

# Dario Serrano

Toronto, Canada — +1 (416) 459-3669 — [dario.serrano@mail.utoronto.ca](mailto:dario.serrano@mail.utoronto.ca) — [linkedin.com/in/darioserrano1213](https://linkedin.com/in/darioserrano1213)

Authorized to work in the U.S. (Citizen), EU (Citizen) and Canada (Work Permit)

## PROFILE

Mechanical Engineering student at the University of Toronto with experience in mechanical design (SolidWorks, ANSYS, Creo, MATLAB) and applied AI (PyTorch). Seeking a 12–16 month co-op/internship (2026) in Mechanical/Mechatronics Engineering, with strong interest in AI-driven systems and analytical modeling.

## EDUCATION

University of Toronto, Toronto, ON	2023–2027
B.A.Sc. Mechanical Engineering + PEY Co-op	
Minor: Robotics & Mechatronics — Certificates: Engineering Business, AI Engineering	
Teams: U of T Baja (Suspension) — U of T Racing (Chassis Design)	

High school distinctions: International Math Modeling Competition (IMMC) top 3 percent, Physics Bowl National Gold

## ENGINEERING EXPERIENCE

Engineering Intern — Schindler Group	Jul–Aug 2024
Shanghai, China	
<ul style="list-style-type: none"><li>Modeled <b>Ω-Beam</b> and <b>L-Beam</b> parts in Creo; performed <b>FEA</b> under <b>FKM</b> guidelines.</li><li>Built <b>MATLAB ODE</b> models to analyze oscillations and validate simulation accuracy.</li><li>3D-printed prototypes on industrial systems for rapid iteration.</li></ul>	

Androgynous Spacecraft Docking Mechanism — Kinematics and Dynamics of Machines	Sep–Dec 2025
Toronto, ON	
<ul style="list-style-type: none"><li>Built a <b>parametric CAD model</b> of a <b>6-arm variable-angle rough-alignment mechanism</b> for a microsatellite docking interface.</li><li>Wrote <b>MATLAB kinematic and static analysis code</b> to compute docking cone half-angle over <b>0.40–0.45 m slider travel</b> and resolve forces under a <b>6 kN axial docking load (1000 N per arm)</b>.</li><li>Solved a <b>6×6 equilibrium system</b> to compute joint reactions and required <b>slider actuator force ≈ 2.17 kN</b>, and implemented <b>Jacobian-based force mapping</b> for Stewart-platform actuator loads.</li></ul>	

CNC Mill Design Project — Mechanical Engineering Design	Sep–Dec 2024
Toronto, ON	
<ul style="list-style-type: none"><li>Designed a <b>functional CNC mill</b> in SolidWorks targeting hobbyist users.</li><li>Ran cost–performance analysis and evaluated design candidates for manufacturability.</li></ul>	

## AI & ANALYTICAL PROJECTS

Seizure Detection with CNN–LSTM — Applied Fundamentals of Deep Learning	May–Sep 2025
Toronto, ON	
<ul style="list-style-type: none"><li>Built a <b>CNN–LSTM</b> model in <b>PyTorch</b> to classify EEG seizure data (CHB-MIT dataset).</li><li>Implemented preprocessing: <b>Butterworth filtering</b>, <b>wavelet denoising</b>, sliding-window segmentation.</li><li>Achieved <b>AUROC 0.96</b> and <b>F1-score 0.84</b>; strong generalization on unseen data.</li></ul>	

Research on Rocket Optimization	Jun–Oct 2022
Remote	
<ul style="list-style-type: none"><li>Published “<i>Applications of Optimization Techniques for Solid Rocket Design</i>” (Darcy &amp; Roy Press).</li><li>Applied <b>numerical optimization</b> for propulsion performance. DOI: <a href="https://doi.org/10.54097/hset.v38i.5936">10.54097/hset.v38i.5936</a></li></ul>	

## OTHER EXPERIENCE

Private Tutor — Freelance	May 2023–Present
Hybrid (China, U.S.)	
<ul style="list-style-type: none"><li>Tutored 50+ international students (Physics, Math, Chemistry, English AP/IB); emphasis on analytical problem-solving.</li></ul>	

## TECHNICAL SKILLS

**Design & Simulation:** SolidWorks, Creo, ANSYS, 3D Printing, Machining

**Programming:** Python, PyTorch, MATLAB, NumPy, pandas, SciPy

**Other:** Microsoft Office, Minitab    **Languages (Native Speaker):** English, Mandarin, Shanghainese

**Reference:** Available upon request from Daryoush Ziai, CEO — Schindler Asia Pacific.