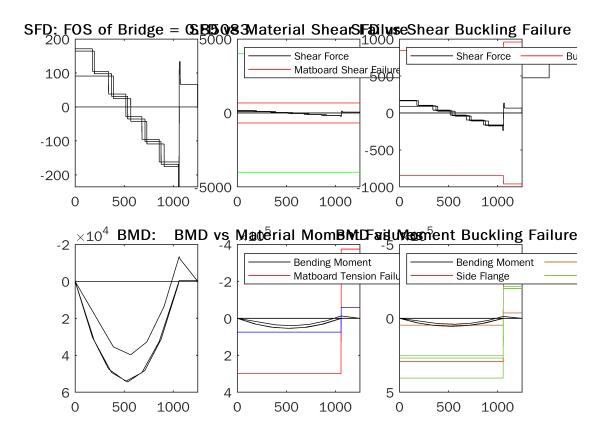
```
응응응응응응응
%TA: Raymond Ma
%Group Members: Grace, Yina, Joaquin
%%% Intial Parameters for both designs and cases:
                           % Number of locations to evaluate bridge failure
n = 1250;
L = 1250;
                           % Length of bridge
x = linspace(1,L,n); % Define x coordinate
locationA = 1;
locationB = 1060;
%Material properties
SigT = 30;
SigC = 6;
E = 4000;
TauU = 4;
TauG = 2;
mu = 0.2;
```

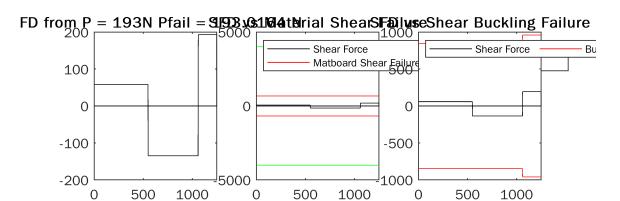
```
%%% Design Zero: Train
SFD_TrainLoad = zeros(1, n);
                                  % Initialize SFD(x)
BMD_TrainLoad = zeros(1, n);
                                  % Initialize BMD
SFD_TrainLoad1 = zeros(1, n);
                                  % Initialize SFD(x)
BMD_TrainLoad1 = zeros(1, n);
                                  % Initialize BMD
SFD_TrainLoad2 = zeros(1, n);
BMD_TrainLoad2 = zeros(1, n);
                                  % Initialize SFD(x)
                                  % Initialize BMD
                                  % Initialize SFD(x)
SFD_TrainLoad3 = zeros(1, n);
BMD_TrainLoad3 = zeros(1, n);
                                  % Initialize BMD
P = 400/6;
%diaphragms for Design 0
a = zeros(1, length(x));
a(1:550) = 550;
a(551:1060) = 510;
a(1061:1250) = 190;
%Cross Section
%% 2. Define cross-sections
% Design 0
dx = n/L; %length between each x coordinate
xc = [1 dx*L]; % x locations of changes in cross section
bVector = [100 1.27 1.27 10 10 80]; %Base of rectangle segments
hVector = [1.27 72.46 72.46 1.27 1.27 1.27]; %height of rectangle segments
yVector = [74.365 37.5 37.5 73.1 73.1 0.635]; % distances between local centroid of substances
I = zeros(1, length(x)); %Initialize I values
yBar = zeros(1, length(x)); %Initialize Y values
[I, yBar] = SectionProperties(I, yBar, xc(1), xc(2), bVector, hVector, yVector); %Calc
cutoffAreaCent = [ 77.46*1.27, 1.27*yBar(1), 1.27*yBar(1)]; %Calculate area from centro
```

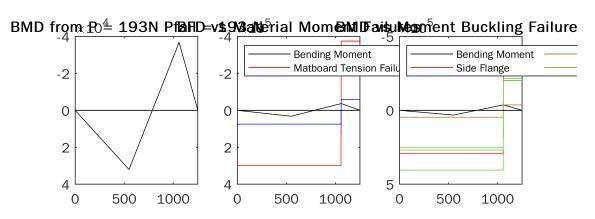
```
yCentCutoff = [ yBar(1)-0.635, yBar(1)/2, yBar(1)/2]; %Calculate y values from centroid
cutoffAreaGlue = [127];
yGlue = [75-yBar(1)-0.635]; % centroid of the cutoff area
Qglue = zeros(1, length(x)); %initialize Q at centriod and Q at glue
Qmax = zeros(1, length(x));
[Qmax, Qglue] = calculateQ( Qmax, Qglue, xc(1), xc(2), cutoffAreaCent, cutoffAreaGlue,
%Other constants
b = zeros(1,length(x)); %Width of Shear surface
bGlue = zeros(1,length(x)); %Width of Shear surface of glue
bGlue(:) = 10;
t = zeros(1,length(x)); %Thickness of board (used for plate buckling)
height = zeros(1,length(x)); %Height of cross section
height(:) = 75;
%% Train Load: 6 points for the 6 wheels
TLocation = 1; %Train at Start
[SFD_TrainLoad, BMD_TrainLoad] = ApplyPL(TLocation, P, x, SFD_TrainLoad, locationA, locationA)
[SFD_TrainLoad, BMD_TrainLoad] = ApplyPL(TLocation + 176, P, x, SFD_TrainLoad, location
[SFD_TrainLoad, BMD_TrainLoad] = ApplyPL(TLocation + 176 + 164, P, x, SFD_TrainLoad, lo
[SFD_TrainLoad, BMD_TrainLoad] = ApplyPL(TLocation + 176 + 164 + 176, P, x, SFD_TrainLoad)
[SFD_TrainLoad, BMD_TrainLoad] = ApplyPL(TLocation + 176 + 164 + 176 + 164, P, x, SFD_T
[SFD_TrainLoad, BMD_TrainLoad] = ApplyPL(TLocation + 176 + 164 + 176 + 164 + 176, P, x
TLocation = 196; %Train at Start
[SFD_TrainLoad2, BMD_TrainLoad2] = ApplyPL(TLocation, P, x, SFD_TrainLoad2, locationA,
[SFD_TrainLoad2, BMD_TrainLoad2] = ApplyPL(TLocation + 176, P, x, SFD_TrainLoad2, locat
[SFD_TrainLoad2, BMD_TrainLoad2] = ApplyPL(TLocation + 176 + 164, P, x, SFD_TrainLoad2,
[SFD_TrainLoad2, BMD_TrainLoad2] = ApplyPL(TLocation + 176 + 164 + 176, P, x, SFD_TrainLoad2)
[SFD_TrainLoad2, BMD_TrainLoad2] = ApplyPL(TLocation + 176 + 164 + 176 + 164, P, x, SFI
[SFD_TrainLoad2, BMD_TrainLoad2] = ApplyPL(TLocation + 176 + 164 + 176 + 164 + 176, P,
TLocation = 391; %Train at Start
[SFD_TrainLoad3, BMD_TrainLoad3] = ApplyPL(TLocation, P, x, SFD_TrainLoad3, locationA,
[SFD_TrainLoad3, BMD_TrainLoad3] = ApplyPL(TLocation + 176, P, x, SFD_TrainLoad3, locat
[SFD_TrainLoad3, BMD_TrainLoad3] = ApplyPL(TLocation + 176 + 164, P, x, SFD_TrainLoad3,
[SFD_TrainLoad3, BMD_TrainLoad3] = ApplyPL(TLocation + 176 + 164 + 176, P, x, SFD_TrainLoad3)
[SFD_TrainLoad3, BMD_TrainLoad3] = ApplyPL(TLocation + 176 + 164 + 176 + 164, P, x, SFI
[SFD_TrainLoad3, BMD_TrainLoad3] = ApplyPL(TLocation + 176 + 164 + 176 + 164 + 176, P,
%Find applied stresses
%Shear Stress demand
ShearStress = VStress(I, b, Qmax, SFD_TrainLoad); %Shear Stress at centroid
ShearStressGlue = VStress(I, 20 + 2*1.27, Qglue, SFD_TrainLoad); %Shear Stress at Glue
%Shear Stress Capacity
ShearBuckle = VBuck(I, t, b, height, E, mu, yBar, a, Qmax); %Buckling Shear capacity
%Bending Stress
%Bending Stress Demand
```

```
BendingStressT = MStressT( I,yBar, height, BMD_TrainLoad); %Tension Stress
BendingStressC = MStressC( I,yBar, height, BMD_TrainLoad); %Compression Stress
%Shear Stress Capacity %Bending Plate Buckling capacity stress
BendingBuck1 = MBuck(I, t, (100-80)/2, E, mu, 2);
BendingBuck2 = MBuck( I, t, 80-2*1.27, E, mu, 1 );
BendingBuck3 = MBuck( I, t, 75-41.701-1.27, E, mu, 3 );
BendingBuck4 = MBuck(I, t, (100-80)/2, E, mu, 2);
BendingBuck5 = MBuck( I, t, 75-41.701-1.27, E, mu, 3 );
BendingBuck6 = MBuck( I, t, 41.701-1.27, E, mu, 3 );
BendingBuck7 = MBuck(I, t, 80-2*1.27, E, mu, 1);
BendingBuck8 = MBuck( I, t, 41.701-1.27, E, mu, 1 );
%Calculate FOS
FOSBridge = FOSCalc(ShearStress, ShearStressGlue, BendingStressT, BendingStressC, SigT,
%Visualization
%Find max Shear Forces and Bending Moments
V_Mat = Vfail(I, b, Qmax, TauU); %Max Shear
V_Buck = VfailBuck( I, t, b, height, E, mu, yBar, a, TauU, Qmax); %Max Shear caused by
V_Glue = Vfail(I, bGlue, Qglue, TauU); %Max Shear at glue
M_MatT = MfailMatT(I, yBar, height, SigT, BMD_TrainLoad); %Max tension
M_MatC = MfailMatC(I, yBar, height, SigC, BMD_TrainLoad); %Max compression
M_Buck1 = MfailBuck(I, t, (100-80)/2, E, mu, BMD_TrainLoad, 2, yBar, height, SigC); %Ma
M_Buck2 = MfailBuck(I, t, 80-2*1.27, E, mu, BMD_TrainLoad, 1, yBar, height, SigC);
M_Buck3 = MfailBuck(I, t, 75-41.701-1.27, E, mu, BMD_TrainLoad, 3, yBar, height, SigC)
M_Buck4 = MfailBuck(I, t, (100-80)/2, E, mu, BMD_TrainLoad, 2, yBar, height, SigC);
M_Buck5 = MfailBuck(I, t, 75-41.701-1.27, E, mu, BMD_TrainLoad, 1, yBar, height, SigC).
M_Buck6 = MfailBuck(I, t, 41.701-1.27, E, mu, BMD_TrainLoad, 3, yBar, height, SigC);
M_Buck7 = MfailBuck(I, t, 80-2*1.27, E, mu, BMD_TrainLoad, 1, yBar, height, SigC);
M_Buck8 = MfailBuck(I, t, 41.701-1.27, E, mu, BMD_TrainLoad, 3, yBar, height, SigC);
%% Visualization
VisualizeTL(x, SFD_TrainLoad, BMD_TrainLoad, SFD_TrainLoad2, BMD_TrainLoad2, SFD_TrainLoad2, S
```



```
%Design 0 Point Loads
SFD_PL = zeros(1, n);
                                                                                           % Initialize SFD(x)
BMD_PL = zeros(1, n);
P = 1; %P = 1 * whatever value, so I can set p to 1
%% 1. Point Loading Analysis (SFD, BMD) Two loads for two points
[SFD_PL, BMD_PL] = ApplyPL(550, P, x, SFD_PL, locationA, locationB); % Construct SFD, BMD_PL, BMD_PL] = ApplyPL(550, P, x, SFD_PL, locationA, locationB); % Construct SFD, BMD_PL, BMD_PL] = ApplyPL(550, P, x, SFD_PL, locationA, locationB); % Construct SFD, BMD_PL, BMD_PL
[SFD_PL, BMD_PL] = ApplyPL(L, P, x, SFD_PL, locationA, locationB); % Construct SFD, B
%%Calculate Failure Load
Pf = FailLoad( SFD_PL, BMD_PL, V_Mat, V_Glue, V_Buck, M_MatT, M_MatC, M_Buck1, M_Buck2
%% Visualization
SFD_FAIL = zeros(1,length(x));
BMD_FAIL = zeros(1, length(x));
[SFD_FAIL, BMD_FAIL] = ApplyPL(550, Pf, x, SFD_FAIL, locationA, locationB); % Construct
[SFD_FAIL, BMD_FAIL] = ApplyPL(L, Pf, x, SFD_FAIL, locationA, locationB);
                                                                                                                                                                                                                                                                   % Construct
VisualizePL(x, SFD_FAIL, BMD_FAIL, V_Mat, V_Glue, V_Buck, M_MatT, M_MatC, M_Buck1, M_Bu
```

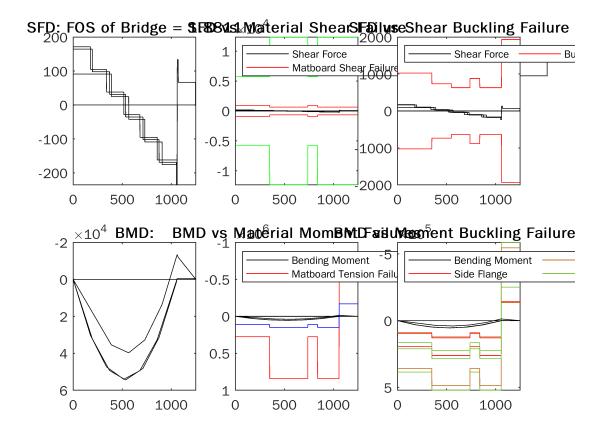




```
%Our Design
%Train:
%diaphragms
a = zeros(1, length(x)); %Our design has 3 different diaphragm spacings
a(1:550) = 104;
a(551:1060) = 120;
a(1060:1250) = 53;
%% 2. Define cross-sections
% Cross Section A
dx = n/L;
xc = [1 dx*350 dx*738 dx*838 dx*L]; % x locations of changes in cross section
I = zeros(1, length(x));
yBar = zeros(1, length(x));
Qglue = zeros(1, length(x));
Qmax = zeros(1, length(x));
%Cross Section A
bVector = [100 1.27 1.27 10 10];
hVector = [1.27 120 120 1.27 1.27];
```

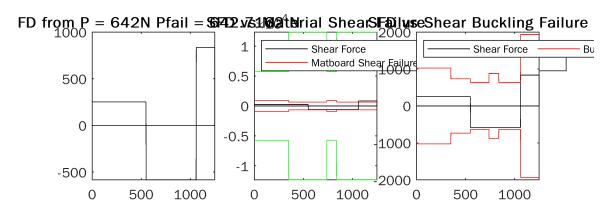
```
yVector = [120.635 60 60 119.365 119.365]; % distances between local centroid of subcor
[I, yBar] = SectionProperties(I, yBar, xc(1), xc(2), bVector, hVector, yVector); %This
[I, yBar] = SectionProperties(I, yBar, xc(3)+1, xc(4), bVector, hVector, yVector);
cutoffAreaCent = [ 1.27*yBar(1), 1.27*yBar(1)];
yCentCutoff = [yBar(1)/2, yBar(1)/2];
cutoffAreaGlue = [127];
yGlue = [121.27-yBar(1)-0.635]; % centroid of the cutoff area
[Qmax, Qglue] = calculateQ( Qmax, Qglue, xc(1), xc(2), cutoffAreaCent, cutoffAreaGlue,
[Qmax, Qglue] = calculateQ( Qmax, Qglue, xc(3)+1, xc(4), cutoffAreaCent, cutoffAreaGlue
% Cross Section B
bVector = [100 1.27 1.27 10 10 10 10 70 70];
hVector = [1.27 117.46 117.46 1.27 1.27 1.27 1.27 1.27];
yVector = [120.635 61.27 61.27 119.365 119.365 3.175 3.175 1.905 0.635]; % distances be
[I, yBar] = SectionProperties(I, yBar, xc(2)+1, xc(3), bVector, hVector, yVector); %Th
[I, yBar] = SectionProperties(I, yBar, xc(4)+1, xc(5), bVector, hVector, yVector);
cutoffAreaCent = [ 127 12.7 12.7 (120-yBar(900))*1.27 (120-yBar(900))*1.27];
yCentCutoff = [121.27-yBar(900)-0.635 120-yBar(900)-0.635 120-yBar(900)-0.65 120-yBar(900)-0.55 120-yBar(900)-0.55 120-yBar(900)-0.55 120-yBar(900)-0.55 120-yBar(900)-0.55 12
cutoffAreaGlue = [127];
yGlue = [121.27-yBar(1)-0.635]; % centroid of the cutoff area
[Qmax, Qglue] = calculateQ( Qmax, Qglue, xc(2)+1, xc(3), cutoffAreaCent, cutoffAreaGlue
[Qmax, Qglue] = calculateQ( Qmax, Qglue, xc(4)+1, xc(5), cutoffAreaCent, cutoffAreaGlue
%Other constants
b = zeros(1, length(x));
b(:) = 2*1.27;
bGlue = zeros(1,length(x));
bGlue(:) = 10;
t = zeros(1, length(x));
t(:) = 1.27;
height = zeros(1,length(x));
height(:) = 120;
% It was uncessary to calculate the SFD and BMD again since it was already
% done for Design 0
%Find applied stresses
%Shear Stress demand
ShearStress = VStress(I, b, Qmax, SFD_TrainLoad);
ShearStressGlue = VStress(I, 20 + 2*1.27, Qglue, SFD_TrainLoad);
%Shear Stress Capacity
ShearBuckle = VBuck(I, t, b, height, E, mu, yBar, a, Qmax);
%Bending Stress
%Bending Stress Demand
BendingStressT = MStressT( I,yBar, height, BMD_TrainLoad);
BendingStressC = MStressC( I,yBar, height, BMD_TrainLoad);
%Shear Stress Capacity
%Cross Section A
BendingBuck1 = MBuck( I, t, 15, E, mu, 2);
BendingBuck2 = MBuck( I, t, 70-2*(1.27), E, mu, 1);
BendingBuck3 = MBuck(I, t, 39.859, E, mu, 3);
```

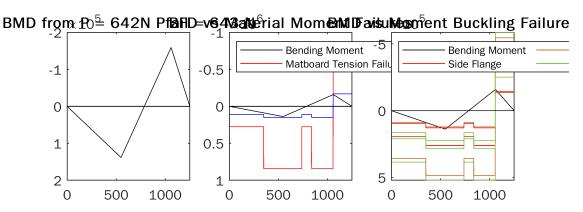
```
BendingBuck4 = MBuck( I, t, 80.1411, E, mu, 3 );
%Cross Section B
BendingBuck5 = MBuck(I, t, 56.4858-2*1.27, E, mu, 3);
BendingBuck6 = MBuck( I, t, 117.46-56.4858, E, mu, 3 );
BendingBuck7 = MBuck( I, 2*t, 70-2*1.27, E, mu, 1 );
BendingBuck8 = MBuck(I, t, 56.4858-2*1.27, E, mu, 3);
FOSBridge = FOSCalc(ShearStress, ShearStressGlue, BendingStressT, BendingStressC, SigT,
%Visualization
V_Mat = Vfail(I, b, Qmax, TauU);
V_Buck = VfailBuck( I, t, b, height, E, mu, yBar, a, TauU, Qmax);
V_Glue = Vfail(I, bGlue, Qglue, TauU);
M_MatT = MfailMatT(I, yBar, height, SigT, BMD_TrainLoad);
M_MatC = MfailMatC(I, yBar, height, SigC, BMD_TrainLoad);
M_Buck1 = MfailBuck(I, t, 15, E, mu, BMD_TrainLoad, 2, yBar, height, SigC);
M_Buck2 = MfailBuck(I, t, 70-2*(1.27), E, mu, BMD_TrainLoad, 1, yBar, height, SigC);
M_Buck3 = MfailBuck(I, t, 39.859, E, mu, BMD_TrainLoad, 3, yBar, height, SigC);
M_Buck4 = MfailBuck(I, t, 80.1411, E, mu, BMD_TrainLoad, 3, yBar, height, SigC);
M_Buck5 = MfailBuck(I, t, 56.4858-2*1.27, E, mu, BMD_TrainLoad, 3, yBar, height, SigC).
M_Buck6 = MfailBuck(I, t, 117.46-56.4858, E, mu, BMD_TrainLoad, 3, yBar, height, SigC).
M_Buck7 = MfailBuck(I, 2*t, 70-2*1.27, E, mu, BMD_TrainLoad, 1, yBar, height, SigC);
M_Buck8 = MfailBuck(I, t, 56.4858-2*1.27, E, mu, BMD_TrainLoad, 3, yBar, height, SigC).
%% Visualization
VisualizeTL(x, SFD_TrainLoad, BMD_TrainLoad, SFD_TrainLoad2, BMD_TrainLoad2, SFD_TrainLoad2, S
```



%Point Load our Design:

Pf = FailLoad(SFD_PL, BMD_PL, V_Mat, V_Glue, V_Buck, M_MatT, M_MatC, M_Buck1, M_Buck2 [SFD_FAIL, BMD_FAIL] = ApplyPL(550, Pf, x, SFD_FAIL, locationA, locationB); % Construct [SFD_FAIL, BMD_FAIL] = ApplyPL(L, Pf, x, SFD_FAIL, locationA, locationB); % Construct VisualizePL(x, SFD_FAIL, BMD_FAIL, V_Mat, V_Glue, V_Buck, M_MatT, M_MatC, M_Buck1, M





```
%% Train failure Functions:
```

```
BendingTensionStress = zeros(1,length(I));
for i = 1 : length(I)
        ybot = y(i);
        ytop = height(i) - y(i);
        if BMD(i) >= 0 % If the moment is positive, the tension failure will be at the
            BendingTensionStress(i) = (BMD(i) * ybot) / I(i);
        elseif BMD < 0 % If the moment is negative, the tension failure will be at the
            BendingTensionStress(i) = (BMD(i) * ytop) / I(i);
        end
end
end
function [ BendingCompressionStress ] = MStressC( I,y, height, BMD ) %Compression
% % Calculates Compression Stress at every x value based on applied load
BendingCompressionStress = zeros(1,length(I));
for i = 1:length(I)
        ybot = y(i);
        ytop = height(i) - y(i);
        if BMD(i) >= 0 % If the moment is positive, the compression failure will be at
            BendingCompressionStress(i) = (BMD(i) * ytop) / I(i);
        elseif BMD(i) > 0 % If the moment is negative, the compression failure will be
            BendingCompressionStress(i) = (BMD(i) * ybot) / I(i);
        end
end
end
function [ MBuckStress ] = MBuck( I, t, bBuck, E, mu, caseNum )
% Calculates Bending Capacity based on plate buckling for every x value
    if caseNum == 1
       k = 4;
    end
    if caseNum == 2
        k = 0.425;
    end
    if caseNum == 3
        k = 6;
    end
    for i = 1:length(I)
        MBuckStress(i) = ((k*E*pi^2)/(12*(1-mu^2))) * (t(i)/bBuck)^2;
    end
end
```

```
function [ FOS ] = FOSCalc( ShearFail, GlueFail, BendingTensionStress, BendingCompress:
        %Finds FOS based on every capacity and every demand -> FOS =
        %Capacity/Demand
        ShearFOS = min(TauCapacity ./ abs(ShearFail));
        GlueFOS = min(GlueCapacity ./ abs(GlueFail));
        ShearBucklingFOS = min(TauBuckling ./ abs(ShearFail));
        TensionFOS = min(TensionCapacity ./ abs(BendingTensionStress));
        CompressionFOS = min(CompressionCapacity ./ abs(BendingCompressionStress));
        CompressionBucklingFOS1 = min(CompressionBucklingCapacity1 ./ abs(BendingCompressionBucklingCapacity1 ./
        CompressionBucklingFOS2 = min(CompressionBucklingCapacity2 ./ abs(BendingCompressionBucklingCapacity2 ./
        CompressionBucklingFOS3 = min(CompressionBucklingCapacity3 ./ abs(BendingCompressionBucklingCapacity3 ./
        CompressionBucklingFOS4 = min(CompressionBucklingCapacity4 ./ abs(BendingCompressionBucklingCapacity4 ./
        CompressionBucklingFOS5 = min(CompressionBucklingCapacity5 ./ abs(BendingCompressionBucklingCapacity5 ./
        CompressionBucklingFOS6 = min(CompressionBucklingCapacity6 ./ abs(BendingCompressionBucklingCapacity6 ./
        CompressionBucklingFOS7 = min(CompressionBucklingCapacity7 ./ abs(BendingCompressionBucklingCapacity7 ./
        CompressionBucklingFOS8 = min(CompressionBucklingCapacity8 ./ abs(BendingCompressionBucklingCapacity8 ./
        %Finds the minimum of the FOS
        FOSes = [ShearFOS GlueFOS ShearBucklingFOS TensionFOS CompressionFOS CompressionBucklingFOS TensionFOS CompressionFOS CompressionFOS CompressionBucklingFOS TensionFOS CompressionFOS Comp
        FOS = min(FOSes);
end
%Cross Section Functions
function [I, yBar] = SectionProperties(I, yBar, xStart, xEnd, bVector, hVector, yVector
      % Input: Geometric Inputs. Format will depend on user
      % Output: Sectional Properties at every value of x. Each property is a 1-D array of
      % finding global centroid
      for i = xStart : xEnd
              sumAY = 0;
              sumA = 0;
              for j = 1:length(bVector)
                       sumAY = sumAY + bVector(j) * hVector(j) * yVector(j);
                       sumA = sumA + bVector(j) * hVector(j);
              end
              yBar(i) = sumAY/sumA;
              %finding I
              for j = 1:length(bVector)
                       I(i) = I(i) + (bVector(j)*hVector(j)^3)/12 + bVector(j)*hVector(j)*(yVector(j))
              end
      end
end
function [Qmax, Qglue] = calculateQ( Qmax, Qglue, xStart, xEnd, cutoffAreaCent, cutoffA
      for i = xStart : xEnd
              %finding Q at centroid
```

```
for j = 1:length(cutoffAreaCent)
           Qmax(i) = Qmax(i) + cutoffAreaCent(j)*yCentCutoff(j);
       end
       %finding Q at glue
       for j = 1:length(cutoffAreaGlue)
           Qglue(i) = Qglue(i) + cutoffAreaGlue(j)*yGlueCutoff(j);
       end
   end
end
function [] = VisualizeTL(x, SFD_PL, BMD_PL, SFD2, BMD2, SFD3, BMD3, V_Mat, V_Glue, V_I
   %Plots all outputs of design process
  figure;
  axis = zeros(1, length(x));
  hold on;
  %shear force diagram
  subplot(2, 3, 1)
  plot(x, SFD_PL, "k")
  hold on
  plot(x, SFD2, "k")
  hold on
  plot(x, SFD3, "k")
  hold on
  plot(x,axis,"k")
  hold off
  title1 = strcat("SFD: FOS of Bridge = ", num2str(FOS));
  title(title1)
  %shear force vs mat shear fail
  subplot(2, 3, 2)
  plot(x, SFD_PL, "k")
  hold on
  plot(x, V_Mat, "r")
  hold on
  plot(x, V_Glue, "g")
  hold on
  plot(x, -V_Mat, "r")
  hold on
  plot(x, -V_Glue, "g")
  hold on
  plot(x, SFD2, "k")
  hold on
  plot(x, SFD3, "k")
  hold on
  hold on
  plot(x,axis,"k")
  hold off
  legend("Shear Force", "Matboard Shear Failure", "Glue Shear Failure", 'Location', 'non
   title("SFD vs Material Shear Failure")
```

```
subplot(2, 3, 3)
plot(x, SFD_PL, "k")
hold on
plot(x, V_Buck, "r")
hold on
plot(x, -V_Buck, "r")
hold on
plot(x, SFD2, "k")
hold on
plot(x, SFD3, "k")
hold on
plot(x,axis,"k")
hold off
legend("Shear Force", "Buckling Failure", 'Location', 'northwest', 'NumColumns',2)
title("SFD vs Shear Buckling Failure")
%BMD Diagrams
subplot(2, 3, 4)
plot(x, BMD_PL, "k")
hold on
plot(x, BMD2, "k")
hold on
plot(x, BMD3, "k")
hold on
plot(x,axis,"k")
hold on
title2 = strcat("BMD:");
title(title2)
set(gca, 'YDir', 'reverse')
set(gca, 'YDir', 'reverse')
hold off
subplot(2, 3, 5)
plot(x, BMD_PL, "k")
hold on
plot(x, M_MatT, "r")
hold on
plot(x, M_MatC, "b")
hold on
plot(x, BMD2, "k")
hold on
plot(x, BMD3, "k")
hold on
plot(x,axis,"k")
hold on
legend("Bending Moment", "Matboard Tension Failure", "Matboard Compression Failure",
title("BMD vs Material Moment Failures")
set(gca, 'YDir', 'reverse')
hold off
subplot(2, 3, 6)
plot(x, BMD_PL, "k")
hold on
plot(x, M_Buck1, "-r")
```

```
hold on
  plot(x, M_Buck2, 'Color', [0.74, 0.36, 0.04])
  plot(x, M_Buck3, 'Color', [0.4, 0.75, 0.13])
  hold on
  plot(x, M_Buck4, "-r")
  hold on
  plot(x, M_Buck5, 'Color', [0.4, 0.75, 0.13])
  hold on
  plot(x, M_Buck6, 'Color', [0.4, 0.75, 0.13])
  hold on
  plot(x, M_Buck7, 'Color', [0.74, 0.36, 0.04])
  hold on
  plot(x, M_Buck8, 'Color', [0.4, 0.75, 0.13])
  hold on
  plot(x, BMD2, "k")
  hold on
  plot(x, BMD3, "k")
  hold on
  plot(x,axis, "k")
  hold on
  %legend("Bending Moment", "Mid Flange Buckling", "Side Flange Buckling", "Web Compre
  title("BMD vs Moment Buckling Failures")
  legend("Bending Moment", "Side Flange", "Mid Flange", "Web Flange", 'Location', 'nort
  set(gca, 'YDir', 'reverse')
  hold off
end
```

```
%%Point Load Functions:
function [ SFD, BMD ] = ApplyPL( xP, P, x, SFD, locationA, locationB) %(Location, Force
% Constructs SFD and BMD for every x value
% Can be iterated since SFD and BMD diagrams can be added together
    %Calculate reaction forces
    SupportB = ((xP * P) / (locationB)); %Using Sum of Moments = 0
    SupportA = (P - SupportB); %Using sum of vertical force = 0
    %Fill out SFD diagram as if by hand
    SFDLocal = zeros(1, length(SFD));
    if xP < locationB %Force is closer to the left side than support B
        for i = 1:(xP-1) %SFD before new load
            SFDLocal(i) = SupportA;
        end
        for i = xP:locationB %SFD after new load
            SFDLocal(i) = (SupportA - P);
        end
        for i = 1:length(SFD) %add the new SFD with the old ones
```

```
SFD(i) = SFD(i) + SFDLocal(i);
        end
    else %Force is farther from left side than support B
        for i = 1:(locationB-1) %SFD before new load
            SFDLocal(i) = SupportA;
        end
        for i = locationB:xP-1 %SFD after new load
            SFDLocal(i) = (SupportA + SupportB);
        end
        for i = xP:length(SFD)
           SFDLocal(i) = 0;
        end
        for i = 1:length(SFD) %add the new SFD with the old ones
            SFD(i) = SFD(i) + SFDLocal(i);
        end
    end
    %form BMD:
    dx = x(2) - x(1);
    BMD = cumsum((SFD * dx));
end
function [ V_fail ] = Vfail(I, b, Qcent, TauU )
% Calculates Shear Fail based on Tau Ultimate
    V_fail = TauU .* I .* b ./ Qcent;
end
function [ V_Buck ] = VfailBuck( I, t, b, height, E, mu, y, a, TauU, Qcent )
% Calculates Shear Fail based on Buckling
    %pi
   pi = 355/113;
    for i = 1:length(I)
        sigma(i) = ((5*E*pi^2)/(12*(1-mu^2))) * ((t(i)/height(i))^2 + (t(i)/a(i))^2);
    end
    %Calculate buckle fail by using the above formula
   V_Buck = Vfail(I, b, Qcent, sigma);
end
function [ M_MatT ] = MfailMatT( I,y, height, SigT, BMD )
% Calculates Tension Fail
for i = 1 : length(I)
        ybot = y;
        ytop = height(i) - y; %I need somesort of height vector
```

```
if BMD(i) > 0 % If the moment is positive, the tension failure will be at the k
            M_MatT(i) = (SigT * I(i)) / ybot(i);
        elseif BMD(i) < 0 % If the moment is negative, the tension failure will be at t
            M_MatT(i) = (-SigT * I(i)) / ytop(i);
        end
    end
end
function [ M_MatC ] = MfailMatC( I,y, height, SigC, BMD )
% Calculates Compression Fail
ybot = y;
ytop = height - y;
for i = 1 : length(I)
        if BMD(i) > 0 % If the moment is positive, the compression failure will be at t
            M_MatC(i) = (SigC * I(i)) / ytop(i);
        elseif BMD(i) < 0 % If the moment is negative, the compression failure will be
            M_MatC(i) = (-SigC * I(i)) / ybot(i);
        end
    end
end
function [ M_Buck ] = MfailBuck( I, t, bBuck, E, mu, BMD, caseNum, y, height, SigC )
% Calculates Bending Fail based on buckling
    %Assign a k value based on the case
    if caseNum == 1
        k = 4;
    end
    if caseNum == 2
        k = 0.425;
    end
    if caseNum == 3
        k = 6;
    end
    for i = 1:length(I)
        sigma(i) = ((k*E*pi^2)/(12*(1-mu^2))) * (t(i)/bBuck)^2;
    end
    %Calculate buckle fail using the above function
    M_Buck = MfailMatC(I,y, height, min(sigma), BMD);
end
function [ Pf ] = FailLoad( SFD, BMD, V_Mat, V_Glue, V_Buck, M_MatT, M_MatC, M_buck1, N
%Calculate the point load that causes the failure
%Flexural Stress
Because P = 1, the BMD and SFD are simply the coefficients of P. By
%dividing them, we are finding P despite the fact that there is no actual P
%variable.
```

```
CompressionFailure = abs(M_MatC) ./ abs(BMD);
TensionFailure = abs(M_MatT) ./ abs(BMD);
BendingBucklingFailure1 = abs(M_buck1) ./ abs(BMD);
BendingBucklingFailure2 = abs(M_buck2) ./ abs(BMD);
BendingBucklingFailure3 = abs(M_buck3) ./ abs(BMD);
BendingBucklingFailure4 = abs(M_buck4) ./ abs(BMD);
BendingBucklingFailure5 = abs(M_buck5) ./ abs(BMD);
BendingBucklingFailure6 = abs(M_buck6) ./ abs(BMD);
BendingBucklingFailure7 = abs(M_buck7) ./ abs(BMD);
BendingBucklingFailure8 = abs(M_buck8) ./ abs(BMD);
%Shear Stress
ShearFailureMat = V_Mat ./ abs(SFD);
ShearFailureGlue = V_Glue ./ abs(SFD);
ShearBuckliingFailure = V_Buck ./ abs(SFD);
%Find the lowest Pf
Pforces = [min(CompressionFailure) min(TensionFailure) min(BendingBucklingFailure1) min
Pf = min(Pforces);
end
function [] = VisualizePL(x, SFD_PL, BMD_PL, V_Mat, V_Glue, V_Buck, M_MatT, M_MatC, M_I
   axis = zeros(1, length(x));
   %Plots all outputs of design process
  figure;
  hold on;
  %shear force diagram
   subplot(2, 3, 1)
  plot(x, SFD_PL, "k")
  hold on
  plot(x,axis, "k")
  hold off
  title1 = strcat("SFD from P = ", int2str(floor(Pf)), "N Pfail = ", num2str(Pf), " N'
   title(title1)
   %shear force vs mat shear fail
   subplot(2, 3, 2)
  plot(x, SFD_PL, "k")
  hold on
  plot(x, V_Mat, "r")
  hold on
  plot(x, V_Glue, "g")
  hold on
  plot(x, -V_Mat, "r")
  hold on
  plot(x, -V_Glue, "g")
  hold on
  hold on
  plot(x,axis,"k")
  legend("Shear Force", "Matboard Shear Failure", "Glue Shear Failure", 'Location', 'non
```

```
title("SFD vs Material Shear Failure")
hold off
subplot(2, 3, 3)
plot(x, SFD_PL, "k")
hold on
plot(x, V_Buck, "r")
hold on
plot(x, -V_Buck, "r")
hold on
hold on
plot(x,axis,"k")
legend("Shear Force", "Buckling Failure", 'Location', 'northwest', 'NumColumns',2)
title("SFD vs Shear Buckling Failure")
hold off
%BMD Diagrams
subplot(2, 3, 4)
plot(x, BMD_PL, "k")
hold on
hold on
plot(x,axis,"k")
title2 = strcat("BMD from P = ", int2str(floor(Pf)), "N Pfail = ", int2str(Pf), " N'
title(title2)
set(gca, 'YDir', 'reverse')
set(gca, 'YDir', 'reverse')
hold off
subplot(2, 3, 5)
plot(x, BMD_PL, "k")
hold on
plot(x, M_MatT, "r")
hold on
plot(x, M_MatC, "b")
hold on
plot(x,axis,"k")
hold on
legend("Bending Moment", "Matboard Tension Failure", "Matboard Compression Failure",
title("BFD vs Material Moment Failures")
set(gca, 'YDir', 'reverse')
hold off
subplot(2, 3, 6)
plot(x, BMD_PL, "-k")
hold on
plot(x, M_Buck1, "-r")
hold on
plot(x, M_Buck2, 'Color', [0.74, 0.36, 0.04])
hold on
plot(x, M_Buck3, 'Color', [0.4, 0.75, 0.13])
hold on
plot(x, M_Buck4, "-r")
hold on
plot(x, M_Buck5, 'Color', [0.4, 0.75, 0.13])
```

```
hold on
plot(x, M_Buck6, 'Color', [0.4, 0.75, 0.13])
hold on
plot(x, M_Buck7, 'Color', [0.74, 0.36, 0.04])
hold on
plot(x, M_Buck8, 'Color', [0.4, 0.75, 0.13])
hold on
plot(x,axis, "k")
hold on
%legend("Bending Moment", "Mid Flange Buckling", "Side Flange Buckling", "Web Compretitle("BMD vs Moment Buckling Failures")
legend("Bending Moment", "Side Flange", "Mid Flange", "Web Flange", 'Location', 'northeset(gca, 'YDir', 'reverse')
hold off
end
```