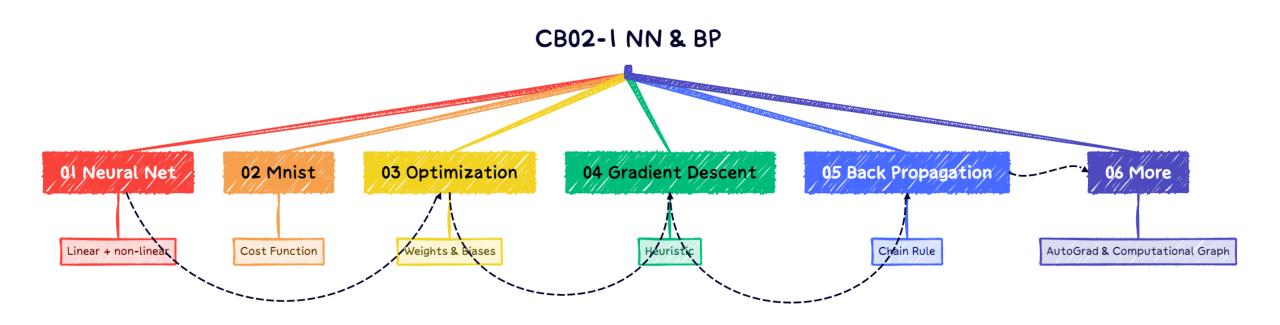


# CB02-1 Neural Network & Back Propagation

# **00 Outline**

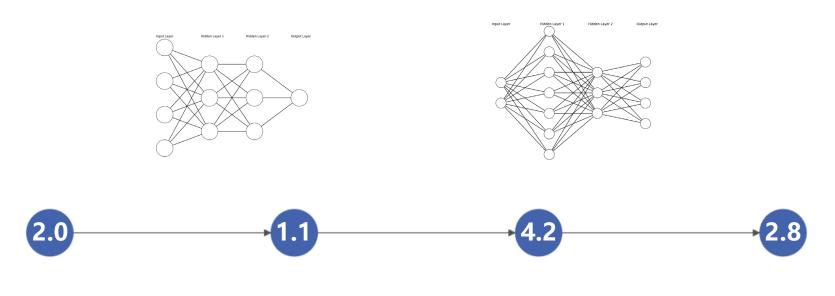


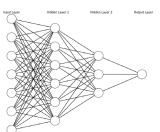


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### **01.1 Just Numbers!**







$$y = kx + b$$

k -> w : weights

$$y = y1 + y2 + y3 + y4$$
  
= sum(wi\*xi)+ b

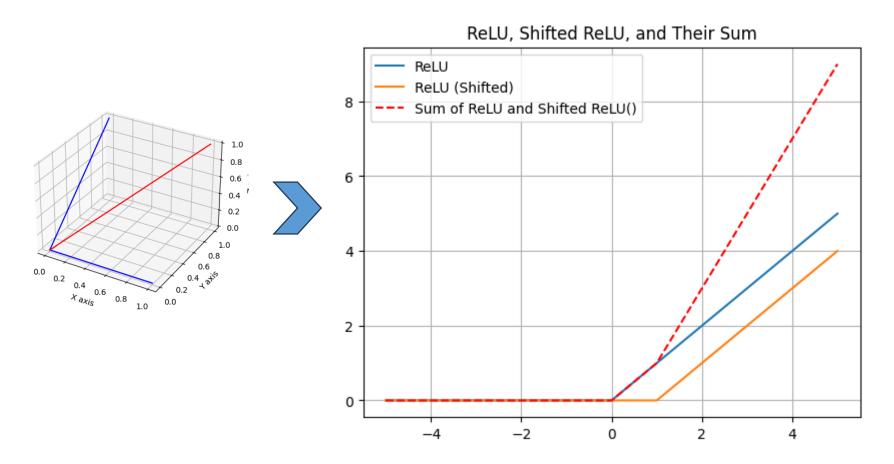
7.2

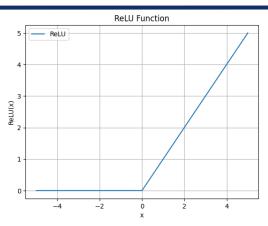
Weights & Biases

#### 01.2 Linear & Nonlinear



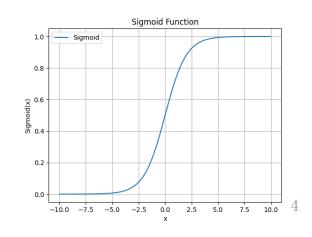






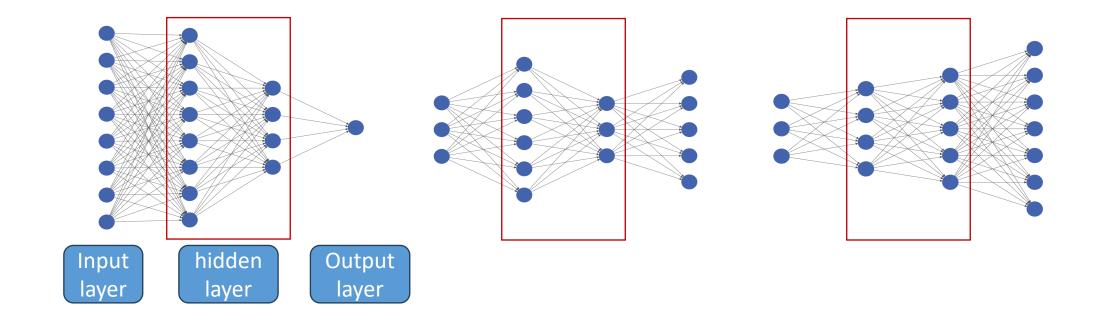
W&B

# adjustment results in desirable output



#### **01.3 Feedforward NN**

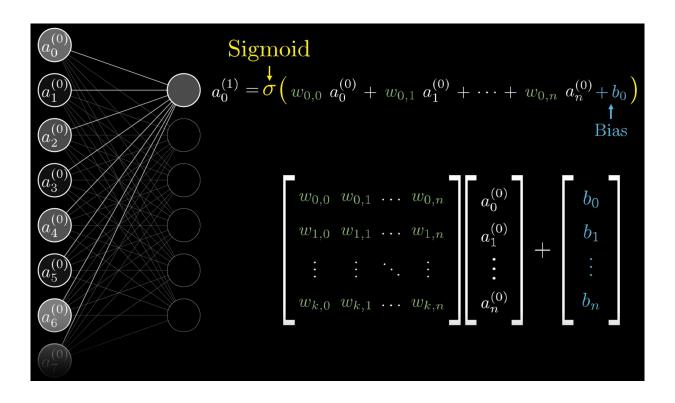


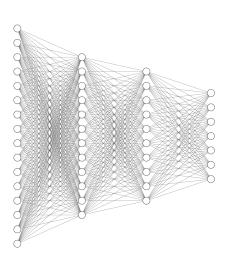


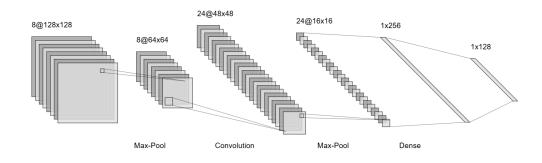
# 01.4 Key Ideas



$$\sigma(w \cdot x + b)$$

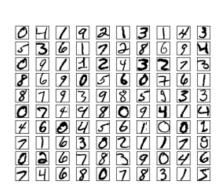


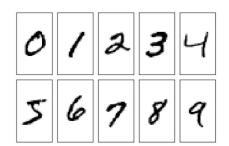


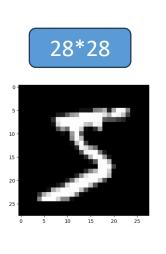


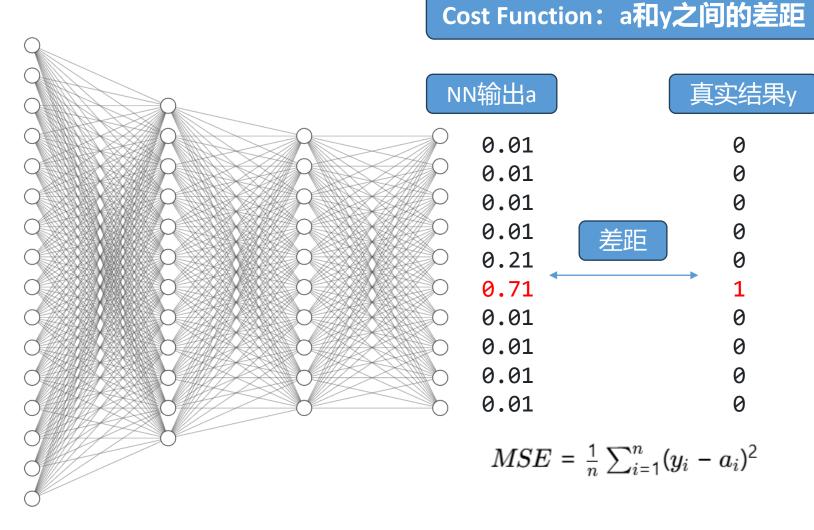
## **02 Mnist & Cost Function**











# **03 Convert to An Optimization Problem**





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#### **04.1 A Heuristic Method—Gradient Descent**



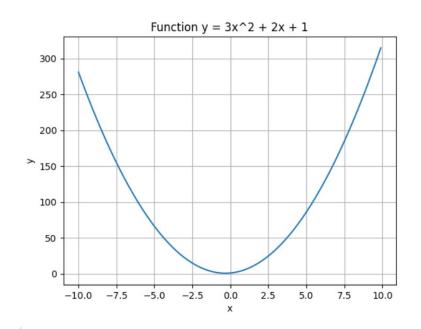
# 第二次抽象 启发式方法

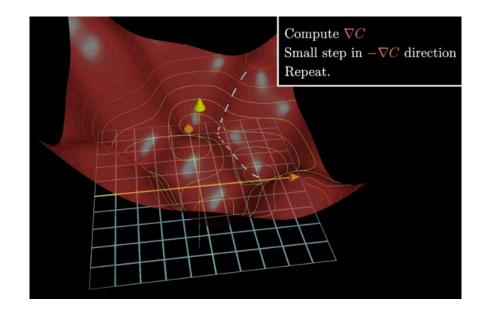
# 沿着Slope方向移动

# 沿着梯度方向移动

 $\nabla f(w_1, w_2, ..., w_n, b_1, b_2, ..., b_n) = \left(\frac{\partial f}{\partial w_1}, \frac{\partial f}{\partial w_2}, ..., \frac{\partial f}{\partial w_n}, \frac{\partial f}{\partial b_1}, \frac{\partial f}{\partial b_2}, ..., \frac{\partial f}{\partial b_n}\right)$ 

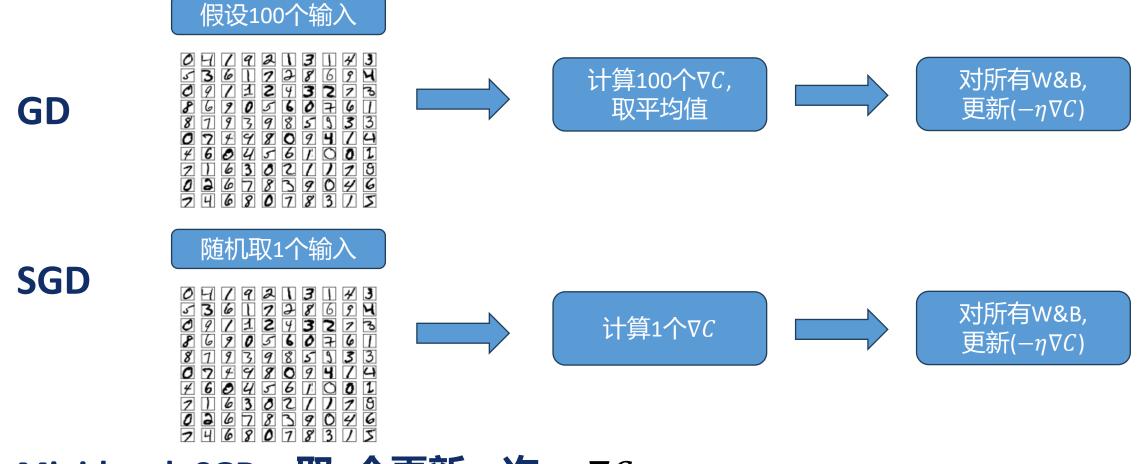






# 04.2 Improve GD--SGD





Mini-batch SGD:  $\mathbf{N}$  取n个更新一次 $-\eta \nabla C$ 

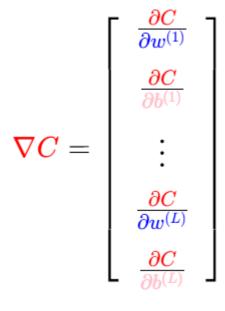
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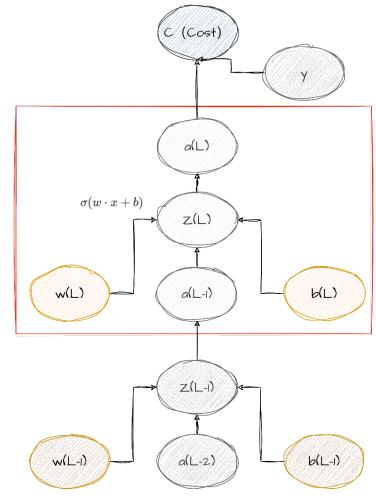
#### 05.1 BP



第三次抽象:核心任务是计算C(对于W&B的)梯度,也就是C对于每一个weights







C->a的偏导数

a->Z的偏导数

Z->W和B的偏导数: 需要上一层的输出a(L-1)

$$rac{\partial C_0}{\partial w_{jk}^{(L)}} = rac{\partial z_j^{(L)}}{\partial w_{jk}^{(L)}} rac{\partial a_j^{(L)}}{\partial z_j^{(L)}} rac{\partial C_0}{\partial a_j^{(L)}}$$

# **05.2 BP = Forward Pass+Backpropagate (Optional)**



1. Input x: Set the corresponding activation  $a^1$  for the input layer.

# 2. **Feedforward:** For each $l=2,3,\ldots,L$ compute $z^l=w^la^{l-1}+b^l$ and $a^l=\sigma(z^l)$ .

- 3. **Output error**  $\delta^L$ : Compute the vector  $\delta^L = \nabla_a C \odot \sigma'(z^L)$ .
- 4. Backpropagate the error: For each  $l=L-1,L-2,\ldots,2$  compute  $\delta^l=((w^{l+1})^T\delta^{l+1})\odot\sigma'(z^l)$ .
- 5. **Output:** The gradient of the cost function is given by  $\frac{\partial C}{\partial w_{jk}^l} = a_k^{l-1} \delta_j^l$  and  $\frac{\partial C}{\partial b_j^l} = \delta_j^l$ .

#### Summary: the equations of backpropagation

$$\delta^L = \nabla_a C \odot \sigma'(z^L) \tag{BP1}$$

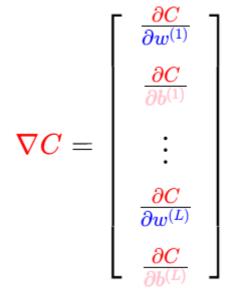
$$\delta^{l} = ((w^{l+1})^{T} \delta^{l+1}) \odot \sigma'(z^{l}) \tag{BP2}$$

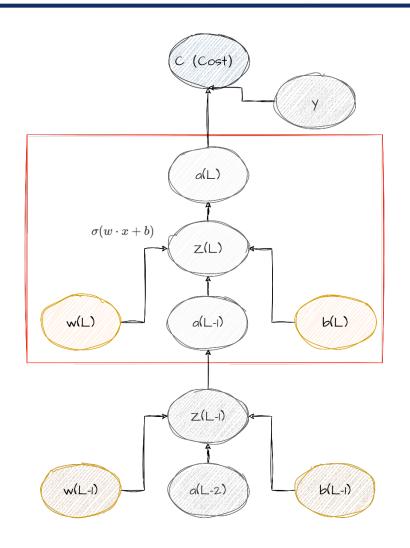
$$\frac{\partial C}{\partial b_j^l} = \delta_j^l \tag{BP3}$$

$$\frac{\partial C}{\partial w_{jk}^l} = a_k^{l-1} \delta_j^l \tag{BP4}$$

# **06 AutoGrad & Computational Graph**



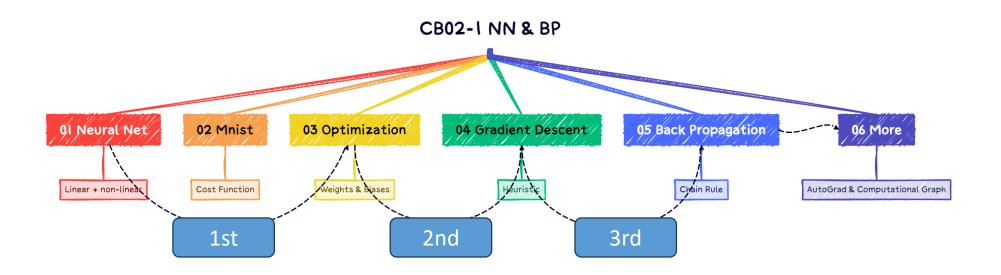




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#### **Review & Next Video**





```
def backprop(x, y):
    # Feedforward Pass
    activations, linear outputs = feedforward(x)
    # Backward Pass
    delta w = [np.zeros(w.shape) for w in network.weights]
    delta b = [np.zeros(b.shape) for b in network.biases]
    delta = cost derivative(activations[-1], y) * \
        (opt.sigmoid prime(linear outputs[-1]))
    delta_w[-1] = np.dot(delta, activations[-2].transpose()) # Last/Output Layer
    delta_b[-1] = delta # Last/Output Layer
    for 1 in range(2, network.num layers): # only index of layer changes
       delta = np.dot(network.weights[-l+1].transpose(), delta) * \
            opt.sigmoid prime(linear outputs[-1])
       delta_w[-l] = np.dot(delta, activations[-l-1].transpose())
        delta b[-1] = delta
    return (delta w, delta b)
```

```
Epoch 0: 9248 / 10000, precision is 92.48%
Epoch 1: 9256 / 10000, precision is 92.56%
Epoch 2: 9247 / 10000, precision is 92.47%
Epoch 3: 9274 / 10000, precision is 92.74%
Epoch 4: 9255 / 10000, precision is 92.55%
Epoch 5: 9282 / 10000, precision is 92.82%
Epoch 6: 9232 / 10000, precision is 92.32%
Epoch 7: 9272 / 10000, precision is 92.72%
Epoch 8: 9302 / 10000, precision is 93.02%
Epoch 9: 9287 / 10000, precision is 92.87%
Epoch 10: 9282 / 10000, precision is 92.82%
Epoch 11: 9285 / 10000, precision is 92.85%
Epoch 12: 9275 / 10000, precision is 92.75%
Epoch 13: 9287 / 10000, precision is 92.87%
Epoch 14: 9301 / 10000, precision is 93.01%
Epoch 15: 9311 / 10000, precision is 93.11%
Epoch 16: 9325 / 10000, precision is 93.25%
```

#### **Refs & Materials**



#### **Main Refs:**

- 1. Michael A. Nielsen, Neural networks and deep learning, github repo (github.com)
- 2. The first 3/4 videos in 3B1B's "Neural networks") series: 3Blue1Brown个人主页 (bilibili.com)
- 3. Video Lecture on MicroGrad By Andrej Karpathy: <u>Andrej Karpathy</u> | <u>详解神经网络和反向传播</u>
- 4. Computational Graph on BP from Chris Olah: Calculus on Computational Graphs

#### Others:

- 1. Chapters 3-5 of the d2l.ai: <u>Dive into Deep Learning (d2l.ai)</u>
- 2. Neural Networks from Scratch in Python Book: (nnfs.io)
- 3. CS231n's Python Numpy Tutorial <a href="Python Numpy Tutorial">Python Numpy Tutorial (with Jupyter and Colab)</a>
- 4. Numpy Tutorial: 《编程不难》--C13-C18: Visualize-ML/Book1 Python-For-Beginners: Book 1
- 5. An efficient pure-PyTorch implementation of KAN: efficient-kan