# Modeling Maxima with autoregressive conditional Fréchet model

Z. Zhao, Z. Zhang, R. Chen

December 10, 2020

Published on Journal of Econometrics (2018)

Presented by Liujun Chen

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#### Introduction

Maximum observations, as the representation of extreme behavior, are of particular interest.

- mutual fund managers: the potential maximum daily loss across all stocks in their managed portfolio
- high-frequency traders: the level of potential intra-day maximum loss

#### Introduction

Most applications of EVT focus on modeling extreme events in time series with a static approach under equilibrium distribution.

- The behavior of the underlying time series may change through time.
- Financial time series tends to exhibit structural changes and time-varying dynamics such as volatility clustering.

#### Introduction

Model time series of maxima  $\{Q_t\}$ , where  $\{Q_t\}$  is a univariate time series of maxima based on a set of underlying financial time series  $\{X_{it}\}_{i=1}^p$ . There are mainly two types of  $Q_t$ .

- time series of cross-sectional maxima e.g. modeling the maximum daily loss across a group of stocks in a portfolio
- the time series of intra-period maxima e.g. intra-day maxima of high-frequency trading losses that occur on the same day.

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# Dynamic Model

- A dynamic GEV framework: a conditional evolution scheme is designed for the parameters  $(\mu_t, \sigma_t, \xi_t)$  of GEV, so that time dependency of  $\{Q_t\}$  can be captured.
- Due to the heavy-tailedness of financial data,  $\{Q_t\}$  can marginally can be well modeled by Fréchet distribution.

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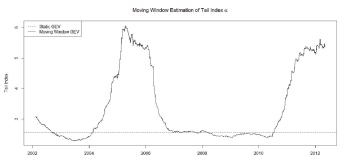
$$Q_t = \mu_t + \sigma_t Y_t^{1/\alpha_t},$$

where  $Y_t$  is a sequence of i.i.d. unit Fréchet random variables.

# Should $\alpha_t$ be dynamic?

- Ad-hoc moving-window GEV analysis on the cross-sectional maxima of negative daily log-returns of S&P 100 index
- The observation period is from January 1, 2000 to December 31, 2014 with 3773 trading days.
- For each trading day t, we record the maximum daily loss across the 100 stocks and denote it by  $Q_t$ , Hence the time series  $\{Q_t\}$  has 3773 observations
- For each  $500 \le t \le 3273$ , a GEV model is fitted using  $\{Q_k\}_{k=t-499}^{t+500}$ .

# Moving Window Estimatio of Tail Index $\alpha$



**Fig. 1.** Tail index  $\hat{\alpha}_t$  estimated by moving window of size 1000 (solid curve) v.s. tail index  $\hat{\alpha}$  estimated by the static GEV model based on total observations (dashed line).

# Model Specification

Specifically, the autoregressive conditional Fréchet(AcF) model assumes the form

$$\log \sigma_{t} = \beta_{0} + \beta_{1} \log \sigma_{t-1} + \eta_{1}(Q_{t-1})$$
$$\log \alpha_{t} = \gamma_{0} + \gamma_{1} \log \sigma_{t-1} + \eta_{2}(Q_{t-1}),$$

where  $\beta_1, \gamma_1 \geq 0$ . The log transform is used to ensure the positivity of the parameters.

Assume that  $\eta_1$  is a continuous increasing function and  $\eta_2$  is a continuous decreasing function of  $Q_{t-1}$ . Choose  $\eta_1, \eta_2$  to be the simple exponential function  $a_0 \exp(-a_1 x)$ .

# Model Specifiction

For the rest of the paper, we consider the following model:

$$Q_t = \mu + \sigma_t Y_t^{1/\alpha_t},$$

$$\log \sigma_t = \beta_0 + \beta_1 \log \sigma_{t-1} - \beta_2 \exp(-\beta_3 Q_{t-1}),$$
(\*)

$$\log \alpha_t = \gamma_0 + \gamma_1 \log \sigma_{t-1} + \gamma_2 \exp(-\gamma_3 Q_{t-1}),$$

where  $\{Y_t\}$  is a sequence of i.i.d. unit Fréchet random variables,  $0 \le \beta_1 \ne \gamma_1 < 1, \ \beta_2, \beta_3, \gamma_2, \gamma_3 > 0.$ 

#### Remark 1

- AcF can be easily extended to include  $q_1$  autoregressive terms of  $\log \sigma_t$  and  $\log \alpha_t$ , and  $q_2$  lagged terms of  $\eta(Q_t)$ , similar to that of GARCH $(q_1, q_2)$  model.
- Similar theoretical properties can be derived and similar estimation procedures can be used.
- Our empirical experience shows that the extension does not necessarily improve the performance of the model.

# Stationarity and ergodicity

The model can be written as

$$\log \sigma_t = \beta_0 + \beta_1 \log \sigma_{t-1} - \beta_2 \exp(-\beta_3 (\mu + \sigma_{t-1} Y_{t-1}^{1/\alpha_{t-1}})),$$

$$\log \alpha_t = \gamma_0 + \gamma_1 \log \sigma_{t-1} + \gamma_2 \exp(-\gamma_3 (\mu + \sigma_{t-1} Y_{t-1}^{1/\alpha_{t-1}})),$$

Hence,  $\{\sigma_t, \alpha_t\}$  form a homogeneous Markov chain in  $\mathbb{R}^2$ .

## Theorem (1)

For an AcF with  $\beta_2, \beta_3, \gamma_2, \gamma_3 > 0$ ,  $\beta_0, \gamma_0, \mu \in \mathbb{R}$  and  $0 \le \beta_1 \ne \gamma_1 < 1$ , the latent process  $\{\sigma_t, \alpha_t\}$  is stationary and geometrically ergodic.

# AcF under a factor model setting

We illustrate that the limiting form of maxima  $Q_t$  under a general factor model framework leads to an AcF model.

• Assume  $\{X_{it}\}_{i=1}^p$  follow a general factor model,

$$X_{it} = f_i(Z_{1t}, \ldots, Z_{dt}) + \sigma_{it}\varepsilon_{it},$$

- $\{X_{it}\}_{i=1}^p$  are observed time series at time t,  $\{Z_{1n},\ldots,Z_{dn}\}$  consist of observed and unobserved factors,  $\{\varepsilon_{it}\}_{i=1}^p$  are i.i.d. random noises that are independent with the factors  $\{Z_{id}\}_{i=1}^d$ .
- Assume that  $\{\varepsilon_{it}\}_{i=1}^p$  are in the domain of attraction of the Fréchet distribution.

# Other Assumptions for the factor model

- $\sup_{1 \le p < \infty} \sup_{1 \le i \le p} f_i(Z_{1t}, \dots, Z_{dt}) < \infty$  a.s.
- $\lim_{p \to \infty} \sum_{i=1}^p \sigma_{it}^{\alpha_t} = \infty$
- $\bullet \ \lim\nolimits_{p\to\infty}\sup\nolimits_{1\leq i\leq p}\frac{\sigma_{it}^{\alpha_t}}{\sum_{i=1}^p\sigma_{it}^{\alpha_{it}}}=0$

# Asymptotic conditional distribution of $Q_t$

#### Proposition (1)

Given 
$$F_{t-1}$$
, denote  $a_{pt}=0$  and  $b_{pt}=(\sum_{j=1}^p\sigma_{it}^{\alpha_t})^{1/\alpha_t}$ , we have, as  $p\to\infty$ , 
$$\frac{Q_t-a_{pt}}{b_{pt}}\stackrel{d}{\to} \exp(-x^{-\alpha_t}).$$

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# **MLE**

- denote all the parameters in the model by  $\theta = (\beta_0, \beta_1, \beta_2, \beta_3, \gamma_0, \gamma_1, \gamma_2, \gamma_3, \mu)$
- denote  $\Theta_s = \{\theta | \beta_0, \gamma_0, \mu \in \mathbb{R}, 0 \le \beta_1, \gamma_1 < 1, \beta_2, \beta_3, \gamma_2, \gamma_3 > 0\}$
- Assume that all allowable parameters are in  $\Theta_s$
- Denote the true parameter by  $\beta_0 = (\beta_0^0, \beta_1^0, \beta_2^0, \beta_3^0, \gamma_0^0, \gamma_1^0, \gamma_2^0, \gamma_3^0, \mu_0)$

### **MLE**

The conditional p.d.f. of  $Q_t$  given  $(\mu_t, \sigma_t, \alpha_t)$  is

$$f_t(\theta) = f(Q_t | \sigma_t, \alpha_t) = \alpha_t \sigma_t^{\sigma_t} (Q_t - \mu)^{-(\alpha_t + 1)} \exp\left\{-\sigma_t^{\alpha_t} (Q_t - \mu)^{-\alpha_t}\right\}.$$

Hence, by conditional independence, the log-likelihood function with observations  $\{Q_t\}_{t=1}^n$  is

$$L_n(\theta) = \frac{1}{n} \sum_{t=1}^n \log f_t(\theta)$$

$$= \frac{1}{n} \sum_{t=1}^n \log \alpha_t + \sigma_t \log \sigma_t - (\alpha_t + 1) \log(Q_t - \mu) - \sigma_t^{\alpha_t} (Q_t - \mu)^{-\alpha_t}$$

where  $\{\sigma_t, \alpha_t\}$  can be obtained recursively through (\*) with an initial value  $(\sigma_1, \alpha_1)$ .



#### Initial Value

- Notice here the true value of  $(\sigma_1, \alpha_1)$ , denoted as  $(\sigma_1^0, \alpha_1^0)$ , is an unknown since the state variables  $\{\sigma_t, \alpha_t\}$  is a hidden process.
- Fortunately, with  $0 \le \beta_1, \gamma_1 < 1$ , the influence of  $(\sigma_1, \alpha_1)$  on future  $(\sigma_t, \alpha_t)$  decays exponentially as t increases
- Hence its impact on parameter estimation will be minimum with a sufficiently large sample size.
- It will be shown that the consistency and asymptotic normality does not depend on the initial value.

# Asymptotic Properties

#### Theorem (Consistency)

Assume the parameter space  $\Theta$  is a compact set of  $\Theta_s$ . Suppose the observations  $\{Q_t\}_{t=1}^n$  are generated by a stationary and ergodic AcF with true parameter  $\theta_0$  and  $\theta_0$  is in the interior of  $\Theta$ , then there exists a sequence  $\theta_n$  of local maximizer of  $L_n(\theta)$  such that  $\theta_n \stackrel{p}{\to} \theta_0$  and  $||\theta_n - \theta_0|| \le \tau_n$  where  $\tau_n = O_p(n^{-r}), 0 < r < 1/2$ . Hence  $\hat{\theta}_n$  is consistent.

# Asymptotic Properties

#### Proposition (Asymptotic Uniqueness)

Denote  $V_n = \{\theta \in \Theta | \mu \le cQ_{n,1} + (1-c)\mu_0\}$  where  $Q_{n,1} = \min_{1 \le t \le n} Q_t$ , under the conditions in the Theorem for consistency, for any fixed 0 < c < 1, there exists a sequence of  $\hat{\theta}_n = \arg\max_{\theta \in V_n} \tilde{L}(\theta)$  such that,  $\hat{\theta}_n \stackrel{P}{\to} \theta_0$ ,  $||\theta_n - \theta_0|| \le \tau_n$  where  $\tau_n = O_p(n^{-r})$ , 0 < r < 1/2, and  $P(\hat{\theta}_n \text{ is the unique global maximizer of } \tilde{L}_n(\theta) \text{ over } V_n) \to 1$ .

# Asymptotic Properties

### Theorem (Asymptotic Normality)

Under the conditions in Theorem for consistency, we have that  $\sqrt{n}(\hat{\theta}_n - \theta_0) \stackrel{d}{\to} N(0, M_0^{-1})$ , where  $\hat{\theta}_n$  is that in Theorem of consistency and  $M_0$  is the Fisher Information matrix evaluated at  $\theta_0$ . Further, the sample variance of plug-in estimated score function  $\left\{\frac{\partial}{\partial \theta} \log f_t(\hat{\theta}_n)\right\}_{t=1}^n$  is a consistent estimator of  $M_0$ .

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# Convergence of maxima in factor model

- ullet we conduct numerical experiments to investigate the finite sample behavior of  $Q_t$
- Specifically, we study the convergence of the marginal distribution of  $Q_t$  to its Fréchet limit under a one-time period factor model.
- To simplify notation, we drop the time index *t* in this section.

# Convergence of maxima in factor model

We simulate data from the following one-factor linear model,

$$X_i = \beta_i Z + \sigma_i \varepsilon_i, \quad i = 1, \dots, p,$$

- $Z \sim N(0,1)$  is the latent model,
- $\beta_i$  are i.i.d. random coefficients generated from a uniform distribution U(-2,2)
- $\varepsilon_i$  are i.i.d. t-distributions with degree of freedom v
- $\sigma_i$  are i.i.d. random variables generated from a mixture of uniform distribution  $\frac{1}{2}U(0.5, 1.5) + \frac{1}{2}U(0.75, 1.25)$

# Finite sample empirical distribution of the maxima Q and its corresponding Fréchet limit

The empirical CDF of Q and its limiting Frechet CDF. df = 2df = 48.0 8.0 9.0 9.0 0.4 0.4 0.2 0.2 0.0 0.0 p=10 p=100 p=1000 Frechet Limit df = 8 df = 60.1 0.8 0.8 9.0 9.0 0.4 0.4 0.2 0.2 0.0 0.0

### AcF estimation for conditional VaR of maxima

- ullet temporal approximation ability of AcF to the maxima  $\{Q_t\}$  process from a general factor model
- Model the  $\{Q_t\}$  process using AcF and calculate the corresponding  $cVaR_t^q$  for  $Q_t$  using the fitted AcF.
- $cVaR_t^q$  is defined as the 1-q extreme quantile of  $Q_t$  given all past information  $\mathcal{F}_{t-1}$

# Model Setting

• Simulate  $\{Q_t\}$  process from a similar one-factor linear model:

$$X_i = 0.09(\beta_i Z_t + \sigma_i \varepsilon_{it}), \quad i = 1, \ldots, p,$$

- p = 100
- $v_t = \gamma_0 + \gamma_1 \log v_{t-1} + \gamma_2 \exp(-\gamma_3 Q_{t-1})$  with  $(\gamma_0, \gamma_1, \gamma_2, \gamma_3) = (-0.1, 0.9, 0.3, 5)$

#### Model Evaluation

- First fit AcF based on the training set  $\{Q_t\}_{t=1}^{T_1}$ .
- Then using fitted AcF, calculate  $cVaR_t^q$  for each  $Q_t$  on the test set  $\{Q_t\}_{t=T_1+1}^{T_1+T_2}$
- The true  $\{Q_t\}_{t=T_1+1}^{T_1+T_2}$  are then compared with the  $\{cVaR_t^q\}_{t=T_1+1}^{T_1+T_2}$  and the number of violations is recorded.
- A violation happens when the observed daily maxima  $Q_t$  is larger than the corresponding  $cVaR_t^q$  given by AcF.
- If AcF approximates the tail behavior of  $\{Q_t\}$  process well, the expected proportion of violations in the test set should be close to q.

#### Model Evaluation

- Also, assess the goodness of approximation by calculating the correlation between the true process  $v_t$  and the estimated process  $\hat{\alpha}_t$  by AcF
- $T_1 = 1000, 2000, 5000$   $T_2 = 100$  and  $q^0 = 0.1, 0.05, 0.01$
- repeat 500 times
- calculate the average violation times  $\bar{q}$ , mean and the median of the correlation.

### Simulation Results

**Table 1**The performance of AcF on approximation of 1-day conditional VaR for  $\{Q_t\}$  process with independent errors  $\varepsilon_{it}$  and the correlation between the true tail index and the one estimated by AcF.

$T_1$	$\bar{q}(q^0=0.1)$	$\bar{q}(q^0 = 0.05)$	$\bar{q}(q^0 = 0.01)$	mean cor.	median cor.
1000	0.095	0.049	0.012	0.871	0.928
2000	0.096	0.049	0.012	0.909	0.952
5000	0.097	0.051	0.012	0.947	0.973

## Performance of the MLE

To study the finite sample performance of the MLE, simulate the data from an AcF with the following parameters  $(\beta_0, \beta_1, \beta_2, \beta_3, \gamma_0, \gamma_1, \gamma_2, \gamma_3, \mu) = (-0.050, 0.96, -0.051, 6.68, -0.068, 0.89, 0.33, 5.33, -0.069)$ 

## Simulation Result

**Table 4**Numerical results for performance of MLE with sample size 1000, 5000, 10 000. Mean and S.D. are the sample mean and standard deviation of the MLE's obtained from 500 simulations. 90% C.I. reports the coverage rate of the 90% C.I. constructed from the estimated Fisher Information matrix; 95% C.I. and 99% C.I. report corresponding coverage rates.

N = 1000	<b>Y</b> 0	γ1	$\gamma_2$	γ <sub>3</sub>	$\beta_0$	$\beta_1$	$\beta_2$	$\beta_3$	$\mu$
True value	-0.068	0.890	0.330	5.33	-0.050	0.960	-0.051	6.68	-0.069
Mean	-0.060	0.884	0.346	6.28	-0.051	0.956	-0.054	5.88	-0.066
S.D.	0.029	0.028	0.058	1.93	0.028	0.019	0.023	3.25	0.011
90% C.I.	81	82	90	91	85	81	75	78	88
95% C.I.	84	88	93	94	87	87	79	80	95
99% C.I.	88	92	97	97	95	94	87	85	98
N = 5000	2/0	<i>γ</i> 1	<i>Y</i> 2	<i>Y</i> 3	$\beta_0$	$\beta_1$	$\beta_2$	$\beta_3$	μ
True value	-0.068	0.890	0.330	5.33	-0.050	0.960	-0.051	6.68	-0.069
Mean	-0.066	0.889	0.332	5.52	-0.051	0.959	-0.052	6.53	-0.069
S.D.	0.014	0.012	0.029	0.88	0.012	0.008	0.009	1.83	0.005
90% C.I.	88	87	90	85	88	87	88	87	86
95% C.I.	92	96	93	94	92	91	93	93	94
99% C.I.	95	99	98	99	98	98	97	97	99
N = 10000	2/0	γ1	<b>Y</b> 2	<i>Y</i> 3	$\beta_0$	$\beta_1$	$\beta_2$	$\beta_3$	μ
True value	-0.068	0.890	0.330	5.33	-0.050	0.960	-0.051	6.68	-0.069
Mean	-0.067	0.890	0.330	5.44	-0.050	0.960	-0.051	6.55	-0.069
S.D.	0.010	0.007	0.018	0.61	0.007	0.005	0.006	1.37	0.003
90% C.I.	90	88	88	85	89	89	86	89	90
95% C.I.	93	94	94	94	92	94	93	94	98
99% C.I.	98	100	100	99	97	98	98	98	99

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# Cross-sectional maxima of the negative daily log-returns of stocks

 Table 5

 MLE for cross-sectional maxima of negative daily log-returns for S&P100 (top) and DJI30 (bottom) from January 1, 2000 to December 31, 2014.

S&P100	<b>y</b> 0	γ1	<i>γ</i> 2	γ3	$\beta_0$	$\beta_1$	$\beta_2$	$\beta_3$	μ		
Mean S.D.	-0.068 0.014	0.890 0.013	0.328 0.063	5.33 1.27	-0.050 0.006	0.961 0.004	-0.051 0.0072	6.68 1.01	-0.069 0.006		
DJI30	7/0	γ1	<i>γ</i> 2	γ3	$\beta_0$	$\beta_1$	$\beta_2$	$\beta_3$	μ		
Mean S.D.	0.023 0.016	0.895 0.013	0.261 0.041	16.32 3.529	-0.052 0.005	0.964 0.004	-0.047 0.0066	7.38 0.813	-0.059 0.006		

2005

# Cross-sectional maxima of the negative daily log-returns of stocks

# Tail Index Plot for SP100 Tail Index (top) Cross-sectional Max Daily Loss (bottom)



2010

2000

2015

# Intra-day maxima of 3-minute negative log-returns for USD/JPY foreign exchange rate

 Table 6

 MLE for intra-day maxima of 3-minute negative log-returns for USD/JPY from January 1, 2008 to June 26, 2013.

	<b>y</b> '0	γ1	<i>γ</i> 2	γ <sub>3</sub>	$\beta_0$	$\beta_1$	$\beta_2$	$\beta_3$	$\mu$
Mean	0.448	0.587	0.658	20.84	-0.120	0.890	-0.195 $0.024$	6.59	-0.051
S.D.	0.144	0.123	0.203	4.52	0.016	0.012		0.955	0.010

# Intra-day maxima of 3-minute negative log-returns for USD/JPY foreign exchange rate

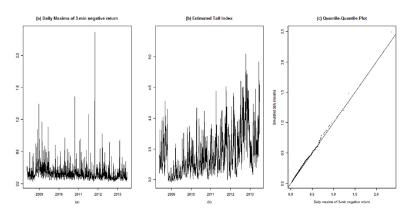


Fig. 7. (a) Daily maxima of 3-minute negative log-returns of USD/JPY from January 1, 2008 to June 26 2013; (b) Estimated tail index  $\{\hat{a}_t\}$  from the fitted AcF; (c) Quantile-quantile plot of real data and simulated data from the fitted AcF.

