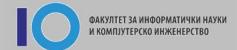
Search trees Algorithms and data structures - lectures -

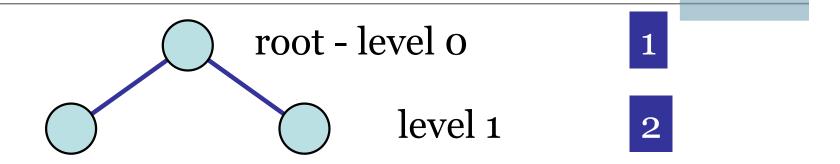




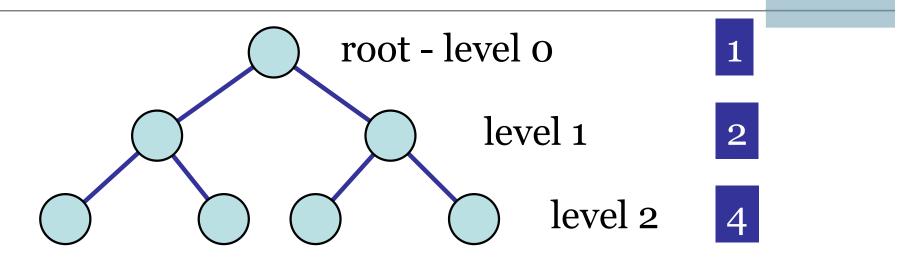
root - level o

1

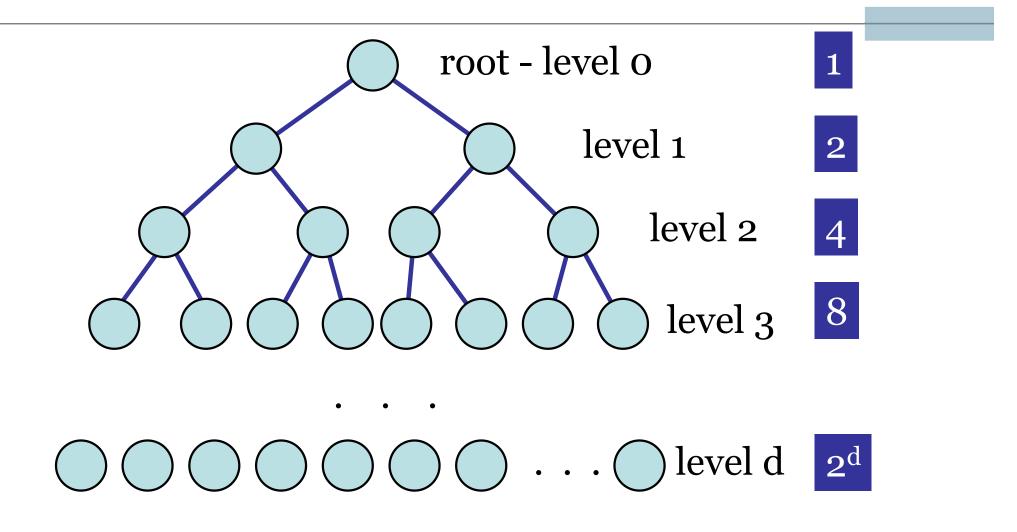




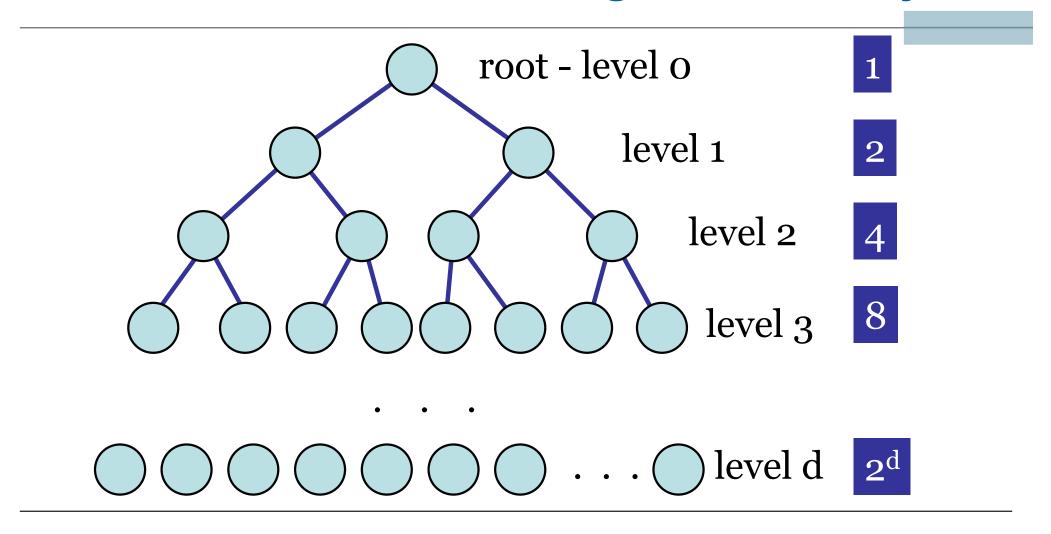












$$1 + 2 + 4 + \ldots + 2^d = 2^{d+1} - 1$$

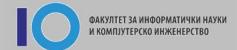


if there is a binary tree with n nodes and tree depth d, then

$$n \leq 2^d - 1$$

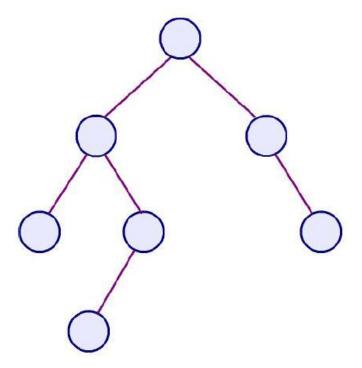
the minimal depth of the binary tree with n nodes can be calculated with

$$d_{\min} = \lceil \log_2(n+1) \rceil$$



Balanced binary tree

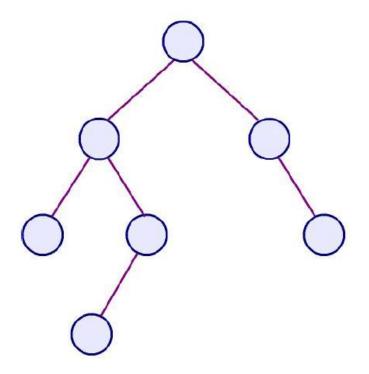
□ A balanced binary tree is a binary tree where for each node in the tree, the heights of its left and right subtrees do not differ by more than one.

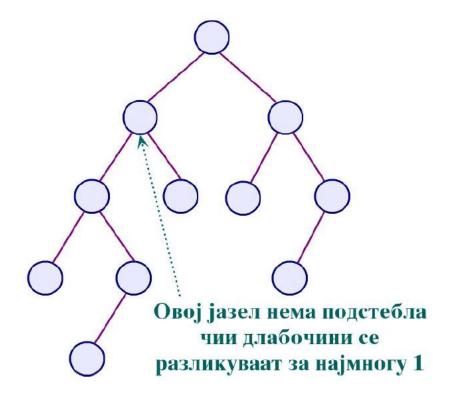




Balanced binary tree

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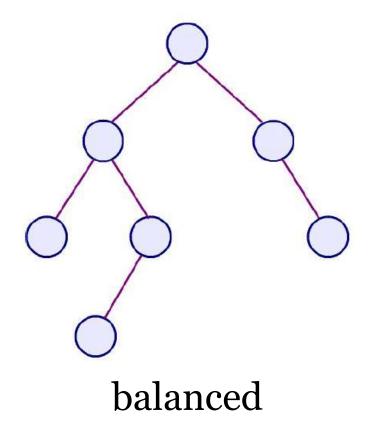


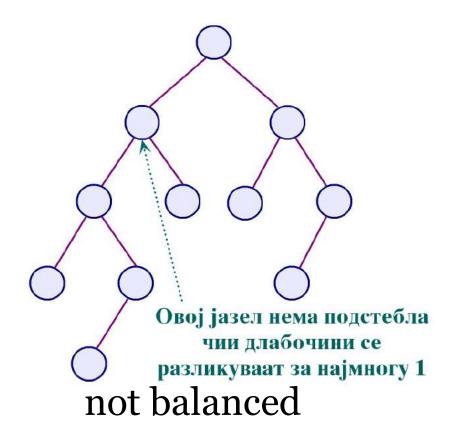




Balanced binary tree

□ A balanced binary tree is a binary tree where for each node in the tree, the heights of its left and right subtrees do not differ by more than one.

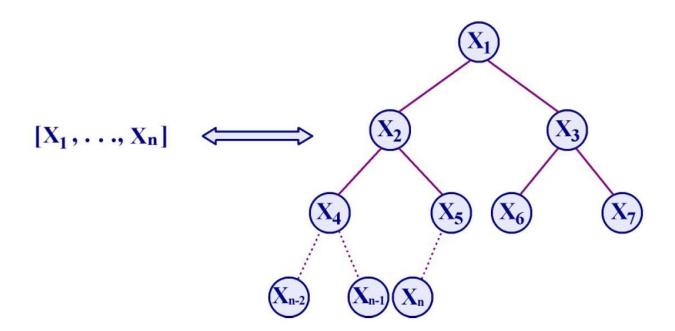






Balanced binary tree application - Heap tree

- A given sequence $(x_1, ..., x_n)$ can be represented in a form of a binary tree
- In doing so, the tree is filled from the root to the leaves in a way that it will be maximally filled





Balanced binary tree application - Heap tree

A heap tree is a complete binary tree for which the key value of the parent node is greater than or equal to the key value of its children, for each node in the tree

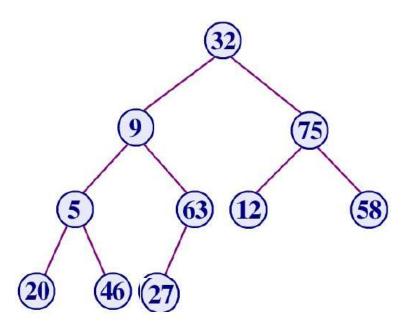
- We will show that inserting and deleting an element in such a tree has complexity O(logN)
- Heap trees are used in the implementation of efficient algorithms for sorting and implementation of priority lists



- Steps in heap sort algorithm:
 - Create a heap tree
 - Until the heap tree is empty
 - place the entry (key) from the root of the heap tree into the resulting sorted array
 - remove that element from the heap tree
 - form a heap tree again
 - Each node R_j has children R_{2j} and R_{2j+1}.
- Heap trees / Heap sort visualization
 - https://www.cs.usfca.edu/~galles/visualization/Heap.html

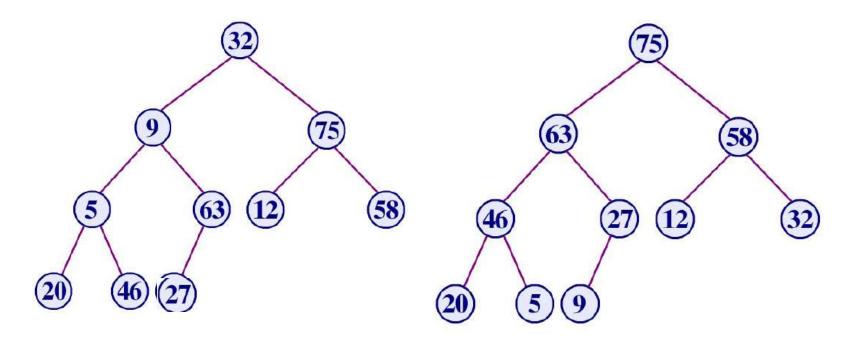


Input array: 32, 9, 75, 5, 63, 12, 58, 20, 46, 27



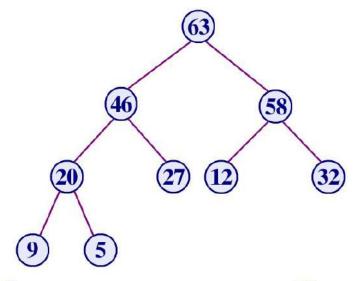


Input array: 32, 9, 75, 5, 63, 12, 58, 20, 46, 27



Initial heap tree





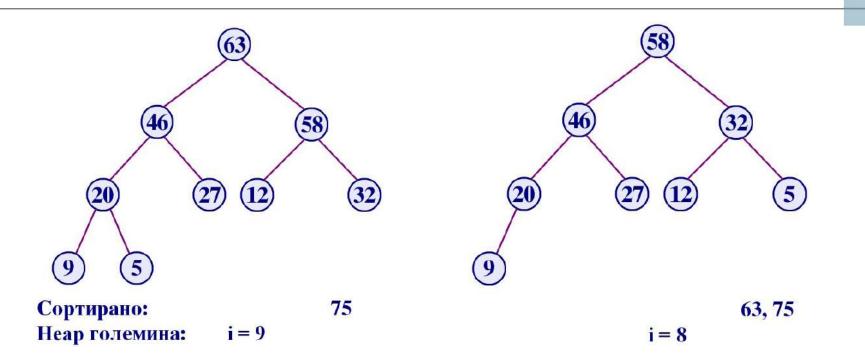
Сортирано:

75

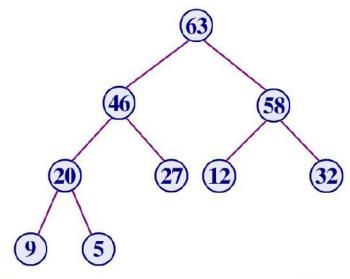
Неар големина:

i = 9







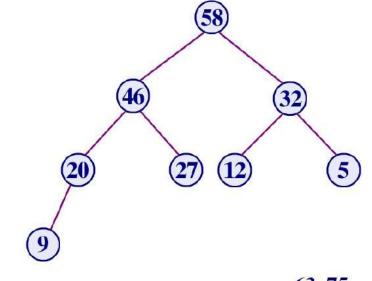


Сортирано:

Неар големина:

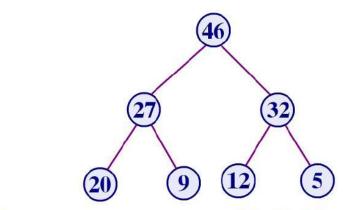
75

i = 9



63, 75

i = 8



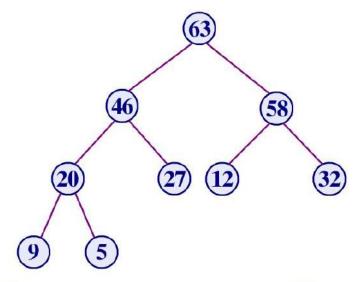
Сортирано:

58, 63, 75

Неар големина:

i = 7



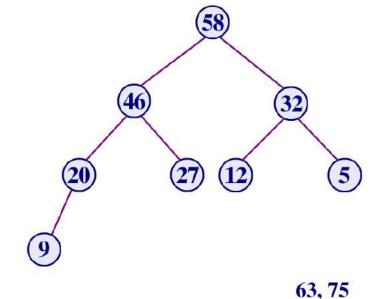


Сортирано:

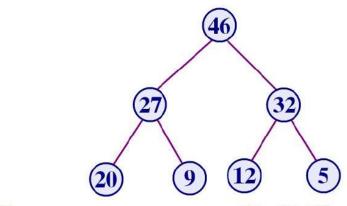
Неар големина:

75

i = 9



i = 8

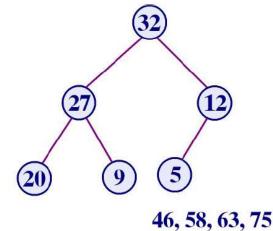


Сортирано:

58, 63, 75

Неар големина:

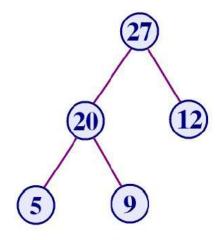
i = 7



46, 58, 63, 75

i = 6

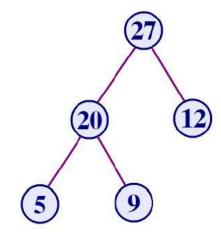




Сортирано: 32, 46, 58, 63, 75

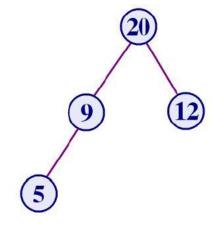
Heap големина: i = 5





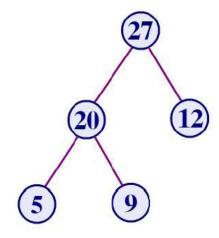
Сортирано: 32, 46, 58, 63, 75

Heap големина: i = 5



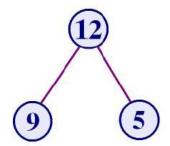
27, 32, 46, 58, 63, 75 i = 4





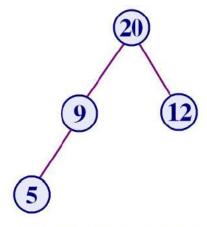
Сортирано: 32, 46, 58, 63, 75

Неар големина: i = 5



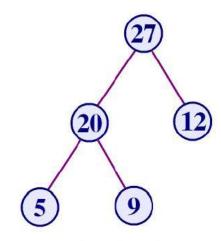
Сортирано: 20, 27, 32, 46, 58, 63, 75

Heap големина: i = 3



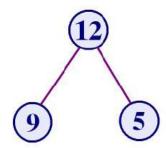
27, 32, 46, 58, 63, 75 i = 4





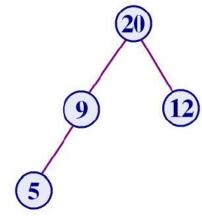
Сортирано: 32, 46, 58, 63, 75

Неар големина: i = 5

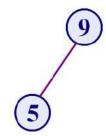


Сортирано: 20, 27, 32, 46, 58, 63, 75

Heap големина: i = 3

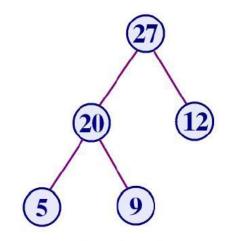


27, 32, 46, 58, 63, 75 i = 4



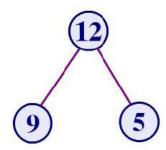
12, 20, 27, 32, 46, 58, 63, 75 i = 2





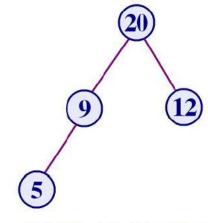
Сортирано: 32, 46, 58, 63, 75

Неар големина: i = 5

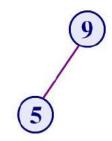


Сортирано: 20, 27, 32, 46, 58, 63, 75

Heap големина: i = 3



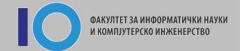
27, 32, 46, 58, 63, 75i = 4



12, 20, 27, 32, 46, 58, 63, 75 i = 2

Сортирано:

5, 9, 12, 15, 27, 32, 46, 58, 63, 77 резултат



```
procedure ADJUST (i,n)
R \leftarrow R_i; K \leftarrow K_i; j \leftarrow 2i
while j \leq n do
    if j < n and K_j < K_{j+1} then j \leftarrow j+1
    if K \geq K_j then exit
    R_{\lfloor j/2 \rfloor} \leftarrow R_j; j \leftarrow 2j
end
R_{\lfloor j/2 \rfloor} \leftarrow R
end ADJUST

Algorith

O

procedure HSORT (R,n)
```

Algorithms complexity *O(nlogn)*

```
procedure HSORT (R,n)

for i \leftarrow \lfloor n/2 \rfloor to 1 by -1 do call ADJUST (i,n)

for i \leftarrow n-1 to 1 by -1 do

T \leftarrow R_{i+1}; R_{i+1} \leftarrow R_1; R_1 \leftarrow T;

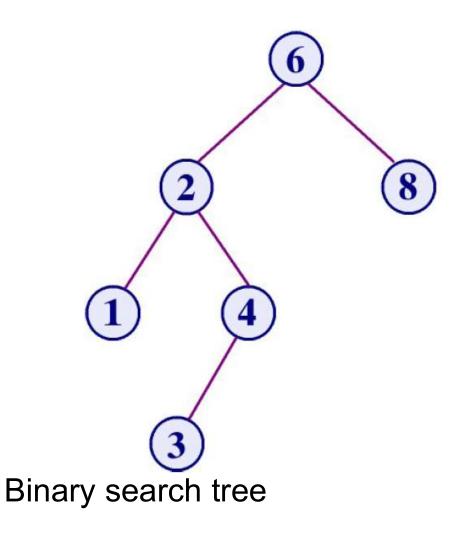
call ADJUST (1,i)

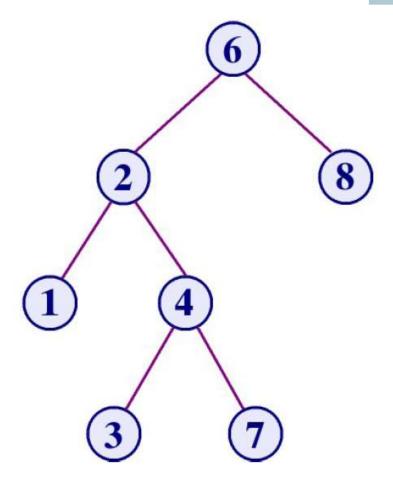
end HSORT
```



- Each node in the tree contains information called key
- For each node that has a value X for the key, the following rule applies:
 - all nodes of its left subtree have key values less than the X value
 - all nodes of its right subtree have key values greater than the X value
 - no duplicate keys







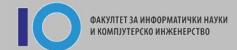
NOT a binary search tree



- Interesting properties of binary search trees:
 - How to find the node with the smallest key value?
 - How to find the node with the highest key value?
 - What do you get when the tree is traversed in inorder?



■ Definition of a node for a binary search tree:



☐ Definition of a node for a binary search tree:

The definition of a node is the same as the definition of a node of any binary tree!

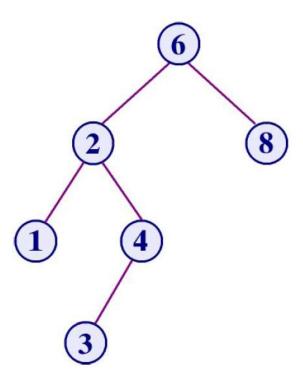


- Operations with binary search trees:
 - inserting a node into the tree
 - deleting a node from the tree
 - search through the tree

■ Visualization : https://visualgo.net/bn/bst

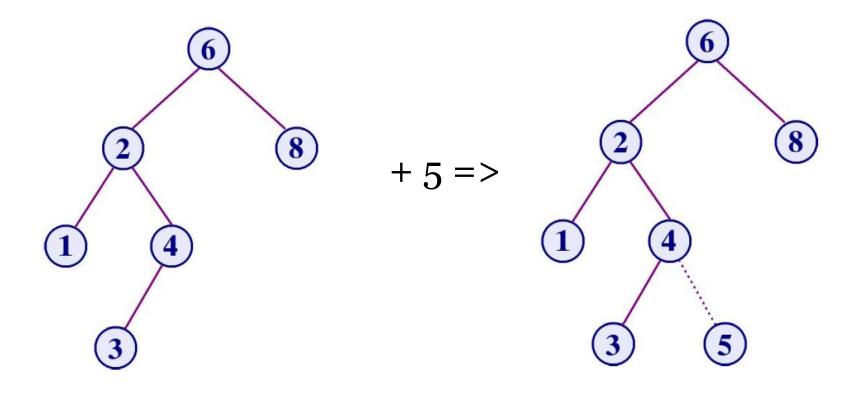


Inserting a node:





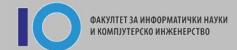
Inserting a node:



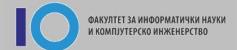


Inserting a node:

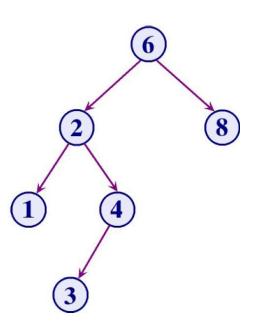
```
TREE-INSERT (T, z)
  y \leftarrow \text{NULL}
  x \leftarrow root[T]
  while x \neq \text{NULL}
  do begin
           V \leftarrow X
            if key[z] < key[x] then x \leftarrow left[x]
           else x \leftarrow right[x]
   end do
   if y = \text{NULL} then root[T] \leftarrow z
  else if key[z] < key[y] then left[y] \leftarrow z
          else right[y] \leftarrow z
```



- Deleting a node:
 - this operation is a bit more complicated
 - deleting a node that is a leaf
 - deleting a node that has one child
 - deleting a node that has two children

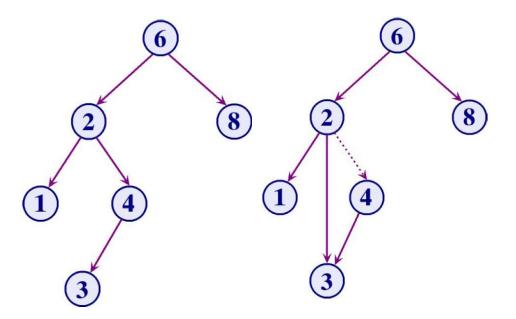


Deleting a node:



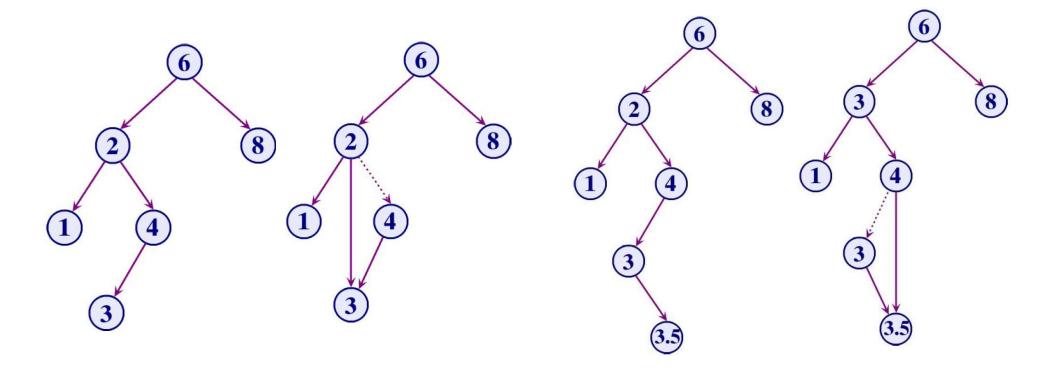


Deleting a node:





Deleting a node:





```
delete ( element type x, SEARCH TREE T )
  tree ptr tmp cell, child;
  if( T == NULL )
     error("Elementot ne e pronajden");
  else
  if( x < T->element ) /* Odi levo */
     T->left = delete(x, T->left);
  else
      if( x > T->element ) /* Odi desno */
         T->right = delete(x, T->right);
     else /* Najdeniot element da se izbrise */
      if( T->left && T->right ) /* Dve deca */
      { /* Zameni so najmaliot od desnoto podsteblo */
         tmp cell = find min( T->right );
         T->element = tmp_cell->element;
         T->right = delete( T->element, T->right );
     else /* Edno dete */
```





Search in the tree:

```
recursive
```

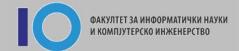
```
TREE-SEARCH (x, k)

if x = \text{NULL} or k = key[x]

then return x

if k < key[x] then return TREE-SEARCH (left[x], k)

else return TREE-SEARCH (right[x], k)
```



Search in the tree :

```
recursive
```

```
TREE-SEARCH (x, k)

if x = \text{NULL} or k = key[x]

then return x

if k < key[x] then return TREE-SEARCH (left[x], k)

else return TREE-SEARCH (right[x], k)
```

```
nonrecursive
```

```
ITERATIVE-TREE-SEARCH (x,k)

while x \neq \text{NULL} and k \neq key[x] do

if k < key[x] then x \leftarrow left[x]

else x \leftarrow right[x]

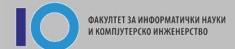
return x
```

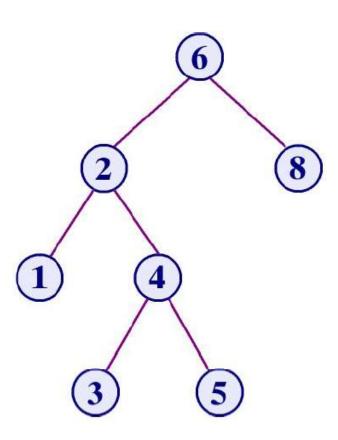


- The duration of all considered operations in binary search trees depends on the height of the node to be processed
- □ The level of nodes in an n-element tree can vary significantly in the interval from log₂n to n
- If we want better performance, the tree should be balanced

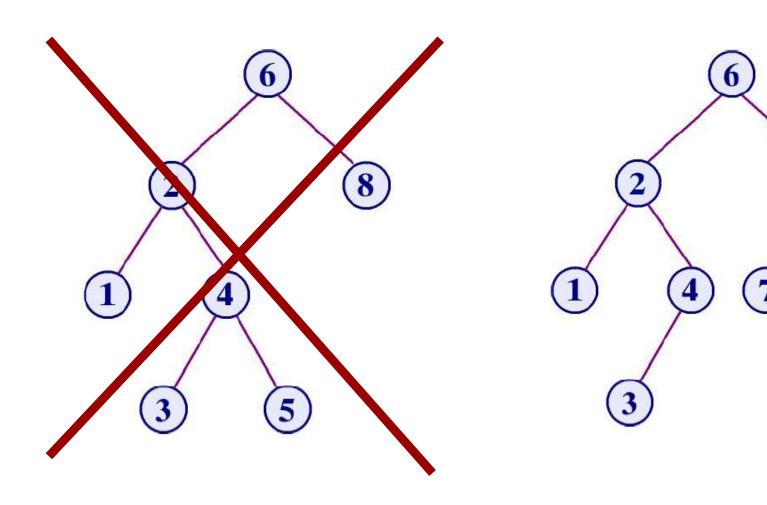


- AVL (Adelson-Velskii & Landis) tree is a binary search tree that is also a balanced tree
- □ This ensures that the depth of the tree (and thus the complexity of the most common operations) is of order O(log n)



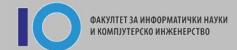








- AVL trees perform better
- The realization of these trees must be done programmatically
- Node insertion and deletion operations will be more complicated than the same operations in binary search trees

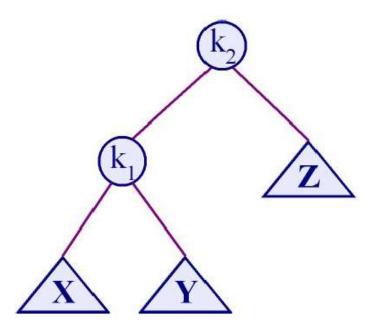


- AVL trees perform better
- The realization of these trees must be done programmatically
- Node insertion and deletion operations will be more complicated than the same operations in binary search trees

Problem: A violation of the balance of the tree!

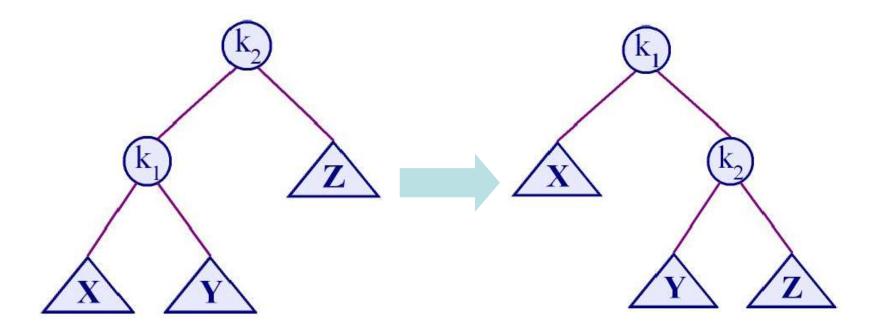


□ The balance of an AVL tree is maintained by a single node rotation operation

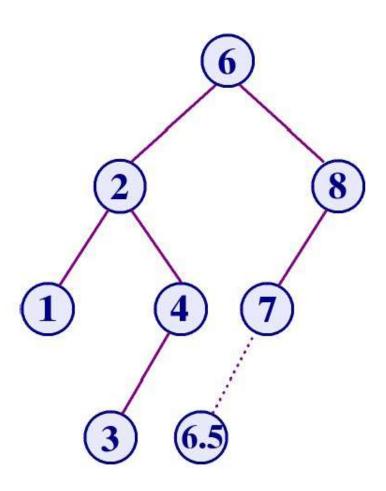




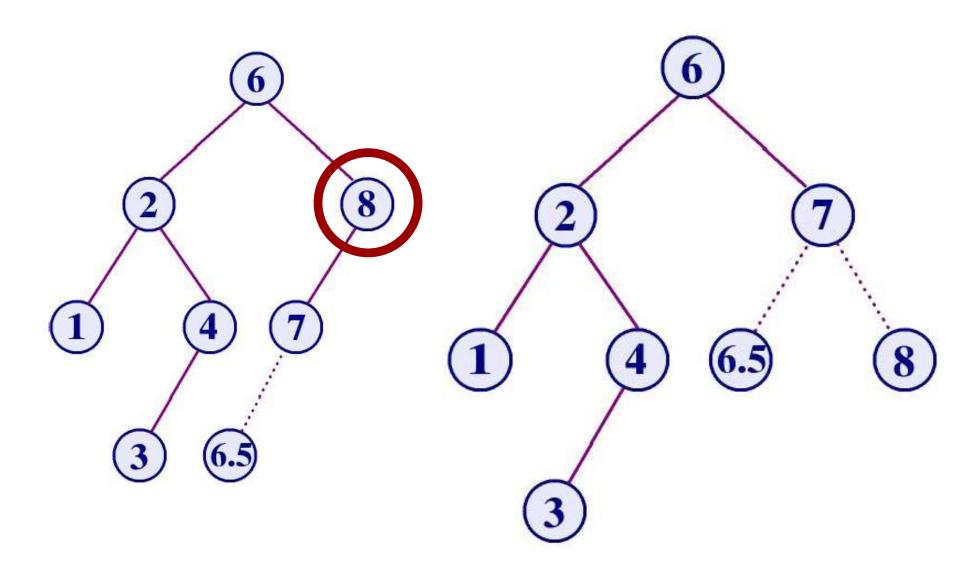
□ The balance of an AVL tree is maintained by a single node rotation operation





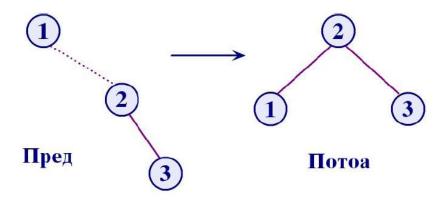






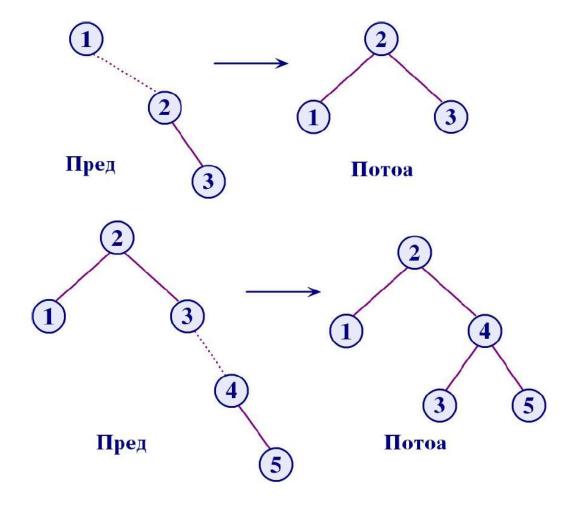


Example: Building an AVL tree from the values 1, 2, 3, 4, 5, 6 and 7

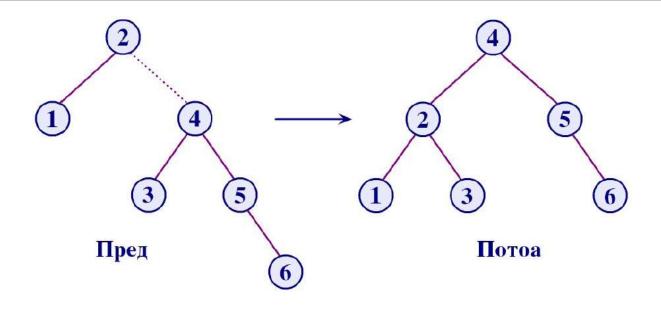




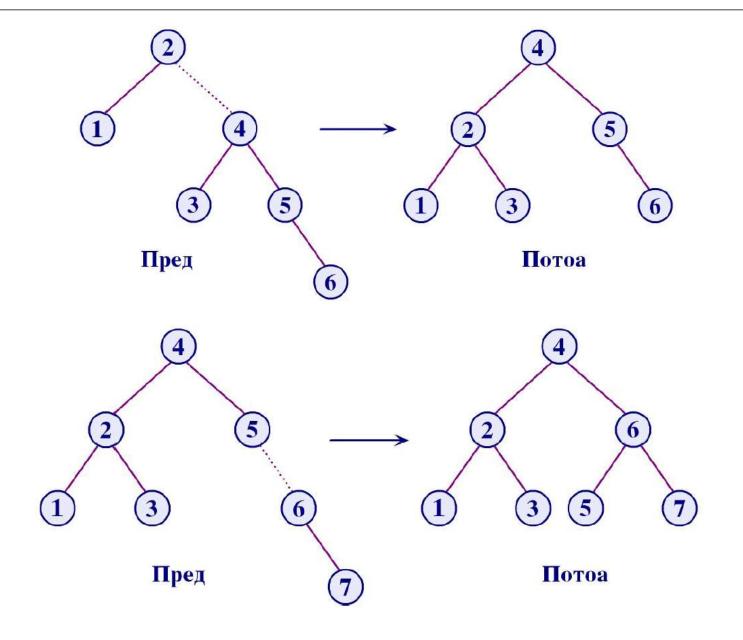
■ Example: Building an AVL tree from the values 1, 2, 3, 4, 5, 6 and 7



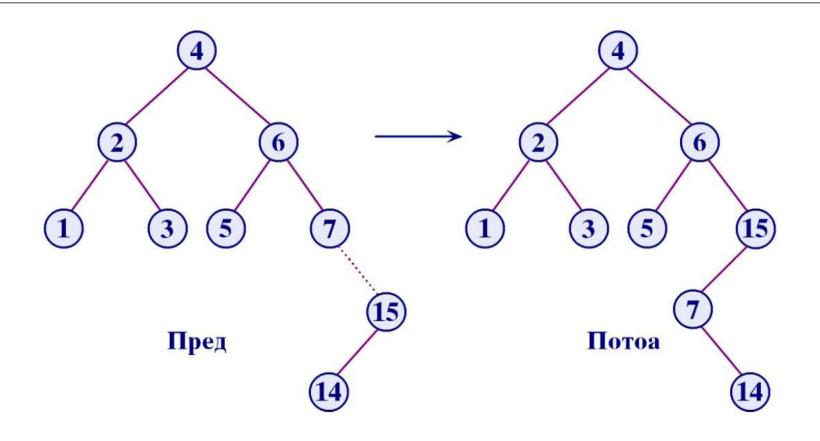


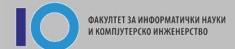


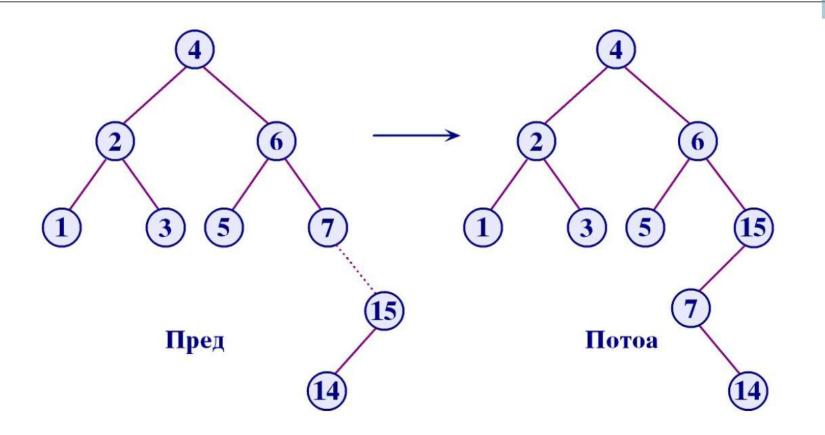












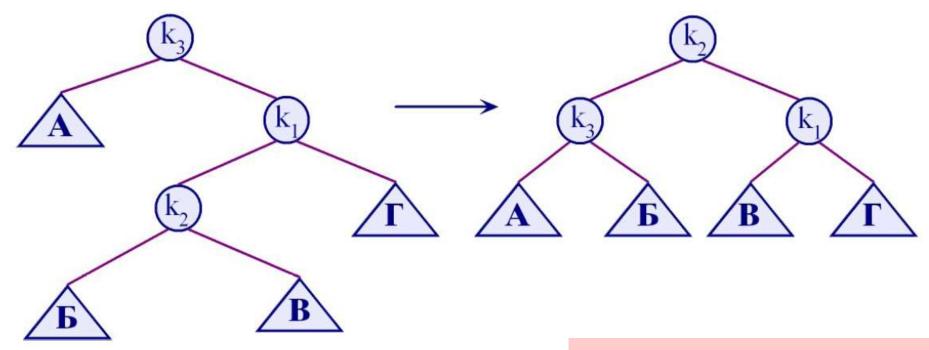
Problem: A single rotation does not help balance the tree in this case!



- Entering key 14 causes an imbalance, but applying a single rotation to the left does not resolve it
- □ This is because the newly entered key is an element (the element that visually goes towards the middle of the subtree) that is:
 - larger than some left subtree
 - smaller than some right subtree



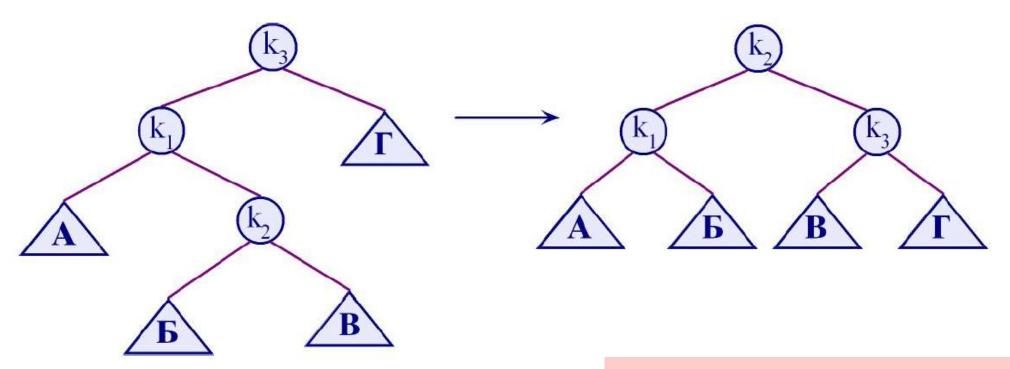
Double node rotation



double rotation right - left

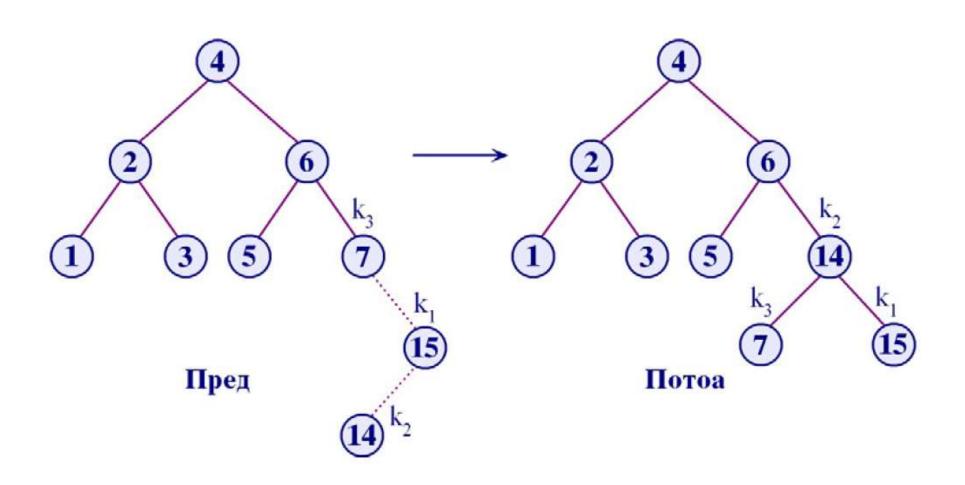


Double node rotation



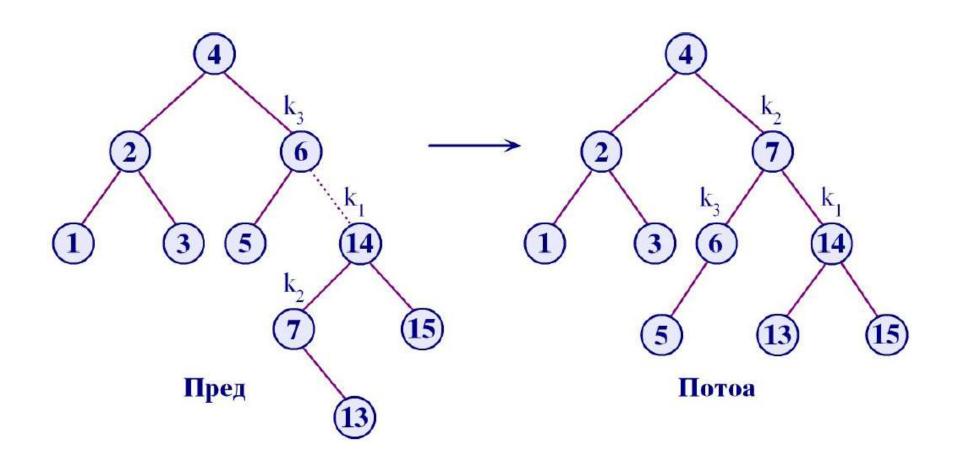
double rotation left - right

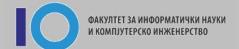


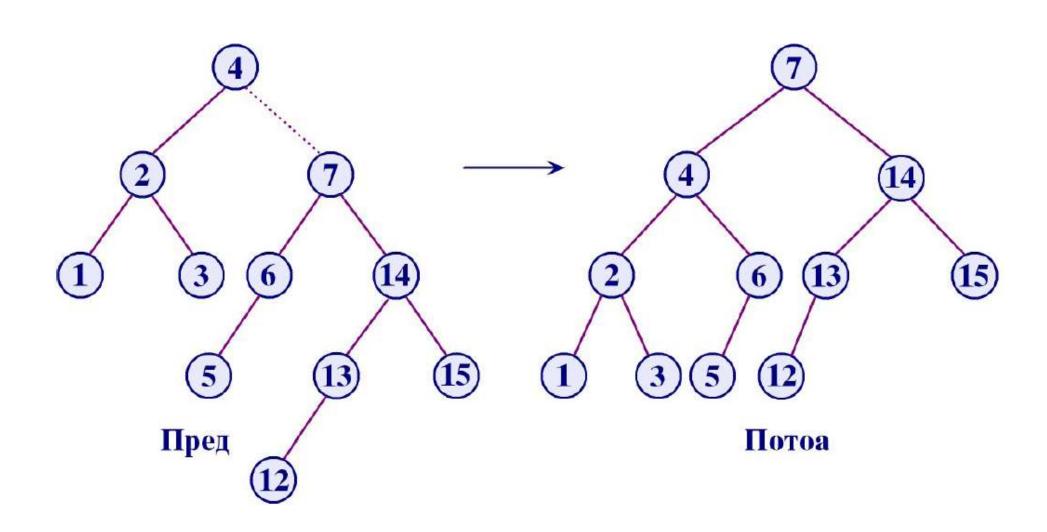




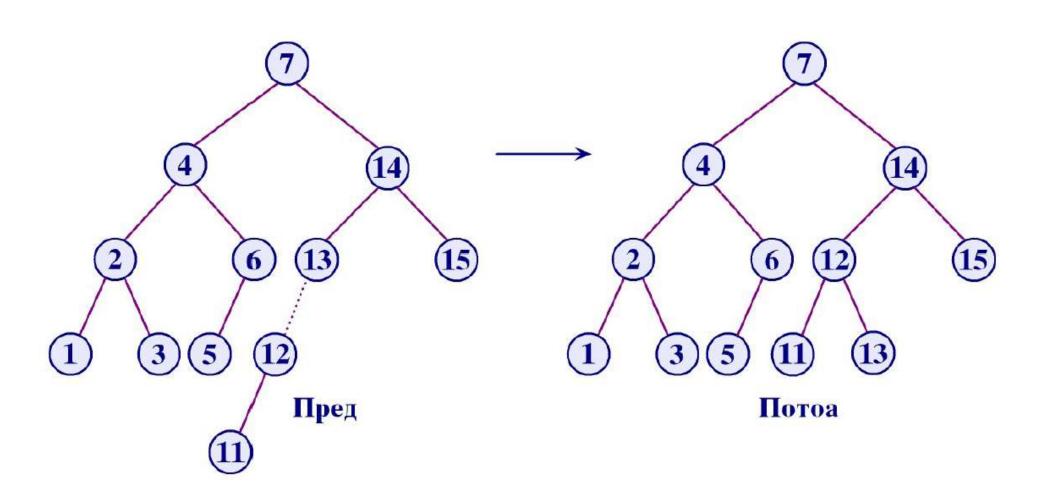
Let's successively proceed by entering information nodes 13, 12, 11, 10, 9 and 8



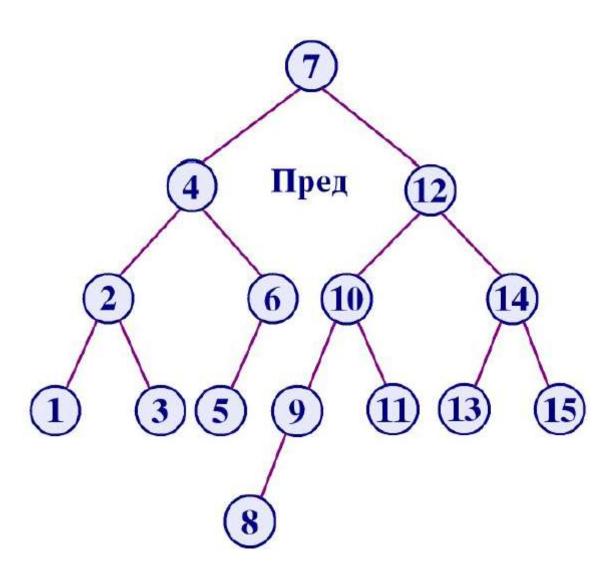














- □ The node deletion operation is much more complicated than the node insertion operation.
- □ The most commonly used is the so-called "lazy" deletion, which marks the nodes that are not used, but does not physically remove them.



B - trees

- Nonbinary search trees (B, B+, B*, R…)
- □ B-tree of order m is a tree with the following structural properties:
 - The root is either a leaf or has between 2 and m children
 - All internal nodes (except the root) have between $\lceil m/2 \rceil$ and m children
 - All leaves are at the same level

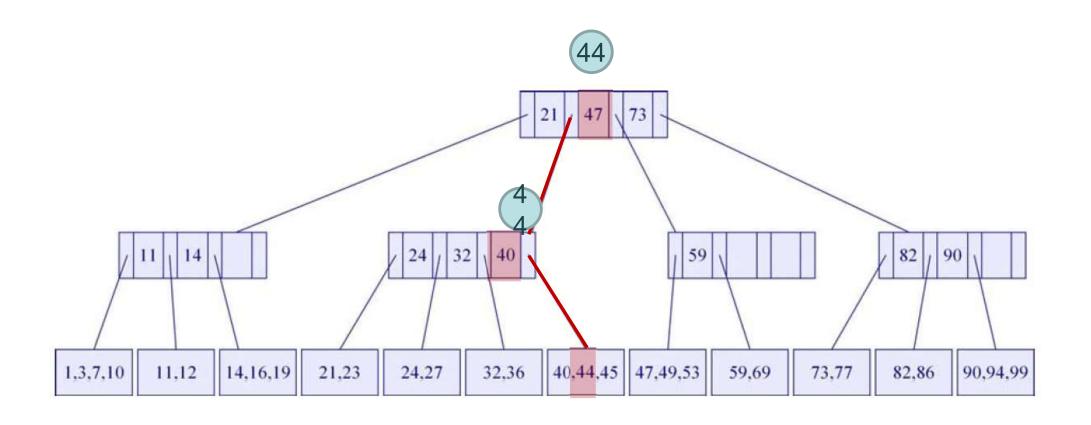


B - trees

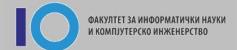
- ☐ Characteristic operations in B-trees:
 - search
 - inserting a value
 - deleting a value



Example: B – tree of order 4



Search: 44

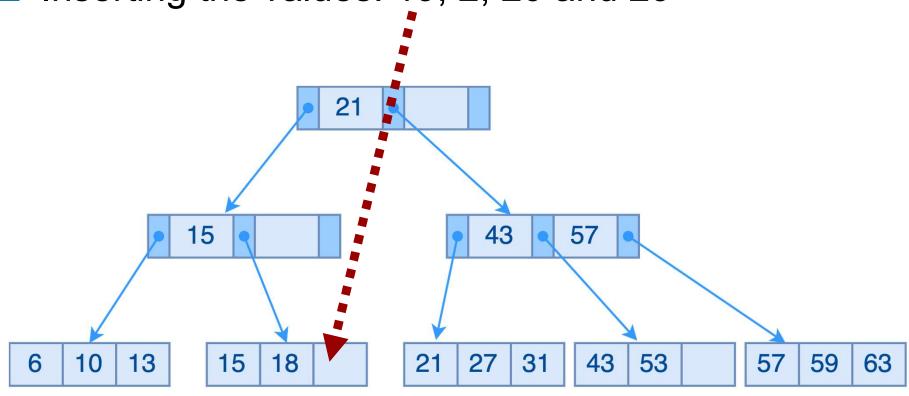


B - trees

- Inserting a value in a B-tree:
 - Finding the node where the value should be inserted
 - Splitting the node
 - if the principles of the B-tree are not preserved
 - the node has more values than allowed in this case the node
 splitting process is applied
 - it can also cause splitting of nodes in higher levels as well

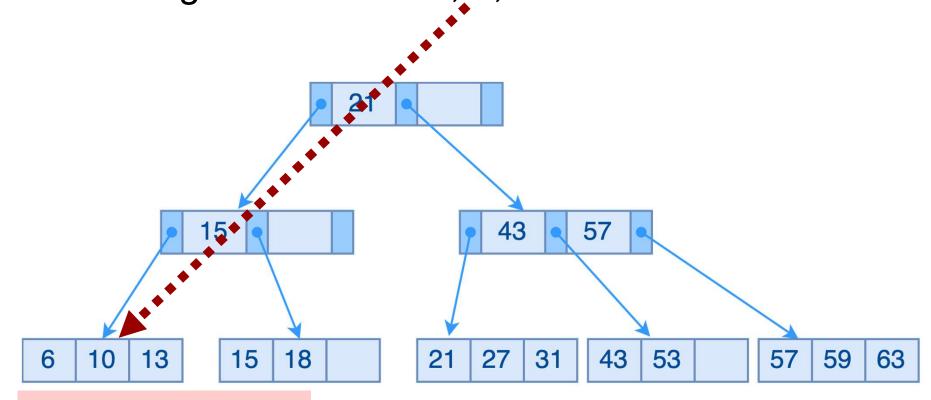


☐ Inserting the values: 19, 2, 20 and 29





☐ Inserting the values: 19, 2, 20 and 29



Problem:

This terminal node is full!

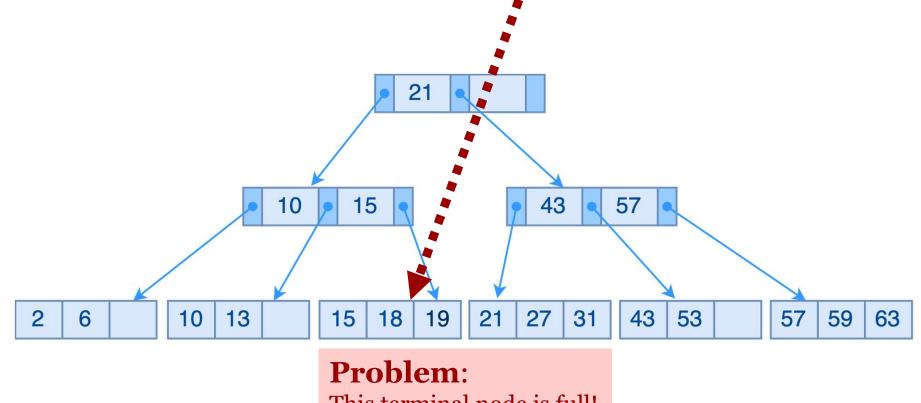
Solution:

Node splitting!

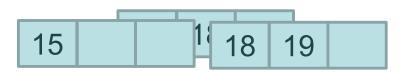
6 10 13



■ Inserting the values: 19, 2, 20 and 29

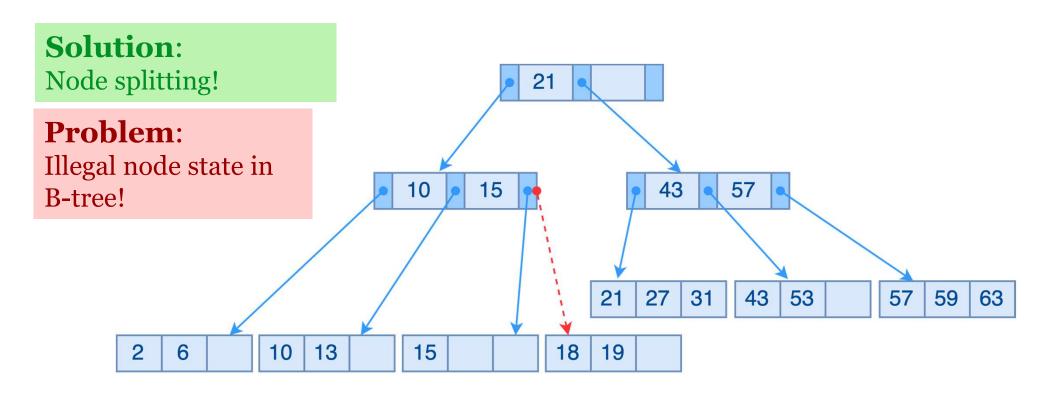


This terminal node is full!





☐ Inserting the values: 19, 2, 20 and 29







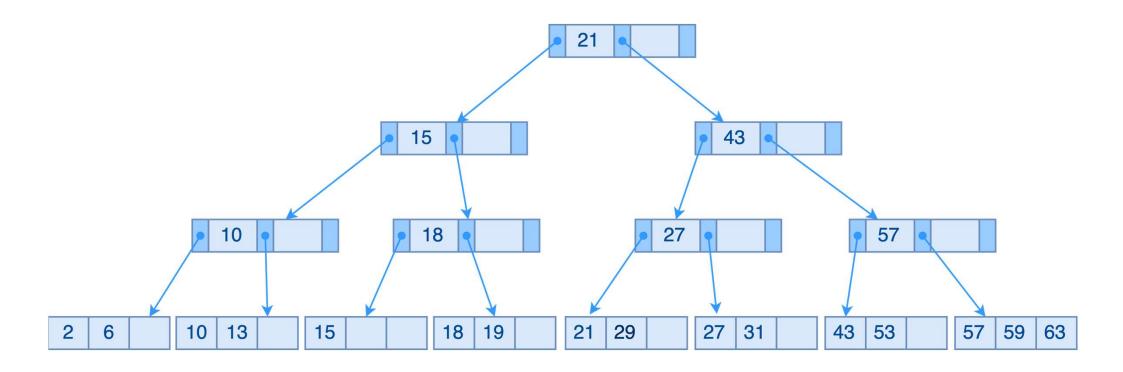


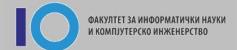
The value of ? is taken to be the leftmost value of the right child, and 15 goes up one level



☐ Inserting the values: 19, 2, 20 and 29 problem



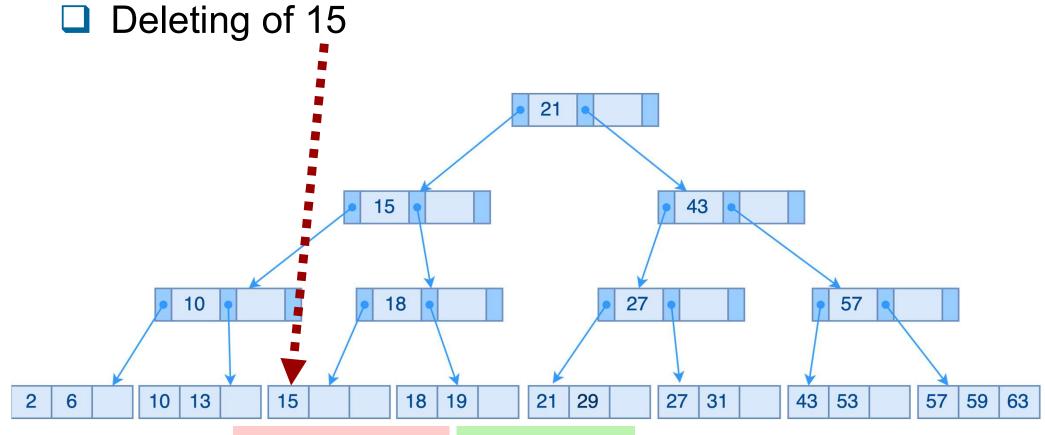




B - trees

- Deleting a value from a B-tree:
 - Finding the value
 - Removing the value from the node
 - the principles of the B-tree are preserved
 - if the node has fewer values than allowed in this case the node merging process is applied





Problem:

The node violates the B-tree structure

Solution:

Merging neighbouring nodes



□ Deleting of 15

