

# Lee Milburn

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## Education

**University of Pennsylvania**

*MSE, Robotics*

Fall 2023 – expected May 2025

*Philadelphia, PA*

**Northeastern University**

*BS, Computer Engineering and Computer Science*

Fall 2018 – May 2023

*Boston, MA*

GPA: 3.8

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## Research Experience

**The Scalable Autonomous Robots (ScalAR) Laboratory**

Oct, 2023 – Present

*Research Assistant*

*Philadelphia, PA*

- Implemented a physics-informed Koopman Operator to estimate non-linear systems.
- Applied a Non-Linear Model Predictive Control (NMPC) based on Koopman system's estimation.

**The Robotics and Intelligent Vehicles Research Laboratory**

Sept, 2020 – Aug, 2023

*Undergraduate Researcher*

*Boston, MA*

- Developed Autonomous UAV - UGV system to identify and pick up trash.
- Wrote networking and collected data for system which uses RGB-D and Hyperspectral data to classify terrain types in real-time for VAST project.
- Designed and constructed autonomous PPE material tests according to industry standards for ACE PPE project. Wrote the system's networking, decision making, and GUI.

**The Dynamic Legged Systems Laboratory**

July, 2022 – Dec, 2022

*Guest Researcher*

*Genova, Italy*

- Developed higher level control for autonomous navigation stack on Vinum-EU precision agriculture project.
- Algorithms for accurately generating navigation waypoints from RGB-D sensors during runtime, while navigating down the vineyard row.
- Trained and implemented a Mask-RCNN to do semantic segmentation of grapevine trunks for autonomous navigation. Hand annotated data-set of 500+ images.

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## Publications

- 1 **L. Milburn**, J. Chiaramonte, J. Fenton and T. Padir, "*TRASH: Tandem Rover and Aerial Scrap Harvester*," 2023 Robotics Automation and Artificial Intelligence (RAAI), December 14-16, 2023. <https://arxiv.org/abs/2301.01704>. **Accepted**.
- 2 **L. Milburn**, J. Gamba, M. Fernandes and C. Semini, "*Computer-Vision Based Real Time Waypoint Generation for Autonomous Vineyard Navigation with Quadruped Robots*," 2023 IEEE International Conference on Autonomous Robot Systems and Competitions (ICARSC), Tomar, Portugal, 2023, pp. 239-244, doi: 10.1109/ICARSC58346.2023.10129563.
- 3 M. H. Shaham, M. Skopin, H. Hochshtein, K. Mabulu, **L. Milburn**, J. Tukpah, A. Tunik, J. Winn, M. Zolotas, D. Erdogmus, and T. Padir, "*Human-Supervised Automation Test Cell to Accelerate Personal Protective Equipment Manufacturing During the COVID-19 Pandemic*," in 2022 IEEE International Symposium on Technologies for Homeland Security (HST), Boston, MA, USA, 2022, pp. 1-8, doi: 10.1109/HST56032.2022.10025429.

- 4 **L. Milburn**, J. Gamba, and C. Semini, "*Towards Computer-Vision Based Vineyard Navigation for Quadraped Robots*" in 2022 Institute for Robotics and Intelligent Machines, October 7-9, 2022.  
<https://doi.org/10.5281/zenodo.7531328>

#### *Research Presentations*

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- 1 **L. Milburn**, J. Chiaramonte, J. Fenton, "*Towards an Error Tolerant Multi-Robot System for Roadside Trash Collection.*" in 2022 International Symposium on Distributed Autonomous Robotic Systems, November 25-28, 2022.
- 2 **L. Milburn**, J. Gamba, and C. Semini, "*Towards Computer-Vision Based Vineyard Navigation for Quadraped Robots*" in 2022 Institute for Robotics and Intelligent Machines, October 7-9, 2022.
- 3 **L. Milburn**, J. Chiaramonte, J. Fenton, J. Raines, C. Ellingham, D. Venkatramen "*TRASH: Tandem Rover and Aerial Scrap Harvester*" in 2022 Northeastern's Research, Innovation, Scholarship and Entrepreneurial Expo, April 14, 2022.

#### *Awards & Honors*

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<b>Northeastern Achievement Award</b>	
<i>Northeastern University</i>	2019-2022
<b>1st Place in ECE Capstone Competition 2022 Award</b>	
<i>Northeastern ECE Department</i>	2022
<b>Project-Based Exploration for the Advancement of Knowledge (PEAK): Summit Award</b>	
<i>Northeastern Undergraduate Research and Fellowships</i>	2022
<b>Fung Leadership Award</b>	
<i>Fung Scholars and Fellows</i>	2022
<b>PEAK: Shout it out Award</b>	
<i>Northeastern Undergraduate Research and Fellowships</i>	2022
<b>Presidential Global Scholarship</b>	
<i>Northeastern Global Experience Office</i>	2022
<b>Graduate School Application Fund Award</b>	
<i>Northeastern Undergraduate Research and Fellowships</i>	2022

#### *Teaching Experience*

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<b>FIRST Robotics Mentor</b>	September, 2023 – Present
<i>Robotics Mentor</i>	Online
<ul style="list-style-type: none"> <li>• Consult on Highschool Robotics FIRST team.</li> <li>• Worked through computer vision principals and helped debug teams technical issues.</li> </ul>	
<b>CS 2510 Fundamentals of Computer Science 2</b>	January, 2023 – May, 2023
<i>Teacher's Assistant</i>	Online
<ul style="list-style-type: none"> <li>• Held Office Hours nine hours each week.</li> <li>• Graded student submissions and tested homework pre-release.</li> </ul>	

## *Employment*

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<b>Scientific Systems Inc. Co.</b>	July, 2021 – July, 2022
<i>Autonomous Systems Coop</i>	<i>Woburn, MA</i>
<ul style="list-style-type: none"><li>• Created and prototyped an algorithm for UAVs to do multi-target pursuit tracking in an unstructured environment. This work was turned into the basis for a government contract.</li><li>• Researched modeling the large neighborhood search and tabu search algorithms for optimizing the Multi- Robot Task Allocation scheduling towards a given time horizon using Optaplanner.</li></ul>	
<b>United Electronics Industries</b>	July, 2020 – December, 2020
<i>Sales Engineer Coop</i>	<i>Waltham, MA</i>
<ul style="list-style-type: none"><li>• Benchmark tested UEI's hardware to determine the max throughput.</li></ul>	
<b>BrainQ Technologies</b>	June, 2019 – August, 2019
<i>Product Intern</i>	<i>Jerusalem, Israel</i>
<ul style="list-style-type: none"><li>• Improved EMG physical therapy product through testing and creating designs. Researched the start-up market to provide information for initiating Series B funding.</li></ul>	

## *Robotics Projects*

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<b>TRASH: Tandem Rover and Aerial Scrap Harvester</b>	
<i>Capstone Project</i>	2022
<b>Visual and Spectral Terrain Classification in Unstructured Multi-Class Environments</b>	
<i>Contributor to IROS 2022 paper</i>	2022
<b>Northeastern's NASA RASC-AL Challenge Club</b>	
<i>Mobile Robotics Team Lead</i>	2021-2022
<b>Hack the Normal Hackathon</b>	
<i>SOAR</i>	2021

## *Extracurricular Activities*

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<b>Jewish Student Union Club</b>	
<i>Member</i>	2020-Present
<b>Disability Resource Center</b>	
<i>Notetaker for EE 2412 Fundamentals of Electronics</i>	2020-2021
<b>Dialogue of Civilizations in Israel</b>	
<i>Multiple Narratives and Cultural Complexities</i>	2019

## *Other Interests*

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<b>Running</b>	
<i>2023 Philadelphia Marathon, 2022 Pisa Marathon, 2020 Malden Half-Marathon</i>	2020-Present
<b>Six month backpacking trip in Southeast Asia</b>	
<i>Thailand, Cambodia, Vietnam, Malaysia</i>	2018