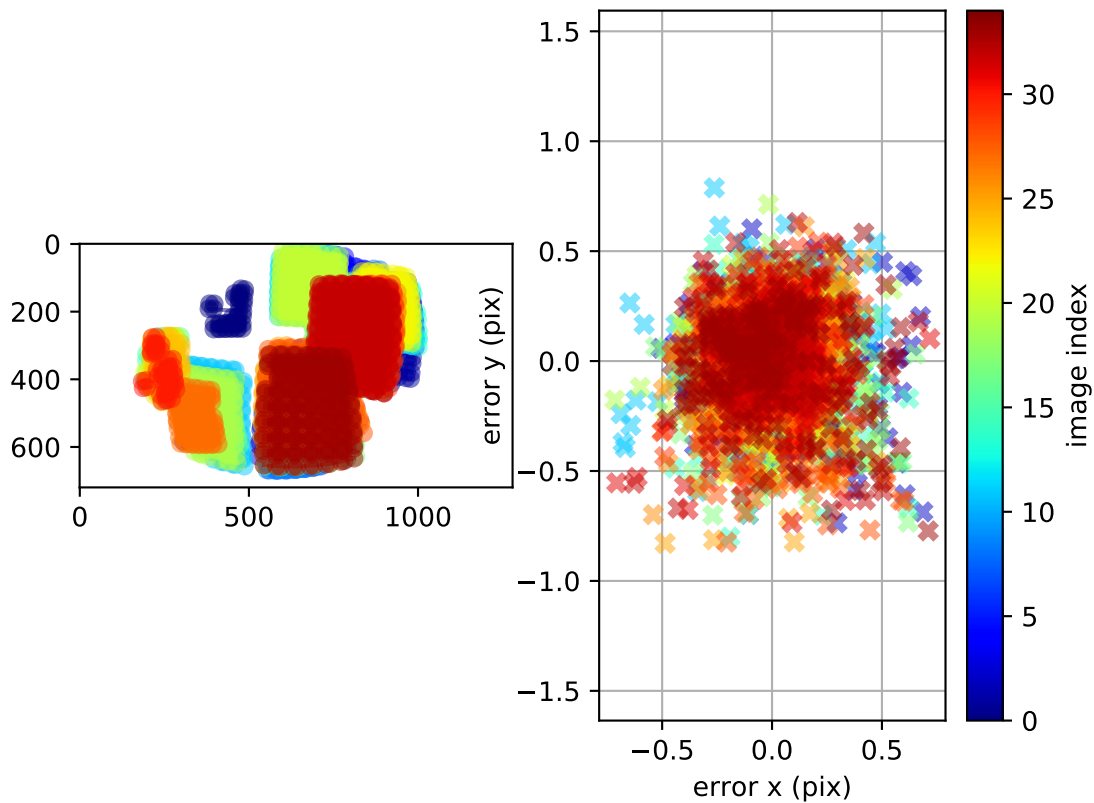
cam0: polar error



cam0: azimuthal error



cam0: reprojection errors



Location of removed outlier corners

