Lee Milburn

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Education

Northeastern University Fall 2018 – expected May 2023
BS, Computer Engineering and Computer Science *Boston, MA*
GPA: 3.78

Research Experience

The Robotics and Intelligent Vehicles Research Laboratory Sept, 2020 – Present
Undergraduate Researcher *Boston, MA*

- Developed Autonomous UAV - UGV system to identify and pick up trash.
- Wrote networking and collected data for system which uses RGB-D and Hyperspectral data to classify terrain types in real-time for VAST project.
- Designed and constructed autonomous PPE material tests according to industry standards for ACE PPE project. Wrote the system's networking, decision making, and GUI.

The Dynamic Legged Systems Laboratory July, 2022 – December, 2022
Guest Researcher *Genova, Italy*

- Developed higher level control for autonomous navigation stack on Vinum-EU precision agriculture project.
- Trained and implemented a Mask-RCNN to do semantic segmentation of grapevine trunks for autonomous navigation. Hand annotated data-set of 450+ images.

Awards & Honors

Northeastern Achievement Award
Northeastern University *2019-2022*

1st Place in ECE Capstone Competition 2022 Award
Northeastern ECE Department *2022*

Project-Based Exploration for the Advancement of Knowledge (PEAK): Summit Award
Northeastern Undergraduate Research and Fellowships *2022*

Fung Leadership Award
Fung Scholars and Fellows *2022*

PEAK: Shout it out Award
Northeastern Undergraduate Research and Fellowships *2022*

Presidential Global Scholarship
Northeastern Global Experience Office *2022*

Graduate School Application Fund Award
Northeastern Undergraduate Research and Fellowships *2022*

Ongoing Research

Multi-Robot Trash Collection

Boston, MA *May, 2021 – Present*

- Evaluating the efficiency of the developed multi-robot framework for finding and collecting trash. Then introducing more UGVs to test the increased task completion speed after implementing a Multi Robot Task Allocation algorithm.

Vinum-EU

Genova, Italy *July, 2022 – December, 2022*

- Testing the effectiveness of the computer vision based autonomous quadruped vineyard navigation by evaluating the autonomously chosen way-points for optimizing the quadruped's robotic workspace.

Publications

1 M. H. Shaham, M. Skopin, H. Hochsztein, K. Mabulu, **L. Milburn**, J. Tukpah, A. Tunik, J. Winn, M. Zolotas, D. Erdogmus, and T. Padir, *"Human-supervised automation test cell to accelerate personal protective equipment manufacturing during the Covid-19 pandemic,"* in 2022 IEEE International Symposium on Technologies for Homeland Security, November 14-15, 2022.

2 **L. Milburn**, J. Gamba, and C. Semini, *"Towards Computer-Vision Based Vineyard Navigation for Quadruped Robots"* in 2022 Institute for Robotics and Intelligent Machines, October 7-9, 2022.

Research Presentations

1 **L. Milburn**, J. Chiaramonte, J. Fenton, *"Towards an Error Tolerant Multi-Robot System for Roadside Trash Collection."* in 2022 International Symposium on Distributed Autonomous Robotic Systems, November 25-28, 2022.

2 **L. Milburn**, J. Gamba, and C. Semini, *"Towards Computer-Vision Based Vineyard Navigation for Quadruped Robots"* in 2022 Institute for Robotics and Intelligent Machines, October 7-9, 2022.

3 **L. Milburn**, J. Chiaramonte, J. Fenton, J. Raines, C. Ellingham, D. Venkatramen *"TRASH: Tandem Rover and Aerial Scrap Harvester"* in 2022 Northeastern's Research, Innovation, Scholarship and Entrepreneurial Expo, April 14, 2022.

Employment

Scientific Systems Inc. Co. July, 2021 – July, 2022

Autonomous Systems Coop *Woburn, MA*

- Created and prototyped an algorithm for UAVs to do multi-target pursuit tracking in an unstructured environment. This work was turned into the basis for a government contract.
- Researched modeling the large neighborhood search and tabu search algorithms for optimizing the Multi- Robot Task Allocation scheduling towards a given time horizon using Optaplanner.

United Electronics Industries July, 2020 – December, 2020

Sales Engineer Coop *Waltham, MA*

- Benchmark tested UEI's hardware to determine the max throughput.

BrainQ Technologies June, 2019 – August, 2019

Product Intern *Jerusalem, Israel*

- Improved EMG physical therapy product through testing and creating designs. Researched the start-up market to provide information for initiating Series B funding.

Robotics Projects

TRASH: Tandem Rover and Aerial Scrap Harvester
Capstone Project *2022*

Visual and Spectral Terrain Classification in Unstructured Multi-Class Environments
Contributor to IROS 2022 paper *2022*

Northeastern's NASA RASC-AL Challenge Club
Mobile Robotics Team Lead *2021-2022*

Hack the Normal Hackathon
SOAR *2021*

Extracurricular Activities

Jewish Student Union Club
Member *2020-Present*

Disability Resource Center
Notetaker for EE 2412 Fundamentals of Electronics *2020-2021*

Dialogue of Civilizations in Israel
Multiple Narratives and Cultural Complexities *2019*

Other Interests

Running
Pisa Marathon, Malden Half-Marathon *2020-Present*

Six month backpacking trip in Southeast Asia
Thailand, Cambodia, Vietnam, Malaysia *2018*