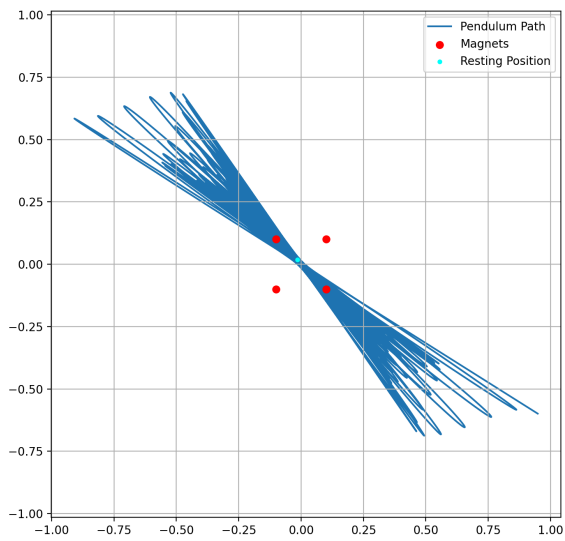
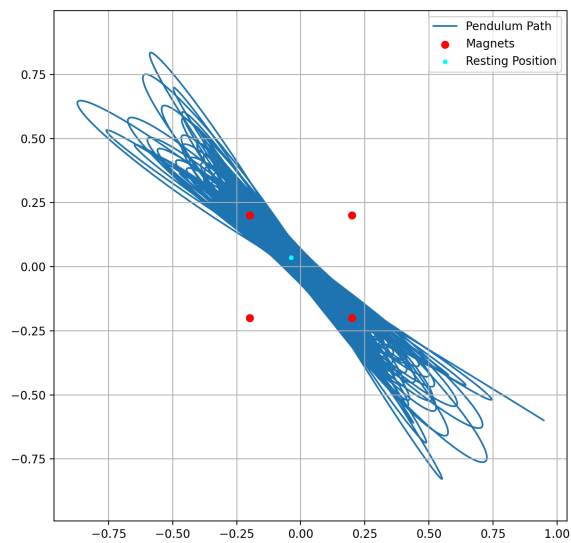


Randomly-chosen initial position : [0.9, -0.6]
Fixed pendulum length = 0.5
Damping constant (b) = 0.05

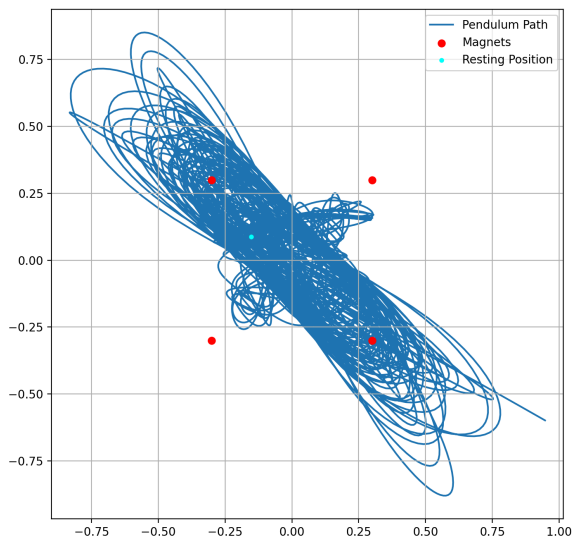
Radius = 0.1:



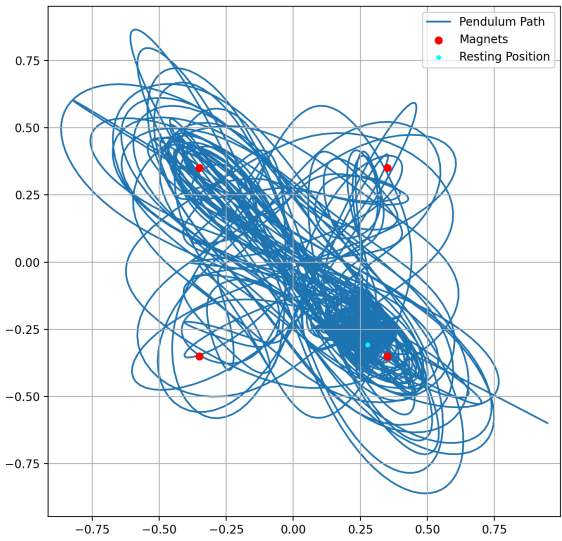
Radius = 0.2:



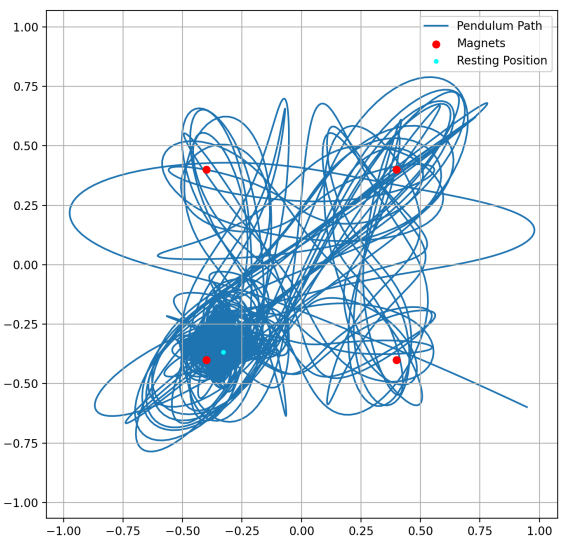
Radius = 0.3:



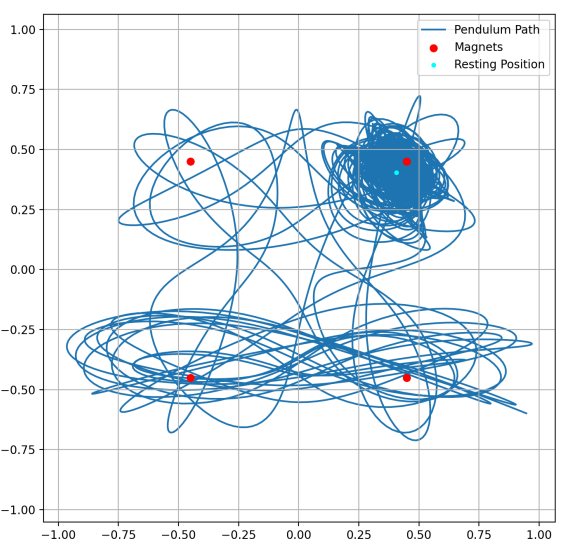
Radius = 0.35:



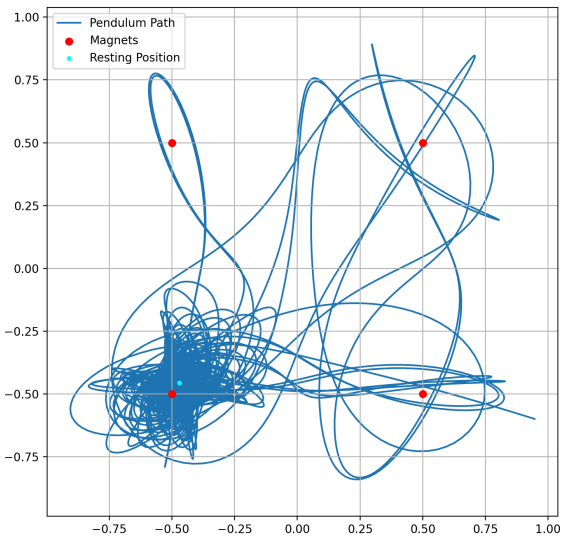
Radius = 0.4:



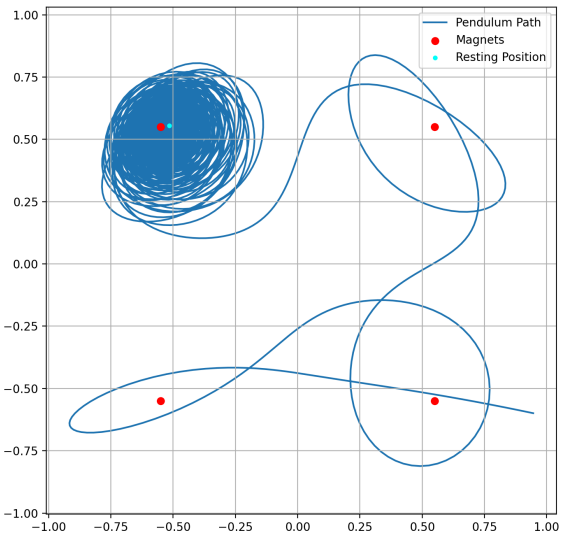
Radius = 0.45:



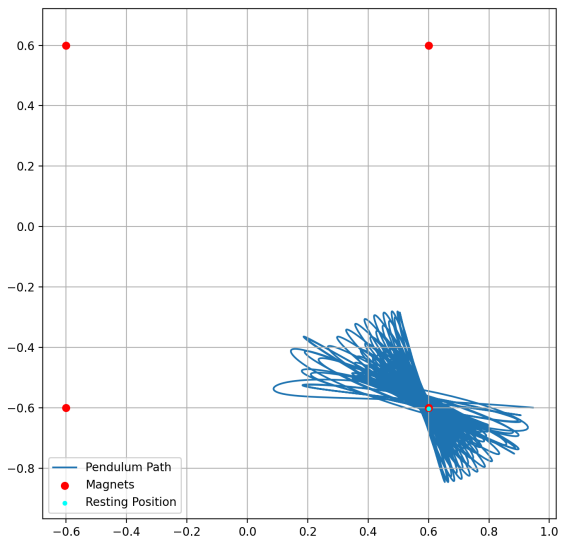
Radius = 0.5:



Radius = 0.55:



Radius = 0.6:



Radius = 0.7:

