Images coloration python

October 1, 2021

```
[]: | %reset -f
[]: | # PART 1 - IMPORTING PYTHON LIBRARIES AND MOUNTING DRIVE
     import cv2
     from google.colab.patches import cv2_imshow
     import numpy as np
     from numpy import genfromtxt
     import pandas as pd
     import csv
     import os, math
     from scipy import ndimage
     import matplotlib
     import matplotlib.pyplot as plt
     import matplotlib.image as mpimg
     from google.colab import drive
     #Mounting Google Drive to access files
     drive.mount('/content/drive', force_remount=False)
```

Mounted at /content/drive

```
mat_position[mat_position == 6] = 2
mat_position[mat_position == 4] = 3
mat_position[mat_position == 0] = 1
# Loading image
original_img = cv2.imread(path_base + '/1. Original Image/Image 1.jpg')[0:
→rows_number, 0:columns_number]
imgR = cv2.imread(path base + '/1. Original Image/Image 1.jpg')[0:rows number,
→0:columns_number]
imgG = cv2.imread(path_base + '/1. Original Image/Image 1.jpg')[0:rows_number,__
→0:columns_number]
imgB = cv2.imread(path_base + '/1. Original Image/Image 1.jpg')[0:rows_number,_
→0:columns_number]
width,height,nb_colors = original_img.shape
img = np.zeros((width,height,nb_colors))
index_save = 0 #index to save results at the end of this code without erasing_
→previous results
# Extraction of R G B channels
# Set blue and green channels to 0
imgR[:,:,0] = 0
                     # X,Y,Z  # O=blue, 1=green, 2=red
imgR[:,:,1] = 0
# Set blue and green channels to 0
imgG[:,:,0] = 0
imgG[:,:,2] = 0
# Set red and green channels to 0
imgB[:,:,1] = 0
imgB[:,:,2] = 0
# Image reconstrution
img[:,:,0] = imgB[:,:,0]
img[:,:,1] = imgG[:,:,1]
img[:,:,2] = imgR[:,:,2]
# Creating a folder for the results and defining the path
path_result = path_base + '/5. Post-Processed images'
list = os.listdir(path_result)
nb folders = len(list) #We take a look at the number of tests already existing
\rightarrow in the destination folder
folder_name = 'Display_'+ str(nb_folders+1) #We assign a new number to the
\rightarrow current test
index = 1
os.mkdir(path_result + '/' + folder_name)
path_display = path_result + '/' + folder_name
```

```
dR = pd.DataFrame(imgR[:,:,2])
    dR.to_csv(path_display + '/R.csv',header=False, index=False)
    dG = pd.DataFrame(imgG[:,:,1])
    dG.to_csv(path_display + '/G.csv',header=False, index=False)
    dB = pd.DataFrame(imgB[:,:,0])
    dB.to_csv(path_display + '/B.csv',header=False, index=False)
    # Plot original image and RGB channels just to show we can sucessfully extract
     \rightarrow them
    cv2_imshow(original_img)
    cv2_imshow(imgR)
    cv2_imshow(imgG)
    cv2_imshow(imgB)
    #cv2_imshow(img)
    cv2.waitKey()
    print('Matrix dimensions =', rows_number, 'x', columns_number)
    # Plot prediction matrix
    my_data_to_crop = genfromtxt(path_base + '/4. Combinated images and matrixes/
     →Image_1_combination_clean.csv', delimiter=',')
    my_data = my_data_to_crop[0:rows_number, 0:columns_number]
    my_data[my_data == 2] = 1
    my_data[my_data == 6] = 2
    my data[my data == 4] = 3
    my_data[my_data == 0] = 1
    plt.imshow(my_data, interpolation='nearest')
    plt.show()
[ ]: #PART 3 - URBAN COOLING SCIENTIFIC DATA USED IN THIS STUDY
    #Canals temperature diminution:
    #0-30m: 1.2°C
    #Forests temperature diminution:
    #Remaining forest:
                              #Street trees:
                                                         #Isolated trees:
                              #(from 2 to 5 trees)
                                                        #(0 to 2 trees)
    #(more than 5 trees)
    #0-50:
             1.32°C
                                                         #0-50: 0.58°C
                              #0-50: 1.01°C
    #50-100: 1.14°C
                              #50-100: 0.94°C
                                                         #50-100:
                                                                    0.52°C
    #100-150: 0.57°C
                              #100-150: 0.73°C
                                                         #100-150: 0.22°C
    #150-200: 0.30°C
                              #150-200: 0.24°C
                                                         #150-200: 0.02°C
    #200-250: 0.16°C
                              #200-250: 0°C
                                                         #200-250: 0°C
    #250-300: 0.13°C
                               #250-300: 0°C
                                                          #250-300: 0°C
    #Average reception of carbon dioxide (CO2) per tree: 21 kg/year
```

Saving RGB channels into the previous folder

```
#Average tree surface in Bangkok: 60.73m^2 based on a study on the three most⊔
→ common tree species in Banqkok:
#Polyalthia longifolia Sonn
                                        (representing 15.7% of Bangkok trees) ->
\rightarrow Average diameter = 2.7432m -> Average surface = 5.91m<sup>2</sup>
                                         (representing 13.0% of Bangkok trees) \rightarrow
#Mangifera indica L.
\rightarrow Average diameter = 10m -> Average surface = 78.74m<sup>2</sup>
#Pithecellobium dulce (Roxb.) Benth. (representing 5.4% of Bangkok trees) ->_
\rightarrow Average diameter = 15m -> Average surface = 176.71m<sup>2</sup>
#Considering these are the only species of trees in Bangkok, 15.7% becomes 46.
\rightarrow 04\%, 13.0% becomes 38.12%, 5.4% becomes 15.84%
#Average surface of a tree in Bangkok according to this data: ((46.04/100)*5.
\rightarrow 91) + ((38.12/100)*78.74) + ((15.84/100)*176.71) = 60.727516 \text{ m}^2
# Defining sizes of "circles" to color around forest and canal areas respecting \Box
\rightarrow ri+1 > ri
R_rf = np.array([50, 100, 150, 200, 250, 300],ndmin=2)
                                                              #"rf" for remaining
\hookrightarrow forest
R \text{ st} = np.array([50, 100, 150, 200, 250, 300], ndmin=2)
                                                             #"st" for street trees
R_it = np.array([50, 100, 150, 200, 250, 300],ndmin=2)
                                                              #"it" for isolated
\rightarrow trees
R_ca = np.array([30],ndmin=2)
                                                               #"ca" for canals
# Defining temperature diminution influence of each forest and canal "circle"
T_rf = np.array([1.32, 1.14, 0.57, 0.30, 0.16, 0.13], ndmin=2)
T_st = np.array([1.01, 0.94, 0.73, 0.24, 0.00, 0.00], ndmin=2)
T_{it} = np.array([0.58, 0.52, 0.22, 0.02, 0.00, 0.00], ndmin=2)
T_{ca} = np.array([1.2],ndmin=2)
# Defining the average tree surface and its carbon reception
surface_tree = 60.73 #Tree surface in m^2
                     #Reception of carbon dioxide (CO2) per year and per tree
carbon_tree = 21
# Defining a scale between meters and pixels
scale = 1668/200 #200m = 1668 pixels
print('Done')
```

Done

```
# PART 4 - FINDING CLUSTERS

# Finding clusters in position matrix
def find_clusters(array, width, height):
    clustered = np.empty_like(array)
    unique_vals = np.unique(array)
    cluster_count = 0
    print(unique_vals)
```

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labelling = np.zeros((len(unique_vals), width, height)) #labelling = 3D_\_
 \rightarrow array, each level [n,:,:] containing all pixel positions and associated
 →cluster number of class number n
    #City class number = 1, Canal class number = 2, Forest class number = 3
   for val in unique vals:
        labelling[int(val-1)], label count = ndimage.label(array == val)
        for k in range(1, label_count + 1):
            clustered[labelling[int(val-1)] == k] = cluster count
            cluster_count += 1
   return clustered, cluster_count, labelling, len(unique_vals)
clusters, cluster_count, cluster_position, val_number =__
→find_clusters(mat_position, width, height)
print("Found {} clusters:".format(cluster_count))
ones = np.ones_like(mat_position, dtype=int)
cluster_sizes = ndimage.sum(ones, labels=clusters, index=range(cluster_count)).
→astype(int)
com = ndimage.center_of_mass(ones, labels=clusters, index=range(cluster_count))
# Creating a matrix to collect information about the size and position of \Box
→center of the different clusters #cluster_count = nb of clusters
Clust = np.zeros((cluster count,4))
for i, (size, center) in enumerate(zip(cluster sizes, com)):
   print("Cluster #{}: {} elements at {}".format(i, size, center))
   Clust[i,0] = i
   Clust[i,1] = round(size)
   Clust[i,2] = round(center[0]) #horizontal coordinate of center of cluster
   Clust[i,3] = round(center[1]) #vertical coordinate of center of cluster
Clust = Clust.astype(int)
# Saving pixel position inside the clusters under csv matrixes
for l in range(0, val_number):
   dcluster position = pd.DataFrame(cluster position[1,:,:])
   dcluster_position.to_csv(path_display + '/cluster_position_' + str(l+1) + '.
# Creating a matrix with the same dimension of the prediction matrix with the
→number of the corresponding cluster on each pixel
which clust = np.zeros((width,height))
\# Creating an array with the number of cluster for dimension to explicit what \sqcup
\hookrightarrow class is associated to this cluster
max_city = int(np.amax(cluster_position[0,:,:]))
max_canal = int(np.amax(cluster_position[1,:,:]))
max_forest = int(np.amax(cluster_position[2,:,:]))
max_tot = max_city + max_canal + max_forest
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which_class = np.zeros((max_tot))
print('\nThere are:\n',max_city,'cluster(s) of city\n', max_canal,'cluster(s)__

→of canals\n', max_forest, 'cluster(s) of forests')
# Filling the previous two matrixes
for a in range(1, max city+1):
  which clust[cluster position[0,:,:] == a] = a-1
 which_class[a-1] = 1 #city
for b in range(1, max_canal+1):
 which_clust[cluster_position[1,:,:] == b] = max_city+b-1
  which_class[max_city+b-1] = 2 #canal
for c in range(1, max_forest+1):
  which_clust[cluster_position[2,:,:] == c] = max_city+max_canal+c-1
  which_class[max_city+max_canal+c-1] = 3 #forest
# Adding to the Clust matrix the associated class number to each cluster and L
→ displaying this matrix
which_class = which_class.astype(int)
Clust = np.concatenate((Clust, which_class[:, None]), axis=1)
print('\nThe following matrix shows the number of the cluster, its size, its⊔
→center x and y positions and its associated class:\n', Clust)
print('assuming 1 = city, 2 = canal, 3 = forest')
# Saving the matrix with the number of the corresponding cluster on each pixel
dwhich clust = pd.DataFrame(which clust)
dwhich_clust.to_csv(path_display + '/which_clust.csv',header=False, index=False)
# For Part 6, defining which temperature diminution value to use according to \Box
→ the forest area size (isolated tree or street trees or remaining forests)
which_coef = np.ones((width, height))
# Studying the size of the clusters
for k in range(0, cluster count):
  if (Clust[k,4] == 3): #If the cluster is a cluster of forest
    clust size sqrt = round((200/1668)*np.sqrt(Clust[k,1]))
    clust_size = np.square(clust_size_sqrt)
    surface_tree = 60.73 #Tree surface in m^2
    nb_tree = float(round(10*float(clust_size/surface_tree))/10) #Truncating_
→ the float number to 1 significant digit
    # Deciding which temperature diminution value to use for each pixel_{\sqcup}
→ depending of the size of its cluster
    if (nb tree > 5):
      which_coef[which_clust == k] = 1
    if (2 <= nb tree <= 5):
      which_coef[which_clust == k] = 2
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if (0 < nb_tree < 2):</pre>
      which_coef[which_clust == k] = 3
which_coef = which_coef.astype(int)
# Saving the previous matrix
dwhich_coef = pd.DataFrame(which_coef)
dwhich_coef.to_csv(path_display + '/which_coef.csv',header=False, index=False)
[1. 2. 3.]
Found 63 clusters:
Cluster #0: 2067678 elements at (664.1320998724173, 1447.2088835882569)
Cluster #1: 3 elements at (0.0, 598.0)
Cluster #2: 3 elements at (0.0, 606.0)
Cluster #3: 3 elements at (14.0, 598.0)
Cluster #4: 3 elements at (14.0, 606.0)
Cluster #5: 2 elements at (15.0, 0.5)
Cluster #6: 2 elements at (15.0, 12.5)
Cluster #7: 1 elements at (18.0, 63.0)
Cluster #8: 2 elements at (20.0, 0.5)
Cluster #9: 2 elements at (20.0, 12.5)
Cluster #10: 1 elements at (22.0, 63.0)
Cluster #11: 2 elements at (25.0, 12.5)
Cluster #12: 2 elements at (30.0, 12.5)
Cluster #13: 2 elements at (57.0, 48.5)
Cluster #14: 2 elements at (62.0, 48.5)
Cluster #15: 2 elements at (79.5, 2527.0)
Cluster #16: 2 elements at (84.5, 2527.0)
Cluster #17: 3 elements at (93.0, 2527.0)
Cluster #18: 256 elements at (342.5, 231.5)
Cluster #19: 6 elements at (383.5, 759.0)
Cluster #20: 6 elements at (383.5, 766.0)
Cluster #21: 6 elements at (397.5, 759.0)
Cluster #22: 6 elements at (397.5, 766.0)
Cluster #23: 1 elements at (399.0, 996.0)
Cluster #24: 1 elements at (399.0, 1000.0)
Cluster #25: 1 elements at (399.0, 1004.0)
Cluster #26: 7430 elements at (506.3520861372813, 2554.7600269179)
Cluster #27: 6 elements at (494.0, 2482.5)
Cluster #28: 7448 elements at (594.3088077336198, 2400.623523093448)
Cluster #29: 9 elements at (563.0, 2303.0)
Cluster #30: 3 elements at (587.0, 2303.0)
Cluster #31: 3 elements at (593.0, 2303.0)
Cluster #32: 4 elements at (623.5, 288.5)
Cluster #33: 4 elements at (629.5, 288.5)
Cluster #34: 4 elements at (635.5, 288.5)
Cluster #35: 4 elements at (641.5, 288.5)
Cluster #36: 7 elements at (690.0, 1583.0)
Cluster #37: 60 elements at (808.5, 333.0)
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Cluster #38: 4 elements at (816.5, 176.0)
Cluster #39: 4 elements at (823.5, 176.0)
Cluster #40: 58232 elements at (1063.372990795439, 97.65153180381921)
Cluster #41: 4 elements at (943.5, 208.5)
Cluster #42: 4 elements at (951.5, 208.5)
Cluster #43: 4 elements at (957.5, 208.5)
Cluster #44: 4 elements at (963.5, 208.5)
Cluster #45: 2 elements at (968.0, 208.5)
Cluster #46: 2 elements at (974.0, 208.5)
Cluster #47: 1 elements at (1186.0, 378.0)
Cluster #48: 1 elements at (1186.0, 384.0)
Cluster #49: 326384 elements at (647.1230238001863, 202.40672030491692)
Cluster #50: 426687 elements at (246.97639487493174, 1018.0501772962382)
Cluster #51: 70 elements at (113.0, 184.5)
Cluster #52: 256 elements at (182.5, 1511.5)
Cluster #53: 10143 elements at (663.4031351671103, 1568.675145420487)
Cluster #54: 1536 elements at (910.5, 1767.5)
Cluster #55: 256 elements at (1014.5, 1847.5)
Cluster #56: 17364 elements at (93.1846348767565, 2270.173923059203)
Cluster #57: 189722 elements at (464.0891778496959, 2457.735945225119)
Cluster #58: 512 elements at (542.5, 2599.5)
Cluster #59: 10496 elements at (1124.5487804878048, 1151.3048780487804)
Cluster #60: 1040 elements at (1186.2230769230769, 631.6538461538462)
Cluster #61: 772 elements at (1190.6088082901554, 279.9300518134715)
Cluster #62: 512 elements at (1190.5, 1919.5)
```

There are:

49 cluster(s) of city
7 cluster(s) of canals
7 cluster(s) of forests

The following matrix shows the number of the cluster, its size, its center x and y positions and its associated class:

]]	0 20	067678	664	1447	1]
[1	3	0	598	1]
[2	3	0	606	1]
[3	3	14	598	1]
[4	3	14	606	1]
[5	2	15	0	1]
[6	2	15	12	1]
[7	1	18	63	1]
[8	2	20	0	1]
[9	2	20	12	1]
[10	1	22	63	1]
[11	2	25	12	1]
[12	2	30	12	1]
[13	2	57	48	1]
[14	2	62	48	1]

[15	2	80	2527	1]
[16	2	84	2527	1]
[17	3	93	2527	1]
[18	256	342	232	1]
[19	6	384	759	1]
[20	6	384	766	1]
[21	6	398	759	1]
[22	6	398	766	1]
[23	1	399	996	1]
[24	1	399	1000	1]
[25	1	399	1004	1]
[26	7430	506	2555	1]
[27	6	494	2482	1]
[28	7448	594	2401	1]
[29	9	563	2303	1]
[30	3	587	2303	1]
[31	3	593	2303	1]
[32	4	624	288	1]
[33	4	630	288	1]
[34	4	636	288	1]
[35	4	642	288	1]
[36	7	690	1583	1]
[37	60	808	333	1]
[38	4	816	176	1]
[39	4	824	176	1]
[40	58232	1063	98	1]
[41	4	944	208	1]
[42	4	952	208	1]
[43	4	958	208	1]
[44	4	964	208	1]
[45	2	968	208	1]
[46	2	974	208	1]
[47	1	1186	378	1]
[48	1	1186	384	1]
[49	326384	647	202	2]
[50	426687	247	1018	2]
[51	70	113	184	2]
[52	256	182	1512	2]
[53	10143	663	1569	2]
[54	1536	910	1768	2]
[55	256	1014	1848	2]
[56	17364	93	2270	3]
[57	189722	464	2458	3]
[58	512	542	2600	3]
[59	10496	1125	1151	3]
[60	1040	1186	632	3]
[61	772	1191	280	3]
[62	512	1190	1920	3]]
-	7-	712			0,1

```
[]: # PART 5 - CREATING MATRIXES FOR FORESTS AND CANALS CONTAINING ALL "CIRCLES"
     → INFORMATION (SIZE, COLOR, ASSOCIATED TEMPERATURE DIMINUTION)
     # Color definition for display using rgb code #f means forest, c means canal
     c0r_c, c0g_c, c0b_c = 0, 76, 153 #blue rgb code
     c0r_f, c0g_f, c0b_f = 0, 102, 0 #green rgb code
     # Color definition for shading
     inicolor_f = [255,215,0] #Initial RGB color #[255,215,0] = Yellow
     fincolor_f = [255,127,80] #Final RGB color #[255,127,80] = Orange
     inicolor_c = [218,165,32] #Initial RGB color #[218,165,32] = Golden yellow
     fincolor_c = [184,184,11] #Final RGB color #[184,184,11] = Dark golden yellow
     # Creating a matrix R_f for forest "circles" sizes information
     R_f_meters_T = np.concatenate((R_rf,R_st,R_it))
     R_f_T = np.matrix.round(R_f_meters_T*scale) #Conversion meters to pixels
     R f = np.matrix.transpose(R f T)
     \# Creating a matrix R_c for canal "circles" sizes information
     R c meters T = R ca
     R_c_T = np.matrix.round(R_c_meters_T*scale) #Conversion meters to pixels
     R_c = np.matrix.transpose(R_c_T)
     # Creating a matrix T_f for forest temperature diminution information
     T_f_T = np.concatenate((T_rf,T_st,T_it))
     T_f = np.matrix.transpose(T_f_T)
     \# Creating a matrix T c for canal temperature diminution information
     T_c_T = T_ca
     T_c = np.matrix.transpose(T_c_T)
     \#print(R_f, ' \ n \ n', T_f, ' \ n \ n', R_c, ' \ n \ n', T_c)
     # Defining the number of tree categories (remaining forest, street trees, u
     \rightarrow isolated trees)
     nb_tree_types = len(R_f[0])
     # Number of outlines for forests and canals areas = number of steps for shading
     step_f = len(R_f)
     step_c = len(R_c)
     # Creating matrixes that we will use in a loop to create the shading
     shade_f = np.zeros((3,1))
                                            #3 rows because 3 channels (RGB)
     mat shade f T = np.zeros((3, step f))
     shade_c = np.zeros((3,1))
    mat shade c T = np.zeros((3, step c))
```

```
# Loop to shade step by step the "circles" color from original color to final
\hookrightarrow color
if (step f > 1): #Loop for forest circles
  for i in range(0,3): #0=R, 1=G, 2=B
    if (inicolor f[i] >= fincolor f[i]):
      shade_f[i] = inicolor_f[i] + (inicolor_f[i] - fincolor_f[i])/(step_f-1)
      for j in range(0,step_f):
        shade_f[i] = shade_f[i] - (inicolor_f[i] - fincolor_f[i])/(step_f-1)
        mat_shade_f_T[i,j] = shade_f[i]
    else:
      shade_f[i] = inicolor_f[i] - (fincolor_f[i] - inicolor_f[i])/(step_f-1)
      for j in range(0,step_f):
        shade_f[i] = shade_f[i] + (fincolor_f[i] - inicolor_f[i])/(step_f-1)
        mat_shade_f_T[i,j] = shade_f[i]
else: #If there is only one circle, the color to display = final color
  for i in range(0,3):
    shade_f[i] = fincolor_f[i]
    for j in range(0,step_f):
      mat_shade_f_T[i,j] = shade_f[i]
if (step_c > 1): #Loop for canal circles
  for i in range(0,3):
    if (inicolor_c[i] >= fincolor_c[i]):
      shade_c[i] = inicolor_c[i] + (inicolor_c[i] - fincolor_c[i])/(step_c-1)
      for j in range(0,step_c):
        shade_c[i] = shade_c[i] - (inicolor_c[i] - fincolor_c[i])/(step_c-1)
        mat_shade_c_T[i,j] = shade_c[i]
      shade_c[i] = inicolor_c[i] - (fincolor_c[i] - inicolor_c[i])/(step_c-1)
      for j in range(0,step_c):
        shade_c[i] = shade_c[i] + (fincolor_c[i] - inicolor_c[i])/(step_c-1)
        mat_shade_c_T[i,j] = shade_c[i]
else: #If there is only one circle, the color to display = final color
  for i in range(0,3):
    shade_c[i] = fincolor_c[i]
    for j in range(0,step c):
      mat_shade_c_T[i,j] = shade_c[i]
# Rounding and transposing the shading matrixes
mat_shade_f = np.matrix.round(np.matrix.transpose(mat_shade_f_T))
mat_shade_c = np.matrix.round(np.matrix.transpose(mat_shade_c_T))
# Gathering all the information in one matrix Dm f for forest and Dm c for
\hookrightarrow canals
Om_f_T = np.concatenate((mat_shade_f_T, R_f_T, T_f_T))
```

```
Om f = np.matrix.transpose(Om f T) # Forests outline matrix #(number of D)
 →outlines, thickness and rqb channels)
#Om_f = Om_f.astype(int) #Convert float matrix to int matrix
#print('Om f matrix: RGB channels ( 3 columns ), Outline sizes
 → (',nb_tree_types, 'columns'), Temperature diminutions
 → (',nb tree types, 'columns )')
Om_c_T = np.concatenate((mat_shade_c_T, R_c_T, T_c_T))
Om_c = np.matrix.transpose(Om_c_T) # Canals outline matrix #(number of_
 →outlines, thickness and rgb channels)
#Om_c = Om_c.astype(int) #Convert float matrix to int matrix
#print('Om_c matrix: RGB channels ( 3 columns ), Outline sizes ( 1 column ), ا
 → Temperature diminutions (1 column )')
# Print validation of model setting
print('Model setting done.\n')
print('Forest RGB channels:\n',mat_shade_f,'\n\nForest circle sizes (m):\n',(np.
 →matrix.round(R_f*200/1668)).astype(int),'\n\nForest temperature diminutions_
 \hookrightarrow (°C):\n',T_f,'\n\n')
print('Canal RGB channels:\n',mat_shade_c,'\n\nCanal circle sizes (m):\n',(np.
 →matrix.round(R_c*200/1668)).astype(int), '\n\nCanal temperature diminutions<sub>□</sub>
 \hookrightarrow (°C):\n',T_c)
Model setting done.
Forest RGB channels:
 [[255. 215.
               0.1
 [255. 197. 16.]
 [255. 180. 32.]
 [255. 162. 48.]
 [255. 145. 64.]
 [255. 127. 80.]]
Forest circle sizes (m):
 [[ 50 50 50]
 [100 100 100]
 [150 150 150]
 [200 200 200]
 [250 250 250]
 [300 300 300]]
Forest temperature diminutions (°C):
 [[1.32 1.01 0.58]
 [1.14 0.94 0.52]
 [0.57 0.73 0.22]
 [0.3 0.24 0.02]
 [0.16 0.
            0. ]
 [0.13 0.
            0. 11
```

```
Canal RGB channels:
     [[184. 184. 11.]]
    Canal circle sizes (m):
     [[30]]
    Canal temperature diminutions (°C):
     [[1.2]]
[]: # PART 6 - COLORATION
     # Extracting number of pixels of forest and number of pixels of canal
     tot_f, tot_c = 0.0
     for k in range (0,cluster_count):
       if (Clust[k,4] == 2):
         tot_c = tot_c + Clust[k,1]
       if (Clust[k,4] == 3):
         tot_f = tot_f + Clust[k,1]
     # Extracting pixel positions of forests and canals
     print('Extracting canal and forest pixels positions...')
     forest = np.zeros((tot_f,2))
     canal = np.zeros((tot_c,2))
    m = 0
     n = 0
     1 = 0
     for i in range(0, width, 1): #start, stop, step
       for j in range(0, height, 1):
         if (mat_position[i,j] == 3):
           forest[m,0] = i
           forest[m,1] = j
           m = m+1
         if (mat_position[i,j] == 2):
           canal[n,0] = i
           canal[n,1] = j
           n = n+1
     forest = forest.astype(int)
     canal = canal.astype(int)
     dforest = pd.DataFrame(forest)
     dforest.to_csv(path_display + '/position_forest.csv',header=False, index=False)
     dcanal = pd.DataFrame(canal)
     dcanal.to_csv(path_display + '/position_canal.csv',header=False, index=False)
     # Creating a matrix with a Treated/Non-treated parameter for each pixel to_{\sqcup}
      →avoid treating the same pixels several times
```

```
pixel_already_treated = np.zeros((width, height)) #0 means non-treated, other_
\rightarrowmeans treated
# Associating maximum temperature diminution +100 to forest and canal areas,
→pixels in pixel_already_treated to be sure they won't be colored as "circles"
pixel_already_treated[mat_position==3] = max(np.amax(T_f),np.amax(T_c)) + 100
pixel_already_treated[mat_position==2] = max(np.amax(T_f),np.amax(T_c)) + 100
# Extracting forest edges to gain time for the next step
# We create a matrix with i, j coordonates of "edge pixels" longer than
→necessary because we don't know yet the length and then we crop the empty !!
edge_f = np.zeros((tot_f,2)) # We use tot_f here because we know tot_f is
obviously superior to the number of "edge pixels" (that we don't know yet)
f = 0
print('Extracting forest edges...')
for m in range(0, tot_f, 1): #start, stop, step
    i = forest[m, 0]
    j = forest[m, 1]
    cond = 0 # This condition is aimed at gaining time by quiting the loop when
→at least one pixel of non-canal and non-forest is found next to the current
→ forest pixel
    a = 0
    while (a < 360) and (cond != 1):
      alpha = np.radians(a)
     x = i + round(np.cos(alpha))
      y = j+ round(np.sin(alpha))
      a = a + 1
      if ((0 < (x) < width) and (0 < (y) < height)
      and (pixel_already_treated[x, y] == 0)): # If there is a pixel which is
\rightarrowneither canal nor forest just next to the current forest pixel then this is
 \rightarrow an edge pixel
        edge_f[f,0] = i
        edge_f[f,1] = j
        f = f + 1
        cond = 1
        \#imgR[:,:,2][i,j] = c0r_c \#useful to color the edge to check if it works
        \#imgG[:,:,1][i,j] = cOg_c
        \#imgB[:,:,0][i,j] = c0b_c
# Extracting canal edges to gain time for the next step
# We create a matrix with i, j coordonates of "edge pixels" longer than
→necessary because we don't know yet the length and then we crop the empty ____
edge_c = np.zeros((tot_c,2)) # We use tot_c here because we know tot_c is_\square
→obviously superior to the number of "edge pixels" (that we don't know yet)
```

```
c = 0
print('Extracting canal edges...')
for n in range(0, tot_c, 1): #start, stop, step
    i = canal[n,0]
    j = canal[n,1]
    cond = 0 # This condition is aimed at gaining time by quiting the loop when ⊔
→at least one pixel of non-canal and non-forest is found next to the current
 \rightarrow forest pixel
    a = 0
    while (a < 360) and (cond != 1):
      alpha = np.radians(a)
     x = i + round(np.cos(alpha))
      y = j+ round(np.sin(alpha))
      a = a + 1
      if ((0 < (x) < width) and (0 < (y) < height)
      and (pixel_already_treated[x, y] == 0)): # If there is a pixel which is \square
\rightarrowneither canal nor forest just next to the current forest pixel then this is \sqcup
\rightarrowan edge pixel
        edge_c[c,0] = i
        edge_c[c,1] = j
        c = c + 1
        cond = 1
        \#imqR[:,:,2][i,j] = cOr_c \#useful to color the edge to check if it works
        \#imgG[:,:,1][i,j] = cOg_c
        \#imqB[:,:,0][i,j] = c0b_c
# Cropping all empty rows in order to keep just the "edge pixels" positions
edge_f = edge_f.astype(int)
mask_f = edge_f == 0
rows_f = np.flatnonzero((~mask_f).sum(axis=1))
cols_f = np.flatnonzero((~mask_f).sum(axis=0))
edge_f = edge_f[rows_f.min():rows_f.max()+1, cols_f.min():cols_f.max()+1]
# Cropping all empty rows in order to keep just the "edge pixels" positions
edge_c = edge_c.astype(int)
mask_c = edge_c == 0
rows_c = np.flatnonzero((~mask_c).sum(axis=1))
cols_c = np.flatnonzero((~mask_c).sum(axis=0))
edge_c = edge_c[rows_c.min():rows_c.max()+1, cols_c.min():cols_c.max()+1]
# Saving previous matrixes
dedge_f = pd.DataFrame(edge_f)
dedge_f.to_csv(path_display + '/edge_f.csv',header=False, index=False)
dedge_c = pd.DataFrame(edge_c)
dedge_c.to_csv(path_display + '/edge_c.csv',header=False, index=False)
# Extracting forest circle pixels
```

```
d_f_m1 = 0
for l in range(0,step_f,1):
 print('Coloration of forest circle number', l+1, '/', step_f,'...')
  for m in range(0, f):
   i = edge_f[m,0]
    j = edge_f[m, 1]
    d_f = int(Om_f[1, 2+which_coef[i,j]])
    if (1 >= 1):
      d f m1 = int(Om f[1-1, 2+which coef[i,j]])
    t_f = Om_f[1, 2+nb_tree_types+which_coef[i,j]]
    for d in range(d f m1,d f):
      a = 0
      while (a < 360):
        alpha = np.radians(a)
        x = i + round(d *np.cos(alpha))
        y = j+ round(d *np.sin(alpha))
        a = a + 1 #Increase a < 360 to gain execution rapidity but losing
\rightarrowprecision of coloration
        if ((0 < (x) < width) and (0 < (y) < height)
        and (pixel_already_treated[x, y] < t_f)):</pre>
          pixel already treated[x, y] = t f
  dpixel_already_treated = pd.DataFrame(pixel_already_treated)
  dpixel_already_treated.to_csv(path_display + '/

-pixel_already_treated_'+str(l+1)+'.csv',header=False, index=False)

  print('pixel_already_treated_',l+1, 'saved')
# Extracting canal circle pixels
d c m1 = 0
for 1 in range(0,step_c):
 print('Coloration of canal circle number',l+1,'/',step_c,'...')
 for n in range(0, c, 1):
    i = edge_c[n, 0]
    j = edge_c[n,1]
    d c = int(Om c[1, 3])
    if (1>=1):
     d_c_m1 = int(0m_c[1-1, 3])
    t_c = Om_c[1, 4]
    for d in range(d_c_m1,d_c):
      a = 0
      while (a < 360):
        alpha = np.radians(a)
        x = i + round(d *np.cos(alpha))
        y = j + round(d *np.sin(alpha))
        a = a + 1 #Increase a < 360 to gain execution rapidity but losing
 →precision of coloration
        if ((0 < (x) < width) and (0 < (y) < height)
        and (pixel_already_treated[x, y] < t_c)):</pre>
```

```
pixel_already_treated[x, y] = t_c
  dpixel_already_treated = pd.DataFrame(pixel_already_treated)
  dpixel_already_treated.to_csv(path_display + '/
 →pixel_already_treated_'+str(step_f+l+1)+'.csv',header=False, index=False)
  print('pixel_already_treated_',step_f+l+1, 'saved')
# Coloring forest "circles"
for u in range(0,step f):
  for v in range(0, nb_tree_types):
    if (Om_f[u, 3+nb_tree_types+v] != 0):
       imgR[:,:,2][pixel_already_treated == Om_f[u, 3+nb_tree_types+v]] = __
 \rightarrow Om_f[u, 0]
       imgG[:,:,1][pixel_already_treated == Om_f[u, 3+nb_tree_types+v]] =_u
 \rightarrow 0m_f[u, 1]
       imgB[:,:,0][pixel_already_treated == Om_f[u, 3+nb_tree_types+v]] =_
 \rightarrow 0m_f[u, 2]
# Coloring canal "circles"
for u in range(0,step_c):
  if (Om c[u, 4] != 0):
    imgR[:,:,2][pixel_already_treated == Om_c[u, 4]] = Om_c[u, 0]
     imgG[:,:,1][pixel_already_treated == Om_c[u, 4]] = Om_c[u, 1]
    imgB[:,:,0][pixel_already_treated == Om_c[u, 4]] = Om_c[u, 2]
# Re-associating the correct temperature diminution to forest and canal areas_
 →pixels in pixel_already_treated after they didn't get colored as "circles"
pixel_already_treated[mat_position==3] = np.amax(T_f)
pixel already treated[mat position==2] = np.amax(T c)
# Forests and canals coloration
imgR[:,:,2][mat_position==3] = cOr_f
imgG[:,:,1][mat_position==3] = c0g_f
imgB[:,:,0][mat position==3] = c0b f
imgR[:,:,2][mat_position==2] = cOr_c
imgG[:,:,1][mat_position==2] = c0g_c
imgB[:,:,0][mat_position==2] = c0b_c
#Saving previous matrixes
dpixel_already_treated = pd.DataFrame(pixel_already_treated)
dpixel_already_treated.to_csv(path_display + '/pixel_already_treated_final.
 ⇔csv',header=False, index=False)
Extracting canal and forest pixels positions...
Extracting forest edges...
Extracting canal edges...
Coloration of forest circle number 1 / 6 ...
Coloration of forest circle number 2 / 6 ...
```

```
Coloration of forest circle number 3 / 6 \dots Coloration of forest circle number 4 / 6 \dots Coloration of forest circle number 5 / 6 \dots Coloration of forest circle number 6 / 6 \dots Coloration of canal circle number 1 / 1 \dots
```

```
[ ]: # PART 7 - IMAGE RECONSTRUCTION AND PLOT
     # Erasing colors on canals and forests
     #ih = cv2.imread(path_base + '/Image 1.jpg')[0:rows_number, 0:columns_number]
     #ihR = cv2.imread(path base + '/Image 1.jpq')[0:rows number, 0:columns number]
     #ihG = cv2.imread(path_base + '/Image 1.jpg')[0:rows_number, 0:columns_number]
     #ihB = cv2.imread(path_base + '/Image 1.jpg')[0:rows_number, 0:columns_number]
     #wid, hei, nb co = ih.shape
     #imge = np.zeros((wid,hei,nb_co))
     \#ihR[:,:,0] = 0
                             # X, Y, Z # O=blue, 1=green, 2=red
     #ihR[:,:,1] = 0
     \#ihG[:,:,0] = 0
     #ihG[:,:,2] = 0
     \#ihB[:,:,1] = 0
     \#ihB[:,:,2] = 0
     \#imqR[:,:,2][mat\_position==3] = ihR[:,:,2][mat\_position==3]
     \#imgG[:,:,1][mat\_position==3] = ihG[:,:,1][mat\_position==3]
     \#imqB[:,:,0][mat\ position==3] = ihB[:,:,0][mat\ position==3]
     \#imgR[:,:,2][mat\_position==2] = ihR[:,:,2][mat\_position==2]
     \#imgG[:,:,1][mat\ position==2] = ihG[:,:,1][mat\ position==2]
     \#imgB[:,:,0][mat\_position==2] = ihB[:,:,0][mat\_position==2]
     # Image reconstrution
     img[:,:,0] = imgB[:,:,0]
     img[:,:,1] = imgG[:,:,1]
     img[:,:,2] = imgR[:,:,2]
     # Transparency of display
     alpha = 0.2 # transparency to change # alpha between 0 et 1
     beta = (1 - alpha)
     # Overlaying the two images with transparency
     cv ori = original img.astype(np.uint8)
     cv_img = img.astype(np.uint8)
     added image = cv2.addWeighted(cv ori,alpha,cv img,beta,0)
     # Plot
     print('\n','Original image:')
     cv2_imshow(original_img)
     cv2.waitKey()
     #print('\n', 'Recolored image without transparency:')
```

```
#cv2_imshow(cv_imq)
     #cv2.waitKey()
     print('\n','Recolored image with transparency at',str(int(alpha*100)),'%.')
     cv2_imshow(added_image)
     cv2.waitKey()
     # Saving result image
     result = cv2.imwrite(path_display + '/image_' + str(index_save) + '_Combined.
     →jpg', added_image)
     if (result == True):
      print('Combined image saved successfully')
     else:
      print('Combined in saving file')
     index_save = index_save + 1
[]: | # PART 8 - WRITE CO2 CAPTATION ON THE PREVIOUS IMAGE WITH CV2
     # Reinitialising the image to the Part 7 one
     alpha = 0.1
     beta = 1 - alpha
     cv_ori = original_img.astype(np.uint8)
     cv_img = img.astype(np.uint8)
     added_image = cv2.addWeighted(cv_ori,alpha,cv_img,beta,0)
     # Defining the font parameters
     FONT = cv2.FONT_HERSHEY_SIMPLEX
```

```
FONT_SCALE = 1
                 #Font size
FONT THICKNESS = 2 #Font thickness
label_color = (0, 0, 0)
# Defining parameters for the rectangle around the text
color = (255, 255, 255) #BGR
thickness = -1 # Line thickness in px, -1 = filled
# Writing the CO2 captation of each cluster on its center
tot_carbon = 0
for k in range(0, cluster_count):
  if (mat_position[Clust[k,2],Clust[k,3]] == 3): #If the cluster is a cluster_
→of trees
    # Calculating the number of trees within the area
    clust_w, clust_h = round((200/1668)*np.sqrt(Clust[k,1])), round((200/
\hookrightarrow1668)*np.sqrt((Clust[k,1])))
    clust_area = clust_w*clust_h
    print('Cluster surface:', clust_area , 'm^2')
    nb_tree = float(round(10*float(clust_area/surface_tree))/10) #Truncating_
 → the float number to 1 significant digit
```

```
print('Considering an average tree surface of 60.73m<sup>2</sup> in Bangkok, the⊔
 →estimation of the number of trees within the area is: ',nb tree,'tree(s).')
   carbon_area = carbon_tree * nb_tree
   print('Considering an average CO2 reception around 21 kilograms per year,
 \rightarrowand per tree, the estimation of the CO2 reception within the area is:
→', carbon area, 'kg/year.')
   tot_carbon = tot_carbon + carbon_area
    # Calculating the position to display the text
   label = str(carbon_area) + 'kg/year' #Text to display
    (label_height, label_width), baseline = cv2.getTextSize(label, FONT,
→FONT SCALE, FONT THICKNESS)
   x = round(Clust[k,3] - label_height/2)
                                             #left
   y = round(Clust[k,2] + label_width/2) #low (by default it is writting in_
 → (0, label_height) so on its lower left corner)
    # The following conditions are aimed at displaying the text within the
\rightarrow image frame
   if (x < 0):
     x = 0
   elif (round(x + label_height) > height):
     x = height - label_height
   if (y < 0):
     y = label_width
   elif (y - label_width > width):
     y = Clust[k, 2]
   # Draw a rectangle around the text
   start_point = (x, y-label_width - 2) #represents the top left corner of u
\rightarrowrectangle
   end_point = (x+label_height, y + 4) #represents the bottom right corner of_
\rightarrowrectangle
   cv2.rectangle(added_image, start_point, end_point, color, thickness)
    # Write text according to the previous information
    cv2.putText(added image, label, (x, y), FONT, FONT SCALE, label color,
→FONT_THICKNESS)
# Display the result image
cv2_imshow(added_image)
cv2.waitKey(0)
# Saving result image
resul = cv2.imwrite(path_display + '/image_' + str(index) +__
if (resul == True):
```

```
print('Combined image saved successfully')
else:
  print('Error in saving combined image')
index = index + 1
```