## Classification of Quadratic Forms over $\mathbb Q$

Shubin Xue

Beijing Institute of Technology

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- Background and Approaches
  - Classification and Representation
  - Local-to-Global Principle
- Quadratic Forms over  $\mathbb{Q}_n$ 
  - General Ideas
  - Classification of Quadratic Forms over R
  - Invariants that Determine the Representation over  $\mathbb{Q}_p$
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  - Classification Results
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#### **Notations**

- K: an arbitrary field and  $\operatorname{char} K \neq 2$ .
- $\bullet$  X, Y, Z: variables.
- ullet  $\mathbb{P}$ : the set of prime numbers.
  - $\bullet \ p \in \mathbb{P}.$
  - $\mathbb{Q}_p$ : the completion of  $\mathbb{Q}$  at p.
- $\mathbb{V}=\mathbb{P}\cup\{\infty\}$ .
  - $v \in \mathbb{V}$ .
  - $\mathbb{Q}_{\infty} = \mathbb{R}$
- Denote by the same letter an element and its class modulo.

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## Quadratic Froms

- $f(\vec{X}) = \sum_{i,j=1}^{n} a_{ij} X_i X_j$  is a quadratic form
  - $\vec{X}=(X_1,\cdots,X_n)\in K^n$  and  $a_{ij}=a_{ji}\in K.$
- The matrix  $A_f = (a_{ij})$  associated with f is Symmetric.
  - $f(\vec{X}) = \vec{X}^T A_f \vec{X}.$
- The pair  $(K^n, f)$  is a quadratic space.
  - $f \sim g$ :  $\exists P \in GL(n,K)$  s.t.  $A_f = P^T A_g P$ .
- $f(X_1, \dots, X_n)$  and  $g(X_1, \dots, X_m)$

$$f \oplus g = f(X_1, \cdots, X_n) + g(X_{n+1}, \cdots, X_{n+m})$$



## Background(17-18th century)

## Theorem (Fermat's Two-Square Theorem)

An odd prime p can be represented as the sum of two squares if and only if  $p \equiv 1 \pmod{4}$ .

### Theorem (Gauss's Three-Square Theorem)

All positive integers except those of the form  $4^a(8m-1)$  can be represented as the sum of three squares.

## Background(19-20th century)

### Theorem (Gauss's Classification of Quadratic Forms)

Quadratic forms in the same equivalence class represent exactly the same set of numbers.

## Theorem (Hasse-Minkowski)

f represents 0 over  $\mathbb{Q}$  iff it represents 0 over all  $\mathbb{Q}_v$ .

## Representing Numbers

• f represents  $a \in K$ :  $\exists 0 \neq x \in K^n$  s.t. f(x) = a.

### **Proposition**

Let  $a \in K^{\times}$ . TFAE:

- f represents a
- $f \sim f_1 \oplus aZ^2$  where  $f_1$  is of rank f 1.
- $f_a = f \oplus -aZ^2$  represents 0.

### Corollary (Hasse-Minkowski Theorem)

f represents  $a \in \mathbb{Q}^{\times}$  over  $\mathbb{Q}$  iff it represents a over all  $\mathbb{Q}_n$ .

• Apply Hasse-Minkowski Theorem to  $f_a = f \oplus -aZ^2$ .

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## Decomposing quadratic spaces

### Theorem (Witt's cancellation)

$$f_1 \oplus g_1 \sim f_2 \oplus g_2$$
 and  $g_1 \sim g_2$  implies  $f_1 \sim f_2$ .

- $\bullet$  (V,Q): A quadratic space.
- $\bullet$  (U,Q) and (W,Q): Isomorphic subspaces.



Figure: Witt's Cancellation Theorem

## $f \sim g \text{ over } \mathbb{Q}$

### Theorem ([Ser73] p. 44, chap. 4, sec. 3.3, theorem 9)

Two non-degenerate quadratic forms of rank n over  $\mathbb{Q}$  are equivalent iff they are equivalent over each  $\mathbb{Q}_v$ .

- Suppose  $f \sim g$  over  $\mathbb{Q}_v$  for all v. Take a represented by f over  $\mathbb{Q}$ .
- Then f represents a over all  $\mathbb{Q}_v$ . And a is represented by g over all  $\mathbb{Q}_v$ , since  $f \sim g$  over all  $\mathbb{Q}_v$ .
- By the Hasse-Minkowski Theorem, a is represented by both f and g over  $\mathbb{Q}$ .
- Thus  $f \sim aZ^2 \oplus f_1$ ,  $g \sim aZ^2 \oplus g_1$ , where rank  $f_1 = \operatorname{rank} g_1 = n 1$ .
- By Witt's cancellation, we have  $f_1 \sim g_1$  over  $\mathbb{Q}_v$  for all  $v \in \mathbb{V}$ .
- By induction on rank n,  $f_1 \sim g_1$  over  $\mathbb{Q}$ , thus  $f \sim g$  over  $\mathbb{Q}$ .

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#### General Ideas

- Reduce to classifying non-degenerate rank n quadratic forms of the shape  $f \sim \sum_{i=1}^n a_i X_i^2$ , where  $a_i \in K^\times/(K^\times)^2$ .
  - Invariant rank: non-degenerate.
  - Symmetric matrices: diagonal.
  - $\sum a_i b_i^2 X_i^2 \sim \sum a_i X_i^2$ : squared-free.
- If  $f \sim g$ ,  $\det(A_f) = \det(P^T A_g P) = \det(A_g) \det(P)^2$ 
  - Invariant discriminant:  $d = \det(A)$  in  $K^{\times}/(K^{\times})^2$ .
- $\mathbb{R}^{\times}/(\mathbb{R}^{\times})^2 \cong \{1, -1\}.$
- $\bullet \mathbb{Q}_p^{\times}/(\mathbb{Q}_p^{\times})^2 \cong K_4 = \{1, a, p, ap\}.$



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#### Case over $\mathbb R$

- Invariants:
  - Rank:  $\operatorname{rank} f = n$ .
  - Signature: (r,s) := (# positive eigenvalues, # negative eigenvalues).

### Theorem (Sylvester's law of inertia)

Let 
$$f = \sum_{i,j=1}^n a_{ij} X_i X_j$$
 be a quadratic form of rank  $n$  over  $\mathbb{R}$ . Then

$$f \sim X_1^2 + X_2^2 + \dots + X_r^2 - X_{r+1}^2 - \dots - X_{r+s}^2$$
.



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# Binary Quadratic Forms over $\mathbb{Q}_{p\neq 2}$

#### Theorem

Two quadratic forms of rank 2 over  $\mathbb{Q}_{p\neq 2}$  are equivalent iff they have the same discriminant d and a common representive number a.

- ullet Take a represented by both f and g.
- $f \sim f_1 \oplus aZ^2$  where rank  $f_1 = 1$ .
- Then  $f_1 = adX^2$ . Thus f is determined. Similarly for g.

# Binary Quadratic Forms over $\mathbb{Q}_{p\neq 2}$

ap		p	a	1	d	
ap		p	a	1	1	
p	)	ap	1		a	
a		1			p	
1					ap	
$\frac{ap}{\text{(a) } p \equiv 1 \pmod{4}}$						

d	1	a	p	ap
1	1	a	p	ap
a		1	ap	p
p			1	a
ap				1

Table: Equivalent classes of nondegenerate quadratic forms over  $\mathbb{Q}_n$  when n=2

• Fix d: classification depends on whether 1 can be represented.

## Hilbert Symbol

$$\bullet \ f = aX^2 + bY^2 \ \text{represents} \ 1 \iff Z^2 \oplus -f \ \text{represents} \ 0.$$

Hilbert symbol:

$$(a,b) = \begin{cases} 1 & Z^2 - aX^2 - bY^2 \text{ represents 0,} \\ -1 & \text{Otherwise.} \end{cases}$$



## Computation of Hilbert Symbol

$\overline{(\cdot,\cdot)}$	0	1	a	p
0	1	1	1	1
1		1	1	1
a			1	-1
p				$(-1)^{\frac{p-1}{2}}$

Table: Hilbert symbol,  $p \neq 2$ 

• Hilbert symbol is a symmetric non-degenerate bilinear form.

#### Hasse Invariant

- $f \sim \sum_{i=1}^n a_i X_i^2$  with  $n \ge 3$ .
  - Hasse invariant:  $\varepsilon(f) = \prod_{i < j} (a_i, a_j)$
- $\bullet$   $f=a_1X_1^2\oplus f_1$  with  $f_1=a_2X_2^2+\cdots+a_nX_n^2$ 
  - $d(f) = \prod_{i=1}^{n} a_i = a_1 \prod_{i=2}^{n} a_i = a_1 d(f_1)$ .
  - $\varepsilon(f) = \prod_{1 \le i < j \le n} (a_i, a_j) = \varepsilon(f_1) \cdot (a_1, a_2 \cdots a_n) = \varepsilon(f_1) \cdot (a_1, a_1 d(f)).$

## Theorem (([Ser73] p. 36, chap. 4, sec. 2.2, theorem 6))

f represents 0 iff:

- For n = 2: d = -1;
- For n = 3:  $(-1, -d) = \varepsilon$ ;
- For n=4:  $d \neq 1$  or d=1 and  $\varepsilon = (-1,-1)$ ;
- For  $n \geq 5$ : no conditions.

By applying Theorem to  $f_a = f \oplus -aZ^2$ , we obtain:

## Corollary (([Ser73] p. 37, chap. 4, sec. 2.2, corollary to themrem 6))

f represents  $a \in \mathbb{Q}_p^{\times}/(\mathbb{Q}_p^{\times})^2$  iff:

- For n = 1: a = d;
- For n = 2:  $(a, -d) = \varepsilon$ ;
- For n=3:  $a \neq d$  or a=d and  $\varepsilon=(-1,-d)$ ;
- For  $n \geq 4$ : no conditions.

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## $f \sim g$ over $\mathbb{Q}_p$

## Theorem (([Ser73] p. 39, chap. 4, sec. 2.3, theorem 7))

Two non-degenerate quadratic forms of rank n over  $\mathbb{Q}_p$  are equivalent iff they have the same discriminant d and Hasse invariant  $\varepsilon$ .

- f,g have same d and  $\varepsilon$ , thus there exists  $a\in\mathbb{Q}_p^{\times}$  which both represented by f and g.
- ullet Then  $f\sim f_1\oplus aZ^2$ , where  $f_1$  is of rank n-1. Similarly for g.
- d and  $\varepsilon$  of  $f_1$  can be determined:
  - $d(f_1) = ad(f) = ad(g) = d(g_1)$
  - $\varepsilon(f_1) = \varepsilon(f) \cdot (a, ad(f)) = \varepsilon(g) \cdot (a, ad(g)) = \varepsilon(g_1)$
- ullet Thus  $f_1,g_1$  share the same d and arepsilon. QED by induction.

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# Classification of Quadratic Forms over $\mathbb{Q}_n$

The invariants d and  $\varepsilon$  satisfy the following relations:

- For n = 1:  $\varepsilon = 1$ :
- For n=2:  $d\neq -1$  or  $\varepsilon=1$ ;
- For n > 3: no conditions.
- n = 1:  $f = dX^2$
- n = 2:  $f = aX^2 + adY^2$
- n = 3:  $f = a \oplus aZ^2$ 
  - d(q) = ad and  $\varepsilon(q) = \varepsilon(a, -d)$
- n > 3:  $f = q(X_1, X_2, X_3) \oplus X_1^2 \oplus \cdots \oplus X_n^2$ 
  - d(g) = d and  $\varepsilon(g) = \varepsilon$



## Classification of Quadratic Forms over O

### Theorem (Product formula)

$$(a,b)_v=1$$
 for almost all  $v\in\mathbb{V}$  and  $\prod_{v\in\mathbb{V}}(a,b)_v=1$ 

The invariants  $d_v$  and  $\varepsilon_v$  satisfy the following relations:

- $\varepsilon_v = 1$  for almost  $v \in \mathbb{V}$ , and  $\prod_{v \in \mathbb{V}} \varepsilon_v = 1$ .
- $\varepsilon_v = 1$  if n = 1 and if n = 2 and if the image  $d_v$  of d in  $\mathbb{Q}_n^{\times}/\mathbb{Q}_n^{\times 2}$  is equal to -1.
- $r, s \ge 0$  and r + s = rank.
- $d_{\infty} = (-1)^s$
- $\varepsilon_{\infty} = (-1)^{s(s-1)/2}$



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#### Skeleton of Proof

### Theorem (Hasse-Minkowski)

f represents 0 over  $\mathbb{Q}$  iff it represents 0 over  $\mathbb{R}$  and all  $\mathbb{Q}_n$ .

#### Skeleton of Proof:

- n=2: Fermat's Two-Square Theorem.
- n=3: Gauss's Three-Square Theorem.
- n=4: Lagrange's Four-Square Theorem.
- n 5: Mathematical induction.

#### References I

[Ser73] Jean-Pierre Serre. A Course in Arithmetic. Vol. 7. Graduate Texts in Mathematics. New York, NY: Springer, 1973. ISBN: 978-0-387-90041-4 978-1-4684-9884-4. DOI: 10.1007/978-1-4684-9884-4.