Computer Vision_HW9

Command Line

python main.py Robert
python main.py Prewitt
python main.py Sobel
python main.py FAC
python main.py Kirsch
python main.py Robinson
python main.py NevatiaBabu

Threshold

Enter Threshold: (choose any threshold you want)

- Two Main Function
 - 1. 平方和開根號

```
def Magnitude(pixel, mask):
    num = len(mask)
    sizeY = len(mask[0])
    sizeX = len(mask[0][0])
    magnitude = []

for i in range(num):
    r = 0
    for y in range(sizeY):
        for x in range(sizeX):
            r += pixel[y][x] * mask[i][y][x]

    magnitude.append(r**2)

return math.sqrt(sum(magnitude))
```

2. 最大值

```
def MaxMagnitude(pixel, mask):
    num = len(mask)
    sizeY = len(mask[0])
    sizeX = len(mask[0][0])
    magnitude = []

for i in range(num):
    r = 0
    for y in range(sizeY):
        for x in range(sizeX):
            r += pixel[y][x] * mask[i][y][x]

    magnitude.append(r)

return max(magnitude)
```

♦ Robert's Operator

```
def Robert(img, threshold):
    img_new = np.full(img.shape, 255, np.int)
    mask = [[[-1,0],[0,1]],[[0,-1],[1,0]]]
    for y in range(img.shape[0]-1):
        for x in range(img.shape[1]-1):
            neighbors = []
            neighbors.append([img[y][x],img[y][x+1]])
            neighbors.append([img[y+1][x],img[y+1][x+1]])
        G = Magnitude(neighbors, mask)

        if G > threshold:
            img_new[y][x] = 0
        else:
            img_new[y][x] = 255

return img_new
```

♦ Prewitt's Edge Detector

Same as Robert's Operator, except the difference of masks

```
\mathsf{mask} = [[[-1,-1,-1],[0,0,0],[1,1,1]],[[-1,0,1],[-1,0,1],[-1,0,1]]]
```

♦ Sobel's Edge Detector

Same as Robert's Operator, except the difference of masks

```
\mathsf{mask} = [[[-1, -2, -1], [0, 0, 0], [1, 2, 1]], [[-1, 0, 1], [-2, 0, 2], [-1, 0, 1]]]
```

♦ Frei and Chen's Gradient Operator

Same as Robert's Operator, except the difference of masks

```
value = math.sqrt(2)
img_new = np.full(img.shape, 255, np.int)
mask = [[[-1,-value,-1],[0,0,0],[1,value,1]],[[-1,0,1],[-value,0,value],[-1,0,1]]]
```

♦ Kirsch's Compass Operator

```
def Kirsch(img, threshold):
    img new = np.full(img.shape, 255, np.int)
    mask = [[[-3, -3, 5], [-3, 0, 5], [-3, -3, 5]],
[[-3, 5, 5], [-3, 0, 5], [-3, -3, -3]],
                      [[5, 5, 5], [-3, 0, -3], [-3, -3, -3]],
                      [[5, 5, -3], [5, 0, -3], [-3, -3, -3]],
                      [[5, -3, -3], [5, 0, -3], [5, -3, -3]],
[[-3, -3, -3], [5, 0, -3], [5, 5, -3]],
                      [[-3, -3, -3], [-3, 0, -3], [5, 5, 5]],
                      [[-3, -3, -3], [-3, 0, 5], [-3, 5, 5]]]
    for y in range(1,img.shape[0]-1):
         for x in range(1,img.shape[1]-1):
             neighbors = []
             neighbors.append([img[y-1][x-1],img[y-1][x],img[y-1][x+1]])
             neighbors.append([img[y][x-1],img[y][x],img[y][x+1]])
             neighbors.append([img[y+1][x-1],img[y+1][x],img[y+1][x+1]])
             G = MaxMagnitude(neighbors, mask)
             if G > threshold:
                  img_new[y][x] = 0
                  img_new[y][x] = 255
    return img_new
```

♦ Robinson's Compass Operator

Same as Kirsch's Compass Operator, except the difference of masks

```
 \text{mask} = [[[-1, -2, -1], [0, 0, 0], [1, 2, 1]], \\ [[0, -1, -2], [1, 0, -1], [2, 1, 0]], \\ [[1, 0, -1], [2, 0, -2], [1, 0, -1]], \\ [[2, 1, 0], [1, 0, -1], [0, -1, -2]], \\ [[1, 2, 1], [0, 0, 0], [-1, -2, -1]], \\ [[0, 1, 2], [-1, 0, 1], [-2, -1, 0]], \\ [[-1, 0, 1], [-2, 0, 2], [-1, 0, 1]], \\ [[-2, -1, 0], [-1, 0, 1], [0, 1, 2]]]
```

♦ Nevatia-Babu 5x5 Operator

Same as Kirsch's Compass Operator, except the difference of masks

```
mask = [[[-100, -100, 0, 100, 100], [-100, -100, 0, 100, 100], [-100, -100, 0, 100, 100], [-100, -100, 0, 100, 100], [-100, -100, 0, 100, 100], [-100, -100, 0, 100, 100], [-100, -100, 0, 100, 100], [[100, 100, 100, 100], [100, 100, 100, 100], [100, 100, 100, 100], [100, 100, 100, 100], [100, 100, 100, 100], [100, 100, 100, 100, 100], [100, 100, 100, 100, 100], [100, 100, 100, 100], [100, 100, 100, 100], [100, 100, 100, 100], [100, 100, 100], [0, 0, 0, 0], [-100, -100, -100, -100, -100], [-100, -100, -100, -100], [100, 100], [-32, 78, 100, 100, 100], [-100, -92, 0, 92, 100], [-100, -100, -100, -78, 32], [-100, -100, -100, -100], [-100, -100, -100], [-100, -100, -100], [-100, -100, -100], [-100, -100, -100], [-100, -100, -100], [-100, -100, -100], [-100, -100, -100], [-100, -100, -100], [-100, -100, -100], [-100, -100, -100, -100], [-100, -100, -100], [-100, -100, -100], [-100, -100, -100], [-100, -100, -100], [-100, -100, -100], [-100, -100, -100], [-100, -100, -100], [-100, -100, -100], [-100, -100, -100], [-100, -100, -100], [-100, -100, -100], [-100, -100, -100], [-100, -100, -100], [-100, -100, -100], [-100, -100, -100], [-100, -100, -100], [-100, -100, -100], [-100, -100, -100], [-100, -100, -100], [-100, -100, -100], [-100, -100, -100], [-100, -100, -100], [-100, -100, -100], [-100, -100, -100], [-100, -100, -100], [-100, -100, -100], [-100, -100, -100], [-100, -100, -100], [-100, -100, -100], [-100, -100, -100], [-100, -100, -100], [-100, -100, -100], [-100, -100, -100], [-100, -100, -100], [-100, -100, -100], [-100, -100, -100], [-100, -100, -100], [-100, -100, -100], [-100, -100, -100], [-100, -100, -100], [-100, -100, -100], [-100, -100], [-100, -100], [-100, -100], [-100, -100], [-100, -100], [-100, -100], [-100, -100], [-100, -100], [-100, -100], [-100, -100], [-100, -100], [-100, -100], [-100, -100], [-100, -100], [-100, -100], [-100, -100], [-100, -100], [-100, -100], [-100, -100], [-100, -100], [-100, -100], [-100, -100], [-100, -100], [-100, -100], [-100, -100], [-100, -100], [-100, -100], [-100,
```

Results

Robert's Operator(threshold=12) Prewitt's Edge Detector(threshold=36)



