

# RS485 SERVER

V0.3

Generated by Doxygen 1.8.8

Fri Apr 22 2016 15:56:03



# Contents

<b>1</b>	<b>RS485 SERVER API Documentation</b>	<b>1</b>
<b>2</b>	<b>Module Index</b>	<b>3</b>
2.1	Modules . . . . .	3
<b>3</b>	<b>Data Structure Index</b>	<b>5</b>
3.1	Data Structures . . . . .	5
<b>4</b>	<b>File Index</b>	<b>7</b>
4.1	File List . . . . .	7
<b>5</b>	<b>Module Documentation</b>	<b>9</b>
5.1	Management . . . . .	9
5.1.1	Detailed Description . . . . .	10
5.2	Protocol . . . . .	11
5.2.1	Detailed Description . . . . .	11
5.3	BACnet . . . . .	12
5.3.1	Detailed Description . . . . .	12
5.4	Modbus . . . . .	13
5.4.1	Detailed Description . . . . .	13
5.5	General . . . . .	14
5.5.1	Detailed Description . . . . .	14
5.6	Device . . . . .	15
5.6.1	Detailed Description . . . . .	15
5.7	AirConditon . . . . .	16
5.7.1	Detailed Description . . . . .	16
5.8	Curtain . . . . .	17
5.8.1	Detailed Description . . . . .	17
5.9	FreshAir . . . . .	18
5.9.1	Detailed Description . . . . .	18
5.10	Adapter management . . . . .	19
5.10.1	Detailed Description . . . . .	20
5.10.2	Function Documentation . . . . .	20

5.10.2.1	adapter_thread_init	20
5.10.2.2	process_read_value_service	20
5.10.2.3	process_write_value_service	21
5.11	DaiKin DTA116A621	23
5.11.1	Detailed Description	23
5.11.2	Function Documentation	23
5.11.2.1	daikin_dta116a621_get_device_info_handle	23
5.11.2.2	daikin_dta116a621_get_device_info_send	24
5.11.2.3	daikin_dta116a621_set_fan	25
5.11.2.4	daikin_dta116a621_set_mode	25
5.11.2.5	daikin_dta116a621_set_swing	26
5.11.2.6	daikin_dta116a621_set_switch	26
5.11.2.7	daikin_dta116a621_set_temperature	27
5.12	Panasonic GuangZhou	28
5.12.1	Detailed Description	28
5.12.2	Function Documentation	28
5.12.2.1	panasonic_rcv_package_handle	28
5.12.2.2	panasonic_send_package_handle	28
5.13	YORK GuangZhou KeLong	30
5.13.1	Detailed Description	30
5.13.2	Function Documentation	30
5.13.2.1	get_air_york_instance	30
5.13.2.2	get_air_york_read_args	30
5.13.2.3	get_air_york_write_args	31
5.14	Aoke GuangZhou	32
5.14.1	Detailed Description	32
5.14.2	Function Documentation	32
5.14.2.1	aoke_rcv_package_handle	32
5.14.2.2	aoke_send_package_handle	32
5.15	Dooya HangZhou	34
5.15.1	Detailed Description	34
5.15.2	Function Documentation	34
5.15.2.1	doya_rcv_package_handle	34
5.15.2.2	doya_send_package_handle	35
5.16	Loreley ShenZhen	37
5.16.1	Detailed Description	37
5.16.2	Function Documentation	37
5.16.2.1	loreley_rcv_package_handle	37
5.16.2.2	loreley_send_package_handle	38
5.17	Device management	40

5.17.1 Detailed Description . . . . .	41
5.17.2 Typedef Documentation . . . . .	41
5.17.2.1 device_management_t . . . . .	41
5.17.3 Function Documentation . . . . .	41
5.17.3.1 check_device_id . . . . .	41
5.17.3.2 create_device . . . . .	42
5.17.3.3 delete_device . . . . .	43
5.17.3.4 device_managemnt_init . . . . .	44
5.17.3.5 find_available_device_id . . . . .	45
5.17.3.6 get_device_addr . . . . .	45
5.17.3.7 get_device_address_len . . . . .	45
5.17.3.8 get_device_factory_name . . . . .	46
5.17.3.9 get_device_management . . . . .	46
5.17.3.10 get_device_name . . . . .	47
5.17.3.11 get_device_object_id . . . . .	48
5.17.3.12 get_device_private . . . . .	48
5.17.3.13 get_device_private_numbers . . . . .	49
5.17.3.14 get_device_protocol . . . . .	49
5.17.3.15 get_device_retransmission . . . . .	50
5.17.3.16 get_device_timeout_ms . . . . .	50
5.17.3.17 get_device_timer . . . . .	51
5.17.3.18 get_device_type . . . . .	51
5.17.3.19 get_read_device_information . . . . .	52
5.17.3.20 set_read_device_information . . . . .	53
5.18 String management . . . . .	55
5.18.1 Detailed Description . . . . .	55
5.18.2 Function Documentation . . . . .	55
5.18.2.1 get_enum_txt_bool . . . . .	55
5.18.2.2 get_enum_txt_device_factory . . . . .	56
5.18.2.3 get_enum_txt_device_method . . . . .	56
5.18.2.4 get_enum_txt_rs485_device_type . . . . .	56
5.18.2.5 get_enum_txt_rs485_protocol_type . . . . .	57
5.18.2.6 get_enum_txt_service . . . . .	57
5.19 Item management . . . . .	58
5.19.1 Detailed Description . . . . .	58
5.19.2 Macro Definition Documentation . . . . .	58
5.19.2.1 PANNO_S_ITEM_ARMANI . . . . .	58
5.19.2.2 PANNO_S_ITEM_CONFIG . . . . .	58
5.19.2.3 PANNO_S_ITEM_DEFAULT . . . . .	59
5.19.2.4 PANNO_S_ITEM_SHAOCHENGGUOJI . . . . .	59

5.19.2.5	PANNO_S_ITEM_WENRUDE . . . . .	59
5.19.3	Function Documentation . . . . .	59
5.19.3.1	panno_s_item_config . . . . .	59
5.20	Object management . . . . .	60
5.20.1	Detailed Description . . . . .	61
5.20.2	Typedef Documentation . . . . .	61
5.20.2.1	object_management_t . . . . .	61
5.20.3	Function Documentation . . . . .	61
5.20.3.1	check_object_id . . . . .	61
5.20.3.2	check_object_numbers_have_idle . . . . .	62
5.20.3.3	create_object . . . . .	63
5.20.3.4	delete_object . . . . .	64
5.20.3.5	find_available_object_id . . . . .	65
5.20.3.6	get_object_mount_device . . . . .	65
5.20.3.7	get_object_queue_sem . . . . .	66
5.20.3.8	get_object_type . . . . .	67
5.20.3.9	get_object_work_queue . . . . .	68
5.20.3.10	object_is_used . . . . .	68
5.20.3.11	object_mount_device_id . . . . .	69
5.20.3.12	object_unmount_device_id . . . . .	70
5.20.3.13	work_thread_clean . . . . .	71
5.20.3.14	work_thread_create . . . . .	71
5.21	BACnet interface . . . . .	73
5.21.1	Detailed Description . . . . .	73
5.21.2	Typedef Documentation . . . . .	73
5.21.2.1	bacnet_port_handle_t . . . . .	73
5.21.3	Function Documentation . . . . .	73
5.21.3.1	bacnet_work_thread_function . . . . .	73
5.22	Handle_property . . . . .	75
5.22.1	Detailed Description . . . . .	75
5.22.2	Macro Definition Documentation . . . . .	75
5.22.2.1	BACNET_READ_ARGS_OBJECT_MAX . . . . .	75
5.22.3	Function Documentation . . . . .	75
5.22.3.1	bacnet_service_init . . . . .	75
5.22.3.2	get_air_condition_bacnet_read_args . . . . .	76
5.22.3.3	get_air_condition_bacnet_write_args . . . . .	77
5.23	General interface . . . . .	79
5.23.1	Detailed Description . . . . .	79
5.23.2	Typedef Documentation . . . . .	79
5.23.2.1	mstp_port_handle_t . . . . .	79

5.23.3	Function Documentation	79
5.23.3.1	general_service_init	79
5.23.3.2	general_work_thread_function	80
5.24	General RS485	82
5.24.1	Detailed Description	82
5.24.2	Function Documentation	82
5.24.2.1	rs485_cleanup	82
5.24.2.2	rs485_get_interface	83
5.24.2.3	rs485_initialize	83
5.24.2.4	rs485_recv_handle_frame	83
5.24.2.5	rs485_send_handle_frame	84
5.24.2.6	rs485_set_baud_rate	85
5.24.2.7	rs485_set_interface	85
5.25	Modbus RS485	86
5.25.1	Detailed Description	86
5.25.2	Function Documentation	86
5.25.2.1	modbus_service_deinit	86
5.25.2.2	modbus_service_init	87
5.25.2.3	modbus_work_thread_function	88
5.26	Service management	89
5.26.1	Detailed Description	89
5.26.2	Function Documentation	89
5.26.2.1	rs485_recv_msg_from_client	89
5.26.2.2	rs485_send_msg_to_client	90
5.26.2.3	rs485_service_create_clean	90
5.26.2.4	rs485_service_running	90
5.26.2.5	rs485_service_running_clean	91
5.26.2.6	rs485_service_start	92
5.26.2.7	rs485_thread_pool_clean	92
5.26.2.8	rs485_thread_pool_create	93
5.26.2.9	send_msg_to_adapter	93
5.27	Device register management	94
5.27.1	Detailed Description	94
5.27.2	Typedef Documentation	94
5.27.2.1	method_recv	94
5.27.2.2	method_send	95
5.27.3	Function Documentation	95
5.27.3.1	check_device_support	95
5.27.3.2	get_device_recv_package_function	96
5.27.3.3	get_device_send_package_function	96

5.27.3.4	<a href="#">get_support_device_profile</a>	96
5.27.3.5	<a href="#">get_support_device_profile_numbers</a>	97
5.28	Timer management	98
5.28.1	Detailed Description	98
5.28.2	Typedef Documentation	98
5.28.2.1	<a href="#">timer_proc_func</a>	98
5.28.3	Function Documentation	98
5.28.3.1	<a href="#">create_device_timer_task</a>	98
5.28.3.2	<a href="#">delete_device_timer_task</a>	99
5.28.3.3	<a href="#">device_timer_task_handle_demo</a>	99
5.28.3.4	<a href="#">timer_task_thread_function</a>	100
<b>6</b>	<b>Data Structure Documentation</b>	<b>101</b>
6.1	<a href="#">adapter_t</a> Struct Reference	101
6.1.1	Detailed Description	101
6.1.2	Field Documentation	102
6.1.2.1	<a href="#">message_content</a>	102
6.1.2.2	<a href="#">message_length</a>	102
6.1.2.3	<a href="#">message_retvl</a>	102
6.1.2.4	<a href="#">message_type</a>	102
6.1.2.5	<a href="#">socket_fd</a>	102
6.2	<a href="#">air_condition_profile_t</a> Struct Reference	102
6.2.1	Detailed Description	103
6.2.2	Field Documentation	103
6.2.2.1	<a href="#">current_fan</a>	103
6.2.2.2	<a href="#">current_mode</a>	103
6.2.2.3	<a href="#">current_set_temperature</a>	103
6.2.2.4	<a href="#">current_swing</a>	103
6.2.2.5	<a href="#">outdoor_temperature</a>	103
6.2.2.6	<a href="#">pipe_temperature</a>	103
6.2.2.7	<a href="#">room_temperature</a>	103
6.3	<a href="#">bacnet</a> Struct Reference	103
6.3.1	Detailed Description	104
6.3.2	Field Documentation	104
6.3.2.1	<a href="#">arg</a>	104
6.3.2.2	<a href="#">command</a>	104
6.3.2.3	<a href="#">device_mac</a>	104
6.3.2.4	<a href="#">device_type</a>	104
6.3.2.5	<a href="#">factory_name</a>	104
6.3.2.6	<a href="#">mac_length</a>	104



6.3.2.7	value	104
6.3.2.8	value_reserve	104
6.4	bacnet_read_args_t Struct Reference	105
6.4.1	Detailed Description	105
6.4.2	Field Documentation	105
6.4.2.1	device_id	105
6.4.2.2	object_instance	105
6.4.2.3	object_numbers	105
6.4.2.4	object_property	105
6.4.2.5	object_type	105
6.5	bacnet_write_args_t Struct Reference	106
6.5.1	Detailed Description	106
6.5.2	Field Documentation	106
6.5.2.1	device_id	106
6.5.2.2	object_instance	106
6.5.2.3	object_property	106
6.5.2.4	object_property_index	106
6.5.2.5	object_property_priority	106
6.5.2.6	object_property_value	107
6.5.2.7	object_property_value_type	107
6.5.2.8	object_type	107
6.6	client_t Struct Reference	107
6.6.1	Detailed Description	107
6.6.2	Field Documentation	107
6.6.2.1	fd	107
6.6.2.2	uid	107
6.7	commonBacObj_s Struct Reference	107
6.7.1	Detailed Description	108
6.7.2	Field Documentation	108
6.7.2.1	mObject_Type	108
6.7.2.2	Object_Instance_Number	108
6.7.2.3	Object_Name	108
6.8	create_object_return_t Struct Reference	108
6.8.1	Detailed Description	108
6.8.2	Field Documentation	109
6.8.2.1	object_id	109
6.9	create_object_t Struct Reference	109
6.9.1	Detailed Description	109
6.9.2	Field Documentation	109
6.9.2.1	address	109

6.9.2.2	address_len	110
6.9.2.3	mount_device_max	110
6.9.2.4	object_name	110
6.9.2.5	object_type	110
6.9.2.6	port	110
6.10	curtain_profile_t Struct Reference	110
6.10.1	Detailed Description	110
6.10.2	Field Documentation	111
6.10.2.1	current_percent	111
6.11	delete_object_return_t Struct Reference	111
6.11.1	Detailed Description	111
6.11.2	Field Documentation	111
6.11.2.1	delete_status	111
6.12	delete_object_t Struct Reference	111
6.12.1	Detailed Description	111
6.12.2	Field Documentation	112
6.12.2.1	object_id	112
6.13	device_management Struct Reference	112
6.13.1	Detailed Description	113
6.13.2	Field Documentation	113
6.13.2.1	device	113
6.13.2.2	device_addr	113
6.13.2.3	device_addr_len	113
6.13.2.4	device_id	113
6.13.2.5	device_info	113
6.13.2.6	device_name	113
6.13.2.7	device_private	113
6.13.2.8	device_private_numbers	114
6.13.2.9	device_status_period	114
6.13.2.10	device_type	114
6.13.2.11	factory_name	114
6.13.2.12	object_id	114
6.13.2.13	object_type	114
6.13.2.14	retransmission	114
6.13.2.15	support_reply	114
6.13.2.16	time_out	114
6.13.2.17	timer	115
6.14	device_profile Struct Reference	115
6.14.1	Detailed Description	115
6.14.2	Field Documentation	115

6.14.2.1	<a href="#">addr_real_len</a>	115
6.14.2.2	<a href="#">method</a>	115
6.14.2.3	<a href="#">recv</a>	115
6.14.2.4	<a href="#">send</a>	115
6.15	<a href="#">devObj_s Struct Reference</a>	116
6.15.1	<a href="#">Detailed Description</a>	116
6.15.2	<a href="#">Field Documentation</a>	116
6.15.2.1	<a href="#">bacDevAddr</a>	116
6.15.2.2	<a href="#">bacObj</a>	116
6.15.2.3	<a href="#">Database_Revision</a>	116
6.15.2.4	<a href="#">Description</a>	117
6.16	<a href="#">fresh_air_profile_t Struct Reference</a>	117
6.16.1	<a href="#">Detailed Description</a>	117
6.16.2	<a href="#">Field Documentation</a>	117
6.16.2.1	<a href="#">fresh_level</a>	117
6.16.2.2	<a href="#">pm2_5</a>	117
6.16.2.3	<a href="#">room_humidity</a>	117
6.16.2.4	<a href="#">room_temperature</a>	117
6.17	<a href="#">message_service_t Union Reference</a>	118
6.17.1	<a href="#">Detailed Description</a>	118
6.17.2	<a href="#">Field Documentation</a>	118
6.17.2.1	<a href="#">delete_object</a>	118
6.17.2.2	<a href="#">delete_object_return</a>	119
6.17.2.3	<a href="#">mount_device</a>	119
6.17.2.4	<a href="#">mount_device_return</a>	119
6.17.2.5	<a href="#">new_object</a>	119
6.17.2.6	<a href="#">new_object_return</a>	119
6.17.2.7	<a href="#">read</a>	119
6.17.2.8	<a href="#">read_return</a>	119
6.17.2.9	<a href="#">unmount_device</a>	119
6.17.2.10	<a href="#">unmount_device_return</a>	119
6.17.2.11	<a href="#">write</a>	119
6.17.2.12	<a href="#">write_return</a>	119
6.18	<a href="#">modbus_port_handle_t Struct Reference</a>	120
6.18.1	<a href="#">Detailed Description</a>	120
6.18.2	<a href="#">Field Documentation</a>	120
6.18.2.1	<a href="#">broadcast</a>	120
6.18.2.2	<a href="#">buffer</a>	120
6.18.2.3	<a href="#">buffer_len</a>	120
6.18.2.4	<a href="#">code</a>	120

6.18.2.5	device_addr	121
6.18.2.6	device_id	121
6.18.2.7	method	121
6.18.2.8	recv_handle	121
6.18.2.9	register_addr	121
6.18.2.10	retransmission	121
6.18.2.11	send_handle	121
6.18.2.12	value	121
6.19	mount_devcie_to_object_t Struct Reference	121
6.19.1	Detailed Description	122
6.19.2	Field Documentation	122
6.19.2.1	device_addr	122
6.19.2.2	device_addr_len	122
6.19.2.3	device_name	122
6.19.2.4	device_status_period	122
6.19.2.5	device_type	122
6.19.2.6	factory_name	122
6.19.2.7	object_id	123
6.19.2.8	object_type	123
6.19.2.9	retransmission	123
6.19.2.10	support_reply	123
6.19.2.11	time_out	123
6.20	mount_device_to_object_return_t Struct Reference	123
6.20.1	Detailed Description	123
6.20.2	Field Documentation	123
6.20.2.1	device_id	123
6.21	mstp_port_handle Struct Reference	124
6.21.1	Detailed Description	124
6.21.2	Field Documentation	124
6.21.2.1	address	124
6.21.2.2	address_len	124
6.21.2.3	arg	124
6.21.2.4	broadcast	125
6.21.2.5	device_id	125
6.21.2.6	except_reply	125
6.21.2.7	method	125
6.21.2.8	package_buffer	125
6.21.2.9	package_buffer_len	125
6.21.2.10	recv_handle	125
6.21.2.11	retransmission	125

6.21.2.12 send_handle . . . . .	125
6.21.2.13 timeout_ms . . . . .	126
6.21.2.14 value . . . . .	126
6.22 object_functions Struct Reference . . . . .	126
6.22.1 Detailed Description . . . . .	126
6.22.2 Field Documentation . . . . .	126
6.22.2.1 Object_Count . . . . .	126
6.22.2.2 Object_COV . . . . .	127
6.22.2.3 Object_COV_Clear . . . . .	127
6.22.2.4 Object_Index_To_Instance . . . . .	127
6.22.2.5 Object_Init . . . . .	127
6.22.2.6 Object_Intrinsic_Reporting . . . . .	127
6.22.2.7 Object_Iterator . . . . .	127
6.22.2.8 Object_Name . . . . .	127
6.22.2.9 Object_Read_Property . . . . .	127
6.22.2.10 Object_RPM_List . . . . .	127
6.22.2.11 Object_RR_Info . . . . .	127
6.22.2.12 Object_Type . . . . .	127
6.22.2.13 Object_Valid_Instance . . . . .	127
6.22.2.14 Object_Value_List . . . . .	128
6.22.2.15 Object_Write_Property . . . . .	128
6.23 object_management Struct Reference . . . . .	128
6.23.1 Detailed Description . . . . .	129
6.23.2 Field Documentation . . . . .	129
6.23.2.1 address . . . . .	129
6.23.2.2 address_len . . . . .	129
6.23.2.3 mount_device . . . . .	129
6.23.2.4 mount_device_max . . . . .	129
6.23.2.5 object_id . . . . .	129
6.23.2.6 object_name . . . . .	129
6.23.2.7 object_private . . . . .	129
6.23.2.8 object_thread . . . . .	129
6.23.2.9 object_type . . . . .	130
6.23.2.10 port . . . . .	130
6.23.2.11 queue_depth . . . . .	130
6.23.2.12 queue_sem . . . . .	130
6.23.2.13 work_queue . . . . .	130
6.23.2.14 work_queue_buffer . . . . .	130
6.24 package Struct Reference . . . . .	130
6.24.1 Detailed Description . . . . .	130

6.24.2	Field Documentation	131
6.24.2.1	addr_high	131
6.24.2.2	addr_low	131
6.24.2.3	cmd	131
6.24.2.4	command	131
6.24.2.5	data	131
6.24.2.6	data_addr	131
6.25	read_device_return_t Struct Reference	131
6.25.1	Detailed Description	132
6.25.2	Field Documentation	132
6.25.2.1	error	132
6.25.2.2	profile	132
6.25.2.3	read_status	132
6.25.2.4	runing	133
6.26	read_device_t Struct Reference	133
6.26.1	Detailed Description	133
6.26.2	Field Documentation	133
6.26.2.1	device_id	133
6.27	rs485_curtain_ao_ke_send_package_t Struct Reference	133
6.27.1	Detailed Description	133
6.27.2	Field Documentation	134
6.27.2.1	d1	134
6.27.2.2	d2	134
6.27.2.3	d3	134
6.27.2.4	d4	134
6.27.2.5	d5	134
6.28	rs485_device_profile Union Reference	134
6.28.1	Detailed Description	135
6.28.2	Field Documentation	135
6.28.2.1	air_condition	135
6.28.2.2	curtain	135
6.28.2.3	fresh_air	135
6.29	rs485_port_t Struct Reference	135
6.29.1	Detailed Description	135
6.29.2	Field Documentation	135
6.29.2.1	baud_rate	135
6.29.2.2	interface_name	136
6.30	thread_pool_t Struct Reference	136
6.30.1	Detailed Description	136
6.30.2	Field Documentation	136

6.30.2.1	arg	136
6.30.2.2	attr	136
6.30.2.3	function	136
6.30.2.4	thread	136
6.30.2.5	thread_status	137
6.31	timer_task_t Struct Reference	137
6.31.1	Detailed Description	137
6.31.2	Field Documentation	137
6.31.2.1	command	137
6.31.2.2	device_id	137
6.31.2.3	function	137
6.31.2.4	tick	137
6.31.2.5	timeout	138
6.32	unmount_device_from_object_return_t Struct Reference	138
6.32.1	Detailed Description	138
6.32.2	Field Documentation	138
6.32.2.1	unmount_status	138
6.33	unmount_device_from_object_t Struct Reference	138
6.33.1	Detailed Description	138
6.33.2	Field Documentation	139
6.33.2.1	device_id	139
6.33.2.2	object_id	139
6.34	write_device_return_t Struct Reference	139
6.34.1	Detailed Description	139
6.34.2	Field Documentation	139
6.34.2.1	write_status	139
6.35	write_device_t Struct Reference	139
6.35.1	Detailed Description	140
6.35.2	Field Documentation	140
6.35.2.1	broadcast	140
6.35.2.2	device_id	140
6.35.2.3	device_method	140
6.35.2.4	method_value	140
6.35.2.5	value_reserve	140
<b>7</b>	<b>File Documentation</b>	<b>141</b>
7.1	include/adapter.h File Reference	141
7.1.1	Detailed Description	142
7.2	include/device.h File Reference	143
7.2.1	Detailed Description	144

7.3	<a href="#">include/device/airCondition/daikin/DTA116A621.h File Reference</a>	145
7.4	<a href="#">include/device/airCondition/panasonic/panasonic.h File Reference</a>	146
7.5	<a href="#">include/device/airCondition/york/york.h File Reference</a>	146
7.6	<a href="#">include/device/curtain/aoke/aoke.h File Reference</a>	147
7.7	<a href="#">include/device/curtain/doya/doya.h File Reference</a>	148
7.8	<a href="#">include/device/freshAir/loreley/loreley.h File Reference</a>	149
7.9	<a href="#">include/enum.h File Reference</a>	150
7.9.1	Detailed Description	152
7.9.2	Macro Definition Documentation	152
7.9.2.1	UNUSED	152
7.9.3	Enumeration Type Documentation	152
7.9.3.1	adapter_thread_status_enum	152
7.9.3.2	modbus_function_code_enum	153
7.9.3.3	object_thread_status_enum	153
7.9.3.4	rs485_device_method_enum	153
7.9.3.5	rs485_device_type_enum	155
7.9.3.6	rs485_factory_name_enum	155
7.9.3.7	rs485_method_air_condition_panonsonnic_enum	155
7.9.3.8	rs485_method_air_condition_york_enum	156
7.9.3.9	rs485_method_curtain_aoke_enum	158
7.9.3.10	rs485_method_curtain_doya_enum	158
7.9.3.11	rs485_method_fresh_air_loreley_enum	158
7.9.3.12	rs485_protocol_type_enum	158
7.9.3.13	rs485_service_type_enum	159
7.9.3.14	timer_task_thread_status_enum	159
7.10	<a href="#">include/enumtxt.h File Reference</a>	159
7.11	<a href="#">include/item_config.h File Reference</a>	160
7.12	<a href="#">include/object.h File Reference</a>	162
7.13	<a href="#">include/protocol/bacnet/bacnet.h File Reference</a>	163
7.14	<a href="#">include/protocol/bacnet/device_client.h File Reference</a>	164
7.14.1	Detailed Description	167
7.14.2	Macro Definition Documentation	167
7.14.2.1	MAX_DEV_DESC_LEN	167
7.14.2.2	MAX_DEV_LOC_LEN	167
7.14.2.3	MAX_DEV_MOD_LEN	167
7.14.2.4	MAX_DEV_NAME_LEN	167
7.14.2.5	MAX_DEV_VER_LEN	167
7.14.3	Typedef Documentation	167
7.14.3.1	COMMON_BAC_OBJECT	167
7.14.3.2	DEVICE_OBJECT_DATA	167



7.14.3.3	object_count_function	167
7.14.3.4	object_cov_clear_function	168
7.14.3.5	object_cov_function	169
7.14.3.6	object_functions_t	169
7.14.3.7	object_index_to_instance_function	169
7.14.3.8	object_init_function	169
7.14.3.9	object_intrinsic_reporting_function	169
7.14.3.10	object_iterate_function	170
7.14.3.11	object_name_function	170
7.14.3.12	object_valid_instance_function	170
7.14.3.13	object_value_list_function	170
7.14.4	Function Documentation	171
7.14.4.1	Add_Routed_Device	171
7.14.4.2	Device_Application_Software_Version	171
7.14.4.3	Device_Count	171
7.14.4.4	Device_COV	171
7.14.4.5	Device_COV_Clear	171
7.14.4.6	Device_Database_Revision	171
7.14.4.7	Device_Description	171
7.14.4.8	Device_Encode_Value_List	171
7.14.4.9	Device_Firmware_Revision	171
7.14.4.10	Device_getCurrentDateTime	171
7.14.4.11	Device_Inc_Database_Revision	171
7.14.4.12	Device_Index_To_Instance	172
7.14.4.13	Device_Init	172
7.14.4.14	Device_Location	172
7.14.4.15	Device_Model_Name	172
7.14.4.16	Device_Object_Instance_Number	172
7.14.4.17	Device_Object_List_Count	173
7.14.4.18	Device_Object_List_Identifier	173
7.14.4.19	Device_Object_Name	174
7.14.4.20	Device_Object_Name_Copy	174
7.14.4.21	Device_Objects_Property_List	175
7.14.4.22	Device_Objects_RR_Info	175
7.14.4.23	Device_Property_Lists	175
7.14.4.24	Device_Protocol_Revision	175
7.14.4.25	Device_Protocol_Version	175
7.14.4.26	Device_Read_Property	175
7.14.4.27	Device_Read_Property_Local	176
7.14.4.28	Device_Reinitialize	176

7.14.4.29 Device_Reinitialized_State . . . . .	176
7.14.4.30 Device_Segmentation_Supported . . . . .	176
7.14.4.31 Device_Set_Application_Software_Version . . . . .	177
7.14.4.32 Device_Set_Database_Revision . . . . .	177
7.14.4.33 Device_Set_Description . . . . .	177
7.14.4.34 Device_Set_Location . . . . .	177
7.14.4.35 Device_Set_Model_Name . . . . .	177
7.14.4.36 Device_Set_Object_Instance_Number . . . . .	177
7.14.4.37 Device_Set_Object_Name . . . . .	178
7.14.4.38 Device_Set_System_Status . . . . .	178
7.14.4.39 Device_Set_Vendor_Identifier . . . . .	178
7.14.4.40 Device_System_Status . . . . .	178
7.14.4.41 Device_Valid_Object_Id . . . . .	178
7.14.4.42 Device_Valid_Object_Instance_Number . . . . .	179
7.14.4.43 Device_Valid_Object_Name . . . . .	179
7.14.4.44 Device_Value_List_Supported . . . . .	179
7.14.4.45 Device_Vendor_Identifier . . . . .	179
7.14.4.46 Device_Vendor_Name . . . . .	180
7.14.4.47 Device_Write_Property . . . . .	180
7.14.4.48 Device_Write_Property_Local . . . . .	180
7.14.4.49 DeviceGetRRInfo . . . . .	180
7.14.4.50 Get_Routed_Device_Address . . . . .	180
7.14.4.51 Get_Routed_Device_Object . . . . .	180
7.14.4.52 Routed_Device_Address_Lookup . . . . .	180
7.14.4.53 Routed_Device_GetNext . . . . .	180
7.14.4.54 Routed_Device_Inc_Database_Revision . . . . .	180
7.14.4.55 Routed_Device_Index_To_Instance . . . . .	180
7.14.4.56 Routed_Device_Is_Valid_Network . . . . .	180
7.14.4.57 Routed_Device_Name . . . . .	180
7.14.4.58 Routed_Device_Object_Instance_Number . . . . .	180
7.14.4.59 Routed_Device_Service_Approval . . . . .	180
7.14.4.60 Routed_Device_Set_Description . . . . .	180
7.14.4.61 Routed_Device_Set_Object_Instance_Number . . . . .	180
7.14.4.62 Routed_Device_Set_Object_Name . . . . .	180
7.14.4.63 Routed_Device_Valid_Object_Instance_Number . . . . .	180
7.14.4.64 routed_get_my_address . . . . .	180
7.14.4.65 Routing_Device_Init . . . . .	181
7.15 include/protocol/bacnet/handle_property.h File Reference . . . . .	181
7.16 include/protocol/bacnet/read_property.h File Reference . . . . .	182
7.16.1 Function Documentation . . . . .	183

7.16.1.1	<a href="#">bacnet_read_property</a>	183
7.17	<a href="#">include/protocol/bacnet/write_property.h</a> File Reference	183
7.17.1	Function Documentation	184
7.17.1.1	<a href="#">bacnet_write_property</a>	184
7.18	<a href="#">include/protocol/general/general.h</a> File Reference	184
7.19	<a href="#">include/protocol/general/rs485.h</a> File Reference	185
7.20	<a href="#">include/rs485.h</a> File Reference	187
7.21	<a href="#">include/protocol/modbus/modbus.h</a> File Reference	187
7.22	<a href="#">include/read_config.h</a> File Reference	188
7.22.1	Variable Documentation	188
7.22.1.1	<a href="#">glb_config_adapter_message_queue_depth</a>	188
7.22.1.2	<a href="#">glb_config_bacnet_work_queue_depth</a>	188
7.22.1.3	<a href="#">glb_config_general_work_package_mtu</a>	188
7.22.1.4	<a href="#">glb_config_general_work_queue_depth</a>	188
7.22.1.5	<a href="#">glb_config_modbus_work_queue_depth</a>	188
7.23	<a href="#">include/service.h</a> File Reference	189
7.23.1	Detailed Description	190
7.24	<a href="#">include/support.h</a> File Reference	190
7.25	<a href="#">include/syslog/log.h</a> File Reference	191
7.25.1	Detailed Description	192
7.25.2	Macro Definition Documentation	192
7.25.2.1	<a href="#">DEBUG_LINUX_SYSLOG</a>	192
7.25.2.2	<a href="#">DEBUG_PRINTF</a>	192
7.25.2.3	<a href="#">syslog_debug</a>	192
7.25.2.4	<a href="#">syslog_error</a>	192
7.25.2.5	<a href="#">syslog_format</a>	192
7.25.2.6	<a href="#">syslog_info</a>	192
7.25.2.7	<a href="#">syslog_warning</a>	192
7.26	<a href="#">include/timer_task.h</a> File Reference	193
7.26.1	Detailed Description	194
7.26.2	Function Documentation	194
7.26.2.1	<a href="#">device_timer_task_handle_curtain_aoke_init</a>	194
7.26.2.2	<a href="#">device_timer_task_handle_curtain_doya_init</a>	194
7.26.2.3	<a href="#">device_timer_task_handle_curtain_init</a>	194
7.27	<a href="#">src/adapter.c</a> File Reference	194
7.27.1	Detailed Description	195
7.27.2	Macro Definition Documentation	195
7.27.2.1	<a href="#">ADAPTER_MESSAGE_QUEUE_MAX_DEPTH</a>	195
7.27.3	Function Documentation	195
7.27.3.1	<a href="#">adapter_thread_function</a>	195

7.27.4	Variable Documentation	196
7.27.4.1	adapter_thread_status	196
7.27.4.2	bacnet	197
7.27.4.3	general	197
7.27.4.4	modbus	197
7.27.4.5	reply_client	197
7.28	src/device.c File Reference	197
7.28.1	Detailed Description	199
7.28.2	Macro Definition Documentation	199
7.28.2.1	RS485_CURTAIN_MAX_FACTORY	199
7.28.2.2	RS485_DEVICE_MAX_NUMBERS	199
7.28.2.3	RS485_DEVICE_NAME_MAX_LENGTH	199
7.28.3	Function Documentation	199
7.28.3.1	find_curtain_factory_is_save	199
7.28.3.2	printf_device	200
7.28.3.3	set_timer	200
7.28.4	Variable Documentation	201
7.28.4.1	curtain_factory	201
7.28.4.2	device_management_lock	201
7.28.4.3	glb_device_manage	201
7.29	src/device/airCondition/daikin/DTA116A621.c File Reference	202
7.29.1	Macro Definition Documentation	203
7.29.1.1	DAIKIN_HOLD_REGISTER_DEVICE_CONTROL_START	203
7.29.1.2	DAIKIN_HOLD_REGISTER_DEVICE_CONTROL_STOP	203
7.29.1.3	DAIKIN_HOLD_REGISTER_DEVICE_MODE_OFFSET	203
7.29.1.4	DAIKIN_HOLD_REGISTER_DEVICE_ON_OFF_SWING_FAN_OFFSET	203
7.29.1.5	DAIKIN_HOLD_REGISTER_DEVICE_TEMPERATURE_OFFSET	203
7.29.1.6	DAIKIN_HOLD_REGISTER_START	203
7.29.1.7	DAIKIN_INPUT_REGISTER_DEVICE_COMM_STATUS_START	203
7.29.1.8	DAIKIN_INPUT_REGISTER_DEVICE_COMM_STATUS_STOP	203
7.29.1.9	DAIKIN_INPUT_REGISTER_DEVICE_CONNECT_STATUS_START	204
7.29.1.10	DAIKIN_INPUT_REGISTER_DEVICE_CONNECT_STATUS_STOP	204
7.29.1.11	DAIKIN_INPUT_REGISTER_DEVICE_FUNCTION_STATUS_START	204
7.29.1.12	DAIKIN_INPUT_REGISTER_DEVICE_FUNCTION_STATUS_STOP	204
7.29.1.13	DAIKIN_INPUT_REGISTER_DEVICE_STATUS_START	204
7.29.1.14	DAIKIN_INPUT_REGISTER_DEVICE_STATUS_STOP	204
7.29.1.15	DAIKIN_INPUT_REGISTER_START	204
7.29.2	Function Documentation	204
7.29.2.1	get_daikin_hold_register_value	204
7.29.2.2	get_daikin_write_register_addr	205

7.29.3	Variable Documentation	206
7.29.3.1	glb_daikin_hold_register_value	206
7.30	src/device/airCondition/panasonic/panasonic.c File Reference	206
7.30.1	Macro Definition Documentation	208
7.30.1.1	ADR_BROADCAST	208
7.30.1.2	ADR_DEFAULT	208
7.30.1.3	ARG_ERROR	209
7.30.1.4	EOI	209
7.30.1.5	ERROR	209
7.30.1.6	GET_AIR_ADDR	209
7.30.1.7	GET_AIR_ADDR_CID_SEND	209
7.30.1.8	GET_AIR_INFO_CID_SEND	209
7.30.1.9	GET_AIR_INFO_ERROR_CODE_NORMAL	209
7.30.1.10	GET_AIR_INFO_OFF	210
7.30.1.11	GET_AIR_INFO_ON	210
7.30.1.12	GET_AIR_INFO_SET_TEMPERATURE	210
7.30.1.13	GET_AIR_INFO_SET_TEMPERATURE_ADD_1	210
7.30.1.14	GET_AIR_INFO_SET_TEMPERATURE_ADD_5	210
7.30.1.15	GET_AIR_INFO_SET_TEMPERATURE_DOWN	210
7.30.1.16	GET_AIR_INFO_SET_TEMPERATURE_DRY	210
7.30.1.17	GET_AIR_INFO_SET_TEMPERATURE_STD	210
7.30.1.18	GET_AIR_INFO_SET_TEMPERATURE_SUB_1	210
7.30.1.19	GET_AIR_INFO_SET_TEMPERATURE_SUB_5	210
7.30.1.20	GET_AIR_INFO_SET_TEMPERATURE_UP	210
7.30.1.21	GET_AIR_INFO_SET_WIND_DIRECTION_FOCUS	210
7.30.1.22	GET_AIR_INFO_SET_WIND_DIRECTION_HANDL1	211
7.30.1.23	GET_AIR_INFO_SET_WIND_DIRECTION_HANDL2	211
7.30.1.24	GET_AIR_INFO_SET_WIND_DIRECTION_HANDL3	211
7.30.1.25	GET_AIR_INFO_SET_WIND_DIRECTION_HANDL4	211
7.30.1.26	GET_AIR_INFO_SET_WIND_DIRECTION_HANDL5	211
7.30.1.27	GET_AIR_INFO_SET_WIND_DIRECTION_WIDE	211
7.30.1.28	GET_AIR_INFO_SET_WIND_RATE_AUTO	211
7.30.1.29	GET_AIR_INFO_SET_WIND_RATE_HIGH	211
7.30.1.30	GET_AIR_INFO_SET_WIND_RATE_LOW	211
7.30.1.31	GET_AIR_INFO_SET_WIND_RATE_MIDDLE	211
7.30.1.32	GET_AIR_INFO_SET_WIND_RATE_MOST	211
7.30.1.33	GET_AIR_INFO_SET_WIND_RATE_MUTE	211
7.30.1.34	GET_AIR_INFO_TELECONTROLLER_MODE_AUTO	212
7.30.1.35	GET_AIR_INFO_TELECONTROLLER_MODE_COLD	212
7.30.1.36	GET_AIR_INFO_TELECONTROLLER_MODE_DRY	212

7.30.1.37 GET_AIR_INFO_TELECONTROLLER_MODE_HOT . . . . .	212
7.30.1.38 GET_AIR_INFO_TELECONTROLLER_MODE_WIND . . . . .	212
7.30.1.39 GET_AIR_INFO_TEMPERATURE_OVERFLOW . . . . .	212
7.30.1.40 GET_AIR_INFO_TEMPERATURE_UNDERFLOW . . . . .	212
7.30.1.41 GET_AIR_INFO_TEMPERATURE_UNKNOWN . . . . .	212
7.30.1.42 HIGH_CHAR . . . . .	212
7.30.1.43 LOW_CHAR . . . . .	212
7.30.1.44 PACKAGE_MAX . . . . .	212
7.30.1.45 RECEIVE_CHK_ERROR . . . . .	212
7.30.1.46 RECEIVE_ERROR . . . . .	213
7.30.1.47 RESET_AIR_CID_SEND . . . . .	213
7.30.1.48 RETURN_CHK_ERROR . . . . .	213
7.30.1.49 RETURN_DATA_INVALID_ERROR . . . . .	213
7.30.1.50 RTN_RECEIVE_CHK_ERROR . . . . .	213
7.30.1.51 RTN_RECEIVE_CMD_INVALID . . . . .	213
7.30.1.52 RTN_RECEIVE_CMD_RIGHT . . . . .	213
7.30.1.53 RTN_SEND . . . . .	213
7.30.1.54 SEND_ERROR . . . . .	213
7.30.1.55 SET_AIR_ARG_CID_SEND . . . . .	213
7.30.1.56 SET_AIR_ARG_CONFIG_OPT_ALL . . . . .	213
7.30.1.57 SET_AIR_ARG_CONFIG_OPT_KEEP . . . . .	213
7.30.1.58 SET_AIR_ARG_CONFIG_OPT_MODE . . . . .	214
7.30.1.59 SET_AIR_ARG_CONFIG_OPT_SWITCH . . . . .	214
7.30.1.60 SET_AIR_ARG_CONFIG_OPT_TEMPERATURE . . . . .	214
7.30.1.61 SET_AIR_ARG_CONFIG_OPT_WIND_DIRECTION . . . . .	214
7.30.1.62 SET_AIR_ARG_CONFIG_OPT_WIND_RATE . . . . .	214
7.30.1.63 SET_AIR_ARG_OFF . . . . .	214
7.30.1.64 SET_AIR_ARG_ON . . . . .	214
7.30.1.65 SET_AIR_ARG_TELECONTROLLER_MODE_AUTO . . . . .	214
7.30.1.66 SET_AIR_ARG_TELECONTROLLER_MODE_COLD . . . . .	214
7.30.1.67 SET_AIR_ARG_TELECONTROLLER_MODE_DRY . . . . .	214
7.30.1.68 SET_AIR_ARG_TELECONTROLLER_MODE_HOT . . . . .	214
7.30.1.69 SET_AIR_ARG_TELECONTROLLER_MODE_WIND . . . . .	214
7.30.1.70 SET_AIR_ARG_TEMPERATURE . . . . .	215
7.30.1.71 SET_AIR_ARG_WIND_DIRECTION_FOCUS . . . . .	215
7.30.1.72 SET_AIR_ARG_WIND_DIRECTION_HANDL . . . . .	215
7.30.1.73 SET_AIR_ARG_WIND_DIRECTION_WIDE . . . . .	215
7.30.1.74 SET_AIR_ARG_WIND_RATE_AUTO . . . . .	215
7.30.1.75 SET_AIR_ARG_WIND_RATE_HIGH . . . . .	215
7.30.1.76 SET_AIR_ARG_WIND_RATE_LOW . . . . .	215

7.30.1.77 SET_AIR_ARG_WIND_RATE_MIDDLE . . . . .	215
7.30.1.78 SET_AIR_ARG_WIND_RATE_MOST . . . . .	215
7.30.1.79 SET_AIR_ARG_WIND_RATE_MUTE . . . . .	215
7.30.1.80 SOI_RECEIVE . . . . .	215
7.30.1.81 SOI_SEND . . . . .	215
7.30.1.82 UNKNOW_ERROR . . . . .	216
7.30.2 Function Documentation . . . . .	216
7.30.2.1 calculate_sum_check . . . . .	216
7.30.2.2 panasonic_send_package . . . . .	216
7.30.3 Variable Documentation . . . . .	216
7.30.3.1 air_command_table . . . . .	217
7.31 src/device/airCondition/york/york.c File Reference . . . . .	217
7.31.1 Enumeration Type Documentation . . . . .	218
7.31.1.1 york_air_conditioner_object . . . . .	218
7.31.2 Function Documentation . . . . .	219
7.31.2.1 get_air_york_write_args . . . . .	219
7.31.3 Variable Documentation . . . . .	219
7.31.3.1 york_air_condition_object . . . . .	219
7.31.3.2 york_air_condition_read_property . . . . .	219
7.32 src/device/curtain/aoke/aoke.c File Reference . . . . .	219
7.32.1 Macro Definition Documentation . . . . .	221
7.32.1.1 RS485_CURTAIN_AO_KE_ADDRING . . . . .	221
7.32.1.2 RS485_CURTAIN_AO_KE_COMMAND_ADDRING . . . . .	221
7.32.1.3 RS485_CURTAIN_AO_KE_COMMAND_CONTROL . . . . .	221
7.32.1.4 RS485_CURTAIN_AO_KE_COMMAND_DELETE . . . . .	221
7.32.1.5 RS485_CURTAIN_AO_KE_COMMAND_GETTING . . . . .	221
7.32.1.6 RS485_CURTAIN_AO_KE_COMMAND_POINT . . . . .	221
7.32.1.7 RS485_CURTAIN_AO_KE_COMMAND_POSTION . . . . .	221
7.32.1.8 RS485_CURTAIN_AO_KE_COMMAND_SETTING . . . . .	221
7.32.1.9 RS485_CURTAIN_AO_KE_CONTROL_DELETE_ADDR . . . . .	221
7.32.1.10 RS485_CURTAIN_AO_KE_CONTROL_DOWN . . . . .	221
7.32.1.11 RS485_CURTAIN_AO_KE_CONTROL_MIDDLE_1 . . . . .	221
7.32.1.12 RS485_CURTAIN_AO_KE_CONTROL_MIDDLE_2 . . . . .	221
7.32.1.13 RS485_CURTAIN_AO_KE_CONTROL_MIDDLE_3 . . . . .	222
7.32.1.14 RS485_CURTAIN_AO_KE_CONTROL_MIDDLE_4 . . . . .	222
7.32.1.15 RS485_CURTAIN_AO_KE_CONTROL_SET_ADDR . . . . .	222
7.32.1.16 RS485_CURTAIN_AO_KE_CONTROL_STOP . . . . .	222
7.32.1.17 RS485_CURTAIN_AO_KE_CONTROL_UP . . . . .	222
7.32.1.18 RS485_CURTAIN_AO_KE_DELETE . . . . .	222
7.32.1.19 RS485_CURTAIN_AO_KE_POINT_DELETE . . . . .	222

7.32.1.20 RS485_CURTAIN_AO_KE_POINT_DOWN . . . . .	222
7.32.1.21 RS485_CURTAIN_AO_KE_POINT_MIDDLE . . . . .	222
7.32.1.22 RS485_CURTAIN_AO_KE_POINT_SAVE . . . . .	222
7.32.1.23 RS485_CURTAIN_AO_KE_POINT_UP . . . . .	222
7.32.1.24 RS485_CURTAIN_AO_KE_SI . . . . .	222
7.32.1.25 RS485_CURTIAN_AO_KE_GETTING_STATUS . . . . .	223
7.32.1.26 RS485_CURTIAN_AO_KE_POSTION . . . . .	223
7.32.1.27 RS485_CURTIAN_AO_KE_SETTING_HANDLE . . . . .	223
7.32.2 Function Documentation . . . . .	223
7.32.2.1 get_check . . . . .	223
7.33 src/device/curtain/doya/doya.c File Reference . . . . .	223
7.33.1 Macro Definition Documentation . . . . .	225
7.33.1.1 CURTAIN_COMMAND . . . . .	225
7.33.1.2 CURTAIN_COMMAND_CLOSE . . . . .	225
7.33.1.3 CURTAIN_COMMAND_DELETE . . . . .	225
7.33.1.4 CURTAIN_COMMAND_OPEN . . . . .	225
7.33.1.5 CURTAIN_COMMAND_PERCENT . . . . .	225
7.33.1.6 CURTAIN_COMMAND_REFACTORY . . . . .	226
7.33.1.7 CURTAIN_COMMAND_STOP . . . . .	226
7.33.1.8 CURTAIN_READ . . . . .	226
7.33.1.9 CURTAIN_READ_WRITE_ADDR . . . . .	226
7.33.1.10 CURTAIN_READ_WRITE_ADDR_HIGH . . . . .	226
7.33.1.11 CURTAIN_READ_WRITE_ADDR_LOW . . . . .	226
7.33.1.12 CURTAIN_READ_WRITE_DIRECTION . . . . .	226
7.33.1.13 CURTAIN_READ_WRITE_HANDLE . . . . .	226
7.33.1.14 CURTAIN_READ_WRITE_PERCENT . . . . .	226
7.33.1.15 CURTAIN_READ_WRITE_SWITCH_ACTIVE . . . . .	226
7.33.1.16 CURTAIN_READ_WRITE_SWITCH_PASSIVE . . . . .	226
7.33.1.17 CURTAIN_READ_WRITE_VERSION . . . . .	226
7.33.1.18 CURTAIN_WRITE . . . . .	227
7.33.1.19 HANDLE_DISABLE . . . . .	227
7.33.1.20 HANDLE_ENABLE . . . . .	227
7.33.1.21 MOTOR_NEGATIVE . . . . .	227
7.33.1.22 MOTOR_POSITIVE . . . . .	227
7.33.1.23 SWITCH_ACTIVE_DOUBLE_LINE . . . . .	227
7.33.1.24 SWITCH_ACTIVE_SINGLE_LINE . . . . .	227
7.33.1.25 SWITCH_PASSIVE_DOUBLE_NO_REBOUND . . . . .	227
7.33.1.26 SWITCH_PASSIVE_DOUBLE_REBOUND . . . . .	227
7.33.1.27 SWITCH_PASSIVE_ELECTRONIC_DC246 . . . . .	227
7.33.1.28 SWITCH_PASSIVE_SINGLE_CYCLE . . . . .	227



7.33.2	Enumeration Type Documentation	227
7.33.2.1	command	227
7.33.3	Function Documentation	228
7.33.3.1	close_curtain_no_reply	228
7.33.3.2	delete_track_curtain_no_reply	228
7.33.3.3	doya_send_package	229
7.33.3.4	modbus_crc16	229
7.33.3.5	open_curtain_no_reply	230
7.33.3.6	percent_curtain_no_reply	231
7.33.3.7	read_percent_curtain_no_reply	231
7.33.3.8	read_version_curtain_no_reply	231
7.33.3.9	receive_package	232
7.33.3.10	refactory_curtain_no_reply	232
7.33.3.11	rs485_read	232
7.33.3.12	rs485_send	233
7.33.3.13	send_package	234
7.33.3.14	set_addr_curtain_no_reply	236
7.33.3.15	set_direction_curtain_no_reply	237
7.33.3.16	set_handle_enable_curtain_no_reply	237
7.33.3.17	set_switch_active_curtain_no_reply	237
7.33.3.18	set_switch_passive_curtain_no_reply	238
7.33.3.19	stop_curtain_no_reply	238
7.33.4	Variable Documentation	238
7.33.4.1	crc_high	238
7.33.4.2	crc_low	239
7.34	src/device/freshAir/loreley/loreley.c File Reference	239
7.34.1	Macro Definition Documentation	241
7.34.1.1	ADR_BROADCAST	241
7.34.1.2	ADR_DEFAULT	241
7.34.1.3	EOI	241
7.34.1.4	NEW_TREND_PACKAGE_MAX	241
7.34.1.5	RS485_NEW_TREND_GET_ADDR_CID	241
7.34.1.6	RS485_NEW_TREND_GET_INFO_CID	241
7.34.1.7	RS485_NEW_TREND_MODE_AUTOING	241
7.34.1.8	RS485_NEW_TREND_MODE_IN_CRC	241
7.34.1.9	RS485_NEW_TREND_MODE_KILLING	241
7.34.1.10	RS485_NEW_TREND_MODE_OUT_CRC	241
7.34.1.11	RS485_NEW_TREND_MODE_WAITING	241
7.34.1.12	RS485_NEW_TREND_RESTART_CID	241
7.34.1.13	RS485_NEW_TREND_RUN_STATUS_OFF	242

7.34.1.14	RS485_NEW_TREND_RUN_STATUS_ON	242
7.34.1.15	RS485_NEW_TREND_SET_ADDR_CID	242
7.34.1.16	RS485_NEW_TREND_SET_ARG_CID	242
7.34.1.17	RS485_NEW_TREND_STATUS_ERROR	242
7.34.1.18	RS485_NEW_TREND_STATUS_NORMAL	242
7.34.1.19	RTN_RECEIVE_CHK_ERROR	242
7.34.1.20	RTN_RECEIVE_CMD_INVALID	242
7.34.1.21	RTN_RECEIVE_CMD_RIGHT	242
7.34.1.22	RTN_SEND	242
7.34.1.23	SOI_RECEIVE	242
7.34.1.24	SOI_SEND	242
7.34.2	Function Documentation	243
7.34.2.1	calculate_sum_check	243
7.34.2.2	loreley_send_package	243
7.34.3	Variable Documentation	243
7.34.3.1	rs485_set_new_trend_table	243
7.35	src/enumtxt.c File Reference	244
7.36	src/item_config.c File Reference	244
7.36.1	Macro Definition Documentation	245
7.36.1.1	PANNO_S_ITEM_ARMANI	245
7.36.1.2	PANNO_S_ITEM_DEFAULT	245
7.36.1.3	PANNO_S_ITEM_SHAOCHENGGUOJI	245
7.36.1.4	PANNO_S_ITEM_WENRUDE	246
7.36.2	Function Documentation	246
7.36.2.1	_mount_device	246
7.37	src/main.c File Reference	246
7.37.1	Detailed Description	247
7.37.2	Macro Definition Documentation	247
7.37.2.1	LOCKFILE	247
7.37.2.2	LOCKMODE	247
7.37.3	Function Documentation	247
7.37.3.1	already_running	247
7.37.3.2	daemonize	248
7.37.3.3	lockfile	248
7.37.3.4	main	248
7.37.3.5	signal_handle_pthread	248
7.37.4	Variable Documentation	248
7.37.4.1	mask	248
7.38	src/object.c File Reference	249
7.38.1	Macro Definition Documentation	250

7.38.1.1	RS485_OBJECT_MAX_NUMBERS	250
7.38.1.2	RS485_WORK_QUEUE_DEPTH	250
7.38.2	Function Documentation	250
7.38.2.1	check_object_is_support	250
7.38.3	Variable Documentation	251
7.38.3.1	glb_object_manage	251
7.38.3.2	glb_work_queue	251
7.39	src/protocol/bacnet/bacnet.c File Reference	251
7.39.1	Function Documentation	252
7.39.1.1	york_air_condition_handle	252
7.40	src/protocol/bacnet/device-client.c File Reference	252
7.40.1	Detailed Description	254
7.40.2	Function Documentation	254
7.40.2.1	Device_Application_Software_Version	254
7.40.2.2	Device_Count	254
7.40.2.3	Device_Database_Revision	254
7.40.2.4	Device_Description	254
7.40.2.5	Device_Firmware_Revision	254
7.40.2.6	Device_Inc_Database_Revision	254
7.40.2.7	Device_Index_To_Instance	255
7.40.2.8	Device_Init	255
7.40.2.9	Device_Location	255
7.40.2.10	Device_Model_Name	255
7.40.2.11	Device_Object_Instance_Number	255
7.40.2.12	Device_Object_List_Count	256
7.40.2.13	Device_Object_List_Identifier	256
7.40.2.14	Device_Object_Name	257
7.40.2.15	Device_Object_Name_Copy	257
7.40.2.16	Device_Objects_Find_Functions	258
7.40.2.17	Device_Protocol_Revision	258
7.40.2.18	Device_Protocol_Version	258
7.40.2.19	Device_Read_Property	259
7.40.2.20	Device_Read_Property_Local	259
7.40.2.21	Device_Segmentation_Supported	260
7.40.2.22	Device_Set_Application_Software_Version	260
7.40.2.23	Device_Set_Database_Revision	260
7.40.2.24	Device_Set_Description	261
7.40.2.25	Device_Set_Location	261
7.40.2.26	Device_Set_Model_Name	261
7.40.2.27	Device_Set_Object_Instance_Number	261

7.40.2.28 Device_Set_Object_Name . . . . .	261
7.40.2.29 Device_Set_System_Status . . . . .	262
7.40.2.30 Device_Set_Vendor_Identifier . . . . .	262
7.40.2.31 Device_System_Status . . . . .	262
7.40.2.32 Device_Valid_Object_Id . . . . .	262
7.40.2.33 Device_Valid_Object_Instance_Number . . . . .	262
7.40.2.34 Device_Valid_Object_Name . . . . .	262
7.40.2.35 Device_Vendor_Identifier . . . . .	263
7.40.2.36 Device_Vendor_Name . . . . .	263
7.40.3 Variable Documentation . . . . .	263
7.40.3.1 Application_Software_Version . . . . .	263
7.40.3.2 Database_Revision . . . . .	263
7.40.3.3 Description . . . . .	263
7.40.3.4 Location . . . . .	263
7.40.3.5 Model_Name . . . . .	264
7.40.3.6 My_Object_Name . . . . .	264
7.40.3.7 Object_Instance_Number . . . . .	264
7.40.3.8 Object_Table . . . . .	264
7.40.3.9 System_Status . . . . .	264
7.40.3.10 Vendor_Identifier . . . . .	264
7.40.3.11 Vendor_Name . . . . .	264
7.41 src/protocol/bacnet/handle_property.c File Reference . . . . .	265
7.41.1 Macro Definition Documentation . . . . .	266
7.41.1.1 MAX_PROPERTY_VALUES . . . . .	266
7.41.2 Function Documentation . . . . .	266
7.41.2.1 enno_dlenv_init . . . . .	266
7.41.2.2 Init_Service_Handlers . . . . .	266
7.41.2.3 My_Read_Property_Ack_Handler . . . . .	267
7.41.2.4 My_Read_Property_Multiple_Ack_Handler . . . . .	268
7.41.2.5 MyAbortHandler . . . . .	268
7.41.2.6 MyErrorHandler . . . . .	268
7.41.2.7 MyRejectHandler . . . . .	268
7.41.2.8 MyWritePropertySimpleAckHandler . . . . .	268
7.41.3 Variable Documentation . . . . .	269
7.41.3.1 glb_config_bacnet_object_instance . . . . .	269
7.42 src/protocol/bacnet/read_property.c File Reference . . . . .	269
7.42.1 Function Documentation . . . . .	270
7.42.1.1 bacnet_read_property . . . . .	270
7.42.1.2 memcpy_read_args . . . . .	270
7.42.1.3 My_Read_Property_Ack_Handler . . . . .	271

7.42.1.4	My_Read_Property_Multiple_Ack_Handler	271
7.42.2	Variable Documentation	271
7.42.2.1	read_access_data	271
7.42.2.2	read_access_data_property	271
7.42.2.3	Request_Invoke_ID	271
7.42.2.4	Target_Address	271
7.43	src/protocol/bacnet/write_property.c File Reference	272
7.43.1	Macro Definition Documentation	273
7.43.1.1	MAX_PROPERTY_VALUES	273
7.43.1.2	RETRANSMISSION_TIMES	273
7.43.2	Function Documentation	273
7.43.2.1	bacnet_write_property	273
7.43.2.2	MyWritePropertySimpleAckHandler	273
7.43.3	Variable Documentation	273
7.43.3.1	Error_Detected	273
7.43.3.2	Request_Invoke_ID	273
7.43.3.3	Rx_Buf	273
7.43.3.4	Target_Address	274
7.43.3.5	Target_Object_Property_Value	274
7.44	src/protocol/general/general.c File Reference	274
7.44.1	Macro Definition Documentation	275
7.44.1.1	BUS_MAX_RETRANSMISSION	275
7.45	src/protocol/general/rs485.c File Reference	275
7.45.1	Macro Definition Documentation	276
7.45.1.1	_POSIX_SOURCE	276
7.45.1.2	RS485_DEBUG	276
7.45.1.3	RS485MOD	276
7.45.2	Function Documentation	276
7.45.2.1	rs485_get_baud_rate	276
7.45.2.2	rs485_interface	276
7.45.3	Variable Documentation	276
7.45.3.1	RS485_Baud	276
7.45.3.2	RS485_Handle	277
7.45.3.3	RS485_oldserial	277
7.45.3.4	RS485_oldtio	277
7.45.3.5	RS485_Port_Name	277
7.45.3.6	RS485_SpecBaud	277
7.46	src/protocol/modbus/modbus.c File Reference	277
7.46.1	Macro Definition Documentation	278
7.46.1.1	RS485_MODBUS_MTU	278

7.47	src/read_config.c File Reference	278
7.47.1	Variable Documentation	279
7.47.1.1	glb_config_adapter_message_queue_depth	279
7.47.1.2	glb_config_bacnet_object_instance	279
7.47.1.3	glb_config_bacnet_work_queue_depth	279
7.47.1.4	glb_config_client_max_numbers	279
7.47.1.5	glb_config_general_work_package_mtu	279
7.47.1.6	glb_config_general_work_queue_depth	279
7.47.1.7	glb_config_modbus_work_queue_depth	279
7.48	src/service.c File Reference	279
7.48.1	Detailed Description	281
7.48.2	Macro Definition Documentation	281
7.48.2.1	NALLOC	281
7.48.2.2	RECEIVE_BUFFER_LENGTH	281
7.48.2.3	RS485_UNIX_DOMAIN_PATH	281
7.48.3	Function Documentation	281
7.48.3.1	adapter_thread_function	281
7.48.3.2	client_add	282
7.48.3.3	client_alloc	283
7.48.3.4	client_del	283
7.48.3.5	process_client_request	283
7.48.3.6	rs485_receive_from_client	284
7.48.3.7	rs485_service_listen	284
7.48.3.8	serv_accept	284
7.48.3.9	timer_task_thread_function	285
7.48.4	Variable Documentation	285
7.48.4.1	adapter_message_queue	285
7.48.4.2	adapter_thread	285
7.48.4.3	addr	285
7.48.4.4	client	285
7.48.4.5	client_size	285
7.48.4.6	glb_config_adapter_message_queue_depth	285
7.48.4.7	glb_config_client_max_numbers	285
7.48.4.8	receive_buffer	285
7.48.4.9	rs485_thread_pool	285
7.48.4.10	socket_fd	286
7.48.4.11	socket_len	286
7.48.4.12	timer_task_thread	286
7.48.4.13	unix_domain_path	286
7.49	src/support.c File Reference	286

7.49.1	Variable Documentation	287
7.49.1.1	air_condition_daikin_dta116a621	287
7.49.1.2	air_condition_panasonic	287
7.49.1.3	curtain_aoke	287
7.49.1.4	curtain_doya	288
7.49.1.5	fresh_air_loreley	288
7.50	src/syslog/log.c File Reference	288
7.50.1	Detailed Description	288
7.51	src/timer_task.c File Reference	289
7.51.1	Detailed Description	290
7.51.2	Macro Definition Documentation	290
7.51.2.1	SYSTEM_TIMER_TICK_SECOND	290
7.51.3	Function Documentation	290
7.51.3.1	device_timer_task_handle_curtain_aoke_init	290
7.51.3.2	device_timer_task_handle_curtain_doya_init	290
7.51.3.3	device_timer_task_handle_curtain_init	291
7.51.3.4	timer_task_init	292
7.51.3.5	timer_task_thread_function	292
7.51.4	Variable Documentation	292
7.51.4.1	timer_task_list	292
7.51.4.2	timer_task_list_iterator	292
7.51.4.3	timer_task_lock	292
7.51.4.4	timer_task_thread_status	293
<b>Index</b>		<b>294</b>





# Chapter 1

## RS485 SERVER API Documentation

This documents the RS485 API, Modbus/BACnet/General, and sample applications.

- The high-level handler interface can be found in the Modules tab.
- Specifics for each file can be found in the Files tab.
- A full list of all functions is provided in the index of the Files->Globals subtab.

While all the central files are included in the file list, not all important functions have been given the javadoc treatment, nor have Modules (chapters) been created yet for all groupings. If you are doing work in an under-documented area, please add the javadoc comments at least to the API calls, and consider adding doxygen's module grouping for your area of interest.

See doc/README.doxygen for notes on building and extending this document.

In particular, if you have graphviz installed, you can enhance this documentation by turning on the function call graphs feature.

Copyright: [www.enno.com](http://www.enno.com)

Author: [chuanjiang.wang](mailto:chuanjiang.wang)

E-mail: [chuanjiang.wang@enno.com](mailto:chuanjiang.wang@enno.com)



## Chapter 2

# Module Index

### 2.1 Modules

Here is a list of all modules:

Management . . . . .	??
Adapter management . . . . .	??
Device management . . . . .	??
String management . . . . .	??
Item management . . . . .	??
Object management . . . . .	??
Service management . . . . .	??
Device register management . . . . .	??
Timer management . . . . .	??
Protocol . . . . .	??
BACnet . . . . .	??
BACnet interface . . . . .	??
Handle_property . . . . .	??
Modbus . . . . .	??
Modbus RS485 . . . . .	??
General . . . . .	??
General interface . . . . .	??
General RS485 . . . . .	??
Device . . . . .	??
AirConditon . . . . .	??
DaiKin DTA116A621 . . . . .	??
Panasonic GuangZhou . . . . .	??
YORK GuangZhou KeLong . . . . .	??
Curtain . . . . .	??
Aoke GuangZhou . . . . .	??
Dooya HangZhou . . . . .	??
FreshAir . . . . .	??
Loreley ShenZhen . . . . .	??



## Chapter 3

# Data Structure Index

### 3.1 Data Structures

Here are the data structures with brief descriptions:

<a href="#">adapter_t</a>	Define the adapter struct . . . . .	??
<a href="#">air_condition_profile_t</a>	The air conditon profile . . . . .	??
<a href="#">bacnet</a>	Bacnet bacnet interface struct . . . . .	??
<a href="#">bacnet_read_args_t</a>	Bacnet read property struct . . . . .	??
<a href="#">bacnet_write_args_t</a>	Bacnet write arg struct . . . . .	??
<a href="#">client_t</a>	. . . . .	??
<a href="#">commonBacObj_s</a>	. . . . .	??
<a href="#">create_object_return_t</a>	Message create a rs485 object return . . . . .	??
<a href="#">create_object_t</a>	Message create a rs485 object . . . . .	??
<a href="#">curtain_profile_t</a>	The curtain profile . . . . .	??
<a href="#">delete_object_return_t</a>	Message delete a rs485 object return . . . . .	??
<a href="#">delete_object_t</a>	Message delete a rs485 object . . . . .	??
<a href="#">device_management</a>	Device define the device management struct . . . . .	??
<a href="#">device_profile</a>	Device_profile device process method . . . . .	??
<a href="#">devObj_s</a>	. . . . .	??
<a href="#">fresh_air_profile_t</a>	The fresh profile . . . . .	??
<a href="#">message_service_t</a>	Define the receive the message type . . . . .	??
<a href="#">modbus_port_handle_t</a>	The modbus port interface . . . . .	??
<a href="#">mount_devcie_to_object_t</a>	Message mount a device to rs485 object . . . . .	??
<a href="#">mount_device_to_object_return_t</a>	Message mount a device to rs485 object return . . . . .	??

<a href="#">mstp_port_handle</a>	
Mstp_port_handle general protocol(user defined)	??
<a href="#">object_functions</a>	??
<a href="#">object_management</a>	
Object_management define the object management struct	??
<a href="#">package</a>	??
<a href="#">read_device_return_t</a>	
Message read value from device return	??
<a href="#">read_device_t</a>	
Message read value from device	??
<a href="#">rs485_curtain_ao_ke_send_package_t</a>	??
<a href="#">rs485_device_profile</a>	
Rs485 device profile	??
<a href="#">rs485_port_t</a>	
The rs485 port physical	??
<a href="#">thread_pool_t</a>	
Define the thread pool struct	??
<a href="#">timer_task_t</a>	
Timer task struct	??
<a href="#">unmount_device_from_object_return_t</a>	
Message unmount a device from rs485 object return	??
<a href="#">unmount_device_from_object_t</a>	
Message unmount a device form rs485 object	??
<a href="#">write_device_return_t</a>	
Message write value to device return	??
<a href="#">write_device_t</a>	
Message write value to device	??

## Chapter 4

# File Index

### 4.1 File List

Here is a list of all files with brief descriptions:

include/ <a href="#">adapter.h</a>	??
include/ <a href="#">device.h</a>	??
include/ <a href="#">enum.h</a>	??
include/ <a href="#">enumtxt.h</a>	??
include/ <a href="#">item_config.h</a>	??
include/ <a href="#">object.h</a>	??
include/ <a href="#">read_config.h</a>	??
include/ <a href="#">rs485.h</a>	??
include/ <a href="#">service.h</a>	??
include/ <a href="#">support.h</a>	??
include/ <a href="#">timer_task.h</a>	??
include/device/airCondition/daikin/ <a href="#">DTA116A621.h</a>	??
include/device/airCondition/panasonic/ <a href="#">panasonic.h</a>	??
include/device/airCondition/york/ <a href="#">york.h</a>	??
include/device/curtain/aoke/ <a href="#">aoke.h</a>	??
include/device/curtain/doya/ <a href="#">doya.h</a>	??
include/device/freshAir/loreley/ <a href="#">loreley.h</a>	??
include/protocol/bacnet/ <a href="#">bacnet.h</a>	??
include/protocol/bacnet/ <a href="#">device_client.h</a>	??
include/protocol/bacnet/ <a href="#">handle_property.h</a>	??
include/protocol/bacnet/ <a href="#">read_property.h</a>	??
include/protocol/bacnet/ <a href="#">write_property.h</a>	??
include/protocol/general/ <a href="#">general.h</a>	??
include/protocol/general/ <a href="#">rs485.h</a>	??
include/protocol/modbus/ <a href="#">modbus.h</a>	??
include/syslog/ <a href="#">log.h</a>	??
src/ <a href="#">adapter.c</a>	??
src/ <a href="#">device.c</a>	??
src/ <a href="#">enumtxt.c</a>	??
src/ <a href="#">item_config.c</a>	??
src/ <a href="#">main.c</a>	??
src/ <a href="#">object.c</a>	??
src/ <a href="#">read_config.c</a>	??
src/ <a href="#">service.c</a>	??
src/ <a href="#">support.c</a>	??
src/ <a href="#">timer_task.c</a>	??
src/device/airCondition/daikin/ <a href="#">DTA116A621.c</a>	??
src/device/airCondition/panasonic/ <a href="#">panasonic.c</a>	??

src/device/airCondition/york/ <a href="#">york.c</a>	??
src/device/curtain/aoke/ <a href="#">aoke.c</a>	??
src/device/curtain/doya/ <a href="#">doya.c</a>	??
src/device/freshAir/loreley/ <a href="#">loreley.c</a>	??
src/protocol/bacnet/ <a href="#">bacnet.c</a>	??
src/protocol/bacnet/ <a href="#">device-client.c</a>	??
src/protocol/bacnet/ <a href="#">handle_property.c</a>	??
src/protocol/bacnet/ <a href="#">read_property.c</a>	??
src/protocol/bacnet/ <a href="#">write_property.c</a>	??
src/protocol/general/ <a href="#">general.c</a>	??
src/protocol/general/ <a href="#">rs485.c</a>	??
src/protocol/modbus/ <a href="#">modbus.c</a>	??
src/syslog/ <a href="#">log.c</a>	??

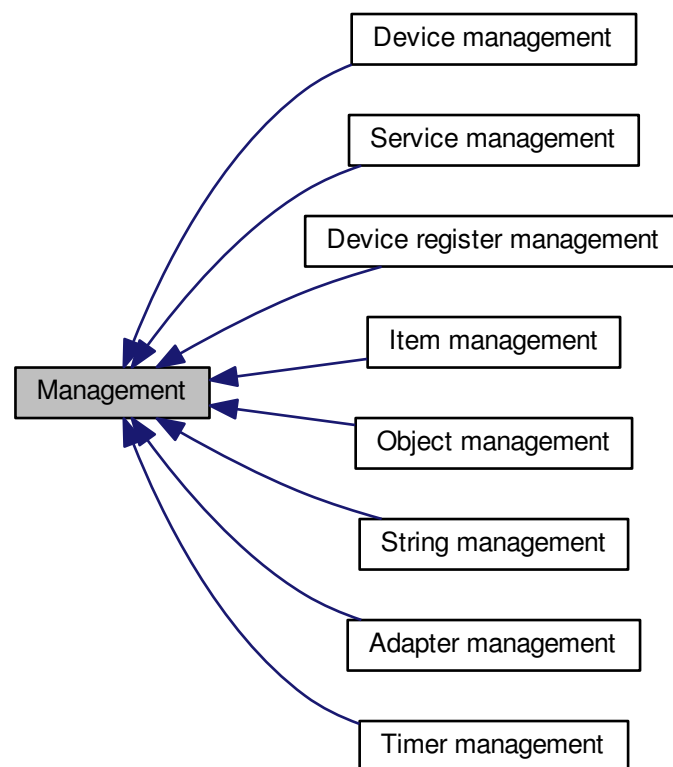


## Chapter 5

# Module Documentation

### 5.1 Management

Collaboration diagram for Management:



#### Modules

- [Adapter management](#)
- [Device management](#)

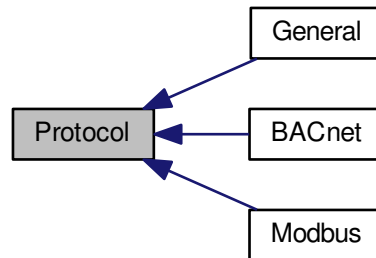
- [String management](#)
- [Item management](#)
- [Object management](#)
- [Service management](#)
- [Device register management](#)
- [Timer management](#)

### 5.1.1 Detailed Description

The RS485 service management

## 5.2 Protocol

Collaboration diagram for Protocol:



### Modules

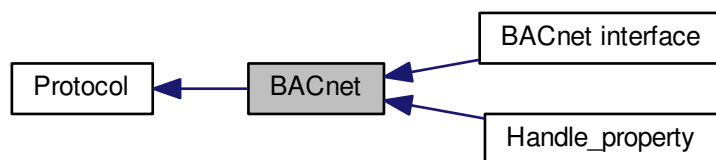
- [BACnet](#)
- [Modbus](#)
- [General](#)

### 5.2.1 Detailed Description

The rs485 support protocol module

## 5.3 BACnet

Collaboration diagram for BACnet:



### Modules

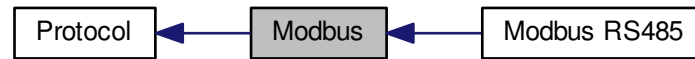
- [BACnet interface](#)
- [Handle\\_property](#)

#### 5.3.1 Detailed Description

The BACnet protocol

## 5.4 Modbus

Collaboration diagram for Modbus:



### Modules

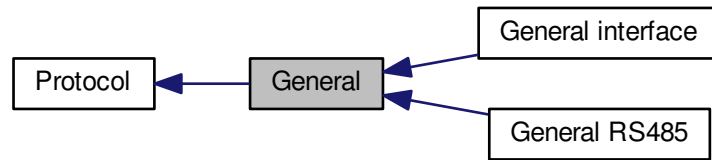
- [Modbus RS485](#)

#### 5.4.1 Detailed Description

The Modbus protocol

## 5.5 General

Collaboration diagram for General:



### Modules

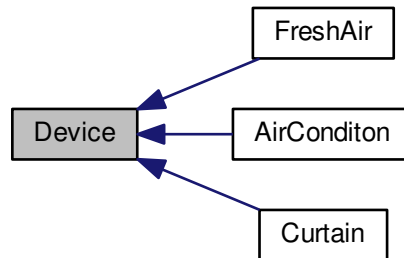
- [General interface](#)
- [General RS485](#)

### 5.5.1 Detailed Description

The user defined protocol

## 5.6 Device

Collaboration diagram for Device:



### Modules

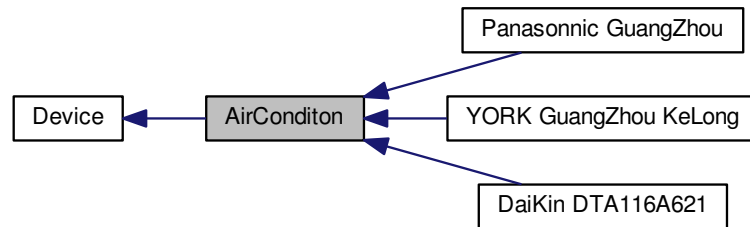
- [AirConditon](#)
- [Curtain](#)
- [FreshAir](#)

#### 5.6.1 Detailed Description

The rs485 support device module

## 5.7 AirConditon

Collaboration diagram for AirConditon:



### Modules

- [DaiKin DTA116A621](#)
- [Panasonic GuangZhou](#)
- [YORK GuangZhou KeLong](#)

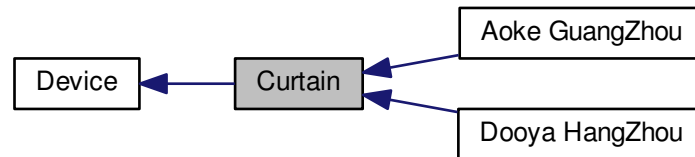
#### 5.7.1 Detailed Description

The air conditon device



## 5.8 Curtain

Collaboration diagram for Curtain:



### Modules

- [Aoke GuangZhou](#)
- [Dooya HangZhou](#)

### 5.8.1 Detailed Description

The curtain device

## 5.9 FreshAir

Collaboration diagram for FreshAir:



### Modules

- [Loreley ShenZhen](#)

#### 5.9.1 Detailed Description

The fresh air device

## 5.10 Adapter management

Collaboration diagram for Adapter management:



### Data Structures

- struct [rs485\\_port\\_t](#)  
*The rs485 port physical.*
- struct [create\\_object\\_t](#)  
*message create a rs485 object*
- struct [create\\_object\\_return\\_t](#)  
*message create a rs485 object return*
- struct [delete\\_object\\_t](#)  
*message delete a rs485 object*
- struct [delete\\_object\\_return\\_t](#)  
*message delete a rs485 object return*
- struct [mount\\_devicie\\_to\\_object\\_t](#)  
*message mount a device to rs485 object*
- struct [mount\\_device\\_to\\_object\\_return\\_t](#)  
*message mount a device to rs485 object return*
- struct [unmount\\_device\\_from\\_object\\_t](#)  
*message unmount a device form rs485 object*
- struct [unmount\\_device\\_from\\_object\\_return\\_t](#)  
*message unmount a device from rs485 ojbject return*
- struct [write\\_device\\_t](#)  
*message write value to device*
- struct [write\\_device\\_return\\_t](#)  
*message write value to device return*
- struct [read\\_device\\_t](#)  
*message read value from device*
- struct [air\\_condition\\_profile\\_t](#)  
*The air conditon profile.*
- struct [curtain\\_profile\\_t](#)  
*The curtain profile.*
- struct [fresh\\_air\\_profile\\_t](#)  
*The fresh profile.*
- union [rs485\\_device\\_profile](#)  
*rs485 device profile*
- struct [read\\_device\\_return\\_t](#)  
*message read value from device return*
- union [message\\_service\\_t](#)  
*define the receive the message type*
- struct [adapter\\_t](#)  
*define the adapter struct*

## Functions

- static int [adapter\\_thread\\_init](#) (void)  
*adapter\_thread\_init initialize the adapter thread , and mesesage queue initial.*
- static int [process\\_write\\_value\\_service](#) (const [adapter\\_t](#) \*adapter)  
*process\_write\_value\_service process the client write value to device service*
- static int [process\\_read\\_value\\_service](#) ([adapter\\_t](#) \*adapter)  
*process\_read\_value\_service process the client read value from device service*

### 5.10.1 Detailed Description

Functions to rs485 device create , delete , management.

### 5.10.2 Function Documentation

#### 5.10.2.1 static int adapter\_thread\_init ( void ) [static]

[adapter\\_thread\\_init](#) initialize the adapter thread , and mesesage queue initial.

#### Returns

0 is initialize success, and others is fail.

Definition at line 65 of file [adapter.c](#).

Here is the call graph for this function:



Here is the caller graph for this function:



#### 5.10.2.2 static int process\_read\_value\_service ( adapter\_t \* adapter ) [static]

[process\\_read\\_value\\_service](#) process the client read value from device service

## Parameters

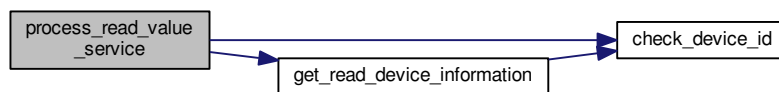
<i>adapter</i>	: The adapter struct information
----------------	----------------------------------

## Returns

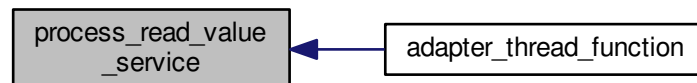
0 is success, and others is fail.

Definition at line 285 of file adapter.c.

Here is the call graph for this function:



Here is the caller graph for this function:



### 5.10.2.3 static int process\_write\_value\_service ( const adapter\_t\* *adapter* ) [static]

`process_write_value_service` process the client write value to device service

## Parameters

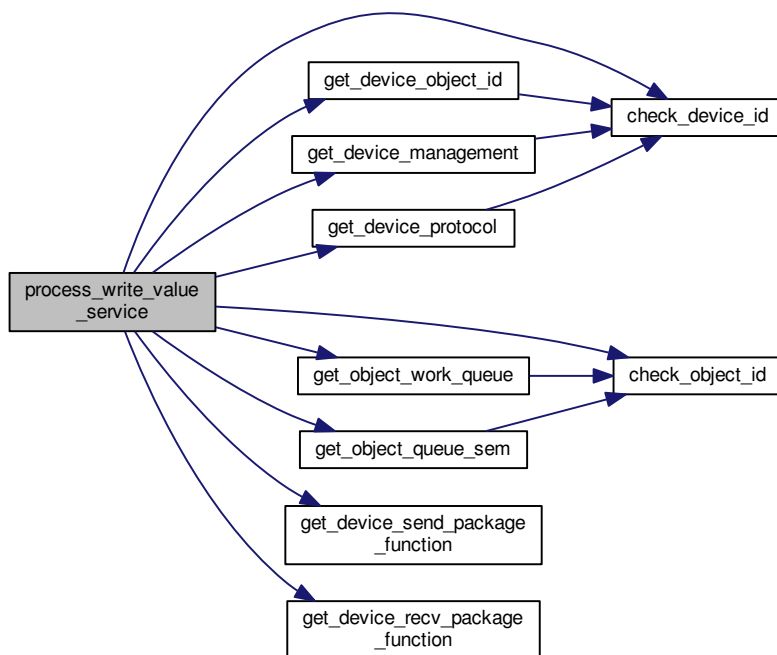
<i>in</i>	<i>adapter</i>	: The adapter struct information
-----------	----------------	----------------------------------

### Returns

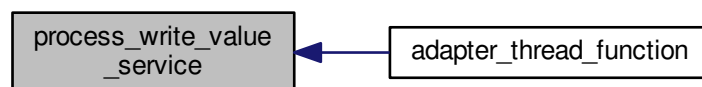
0 is success, and others is fail.

Definition at line 94 of file adapter.c.

Here is the call graph for this function:

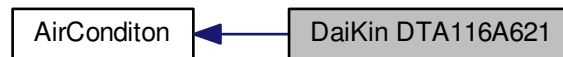


Here is the caller graph for this function:



## 5.11 DaiKin DTA116A621

Collaboration diagram for DaiKin DTA116A621:



### Functions

- int [daikin\\_dta116a621\\_set\\_temperature](#) (volatile void \*arg)  
*daikin\_dta116a621\_set\_temperature set daikin air conditon temperature send package to "modbus\_port\_handle\_t"*
- int [daikin\\_dta116a621\\_set\\_mode](#) (volatile void \*arg)  
*daikin\_dta116a621\_set\_mode set daikin air conditon mode send package to "modbus\_port\_handle\_t"*
- int [daikin\\_dta116a621\\_set\\_swing](#) (volatile void \*arg)  
*daikin\_dta116a621\_set\_swing set daikin air conditon swing send package to "modbus\_port\_handle\_t"*
- int [daikin\\_dta116a621\\_set\\_fan](#) (volatile void \*arg)  
*daikin\_dta116a621\_set\_fan set daikin air conditon fan send package to "modbus\_port\_handle\_t"*
- int [daikin\\_dta116a621\\_set\\_switch](#) (volatile void \*arg)  
*daikin\_dta116a621\_set\_switch set daikin air conditon switch send package to "modbus\_port\_handle\_t"*
- int [daikin\\_dta116a621\\_get\\_device\\_info\\_send](#) (volatile void \*arg)  
*daikin\_dta116a621\_get\_device\_info\_send set daikin air conditon device information send package to "modbus\_port\_handle\_t"*
- int [daikin\\_dta116a621\\_get\\_device\\_info\\_handle](#) (volatile void \*arg)  
*daikin\_dta116a621\_get\_device\_info\_handle process daikin air conditon get device information send package to "modbus\_port\_handle\_t"*

### 5.11.1 Detailed Description

Functions to DaiKin DTA116A621 interface.

### 5.11.2 Function Documentation

#### 5.11.2.1 int daikin\_dta116a621\_get\_device\_info\_handle ( volatile void \* arg )

`daikin_dta116a621_get_device_info_handle` process daikin air conditon get device information send package to "modbus\_port\_handle\_t"

#### Parameters

<code>in, out</code>	<code>arg</code>	: The struct ( <a href="#">modbus_port_handle_t</a> ) pointer
----------------------	------------------	---

#### Returns

0 is success, others is fail.

Definition at line 507 of file DTA116A621.c.

5.11.2.2 `int daikin_dta116a621_get_device_info_send ( volatile void * arg )`

`daikin_dta116a621_get_device_info_send` set daikin air conditon device information send package to "modbus\_↔  
`port_handle_t`"



**Parameters**

<i>in, out</i>	<i>arg</i>	: The struct ( <a href="#">modbus_port_handle_t</a> ) pointer
----------------	------------	---

**Returns**

Return the set device information send package length, if have a error , return a negative value.

Definition at line 495 of file DTA116A621.c.

**5.11.2.3 int daikin\_dta116a621\_set\_fan ( volatile void \* *arg* )**

daikin\_dta116a621\_set\_fan set daikin air conditon fan send package to "modbus\_port\_handle\_t"

**Parameters**

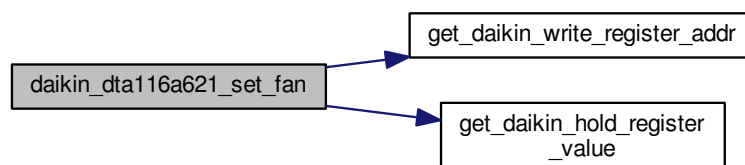
<i>in, out</i>	<i>arg</i>	: The struct ( <a href="#">modbus_port_handle_t</a> ) pointer
----------------	------------	---

**Returns**

Return the set fan send package length, if have a error , return a negative value.

Definition at line 428 of file DTA116A621.c.

Here is the call graph for this function:

**5.11.2.4 int daikin\_dta116a621\_set\_mode ( volatile void \* *arg* )**

daikin\_dta116a621\_set\_mode set daikin air conditon mode send package to "modbus\_port\_handle\_t"

**Parameters**

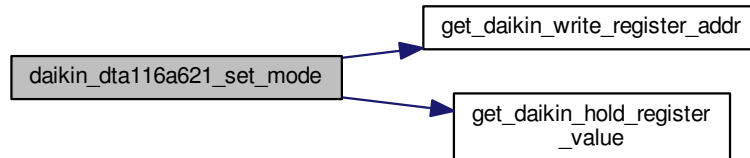
<i>in, out</i>	<i>arg</i>	: The struct ( <a href="#">modbus_port_handle_t</a> ) pointer
----------------	------------	---

**Returns**

Return the set mode send package length, if have a error , return a negative value.

Definition at line 362 of file DTA116A621.c.

Here is the call graph for this function:



#### 5.11.2.5 int daikin\_dta116a621\_set\_swing ( volatile void \* arg )

`daikin_dta116a621_set_swing` set daikin air conditon swing send package to "modbus\_port\_handle\_t"

**Parameters**

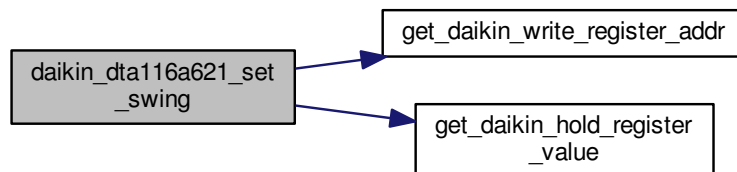
<i>in, out</i>	<i>arg</i>	: The struct ( <a href="#">modbus_port_handle_t</a> ) pointer
----------------	------------	---

**Returns**

Return the set swing send package length, if have a error , return a negative value.

Definition at line 395 of file DTA116A621.c.

Here is the call graph for this function:



#### 5.11.2.6 int daikin\_dta116a621\_set\_switch ( volatile void \* arg )

`daikin_dta116a621_set_switch` set daikin air conditon switch send package to "modbus\_port\_handle\_t"

**Parameters**

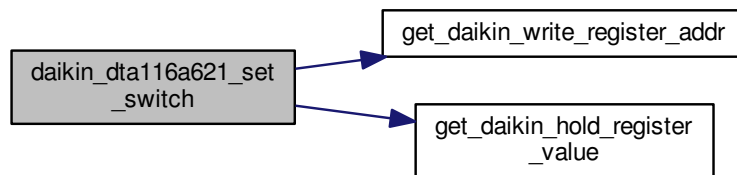
in, out	arg	: The struct ( <a href="#">modbus_port_handle_t</a> ) pointer
---------	-----	---

**Returns**

Return the set switch send package length, if have a error , return a negative value.

Definition at line 461 of file DTA116A621.c.

Here is the call graph for this function:

**5.11.2.7 int daikin\_dta116a621\_set\_temperature ( volatile void \* arg )**

`daikin_dta116a621_set_temperature` set daikin air condition temperature send package to "modbus\_port\_handle\_t"

**Parameters**

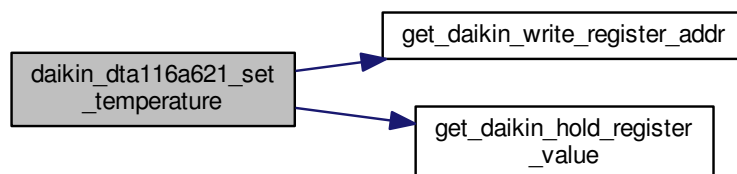
in, out	arg	: The struct ( <a href="#">modbus_port_handle_t</a> ) pointer
---------	-----	---

**Returns**

Return the set temperature send package length, if have a error ,return a negative value.

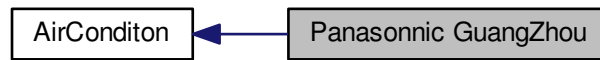
Definition at line 329 of file DTA116A621.c.

Here is the call graph for this function:



## 5.12 Panasonic GuangZhou

Collaboration diagram for Panasonic GuangZhou:



### Functions

- int [panasonic\\_send\\_package\\_handle](#) (volatile void \*arg)  
*panasonic\_send\_package\_handle* The panasonic package a send buffer interface.
- int [panasonic\\_rcv\\_package\\_handle](#) (volatile void \*arg)  
*panasonic\_send\_package\_handle* The panasonic package a receive buffer processs interface.

#### 5.12.1 Detailed Description

Functions to Panasonic air condition interface.

#### 5.12.2 Function Documentation

##### 5.12.2.1 int panasonic\_rcv\_package\_handle ( volatile void \* arg )

[panasonic\\_send\\_package\\_handle](#) The panasonic package a receive buffer processs interface.

##### Parameters

in	arg	: The struct "mstp_port_handle_t" defined by <a href="#">general.h</a>
----	-----	--

##### Returns

0 is success , others is fail.

Definition at line 1138 of file panasonic.c.

##### 5.12.2.2 int panasonic\_send\_package\_handle ( volatile void \* arg )

[panasonic\\_send\\_package\\_handle](#) The panasonic package a send buffer interface.

##### Parameters

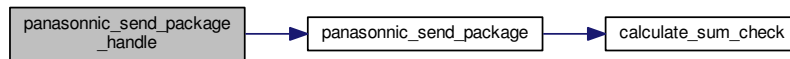
in, out	arg	: The struct "mstp_port_handle_t" defined by <a href="#">general.h</a>
---------	-----	--

**Returns**

Return The send package length, if have a error , return a negative value.

Definition at line 821 of file panasonic.c.

Here is the call graph for this function:



## 5.13 YORK GuangZhou KeLong

Collaboration diagram for YORK GuangZhou KeLong:



### Functions

- int [get\\_air\\_york\\_write\\_args](#) ([bacnet\\_write\\_args\\_t](#) \*args, unsigned int device\_id, int [command](#), int value)  
*get\_air\_york\_write\_args* The york air condition bacnet interface
- int [get\\_air\\_york\\_read\\_args](#) ([bacnet\\_read\\_args\\_t](#) \*args, unsigned int device\_id)  
*get\_air\_york\_read\_args* The york air confition bacnet read interface
- int [get\\_air\\_york\\_instance](#) (unsigned char mac)  
*get\_air\_york\_instance* get the youk bacnet instance.

#### 5.13.1 Detailed Description

Functions to york air condition interface.

#### 5.13.2 Function Documentation

##### 5.13.2.1 int [get\\_air\\_york\\_instance](#) ( unsigned char *mac* )

[get\\_air\\_york\\_instance](#) get the youk bacnet instance.

##### Parameters

in	<i>mac</i>	: The device MAC address
----	------------	--------------------------

##### Returns

return the instance, if return negative value is error

Definition at line 301 of file york.c.

Here is the caller graph for this function:



##### 5.13.2.2 int [get\\_air\\_york\\_read\\_args](#) ( [bacnet\\_read\\_args\\_t](#) \* *args*, unsigned int *device\_id* )

[get\\_air\\_york\\_read\\_args](#) The york air confition bacnet read interface

**Parameters**

in, out	<i>args</i>	: The bacnet read struct, so need to full it.
in	<i>device_id</i>	: The bacnet device id.

**Returns**

0 is success, and others is fail.

Definition at line 280 of file york.c.

Here is the caller graph for this function:



### 5.13.2.3 int get\_air\_york\_write\_args ( bacnet\_write\_args\_t \* args, unsigned int device\_id, int command, int value )

get\_air\_york\_write\_args The york air condition bacnet interface

**Parameters**

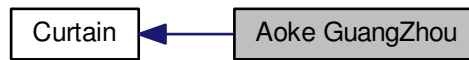
in, out	<i>args</i>	: The bacnet write struct, so need to full it.
in	<i>device_id</i>	: The bacnet device id.
in	<i>command</i>	: The device command, method too.
in	<i>value</i>	: The value mayto is unused.

**Returns**

0 is success, and others is fail.

## 5.14 AoKe GuangZhou

Collaboration diagram for AoKe GuangZhou:



### Functions

- int [aoke\\_send\\_package\\_handle](#) (volatile void \*arg)  
*aoke\_send\_package\_handle aoke curtian package a send buffer*
- int [aoke\\_rcv\\_package\\_handle](#) (volatile void \*arg)  
*aoke\_rcv\_package\_handle aoke curtain process the receive package*

#### 5.14.1 Detailed Description

Functions to aoke curtain interface.

#### 5.14.2 Function Documentation

##### 5.14.2.1 int aoke\_rcv\_package\_handle ( volatile void \* arg )

aoke\_rcv\_package\_handle aoke curtain process the receive package

##### Parameters

in	arg	: The struct "mstp_port_handle_t" pointer
----	-----	---

##### Returns

0 is success, others is fail.

Definition at line 438 of file aoke.c.

##### 5.14.2.2 int aoke\_send\_package\_handle ( volatile void \* arg )

aoke\_send\_package\_handle aoke curtian package a send buffer

##### Parameters

in, out	arg	: The struct "mstp_port_handle_t" pointer
---------	-----	---

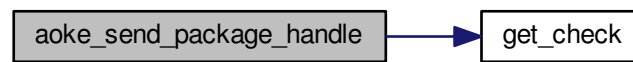


#### Returns

The send package length, if have a error return a negative value.

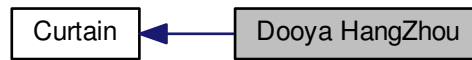
Definition at line 349 of file aoke.c.

Here is the call graph for this function:



## 5.15 Dooya HangZhou

Collaboration diagram for Dooya HangZhou:



### Functions

- int [doya\\_send\\_package\\_handle](#) (volatile void \*arg)  
*doya\_send\_package\_handle* The dooya curtain package a send buffer
- int [doya\\_rcv\\_package\\_handle](#) (volatile void \*arg)  
*doya\_rcv\_package\_handle* The dooya curtain process the receive data.

#### 5.15.1 Detailed Description

Functions to dooya curtain interface.

#### 5.15.2 Function Documentation

##### 5.15.2.1 int doya\_rcv\_package\_handle ( volatile void \* arg )

*doya\_rcv\_package\_handle* The dooya curtain process the receive data.

##### Parameters

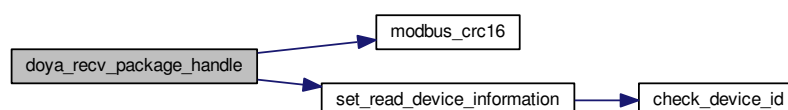
in	<i>arg</i>	: The struct "mstp_port_handle_t" pointer
----	------------	---

##### Returns

0 is success, others is fail.

Definition at line 886 of file doya.c.

Here is the call graph for this function:



5.15.2.2 `int doya_send_package_handle ( volatile void * arg )`

`doya_send_package_handle` The dooya curtain package a send buffer

**Parameters**

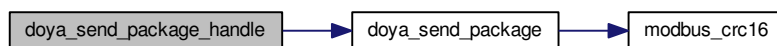
<code>in, out</code>	<code>arg</code>	: The struct "mstp_port_handle_t" pointer
----------------------	------------------	---

**Returns**

The send buffer package length, if have a error, return a negative value.

Definition at line 764 of file doya.c.

Here is the call graph for this function:



## 5.16 Loreley ShenZhen

Collaboration diagram for Loreley ShenZhen:



### Functions

- int [loreley\\_send\\_package\\_handle](#) (volatile void \*arg)  
*loreley\_send\_package\_handle loreley fresh air package send a buffer*
- int [loreley\\_rcv\\_package\\_handle](#) (volatile void \*arg)  
*loreley\_rcv\_package\_handle loreley fresh air process the receive data.*

#### 5.16.1 Detailed Description

Functions to loreley fresh air interface.

#### 5.16.2 Function Documentation

##### 5.16.2.1 int [loreley\\_rcv\\_package\\_handle](#) ( volatile void \* *arg* )

[loreley\\_rcv\\_package\\_handle](#) loreley fresh air process the receive data.

##### Parameters

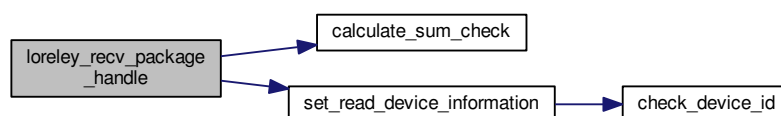
in	<i>arg</i>	: The struct "mstp_port_handle_t" pointer.
----	------------	--

##### Returns

0 is success, others is fail.

Definition at line 640 of file loreley.c.

Here is the call graph for this function:



5.16.2.2 `int loreley_send_package_handle ( volatile void * arg )`

loreley\_send\_package\_handle loreley fresh air package send a buffer

**Parameters**

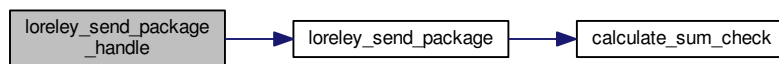
<code>in, out</code>	<code>arg</code>	: The struct "mstp_port_handle_t" pointer.
----------------------	------------------	--

**Returns**

The send buffer package length, if have a error ,return negative value.

Definition at line 532 of file loreley.c.

Here is the call graph for this function:



## 5.17 Device management

Collaboration diagram for Device management:



### Data Structures

- struct [device\\_management](#)  
*device define the device management struct*

### Typedefs

- typedef struct [device\\_management](#) [device\\_management\\_t](#)  
*device define the device management struct*

### Functions

- static int [find\\_available\\_device\\_id](#) (void)  
*find\_available\_device\_id find a available device ID*
- int [create\\_device](#) ([adapter\\_t](#) \*adapter)  
*create\_device create a rs485 device, mount the device to protocol*
- int [delete\\_device](#) (int object\_id, int device\_id)  
*delete\_device delete a device form device management table.*
- int [get\\_device\\_name](#) (char \*out, int out\_len, int device\_id)  
*get\_device\_name get a device name from device database.*
- int [get\\_device\\_type](#) (int device\_id)  
*get\_device\_type get a device type from device database, just like air condition, fresh air.....*
- int [get\\_device\\_protocol](#) (int device\_id)  
*get\_device\_protocol get a device protocol from device database, just like BACnet, MODUBS...*
- int [get\\_device\\_addr](#) (unsigned char \*addr, unsigned int addr\_len, int device\_id)  
*get\_device\_addr get a rs485 device addr, you maybe have no address for some device.*
- [timer\\_task\\_t](#) \* [get\\_device\\_timer](#) (int device\_id)  
*get\_device\_timer get a device timer task.*
- struct [device\\_profile](#) \* [get\\_device\\_private](#) (int device\_id)  
*get\_device\_private get a device private profile*
- int [get\\_device\\_private\\_numbers](#) (int device\_id)  
*get\_device\_private\_numbers*
- bool [check\\_device\\_id](#) (int device\_id)  
*check\_object\_id check the object is legal*
- int [get\\_device\\_object\\_id](#) (int device\_id)  
*get\_device\_object\_id get the object id by device id*
- int [get\\_device\\_factory\\_name](#) (int device\_id)



- get\_device\_factory\_name* Get the device factory name
- int [get\\_device\\_retransmission](#) (int device\_id)
  - get\_device\_retransmission* Get the device retransmission count on bus
- int [get\\_device\\_timeout\\_ms](#) (int device\_id)
  - get\_device\_timeout\_ms* Get The device timeout (ms), The bus have send a package have wait timeout count.
- int [get\\_device\\_address\\_len](#) (int device\_id)
  - get\_device\_address\_len* Get the device address length.
- [device\\_management\\_t](#) \* [get\\_device\\_management](#) (int device\_id)
  - get\_device\_management* get the device management pointer
- int [device\\_management\\_init](#) (void)
  - device\_management\_init* The device management modele have a initialize
- int [set\\_read\\_device\\_information](#) (const [read\\_device\\_return\\_t](#) \*info, int device\_id)
  - set\_read\_device\_information* bus have get a device information have wirte it.
- int [get\\_read\\_device\\_information](#) ([read\\_device\\_return\\_t](#) \*out, int device\_id)
  - get\_read\_device\_information* It's read a device information called by adapter layer.

### 5.17.1 Detailed Description

Functions to rs485 device create , delete , management.

### 5.17.2 Typedef Documentation

#### 5.17.2.1 typedef struct device\_management device\_management\_t

device define the device management struct

### 5.17.3 Function Documentation

#### 5.17.3.1 bool check\_device\_id ( int device\_id ) [inline]

[check\\_object\\_id](#) check the object is legal

##### Parameters

in	<i>device_id</i>	: The need to check device id.
----	------------------	--------------------------------

##### Returns

if object id is legal return true, and return false.

[check\\_object\\_id](#) check the object is legal

##### Parameters

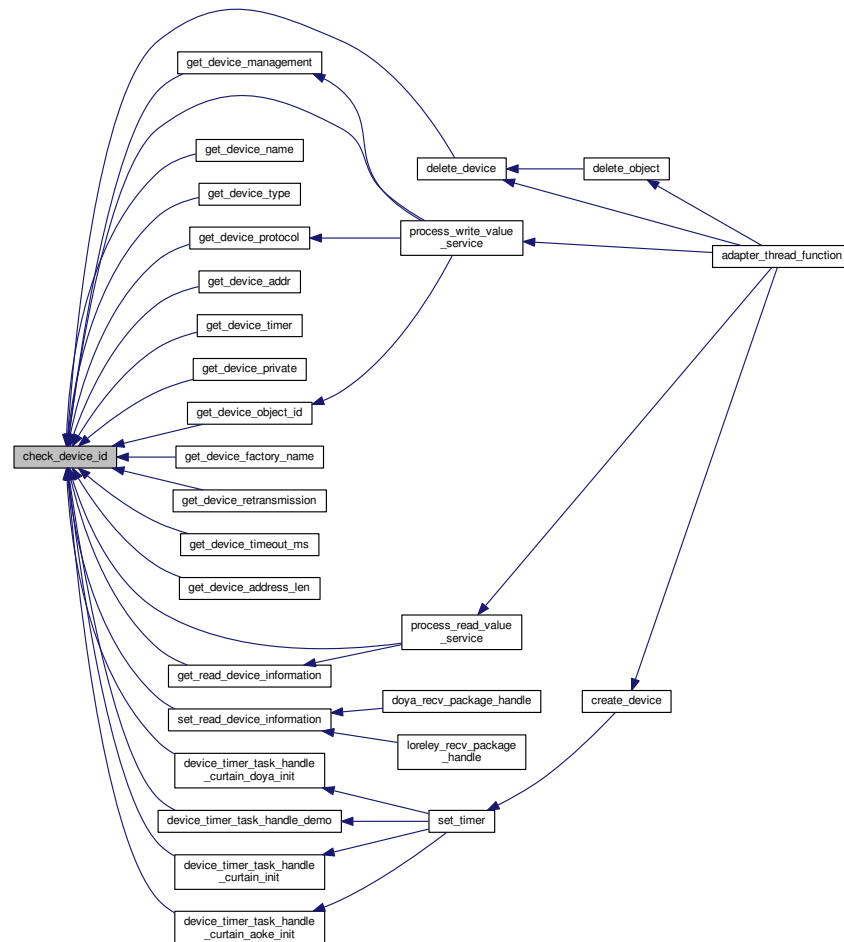
in	<i>device_id</i>	: The need to check device id.
----	------------------	--------------------------------

## Returns

if device id is legal return true, and return false.

Definition at line 117 of file device.c.

Here is the caller graph for this function:



### 5.17.3.2 int create\_device ( adapter\_t \* adapter )

create\_device create a rs485 device, mount the device to protocol

#### Parameters

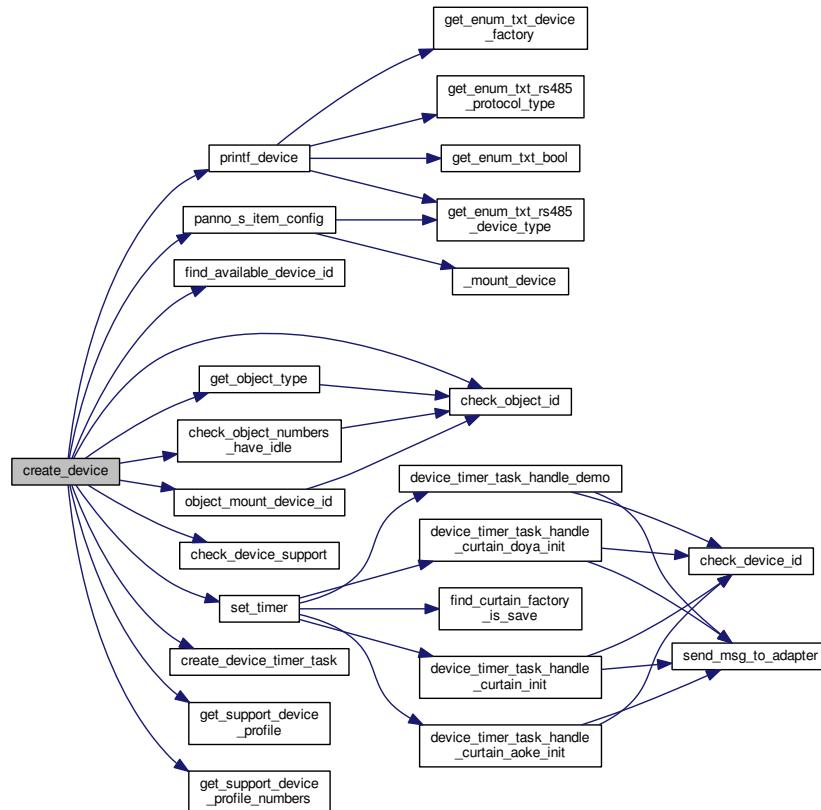
in	adapter	: The adapter message service type
----	---------	------------------------------------

## Returns

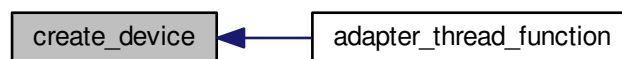
return the device id. if the device id have a negative value, you have create device fail.

Definition at line 214 of file device.c.

Here is the call graph for this function:



Here is the caller graph for this function:



### 5.17.3.3 int delete\_device ( int object\_id, int device\_id )

delete\_device delete a device form device management table.

**Parameters**

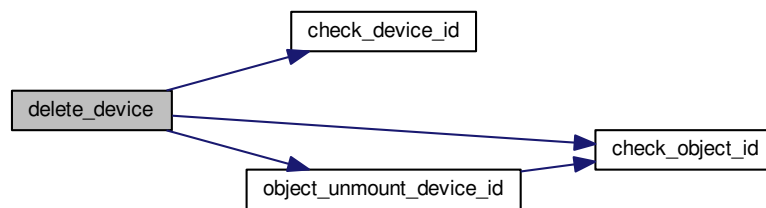
in	<i>device_id</i>	: The device id .
in	<i>object_id</i>	: The object id .

**Returns**

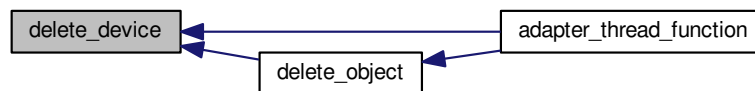
0 is success, others is fail.

Definition at line 380 of file device.c.

Here is the call graph for this function:



Here is the caller graph for this function:

**5.17.3.4 int device\_managemnt\_init ( void )**

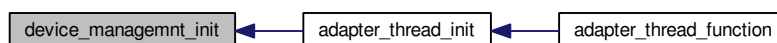
`device_managemnt_init` The device management modele have a initialize

**Returns**

0 is success, others is fail.

Definition at line 559 of file device.c.

Here is the caller graph for this function:



#### 5.17.3.5 static int find\_available\_device\_id ( void ) [inline],[static]

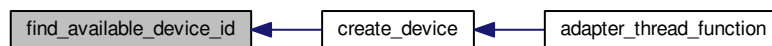
find\_available\_device\_id find a available device ID

##### Returns

return the device id, but The not positive value is a error.

Definition at line 88 of file device.c.

Here is the caller graph for this function:



#### 5.17.3.6 int get\_device\_addr ( unsigned char \* addr, unsigned int addr\_len, int device\_id ) [inline]

get\_device\_addr get a rs485 device addr, you maybe have no address for some device.

##### Parameters

in, out	<i>addr</i>	: The device address pointer
in	<i>addr_len</i>	: The device address buffer length.
in	<i>device_id</i>	: The device id.

##### Returns

0 is success, and others is fail.

Definition at line 447 of file device.c.

Here is the call graph for this function:



#### 5.17.3.7 int get\_device\_address\_len ( int device\_id ) [inline]

get\_device\_address\_len Get the device address length.

**Parameters**

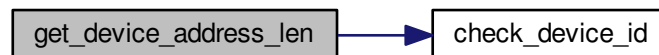
in	<i>device_id</i>	: The device id.
----	------------------	------------------

**Returns**

The device address len, if have a error return negative value.

Definition at line 536 of file device.c.

Here is the call graph for this function:

**5.17.3.8** `int get_device_factory_name ( int device_id ) [inline]`

get\_device\_factory\_name Get the device factory name

**Parameters**

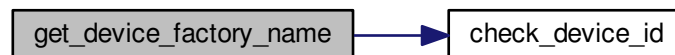
in	<i>device_id</i>	: The device id.
----	------------------	------------------

**Returns**

The device factory name numbers define by [enum.h](#)

Definition at line 503 of file device.c.

Here is the call graph for this function:

**5.17.3.9** `device_management_t* get_device_management ( int device_id )`

get\_device\_management get the device management pointer

## Parameters

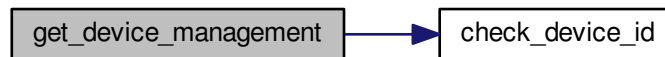
<i>device_id</i>	: The device id
------------------	-----------------

## Returns

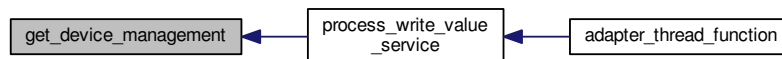
The device management pointer, if error, and return NULL.

Definition at line 547 of file device.c.

Here is the call graph for this function:



Here is the caller graph for this function:



### 5.17.3.10 `int get_device_name ( char * out, int out_len, int device_id ) [inline]`

`get_device_name` get a device name from device database.

## Parameters

<i>in, out</i>	<i>out</i>	: The device name have write it.
<i>in</i>	<i>out_len</i>	: The devide name buffer length.
<i>in</i>	<i>device_id</i>	: The device id.

## Returns

0 is success, and others is fail.

Definition at line 410 of file device.c.

Here is the call graph for this function:



#### 5.17.3.11 `int get_device_object_id ( int device_id ) [inline]`

`get_device_object_id` get the object id by device id

##### Parameters

<code>in</code>	<code><i>device_id</i></code>	: The device id.
-----------------	-------------------------------	------------------

##### Returns

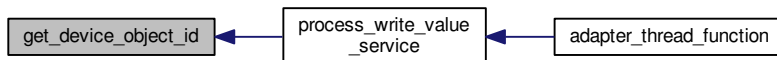
The object id, if have a error return negative value.

Definition at line 491 of file `device.c`.

Here is the call graph for this function:



Here is the caller graph for this function:



#### 5.17.3.12 `struct device_profile* get_device_private ( int device_id )`

`get_device_private` get a device private profile

##### Parameters

<code>in</code>	<code><i>device_id</i></code>	: The device id.
-----------------	-------------------------------	------------------



**Returns**

The private ppointer, if error ,and return NULL. FIXME: the private pointer is have memcpy a buffer, so, the struct have used?

Definition at line 475 of file device.c.

Here is the call graph for this function:



### 5.17.3.13 int get\_device\_private\_numbers ( int *device\_id* ) [inline]

get\_device\_private\_numbers

**Parameters**

in	<i>device_id</i>	: The device id
----	------------------	-----------------

**Returns**

The private profile numbers, if error, and return negative value.

Definition at line 486 of file device.c.

### 5.17.3.14 int get\_device\_protocol ( int *device\_id* ) [inline]

get\_device\_protocol get a device protocol from device database, just like BACnet, MODUBS...

**Parameters**

in	<i>device_id</i>	: The device id.
----	------------------	------------------

**Returns**

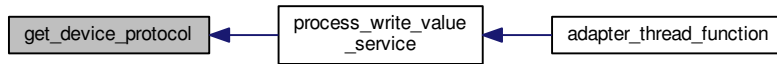
0 is success, and others is fail.

Definition at line 434 of file device.c.

Here is the call graph for this function:



Here is the caller graph for this function:



#### 5.17.3.15 `int get_device_retransmission ( int device_id ) [inline]`

`get_device_retransmission` Get the device retransmission count on bus

##### Parameters

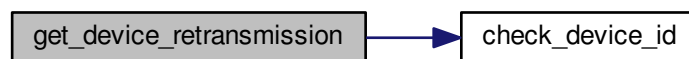
in	<i>device_id</i>	: The device id.
----	------------------	------------------

##### Returns

The device retransmission numbers, if have a error return negative value.

Definition at line 514 of file `device.c`.

Here is the call graph for this function:



#### 5.17.3.16 `int get_device_timeout_ms ( int device_id ) [inline]`

`get_device_timeout_ms` Get The device timeout (ms), The bus have send a package have wait timeout count.

##### Parameters

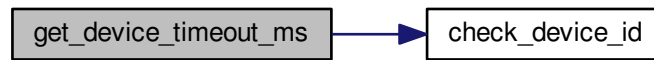
in	<i>device_id</i>	: The device id.
----	------------------	------------------

**Returns**

The device timeout, if have a error return negative value.

Definition at line 525 of file device.c.

Here is the call graph for this function:

**5.17.3.17 timer\_task\_t\* get\_device\_timer ( int device\_id ) [inline]**

get\_device\_timer get a device timer task.

**Parameters**

in	device_id	: The devcie id.
----	-----------	------------------

**Returns**

0 is success, and others is fail.

FIXME: the timer pointer is have memcpy a buffer, so, the struct have used?

Definition at line 463 of file device.c.

Here is the call graph for this function:

**5.17.3.18 int get\_device\_type ( int device\_id ) [inline]**

get\_device\_type get a device type from device database, just like air condition, fresh air....

**Parameters**

in	device_id	: The device id.
----	-----------	------------------

**Returns**

0 is success, and others is fail.

Definition at line 423 of file device.c.

Here is the call graph for this function:



#### 5.17.3.19 `int get_read_device_information ( read_device_return_t * out, int device_id )`

`get_read_device_information` It's read a device information called by adapter layer.

**Parameters**

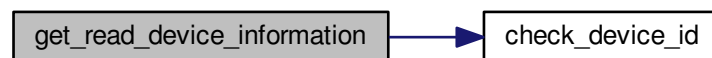
out	<i>out</i>	: The device private information
in	<i>device_id</i>	: The device id.

**Returns**

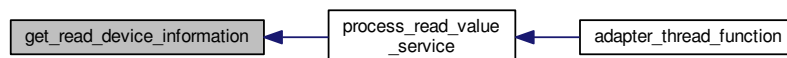
0 is success, others is fail.

Definition at line 586 of file device.c.

Here is the call graph for this function:



Here is the caller graph for this function:



5.17.3.20 int set\_read\_device\_information ( const read\_device\_return\_t \* *info*, int *device\_id* )

set\_read\_device\_information bus have get a device information have wirte it.

**Parameters**

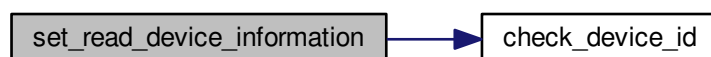
in	<i>info</i>	: The device private information
in	<i>device_id</i>	: The device id.

**Returns**

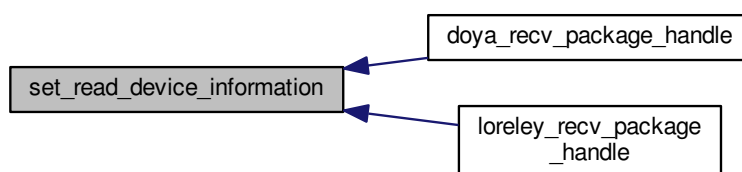
0 is success, others is fail.

Definition at line 571 of file device.c.

Here is the call graph for this function:



Here is the caller graph for this function:



## 5.18 String management

Collaboration diagram for String management:



### Functions

- char \* [get\\_enum\\_txt\\_service](#) (rs485\_service\_type\_enum type)  
*get\_enum\_txt\_service get enum rs485 service message type*
- char \* [get\\_enum\\_txt\\_rs485\\_device\\_type](#) (rs485\_device\_type\_enum type)  
*get\_enum\_txt\_rs485\_device\_type get enum rs485 device type*
- char \* [get\\_enum\\_txt\\_rs485\\_protocol\\_type](#) (rs485\_protocol\_type\_enum type)  
*get\_enum\_txt\_rs485\_protocol\_type get enum rs485 protocol type*
- char \* [get\\_enum\\_txt\\_device\\_method](#) (rs485\_device\_method\_enum type)  
*get\_enum\_txt\_device\_method get enum device method(command)*
- char \* [get\\_enum\\_txt\\_device\\_factory](#) (rs485\_factory\_name\_enum name)  
*get\_enum\_txt\_device\_factory get enum device factory name*
- char \* [get\\_enum\\_txt\\_bool](#) (bool status)  
*get\_enum\_txt\_bool get the string about bool value*

### 5.18.1 Detailed Description

Functions to rs485 service enum to string.

### 5.18.2 Function Documentation

#### 5.18.2.1 char\* get\_enum\_txt\_bool ( bool status )

get\_enum\_txt\_bool get the string about bool value

Parameters

in	status	: The bool status
----	--------	-------------------

**Returns**

a string about the true and false value.

Definition at line 235 of file enumtxt.c.

Here is the caller graph for this function:



### 5.18.2.2 `char* get_enum_txt_device_factory ( rs485_factory_name_enum name )`

`get_enum_txt_device_factory` get enum device factory name

**Parameters**

in	<i>name</i>	: The rs485 device factory name , define on <a href="#">enum.h</a>
----	-------------	--

**Returns**

a string about the device factory name

Definition at line 210 of file enumtxt.c.

Here is the caller graph for this function:



### 5.18.2.3 `char* get_enum_txt_device_method ( rs485_device_method_enum type )`

`get_enum_txt_device_method` get enum device method(command)

**Parameters**

in	<i>type</i>	: rs485 device method type , define on <a href="#">enum.h</a>
----	-------------	---

**Returns**

a string about the device command

Definition at line 95 of file enumtxt.c.

### 5.18.2.4 `char* get_enum_txt_rs485_device_type ( rs485_device_type_enum type )`

`get_enum_txt_rs485_device_type` get enum rs485 device type



## Parameters

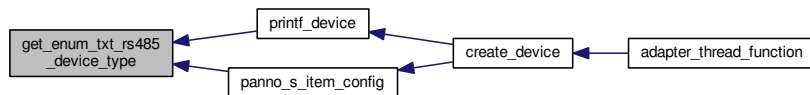
<i>in</i>	<i>type</i>	: rs485 device type, define on <a href="#">enum.h</a>
-----------	-------------	---

## Returns

a string about the device type

Definition at line 56 of file enumtxt.c.

Here is the caller graph for this function:



#### 5.18.2.5 `char* get_enum_txt_rs485_protocol_type ( rs485_protocol_type_enum type )`

`get_enum_txt_rs485_protocol_type` get enum rs485 protocol type

## Parameters

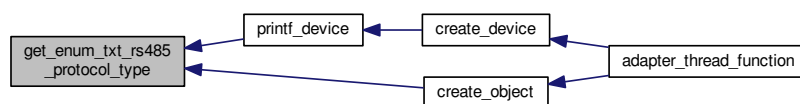
<i>in</i>	<i>type</i>	: rs485 protocol type, define on <a href="#">enum.h</a>
-----------	-------------	---

## Returns

a string about the rs485 protocol type

Definition at line 76 of file enumtxt.c.

Here is the caller graph for this function:



#### 5.18.2.6 `char* get_enum_txt_service ( rs485_service_type_enum type )`

`get_enum_txt_service` get enum rs485 service message type

## Parameters

<i>in</i>	<i>type</i>	: rs485 service type , define on <a href="#">enum.h</a>
-----------	-------------	---

## Returns

a string about the message

Definition at line 29 of file enumtxt.c.

## 5.19 Item management

Collaboration diagram for Item management:



### Macros

- #define [PANNO\\_S\\_ITEM\\_CONFIG](#)
- #define [PANNO\\_S\\_ITEM\\_DEFAULT](#) (1)
- #define [PANNO\\_S\\_ITEM\\_WENRUDE](#) (0)
- #define [PANNO\\_S\\_ITEM\\_ARMANI](#) (0)
- #define [PANNO\\_S\\_ITEM\\_SHAOCHENGGUOJI](#) (0)

### Functions

- void [panno\\_s\\_item\\_config](#) ([adapter\\_t](#) \*adapter, [rs485\\_device\\_type\\_enum](#) device\_type, unsigned char device\_addr)  
*panno\_s\_item\_config This function is offer the pannoS item config*

#### 5.19.1 Detailed Description

This module have offer the item configure.

Default config is : user defiend protocol,

The different item have a different device, so you need to configure it.

#### 5.19.2 Macro Definition Documentation

##### 5.19.2.1 #define PANNO\_S\_ITEM\_ARMANI (0)

The Chengdu armani item configure

Definition at line 72 of file item\_config.h.

##### 5.19.2.2 #define PANNO\_S\_ITEM\_CONFIG

The pannoS item define , if have no define it, This information have write by client.

Definition at line 42 of file item\_config.h.

## 5.19.2.3 #define PANNO\_S\_ITEM\_DEFAULT (1)

The pannoS default item configure

Definition at line 66 of file item\_config.h.

## 5.19.2.4 #define PANNO\_S\_ITEM\_SHAOCHENGGUOJI (0)

The Chengdu shaochengguoji item configure

Definition at line 75 of file item\_config.h.

## 5.19.2.5 #define PANNO\_S\_ITEM\_WENRUDE (0)

The Chengdu wenrude item configure

Definition at line 69 of file item\_config.h.

## 5.19.3 Function Documentation

## 5.19.3.1 void panno\_s\_item\_config ( adapter\_t \* adapter, rs485\_device\_type\_enum device\_type, unsigned char device\_addr )

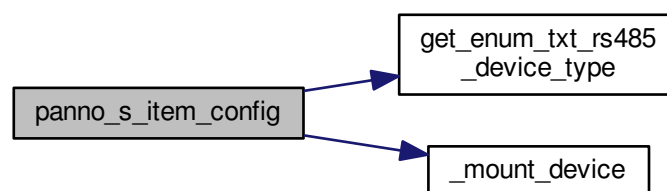
panno\_s\_item\_config This function is offer the pannoS item config

## Parameters

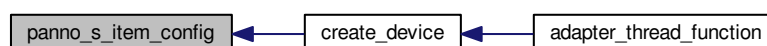
in, out	adapter	: The adapter struct, have write some device information in it.
in	device_type	: The device type, air condition/curtain/fresh air/...
in	device_addr	: The device addr, just for pannoS KNX 1 byte address.

Definition at line 157 of file item\_config.c.

Here is the call graph for this function:



Here is the caller graph for this function:



## 5.20 Object management

Collaboration diagram for Object management:



### Data Structures

- struct [object\\_management](#)  
*object\_management* define the object management struct

### Typedefs

- typedef struct [object\\_management](#) [object\\_management\\_t](#)  
*object\_management* define the object management struct

### Functions

- bool [check\\_object\\_id](#) (int object\_id)  
*check\_object\_id* check the object is legal
- static int [find\\_available\\_object\\_id](#) (void)  
*find\_available\_object\_id* Find a available object id from object table
- static bool [object\\_is\\_used](#) (const [adapter\\_t](#) \*adapter)  
*object\_is\_used* To determine whether the object id has been used
- static int [work\\_thread\\_create](#) ([object\\_management\\_t](#) \*object)  
*work\_thread\_create* create work thread
- static void [work\\_thread\\_clean](#) ([object\\_management\\_t](#) \*object)  
*work\_thread\_clean* clean the work thread
- int [create\\_object](#) (const [adapter\\_t](#) \*adapter)  
*create\_object* create a object by the adapter message
- int [delete\\_object](#) (int object\_id)  
*delete\_object* delete a rs485 object by object id
- int [get\\_object\\_type](#) (int object\_id)  
*get\_object\_type* get the object protocol type
- int [get\\_object\\_mount\\_device](#) (int object\_id, int \*out\_id, int out\_id\_len)  
*get\_object\_mount\_device* get the object mount device
- bool [check\\_object\\_numbers\\_have\\_idle](#) (int object\_id)  
*check\_object\_numbers\_have\_idle* check object mount device is full ?
- int [object\\_mount\\_device\\_id](#) (int object\_id, int device\_id)  
*object\_mount\_device\_id* add a device to his object
- void [object\\_unmount\\_device\\_id](#) (int object\_id, int device\_id)  
*object\_unmount\_device\_id* delete a device form his object
- void \* [get\\_object\\_work\\_queue](#) (int object\_id)

*get\_object\_work\_queue* get the object of work queue

- void \* [get\\_object\\_queue\\_sem](#) (int object\_id)

*get\_object\_queue\_sem* get the object of work queue semaphore

### 5.20.1 Detailed Description

Functions to rs485 Object create ,delete, management.

The object It's consist of the rs485 protocol .  
The Modbus is a object,  
The BACnet is a object,

every object have create a work thread to process the work.

### 5.20.2 Typedef Documentation

#### 5.20.2.1 typedef struct object\_management object\_management\_t

[object\\_management](#) define the object management struct

### 5.20.3 Function Documentation

#### 5.20.3.1 bool check\_object\_id ( int *object\_id* ) [inline]

check\_object\_id check the object is legal

Parameters

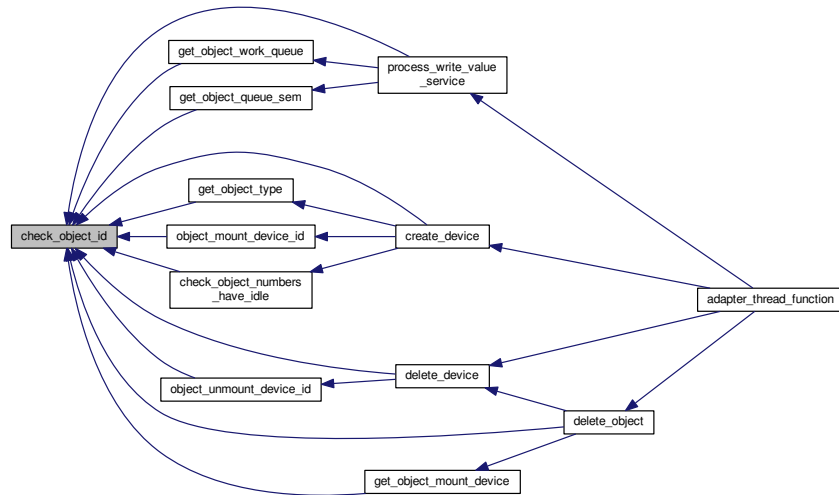
in	<i>object_id</i>	: The need to check object id.
----	------------------	--------------------------------

**Returns**

if object id is legal return true, and return false.

Definition at line 74 of file object.c.

Here is the caller graph for this function:



### 5.20.3.2 bool check\_object\_numbers\_have\_idle ( int *object\_id* )

check\_object\_numbers\_have\_idle check object mount device is full ?

**Parameters**

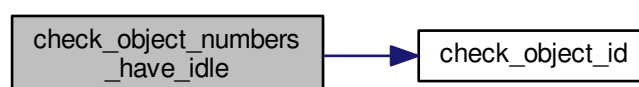
in	<i>object_id</i>	: The object id
----	------------------	-----------------

**Returns**

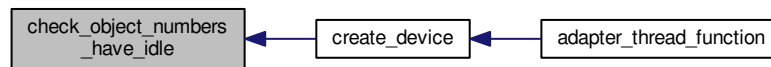
If the object have mount device have not full return true, or return false.

Definition at line 535 of file object.c.

Here is the call graph for this function:



Here is the caller graph for this function:



### 5.20.3.3 int create\_object ( const adapter\_t \* adapter )

`create_object` create a object by the adapter message

#### Parameters

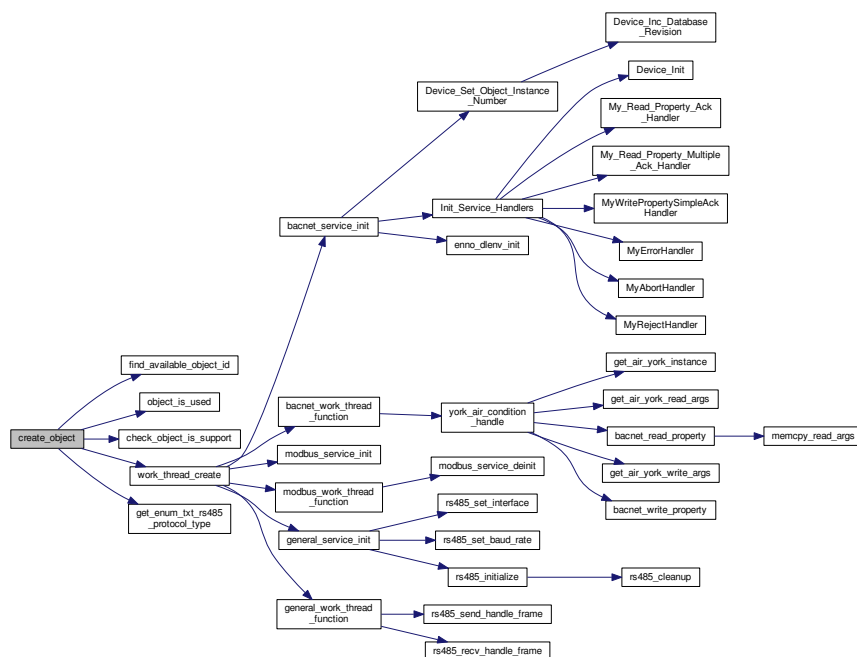
in	<i>adapter</i>	: The adapter message
----	----------------	-----------------------

#### Returns

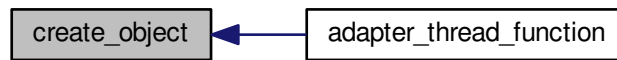
0 is success, others is fail.

Definition at line 326 of file object.c.

Here is the call graph for this function:



Here is the caller graph for this function:



#### 5.20.3.4 int delete\_object ( int *object\_id* )

`delete_object` delete a rs485 object by object id

##### Parameters

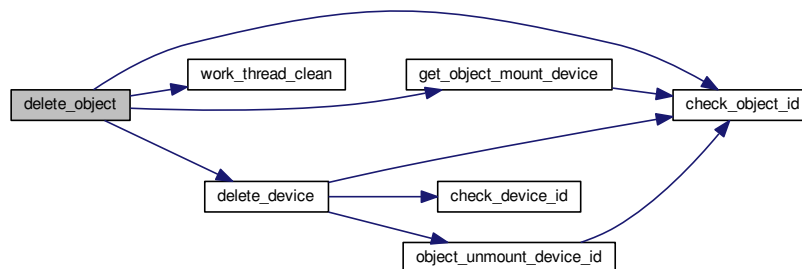
in	<i>object_id</i>	: The you want to delete object id.
----	------------------	-------------------------------------

##### Returns

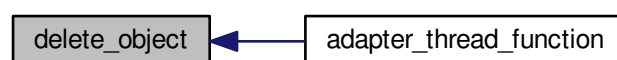
0 is success, others is fail.

Definition at line 421 of file `object.c`.

Here is the call graph for this function:



Here is the caller graph for this function:





### 5.20.3.5 static int find\_available\_object\_id ( void ) [inline],[static]

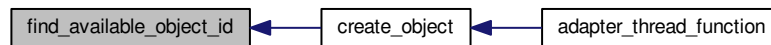
find\_available\_object\_id Find a available object id from object table

#### Returns

return the available object id, or return negative

Definition at line 96 of file object.c.

Here is the caller graph for this function:



### 5.20.3.6 int get\_object\_mount\_device ( int object\_id, int \* out\_id, int out\_id\_len )

get\_object\_mount\_device get the object mount device

#### Parameters

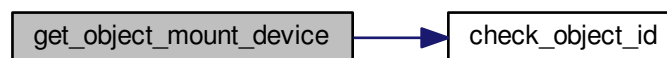
in	<i>object_id</i>	: The object id
out	<i>out_id</i>	: Out the device id on this object
in	<i>out_id_len</i>	: The out buffer length.

#### Returns

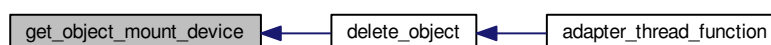
return the mount device numbers ,negative value is error

Definition at line 467 of file object.c.

Here is the call graph for this function:



Here is the caller graph for this function:



5.20.3.7 void\* get\_object\_queue\_sem ( int *object\_id* )

get\_object\_queue\_sem get the object of work queue semaphore

**Parameters**

in	<i>object_id</i>	: The object id
----	------------------	-----------------

**Returns**

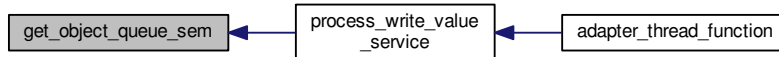
The object of work queue semaphore pointer, or return NULL.

Definition at line 564 of file object.c.

Here is the call graph for this function:



Here is the caller graph for this function:

**5.20.3.8 int get\_object\_type ( int *object\_id* )**

`get_object_type` get the object protocol type

**Parameters**

in	<i>object_id</i>	: The object id
----	------------------	-----------------

**Returns**

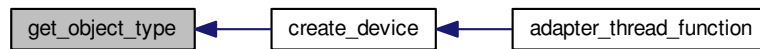
return the protocol type, return a negative value is error

Definition at line 455 of file object.c.

Here is the call graph for this function:



Here is the caller graph for this function:



#### 5.20.3.9 void\* get\_object\_work\_queue ( int *object\_id* )

`get_object_work_queue` get the object of work queue

##### Parameters

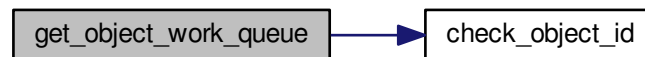
in	<i>object_id</i>	: The object id
----	------------------	-----------------

##### Returns

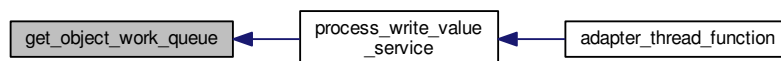
The object of work queue pointer, or return NULL.

Definition at line 554 of file `object.c`.

Here is the call graph for this function:



Here is the caller graph for this function:



#### 5.20.3.10 static bool object\_is\_used ( const adapter\_t\* *adapter* ) [inline],[static]

`object_is_used` To determine whether the object id has been used

## Parameters

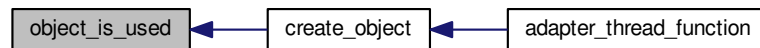
<i>adapter</i>	: The adapter struct.
----------------	-----------------------

## Returns

if have used return false, and return true;

Definition at line 127 of file object.c.

Here is the caller graph for this function:

5.20.3.11 `int object_mount_device_id ( int object_id, int device_id )`

`object_mount_device_id` add a device to his object

## Parameters

<i>in</i>	<i>object_id</i>	: The object id
<i>in</i>	<i>device_id</i>	: The device id

## Returns

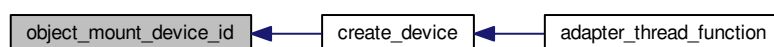
0 is success, others is fail.

Definition at line 493 of file object.c.

Here is the call graph for this function:



Here is the caller graph for this function:



5.20.3.12 void object\_unmount\_device\_id ( int *object\_id*, int *device\_id* )

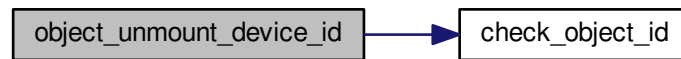
object\_unmount\_device\_id delete a device form his object

## Parameters

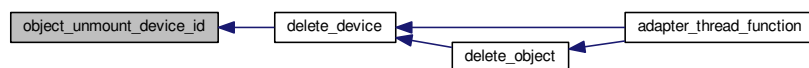
in	<i>object_id</i>	: The object id
in	<i>device_id</i>	: The device id

Definition at line 516 of file object.c.

Here is the call graph for this function:



Here is the caller graph for this function:



#### 5.20.3.13 static void work\_thread\_clean ( object\_management\_t \* object ) [static]

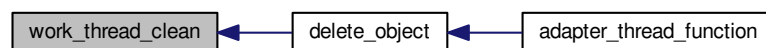
work\_thread\_clean clean the work thread

## Parameters

in	<i>object</i>	: The object device_management_t struct.
----	---------------	--

Definition at line 305 of file object.c.

Here is the caller graph for this function:



#### 5.20.3.14 static int work\_thread\_create ( object\_management\_t \* object ) [static]

work\_thread\_create create work thread

## Parameters

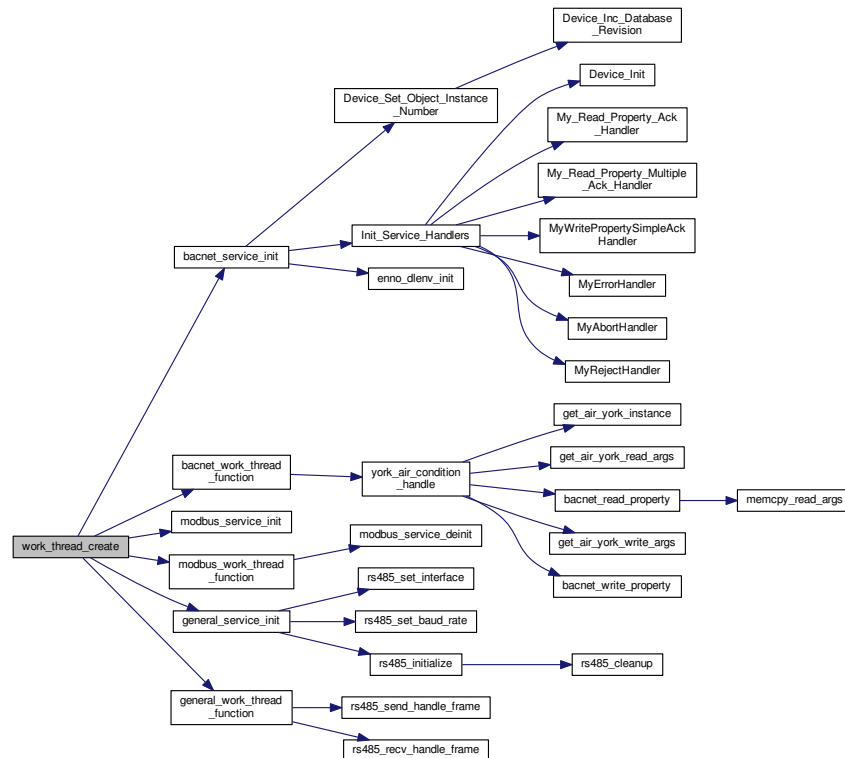
<code>in, out</code>	<code>object</code>	: The object struct information
----------------------	---------------------	---------------------------------

## Returns

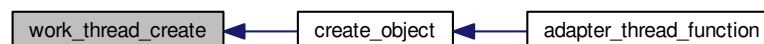
0 is create success, others is fail.

Definition at line 158 of file object.c.

Here is the call graph for this function:



Here is the caller graph for this function:





## 5.21 BACnet interface

Collaboration diagram for BACnet interface:



### Data Structures

- struct `bacnet`  
*bacnet bacnet interface struct*

### Typedefs

- typedef struct `bacnet bacnet_port_handle_t`  
*bacnet bacnet interface struct*

### Functions

- void \* `bacnet_work_thread_function` (void \*arg)  
*bacnet\_work\_thread\_function The bacnet work thread*

#### 5.21.1 Detailed Description

define the bacnet interface

#### 5.21.2 Typedef Documentation

##### 5.21.2.1 typedef struct `bacnet bacnet_port_handle_t`

bacnet bacnet interface struct

#### 5.21.3 Function Documentation

##### 5.21.3.1 void\* `bacnet_work_thread_function` ( void \* *arg* )

`bacnet_work_thread_function` The bacnet work thread

Parameters

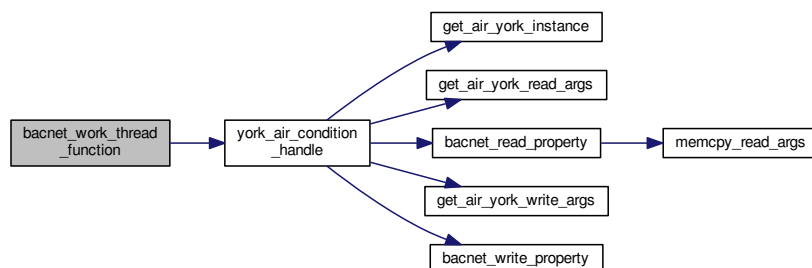
<i>in</i>	<i>arg</i>	: The object management pointer
-----------	------------	---------------------------------

### Returns

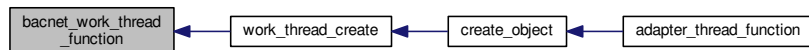
have no return.

Definition at line 107 of file bacnet.c.

Here is the call graph for this function:

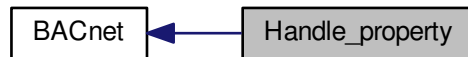


Here is the caller graph for this function:



## 5.22 Handle\_property

Collaboration diagram for Handle\_property:



### Data Structures

- struct [bacnet\\_write\\_args\\_t](#)  
*bacnet write arg struct*
- struct [bacnet\\_read\\_args\\_t](#)  
*bacnet read property struct*

### Macros

- `#define BACNET_READ_ARGS_OBJECT_MAX 10`

### Functions

- int [get\\_air\\_condition\\_bacnet\\_write\\_args](#) ([bacnet\\_write\\_args\\_t](#) \*args, unsigned int device\_id, int [command](#))  
*get\_air\_condition\_bacnet\_write\_args bacnet write args*
- int [get\\_air\\_condition\\_bacnet\\_read\\_args](#) ([bacnet\\_read\\_args\\_t](#) \*args, unsigned int device\_id)  
*get\_air\_condition\_bacnet\_read\_args bacnet read args*
- int [bacnet\\_service\\_init](#) ([object\\_management\\_t](#) \*adapter)  
*bacnet\_service\_init bacnet physics initialize.*

#### 5.22.1 Detailed Description

Function of BACnet handle property.

#### 5.22.2 Macro Definition Documentation

##### 5.22.2.1 `#define BACNET_READ_ARGS_OBJECT_MAX 10`

Definition at line 51 of file `handle_property.h`.

#### 5.22.3 Function Documentation

##### 5.22.3.1 `int bacnet_service_init ( object_management_t * adapter )`

`bacnet_service_init` bacnet physics initialize.

**Parameters**

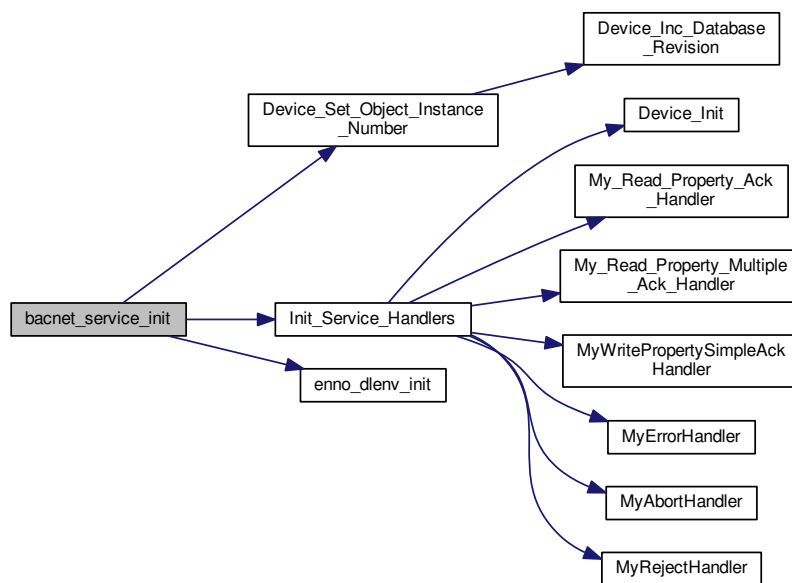
in	<i>adapter</i>	: bacnet work thread initial.
----	----------------	-------------------------------

**Returns**

0 is success, others is fail.

Definition at line 149 of file handle\_property.c.

Here is the call graph for this function:



Here is the caller graph for this function:



### 5.22.3.2 int get\_air\_condition\_bacnet\_read\_args ( bacnet\_read\_args\_t \* args, unsigned int device\_id )

get\_air\_condition\_bacnet\_read\_args bacnet read args

**Parameters**

in	<i>args</i>	: bacnet read args struct
in	<i>device_id</i>	: bacnet device id

**Returns**

0 is success, others is fail.

5.22.3.3 int get\_air\_condition\_bacnet\_write\_args ( bacnet\_write\_args\_t \* args, unsigned int device\_id, int command )

get\_air\_condition\_bacnet\_write\_args bacnet write args

**Parameters**

in	<i>args</i>	: bacnet write args struct
in	<i>device_id</i>	: bacnet device id
in	<i>command</i>	: bacnet air command

**Returns**

0 is success, others is fail.

## 5.23 General interface

Collaboration diagram for General interface:



### Data Structures

- struct [mstp\\_port\\_handle](#)  
*mstp\_port\_handle* general protocol(user defined)

### Typedefs

- typedef struct [mstp\\_port\\_handle](#) [mstp\\_port\\_handle\\_t](#)  
*mstp\_port\_handle* general protocol(user defined)

### Functions

- int [general\\_service\\_init](#) ([object\\_management\\_t](#) \*object)  
*general\_service\_init* The general protocol(user defined) initialize
- void \* [general\\_work\\_thread\\_function](#) (void \*arg)  
*general\_work\_thread\_function* The general work thread function

#### 5.23.1 Detailed Description

define the general interface interface

#### 5.23.2 Typedef Documentation

##### 5.23.2.1 typedef struct [mstp\\_port\\_handle](#) [mstp\\_port\\_handle\\_t](#)

[mstp\\_port\\_handle](#) general protocol(user defined)

#### 5.23.3 Function Documentation

##### 5.23.3.1 int [general\\_service\\_init](#) ( [object\\_management\\_t](#) \* *object* )

[general\\_service\\_init](#) The general protocol(user defined) initialize

**Parameters**

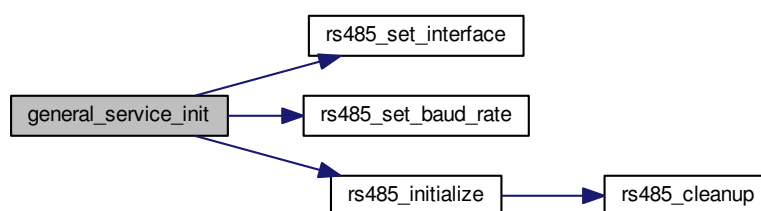
<i>in</i>	<i>object</i>	: The object information.
-----------	---------------	---------------------------

**Returns**

0 is success, others is fail.

Definition at line 46 of file general.c.

Here is the call graph for this function:



Here is the caller graph for this function:



### 5.23.3.2 void\* general\_work\_thread\_function ( void \* arg )

`general_work_thread_function` The general work thread function

**Parameters**

<i>in</i>	<i>arg</i>	: The thread argument , This arg uesd "The general object, mstp_port_↔ handle_t"
-----------	------------	--

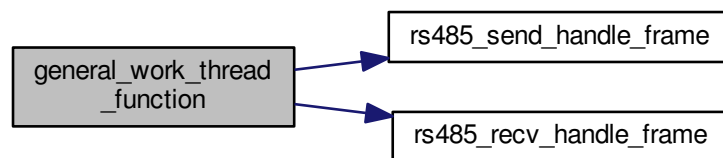


**Returns**

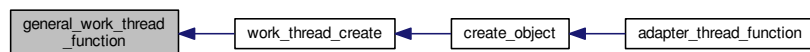
Thread have error have a return.

Definition at line 67 of file general.c.

Here is the call graph for this function:



Here is the caller graph for this function:



## 5.24 General RS485

Collaboration diagram for General RS485:



### Functions

- void [rs485\\_set\\_interface](#) (char \*ifname)  
*RS485\_Set\_Interface rs485 interface name.*
- const char \* [rs485\\_get\\_interface](#) (void)  
*RS485\_Get\_Interface get the rs485 interface name.*
- void [rs485\\_initialize](#) (void)  
*RS485\_Initialize.*
- int [rs485\\_send\\_handle\\_frame](#) (volatile struct [mstp\\_port\\_handle](#) \*mstp\_port)  
*rs485\_send\_handle\_frame rs485 bus package a send frame, and send the package to bus.*
- int [rs485\\_rcv\\_handle\\_frame](#) (volatile struct [mstp\\_port\\_handle](#) \*mstp\_port)  
*rs485\_rcv\_handle\_frame rs485 bus receive a frame, and call process these data.*
- bool [rs485\\_set\\_baud\\_rate](#) (uint32\_t baud)  
*RS485\_Set\_Baud\_Rate set the rs485 buad rate.*
- void [rs485\\_cleanup](#) (void)  
*RS485\_Cleanup The rs485 initaialize fail, have clean.*

### 5.24.1 Detailed Description

define the rs485 physics driver interface

### 5.24.2 Function Documentation

#### 5.24.2.1 void [rs485\\_cleanup](#) ( void )

[RS485\\_Cleanup](#) The rs485 initaialize fail, have clean.

Definition at line 401 of file [rs485.c](#).

Here is the caller graph for this function:



#### 5.24.2.2 `const char* rs485_get_interface ( void )`

RS485\_Get\_Interface get the rs485 interface name.

##### Returns

The rs485 interface name

#### 5.24.2.3 `void rs485_initialize ( void )`

RS485\_Initialize.

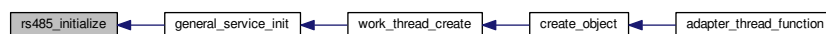
initiallize a rs485 interface

Definition at line 411 of file rs485.c.

Here is the call graph for this function:



Here is the caller graph for this function:



#### 5.24.2.4 `int rs485_rcv_handle_frame ( volatile struct mstp_port_handle * mstp_port )`

rs485\_rcv\_handle\_frame rs485 bus receive a frame, and call process these data.

##### Parameters

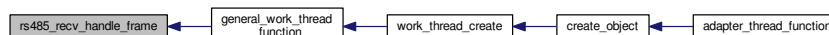
in	<i>mstp_port</i>	: The mstp_port struct, and consist of some frame infromation
----	------------------	---

##### Returns

0 is success, and others is fail.

Definition at line 331 of file rs485.c.

Here is the caller graph for this function:



5.24.2.5 `int rs485_send_handle_frame ( volatile struct mstp_port_handle * mstp_port )`

`rs485_send_handle_frame` rs485 bus package a send frame, and send the package to bus.

**Parameters**

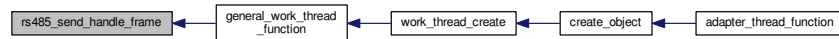
<i>in</i>	<i>mstp_port</i>	: The mstp_port struct, and consist of some send frame information
-----------	------------------	--

**Returns**

0 is success, and others is fail.

Definition at line 281 of file rs485.c.

Here is the caller graph for this function:

**5.24.2.6 bool rs485\_set\_baud\_rate ( uint32\_t baud )**

RS485\_Set\_Baud\_Rate set the rs485 buad rate.

**Parameters**

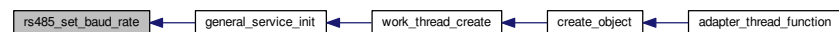
<i>in</i>	<i>baud</i>	: The rs485 UART buad, like "B9600" "B38400"
-----------	-------------	--

**Returns**

True is set ok, and others is set fail.

Definition at line 200 of file rs485.c.

Here is the caller graph for this function:

**5.24.2.7 void rs485\_set\_interface ( char \* ifname )**

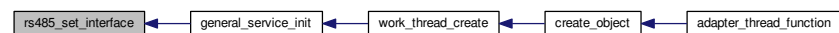
RS485\_Set\_Interface rs485 interface name.

**Parameters**

<i>in</i>	<i>ifname</i>	: The rs485 name , just like "rs4851"
-----------	---------------	---------------------------------------

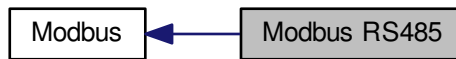
Definition at line 90 of file rs485.c.

Here is the caller graph for this function:



## 5.25 Modbus RS485

Collaboration diagram for Modbus RS485:



### Data Structures

- struct `modbus_port_handle_t`  
*The modbus port interface.*

### Functions

- void \* `modbus_work_thread_function` (void \*arg)  
*modbus\_work\_thread\_function The modbus work thread*
- int `modbus_service_init` (`object_management_t` \*object)  
*modbus\_service\_init The modbus interface initialize.*
- void `modbus_service_deinit` (`object_management_t` \*object)  
*modbus\_service\_deinit clean the modbus service, The haved called by thread have exit.*

#### 5.25.1 Detailed Description

define the modbus interface

#### 5.25.2 Function Documentation

##### 5.25.2.1 void modbus\_service\_deinit ( object\_management\_t \* object )

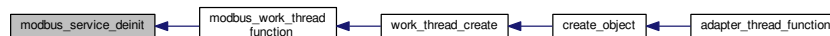
`modbus_service_deinit` clean the modbus service, The haved called by thread have exit.

Parameters

in	<i>object</i>	: The object information
----	---------------	--------------------------

Definition at line 292 of file `modbus.c`.

Here is the caller graph for this function:



5.25.2.2 `int modbus_service_init ( object_management_t * object )`

`modbus_service_init` The modbus interface initialize.

**Parameters**

<i>in</i>	<i>object</i>	: The object port information
-----------	---------------	-------------------------------

**Returns**

0 is success, others is fail.

Definition at line 254 of file modbus.c.

Here is the caller graph for this function:

**5.25.2.3 void\* modbus\_work\_thread\_function ( void \* arg )**

`modbus_work_thread_function` The modbus work thread

**Parameters**

<i>in</i>	<i>arg</i>	: The thread argument is object management pointer.
-----------	------------	---

**Returns**

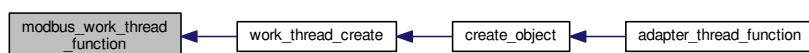
Have no return.

Definition at line 48 of file modbus.c.

Here is the call graph for this function:



Here is the caller graph for this function:





## 5.26 Service management

Collaboration diagram for Service management:



### Data Structures

- struct [thread\\_pool\\_t](#)  
*define the thread pool struct*

### Functions

- static int [rs485\\_thread\\_pool\\_create](#) ([thread\\_pool\\_t](#) \*pool, int numbers)  
*rs485\_thread\_pool\_create create linux thread pool*
- static void [rs485\\_thread\\_pool\\_clean](#) (void)  
*rs485\_thread\_pool\_clean clean the linux thread haved create*
- void [rs485\\_service\\_create\\_clean](#) (void)  
*rs485\_service\_create\_clean have clean the rs485 socket communicate*
- static int [rs485\\_service\\_running](#) (const char \*path)  
*rs485\_service\_running The rs485 service function, It's wait the client requests. It's block*
- static void [rs485\\_service\\_running\\_clean](#) (void)  
*rs485\_service\_running\_clean Have clean the service running*
- int [rs485\\_service\\_start](#) (void)  
*rs485\_service\_start The rs485 service start*
- int [rs485\\_send\\_msg\\_to\\_client](#) (int clifd, void \*buffer, int buffer\_len)  
*rs485\_send\_msg\_to\_client send The message to a client*
- int [rs485\\_rcv\\_msg\\_from\\_client](#) (int clifd, void \*buffer, int buffer\_len)  
*rs485\_rcv\_msg\_from\_client recieve a message from client*
- int [send\\_msg\\_to\\_adapter](#) (const [adapter\\_t](#) \*adapter)  
*send\_msg\_to\_adapter send a message to self,*

#### 5.26.1 Detailed Description

Functions to rs485 server have offer the service.

#### 5.26.2 Function Documentation

5.26.2.1 int [rs485\\_rcv\\_msg\\_from\\_client](#) ( int *clifd*, void \* *buffer*, int *buffer\_len* )

[rs485\\_rcv\\_msg\\_from\\_client](#) recieve a message from client

**Parameters**

in	<i>clifd</i>	: The client socket descriptor
out	<i>buffer</i>	: The buffer have receive data
in	<i>buffer_len</i>	: The receive buffer length

**Returns**

The receive data length, If have a error have return negative value.

#### 5.26.2.2 `int rs485_send_msg_to_client ( int clifd, void * buffer, int buffer_len )`

`rs485_send_msg_to_client` send The message to a client

**Parameters**

in	<i>clifd</i>	: The client socket descriptor
in	<i>buffer</i>	: The data buffer you want to send
in	<i>buffer_len</i>	: The data buffer length

**Returns**

The send buffer length, If have a error have return negative value.

Definition at line 246 of file `service.c`.

Here is the caller graph for this function:



#### 5.26.2.3 `void rs485_service_create_clean ( void )`

`rs485_service_create_clean` have clean the rs485 socket communicate

Definition at line 233 of file `service.c`.

#### 5.26.2.4 `static int rs485_service_running ( const char * path ) [static]`

`rs485_service_running` The rs485 service function, It's wait the client requests. It's block

**Parameters**

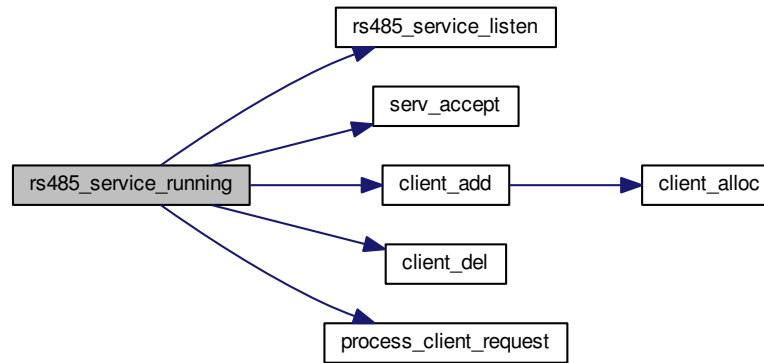
in	<i>path</i>	: The communicate unix path.
----	-------------	------------------------------

**Returns**

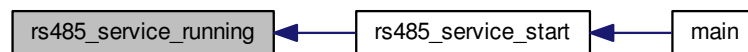
0 is success, and others is fail.

Definition at line 417 of file service.c.

Here is the call graph for this function:



Here is the caller graph for this function:

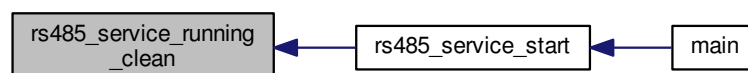


#### 5.26.2.5 static void rs485\_service\_running\_clean ( void ) [static]

`rs485_service_running_clean` Have clean the service running

Definition at line 511 of file service.c.

Here is the caller graph for this function:



### 5.26.2.6 `int rs485_service_start ( void )`

`rs485_service_start` The rs485 service start

#### Note

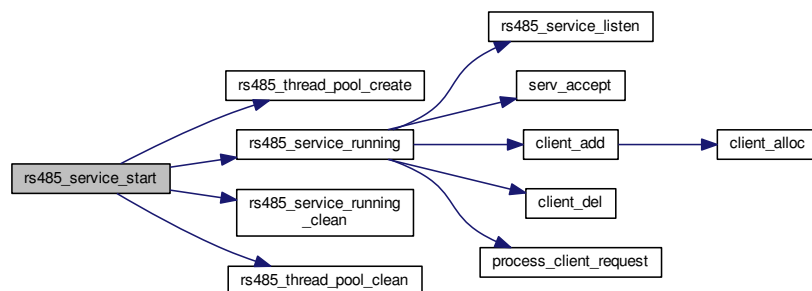
: It's should have not return, until have a error

#### Returns

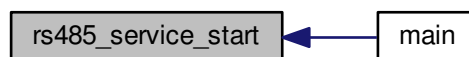
0 is success, and others is fail.

Definition at line 517 of file `service.c`.

Here is the call graph for this function:



Here is the caller graph for this function:

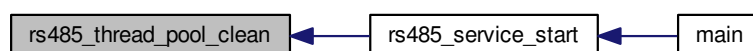


### 5.26.2.7 `static void rs485_thread_pool_clean ( void ) [static]`

`rs485_thread_pool_clean` clean the linux thread haved create

Definition at line 146 of file `service.c`.

Here is the caller graph for this function:



5.26.2.8 `static int rs485_thread_pool_create ( thread_pool_t * pool, int numbers ) [static]`

rs485\_thread\_pool\_create create linux thread pool

#### Parameters

<i>pool[]</i>	: The thread pool struct, just statement initialization
<i>numbers</i>	: The thread pool array numbers

#### Returns

0 is success, others is fail.

Definition at line 110 of file service.c.

Here is the caller graph for this function:



5.26.2.9 `int send_msg_to_adapter ( const adapter_t * adapter )`

send\_msg\_to\_adapter send a message to self,

#### Parameters

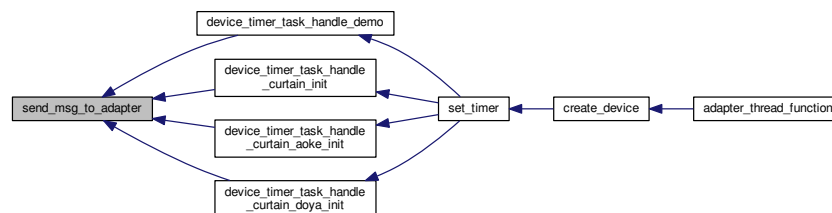
<i>in</i>	<i>adapter</i>	: The message struct
-----------	----------------	----------------------

#### Returns

0 is success, and others is fail.

Definition at line 276 of file service.c.

Here is the caller graph for this function:



## 5.27 Device register management

Collaboration diagram for Device register management:



### Data Structures

- struct [device\\_profile](#)  
*device\_profile device process method*

### Typedefs

- typedef int(\* [method\\_send](#))(volatile void \*context)  
*int you have full the context pointer.*
- typedef int(\* [method\\_rcv](#))(volatile void \*context)  
*int you have full the context pointer.*

### Functions

- bool [check\\_device\\_support](#) (const [adapter\\_t](#) \*adatper)  
*check\_device\_support check the device have supported by rs485 service*
- struct [device\\_profile](#) \* [get\\_support\\_device\\_profile](#) ([rs485\\_factory\\_name\\_enum](#) name)  
*get\_support\_device\_profile Get the device profile, The struct [device\\_profile](#)*
- int [get\\_support\\_device\\_profile\\_numbers](#) ([rs485\\_factory\\_name\\_enum](#) name)  
*get\_support\_device\_profile\_numbers Get the device profile have support how many command.*
- [method\\_send](#) [get\\_device\\_send\\_package\\_function](#) (const struct [device\\_profile](#) \*profile, int profile\_numbers, int command)  
*get\_device\_send\_package\_function Get the device profile send package callback function*
- [method\\_rcv](#) [get\\_device\\_rcv\\_package\\_function](#) (const struct [device\\_profile](#) \*profile, int profile\_numbers, int command)  
*get\_device\_rcv\_package\_function Get the device profile receive package callback function*

#### 5.27.1 Detailed Description

Functions to device register on rs485 service.

#### 5.27.2 Typedef Documentation

##### 5.27.2.1 typedef int(\* [method\\_rcv](#))(volatile void \*context)

int you have full the context pointer.

**Note**

```

if the interface is general, The context = mstp_port_handle_t* handle;
if the interface is bacnet, The context = bacnet_port_handle_t* handle;
if the interface is modbus, The context = modbus_port_handle_t* handle;

```

**Parameters**

<i>context, The</i>	*_port_handle_t pointer.
---------------------	--------------------------

**Returns**

The send byte numbers, or, return negative value

Definition at line 75 of file support.h.

**5.27.2.2 typedef int(\* method\_send)(volatile void \*context)**

int you have full the context pointer.

**Note**

```

if the interface is general, The context = mstp_port_handle_t* handle;
if the interface is bacnet, The context = bacnet_port_handle_t* handle;
if the interface is modbus, The context = modbus_port_handle_t* handle;

```

**Parameters**

<i>context, The</i>	*_port_handle_t pointer.
---------------------	--------------------------

**Returns**

The send byte numbers, or, return negative value

Definition at line 57 of file support.h.

**5.27.3 Function Documentation****5.27.3.1 bool check\_device\_support ( const adapter\_t \* adapter )**

check\_device\_support check the device have supported by rs485 service

**Parameters**

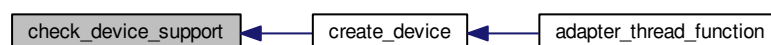
in	<i>adapter</i>	: The adapter struct, It's define by adapter.h
----	----------------	--

**Returns**

If the rs485 service have support this device return true, or return false.

Definition at line 150 of file support.c.

Here is the caller graph for this function:



**5.27.3.2 method\_rcv** `get_device_rcv_package_function ( const struct device_profile * profile, int profile_numbers, int command ) [inline]`

`get_device_rcv_package_function` Get the device profile receive package callback function

#### Parameters

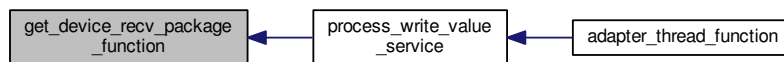
in	<i>profile</i>	: The device profile pointer.
in	<i>profile_numbers</i>	: The device profile have support command numbers.
in	<i>command</i>	: The which command you have chose.

#### Returns

return the device method rcv package callback function pointer, or return NULL.

Definition at line 221 of file support.c.

Here is the caller graph for this function:



**5.27.3.3 method\_send** `get_device_send_package_function ( const struct device_profile * profile, int profile_numbers, int command ) [inline]`

`get_device_send_package_function` Get the device profile send package callback function

#### Parameters

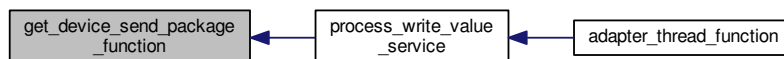
in	<i>profile</i>	: The device profile pointer.
in	<i>profile_numbers</i>	: The device profile have support command numbers.
in	<i>command</i>	: The which command you have chose.

#### Returns

return the device method send package callback function pointer, or return NULL.

Definition at line 205 of file support.c.

Here is the caller graph for this function:



**5.27.3.4 struct device\_profile\*** `get_support_device_profile ( rs485_factory_name_enum name )`

`get_support_device_profile` Get the device profile, The struct [device\\_profile](#)



## Parameters

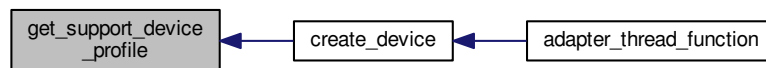
<i>in</i>	<i>name</i>	: The device factory name enum, It's define by <a href="#">enum.h</a>
-----------	-------------	---

## Returns

return The device profile pointer, or return NULL.

Definition at line 156 of file support.c.

Here is the caller graph for this function:



#### 5.27.3.5 int get\_support\_device\_profile\_numbers ( rs485\_factory\_name\_enum name )

`get_support_device_profile_numbers` Get the device profile have support how many command.

## Parameters

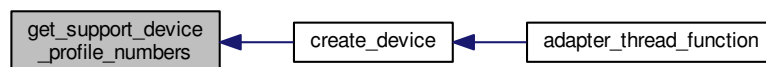
<i>in</i>	<i>name</i>	: The device factory name enum, It's define by <a href="#">enum.h</a>
-----------	-------------	---

## Returns

return the numbers about of device support command, or return negative value.

Definition at line 181 of file support.c.

Here is the caller graph for this function:



## 5.28 Timer management

Collaboration diagram for Timer management:



### Data Structures

- struct [timer\\_task\\_t](#)  
*timer task struct*

### Typedefs

- typedef int(\* [timer\\_proc\\_func](#))(int device\_id, int [command](#))

### Functions

- void \* [timer\\_task\\_thread\\_function](#) (void \*arg)  
*timer\_task\_thread\_function The timer task thread start function, just return when they have an error*
- int [create\\_device\\_timer\\_task](#) ([timer\\_task\\_t](#) \*task)  
*create\_device\_timer\_task create a device timer task, The timer task min tick is 10 second*
- int [delete\\_device\\_timer\\_task](#) ([timer\\_task\\_t](#) \*task)  
*delete\_device\_timer\_task delete a device timer task from the timer list.*
- int [device\\_timer\\_task\\_handle\\_demo](#) (int device\_id, int [command](#))  
*device\_timer\_task\_handle\_demo timer task handle function demo*

#### 5.28.1 Detailed Description

Functions to create or delete the timer task on timer task thread.

#### 5.28.2 Typedef Documentation

##### 5.28.2.1 typedef int(\* timer\_proc\_func)(int device\_id, int command)

Definition at line 32 of file timer\_task.h.

#### 5.28.3 Function Documentation

##### 5.28.3.1 int create\_device\_timer\_task ( timer\_task\_t \* task )

*create\_device\_timer\_task create a device timer task, The timer task min tick is 10 second*

**Parameters**

<i>in</i>	<i>task</i>	: The timer task sturct.
-----------	-------------	--------------------------

**Returns**

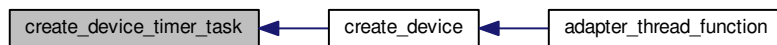
0 is success , others is fail.

**Note**

The task argument, have used by timer list, so The task struct you must malloc a buffer

Definition at line 153 of file timer\_task.c.

Here is the caller graph for this function:

**5.28.3.2 int delete\_device\_timer\_task ( timer\_task\_t \* task )**

`delete_device_timer_task` delete a device timer task from The timer list.

**Parameters**

<i>in</i>	<i>task</i>	: The timer task sturct, you have remote from the list.
-----------	-------------	---

**Returns**

0 is success, others is fail.

Definition at line 196 of file timer\_task.c.

**5.28.3.3 int device\_timer\_task\_handle\_demo ( int device\_id, int command )**

`device_timer_task_handle_demo` timer task handle fucntion demo

**Parameters**

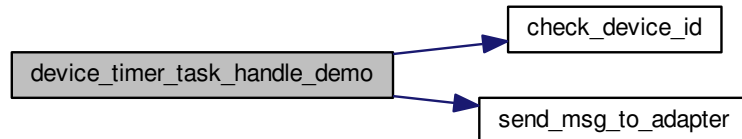
<i>in</i>	<i>device_id</i>	: The device Id.
<i>in</i>	<i>command</i>	: Get the device information command ,defined by <a href="#">enum.h</a>

**Returns**

0 is success, others is fail.

Definition at line 222 of file timer\_task.c.

Here is the call graph for this function:



Here is the caller graph for this function:



#### 5.28.3.4 void\* timer\_task\_thread\_function ( void \* arg )

`timer_task_thread_function` The timer task thread start function, just return when they have an error

**Parameters**

<i>in</i>	<i>arg</i>	: The thread argument, unused.
-----------	------------	--------------------------------

**Returns**

: The thread return value.

FIXME : The thread join status, have not set.

## Chapter 6

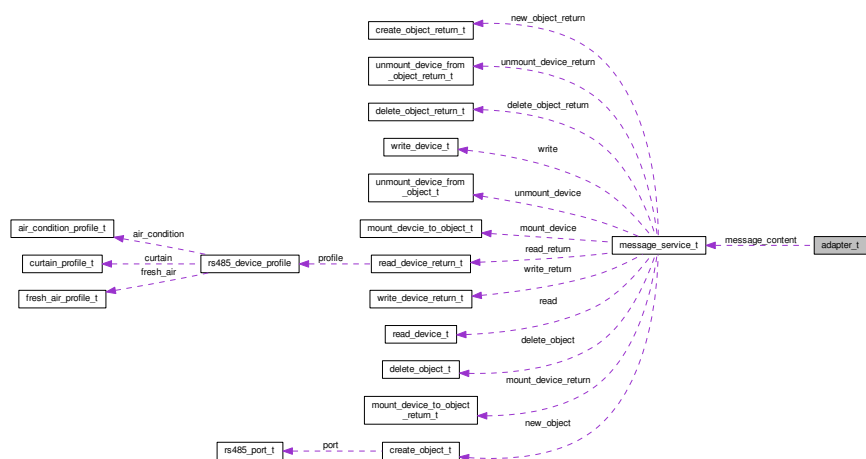
# Data Structure Documentation

### 6.1 adapter\_t Struct Reference

define the adapter struct

```
#include <adapter.h>
```

Collaboration diagram for adapter\_t:



### Data Fields

- [rs485\\_service\\_type\\_enum](#) `message_type`
- unsigned int [message\\_length](#)
- int [message\\_retval](#)
- int [socket\\_fd](#)
- [message\\_service\\_t](#) `message_content`

#### 6.1.1 Detailed Description

define the adapter struct

Definition at line 313 of file `adapter.h`.

## 6.1.2 Field Documentation

### 6.1.2.1 `message_service_t` `message_content`

The message content

Definition at line 324 of file `adapter.h`.

### 6.1.2.2 `unsigned int` `message_length`

The message length, just like "`sizeof(struct adapter_t)`", It's used to check the package imperfections

Definition at line 318 of file `adapter.h`.

### 6.1.2.3 `int` `message_retvl`

The message `retvl`, just message process `retvl`, the `retvl`, have used to client to check the service

Definition at line 320 of file `adapter.h`.

### 6.1.2.4 `rs485_service_type_enum` `message_type`

The message service type

Definition at line 316 of file `adapter.h`.

### 6.1.2.5 `int` `socket_fd`

The message socket id

Definition at line 322 of file `adapter.h`.

The documentation for this struct was generated from the following file:

- `include/adapter.h`

## 6.2 `air_condition_profile_t` Struct Reference

The air conditon profile.

```
#include <adapter.h>
```

### Data Fields

- `int` `room_temperature`
- `int` `outdoor_temperature`
- `int` `pipe_temperature`
- `int` `current_mode`
- `int` `current_swing`
- `int` `current_fan`
- `int` `current_set_temperature`

### 6.2.1 Detailed Description

The air conditon profile.

Definition at line 216 of file adapter.h.

### 6.2.2 Field Documentation

#### 6.2.2.1 int current\_fan

Definition at line 223 of file adapter.h.

#### 6.2.2.2 int current\_mode

Definition at line 221 of file adapter.h.

#### 6.2.2.3 int current\_set\_temperature

Definition at line 224 of file adapter.h.

#### 6.2.2.4 int current\_swing

Definition at line 222 of file adapter.h.

#### 6.2.2.5 int outdoor\_temperature

Definition at line 219 of file adapter.h.

#### 6.2.2.6 int pipe\_temperature

Definition at line 220 of file adapter.h.

#### 6.2.2.7 int room\_temperature

Definition at line 218 of file adapter.h.

The documentation for this struct was generated from the following file:

- [include/adapter.h](#)

## 6.3 bacnet Struct Reference

bacnet bacnet interface struct

```
#include <bacnet.h>
```

### Data Fields

- unsigned char [device\\_mac](#) [4]
- unsigned int [mac\\_length](#)
- [rs485\\_factory\\_name\\_enum](#) [factory\\_name](#)

- [rs485\\_device\\_type\\_enum device\\_type](#)
- unsigned int [command](#)
- int [value](#)
- int [value\\_reserve](#)
- void \* [arg](#)

### 6.3.1 Detailed Description

bacnet bacnet interface struct

Definition at line 41 of file bacnet.h.

### 6.3.2 Field Documentation

#### 6.3.2.1 void\* arg

Definition at line 50 of file bacnet.h.

#### 6.3.2.2 unsigned int command

Definition at line 47 of file bacnet.h.

#### 6.3.2.3 unsigned char device\_mac[4]

Definition at line 43 of file bacnet.h.

#### 6.3.2.4 rs485\_device\_type\_enum device\_type

Definition at line 46 of file bacnet.h.

#### 6.3.2.5 rs485\_factory\_name\_enum factory\_name

Definition at line 45 of file bacnet.h.

#### 6.3.2.6 unsigned int mac\_length

Definition at line 44 of file bacnet.h.

#### 6.3.2.7 int value

Definition at line 48 of file bacnet.h.

#### 6.3.2.8 int value\_reserve

Definition at line 49 of file bacnet.h.

The documentation for this struct was generated from the following file:

- include/protocol/bacnet/[bacnet.h](#)



## 6.4 bacnet\_read\_args\_t Struct Reference

bacnet read property struct

```
#include <handle_property.h>
```

### Data Fields

- unsigned int [device\\_id](#)
- int [object\\_numbers](#)
- int [object\\_type](#) [BACNET\_READ\_ARGS\_OBJECT\_MAX]
- int [object\\_instance](#) [BACNET\_READ\_ARGS\_OBJECT\_MAX]
- int [object\\_property](#) [BACNET\_READ\_ARGS\_OBJECT\_MAX]

### 6.4.1 Detailed Description

bacnet read property struct

Definition at line 57 of file [handle\\_property.h](#).

### 6.4.2 Field Documentation

#### 6.4.2.1 unsigned int [device\\_id](#)

device id, This device id is BACnet instance id

Definition at line 60 of file [handle\\_property.h](#).

#### 6.4.2.2 int [object\\_instance](#)[BACNET\_READ\_ARGS\_OBJECT\_MAX]

read object property instance

Definition at line 66 of file [handle\\_property.h](#).

#### 6.4.2.3 int [object\\_numbers](#)

read object property numbers

Definition at line 62 of file [handle\\_property.h](#).

#### 6.4.2.4 int [object\\_property](#)[BACNET\_READ\_ARGS\_OBJECT\_MAX]

read object property

Definition at line 68 of file [handle\\_property.h](#).

#### 6.4.2.5 int [object\\_type](#)[BACNET\_READ\_ARGS\_OBJECT\_MAX]

read object property type array

Definition at line 64 of file [handle\\_property.h](#).

The documentation for this struct was generated from the following file:

- [include/protocol/bacnet/handle\\_property.h](#)

## 6.5 bacnet\_write\_args\_t Struct Reference

bacnet write arg struct

```
#include <handle_property.h>
```

### Data Fields

- unsigned int [device\\_id](#)
- int [object\\_type](#)
- int [object\\_instance](#)
- int [object\\_property](#)
- int [object\\_property\\_priority](#)
- unsigned int [object\\_property\\_index](#)
- int [object\\_property\\_value\\_type](#)
- char [object\\_property\\_value](#) [32]

### 6.5.1 Detailed Description

bacnet write arg struct

Definition at line 30 of file [handle\\_property.h](#).

### 6.5.2 Field Documentation

#### 6.5.2.1 unsigned int device\_id

device id, This device id is BACnet instance id

Definition at line 33 of file [handle\\_property.h](#).

#### 6.5.2.2 int object\_instance

bacnet object instance

Definition at line 37 of file [handle\\_property.h](#).

#### 6.5.2.3 int object\_property

bacnet object property

Definition at line 39 of file [handle\\_property.h](#).

#### 6.5.2.4 unsigned int object\_property\_index

bacnet property index, have no index is -1

Definition at line 43 of file [handle\\_property.h](#).

#### 6.5.2.5 int object\_property\_priority

bacnet property priority default is 16

Definition at line 41 of file [handle\\_property.h](#).

#### 6.5.2.6 char object\_property\_value[32]

bacnet property value

Definition at line 47 of file handle\_property.h.

#### 6.5.2.7 int object\_property\_value\_type

bacnet property value type

Definition at line 45 of file handle\_property.h.

#### 6.5.2.8 int object\_type

bacnet object type

Definition at line 35 of file handle\_property.h.

The documentation for this struct was generated from the following file:

- include/protocol/bacnet/[handle\\_property.h](#)

## 6.6 client\_t Struct Reference

### Data Fields

- int [fd](#)
- uid\_t [uid](#)

### 6.6.1 Detailed Description

Definition at line 58 of file service.c.

### 6.6.2 Field Documentation

#### 6.6.2.1 int fd

Definition at line 60 of file service.c.

#### 6.6.2.2 uid\_t uid

Definition at line 61 of file service.c.

The documentation for this struct was generated from the following file:

- src/[service.c](#)

## 6.7 commonBacObj\_s Struct Reference

```
#include <device_client.h>
```

## Data Fields

- BACNET\_OBJECT\_TYPE [mObject\\_Type](#)
- uint32\_t [Object\\_Instance\\_Number](#)
- char [Object\\_Name](#) [MAX\_DEV\_NAME\_LEN]

### 6.7.1 Detailed Description

Structure to define the Object Properties common to all Objects.

Definition at line 177 of file device\_client.h.

### 6.7.2 Field Documentation

#### 6.7.2.1 BACNET\_OBJECT\_TYPE mObject\_Type

The BACnet type of this object (ie, what class is this object from?). This property, of type BACnetObjectType, indicates membership in a particular object type class. Each inherited class will be of one type.

Definition at line 183 of file device\_client.h.

#### 6.7.2.2 uint32\_t Object\_Instance\_Number

The instance number for this class instance.

Definition at line 186 of file device\_client.h.

#### 6.7.2.3 char Object\_Name[MAX\_DEV\_NAME\_LEN]

Object Name; must be unique. This property, of type CharacterString, shall represent a name for the object that is unique within the BACnet Device that maintains it.

Definition at line 192 of file device\_client.h.

The documentation for this struct was generated from the following file:

- include/protocol/bacnet/[device\\_client.h](#)

## 6.8 create\_object\_return\_t Struct Reference

message create a rs485 object return

```
#include <adapter.h>
```

## Data Fields

- int [object\\_id](#)

### 6.8.1 Detailed Description

message create a rs485 object return

Definition at line 74 of file adapter.h.

## 6.8.2 Field Documentation

### 6.8.2.1 int object\_id

The object ID, the id have created by server

Definition at line 77 of file adapter.h.

The documentation for this struct was generated from the following file:

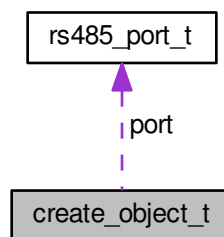
- include/adapter.h

## 6.9 create\_object\_t Struct Reference

message create a rs485 object

```
#include <adapter.h>
```

Collaboration diagram for create\_object\_t:



## Data Fields

- char [object\\_name](#) [36]
- [rs485\\_protocol\\_type\\_enum](#) object\_type
- int [mount\\_device\\_max](#)
- [rs485\\_port\\_t](#) port
- unsigned char [address](#) [4]
- int [address\\_len](#)

### 6.9.1 Detailed Description

message create a rs485 object

Definition at line 52 of file adapter.h.

## 6.9.2 Field Documentation

### 6.9.2.1 unsigned char address[4]

The rs485 address, just master device address

Definition at line 63 of file adapter.h.

#### 6.9.2.2 int address\_len

The address length

Definition at line 65 of file adapter.h.

#### 6.9.2.3 int mount\_device\_max

The rs485 object mount max device numbers

Definition at line 59 of file adapter.h.

#### 6.9.2.4 char object\_name[36]

The rs485 object name

Definition at line 55 of file adapter.h.

#### 6.9.2.5 rs485\_protocol\_type\_enum object\_type

The rs485 protocol type , every protocol type represent a object

Definition at line 57 of file adapter.h.

#### 6.9.2.6 rs485\_port\_t port

The rs485 port message

Definition at line 61 of file adapter.h.

The documentation for this struct was generated from the following file:

- include/[adapter.h](#)

## 6.10 curtain\_profile\_t Struct Reference

The curtain profile.

```
#include <adapter.h>
```

### Data Fields

- int [current\\_percent](#)

### 6.10.1 Detailed Description

The curtain profile.

Definition at line 232 of file adapter.h.

## 6.10.2 Field Documentation

### 6.10.2.1 int current\_percent

Definition at line 234 of file adapter.h.

The documentation for this struct was generated from the following file:

- include/[adapter.h](#)

## 6.11 delete\_object\_return\_t Struct Reference

message delete a rs485 object return

```
#include <adapter.h>
```

### Data Fields

- int [delete\\_status](#)

### 6.11.1 Detailed Description

message delete a rs485 object return

Definition at line 97 of file adapter.h.

## 6.11.2 Field Documentation

### 6.11.2.1 int delete\_status

Definition at line 99 of file adapter.h.

The documentation for this struct was generated from the following file:

- include/[adapter.h](#)

## 6.12 delete\_object\_t Struct Reference

message delete a rs485 object

```
#include <adapter.h>
```

### Data Fields

- int [object\\_id](#)

### 6.12.1 Detailed Description

message delete a rs485 object

Definition at line 86 of file adapter.h.

## 6.12.2 Field Documentation

### 6.12.2.1 int object\_id

The object id, your want to delete it.

Definition at line 89 of file adapter.h.

The documentation for this struct was generated from the following file:

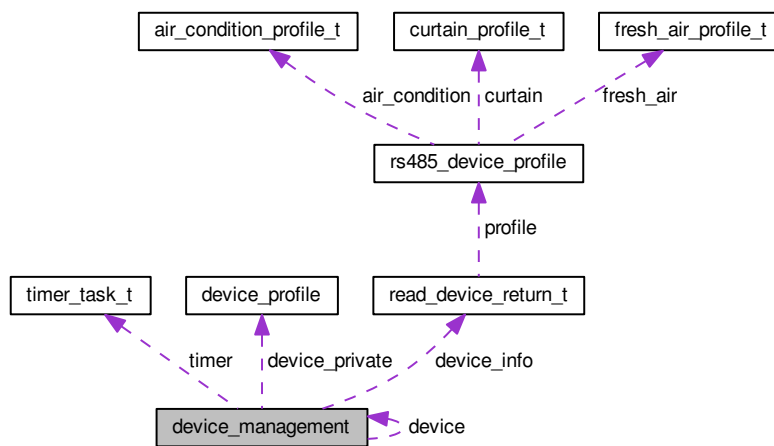
- include/adapter.h

## 6.13 device\_management Struct Reference

device define the device management struct

```
#include <device.h>
```

Collaboration diagram for device\_management:



## Data Fields

- struct [device\\_management](#) \* [device](#)
- char \* [device\\_name](#)
- [rs485\\_factory\\_name\\_enum](#) [factory\\_name](#)
- int [object\\_id](#)
- [rs485\\_protocol\\_type\\_enum](#) [object\\_type](#)
- int [device\\_id](#)
- [rs485\\_device\\_type\\_enum](#) [device\\_type](#)
- int [device\\_addr\\_len](#)
- unsigned char [device\\_addr](#) [4]
- unsigned int [time\\_out](#)
- unsigned int [device\\_status\\_period](#)
- unsigned int [retransmission](#)
- bool [support\\_reply](#)
- [read\\_device\\_return\\_t](#) \* [device\\_info](#)



- [timer\\_task\\_t](#) \* timer
- struct [device\\_profile](#) \* device\_private
- int [device\\_private\\_numbers](#)

### 6.13.1 Detailed Description

device define the device management struct

Definition at line 38 of file device.h.

### 6.13.2 Field Documentation

#### 6.13.2.1 struct device\_management\* device

The device pointer self

Definition at line 41 of file device.h.

#### 6.13.2.2 unsigned char device\_addr[4]

The device address, The used length is 4, just for struct have align

Definition at line 57 of file device.h.

#### 6.13.2.3 int device\_addr\_len

The device address len

Definition at line 55 of file device.h.

#### 6.13.2.4 int device\_id

The device id, It's a key

Definition at line 51 of file device.h.

#### 6.13.2.5 read\_device\_return\_t\* device\_info

The device information

Definition at line 67 of file device.h.

#### 6.13.2.6 char\* device\_name

The device name

Definition at line 43 of file device.h.

#### 6.13.2.7 struct device\_profile\* device\_private

The device have a private profile

Definition at line 71 of file device.h.

**6.13.2.8 int device\_private\_numbers**

The device private profile numbers

Definition at line 73 of file device.h.

**6.13.2.9 unsigned int device\_status\_period**

The rs485 device timer task cyc period

Definition at line 61 of file device.h.

**6.13.2.10 rs485\_device\_type\_enum device\_type**

The device type

Definition at line 53 of file device.h.

**6.13.2.11 rs485\_factory\_name\_enum factory\_name**

The device factory name

Definition at line 45 of file device.h.

**6.13.2.12 int object\_id**

The device belong to RS485 object

Definition at line 47 of file device.h.

**6.13.2.13 rs485\_protocol\_type\_enum object\_type**

The device protocol, It's define by [enum.h](#) too

Definition at line 49 of file device.h.

**6.13.2.14 unsigned int retransmission**

The rs485 device send to fail, and retransmission count

Definition at line 63 of file device.h.

**6.13.2.15 bool support\_reply**

The device have support reply

Definition at line 65 of file device.h.

**6.13.2.16 unsigned int time\_out**

The rs485 device have use the bus time, The max time is 1s

Definition at line 59 of file device.h.

#### 6.13.2.17 timer\_task\_t\* timer

The timer task, every device have create a timer task

Definition at line 69 of file device.h.

The documentation for this struct was generated from the following file:

- include/[device.h](#)

## 6.14 device\_profile Struct Reference

[device\\_profile](#) device process method

```
#include <support.h>
```

### Data Fields

- int [addr\\_real\\_len](#)
- int [method](#)
- [method\\_send](#) send
- [method\\_rcv](#) rcv

#### 6.14.1 Detailed Description

[device\\_profile](#) device process method

Definition at line 84 of file support.h.

#### 6.14.2 Field Documentation

##### 6.14.2.1 int addr\_real\_len

Definition at line 87 of file support.h.

##### 6.14.2.2 int method

Definition at line 89 of file support.h.

##### 6.14.2.3 method\_rcv rcv

Definition at line 93 of file support.h.

##### 6.14.2.4 method\_send send

Definition at line 91 of file support.h.

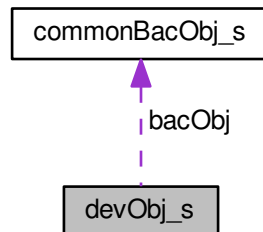
The documentation for this struct was generated from the following file:

- include/[support.h](#)

## 6.15 devObj\_s Struct Reference

```
#include <device_client.h>
```

Collaboration diagram for devObj\_s:



### Data Fields

- BACNET\_ADDRESS [bacDevAddr](#)
- COMMON\_BAC\_OBJECT [bacObj](#)
- char [Description](#) [[MAX\\_DEV\\_DESC\\_LEN](#)]
- uint32\_t [Database\\_Revision](#)

### 6.15.1 Detailed Description

Structure to define the Properties of Device Objects which distinguish one instance from another. This structure only defines fields for properties that are unique to a given Device object. The rest may be fixed in [device.c](#) or hard-coded into the read-property encoding. This may be useful for implementations which manage multiple Devices, eg, a Gateway.

Definition at line 205 of file [device\\_client.h](#).

### 6.15.2 Field Documentation

#### 6.15.2.1 BACNET\_ADDRESS [bacDevAddr](#)

The BACnet Device Address for this device; ->len depends on DLL type.

Definition at line 207 of file [device\\_client.h](#).

#### 6.15.2.2 COMMON\_BAC\_OBJECT [bacObj](#)

Structure for the Object Properties common to all Objects.

Definition at line 210 of file [device\\_client.h](#).

#### 6.15.2.3 uint32\_t [Database\\_Revision](#)

The upcounter that shows if the Device ID or object structure has changed.

Definition at line 216 of file [device\\_client.h](#).

#### 6.15.2.4 char Description[MAX\_DEV\_DESC\_LEN]

Device Description.

Definition at line 213 of file device\_client.h.

The documentation for this struct was generated from the following file:

- include/protocol/bacnet/[device\\_client.h](#)

## 6.16 fresh\_air\_profile\_t Struct Reference

The fresh profile.

```
#include <adapter.h>
```

### Data Fields

- int [room\\_temperature](#)
- int [room\\_humidity](#)
- int [pm2\\_5](#)
- int [fresh\\_level](#)

### 6.16.1 Detailed Description

The fresh profile.

Definition at line 243 of file adapter.h.

### 6.16.2 Field Documentation

#### 6.16.2.1 int fresh\_level

Definition at line 248 of file adapter.h.

#### 6.16.2.2 int pm2\_5

Definition at line 247 of file adapter.h.

#### 6.16.2.3 int room\_humidity

Definition at line 246 of file adapter.h.

#### 6.16.2.4 int room\_temperature

Definition at line 245 of file adapter.h.

The documentation for this struct was generated from the following file:

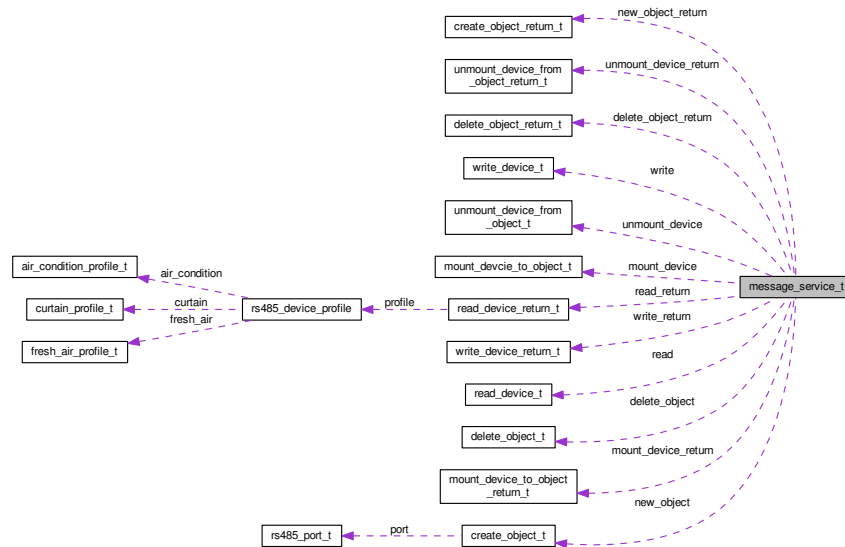
- include/[adapter.h](#)

## 6.17 message\_service\_t Union Reference

define the receive the message type

```
#include <adapter.h>
```

Collaboration diagram for message\_service\_t:



### Data Fields

- [create\\_object\\_t](#) new\_object
- [delete\\_object\\_t](#) delete\_object
- [mount\\_device\\_to\\_object\\_t](#) mount\_device
- [unmount\\_device\\_from\\_object\\_t](#) unmount\_device
- [write\\_device\\_t](#) write
- [read\\_device\\_t](#) read
- [create\\_object\\_return\\_t](#) new\_object\_return
- [delete\\_object\\_return\\_t](#) delete\_object\_return
- [mount\\_device\\_to\\_object\\_return\\_t](#) mount\_device\_return
- [unmount\\_device\\_from\\_object\\_return\\_t](#) unmount\_device\_return
- [write\\_device\\_return\\_t](#) write\_return
- [read\\_device\\_return\\_t](#) read\_return

### 6.17.1 Detailed Description

define the receive the message type

Definition at line 289 of file adapter.h.

### 6.17.2 Field Documentation

#### 6.17.2.1 delete\_object\_t delete\_object

Definition at line 293 of file adapter.h.

**6.17.2.2 delete\_object\_return\_t delete\_object\_return**

Definition at line 301 of file adapter.h.

**6.17.2.3 mount\_devcie\_to\_object\_t mount\_device**

Definition at line 294 of file adapter.h.

**6.17.2.4 mount\_device\_to\_object\_return\_t mount\_device\_return**

Definition at line 302 of file adapter.h.

**6.17.2.5 create\_object\_t new\_object**

Definition at line 292 of file adapter.h.

**6.17.2.6 create\_object\_return\_t new\_object\_return**

Definition at line 300 of file adapter.h.

**6.17.2.7 read\_device\_t read**

Definition at line 297 of file adapter.h.

**6.17.2.8 read\_device\_return\_t read\_return**

Definition at line 305 of file adapter.h.

**6.17.2.9 unmount\_device\_from\_object\_t unmount\_device**

Definition at line 295 of file adapter.h.

**6.17.2.10 unmount\_device\_from\_object\_return\_t unmount\_device\_return**

Definition at line 303 of file adapter.h.

**6.17.2.11 write\_device\_t write**

Definition at line 296 of file adapter.h.

**6.17.2.12 write\_device\_return\_t write\_return**

Definition at line 304 of file adapter.h.

The documentation for this union was generated from the following file:

- [include/adapter.h](#)

## 6.18 modbus\_port\_handle\_t Struct Reference

The modbus port interface.

```
#include <modbus.h>
```

### Data Fields

- int [device\\_id](#)
- bool [broadcast](#)
- unsigned int [retransmission](#)
- [modbus\\_function\\_code\\_enum](#) code
- int [method](#)
- int [value](#)
- unsigned char \* [buffer](#)
- unsigned int [buffer\\_len](#)
- unsigned int [device\\_addr](#)
- unsigned int [register\\_addr](#)
- [method\\_send](#) send\_handle
- [method\\_rcv](#) rcv\_handle

### 6.18.1 Detailed Description

The modbus port interface.

Definition at line 45 of file modbus.h.

### 6.18.2 Field Documentation

#### 6.18.2.1 bool broadcast

The message data is brodadcas ?

Definition at line 50 of file modbus.h.

#### 6.18.2.2 unsigned char\* buffer

temp save the data

Definition at line 60 of file modbus.h.

#### 6.18.2.3 unsigned int buffer\_len

The buffer length

Definition at line 62 of file modbus.h.

#### 6.18.2.4 modbus\_function\_code\_enum code

The modbus function code, define by [enum.h](#)

Definition at line 54 of file modbus.h.



#### 6.18.2.5 unsigned int device\_addr

The device address

Definition at line 64 of file modbus.h.

#### 6.18.2.6 int device\_id

device id

Definition at line 48 of file modbus.h.

#### 6.18.2.7 int method

The device method,(command) define by [enum.h](#)

Definition at line 56 of file modbus.h.

#### 6.18.2.8 method\_recv recv\_handle

The receive package callback function

Definition at line 70 of file modbus.h.

#### 6.18.2.9 unsigned int register\_addr

The you need to operator device register address

Definition at line 66 of file modbus.h.

#### 6.18.2.10 unsigned int retransmission

The device have send fail. retransmission count

Definition at line 52 of file modbus.h.

#### 6.18.2.11 method\_send send\_handle

The send package callback function

Definition at line 68 of file modbus.h.

#### 6.18.2.12 int value

The method have a value.

Definition at line 58 of file modbus.h.

The documentation for this struct was generated from the following file:

- include/protocol/modbus/[modbus.h](#)

## 6.19 mount\_devcie\_to\_object\_t Struct Reference

message mount a device to rs485 object

```
#include <adapter.h>
```

## Data Fields

- char [device\\_name](#) [36]
- [rs485\\_factory\\_name\\_enum](#) [factory\\_name](#)
- int [object\\_id](#)
- [rs485\\_protocol\\_type\\_enum](#) [object\\_type](#)
- char [device\\_addr](#) [4]
- unsigned int [device\\_addr\\_len](#)
- [rs485\\_device\\_type\\_enum](#) [device\\_type](#)
- unsigned int [time\\_out](#)
- unsigned int [support\\_reply](#)
- unsigned int [device\\_status\\_period](#)
- unsigned int [retransmission](#)

### 6.19.1 Detailed Description

message mount a device to rs485 object

Definition at line 107 of file [adapter.h](#).

### 6.19.2 Field Documentation

#### 6.19.2.1 char [device\\_addr](#)[4]

The rs485 device address, and the address maybe to NULL

Definition at line 118 of file [adapter.h](#).

#### 6.19.2.2 unsigned int [device\\_addr\\_len](#)

The rs485 device address length

Definition at line 120 of file [adapter.h](#).

#### 6.19.2.3 char [device\\_name](#)[36]

The device name

Definition at line 110 of file [adapter.h](#).

#### 6.19.2.4 unsigned int [device\\_status\\_period](#)

The rs485 device timer task cyc period

Definition at line 128 of file [adapter.h](#).

#### 6.19.2.5 [rs485\\_device\\_type\\_enum](#) [device\\_type](#)

The rs485 device type, reference [enum.h](#)

Definition at line 122 of file [adapter.h](#).

#### 6.19.2.6 [rs485\\_factory\\_name\\_enum](#) [factory\\_name](#)

The device factory

Definition at line 112 of file [adapter.h](#).

#### 6.19.2.7 int object\_id

The device mount the which object,so ,you must have crate a object frist  
Definition at line 114 of file adapter.h.

#### 6.19.2.8 rs485\_protocol\_type\_enum object\_type

The rs485 protocol type, The object type, we need to check it  
Definition at line 116 of file adapter.h.

#### 6.19.2.9 unsigned int retransmission

The rs485 device send to fail, and retransmission count  
Definition at line 130 of file adapter.h.

#### 6.19.2.10 unsigned int support\_reply

The rs485 device have wiat the device reply  
Definition at line 126 of file adapter.h.

#### 6.19.2.11 unsigned int time\_out

The rs485 device have use the bus time, The max time is 1s  
Definition at line 124 of file adapter.h.

The documentation for this struct was generated from the following file:

- include/[adapter.h](#)

## 6.20 mount\_device\_to\_object\_return\_t Struct Reference

message mount a device to rs485 object return

```
#include <adapter.h>
```

### Data Fields

- int [device\\_id](#)

### 6.20.1 Detailed Description

message mount a device to rs485 object return

Definition at line 138 of file adapter.h.

### 6.20.2 Field Documentation

#### 6.20.2.1 int device\_id

return the device id , if the device have a negative value, It's mount fail

Definition at line 141 of file adapter.h.

The documentation for this struct was generated from the following file:

- include/[adapter.h](#)

## 6.21 mstp\_port\_handle Struct Reference

[mstp\\_port\\_handle](#) general protocol(user defined)

```
#include <general.h>
```

### Data Fields

- unsigned char \* [package\\_buffer](#)
- unsigned int [package\\_buffer\\_len](#)
- bool [except\\_reply](#)
- unsigned int [retransmission](#)
- unsigned int [timeout\\_ms](#)
- unsigned char [address](#) [4]
- unsigned int [address\\_len](#)
- bool [broadcast](#)
- [method\\_send](#) [send\\_handle](#)
- int [method](#)
- int [value](#)
- [method\\_rcv](#) [rcv\\_handle](#)
- int [device\\_id](#)
- void \* [arg](#)

### 6.21.1 Detailed Description

[mstp\\_port\\_handle](#) general protocol(user defined)

Definition at line 43 of file general.h.

### 6.21.2 Field Documentation

#### 6.21.2.1 unsigned char address[4]

The device addresss

Definition at line 56 of file general.h.

#### 6.21.2.2 unsigned int address\_len

The device address len, should less than 4 byte

Definition at line 58 of file general.h.

#### 6.21.2.3 void\* arg

resaved argument

Definition at line 72 of file general.h.

#### 6.21.2.4 bool broadcast

The send package is a broadcast ?

Definition at line 60 of file general.h.

#### 6.21.2.5 int device\_id

The device id.

Definition at line 70 of file general.h.

#### 6.21.2.6 bool except\_reply

Is wait device reply data?

Definition at line 50 of file general.h.

#### 6.21.2.7 int method

The device method

Definition at line 64 of file general.h.

#### 6.21.2.8 unsigned char\* package\_buffer

The send buffer data to bus

Definition at line 46 of file general.h.

#### 6.21.2.9 unsigned int package\_buffer\_len

The send buffer length

Definition at line 48 of file general.h.

#### 6.21.2.10 method\_rcv rcv\_handle

process the receive buffer

Definition at line 68 of file general.h.

#### 6.21.2.11 unsigned int retransmission

send the data to device have fail, you can retransmission count

Definition at line 52 of file general.h.

#### 6.21.2.12 method\_send send\_handle

package a send data callback function

Definition at line 62 of file general.h.

#### 6.21.2.13 unsigned int timeout\_ms

wait the device reply timeout (ms)

Definition at line 54 of file general.h.

#### 6.21.2.14 int value

The device method include value

Definition at line 66 of file general.h.

The documentation for this struct was generated from the following file:

- include/protocol/general/[general.h](#)

## 6.22 object\_functions Struct Reference

```
#include <device_client.h>
```

### Data Fields

- BACNET\_OBJECT\_TYPE [Object\\_Type](#)
- [object\\_init\\_function](#) [Object\\_Init](#)
- [object\\_count\\_function](#) [Object\\_Count](#)
- [object\\_index\\_to\\_instance\\_function](#) [Object\\_Index\\_To\\_Instance](#)
- [object\\_valid\\_instance\\_function](#) [Object\\_Valid\\_Instance](#)
- [object\\_name\\_function](#) [Object\\_Name](#)
- [read\\_property\\_function](#) [Object\\_Read\\_Property](#)
- [write\\_property\\_function](#) [Object\\_Write\\_Property](#)
- [rpm\\_property\\_lists\\_function](#) [Object\\_RPM\\_List](#)
- [rr\\_info\\_function](#) [Object\\_RR\\_Info](#)
- [object\\_iterate\\_function](#) [Object\\_Iterator](#)
- [object\\_value\\_list\\_function](#) [Object\\_Value\\_List](#)
- [object\\_cov\\_function](#) [Object\\_COV](#)
- [object\\_cov\\_clear\\_function](#) [Object\\_COV\\_Clear](#)
- [object\\_intrinsic\\_reporting\\_function](#) [Object\\_Intrinsic\\_Reporting](#)

### 6.22.1 Detailed Description

Defines the group of object helper functions for any supported Object.

Each Object must provide some implementation of each of these helpers in order to properly support the handlers. Eg, the ReadProperty handler `handler_read_property()` relies on the instance of `Object_Read_Property` for each Object type, or configure the function as NULL. In both appearance and operation, this group of functions acts like they are member functions of a C++ Object base class.

Definition at line 151 of file `device_client.h`.

### 6.22.2 Field Documentation

#### 6.22.2.1 [object\\_count\\_function](#) [Object\\_Count](#)

Definition at line 154 of file `device_client.h`.

**6.22.2.2 object\_cov\_function Object\_COV**

Definition at line 164 of file device\_client.h.

**6.22.2.3 object\_cov\_clear\_function Object\_COV\_Clear**

Definition at line 165 of file device\_client.h.

**6.22.2.4 object\_index\_to\_instance\_function Object\_Index\_To\_Instance**

Definition at line 155 of file device\_client.h.

**6.22.2.5 object\_init\_function Object\_Init**

Definition at line 153 of file device\_client.h.

**6.22.2.6 object\_intrinsic\_reporting\_function Object\_Intrinsic\_Reporting**

Definition at line 166 of file device\_client.h.

**6.22.2.7 object\_iterate\_function Object\_Iterator**

Definition at line 162 of file device\_client.h.

**6.22.2.8 object\_name\_function Object\_Name**

Definition at line 157 of file device\_client.h.

**6.22.2.9 read\_property\_function Object\_Read\_Property**

Definition at line 158 of file device\_client.h.

**6.22.2.10 rpm\_property\_lists\_function Object\_RPM\_List**

Definition at line 160 of file device\_client.h.

**6.22.2.11 rr\_info\_function Object\_RR\_Info**

Definition at line 161 of file device\_client.h.

**6.22.2.12 BACNET\_OBJECT\_TYPE Object\_Type**

Definition at line 152 of file device\_client.h.

**6.22.2.13 object\_valid\_instance\_function Object\_Valid\_Instance**

Definition at line 156 of file device\_client.h.

#### 6.22.2.14 `object_value_list_function` `Object_Value_List`

Definition at line 163 of file `device_client.h`.

#### 6.22.2.15 `write_property_function` `Object_Write_Property`

Definition at line 159 of file `device_client.h`.

The documentation for this struct was generated from the following file:

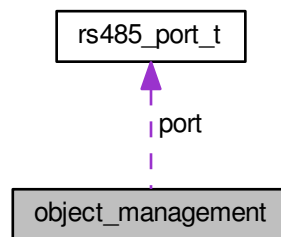
- `include/protocol/bacnet/device_client.h`

## 6.23 `object_management` Struct Reference

`object_management` define the object management struct

```
#include <object.h>
```

Collaboration diagram for `object_management`:



### Data Fields

- `pthread_t` `object_thread`
- `int` `queue_depth`
- `int` `object_id`
- `char *` `object_name`
- `rs485_protocol_type_enum` `object_type`
- `int` `mount_device_max`
- `rs485_port_t` `port`
- `unsigned char` `address` [4]
- `int` `address_len`
- `int *` `mount_device`
- `struct ring_buffer_t *` `work_queue`
- `uint8_t *` `work_queue_buffer`
- `sem_t` `queue_sem`
- `void *` `object_private`



### 6.23.1 Detailed Description

[object\\_management](#) define the object management struct

Definition at line 56 of file object.h.

### 6.23.2 Field Documentation

#### 6.23.2.1 unsigned char address[4]

The rs485 object MAC address, It's have 1 byte

Definition at line 73 of file object.h.

#### 6.23.2.2 int address\_len

The rs485 object address length

Definition at line 75 of file object.h.

#### 6.23.2.3 int\* mount\_device

The buffer have save the device id, It's malloc

Definition at line 77 of file object.h.

#### 6.23.2.4 int mount\_device\_max

The rs485 object have mount max device numbers

Definition at line 69 of file object.h.

#### 6.23.2.5 int object\_id

The object ID

Definition at line 63 of file object.h.

#### 6.23.2.6 char\* object\_name

The object name , It's malloc

Definition at line 65 of file object.h.

#### 6.23.2.7 void\* object\_private

The pointer have save the device private profile

Definition at line 85 of file object.h.

#### 6.23.2.8 pthread\_t object\_thread

The linux thread descriptor , it's be used to save the work thread

Definition at line 59 of file object.h.

#### 6.23.2.9 rs485\_protocol\_type\_enum object\_type

The rs485 protocol type, It's defined by [enum.h](#)

Definition at line 67 of file object.h.

#### 6.23.2.10 rs485\_port\_t port

The rs485 object UART physics information, The port struct have define by [adapter.h](#)

Definition at line 71 of file object.h.

#### 6.23.2.11 int queue\_depth

The work thread queue depth

Definition at line 61 of file object.h.

#### 6.23.2.12 sem\_t queue\_sem

The work queue semaphore , it's be used to save the work queue semaphore

Definition at line 83 of file object.h.

#### 6.23.2.13 struct ring\_buffer\_t\* work\_queue

The work thread have use a queue

Definition at line 79 of file object.h.

#### 6.23.2.14 uint8\_t\* work\_queue\_buffer

The work queue buffer, It's malloc

Definition at line 81 of file object.h.

The documentation for this struct was generated from the following file:

- include/[object.h](#)

## 6.24 package Struct Reference

### Data Fields

- unsigned char [addr\\_low](#)
- unsigned char [addr\\_high](#)
- unsigned char [command](#)
- unsigned char [data\\_addr](#)
- unsigned char [data](#) [4]
- int [cmd](#)

#### 6.24.1 Detailed Description

Definition at line 77 of file doya.c.

### 6.24.2 Field Documentation

#### 6.24.2.1 unsigned char addr\_high

Definition at line 81 of file doya.c.

#### 6.24.2.2 unsigned char addr\_low

Definition at line 80 of file doya.c.

#### 6.24.2.3 int cmd

Definition at line 87 of file doya.c.

#### 6.24.2.4 unsigned char command

Definition at line 82 of file doya.c.

#### 6.24.2.5 unsigned char data[4]

Definition at line 84 of file doya.c.

#### 6.24.2.6 unsigned char data\_addr

Definition at line 83 of file doya.c.

The documentation for this struct was generated from the following file:

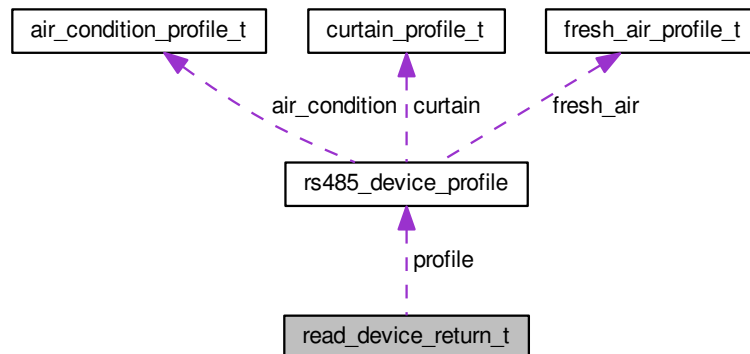
- [src/device/curtain/doya/doya.c](#)

## 6.25 read\_device\_return\_t Struct Reference

message read value from device return

```
#include <adapter.h>
```

Collaboration diagram for `read_device_return_t`:



## Data Fields

- bool [read\\_status](#)
- bool [runing](#)
- bool [error](#)
- union [rs485\\_device\\_profile](#) [profile](#)

### 6.25.1 Detailed Description

message read value from device return

Definition at line 271 of file adapter.h.

### 6.25.2 Field Documentation

#### 6.25.2.1 bool error

the device have a error status

Definition at line 278 of file adapter.h.

#### 6.25.2.2 union [rs485\\_device\\_profile](#) [profile](#)

the device profile , have fill it

Definition at line 280 of file adapter.h.

#### 6.25.2.3 bool [read\\_status](#)

The read request status

Definition at line 274 of file adapter.h.

#### 6.25.2.4 bool runing

the read device status

Definition at line 276 of file adapter.h.

The documentation for this struct was generated from the following file:

- include/[adapter.h](#)

## 6.26 read\_device\_t Struct Reference

message read value from device

```
#include <adapter.h>
```

### Data Fields

- int [device\\_id](#)

### 6.26.1 Detailed Description

message read value from device

Definition at line 203 of file adapter.h.

### 6.26.2 Field Documentation

#### 6.26.2.1 int device\_id

The device id what you want to read device value

Definition at line 206 of file adapter.h.

The documentation for this struct was generated from the following file:

- include/[adapter.h](#)

## 6.27 rs485\_curtain\_ao\_ke\_send\_package\_t Struct Reference

### Data Fields

- unsigned char [d1](#)
- unsigned char [d2](#)
- unsigned char [d3](#)
- unsigned char [d4](#)
- unsigned char [d5](#)

### 6.27.1 Detailed Description

Definition at line 84 of file aoke.c.

## 6.27.2 Field Documentation

### 6.27.2.1 unsigned char d1

Definition at line 86 of file aoke.c.

### 6.27.2.2 unsigned char d2

Definition at line 87 of file aoke.c.

### 6.27.2.3 unsigned char d3

Definition at line 88 of file aoke.c.

### 6.27.2.4 unsigned char d4

Definition at line 89 of file aoke.c.

### 6.27.2.5 unsigned char d5

Definition at line 90 of file aoke.c.

The documentation for this struct was generated from the following file:

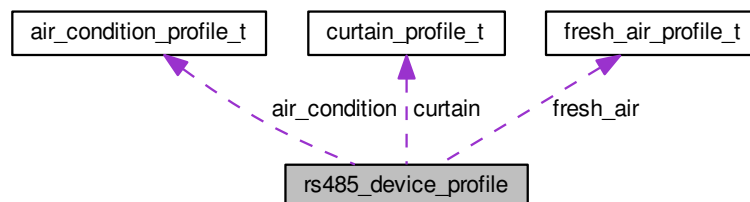
- [src/device/curtain/aoke/aoke.c](#)

## 6.28 rs485\_device\_profile Union Reference

rs485 device profile

```
#include <adapter.h>
```

Collaboration diagram for rs485\_device\_profile:



## Data Fields

- [air\\_condition\\_profile\\_t](#) `air_condition`
- [curtain\\_profile\\_t](#) `curtain`
- [fresh\\_air\\_profile\\_t](#) `fresh_air`

### 6.28.1 Detailed Description

rs485 device profile

Definition at line 256 of file adapter.h.

### 6.28.2 Field Documentation

#### 6.28.2.1 air\_condition\_profile\_t air\_condition

The air conditioner profile

Definition at line 259 of file adapter.h.

#### 6.28.2.2 curtain\_profile\_t curtain

The curtain conditioner profile

Definition at line 261 of file adapter.h.

#### 6.28.2.3 fresh\_air\_profile\_t fresh\_air

The fresh air profile

Definition at line 263 of file adapter.h.

The documentation for this union was generated from the following file:

- include/[adapter.h](#)

## 6.29 rs485\_port\_t Struct Reference

The rs485 port physical.

```
#include <adapter.h>
```

### Data Fields

- unsigned int [baud\\_rate](#)
- char [interface\\_name](#) [16]

### 6.29.1 Detailed Description

The rs485 port physical.

Definition at line 39 of file adapter.h.

### 6.29.2 Field Documentation

#### 6.29.2.1 unsigned int baud\_rate

The rs485 baud rate, like 9600, 115200 ...

Definition at line 42 of file adapter.h.

#### 6.29.2.2 char interface\_name[16]

The rs485 port profile, like /dev/ttyS1, /dev/usbS0....

Definition at line 44 of file adapter.h.

The documentation for this struct was generated from the following file:

- include/[adapter.h](#)

## 6.30 thread\_pool\_t Struct Reference

define the thread pool struct

```
#include <service.h>
```

### Data Fields

- pthread\_t \* [thread](#)
- pthread\_attr\_t \* [attr](#)
- void (\*)([function](#))(void \*[arg](#))
- void \* [arg](#)
- bool [thread\\_status](#)

### 6.30.1 Detailed Description

define the thread pool struct

Definition at line 37 of file service.h.

### 6.30.2 Field Documentation

#### 6.30.2.1 void\* arg

the thread function argument

Definition at line 46 of file service.h.

#### 6.30.2.2 pthread\_attr\_t\* attr

the thread addr argument

Definition at line 42 of file service.h.

#### 6.30.2.3 void\*(\* function)(void \*arg)

the thread service function

Definition at line 44 of file service.h.

#### 6.30.2.4 pthread\_t\* thread

the thread Id

Definition at line 40 of file service.h.



#### 6.30.2.5 bool thread\_status

the thread create status, It's will used to clean it

Definition at line 48 of file service.h.

The documentation for this struct was generated from the following file:

- [include/service.h](#)

## 6.31 timer\_task\_t Struct Reference

timer task struct

```
#include <timer_task.h>
```

### Data Fields

- unsigned int [tick](#)
- unsigned int [timeout](#)
- [timer\\_proc\\_func](#) function
- int [device\\_id](#)
- int [command](#)

### 6.31.1 Detailed Description

timer task struct

Definition at line 39 of file timer\_task.h.

### 6.31.2 Field Documentation

#### 6.31.2.1 int command

The get the device information

Definition at line 50 of file timer\_task.h.

#### 6.31.2.2 int device\_id

The function argument

Definition at line 48 of file timer\_task.h.

#### 6.31.2.3 timer\_proc\_func function

The timer task function, timeout have call it.

Definition at line 46 of file timer\_task.h.

#### 6.31.2.4 unsigned int tick

The timer tick time, sleep every tick

Definition at line 42 of file timer\_task.h.

#### 6.31.2.5 unsigned int timeout

The timeout time, when the tick  $\geq$  timeout, process

Definition at line 44 of file timer\_task.h.

The documentation for this struct was generated from the following file:

- include/[timer\\_task.h](#)

### 6.32 unmount\_device\_from\_object\_return\_t Struct Reference

message unmount a device from rs485 object return

```
#include <adapter.h>
```

#### Data Fields

- int [unmount\\_status](#)

#### 6.32.1 Detailed Description

message unmount a device from rs485 object return

Definition at line 162 of file adapter.h.

#### 6.32.2 Field Documentation

##### 6.32.2.1 int unmount\_status

The device unmount status

Definition at line 165 of file adapter.h.

The documentation for this struct was generated from the following file:

- include/[adapter.h](#)

### 6.33 unmount\_device\_from\_object\_t Struct Reference

message unmount a device form rs485 object

```
#include <adapter.h>
```

#### Data Fields

- int [device\\_id](#)
- int [object\\_id](#)

#### 6.33.1 Detailed Description

message unmount a device form rs485 object

Definition at line 149 of file adapter.h.

### 6.33.2 Field Documentation

#### 6.33.2.1 int device\_id

The device id what you want to unmount

Definition at line 152 of file adapter.h.

#### 6.33.2.2 int object\_id

The object id that the device have mounted

Definition at line 154 of file adapter.h.

The documentation for this struct was generated from the following file:

- include/[adapter.h](#)

## 6.34 write\_device\_return\_t Struct Reference

message write value to device return

```
#include <adapter.h>
```

### Data Fields

- int [write\\_status](#)

### 6.34.1 Detailed Description

message write value to device return

Definition at line 192 of file adapter.h.

### 6.34.2 Field Documentation

#### 6.34.2.1 int write\_status

The write value return status, just to wirte to work thread have return the struct

Definition at line 195 of file adapter.h.

The documentation for this struct was generated from the following file:

- include/[adapter.h](#)

## 6.35 write\_device\_t Struct Reference

message write value to device

```
#include <adapter.h>
```

## Data Fields

- int [device\\_id](#)
- bool [broadcast](#)
- unsigned int [device\\_method](#)
- int [method\\_value](#)
- int [value\\_reserve](#)

### 6.35.1 Detailed Description

message write value to device

Definition at line 173 of file adapter.h.

### 6.35.2 Field Documentation

#### 6.35.2.1 bool broadcast

The write message is broadcast

Definition at line 178 of file adapter.h.

#### 6.35.2.2 int device\_id

The device id, you must create a device, you can used it

Definition at line 176 of file adapter.h.

#### 6.35.2.3 unsigned int device\_method

The device method, you can reference [enum.h](#)

Definition at line 180 of file adapter.h.

#### 6.35.2.4 int method\_value

The device method value, just like set the air condition 24

Definition at line 182 of file adapter.h.

#### 6.35.2.5 int value\_reserve

The reserve value, you can't used it.

Definition at line 184 of file adapter.h.

The documentation for this struct was generated from the following file:

- include/[adapter.h](#)

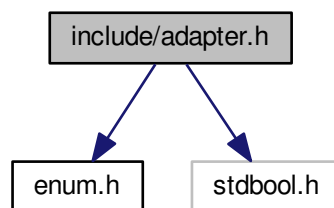
## Chapter 7

# File Documentation

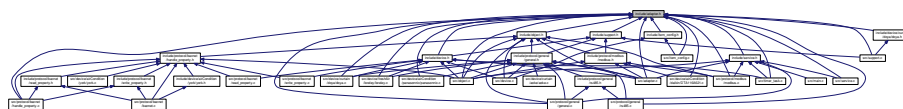
### 7.1 include/adapter.h File Reference

```
#include "enum.h"
#include <stdbool.h>
```

Include dependency graph for adapter.h:



This graph shows which files directly or indirectly include this file:



### Data Structures

- struct [rs485\\_port\\_t](#)  
*The rs485 port physical.*
- struct [create\\_object\\_t](#)  
*message create a rs485 object*
- struct [create\\_object\\_return\\_t](#)  
*message create a rs485 object return*
- struct [delete\\_object\\_t](#)  
*message delete a rs485 object*

- struct [delete\\_object\\_return\\_t](#)  
*message delete a rs485 object return*
- struct [mount\\_devcie\\_to\\_object\\_t](#)  
*message mount a device to rs485 object*
- struct [mount\\_device\\_to\\_object\\_return\\_t](#)  
*message mount a device to rs485 object return*
- struct [unmount\\_device\\_from\\_object\\_t](#)  
*message unmount a device form rs485 object*
- struct [unmount\\_device\\_from\\_object\\_return\\_t](#)  
*message unmount a device from rs485 ojbect return*
- struct [write\\_device\\_t](#)  
*message write value to device*
- struct [write\\_device\\_return\\_t](#)  
*message write value to device return*
- struct [read\\_device\\_t](#)  
*message read value from device*
- struct [air\\_condition\\_profile\\_t](#)  
*The air conditon profile.*
- struct [curtain\\_profile\\_t](#)  
*The curtain profile.*
- struct [fresh\\_air\\_profile\\_t](#)  
*The fresh profile.*
- union [rs485\\_device\\_profile](#)  
*rs485 device profile*
- struct [read\\_device\\_return\\_t](#)  
*message read value from device return*
- union [message\\_service\\_t](#)  
*define the receive the message type*
- struct [adapter\\_t](#)  
*define the adapter struct*

### 7.1.1 Detailed Description

www.enno.com

Date

: Mar 15, 2016

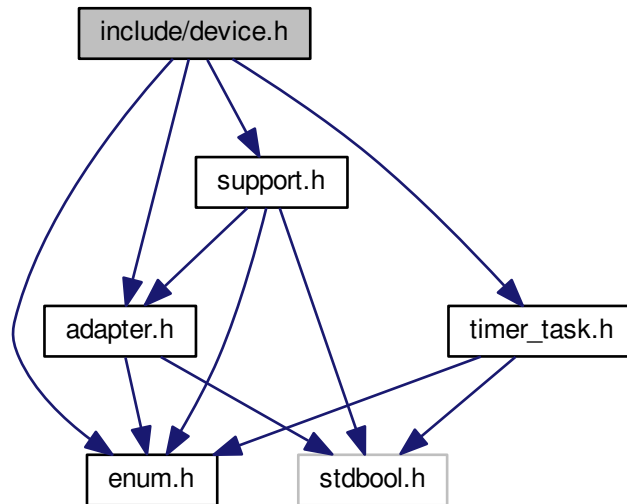
Author

: wong

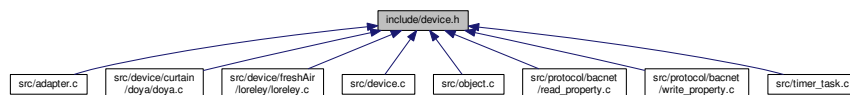
Definition in file [adapter.h](#).

## 7.2 include/device.h File Reference

```
#include "enum.h"
#include "timer_task.h"
#include "adapter.h"
#include "support.h"
Include dependency graph for device.h:
```



This graph shows which files directly or indirectly include this file:



### Data Structures

- struct `device_management`  
device define the device management struct

### Typedefs

- typedef struct `device_management` `device_management_t`  
device define the device management struct

### Functions

- int `create_device(adapter_t *adapter)`

- create\_device* create a rs485 device, mount the device to protocol
- int [delete\\_device](#) (int object\_id, int device\_id)  
*delete\_device* delete a device form device management table.
- int [get\\_device\\_name](#) (char \*out, int out\_len, int device\_id)  
*get\_device\_name* get a device name from device database.
- int [get\\_device\\_type](#) (int device\_id)  
*get\_device\_type* get a device type from device database, just like air condition, fresh air....
- int [get\\_device\\_protocol](#) (int device\_id)  
*get\_device\_protocol* get a device protocol from device database, just like BACnet, MODUBS...
- int [get\\_device\\_addr](#) (unsigned char \*addr, unsigned int addr\_len, int device\_id)  
*get\_device\_addr* get a rs485 device addr, you maybe have no address for some device.
- [timer\\_task\\_t](#) \* [get\\_device\\_timer](#) (int device\_id)  
*get\_device\_timer* get a device timer task.
- struct [device\\_profile](#) \* [get\\_device\\_private](#) (int device\_id)  
*get\_device\_private* get a device private profile
- int [get\\_device\\_private\\_numbers](#) (int device\_id)  
*get\_device\_private\_numbers*
- bool [check\\_device\\_id](#) (int device\_id)  
*check\_object\_id* check the object is legal
- int [get\\_device\\_object\\_id](#) (int device\_id)  
*get\_device\_object\_id* get the object id by device id
- int [get\\_device\\_factory\\_name](#) (int device\_id)  
*get\_device\_factory\_name* Get the device factory name
- int [get\\_device\\_retransmission](#) (int device\_id)  
*get\_device\_retransmission* Get the device retransmission count on bus
- int [get\\_device\\_timeout\\_ms](#) (int device\_id)  
*get\_device\_timeout\_ms* Get The device timeout (ms), The bus have send a package have wait timeout count.
- int [get\\_device\\_address\\_len](#) (int device\_id)  
*get\_device\_address\_len* Get the device address length.
- [device\\_management\\_t](#) \* [get\\_device\\_management](#) (int device\_id)  
*get\_device\_management* get the device management pointer
- int [device\\_managemnt\\_init](#) (void)  
*device\_managemnt\_init* The device management modele have a initialize
- int [set\\_read\\_device\\_information](#) (const [read\\_device\\_return\\_t](#) \*info, int device\_id)  
*set\_read\_device\_information* bus have get a device information have wirte it.
- int [get\\_read\\_device\\_information](#) ([read\\_device\\_return\\_t](#) \*out, int device\_id)  
*get\_read\_device\_information* It's read a device information called by adapter layer.

### 7.2.1 Detailed Description

www.enno.com

Date

: Mar 24, 2016

Author

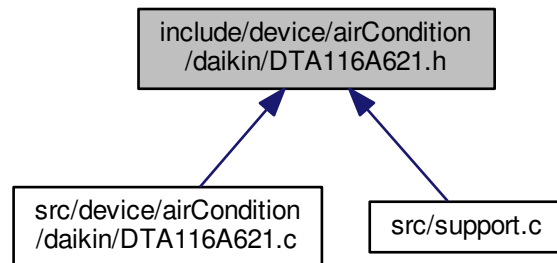
: wong

Definition in file [device.h](#).



## 7.3 include/device/airCondition/daikin/DTA116A621.h File Reference

This graph shows which files directly or indirectly include this file:

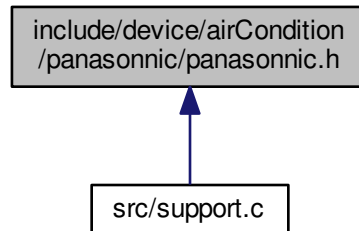


### Functions

- int [daikin\\_dta116a621\\_set\\_temperature](#) (volatile void \*arg)  
*daikin\_dta116a621\_set\_temperature set daikin air condition temperature send package to "modbus\_port\_handle\_t"*
- int [daikin\\_dta116a621\\_set\\_mode](#) (volatile void \*arg)  
*daikin\_dta116a621\_set\_mode set daikin air conditon mode send package to "modbus\_port\_handle\_t"*
- int [daikin\\_dta116a621\\_set\\_swing](#) (volatile void \*arg)  
*daikin\_dta116a621\_set\_swing set daikin air conditon swing send package to "modbus\_port\_handle\_t"*
- int [daikin\\_dta116a621\\_set\\_fan](#) (volatile void \*arg)  
*daikin\_dta116a621\_set\_fan set daikin air conditon fan send package to "modbus\_port\_handle\_t"*
- int [daikin\\_dta116a621\\_set\\_switch](#) (volatile void \*arg)  
*daikin\_dta116a621\_set\_switch set daikin air conditon switch send package to "modbus\_port\_handle\_t"*
- int [daikin\\_dta116a621\\_get\\_device\\_info\\_send](#) (volatile void \*arg)  
*daikin\_dta116a621\_get\_device\_info\_send set daikin air conditon device information send package to "modbus\_↔ port\_handle\_t"*
- int [daikin\\_dta116a621\\_get\\_device\\_info\\_handle](#) (volatile void \*arg)  
*daikin\_dta116a621\_get\_device\_info\_handle process daikin air conditon get device information send package to "modbus\_port\_handle\_t"*

## 7.4 include/device/airCondition/panasonic/panasonic.h File Reference

This graph shows which files directly or indirectly include this file:



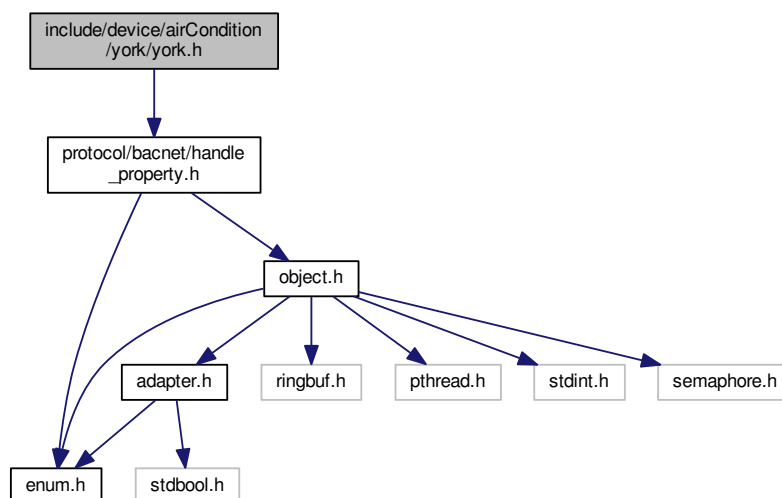
### Functions

- int [panasonic\\_send\\_package\\_handle](#) (volatile void \*arg)  
*panasonic\_send\_package\_handle* The panasonic package a send buffer interface.
- int [panasonic\\_rcv\\_package\\_handle](#) (volatile void \*arg)  
*panasonic\_send\_package\_handle* The panasonic package a receive buffer processs interface.

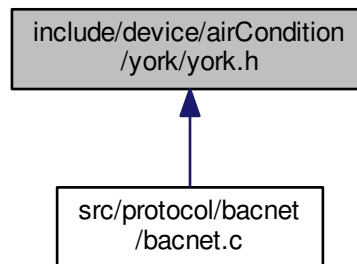
## 7.5 include/device/airCondition/york/york.h File Reference

```
#include "protocol/bacnet/handle_property.h"
```

Include dependency graph for york.h:



This graph shows which files directly or indirectly include this file:



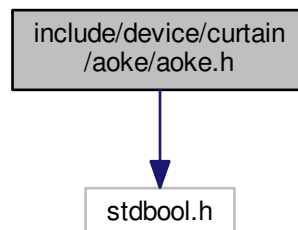
## Functions

- int [get\\_air\\_york\\_write\\_args](#) ([bacnet\\_write\\_args\\_t](#) \*args, unsigned int device\_id, int [command](#), int value)  
*get\_air\_york\_write\_args* The york air condition bacnet interface
- int [get\\_air\\_york\\_read\\_args](#) ([bacnet\\_read\\_args\\_t](#) \*args, unsigned int device\_id)  
*get\_air\_york\_read\_args* The york air confition bacnet read interface
- int [get\\_air\\_york\\_instance](#) (unsigned char mac)  
*get\_air\_york\_instance* get the youk bacnet instance.

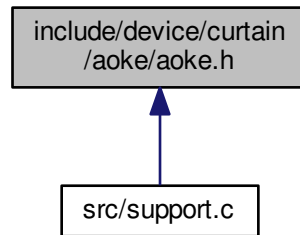
## 7.6 include/device/curtain/aoke/aoke.h File Reference

```
#include <stdbool.h>
```

Include dependency graph for aoke.h:



This graph shows which files directly or indirectly include this file:

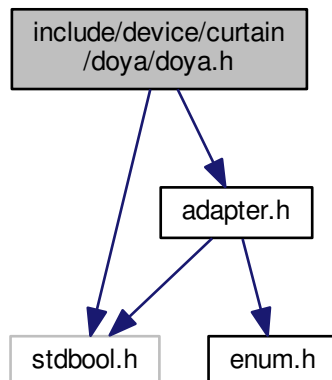


## Functions

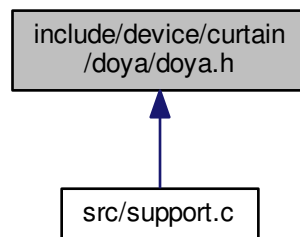
- int [aoke\\_send\\_package\\_handle](#) (volatile void \*arg)  
*aoke\_send\_package\_handle aoke curtian package a send buffer*
- int [aoke\\_rcv\\_package\\_handle](#) (volatile void \*arg)  
*aoke\_rcv\_package\_handle aoke curtain process the receive package*

## 7.7 include/device/curtain/doya/doya.h File Reference

```
#include <stdbool.h>
#include "adapter.h"
Include dependency graph for doya.h:
```



This graph shows which files directly or indirectly include this file:

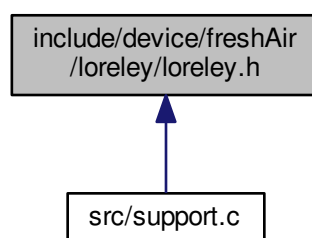


### Functions

- int [doya\\_send\\_package\\_handle](#) (volatile void \*arg)  
*doya\_send\_package\_handle* The dooya curtain package a send buffer
- int [doya\\_rcv\\_package\\_handle](#) (volatile void \*arg)  
*doya\_rcv\_package\_handle* The dooya curtain process the receive data.

## 7.8 include/device/freshAir/loreley/loreley.h File Reference

This graph shows which files directly or indirectly include this file:



### Functions

- int [loreley\\_send\\_package\\_handle](#) (volatile void \*arg)  
*loreley\_send\_package\_handle* loreley fresh air package send a buffer
- int [loreley\\_rcv\\_package\\_handle](#) (volatile void \*arg)  
*loreley\_rcv\_package\_handle* loreley fresh air process the receive data.

## 7.9 include/enum.h File Reference

This graph shows which files directly or indirectly include this file:



### Macros

- `#define UNUSED(x) UNUSED_ ## x __attribute__((unused))`

### Enumerations

- `enum timer_task_thread_status_enum {  
TIMER_TASK_THREAD_STATUS_START, TIMER_TASK_THREAD_STATUS_INIT, TIMER_TASK_TH↵  
READ_STATUS_ADDING, TIMER_TASK_THREAD_STATUS_DELETEING,  
TIMER_TASK_THREAD_STATUS_RUNNING, TIMER_TASK_THREAD_STATUS_STOP, TIMER_TASK↵  
_THREAD_STATUS_UNKNOWN }`  
*define the thread status*
- `enum adapter_thread_status_enum {  
ADAPTER_THREAD_STATUS_START, ADAPTER_THREAD_STATUS_INIT, ADAPTER_THREAD_STA↵  
TUS_RUNNING, ADAPTER_THREAD_STATUS_STOP,  
ADAPTER_THREAD_STATUS_UNKNOWN }`
- `enum object_thread_status_enum {  
OBJECT_THREAD_STATUS_START, OBJECT_THREAD_STATUS_INIT, OBJECT_THREAD_STATUS↵  
_RUNNING, OBJECT_THREAD_STATUS_STOP,  
OBJECT_THREAD_STATUS_UNKNOWN }`
- `enum rs485_service_type_enum {  
SERVICE_CREATE_RS485_OBJECT, SERVICE_DELETE_RS485_OBJECT, SERVICE_MOUNT_DEVI↵  
CE_TO_OBJECT, SERVICE_UNMOUNT_DEVICE_FROM_OBJECT,  
SERVICE_WRITE_VALUE_TO_DEVICE, SERVICE_READ_VALUE_FROM_DEVICE, SERVICE_SYSTE↵  
M_UPDATE_START, SERVICE_SYSTEM_UPDATE_STOP,  
SERVICE_UNKNOWN }`  
*define the service type*
- `enum rs485_device_type_enum { RS485_DEVICE_TYPE_AIR_CONDITION, RS485_DEVICE_TYPE_CU↵  
RTAIN, RS485_DEVICE_TYPE_FRESH_AIR, RS485_DEVICE_TYPE_UNKNOWN }`  
*define the device type*
- `enum rs485_protocol_type_enum { RS485_PROTOCOL_TYPE_BACNET, RS485_PROTOCOL_TYPE_M↵  
ODBUS, RS485_PROTOCOL_TYPE_GENERAL, RS485_PROTOCOL_TYPE_UNKNOWN }`  
*define the protocol type*
- `enum rs485_factory_name_enum {  
RS485_FACTORY_YORK, RS485_FACTORY_PANASONNIC, RS485_FACTORY_DAIKIN_DTA116A621,  
RS485_FACTORY_DOYA,  
RS485_FACTORY_AOKE, RS485_FACTORY_LORELEY, RS485_FACTORY_UNKNOWN }`  
*define the support information*
- `enum modbus_function_code_enum {  
MODBUS_FUNCTION_CODE_WRITE_SIGNLE_COIL, MODBUS_FUNCTION_CODE_READ_SIGNLE↵  
COIL, MODBUS_FUNCTION_CODE_WRITE_MULTIPLE_COILS, MODBUS_FUNCTION_CODE_READ↵  
_MULTIPLE_COILS,  
MODBUS_FUNCTION_CODE_WRITE_SIGNLE_REGISTER, MODBUS_FUNCTION_CODE_READ_SIG↵  
NLE_REGISTER, MODBUS_FUNCTION_CODE_WRITE_MULTIPLE_REGISTERS, MODBUS FUNCTI↵`

- ```

ON_CODE_READ_MULTIPLE_REGISTERS,
MODBUS_FUNCTION_CODE_DO_NOTHING }

```
- enum rs485\_method\_air\_condition\_york\_enum {
 RS485\_YORK\_AIR\_SET\_TEMP\_18 = 18, RS485\_YORK\_AIR\_SET\_TEMP\_19 = 19, RS485\_YORK\_AIR↵
 \_SET\_TEMP\_20 = 20, RS485\_YORK\_AIR\_SET\_TEMP\_21 = 21,
 RS485\_YORK\_AIR\_SET\_TEMP\_22 = 22, RS485\_YORK\_AIR\_SET\_TEMP\_23 = 23, RS485\_YORK\_AIR↵
 \_SET\_TEMP\_24 = 24, RS485\_YORK\_AIR\_SET\_TEMP\_25 = 25,
 RS485\_YORK\_AIR\_SET\_TEMP\_26 = 26, RS485\_YORK\_AIR\_SET\_TEMP\_27 = 27, RS485\_YORK\_AIR↵
 \_SET\_TEMP\_28 = 28, RS485\_YORK\_AIR\_SET\_TEMP\_29 = 29,
 RS485\_YORK\_AIR\_SET\_TEMP\_30 = 30, RS485\_YORK\_AIR\_SET\_TEMP\_31 = 31, RS485\_YORK\_AIR↵
 \_SET\_TEMP\_32 = 32, RS485\_YORK\_AIR\_SET\_HUMIDITY = 33,
 RS485\_YORK\_AIR\_SWING\_AUTO = 41, RS485\_YORK\_AIR\_SWING\_UP\_DOWN = 42, RS485\_YORK\_A↵
 IR\_SWING\_LEFT\_RIGHT = 43, RS485\_YORK\_AIR\_SWING\_UP\_DOWN\_LEFT\_RIGHT = 44,
 RS485\_YORK\_AIR\_FAN\_AUTO = 51, RS485\_YORK\_AIR\_FAN\_HIGH = 52, RS485\_YORK\_AIR\_FAN\_M↵
 IDDLE = 53, RS485\_YORK\_AIR\_FAN\_LOW = 54,
 RS485\_YORK\_AIR\_MODE\_FANING = 61, RS485\_YORK\_AIR\_MODE\_HEATING = 62, RS485\_YORK\_A↵
 IR\_MODE\_COOLING = 63, RS485\_YORK\_AIR\_MODE\_DRYING = 64,
 RS485\_YORK\_AIR\_MODE\_AUTOING = 65, RS485\_YORK\_AIR\_OFF = 77, RS485\_YORK\_AIR\_ON = 78,
 RS485\_YORK\_AIR\_GET\_DEVICE\_INFO = 81,
 RS485\_YORK\_AIR\_ERR\_RESET\_YES, RS485\_YORK\_AIR\_ERR\_RESET\_NO, RS485\_YORK\_AIR\_NE↵
 T\_RESET\_YES, RS485\_YORK\_AIR\_NET\_RESET\_NO,
 RS485\_YORK\_AIR\_SLEEP\_YES, RS485\_YORK\_AIR\_SLEEP\_NO, RS485\_YORK\_AIR\_ELECTRICAL\_↵
 HEAT\_YES, RS485\_YORK\_AIR\_ELECTRICAL\_HEAT\_NO,
 RS485\_YORK\_AIR\_HEALTH\_AIR\_YES, RS485\_YORK\_AIR\_HEALTH\_AIR\_NO, RS485\_YORK\_AIR\_H↵
 OT\_WATER\_YES, RS485\_YORK\_AIR\_HOT\_WATER\_NO,
 RS485\_YORK\_AIR\_HOME\_LEFT\_YES, RS485\_YORK\_AIR\_HOME\_LEFT\_NO, RS485\_YORK\_AIR\_FIX↵
 \_RUN\_YES, RS485\_YORK\_AIR\_FIX\_RUN\_NO,
 RS485\_YORK\_AIR\_SAVING\_YES, RS485\_YORK\_AIR\_SAVING\_NO, RS485\_YORK\_AIR\_DEFROST\_Y↵
 ES, RS485\_YORK\_AIR\_DEFROST\_NO,
 RS485\_YORK\_AIR\_COOL\_ONLY\_YES, RS485\_YORK\_AIR\_COOL\_ONLY\_NO, RS485\_YORK\_AIR\_CE↵
 NTRAL\_CONTROL\_ONLY\_YES, RS485\_YORK\_AIR\_CENTRAL\_CONTROL\_ONLY\_NO }
  - enum rs485\_method\_air\_condition\_panasonic\_enum {
 RS485\_PANASONNIC\_AIR\_SET\_TEMP\_16 = 16, RS485\_PANASONNIC\_AIR\_SET\_TEMP\_17 = 17, R↵
 S485\_PANASONNIC\_AIR\_SET\_TEMP\_18 = 18, RS485\_PANASONNIC\_AIR\_SET\_TEMP\_19 = 19,
 RS485\_PANASONNIC\_AIR\_SET\_TEMP\_20 = 20, RS485\_PANASONNIC\_AIR\_SET\_TEMP\_21 = 21, R↵
 S485\_PANASONNIC\_AIR\_SET\_TEMP\_22 = 22, RS485\_PANASONNIC\_AIR\_SET\_TEMP\_23 = 23,
 RS485\_PANASONNIC\_AIR\_SET\_TEMP\_24 = 24, RS485\_PANASONNIC\_AIR\_SET\_TEMP\_25 = 25, R↵
 S485\_PANASONNIC\_AIR\_SET\_TEMP\_26 = 26, RS485\_PANASONNIC\_AIR\_SET\_TEMP\_27 = 27,
 RS485\_PANASONNIC\_AIR\_SET\_TEMP\_28 = 28, RS485\_PANASONNIC\_AIR\_SET\_TEMP\_29 = 29, R↵
 S485\_PANASONNIC\_AIR\_SET\_TEMP\_30 = 30, RS485\_PANASONNIC\_AIR\_SWING\_AUTO = 41,
 RS485\_PANASONNIC\_AIR\_SWING\_HAND5 = 42, RS485\_PANASONNIC\_AIR\_SWING\_HAND4 = 43, R↵
 S485\_PANASONNIC\_AIR\_SWING\_HAND3 = 44, RS485\_PANASONNIC\_AIR\_SWING\_HAND2 = 45,
 RS485\_PANASONNIC\_AIR\_SWING\_HAND1 = 46, RS485\_PANASONNIC\_AIR\_FAN\_AUTO = 51, R↵
 S485\_PANASONNIC\_AIR\_FAN\_HIGH = 52, RS485\_PANASONNIC\_AIR\_FAN\_MIDDLE = 53,
 RS485\_PANASONNIC\_AIR\_FAN\_LOW = 54, RS485\_PANASONNIC\_AIR\_FAN\_MOST = 55, RS485\_PA↵
 NASONNIC\_AIR\_FAN\_MUTE = 56, RS485\_PANASONNIC\_AIR\_MODE\_FANING = 61,
 RS485\_PANASONNIC\_AIR\_MODE\_HEATING = 62, RS485\_PANASONNIC\_AIR\_MODE\_COOLING = 63,
 RS485\_PANASONNIC\_AIR\_MODE\_DRYING = 64, RS485\_PANASONNIC\_AIR\_MODE\_AUTOING = 65,
 RS485\_PANASONNIC\_AIR\_OFF = 71, RS485\_PANASONNIC\_AIR\_ON = 72, RS485\_PANASONNIC\_AI↵
 R\_RESET = 73, RS485\_PANASONNIC\_AIR\_GET\_DEVICE\_INFO = 81 }
  - enum rs485\_method\_curtain\_aoke\_enum {
 RS485\_AOKE\_CURTAIN\_OPEN = 101, RS485\_AOKE\_CURTAIN\_CLOSE = 102, RS485\_AOKE\_CURT↵
 AIN\_SET\_PERCENT = 103, RS485\_AOKE\_CURTAIN\_RESET = 104,
 RS485\_AOKE\_CURTAIN\_GET\_DEVICE\_INFO = 105 }
  - enum rs485\_method\_curtain\_doya\_enum {
 RS485\_DOYA\_CURTAIN\_OPEN = 101, RS485\_DOYA\_CURTAIN\_CLOSE = 102, RS485\_DOYA\_CURT↵
 AIN\_SET\_PERCENT = 103, RS485\_DOYA\_CURTAIN\_RESET = 104,
 RS485\_DOYA\_CURTAIN\_GET\_DEVICE\_INFO = 105 }

- enum `rs485_method_fresh_air_loreley_enum` { `RS485_LORELEY_FRESH_AIR_AUTO_ON` = 201, `RS485_LORELEY_FRESH_AIR_AUTO_OFF` = 202, `RS485_LORELEY_FRESH_AIR_RESET` = 203, `RS485_LORELEY_FRESH_AIR_GET_DEVICE_INFO` = 204 }
- enum `rs485_device_method_enum` {  
`RS485_AIR_SET_TEMP` = 10, `RS485_AIR_SET_TEMP_18` = 18, `RS485_AIR_SET_TEMP_19` = 19, `RS485_AIR_SET_TEMP_20` = 20,  
`RS485_AIR_SET_TEMP_21` = 21, `RS485_AIR_SET_TEMP_22` = 22, `RS485_AIR_SET_TEMP_23` = 23,  
`RS485_AIR_SET_TEMP_24` = 24,  
`RS485_AIR_SET_TEMP_25` = 25, `RS485_AIR_SET_TEMP_26` = 26, `RS485_AIR_SET_TEMP_27` = 27,  
`RS485_AIR_SET_TEMP_28` = 28,  
`RS485_AIR_SET_TEMP_29` = 29, `RS485_AIR_SET_TEMP_30` = 30, `RS485_AIR_SWING` = 40, `RS485_AIR_SWING_AUTO` = 41,  
`RS485_AIR_SWING_UP_DOWN` = 42, `RS485_AIR_SWING_LEFT_RIGHT` = 43, `RS485_AIR_SWING_UP_DOWN_LEFT_RIGHT` = 44, `RS485_AIR_FAN` = 50,  
`RS485_AIR_FAN_AUTO` = 51, `RS485_AIR_FAN_HIGH` = 52, `RS485_AIR_FAN_MIDDLE` = 53, `RS485_AIR_FAN_LOW` = 54,  
`RS485_AIR_MODE` = 60, `RS485_AIR_MODE_FANING` = 61, `RS485_AIR_MODE_HEATING` = 62, `RS485_AIR_MODE_COOLING` = 63,  
`RS485_AIR_MODE_DRYING` = 64, `RS485_AIR_MODE_AUTOING` = 65, `RS485_AIR_SWITCH` = 70, `RS485_AIR_OFF` = 71,  
`RS485_AIR_ON` = 72, `RS485_AIR_RESTART` = 73, `RS485_AIR_GET_DEVICE_INFO` = 81, `RS485_CURTAIN_OPEN` = 100,  
`RS485_CURTAIN_OPEN` = 101, `RS485_CURTAIN_CLOSE` = 102, `RS485_CURTAIN_SET_PERCENT` = 103, `RS485_CURTAIN_RESET` = 104,  
`RS485_CURTAIN_GET_DEVICE_INFO` = 105, `RS485_FRESH_AIR` = 200, `RS485_FRESH_AIR_AUTO_ON` = 201, `RS485_FRESH_AIR_AUTO_OFF` = 202,  
`RS485_FRESH_AIR_RESET` = 203, `RS485_FRESH_AIR_GET_DEVICE_INFO` = 204 }

### 7.9.1 Detailed Description

[www.enno.com](http://www.enno.com)

Date

: Mar 15, 2016

Author

: wong

Definition in file [enum.h](#).

### 7.9.2 Macro Definition Documentation

#### 7.9.2.1 #define UNUSED( x ) UNUSED\_ ## x \_\_attribute\_\_((unused))

define the unused mac

Definition at line 387 of file [enum.h](#).

### 7.9.3 Enumeration Type Documentation

#### 7.9.3.1 enum adapter\_thread\_status\_enum

define the adapter thread run status



## Enumerator

***ADAPTER\_THREAD\_STATUS\_START***  
***ADAPTER\_THREAD\_STATUS\_INIT***  
***ADAPTER\_THREAD\_STATUS\_RUNNING***  
***ADAPTER\_THREAD\_STATUS\_STOP***  
***ADAPTER\_THREAD\_STATUS\_UNKNOWN***

Definition at line 38 of file enum.h.

## 7.9.3.2 enum modbus\_function\_code\_enum

## Enumerator

***MODBUS\_FUNCTION\_CODE\_WRITE\_SIGNLE\_COIL***  
***MODBUS\_FUNCTION\_CODE\_READ\_SIGNLE\_COIL***  
***MODBUS\_FUNCTION\_CODE\_WRITE\_MULTIPLE\_COILS***  
***MODBUS\_FUNCTION\_CODE\_READ\_MULTIPLE\_COILS***  
***MODBUS\_FUNCTION\_CODE\_WRITE\_SIGNLE\_REGISTER***  
***MODBUS\_FUNCTION\_CODE\_READ\_SIGNLE\_REGISTER***  
***MODBUS\_FUNCTION\_CODE\_WRITE\_MULTIPLE\_REGISTERS***  
***MODBUS\_FUNCTION\_CODE\_READ\_MULTIPLE\_REGISTERS***  
***MODBUS\_FUNCTION\_CODE\_DO\_NOTHING***

Definition at line 136 of file enum.h.

## 7.9.3.3 enum object\_thread\_status\_enum

define the object thread run status

## Enumerator

***OBJECT\_THREAD\_STATUS\_START***  
***OBJECT\_THREAD\_STATUS\_INIT***  
***OBJECT\_THREAD\_STATUS\_RUNNING***  
***OBJECT\_THREAD\_STATUS\_STOP***  
***OBJECT\_THREAD\_STATUS\_UNKNOWN***

Definition at line 49 of file enum.h.

## 7.9.3.4 enum rs485\_device\_method\_enum

define the device support method

## Enumerator

***RS485\_AIR\_SET\_TEMP***  
***RS485\_AIR\_SET\_TEMP\_18***  
***RS485\_AIR\_SET\_TEMP\_19***  
***RS485\_AIR\_SET\_TEMP\_20***  
***RS485\_AIR\_SET\_TEMP\_21***  
***RS485\_AIR\_SET\_TEMP\_22***

*RS485\_AIR\_SET\_TEMP\_23*  
*RS485\_AIR\_SET\_TEMP\_24*  
*RS485\_AIR\_SET\_TEMP\_25*  
*RS485\_AIR\_SET\_TEMP\_26*  
*RS485\_AIR\_SET\_TEMP\_27*  
*RS485\_AIR\_SET\_TEMP\_28*  
*RS485\_AIR\_SET\_TEMP\_29*  
*RS485\_AIR\_SET\_TEMP\_30*  
*RS485\_AIR\_SWING*  
*RS485\_AIR\_SWING\_AUTO*  
*RS485\_AIR\_SWING\_UP\_DOWN*  
*RS485\_AIR\_SWING\_LEFT\_RIGHT*  
*RS485\_AIR\_SWING\_UP\_DOWN\_LEFT\_RIGHT*  
*RS485\_AIR\_FAN*  
*RS485\_AIR\_FAN\_AUTO*  
*RS485\_AIR\_FAN\_HIGH*  
*RS485\_AIR\_FAN\_MIDDLE*  
*RS485\_AIR\_FAN\_LOW*  
*RS485\_AIR\_MODE*  
*RS485\_AIR\_MODE\_FANING*  
*RS485\_AIR\_MODE\_HEATING*  
*RS485\_AIR\_MODE\_COOLING*  
*RS485\_AIR\_MODE\_DRYING*  
*RS485\_AIR\_MODE\_AUTOING*  
*RS485\_AIR\_SWITCH*  
*RS485\_AIR\_OFF*  
*RS485\_AIR\_ON*  
*RS485\_AIR\_RESTART*  
*RS485\_AIR\_GET\_DEVICE\_INFO*  
*RS485\_CURTAIN*  
*RS485\_CURTAIN\_OPEN*  
*RS485\_CURTAIN\_CLOSE*  
*RS485\_CURTAIN\_SET\_PERCENT*  
*RS485\_CURTAIN\_RESET*  
*RS485\_CURTAIN\_GET\_DEVICE\_INFO*  
*RS485\_FRESH\_AIR*  
*RS485\_FRESH\_AIR\_AUTO\_ON*  
*RS485\_FRESH\_AIR\_AUTO\_OFF*  
*RS485\_FRESH\_AIR\_RESET*  
*RS485\_FRESH\_AIR\_GET\_DEVICE\_INFO*

Definition at line 320 of file enum.h.

## 7.9.3.5 enum rs485\_device\_type\_enum

define the device type

define the rs485 device type

Enumerator

***RS485\_DEVICE\_TYPE\_AIR\_CONDITION***  
***RS485\_DEVICE\_TYPE\_CURTAIN***  
***RS485\_DEVICE\_TYPE\_FRESH\_AIR***  
***RS485\_DEVICE\_TYPE\_UNKNOWN***

Definition at line 91 of file enum.h.

## 7.9.3.6 enum rs485\_factory\_name\_enum

define the support information

define the factory name

Enumerator

***RS485\_FACTORY\_YORK***  
***RS485\_FACTORY\_PANASONNIC***  
***RS485\_FACTORY\_DAIKIN\_DTA116A621***  
***RS485\_FACTORY\_DOYA***  
***RS485\_FACTORY\_AOKE***  
***RS485\_FACTORY\_LORELEY***  
***RS485\_FACTORY\_UNKNOWN***

Definition at line 124 of file enum.h.

## 7.9.3.7 enum rs485\_method\_air\_condition\_panasonic\_enum

Enumerator

***RS485\_PANASONNIC\_AIR\_SET\_TEMP\_16***  
***RS485\_PANASONNIC\_AIR\_SET\_TEMP\_17***  
***RS485\_PANASONNIC\_AIR\_SET\_TEMP\_18***  
***RS485\_PANASONNIC\_AIR\_SET\_TEMP\_19***  
***RS485\_PANASONNIC\_AIR\_SET\_TEMP\_20***  
***RS485\_PANASONNIC\_AIR\_SET\_TEMP\_21***  
***RS485\_PANASONNIC\_AIR\_SET\_TEMP\_22***  
***RS485\_PANASONNIC\_AIR\_SET\_TEMP\_23***  
***RS485\_PANASONNIC\_AIR\_SET\_TEMP\_24***  
***RS485\_PANASONNIC\_AIR\_SET\_TEMP\_25***  
***RS485\_PANASONNIC\_AIR\_SET\_TEMP\_26***  
***RS485\_PANASONNIC\_AIR\_SET\_TEMP\_27***  
***RS485\_PANASONNIC\_AIR\_SET\_TEMP\_28***  
***RS485\_PANASONNIC\_AIR\_SET\_TEMP\_29***  
***RS485\_PANASONNIC\_AIR\_SET\_TEMP\_30***

*RS485\_PANASONNIC\_AIR\_SWING\_AUTO*  
*RS485\_PANASONNIC\_AIR\_SWING\_HAND5*  
*RS485\_PANASONNIC\_AIR\_SWING\_HAND4*  
*RS485\_PANASONNIC\_AIR\_SWING\_HAND3*  
*RS485\_PANASONNIC\_AIR\_SWING\_HAND2*  
*RS485\_PANASONNIC\_AIR\_SWING\_HAND1*  
*RS485\_PANASONNIC\_AIR\_FAN\_AUTO*  
*RS485\_PANASONNIC\_AIR\_FAN\_HIGH*  
*RS485\_PANASONNIC\_AIR\_FAN\_MIDDLE*  
*RS485\_PANASONNIC\_AIR\_FAN\_LOW*  
*RS485\_PANASONNIC\_AIR\_FAN\_MOST*  
*RS485\_PANASONNIC\_AIR\_FAN\_MUTE*  
*RS485\_PANASONNIC\_AIR\_MODE\_FANING*  
*RS485\_PANASONNIC\_AIR\_MODE\_HEATING*  
*RS485\_PANASONNIC\_AIR\_MODE\_COOLING*  
*RS485\_PANASONNIC\_AIR\_MODE\_DRYING*  
*RS485\_PANASONNIC\_AIR\_MODE\_AUTOING*  
*RS485\_PANASONNIC\_AIR\_OFF*  
*RS485\_PANASONNIC\_AIR\_ON*  
*RS485\_PANASONNIC\_AIR\_RESET*  
*RS485\_PANASONNIC\_AIR\_GET\_DEVICE\_INFO*

Definition at line 241 of file enum.h.

#### 7.9.3.8 enum rs485\_method\_air\_condition\_york\_enum

device method define

Enumerator

*RS485\_YORK\_AIR\_SET\_TEMP\_18*  
*RS485\_YORK\_AIR\_SET\_TEMP\_19*  
*RS485\_YORK\_AIR\_SET\_TEMP\_20*  
*RS485\_YORK\_AIR\_SET\_TEMP\_21*  
*RS485\_YORK\_AIR\_SET\_TEMP\_22*  
*RS485\_YORK\_AIR\_SET\_TEMP\_23*  
*RS485\_YORK\_AIR\_SET\_TEMP\_24*  
*RS485\_YORK\_AIR\_SET\_TEMP\_25*  
*RS485\_YORK\_AIR\_SET\_TEMP\_26*  
*RS485\_YORK\_AIR\_SET\_TEMP\_27*  
*RS485\_YORK\_AIR\_SET\_TEMP\_28*  
*RS485\_YORK\_AIR\_SET\_TEMP\_29*  
*RS485\_YORK\_AIR\_SET\_TEMP\_30*  
*RS485\_YORK\_AIR\_SET\_TEMP\_31*  
*RS485\_YORK\_AIR\_SET\_TEMP\_32*  
*RS485\_YORK\_AIR\_SET\_HUMIDITY*  
*RS485\_YORK\_AIR\_SWING\_AUTO*

*RS485\_YORK\_AIR\_SWING\_UP\_DOWN*  
*RS485\_YORK\_AIR\_SWING\_LEFT\_RIGHT*  
*RS485\_YORK\_AIR\_SWING\_UP\_DOWN\_LEFT\_RIGHT*  
*RS485\_YORK\_AIR\_FAN\_AUTO*  
*RS485\_YORK\_AIR\_FAN\_HIGH*  
*RS485\_YORK\_AIR\_FAN\_MIDDLE*  
*RS485\_YORK\_AIR\_FAN\_LOW*  
*RS485\_YORK\_AIR\_MODE\_FANING*  
*RS485\_YORK\_AIR\_MODE\_HEATING*  
*RS485\_YORK\_AIR\_MODE\_COOLING*  
*RS485\_YORK\_AIR\_MODE\_DRYING*  
*RS485\_YORK\_AIR\_MODE\_AUTOING*  
*RS485\_YORK\_AIR\_OFF*  
*RS485\_YORK\_AIR\_ON*  
*RS485\_YORK\_AIR\_GET\_DEVICE\_INFO*  
*RS485\_YORK\_AIR\_ERR\_RESET\_YES*  
*RS485\_YORK\_AIR\_ERR\_RESET\_NO*  
*RS485\_YORK\_AIR\_NET\_RESET\_YES*  
*RS485\_YORK\_AIR\_NET\_RESET\_NO*  
*RS485\_YORK\_AIR\_SLEEP\_YES*  
*RS485\_YORK\_AIR\_SLEEP\_NO*  
*RS485\_YORK\_AIR\_ELECTRICAL\_HEAT\_YES*  
*RS485\_YORK\_AIR\_ELECTRICAL\_HEAT\_NO*  
*RS485\_YORK\_AIR\_HEALTH\_AIR\_YES*  
*RS485\_YORK\_AIR\_HEALTH\_AIR\_NO*  
*RS485\_YORK\_AIR\_HOT\_WATER\_YES*  
*RS485\_YORK\_AIR\_HOT\_WATER\_NO*  
*RS485\_YORK\_AIR\_HOME\_LEFT\_YES*  
*RS485\_YORK\_AIR\_HOME\_LEFT\_NO*  
*RS485\_YORK\_AIR\_FIX\_RUN\_YES*  
*RS485\_YORK\_AIR\_FIX\_RUN\_NO*  
*RS485\_YORK\_AIR\_SAVING\_YES*  
*RS485\_YORK\_AIR\_SAVING\_NO*  
*RS485\_YORK\_AIR\_DEFROST\_YES*  
*RS485\_YORK\_AIR\_DEFROST\_NO*  
*RS485\_YORK\_AIR\_COOL\_ONLY\_YES*  
*RS485\_YORK\_AIR\_COOL\_ONLY\_NO*  
*RS485\_YORK\_AIR\_CENTRAL\_CONTROL\_ONLY\_YES*  
*RS485\_YORK\_AIR\_CENTRAL\_CONTROL\_ONLY\_NO*

Definition at line 161 of file enum.h.

#### 7.9.3.9 enum rs485\_method\_curtain\_aoke\_enum

Enumerator

***RS485\_AOKE\_CURTAIN\_OPEN***  
***RS485\_AOKE\_CURTAIN\_CLOSE***  
***RS485\_AOKE\_CURTAIN\_SET\_PERCENT***  
***RS485\_AOKE\_CURTAIN\_RESET***  
***RS485\_AOKE\_CURTAIN\_GET\_DEVICE\_INFO***

Definition at line 288 of file enum.h.

#### 7.9.3.10 enum rs485\_method\_curtain\_doya\_enum

Enumerator

***RS485\_DOYA\_CURTAIN\_OPEN***  
***RS485\_DOYA\_CURTAIN\_CLOSE***  
***RS485\_DOYA\_CURTAIN\_SET\_PERCENT***  
***RS485\_DOYA\_CURTAIN\_RESET***  
***RS485\_DOYA\_CURTAIN\_GET\_DEVICE\_INFO***

Definition at line 298 of file enum.h.

#### 7.9.3.11 enum rs485\_method\_fresh\_air\_loreley\_enum

Enumerator

***RS485\_LORELEY\_FRESH\_AIR\_AUTO\_ON***  
***RS485\_LORELEY\_FRESH\_AIR\_AUTO\_OFF***  
***RS485\_LORELEY\_FRESH\_AIR\_RESET***  
***RS485\_LORELEY\_FRESH\_AIR\_GET\_DEVICE\_INFO***

Definition at line 309 of file enum.h.

#### 7.9.3.12 enum rs485\_protocol\_type\_enum

define the protocol type

define the rs485 protocol type

Enumerator

***RS485\_PROTOCOL\_TYPE\_BACNET***  
***RS485\_PROTOCOL\_TYPE\_MODBUS***  
***RS485\_PROTOCOL\_TYPE\_GENERAL***  
***RS485\_PROTOCOL\_TYPE\_UNKNOWN***

Definition at line 107 of file enum.h.

## 7.9.3.13 enum rs485\_service\_type\_enum

define the service type

define the adapter message type

Enumerator

***SERVICE\_CREATE\_RS485\_OBJECT***

***SERVICE\_DELETE\_RS485\_OBJECT***

***SERVICE\_MOUNT\_DEVICE\_TO\_OBJECT***

***SERVICE\_UNMOUNT\_DEVICE\_FROM\_OBJECT***

***SERVICE\_WRITE\_VALUE\_TO\_DEVICE***

***SERVICE\_READ\_VALUE\_FROM\_DEVICE***

***SERVICE\_SYSTEM\_UPDATE\_START***

***SERVICE\_SYSTEM\_UPDATE\_STOP***

***SERVICE\_UNKNOWN***

Definition at line 69 of file enum.h.

## 7.9.3.14 enum timer\_task\_thread\_status\_enum

define the thread status

define the timer task thread run status

Enumerator

***TIMER\_TASK\_THREAD\_STATUS\_START***

***TIMER\_TASK\_THREAD\_STATUS\_INIT***

***TIMER\_TASK\_THREAD\_STATUS\_ADDING***

***TIMER\_TASK\_THREAD\_STATUS\_DELETEING***

***TIMER\_TASK\_THREAD\_STATUS\_RUNNING***

***TIMER\_TASK\_THREAD\_STATUS\_STOP***

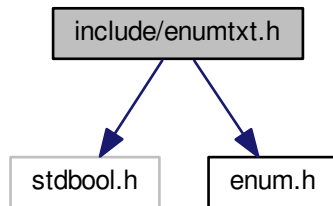
***TIMER\_TASK\_THREAD\_STATUS\_UNKNOWN***

Definition at line 25 of file enum.h.

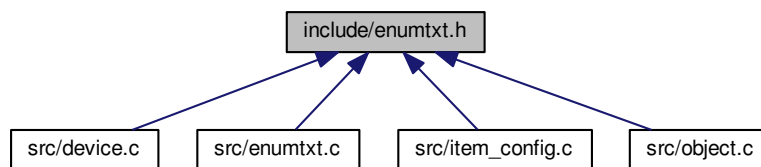
## 7.10 include/enumtxt.h File Reference

```
#include <stdbool.h>
#include "enum.h"
```

Include dependency graph for enumtxt.h:



This graph shows which files directly or indirectly include this file:



## Functions

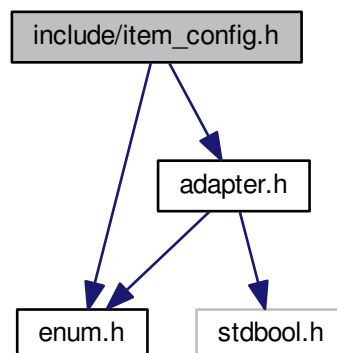
- char \* [get\\_enum\\_txt\\_service](#) (rs485\_service\_type\_enum type)  
*get\_enum\_txt\_service get enum rs485 service message type*
- char \* [get\\_enum\\_txt\\_rs485\\_device\\_type](#) (rs485\_device\_type\_enum type)  
*get\_enum\_txt\_rs485\_device\_type get enum rs485 device type*
- char \* [get\\_enum\\_txt\\_rs485\\_protocol\\_type](#) (rs485\_protocol\_type\_enum type)  
*get\_enum\_txt\_rs485\_protocol\_type get enum rs485 protocol type*
- char \* [get\\_enum\\_txt\\_device\\_method](#) (rs485\_device\_method\_enum type)  
*get\_enum\_txt\_device\_method get enum device method(command)*
- char \* [get\\_enum\\_txt\\_device\\_factory](#) (rs485\_factory\_name\_enum name)  
*get\_enum\_txt\_device\_factory get enum device factory name*
- char \* [get\\_enum\\_txt\\_bool](#) (bool status)  
*get\_enum\_txt\_bool get the string about bool value*

## 7.11 include/item\_config.h File Reference

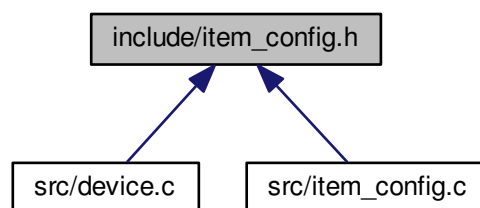
```
#include "enum.h"
#include "adapter.h"
```



Include dependency graph for item\_config.h:



This graph shows which files directly or indirectly include this file:



## Macros

- `#define PANNO_S_ITEM_CONFIG`
- `#define PANNO_S_ITEM_DEFAULT (1)`
- `#define PANNO_S_ITEM_WENRUDE (0)`
- `#define PANNO_S_ITEM_ARMANI (0)`
- `#define PANNO_S_ITEM_SHAOCHENGGUOJI (0)`

## Functions

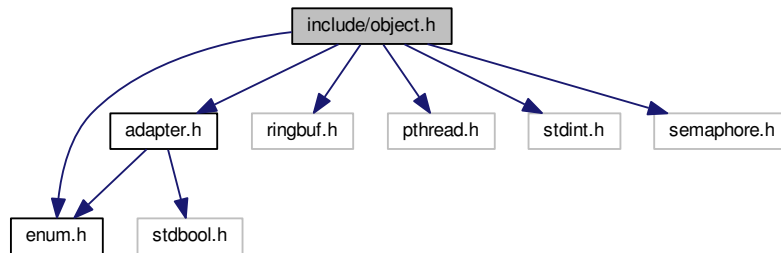
- void `panno_s_item_config` (`adapter_t` \*adapter, `rs485_device_type_enum` device\_type, unsigned char device\_addr)

*panno\_s\_item\_config* This function is offer the pannoS item config

## 7.12 include/object.h File Reference

```
#include "enum.h"
#include "adapter.h"
#include "ringbuf.h"
#include <pthread.h>
#include <stdint.h>
#include <semaphore.h>
```

Include dependency graph for object.h:



This graph shows which files directly or indirectly include this file:



### Data Structures

- struct [object\\_management](#)  
*object\_management* define the object management struct

### Typedefs

- typedef struct [object\\_management](#) [object\\_management\\_t](#)  
*object\_management* define the object management struct

### Functions

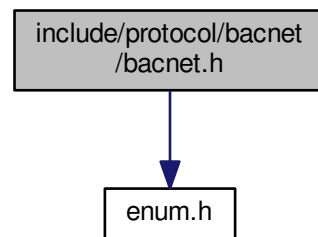
- int [create\\_object](#) (const [adapter\\_t](#) \*adapter)  
*create\_object* create a object by the adapter message
- int [delete\\_object](#) (int object\_id)  
*delete\_object* delete a rs485 object by object id
- bool [check\\_object\\_id](#) (int object\_id)  
*check\_object\_id* check the object is legal
- int [get\\_object\\_type](#) (int object\_id)  
*get\_object\_type* get the object protocol type
- int [get\\_object\\_mount\\_device](#) (int object\_id, int \*out\_id, int out\_id\_len)

- get\_object\_mount\_device* get the object mount device
- bool [check\\_object\\_numbers\\_have\\_idle](#) (int object\_id)  
*check\_object\_numbers\_have\_idle* check object mount device is full ?
- int [object\\_mount\\_device\\_id](#) (int object\_id, int device\_id)  
*object\_mount\_device\_id* add a device to his object
- void [object\\_unmount\\_device\\_id](#) (int object\_id, int device\_id)  
*object\_unmount\_device\_id* delete a device form his object
- void \* [get\\_object\\_work\\_queue](#) (int object\_id)  
*get\_object\_work\_queue* get the object of work queue
- void \* [get\\_object\\_queue\\_sem](#) (int object\_id)  
*get\_object\_queue\_sem* get the object of work queue semaphore

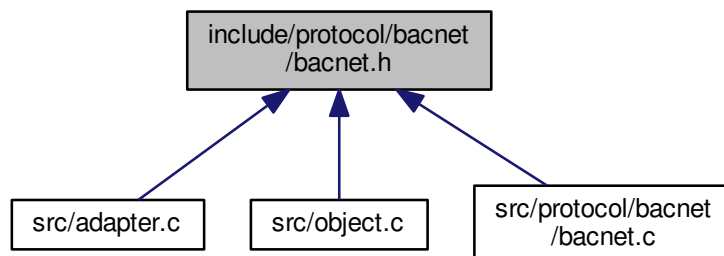
## 7.13 include/protocol/bacnet/bacnet.h File Reference

```
#include "enum.h"
```

Include dependency graph for bacnet.h:



This graph shows which files directly or indirectly include this file:



## Data Structures

- struct [bacnet](#)

*bacnet bacnet interface struct*

## Typedefs

- typedef struct [bacnet](#) [bacnet\\_port\\_handle\\_t](#)

*bacnet bacnet interface struct*

## Functions

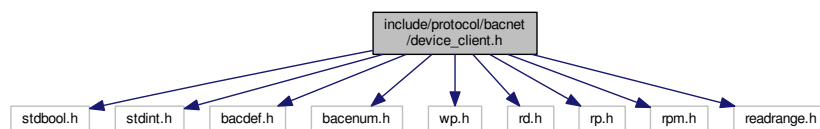
- void \* [bacnet\\_work\\_thread\\_function](#) (void \*arg)

*bacnet\_work\_thread\_function* The bacnet work thread

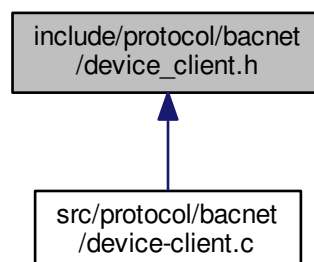
## 7.14 include/protocol/bacnet/device\_client.h File Reference

```
#include <stdbool.h>
#include <stdint.h>
#include "bacdef.h"
#include "bacenum.h"
#include "wp.h"
#include "rd.h"
#include "rp.h"
#include "rpm.h"
#include "readrange.h"
```

Include dependency graph for device\_client.h:



This graph shows which files directly or indirectly include this file:



## Data Structures

- struct [object\\_functions](#)
- struct [commonBacObj\\_s](#)
- struct [devObj\\_s](#)

## Macros

- #define [MAX\\_DEV\\_NAME\\_LEN](#) 32
- #define [MAX\\_DEV\\_LOC\\_LEN](#) 64
- #define [MAX\\_DEV\\_MOD\\_LEN](#) 32
- #define [MAX\\_DEV\\_VER\\_LEN](#) 16
- #define [MAX\\_DEV\\_DESC\\_LEN](#) 64

## Typedefs

- typedef void(\* [object\\_init\\_function](#) )(void)
- typedef unsigned(\* [object\\_count\\_function](#) )(void)
- typedef uint32\_t(\* [object\\_index\\_to\\_instance\\_function](#) )(unsigned index)
- typedef bool(\* [object\\_name\\_function](#) )(uint32\_t object\_instance, BACNET\_CHARACTER\_STRING \*object\_name)
- typedef bool(\* [object\\_valid\\_instance\\_function](#) )(uint32\_t object\_instance)
- typedef unsigned(\* [object\\_iterate\\_function](#) )(unsigned current\_index)
- typedef bool(\* [object\\_value\\_list\\_function](#) )(uint32\_t object\_instance, BACNET\_PROPERTY\_VALUE \*value\_list)
- typedef bool(\* [object\\_cov\\_function](#) )(uint32\_t object\_instance)
- typedef void(\* [object\\_cov\\_clear\\_function](#) )(uint32\_t object\_instance)
- typedef void(\* [object\\_intrinsic\\_reporting\\_function](#) )(uint32\_t object\_instance)
- typedef struct [object\\_functions](#) [object\\_functions\\_t](#)
- typedef struct [commonBacObj\\_s](#) [COMMON\\_BAC\\_OBJECT](#)
- typedef struct [devObj\\_s](#) [DEVICE\\_OBJECT\\_DATA](#)

## Functions

- void [Device\\_Init](#) ([object\\_functions\\_t](#) \*object\_table)
- bool [Device\\_Reinitialize](#) (BACNET\_REINITIALIZE\_DEVICE\_DATA \*rd\_data)
- BACNET\_REINITIALIZED\_STATE [Device\\_Reinitialized\\_State](#) (void)
- rr\_info\_function [Device\\_Objects\\_RR\\_Info](#) (BACNET\_OBJECT\_TYPE object\_type)
- void [Device\\_getCurrentDateTime](#) (BACNET\_DATE\_TIME \*DateTime)
- void [Device\\_Property\\_Lists](#) (const int \*\*pRequired, const int \*\*pOptional, const int \*\*pProprietary)
- void [Device\\_Objects\\_Property\\_List](#) (BACNET\_OBJECT\_TYPE object\_type, struct special\_property\_list\_t \*pPropertyList)
- bool [Device\\_Encode\\_Value\\_List](#) (BACNET\_OBJECT\_TYPE object\_type, uint32\_t object\_instance, BACNET\_PROPERTY\_VALUE \*value\_list)
- bool [Device\\_Value\\_List\\_Supported](#) (BACNET\_OBJECT\_TYPE object\_type)
- bool [Device\\_COV](#) (BACNET\_OBJECT\_TYPE object\_type, uint32\_t object\_instance)
- void [Device\\_COV\\_Clear](#) (BACNET\_OBJECT\_TYPE object\_type, uint32\_t object\_instance)
- uint32\_t [Device\\_Object\\_Instance\\_Number](#) (void)
- bool [Device\\_Set\\_Object\\_Instance\\_Number](#) (uint32\_t object\_id)
- bool [Device\\_Valid\\_Object\\_Instance\\_Number](#) (uint32\_t object\_id)
- unsigned [Device\\_Object\\_List\\_Count](#) (void)
- bool [Device\\_Object\\_List\\_Identifier](#) (unsigned array\_index, int \*object\_type, uint32\_t \*instance)
- unsigned [Device\\_Count](#) (void)

- uint32\_t [Device\\_Index\\_To\\_Instance](#) (unsigned index)
- bool [Device\\_Object\\_Name](#) (uint32\_t object\_instance, BACNET\_CHARACTER\_STRING \*object\_name)
- bool [Device\\_Set\\_Object\\_Name](#) (BACNET\_CHARACTER\_STRING \*object\_name)
- bool [Device\\_Object\\_Name\\_Copy](#) (BACNET\_OBJECT\_TYPE object\_type, uint32\_t object\_instance, BACNET\_CHARACTER\_STRING \*object\_name)
- BACNET\_DEVICE\_STATUS [Device\\_System\\_Status](#) (void)
- int [Device\\_Set\\_System\\_Status](#) (BACNET\_DEVICE\_STATUS status, bool local)
- const char \* [Device\\_Vendor\\_Name](#) (void)
- uint16\_t [Device\\_Vendor\\_Identifier](#) (void)
- void [Device\\_Set\\_Vendor\\_Identifier](#) (uint16\_t vendor\_id)
- const char \* [Device\\_Model\\_Name](#) (void)
- bool [Device\\_Set\\_Model\\_Name](#) (const char \*name, size\_t length)
- const char \* [Device\\_Firmware\\_Revision](#) (void)
- const char \* [Device\\_Application\\_Software\\_Version](#) (void)
- bool [Device\\_Set\\_Application\\_Software\\_Version](#) (const char \*name, size\_t length)
- const char \* [Device\\_Description](#) (void)
- bool [Device\\_Set\\_Description](#) (const char \*name, size\_t length)
- const char \* [Device\\_Location](#) (void)
- bool [Device\\_Set\\_Location](#) (const char \*name, size\_t length)
- uint8\_t [Device\\_Protocol\\_Version](#) (void)
- uint8\_t [Device\\_Protocol\\_Revision](#) (void)
- BACNET\_SEGMENTATION [Device\\_Segmentation\\_Supported](#) (void)
- uint32\_t [Device\\_Database\\_Revision](#) (void)
- void [Device\\_Set\\_Database\\_Revision](#) (uint32\_t revision)
- void [Device\\_Inc\\_Database\\_Revision](#) (void)
- bool [Device\\_Valid\\_Object\\_Name](#) (BACNET\_CHARACTER\_STRING \*object\_name, int \*object\_type, uint32\_t \*object\_instance)
- bool [Device\\_Valid\\_Object\\_Id](#) (int object\_type, uint32\_t object\_instance)
- int [Device\\_Read\\_Property](#) (BACNET\_READ\_PROPERTY\_DATA \*rpdata)
- bool [Device\\_Write\\_Property](#) (BACNET\_WRITE\_PROPERTY\_DATA \*wp\_data)
- bool [DeviceGetRRInfo](#) (BACNET\_READ\_RANGE\_DATA \*pRequest, RR\_PROP\_INFO \*pInfo)
- int [Device\\_Read\\_Property\\_Local](#) (BACNET\_READ\_PROPERTY\_DATA \*rpdata)
- bool [Device\\_Write\\_Property\\_Local](#) (BACNET\_WRITE\_PROPERTY\_DATA \*wp\_data)
- void [Routing\\_Device\\_Init](#) (uint32\_t first\_object\_instance)
- uint16\_t [Add\\_Routed\\_Device](#) (uint32\_t Object\_Instance, BACNET\_CHARACTER\_STRING \*Object\_Name, const char \*Description)
- BACNET\_OBJECT\_DATA \* [Get\\_Routed\\_Device\\_Object](#) (int idx)
- BACNET\_ADDRESS \* [Get\\_Routed\\_Device\\_Address](#) (int idx)
- void [routed\\_get\\_my\\_address](#) (BACNET\_ADDRESS \*my\_address)
- bool [Routed\\_Device\\_Address\\_Lookup](#) (int idx, uint8\_t address\_len, uint8\_t \*mac\_address)
- bool [Routed\\_Device\\_GetNext](#) (BACNET\_ADDRESS \*dest, int \*DNET\_list, int \*cursor)
- bool [Routed\\_Device\\_Is\\_Valid\\_Network](#) (uint16\_t dest\_net, int \*DNET\_list)
- uint32\_t [Routed\\_Device\\_Index\\_To\\_Instance](#) (unsigned index)
- bool [Routed\\_Device\\_Valid\\_Object\\_Instance\\_Number](#) (uint32\_t object\_id)
- bool [Routed\\_Device\\_Name](#) (uint32\_t object\_instance, BACNET\_CHARACTER\_STRING \*object\_name)
- uint32\_t [Routed\\_Device\\_Object\\_Instance\\_Number](#) (void)
- bool [Routed\\_Device\\_Set\\_Object\\_Instance\\_Number](#) (uint32\_t object\_id)
- bool [Routed\\_Device\\_Set\\_Object\\_Name](#) (uint8\_t encoding, const char \*value, size\_t length)
- bool [Routed\\_Device\\_Set\\_Description](#) (const char \*name, size\_t length)
- void [Routed\\_Device\\_Inc\\_Database\\_Revision](#) (void)
- int [Routed\\_Device\\_Service\\_Approval](#) (BACNET\_CONFIRMED\_SERVICE service, int service\_argument, uint8\_t \*apdu\_buff, uint8\_t invoke\_id)

### 7.14.1 Detailed Description

Defines functions for handling all BACnet objects belonging to a BACnet device, as well as Device-specific properties.

Definition in file [device\\_client.h](#).

### 7.14.2 Macro Definition Documentation

#### 7.14.2.1 `#define MAX_DEV_DESC_LEN 64`

Definition at line 174 of file [device\\_client.h](#).

#### 7.14.2.2 `#define MAX_DEV_LOC_LEN 64`

Definition at line 171 of file [device\\_client.h](#).

#### 7.14.2.3 `#define MAX_DEV_MOD_LEN 32`

Definition at line 172 of file [device\\_client.h](#).

#### 7.14.2.4 `#define MAX_DEV_NAME_LEN 32`

Definition at line 170 of file [device\\_client.h](#).

#### 7.14.2.5 `#define MAX_DEV_VER_LEN 16`

Definition at line 173 of file [device\\_client.h](#).

### 7.14.3 Typedef Documentation

#### 7.14.3.1 `typedef struct commonBacObj_s COMMON_BAC_OBJECT`

Structure to define the Object Properties common to all Objects.

#### 7.14.3.2 `typedef struct devObj_s DEVICE_OBJECT_DATA`

Structure to define the Properties of Device Objects which distinguish one instance from another. This structure only defines fields for properties that are unique to a given Device object. The rest may be fixed in [device.c](#) or hard-coded into the read-property encoding. This may be useful for implementations which manage multiple Devices, eg, a Gateway.

#### 7.14.3.3 `typedef unsigned(* object_count_function)(void)`

Counts the number of objects of this type.

#### Returns

Count of implemented objects of this type.

Definition at line 54 of file [device\\_client.h](#).

7.14.3.4 `typedef void( * object_cov_clear_function)(uint32_t object_instance)`

Look in the table of objects for this instance to clear the changed flag.



**Parameters**

|           |            |                                         |
|-----------|------------|-----------------------------------------|
| <i>in</i> | <i>The</i> | object instance number to be looked up. |
|-----------|------------|-----------------------------------------|

Definition at line 130 of file device\_client.h.

**7.14.3.5 typedef bool( \* object\_cov\_function)(uint32\_t object\_instance)**

Look in the table of objects for this instance to see if value changed.

**Parameters**

|           |            |                                         |
|-----------|------------|-----------------------------------------|
| <i>in</i> | <i>The</i> | object instance number to be looked up. |
|-----------|------------|-----------------------------------------|

**Returns**

True if the object instance has changed.

Definition at line 122 of file device\_client.h.

**7.14.3.6 typedef struct object\_functions object\_functions\_t**

Defines the group of object helper functions for any supported Object.

Each Object must provide some implementation of each of these helpers in order to properly support the handlers. Eg, the ReadProperty handler handler\_read\_property() relies on the instance of Object\_Read\_Property for each Object type, or configure the function as NULL. In both appearance and operation, this group of functions acts like they are member functions of a C++ Object base class.

**7.14.3.7 typedef uint32\_t( \* object\_index\_to\_instance\_function)(unsigned index)**

Maps an object index position to its corresponding BACnet object instance number.

**Parameters**

|              |                                                                    |
|--------------|--------------------------------------------------------------------|
| <i>index</i> | [in] The index of the object, in the array of objects of its type. |
|--------------|--------------------------------------------------------------------|

**Returns**

The BACnet object instance number to be used in a BACNET\_OBJECT\_ID.

Definition at line 64 of file device\_client.h.

**7.14.3.8 typedef void( \* object\_init\_function)(void)**

Called so a BACnet object can perform any necessary initialization.

Definition at line 46 of file device\_client.h.

**7.14.3.9 typedef void( \* object\_intrinsic\_reporting\_function)(uint32\_t object\_instance)**

Intrinsic Reporting functionality.

**Parameters**

|           |               |           |
|-----------|---------------|-----------|
| <i>in</i> | <i>Object</i> | instance. |
|-----------|---------------|-----------|

Definition at line 138 of file device\_client.h.

**7.14.3.10 typedef unsigned( \* object\_iterate\_function)(unsigned current\_index)**

Helper function to step through an array of objects and find either the first one or the next one of a given type. Used to step through an array of objects which is not necessarily contiguous for each type i.e. the index for the 'n'th object of a given type is not necessarily 'n'.

**Parameters**

|           |            |                                                                                  |
|-----------|------------|----------------------------------------------------------------------------------|
| <i>in</i> | <i>The</i> | index of the current object or a value of ~0 to indicate start at the beginning. |
|-----------|------------|----------------------------------------------------------------------------------|

**Returns**

The index of the next object of the required type or ~0 (all bits == 1) to indicate no more objects found.

Definition at line 102 of file device\_client.h.

**7.14.3.11 typedef bool( \* object\_name\_function)(uint32\_t object\_instance, BACNET\_CHARACTER\_STRING \*object\_name)**

Provides the BACnet Object\_Name for a given object instance of this type.

**Parameters**

|                        |          |                                                                                                                      |
|------------------------|----------|----------------------------------------------------------------------------------------------------------------------|
| <i>object_instance</i> | [in]     | The object instance number to be looked up.                                                                          |
| <i>object_name</i>     | [in,out] | Pointer to a character_string structure that will hold a copy of the object name if this is a valid object_instance. |

**Returns**

True if the object\_instance is valid and object\_name has been filled with a copy of the Object's name.

Definition at line 77 of file device\_client.h.

**7.14.3.12 typedef bool( \* object\_valid\_instance\_function)(uint32\_t object\_instance)**

Look in the table of objects of this type, and see if this is a valid instance number.

**Parameters**

|           |            |                                         |
|-----------|------------|-----------------------------------------|
| <i>in</i> | <i>The</i> | object instance number to be looked up. |
|-----------|------------|-----------------------------------------|

**Returns**

True if the object instance refers to a valid object of this type.

Definition at line 88 of file device\_client.h.

**7.14.3.13 typedef bool( \* object\_value\_list\_function)(uint32\_t object\_instance, BACNET\_PROPERTY\_VALUE \*value\_list)**

Look in the table of objects of this type, and get the COV Value List.

**Parameters**

|     |            |                                         |
|-----|------------|-----------------------------------------|
| in  | <i>The</i> | object instance number to be looked up. |
| out | <i>The</i> | value list                              |

**Returns**

True if the object instance supports this feature, and has changed.

Definition at line 112 of file device\_client.h.

**7.14.4 Function Documentation**

**7.14.4.1** `uint16_t Add_Routed_Device ( uint32_t Object_Instance, BACNET_CHARACTER_STRING * Object_Name, const char * Description )`

**7.14.4.2** `const char* Device_Application_Software_Version ( void )`

Definition at line 362 of file device-client.c.

**7.14.4.3** `unsigned Device_Count ( void )`

Definition at line 163 of file device-client.c.

**7.14.4.4** `bool Device_COV ( BACNET_OBJECT_TYPE object_type, uint32_t object_instance )`

**7.14.4.5** `void Device_COV_Clear ( BACNET_OBJECT_TYPE object_type, uint32_t object_instance )`

**7.14.4.6** `uint32_t Device_Database_Revision ( void )`

Definition at line 443 of file device-client.c.

**7.14.4.7** `const char* Device_Description ( void )`

Definition at line 383 of file device-client.c.

**7.14.4.8** `bool Device_Encode_Value_List ( BACNET_OBJECT_TYPE object_type, uint32_t object_instance, BACNET_PROPERTY_VALUE * value_list )`

**7.14.4.9** `const char* Device_Firmware_Revision ( void )`

Definition at line 356 of file device-client.c.

**7.14.4.10** `void Device_getCurrentDateTime ( BACNET_DATE_TIME * DateTime )`

**7.14.4.11** `void Device_Inc_Database_Revision ( void )`

Definition at line 460 of file device-client.c.

Here is the caller graph for this function:



#### 7.14.4.12 uint32\_t Device\_Index\_To\_Instance ( unsigned index )

Definition at line 169 of file device-client.c.

#### 7.14.4.13 void Device\_Init ( object\_functions\_t \* object\_table )

Initialize the Device Object. Initialize the group of object helper functions for any supported Object. Initialize each of the Device Object child Object instances.

##### Parameters

|                     |                                                                                                                                                                                     |
|---------------------|-------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| <i>object_table</i> | [in,out] array of structure with object functions. Each Child Object must provide some implementation of each of these functions in order to properly support the default handlers. |
|---------------------|-------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|

Definition at line 895 of file device-client.c.

Here is the caller graph for this function:



#### 7.14.4.14 const char\* Device\_Location ( void )

Definition at line 404 of file device-client.c.

#### 7.14.4.15 const char\* Device\_Model\_Name ( void )

Definition at line 335 of file device-client.c.

#### 7.14.4.16 uint32\_t Device\_Object\_Instance\_Number ( void )

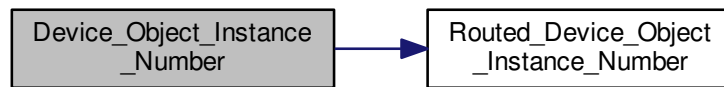
Return the Object Instance number for our (single) Device Object. This is a key function, widely invoked by the handler code, since it provides "our" (ie, local) address.

##### Returns

The Instance number used in the BACNET\_OBJECT\_ID for the Device.

Definition at line 184 of file device-client.c.

Here is the call graph for this function:



#### 7.14.4.17 unsigned Device\_Object\_List\_Count ( void )

Get the total count of objects supported by this Device Object.

##### Note

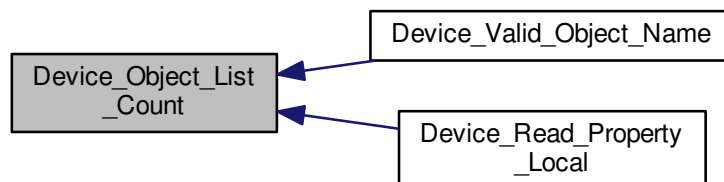
Since many network clients depend on the object list for discovery, it must be consistent!

##### Returns

The count of objects, for all supported Object types.

Definition at line 471 of file device-client.c.

Here is the caller graph for this function:



#### 7.14.4.18 bool Device\_Object\_List\_Identifier ( unsigned array\_index, int \* object\_type, uint32\_t \* instance )

Lookup the Object at the given array index in the Device's Object List. Even though we don't keep a single linear array of objects in the Device, this method acts as though we do and works through a virtual, concatenated array of all of our object type arrays.

##### Parameters

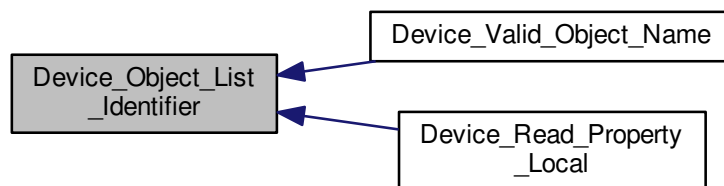
|                    |                                               |
|--------------------|-----------------------------------------------|
| <i>array_index</i> | [in] The desired array index (1 to N)         |
| <i>object_type</i> | [out] The object's type, if found.            |
| <i>instance</i>    | [out] The object's instance number, if found. |

**Returns**

True if found, else false.

Definition at line 499 of file device-client.c.

Here is the caller graph for this function:



7.14.4.19 `bool Device_Object_Name ( uint32_t object_instance, BACNET_CHARACTER_STRING * object_name )`

Definition at line 215 of file device-client.c.

7.14.4.20 `bool Device_Object_Name_Copy ( BACNET_OBJECT_TYPE object_type, uint32_t object_instance, BACNET_CHARACTER_STRING * object_name )`

Copy a child object's object\_name value, given its ID.

**Parameters**

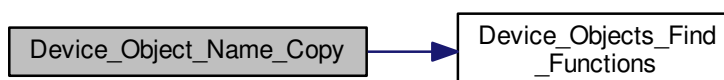
|                        |                                                      |
|------------------------|------------------------------------------------------|
| <i>object_type</i>     | [in] The BACNET_OBJECT_TYPE of the child Object.     |
| <i>object_instance</i> | [in] The object instance number of the child Object. |
| <i>object_name</i>     | [out] The Object Name found for this child Object.   |

**Returns**

True on success or else False if not found.

Definition at line 620 of file device-client.c.

Here is the call graph for this function:



7.14.4.21 void Device\_Objects\_Property\_List ( BACNET\_OBJECT\_TYPE *object\_type*, struct special\_property\_list\_t \* *pPropertyList* )

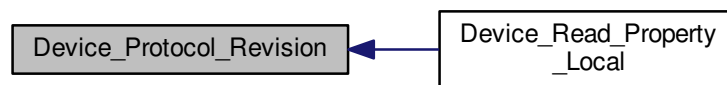
7.14.4.22 rr\_info\_function Device\_Objects\_RR\_Info ( BACNET\_OBJECT\_TYPE *object\_type* )

7.14.4.23 void Device\_Property\_Lists ( const int \*\* *pRequired*, const int \*\* *pOptional*, const int \*\* *pProprietary* )

7.14.4.24 uint8\_t Device\_Protocol\_Revision ( void )

Definition at line 431 of file device-client.c.

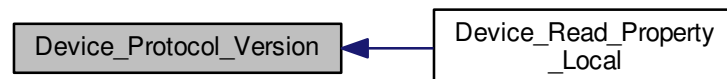
Here is the caller graph for this function:



7.14.4.25 uint8\_t Device\_Protocol\_Version ( void )

Definition at line 425 of file device-client.c.

Here is the caller graph for this function:



7.14.4.26 int Device\_Read\_Property ( BACNET\_READ\_PROPERTY\_DATA \* *rpdata* )

Looks up the requested Object and Property, and encodes its Value in an APDU.

If the Object or Property can't be found, sets the error class and code.

Parameters

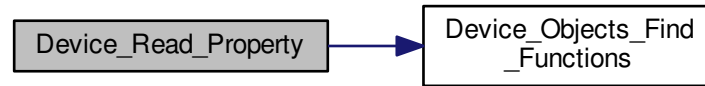
|               |                                                                                                    |
|---------------|----------------------------------------------------------------------------------------------------|
| <i>rpdata</i> | [in,out] Structure with the desired Object and Property info on entry, and APDU message on return. |
|---------------|----------------------------------------------------------------------------------------------------|

**Returns**

The length of the APDU on success, else BACNET\_STATUS\_ERROR

Definition at line 859 of file device-client.c.

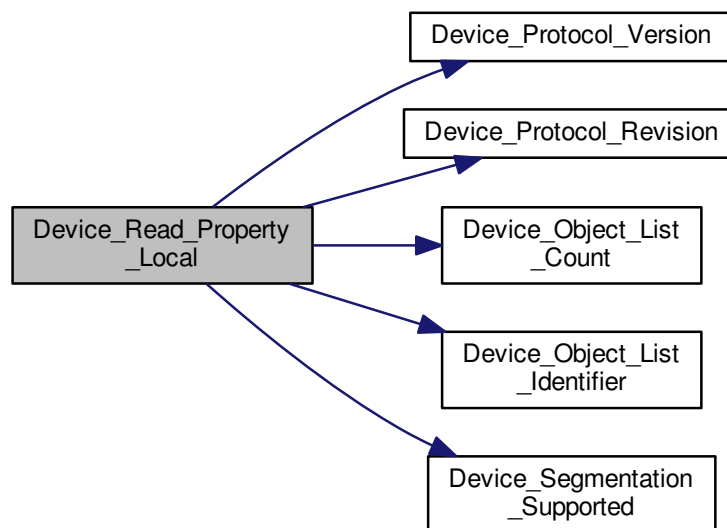
Here is the call graph for this function:



**7.14.4.27** int Device\_Read\_Property\_Local ( BACNET\_READ\_PROPERTY\_DATA \* *rpdata* )

Definition at line 638 of file device-client.c.

Here is the call graph for this function:



**7.14.4.28** bool Device\_Reinitialize ( BACNET\_REINITIALIZE\_DEVICE\_DATA \* *rd\_data* )

**7.14.4.29** BACNET\_REINITIALIZED\_STATE Device\_Reinitialized\_State ( void )

**7.14.4.30** BACNET\_SEGMENTATION Device\_Segmentation\_Supported ( void )

Definition at line 437 of file device-client.c.



Here is the caller graph for this function:



**7.14.4.31** `bool Device_Set_Application_Software_Version ( const char * name, size_t length )`

Definition at line 368 of file device-client.c.

**7.14.4.32** `void Device_Set_Database_Revision ( uint32_t revision )`

Definition at line 449 of file device-client.c.

**7.14.4.33** `bool Device_Set_Description ( const char * name, size_t length )`

Definition at line 389 of file device-client.c.

**7.14.4.34** `bool Device_Set_Location ( const char * name, size_t length )`

Definition at line 410 of file device-client.c.

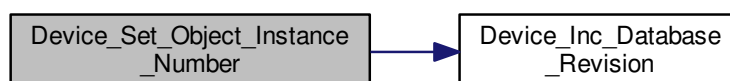
**7.14.4.35** `bool Device_Set_Model_Name ( const char * name, size_t length )`

Definition at line 341 of file device-client.c.

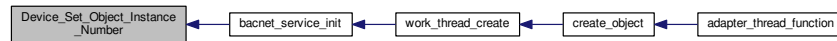
**7.14.4.36** `bool Device_Set_Object_Instance_Number ( uint32_t object_id )`

Definition at line 194 of file device-client.c.

Here is the call graph for this function:



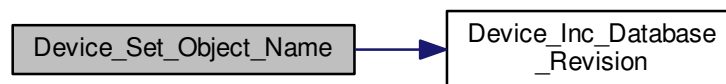
Here is the caller graph for this function:



#### 7.14.4.37 bool Device\_Set\_Object\_Name ( BACNET\_CHARACTER\_STRING \* *object\_name* )

Definition at line 228 of file device-client.c.

Here is the call graph for this function:



#### 7.14.4.38 int Device\_Set\_System\_Status ( BACNET\_DEVICE\_STATUS *status*, bool *local* )

Definition at line 248 of file device-client.c.

#### 7.14.4.39 void Device\_Set\_Vendor\_Identifier ( uint16\_t *vendor\_id* )

Definition at line 329 of file device-client.c.

#### 7.14.4.40 BACNET\_DEVICE\_STATUS Device\_System\_Status ( void )

Definition at line 242 of file device-client.c.

#### 7.14.4.41 bool Device\_Valid\_Object\_Id ( int *object\_type*, uint32\_t *object\_instance* )

Determine if we have an object of this type and instance number.

##### Parameters

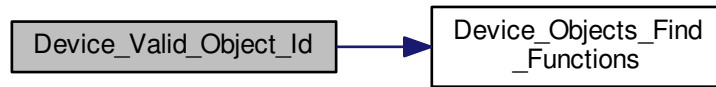
|                        |                                                  |
|------------------------|--------------------------------------------------|
| <i>object_type</i>     | [in] The desired BACNET_OBJECT_TYPE              |
| <i>object_instance</i> | [in] The object instance number to be looked up. |

##### Returns

True if found, else False if no such Object in this device.

Definition at line 599 of file device-client.c.

Here is the call graph for this function:



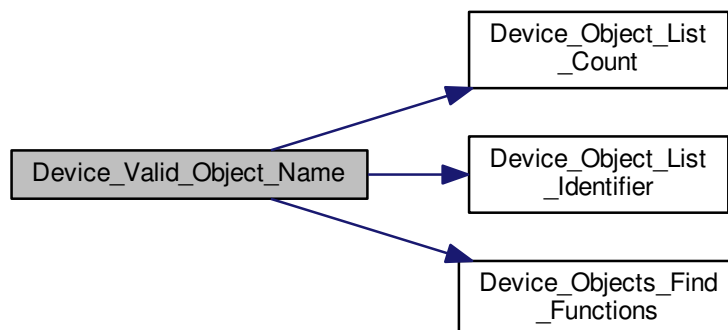
7.14.4.42 `bool Device_Valid_Object_Instance_Number ( uint32_t object_id )`

Definition at line 209 of file device-client.c.

7.14.4.43 `bool Device_Valid_Object_Name ( BACNET_CHARACTER_STRING * object_name, int * object_type, uint32_t * object_instance )`

Definition at line 558 of file device-client.c.

Here is the call graph for this function:



7.14.4.44 `bool Device_Value_List_Supported ( BACNET_OBJECT_TYPE object_type )`

7.14.4.45 `uint16_t Device_Vendor_Identifier ( void )`

Returns the Vendor ID for this Device. See the assignments at <http://www.bacnet.org/VendorID/BACnet%20Vendor%20IDs.htm>

**Returns**

The Vendor ID of this Device.

Definition at line 323 of file device-client.c.

7.14.4.46 `const char* Device_Vendor_Name ( void )`

Definition at line 313 of file device-client.c.

7.14.4.47 `bool Device_Write_Property ( BACNET_WRITE_PROPERTY_DATA * wp_data )`

7.14.4.48 `bool Device_Write_Property_Local ( BACNET_WRITE_PROPERTY_DATA * wp_data )`

7.14.4.49 `bool DeviceGetRRInfo ( BACNET_READ_RANGE_DATA * pRequest, RR_PROP_INFO * pInfo )`

7.14.4.50 `BACNET_ADDRESS* Get_Routed_Device_Address ( int idx )`

7.14.4.51 `DEVICE_OBJECT_DATA* Get_Routed_Device_Object ( int idx )`

7.14.4.52 `bool Routed_Device_Address_Lookup ( int idx, uint8_t address_len, uint8_t * mac_address )`

7.14.4.53 `bool Routed_Device_GetNext ( BACNET_ADDRESS * dest, int * DNET_list, int * cursor )`

7.14.4.54 `void Routed_Device_Inc_Database_Revision ( void )`

7.14.4.55 `uint32_t Routed_Device_Index_To_Instance ( unsigned index )`

7.14.4.56 `bool Routed_Device_Is_Valid_Network ( uint16_t dest_net, int * DNET_list )`

7.14.4.57 `bool Routed_Device_Name ( uint32_t object_instance, BACNET_CHARACTER_STRING * object_name )`

7.14.4.58 `uint32_t Routed_Device_Object_Instance_Number ( void )`

Here is the caller graph for this function:



7.14.4.59 `int Routed_Device_Service_Approval ( BACNET_CONFIRMED_SERVICE service, int service_argument, uint8_t * apdu_buff, uint8_t invoke_id )`

7.14.4.60 `bool Routed_Device_Set_Description ( const char * name, size_t length )`

7.14.4.61 `bool Routed_Device_Set_Object_Instance_Number ( uint32_t object_id )`

7.14.4.62 `bool Routed_Device_Set_Object_Name ( uint8_t encoding, const char * value, size_t length )`

7.14.4.63 `bool Routed_Device_Valid_Object_Instance_Number ( uint32_t object_id )`

7.14.4.64 `void routed_get_my_address ( BACNET_ADDRESS * my_address )`

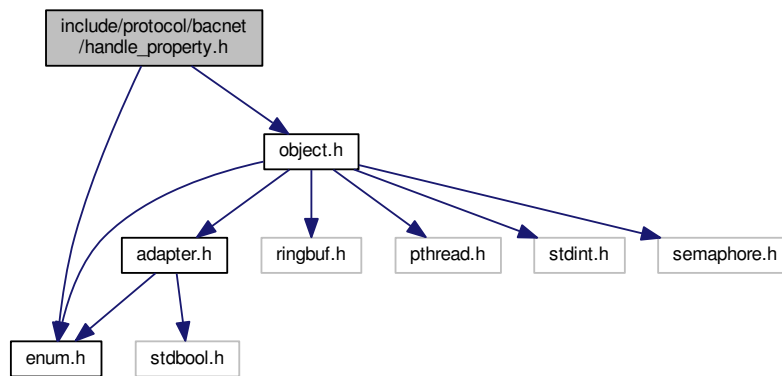
7.14.4.65 void Routing\_Device\_Init ( uint32\_t first\_object\_instance )

## 7.15 include/protocol/bacnet/handle\_property.h File Reference

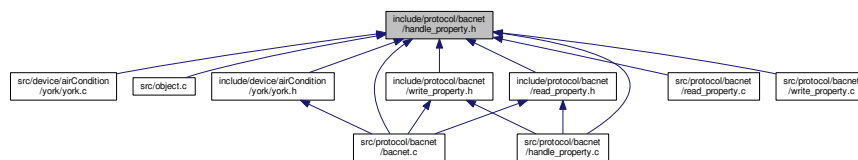
```
#include "enum.h"
```

```
#include "object.h"
```

Include dependency graph for handle\_property.h:



This graph shows which files directly or indirectly include this file:



## Data Structures

- struct `bacnet_write_args_t`  
*bacnet write arg struct*
- struct `bacnet_read_args_t`  
*bacnet read property struct*

## Macros

- `#define BACNET_READ_ARGS_OBJECT_MAX 10`

## Functions

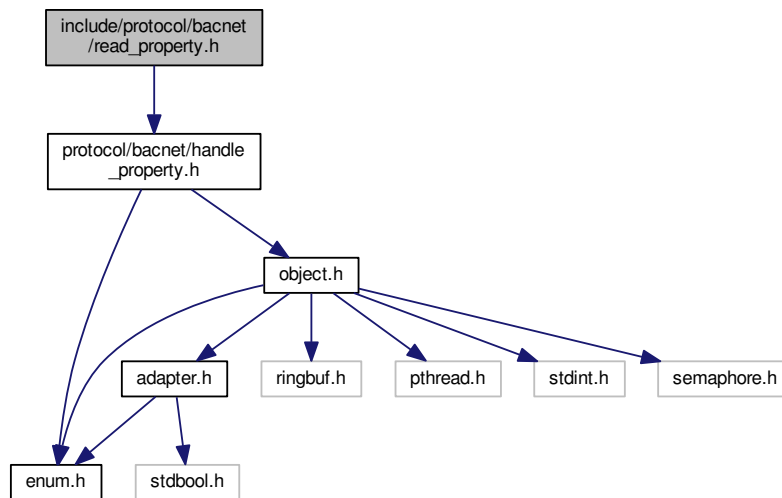
- int `get_air_condition_bacnet_write_args` (`bacnet_write_args_t` \*args, unsigned int device\_id, int command)  
*get\_air\_condition\_bacnet\_write\_args bacnet write args*
- int `get_air_condition_bacnet_read_args` (`bacnet_read_args_t` \*args, unsigned int device\_id)

- get\_air\_condition\_bacnet\_read\_args bacnet read args*
- int `bacnet_service_init` (`object_management_t` \*adapter)
- bacnet\_service\_init bacnet physics initialize.*

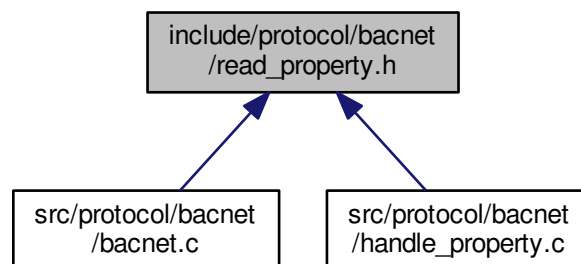
## 7.16 include/protocol/bacnet/read\_property.h File Reference

```
#include "protocol/bacnet/handle_property.h"
```

Include dependency graph for read\_property.h:



This graph shows which files directly or indirectly include this file:



## Functions

- int `bacnet_read_property` (`bacnet_read_args_t` \*args)

### 7.16.1 Function Documentation

#### 7.16.1.1 `int bacnet_read_property ( bacnet_read_args_t * args )`

Definition at line 152 of file `read_property.c`.

Here is the call graph for this function:



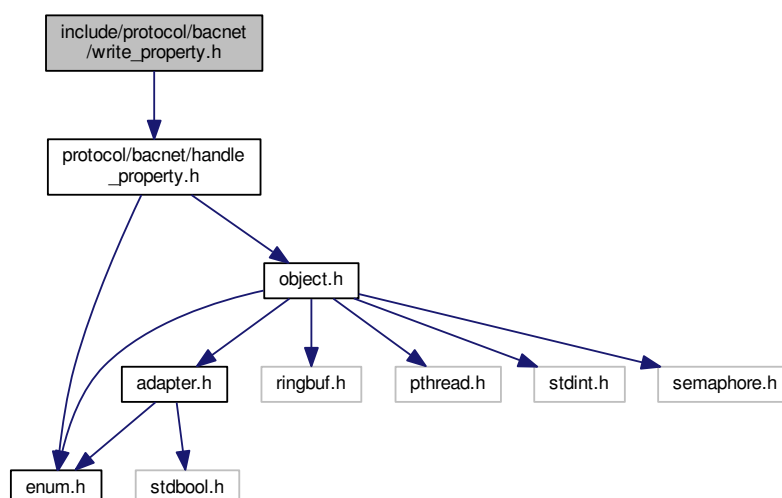
Here is the caller graph for this function:



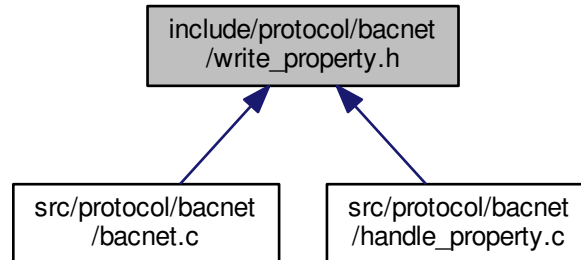
## 7.17 include/protocol/bacnet/write\_property.h File Reference

```
#include "protocol/bacnet/handle_property.h"
```

Include dependency graph for `write_property.h`:



This graph shows which files directly or indirectly include this file:



## Functions

- int `bacnet_write_property` (const `bacnet_write_args_t` \*args)

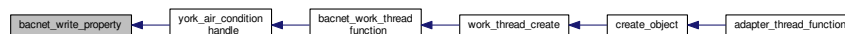
### 7.17.1 Function Documentation

#### 7.17.1.1 int `bacnet_write_property` ( const `bacnet_write_args_t` \* args )

500ms\*4, 2s

Definition at line 63 of file `write_property.c`.

Here is the caller graph for this function:

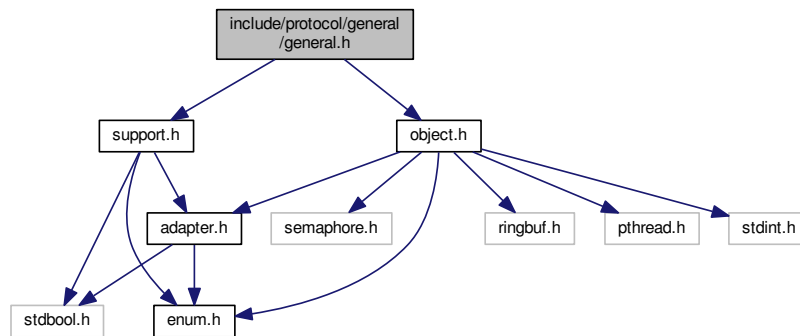


## 7.18 include/protocol/general/general.h File Reference

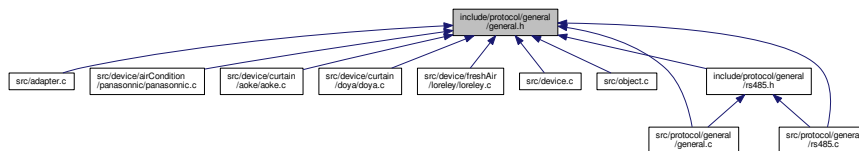
```
#include "support.h"
#include "object.h"
```



Include dependency graph for general.h:



This graph shows which files directly or indirectly include this file:



## Data Structures

- struct [mstp\\_port\\_handle](#)  
*mstp\_port\_handle* general protocol(user defined)

## Typedefs

- typedef struct [mstp\\_port\\_handle](#) [mstp\\_port\\_handle\\_t](#)  
*mstp\_port\_handle* general protocol(user defined)

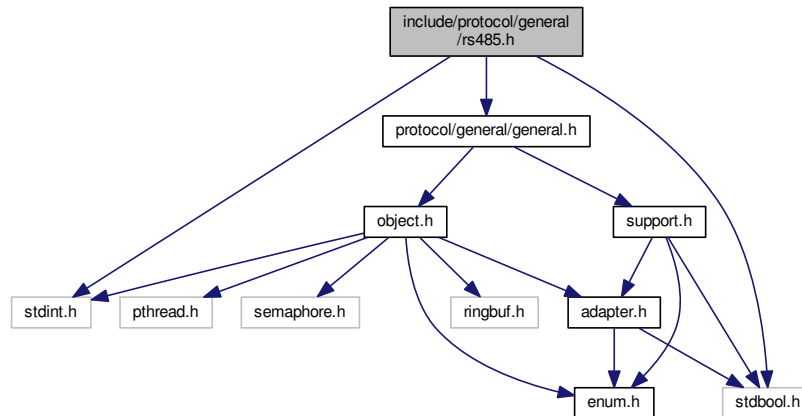
## Functions

- int [general\\_service\\_init](#) ([object\\_management\\_t](#) \*object)  
*general\_service\_init* The general protocol(user defined) initialize
- void \* [general\\_work\\_thread\\_function](#) (void \*arg)  
*general\_work\_thread\_function* The general work thread function

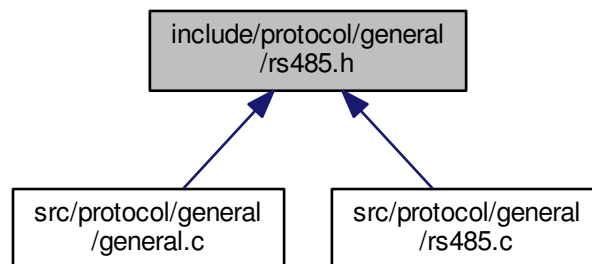
## 7.19 include/protocol/general/rs485.h File Reference

```
#include <stdint.h>
#include <stdbool.h>
#include "protocol/general/general.h"
```

Include dependency graph for rs485.h:



This graph shows which files directly or indirectly include this file:



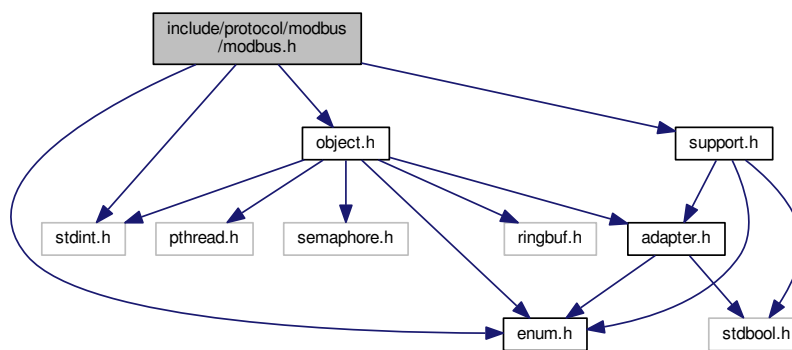
## Functions

- void `rs485_set_interface` (char \*ifname)  
*RS485\_Set\_Interface rs485 interface name.*
- const char \* `rs485_get_interface` (void)  
*RS485\_Get\_Interface get the rs485 interface name.*
- void `rs485_initialize` (void)  
*RS485\_Initialize.*
- int `rs485_send_handle_frame` (volatile struct `mstp_port_handle` \*mstp\_port)  
*rs485\_send\_handle\_frame rs485 bus package a send frame, and send the package to bus.*
- int `rs485_rcv_handle_frame` (volatile struct `mstp_port_handle` \*mstp\_port)  
*rs485\_rcv\_handle\_frame rs485 bus receive a frame, and call process these data.*
- bool `rs485_set_baud_rate` (uint32\_t baud)  
*RS485\_Set\_Baud\_Rate set the rs485 buad rate.*
- void `rs485_cleanup` (void)  
*RS485\_Cleanup The rs485 initailize fail, have clean.*

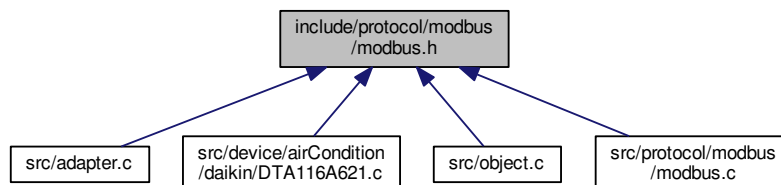
## 7.20 include/rs485.h File Reference

### 7.21 include/protocol/modbus/modbus.h File Reference

```
#include <stdint.h>
#include "enum.h"
#include "object.h"
#include "support.h"
Include dependency graph for modbus.h:
```



This graph shows which files directly or indirectly include this file:



## Data Structures

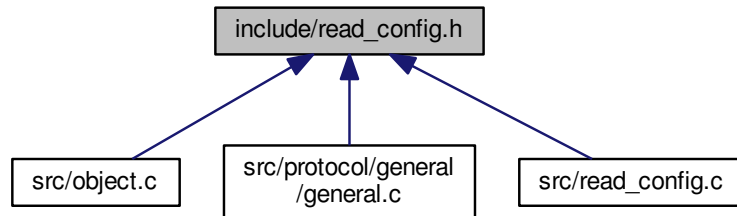
- struct `modbus_port_handle_t`  
The modbus port interface.

## Functions

- void \* `modbus_work_thread_function` (void \*arg)  
`modbus_work_thread_function` The modbus work thread
- int `modbus_service_init` (`object_management_t` \*object)  
`modbus_service_init` The modbus interface initialize.
- void `modbus_service_deinit` (`object_management_t` \*object)  
`modbus_service_deinit` clean the modbus service, The haved called by thread have exit.

## 7.22 include/read\_config.h File Reference

This graph shows which files directly or indirectly include this file:



### Variables

- int [glb\\_config\\_general\\_work\\_queue\\_depth](#)
- int [glb\\_config\\_bacnet\\_work\\_queue\\_depth](#)
- int [glb\\_config\\_modbus\\_work\\_queue\\_depth](#)
- int [glb\\_config\\_adapter\\_message\\_queue\\_depth](#)
- int [glb\\_config\\_general\\_work\\_package\\_mtu](#)

### 7.22.1 Variable Documentation

#### 7.22.1.1 int [glb\\_config\\_adapter\\_message\\_queue\\_depth](#)

Definition at line 32 of file [read\\_config.c](#).

#### 7.22.1.2 int [glb\\_config\\_bacnet\\_work\\_queue\\_depth](#)

Definition at line 26 of file [read\\_config.c](#).

#### 7.22.1.3 int [glb\\_config\\_general\\_work\\_package\\_mtu](#)

Definition at line 23 of file [read\\_config.c](#).

#### 7.22.1.4 int [glb\\_config\\_general\\_work\\_queue\\_depth](#)

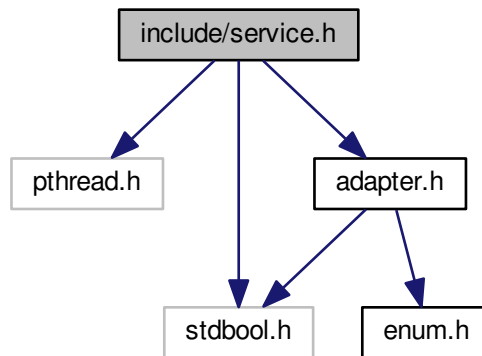
Definition at line 21 of file [read\\_config.c](#).

#### 7.22.1.5 int [glb\\_config\\_modbus\\_work\\_queue\\_depth](#)

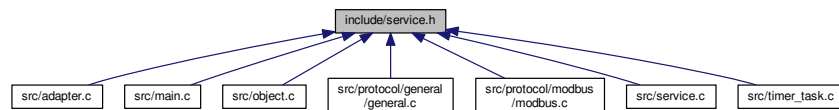
Definition at line 29 of file [read\\_config.c](#).

## 7.23 include/service.h File Reference

```
#include <pthread.h>
#include <stdbool.h>
#include "adapter.h"
Include dependency graph for service.h:
```



This graph shows which files directly or indirectly include this file:



### Data Structures

- struct [thread\\_pool\\_t](#)  
*define the thread pool struct*

### Functions

- int [rs485\\_service\\_start](#) (void)  
*rs485\_service\_start The rs485 service start*
- int [rs485\\_send\\_msg\\_to\\_client](#) (int clifd, void \*buffer, int buffer\_len)  
*rs485\_send\_msg\_to\_client send The message to a client*
- int [rs485\\_rcv\\_msg\\_from\\_client](#) (int clifd, void \*buffer, int buffer\_len)  
*rs485\_rcv\_msg\_from\_client recieve a message from client*
- int [send\\_msg\\_to\\_adapter](#) (const [adapter\\_t](#) \*adapter)  
*send\_msg\_to\_adapter send a message to self,*

### 7.23.1 Detailed Description

www.enno.com

Date

: Mar 15, 2016

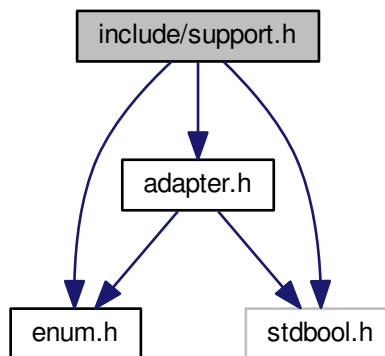
Author

: wong

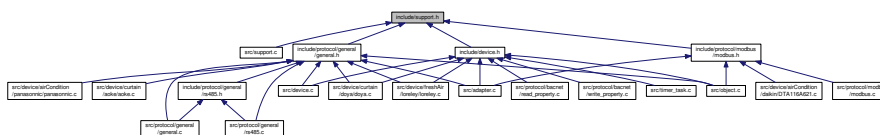
Definition in file [service.h](#).

### 7.24 include/support.h File Reference

```
#include "enum.h"
#include "adapter.h"
#include <stdbool.h>
Include dependency graph for support.h:
```



This graph shows which files directly or indirectly include this file:



### Data Structures

- struct [device\\_profile](#)  
*device\_profile* device process method

## Typedefs

- typedef int(\* [method\\_send](#) )(volatile void \*context)  
*int you have full the context pointer.*
- typedef int(\* [method\\_rcv](#) )(volatile void \*context)  
*int you have full the context pointer.*

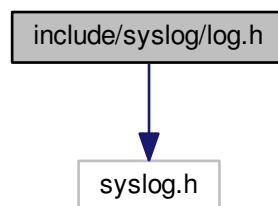
## Functions

- bool [check\\_device\\_support](#) (const [adapter\\_t](#) \*adatper)  
*check\_device\_support check the device have supported by rs485 service*
- struct [device\\_profile](#) \* [get\\_support\\_device\\_profile](#) ([rs485\\_factory\\_name\\_enum](#) name)  
*get\_support\_device\_profile Get the device profile, The struct [device\\_profile](#)*
- int [get\\_support\\_device\\_profile\\_numbers](#) ([rs485\\_factory\\_name\\_enum](#) name)  
*get\_support\_device\_profile\_numbers Get the device profile have support how many command.*
- [method\\_send](#) [get\\_device\\_send\\_package\\_function](#) (const struct [device\\_profile](#) \*profile, int profile\_numbers, int [command](#))  
*get\_device\_send\_package\_function Get the device profile send package callback function*
- [method\\_rcv](#) [get\\_device\\_rcv\\_package\\_function](#) (const struct [device\\_profile](#) \*profile, int profile\_numbers, int [command](#))  
*get\_device\_rcv\_package\_function Get the device profile receive package callback function*

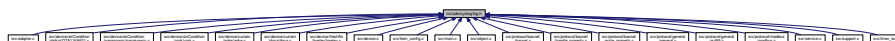
## 7.25 include/syslog/log.h File Reference

```
#include <syslog.h>
```

Include dependency graph for log.h:



This graph shows which files directly or indirectly include this file:



## Macros

- #define [DEBUG\\_LINUX\\_SYSLOG](#) (0)
- #define [DEBUG\\_PRINTF](#) (1)

- `#define syslog_error( _fmt_,... ) printf( _fmt_ "file:%s,line:%d\n", ##__VA_ARGS__, __FILE__, __LINE__ )`
- `#define syslog_warning( _fmt_,... ) printf( _fmt_ "file:%s,line:%d\n", ##__VA_ARGS__, __FILE__, __LINE__ )`
- `#define syslog_info( _fmt_,... ) printf( _fmt_ "\n", ##__VA_ARGS__ )`
- `#define syslog_debug( _fmt_,... ) printf( _fmt_ "\n", ##__VA_ARGS__ )`
- `#define syslog_format printf`

### 7.25.1 Detailed Description

www.enno.com

Date

: Mar 15, 2016

Author

: wong

Definition in file [log.h](#).

### 7.25.2 Macro Definition Documentation

#### 7.25.2.1 `#define DEBUG_LINUX_SYSLOG (0)`

Definition at line 18 of file [log.h](#).

#### 7.25.2.2 `#define DEBUG_PRINTF (1)`

Definition at line 19 of file [log.h](#).

#### 7.25.2.3 `#define syslog_debug( _fmt_, ... ) printf( _fmt_ "\n", ##__VA_ARGS__ )`

Definition at line 38 of file [log.h](#).

#### 7.25.2.4 `#define syslog_error( _fmt_, ... ) printf( _fmt_ "file:%s,line:%d\n", ##__VA_ARGS__, __FILE__, __LINE__ )`

Definition at line 35 of file [log.h](#).

#### 7.25.2.5 `#define syslog_format printf`

Definition at line 39 of file [log.h](#).

#### 7.25.2.6 `#define syslog_info( _fmt_, ... ) printf( _fmt_ "\n", ##__VA_ARGS__ )`

Definition at line 37 of file [log.h](#).

#### 7.25.2.7 `#define syslog_warning( _fmt_, ... ) printf( _fmt_ "file:%s,line:%d\n", ##__VA_ARGS__, __FILE__, __LINE__ )`

Definition at line 36 of file [log.h](#).

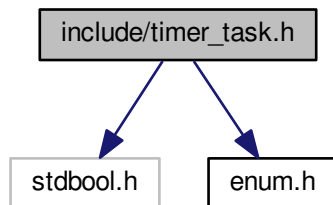


## 7.26 include/timer\_task.h File Reference

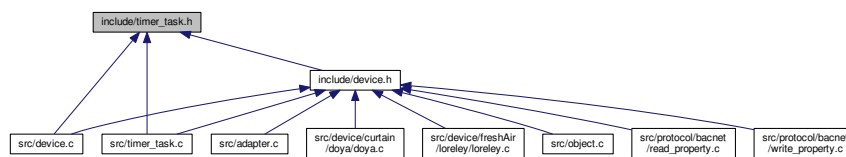
```
#include <stdbool.h>
```

```
#include "enum.h"
```

Include dependency graph for timer\_task.h:



This graph shows which files directly or indirectly include this file:



### Data Structures

- struct [timer\\_task\\_t](#)  
*timer task struct*

### Typedefs

- typedef int(\* [timer\\_proc\\_func](#))(int device\_id, int [command](#))

### Functions

- void \* [timer\\_task\\_thread\\_function](#) (void \*arg)  
*timer\_task\_thread\_function The timer task thread start function, just return when they have an error*
- int [create\\_device\\_timer\\_task](#) ([timer\\_task\\_t](#) \*task)  
*create\_device\_timer\_task create a device timer task, The timer task min tick is 10 second*
- int [delete\\_device\\_timer\\_task](#) ([timer\\_task\\_t](#) \*task)  
*delete\_device\_timer\_task delete a device timer task from the timer list.*
- int [device\\_timer\\_task\\_handle\\_demo](#) (int device\_id, int [command](#))  
*device\_timer\_task\_handle\_demo timer task handle function demo*
- int [device\\_timer\\_task\\_handle\\_curtain\\_init](#) (int device\_id, int [command](#))
- int [device\\_timer\\_task\\_handle\\_curtain\\_aoke\\_init](#) (int device\_id, int [command](#))
- int [device\\_timer\\_task\\_handle\\_curtain\\_doya\\_init](#) (int device\_id, int [command](#))

### 7.26.1 Detailed Description

www.enno.com

Date

: Mar 15, 2016

Author

: wong

Definition in file [timer\\_task.h](#).

### 7.26.2 Function Documentation

7.26.2.1 `int device_timer_task_handle_curtain_aoke_init ( int device_id, int command )`

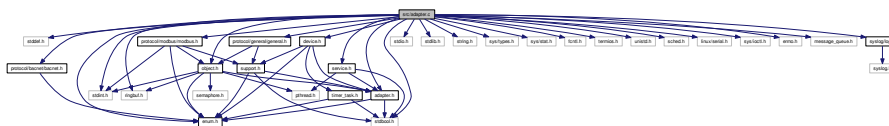
7.26.2.2 `int device_timer_task_handle_curtain_doya_init ( int device_id, int command )`

7.26.2.3 `int device_timer_task_handle_curtain_init ( int device_id, int command )`

## 7.27 src/adapter.c File Reference

```
#include <stddef.h>
#include <stdint.h>
#include <stdbool.h>
#include <stdio.h>
#include <stdlib.h>
#include <string.h>
#include <sys/types.h>
#include <sys/stat.h>
#include <fcntl.h>
#include <termios.h>
#include <unistd.h>
#include <sched.h>
#include <linux/serial.h>
#include <sys/ioctl.h>
#include <errno.h>
#include "enum.h"
#include "adapter.h"
#include "message_queue.h"
#include "syslog/log.h"
#include "device.h"
#include "object.h"
#include "service.h"
#include "protocol/bacnet/bacnet.h"
#include "protocol/modbus/modbus.h"
#include "protocol/general/general.h"
#include "ringbuf.h"
```

Include dependency graph for adapter.c:



## Macros

- `#define ADAPTER_MESSAGE_QUEUE_MAX_DEPTH (48)`

## Functions

- static int `adapter_thread_init` (void)  
*adapter\_thread\_init initialize the adapter thread , and mesesage queue initial.*
- static int `process_write_value_service` (const `adapter_t` \*adapter)  
*process\_write\_value\_service process the client write value to device service*
- static int `process_read_value_service` (`adapter_t` \*adapter)  
*process\_read\_value\_service process the client read value from device service*
- void \* `adapter_thread_function` (void \*arg)

## Variables

- static `adapter_thread_status_enum` `adapter_thread_status` = `ADAPTER_THREAD_STATUS_START`
- static `adapter_t` `reply_client`
- static `bacnet_port_handle_t` `bacnet`
- static `modbus_port_handle_t` `modbus`
- static `mstp_port_handle_t` `general`

### 7.27.1 Detailed Description

www.enno.com

Date

: Mar 14, 2016

Author

: chuanjiang.wong

Definition in file [adapter.c](#).

### 7.27.2 Macro Definition Documentation

#### 7.27.2.1 `#define ADAPTER_MESSAGE_QUEUE_MAX_DEPTH (48)`

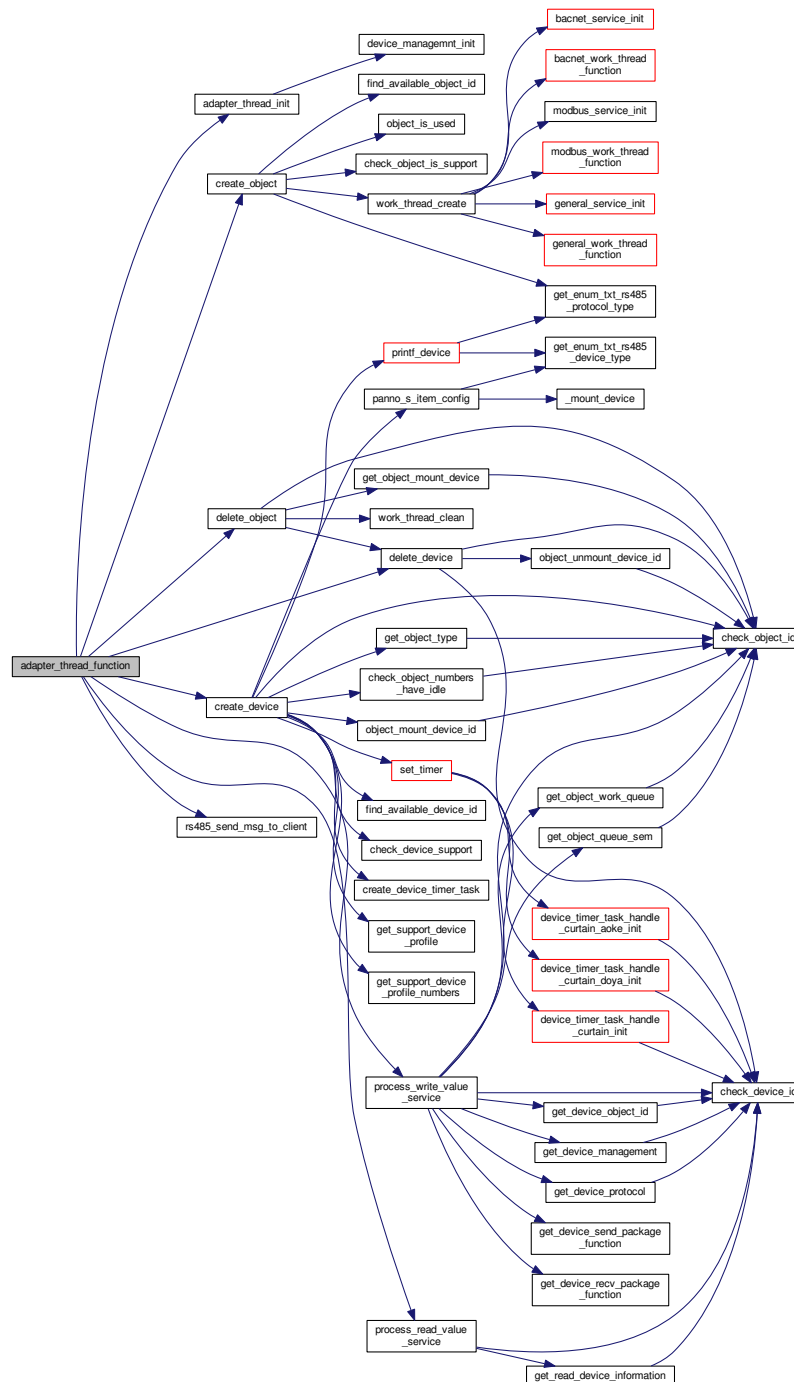
Definition at line 46 of file `adapter.c`.

### 7.27.3 Function Documentation

#### 7.27.3.1 `void* adapter_thread_function ( void * arg )`

Definition at line 300 of file `adapter.c`.

Here is the call graph for this function:



## 7.27.4 Variable Documentation

### 7.27.4.1 `adapter_thread_status_enum` `adapter_thread_status = ADAPTER_THREAD_STATUS_START` [static]

define the thread status

Definition at line 51 of file `adapter.c`.

7.27.4.2 `bacnet_port_handle_t bacnet` [static]

The bacnet interface

Definition at line 76 of file adapter.c.

7.27.4.3 `mstp_port_handle_t general` [static]

The general interface

Definition at line 80 of file adapter.c.

7.27.4.4 `modbus_port_handle_t modbus` [static]

The modbus interface

Definition at line 78 of file adapter.c.

7.27.4.5 `adapter_t reply_client` [static]

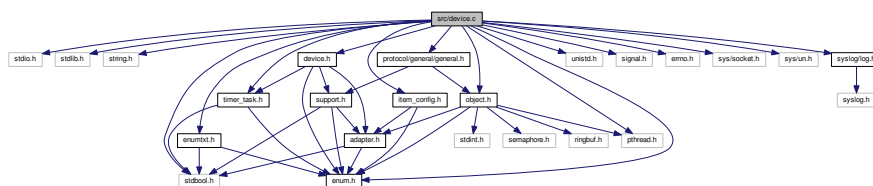
define the message queue

Definition at line 53 of file adapter.c.

7.28 `src/device.c` File Reference

```
#include <stdio.h>
#include <stdlib.h>
#include <string.h>
#include <stdbool.h>
#include <unistd.h>
#include <signal.h>
#include <errno.h>
#include <sys/socket.h>
#include <sys/un.h>
#include <pthread.h>
#include "device.h"
#include "enum.h"
#include "syslog/log.h"
#include "timer_task.h"
#include "object.h"
#include "protocol/general/general.h"
#include "enumtxt.h"
#include "item_config.h"
```

Include dependency graph for device.c:



## Macros

- `#define RS485_DEVICE_MAX_NUMBERS` (100)
- `#define RS485_DEVICE_NAME_MAX_LENGTH` (108)
- `#define RS485_CURTAIN_MAX_FACTORY` (16)

## Functions

- static bool `find_curtain_factory_is_save` (`rs485_factory_name_enum` factory)
- static int `find_available_device_id` (void)  
*find\_available\_device\_id find a available device ID*
- bool `check_device_id` (int device\_id)  
*check\_device\_id check the device is legal*
- static bool `set_timer` (`device_management_t` \*new\_device)
- static void `printf_device` (const `device_management_t` \*device)
- int `create_device` (`adapter_t` \*adapter)  
*create\_device create a rs485 device, mount the device to protocol*
- int `delete_device` (int object\_id, int device\_id)  
*delete\_device delete a device form device management table.*
- int `get_device_name` (char \*out, int out\_len, int device\_id)  
*get\_device\_name get a device name from device database.*
- int `get_device_type` (int device\_id)  
*get\_device\_type get a device type from device database, just like air condition, fresh air....*
- int `get_device_protocol` (int device\_id)  
*get\_device\_protocol get a device protocol from device database, just like BACnet, MODUBS...*
- int `get_device_addr` (unsigned char \*addr, unsigned int addr\_len, int device\_id)  
*get\_device\_addr get a rs485 device addr, you maybe have no address for some device.*
- `timer_task_t` \* `get_device_timer` (int device\_id)  
*get\_device\_timer get a device timer task.*
- struct `device_profile` \* `get_device_private` (int device\_id)  
*get\_device\_private get a device private profile*
- int `get_device_private_numbers` (int device\_id)  
*get\_device\_private\_numbers*
- int `get_device_object_id` (int device\_id)  
*get\_device\_object\_id get the object id by device id*
- int `get_device_factory_name` (int device\_id)  
*get\_device\_factory\_name Get the device factory name*
- int `get_device_retransmission` (int device\_id)  
*get\_device\_retransmission Get the device retransmission count on bus*
- int `get_device_timeout_ms` (int device\_id)  
*get\_device\_timeout\_ms Get The device timeout (ms), The bus have send a package have wait timeout count.*
- int `get_device_address_len` (int device\_id)  
*get\_device\_address\_len Get the device address length.*
- `device_management_t` \* `get_device_management` (int device\_id)  
*get\_device\_management get the device management pointer*
- int `device_management_init` (void)  
*device\_management\_init The device management modele have a initialize*
- int `set_read_device_information` (const `read_device_return_t` \*info, int device\_id)  
*set\_read\_device\_information bus have get a device information have wirte it.*
- int `get_read_device_information` (`read_device_return_t` \*out, int device\_id)  
*get\_read\_device\_information It's read a device information called by adapter layer.*

## Variables

- static `device_management_t` \* `glb_device_manage` [`RS485_DEVICE_MAX_NUMBERS`] = { `NULL` }
- static `pthread_mutex_t` `device_management_lock`
- static unsigned char `curtain_factory` [`RS485_CURTAIN_MAX_FACTORY`] = { `0` }

### 7.28.1 Detailed Description

`www.enno.com`

Date

: Mar 24, 2016

Author

: wong

Definition in file `device.c`.

### 7.28.2 Macro Definition Documentation

#### 7.28.2.1 `#define RS485_CURTAIN_MAX_FACTORY (16)`

Definition at line 43 of file `device.c`.

#### 7.28.2.2 `#define RS485_DEVICE_MAX_NUMBERS (100)`

Definition at line 35 of file `device.c`.

#### 7.28.2.3 `#define RS485_DEVICE_NAME_MAX_LENGTH (108)`

Definition at line 39 of file `device.c`.

### 7.28.3 Function Documentation

#### 7.28.3.1 `static bool find_curtain_factory_is_save ( rs485_factory_name_enum factory )` [`inline`], [`static`]

Definition at line 58 of file `device.c`.

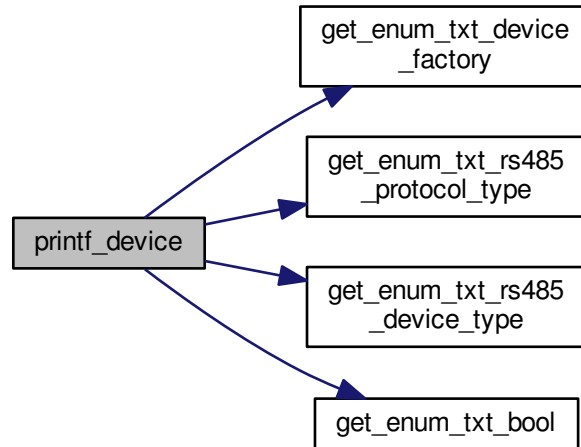
Here is the caller graph for this function:



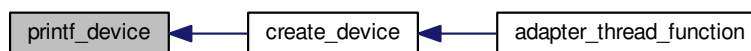
### 7.28.3.2 `static void printf_device ( const device_management_t* device ) [static]`

Definition at line 188 of file device.c.

Here is the call graph for this function:



Here is the caller graph for this function:

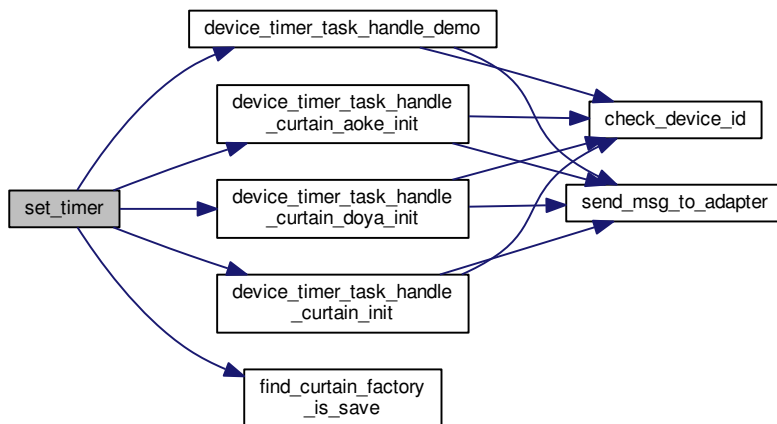


### 7.28.3.3 `static bool set_timer ( device_management_t* new_device ) [inline],[static]`

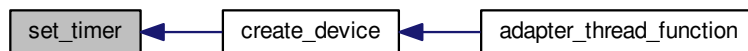
Definition at line 128 of file device.c.



Here is the call graph for this function:



Here is the caller graph for this function:



## 7.28.4 Variable Documentation

### 7.28.4.1 `unsigned char curtain_factory[RS485_CURTAIN_MAX_FACTORY] = { 0 }` `[static]`

save the curtain factory

Definition at line 54 of file device.c.

### 7.28.4.2 `pthread_mutex_t device_management_lock` `[static]`

define the device management lock

Definition at line 51 of file device.c.

### 7.28.4.3 `device_management_t* glb_device_manage[RS485_DEVICE_MAX_NUMBERS] = { NULL }` `[static]`

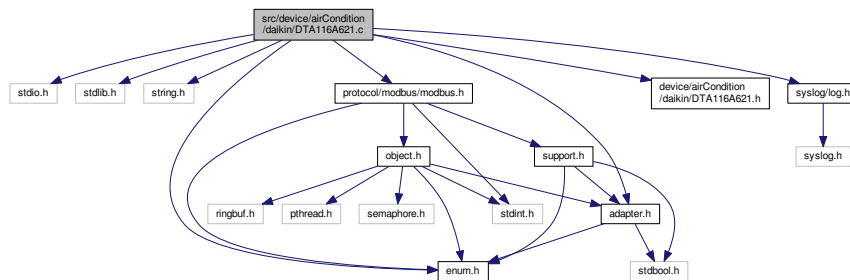
define the device management table

Definition at line 48 of file device.c.

## 7.29 src/device/airCondition/daikin/DTA116A621.c File Reference

```
#include <stdio.h>
#include <stdlib.h>
#include <string.h>
#include "enum.h"
#include "adapter.h"
#include "device/airCondition/daikin/DTA116A621.h"
#include "protocol/modbus/modbus.h"
#include "syslog/log.h"
```

Include dependency graph for DTA116A621.c:



### Macros

- #define [DAIKIN\\_INPUT\\_REGISTER\\_START](#) (30001)
- #define [DAIKIN\\_INPUT\\_REGISTER\\_DEVICE\\_CONNECT\\_STATUS\\_START](#) (30002)
- #define [DAIKIN\\_INPUT\\_REGISTER\\_DEVICE\\_CONNECT\\_STATUS\\_STOP](#) (30005)
- #define [DAIKIN\\_INPUT\\_REGISTER\\_DEVICE\\_COMM\\_STATUS\\_START](#) (30006)
- #define [DAIKIN\\_INPUT\\_REGISTER\\_DEVICE\\_COMM\\_STATUS\\_STOP](#) (30009)
- #define [DAIKIN\\_INPUT\\_REGISTER\\_DEVICE\\_FUNCTION\\_STATUS\\_START](#) (31001)
- #define [DAIKIN\\_INPUT\\_REGISTER\\_DEVICE\\_FUNCTION\\_STATUS\\_STOP](#) (31192)
- #define [DAIKIN\\_INPUT\\_REGISTER\\_DEVICE\\_STATUS\\_START](#) (32001)
- #define [DAIKIN\\_INPUT\\_REGISTER\\_DEVICE\\_STATUS\\_STOP](#) (32384)
- #define [DAIKIN\\_HOLD\\_REGISTER\\_START](#) (40001)
- #define [DAIKIN\\_HOLD\\_REGISTER\\_DEVICE\\_CONTROL\\_START](#) (42001)
- #define [DAIKIN\\_HOLD\\_REGISTER\\_DEVICE\\_CONTROL\\_STOP](#) (42192)
- #define [DAIKIN\\_HOLD\\_REGISTER\\_DEVICE\\_ON\\_OFF\\_SWING\\_FAN\\_OFFSET](#) (0)
- #define [DAIKIN\\_HOLD\\_REGISTER\\_DEVICE\\_MODE\\_OFFSET](#) (1)
- #define [DAIKIN\\_HOLD\\_REGISTER\\_DEVICE\\_TEMPERATURE\\_OFFSET](#) (2)

### Functions

- static uint16\_t [get\\_daikin\\_write\\_register\\_addr](#) (unsigned char device\_addr)  
*get\_daikin\_write\_register\_addr*
- static uint16\_t [get\\_daikin\\_hold\\_register\\_value](#) (rs485\_device\_method\_enum method, int value, unsigned char device\_addr)
- int [daikin\\_dta116a621\\_set\\_temperature](#) (volatile void \*arg)  
*daikin\_dta116a621\_set\_temperature set daikin air condition temperature send package to "modbus\_port\_handle\_t"*
- int [daikin\\_dta116a621\\_set\\_mode](#) (volatile void \*arg)  
*daikin\_dta116a621\_set\_mode set daikin air conditon mode send package to "modbus\_port\_handle\_t"*
- int [daikin\\_dta116a621\\_set\\_swing](#) (volatile void \*arg)

- daikin\_dta116a621\_set\_swing* set daikin air conditon swing send package to "modbus\_port\_handle\_t"
- int [daikin\\_dta116a621\\_set\\_fan](#) (volatile void \*arg)
  - daikin\_dta116a621\_set\_fan* set daikin air conditon fan send package to "modbus\_port\_handle\_t"
- int [daikin\\_dta116a621\\_set\\_switch](#) (volatile void \*arg)
  - daikin\_dta116a621\_set\_switch* set daikin air conditon switch send package to "modbus\_port\_handle\_t"
- int [daikin\\_dta116a621\\_get\\_device\\_info\\_send](#) (volatile void \*arg)
  - daikin\_dta116a621\_get\_device\_info\_send* set daikin air conditon device information send package to "modbus\_↵  
port\_handle\_t"
- int [daikin\\_dta116a621\\_get\\_device\\_info\\_handle](#) (volatile void \*arg)
  - daikin\_dta116a621\_get\_device\_info\_handle* process daikin air conditon get device information send package to "modbus\_port\_handle\_t"

## Variables

- static uint16\_t [glb\\_daikin\\_hold\\_register\\_value](#) [64][3]

## 7.29.1 Macro Definition Documentation

### 7.29.1.1 #define DAIKIN\_HOLD\_REGISTER\_DEVICE\_CONTROL\_START (42001)

Definition at line 41 of file DTA116A621.c.

### 7.29.1.2 #define DAIKIN\_HOLD\_REGISTER\_DEVICE\_CONTROL\_STOP (42192)

Definition at line 42 of file DTA116A621.c.

### 7.29.1.3 #define DAIKIN\_HOLD\_REGISTER\_DEVICE\_MODE\_OFFSET (1)

Definition at line 45 of file DTA116A621.c.

### 7.29.1.4 #define DAIKIN\_HOLD\_REGISTER\_DEVICE\_ON\_OFF\_SWING\_FAN\_OFFSET (0)

Definition at line 44 of file DTA116A621.c.

### 7.29.1.5 #define DAIKIN\_HOLD\_REGISTER\_DEVICE\_TEMPERATURE\_OFFSET (2)

Definition at line 46 of file DTA116A621.c.

### 7.29.1.6 #define DAIKIN\_HOLD\_REGISTER\_START (40001)

Definition at line 40 of file DTA116A621.c.

### 7.29.1.7 #define DAIKIN\_INPUT\_REGISTER\_DEVICE\_COMM\_STATUS\_START (30006)

Definition at line 33 of file DTA116A621.c.

### 7.29.1.8 #define DAIKIN\_INPUT\_REGISTER\_DEVICE\_COMM\_STATUS\_STOP (30009)

Definition at line 34 of file DTA116A621.c.

7.29.1.9 `#define DAIKIN_INPUT_REGISTER_DEVICE_CONNECT_STATUS_START (30002)`

Definition at line 31 of file DTA116A621.c.

7.29.1.10 `#define DAIKIN_INPUT_REGISTER_DEVICE_CONNECT_STATUS_STOP (30005)`

Definition at line 32 of file DTA116A621.c.

7.29.1.11 `#define DAIKIN_INPUT_REGISTER_DEVICE_FUNCTION_STATUS_START (31001)`

Definition at line 35 of file DTA116A621.c.

7.29.1.12 `#define DAIKIN_INPUT_REGISTER_DEVICE_FUNCTION_STATUS_STOP (31192)`

Definition at line 36 of file DTA116A621.c.

7.29.1.13 `#define DAIKIN_INPUT_REGISTER_DEVICE_STATUS_START (32001)`

Definition at line 37 of file DTA116A621.c.

7.29.1.14 `#define DAIKIN_INPUT_REGISTER_DEVICE_STATUS_STOP (32384)`

Definition at line 38 of file DTA116A621.c.

7.29.1.15 `#define DAIKIN_INPUT_REGISTER_START (30001)`

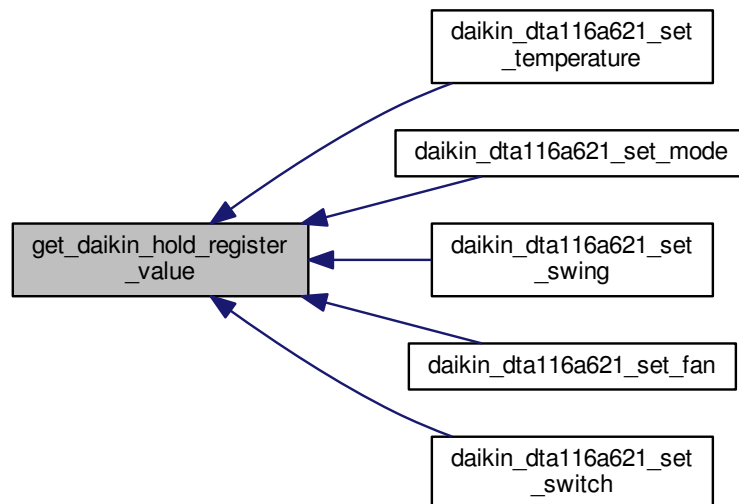
Definition at line 30 of file DTA116A621.c.

## 7.29.2 Function Documentation

7.29.2.1 `static uint16_t get_daikin_hold_register_value ( rs485_device_method_enum method, int value, unsigned char device_addr ) [static]`

Definition at line 133 of file DTA116A621.c.

Here is the caller graph for this function:



7.29.2.2 `static uint16_t get_daikin_write_register_addr ( unsigned char device_addr ) [static]`

`get_daikin_write_register_addr`

Parameters

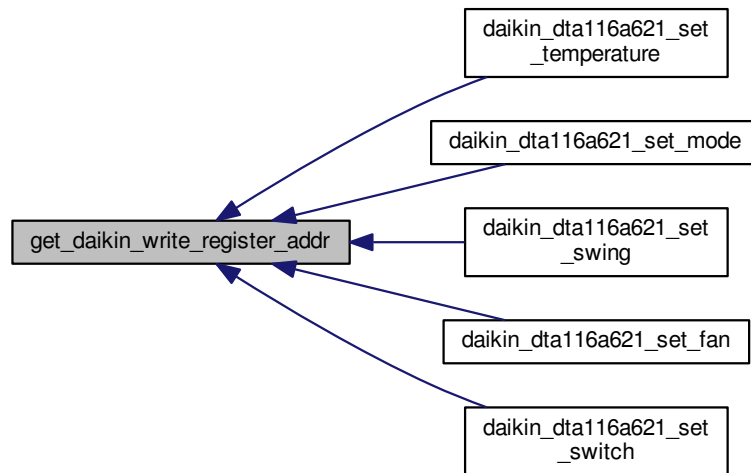
|    |                    |        |
|----|--------------------|--------|
| in | <i>device_addr</i> | : 0~63 |
|----|--------------------|--------|

Returns

The daikin register address

Definition at line 127 of file DTA116A621.c.

Here is the caller graph for this function:



### 7.29.3 Variable Documentation

#### 7.29.3.1 `uint16_t glb_daikin_hold_register_value[64][3]` `[static]`

Definition at line 49 of file `DTA116A621.c`.

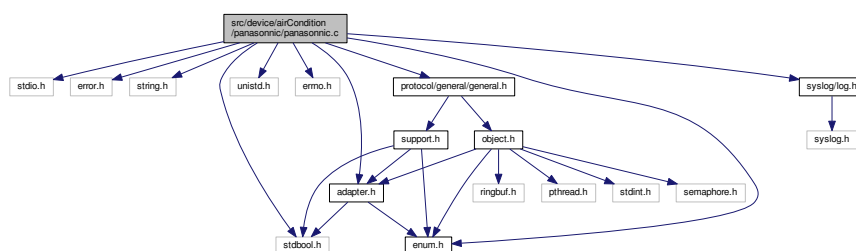
## 7.30 `src/device/airCondition/panasonic/panasonic.c` File Reference

```

#include <stdio.h>
#include <error.h>
#include <string.h>
#include <stdbool.h>
#include <unistd.h>
#include <errno.h>
#include "enum.h"
#include "adapter.h"
#include "protocol/general/general.h"
#include "syslog/log.h"

```

Include dependency graph for `panasonic.c`:



## Macros

- #define GET\_AIR\_ADDR\_CID\_SEND 0x01
- #define GET\_AIR\_ADDR
- #define GET\_AIR\_INFO\_CID\_SEND 0x02
- #define GET\_AIR\_INFO\_TELECONTROLLER\_MODE\_AUTO 0x00
- #define GET\_AIR\_INFO\_TELECONTROLLER\_MODE\_DRY 0x02
- #define GET\_AIR\_INFO\_TELECONTROLLER\_MODE\_COLD 0x03
- #define GET\_AIR\_INFO\_TELECONTROLLER\_MODE\_HOT 0x04
- #define GET\_AIR\_INFO\_TELECONTROLLER\_MODE\_WIND 0x06
- #define GET\_AIR\_INFO\_ON 0x01
- #define GET\_AIR\_INFO\_OFF 0x00
- #define GET\_AIR\_INFO\_SET\_WIND\_RATE\_LOW 0x03
- #define GET\_AIR\_INFO\_SET\_WIND\_RATE\_MIDDLE 0x05
- #define GET\_AIR\_INFO\_SET\_WIND\_RATE\_HIGH 0x07
- #define GET\_AIR\_INFO\_SET\_WIND\_RATE\_MOST 0x09
- #define GET\_AIR\_INFO\_SET\_WIND\_RATE\_AUTO 0x0a
- #define GET\_AIR\_INFO\_SET\_WIND\_RATE\_MUTE 0x0b
- #define GET\_AIR\_INFO\_SET\_WIND\_DIRECTION\_HANDL1 0x01
- #define GET\_AIR\_INFO\_SET\_WIND\_DIRECTION\_HANDL2 0x02
- #define GET\_AIR\_INFO\_SET\_WIND\_DIRECTION\_HANDL3 0x03
- #define GET\_AIR\_INFO\_SET\_WIND\_DIRECTION\_HANDL4 0x04
- #define GET\_AIR\_INFO\_SET\_WIND\_DIRECTION\_HANDL5 0x05
- #define GET\_AIR\_INFO\_SET\_WIND\_DIRECTION\_FOCUS 0x0e
- #define GET\_AIR\_INFO\_SET\_WIND\_DIRECTION\_WIDE 0x0f
- #define GET\_AIR\_INFO\_SET\_TEMPERATURE(x) (x)/2
- #define GET\_AIR\_INFO\_SET\_TEMPERATURE\_UP 0xe1
- #define GET\_AIR\_INFO\_SET\_TEMPERATURE\_STD 0xe0
- #define GET\_AIR\_INFO\_SET\_TEMPERATURE\_DOWN 0xff
- #define GET\_AIR\_INFO\_SET\_TEMPERATURE\_ADD\_5 0xca
- #define GET\_AIR\_INFO\_SET\_TEMPERATURE\_ADD\_1 0xc2
- #define GET\_AIR\_INFO\_SET\_TEMPERATURE\_DRY 0xc0
- #define GET\_AIR\_INFO\_SET\_TEMPERATURE\_SUB\_1 0xde
- #define GET\_AIR\_INFO\_SET\_TEMPERATURE\_SUB\_5 0xd6
- #define GET\_AIR\_INFO\_TEMPERATURE\_UNDERFLOW 0x80
- #define GET\_AIR\_INFO\_TEMPERATURE\_OVERFLOW 0x7f
- #define GET\_AIR\_INFO\_TEMPERATURE\_UNKNOWN 0x7e
- #define GET\_AIR\_INFO\_ERROR\_CODE\_NORMAL 0x00
- #define SET\_AIR\_ARG\_CID\_SEND 0x03
- #define SET\_AIR\_ARG\_CONFIG\_OPT\_ALL 0x00
- #define SET\_AIR\_ARG\_CONFIG\_OPT\_SWITCH 0x01
- #define SET\_AIR\_ARG\_CONFIG\_OPT\_MODE 0x02
- #define SET\_AIR\_ARG\_CONFIG\_OPT\_WIND\_DIRECTION 0x03
- #define SET\_AIR\_ARG\_CONFIG\_OPT\_WIND\_RATE 0x04
- #define SET\_AIR\_ARG\_CONFIG\_OPT\_TEMPERATURE 0x05
- #define SET\_AIR\_ARG\_CONFIG\_OPT\_KEEP 0xff
- #define SET\_AIR\_ARG\_ON 0x00
- #define SET\_AIR\_ARG\_OFF 0x01
- #define SET\_AIR\_ARG\_TELECONTROLLER\_MODE\_AUTO 0x00
- #define SET\_AIR\_ARG\_TELECONTROLLER\_MODE\_DRY 0x02
- #define SET\_AIR\_ARG\_TELECONTROLLER\_MODE\_COLD 0x03
- #define SET\_AIR\_ARG\_TELECONTROLLER\_MODE\_HOT 0x04
- #define SET\_AIR\_ARG\_TELECONTROLLER\_MODE\_WIND 0x06
- #define SET\_AIR\_ARG\_WIND\_RATE\_LOW 0x03
- #define SET\_AIR\_ARG\_WIND\_RATE\_MIDDLE 0x05

- `#define SET_AIR_ARG_WIND_RATE_HIGH 0x07`
- `#define SET_AIR_ARG_WIND_RATE_MOST 0x09`
- `#define SET_AIR_ARG_WIND_RATE_AUTO 0x0a`
- `#define SET_AIR_ARG_WIND_RATE_MUTE 0x0b`
- `#define SET_AIR_ARG_WIND_DIRECTION_HANDL (0x01 | 0x02 | 0x03 | 0x04 | 0x05)`
- `#define SET_AIR_ARG_WIND_DIRECTION_FOCUS 0x0e`
- `#define SET_AIR_ARG_WIND_DIRECTION_WIDE 0x0f`
- `#define SET_AIR_ARG_TEMPERATURE(x) temperature_to_bin(x)`
- `#define RESET_AIR_CID_SEND 0x04`
- `#define SOI_SEND 0xaa`
- `#define SOI_RECEIVE 0x55`
- `#define ADR_BROADCAST 0xff`
- `#define ADR_DEFAULT 0x01`
- `#define RTN_SEND 0x60`
- `#define RTN_RECEIVE_CMD_RIGHT 0x01`
- `#define RTN_RECEIVE_CHK_ERROR 0x02`
- `#define RTN_RECEIVE_CMD_INVALID 0x03`
- `#define EOI 0x0d`
- `#define SEND_ERROR -2`
- `#define RECEIVE_ERROR -3`
- `#define RECEIVE_CHK_ERROR -4`
- `#define RETURN_DATA_INVALID_ERROR -5`
- `#define RETURN_CHK_ERROR -6`
- `#define ARG_ERROR -7`
- `#define UNKNOW_ERROR -8`
- `#define ERROR -1`
- `#define PACKAGE_MAX 20`
- `#define HIGH_CHAR(x) (x)>>4`
- `#define LOW_CHAR(x) (x) & 0xff`

## Functions

- static unsigned char `calculate_sum_check` (unsigned char \*value, int length)
- static int `panasonic_send_package` (unsigned char \*out, int out\_len, unsigned char `addr`, unsigned char msg\_cid, const unsigned char \*data, int data\_len)
- int `panasonic_send_package_handle` (volatile void \*arg)  
*panasonic\_send\_package\_handle The panasonic package a send buffer interface.*
- int `panasonic_rcv_package_handle` (volatile void \*arg)  
*panasonic\_send\_package\_handle The panasonic package a receive buffer processs interface.*

## Variables

- const unsigned char `air_command_table` [34][5]

### 7.30.1 Macro Definition Documentation

#### 7.30.1.1 `#define ADR_BROADCAST 0xff`

Definition at line 123 of file panasonic.c.

#### 7.30.1.2 `#define ADR_DEFAULT 0x01`

Definition at line 124 of file panasonic.c.



#### 7.30.1.3 #define ARG\_ERROR -7

Definition at line 138 of file panasonic.c.

#### 7.30.1.4 #define EOI 0x0d

Definition at line 129 of file panasonic.c.

#### 7.30.1.5 #define ERROR -1

define air conditioner transmit frame, it's up RS485 struct Package\_air\_transmit

```
{  
    unsigned char |soi; |  
    unsigned char |addr; |  
    unsigned char |cid; |  
    unsigned char |rtn; |  
    unsigned char |length; |  
    length |data; |  
    unsigned char |sum_chk; |  
    unsigned char |eoi; |  
};
```

Definition at line 167 of file panasonic.c.

#### 7.30.1.6 #define GET\_AIR\_ADDR

Definition at line 39 of file panasonic.c.

#### 7.30.1.7 #define GET\_AIR\_ADDR\_CID\_SEND 0x01

get air conditioner address

Definition at line 38 of file panasonic.c.

#### 7.30.1.8 #define GET\_AIR\_INFO\_CID\_SEND 0x02

get air conditioner information

Definition at line 42 of file panasonic.c.

#### 7.30.1.9 #define GET\_AIR\_INFO\_ERROR\_CODE\_NORMAL 0x00

Definition at line 82 of file panasonic.c.

7.30.1.10 `#define GET_AIR_INFO_OFF 0x00`

Definition at line 51 of file panasonic.c.

7.30.1.11 `#define GET_AIR_INFO_ON 0x01`

Definition at line 50 of file panasonic.c.

7.30.1.12 `#define GET_AIR_INFO_SET_TEMPERATURE( x ) (x)/2`

Definition at line 68 of file panasonic.c.

7.30.1.13 `#define GET_AIR_INFO_SET_TEMPERATURE_ADD_1 0xc2`

Definition at line 73 of file panasonic.c.

7.30.1.14 `#define GET_AIR_INFO_SET_TEMPERATURE_ADD_5 0xca`

Definition at line 72 of file panasonic.c.

7.30.1.15 `#define GET_AIR_INFO_SET_TEMPERATURE_DOWN 0xff`

Definition at line 71 of file panasonic.c.

7.30.1.16 `#define GET_AIR_INFO_SET_TEMPERATURE_DRY 0xc0`

Definition at line 74 of file panasonic.c.

7.30.1.17 `#define GET_AIR_INFO_SET_TEMPERATURE_STD 0xe0`

Definition at line 70 of file panasonic.c.

7.30.1.18 `#define GET_AIR_INFO_SET_TEMPERATURE_SUB_1 0xde`

Definition at line 75 of file panasonic.c.

7.30.1.19 `#define GET_AIR_INFO_SET_TEMPERATURE_SUB_5 0xd6`

Definition at line 76 of file panasonic.c.

7.30.1.20 `#define GET_AIR_INFO_SET_TEMPERATURE_UP 0xe1`

Definition at line 69 of file panasonic.c.

7.30.1.21 `#define GET_AIR_INFO_SET_WIND_DIRECTION_FOCUS 0x0e`

Definition at line 65 of file panasonic.c.

7.30.1.22 `#define GET_AIR_INFO_SET_WIND_DIRECTION_HANDL1 0x01`

Definition at line 60 of file panasonic.c.

7.30.1.23 `#define GET_AIR_INFO_SET_WIND_DIRECTION_HANDL2 0x02`

Definition at line 61 of file panasonic.c.

7.30.1.24 `#define GET_AIR_INFO_SET_WIND_DIRECTION_HANDL3 0x03`

Definition at line 62 of file panasonic.c.

7.30.1.25 `#define GET_AIR_INFO_SET_WIND_DIRECTION_HANDL4 0x04`

Definition at line 63 of file panasonic.c.

7.30.1.26 `#define GET_AIR_INFO_SET_WIND_DIRECTION_HANDL5 0x05`

Definition at line 64 of file panasonic.c.

7.30.1.27 `#define GET_AIR_INFO_SET_WIND_DIRECTION_WIDE 0x0f`

Definition at line 66 of file panasonic.c.

7.30.1.28 `#define GET_AIR_INFO_SET_WIND_RATE_AUTO 0x0a`

Definition at line 57 of file panasonic.c.

7.30.1.29 `#define GET_AIR_INFO_SET_WIND_RATE_HIGH 0x07`

Definition at line 55 of file panasonic.c.

7.30.1.30 `#define GET_AIR_INFO_SET_WIND_RATE_LOW 0x03`

Definition at line 53 of file panasonic.c.

7.30.1.31 `#define GET_AIR_INFO_SET_WIND_RATE_MIDDLE 0x05`

Definition at line 54 of file panasonic.c.

7.30.1.32 `#define GET_AIR_INFO_SET_WIND_RATE_MOST 0x09`

Definition at line 56 of file panasonic.c.

7.30.1.33 `#define GET_AIR_INFO_SET_WIND_RATE_MUTE 0x0b`

Definition at line 58 of file panasonic.c.

7.30.1.34 **#define GET\_AIR\_INFO\_TELECONTROLLER\_MODE\_AUTO 0x00**

Definition at line 44 of file panasonic.c.

7.30.1.35 **#define GET\_AIR\_INFO\_TELECONTROLLER\_MODE\_COLD 0x03**

Definition at line 46 of file panasonic.c.

7.30.1.36 **#define GET\_AIR\_INFO\_TELECONTROLLER\_MODE\_DRY 0x02**

Definition at line 45 of file panasonic.c.

7.30.1.37 **#define GET\_AIR\_INFO\_TELECONTROLLER\_MODE\_HOT 0x04**

Definition at line 47 of file panasonic.c.

7.30.1.38 **#define GET\_AIR\_INFO\_TELECONTROLLER\_MODE\_WIND 0x06**

Definition at line 48 of file panasonic.c.

7.30.1.39 **#define GET\_AIR\_INFO\_TEMPERATURE\_OVERFLOW 0x7f**

Definition at line 79 of file panasonic.c.

7.30.1.40 **#define GET\_AIR\_INFO\_TEMPERATURE\_UNDERFLOW 0x80**

Definition at line 78 of file panasonic.c.

7.30.1.41 **#define GET\_AIR\_INFO\_TEMPERATURE\_UNKNOWN 0x7e**

Definition at line 80 of file panasonic.c.

7.30.1.42 **#define HIGH\_CHAR( x ) (x)>>4**

Definition at line 172 of file panasonic.c.

7.30.1.43 **#define LOW\_CHAR( x ) (x) & 0xff**

Definition at line 173 of file panasonic.c.

7.30.1.44 **#define PACKAGE\_MAX 20**

Definition at line 170 of file panasonic.c.

7.30.1.45 **#define RECEIVE\_CHK\_ERROR -4**

Definition at line 135 of file panasonic.c.

**7.30.1.46 #define RECEIVE\_ERROR -3**

Definition at line 134 of file panasonic.c.

**7.30.1.47 #define RESET\_AIR\_CID\_SEND 0x04**

when the air conditioner unusual, will reset it

Definition at line 118 of file panasonic.c.

**7.30.1.48 #define RETURN\_CHK\_ERROR -6**

Definition at line 137 of file panasonic.c.

**7.30.1.49 #define RETURN\_DATA\_INVALID\_ERROR -5**

Definition at line 136 of file panasonic.c.

**7.30.1.50 #define RTN\_RECEIVE\_CHK\_ERROR 0x02**

Definition at line 127 of file panasonic.c.

**7.30.1.51 #define RTN\_RECEIVE\_CMD\_INVALID 0x03**

Definition at line 128 of file panasonic.c.

**7.30.1.52 #define RTN\_RECEIVE\_CMD\_RIGHT 0x01**

Definition at line 126 of file panasonic.c.

**7.30.1.53 #define RTN\_SEND 0x60**

Definition at line 125 of file panasonic.c.

**7.30.1.54 #define SEND\_ERROR -2**

Definition at line 133 of file panasonic.c.

**7.30.1.55 #define SET\_AIR\_ARG\_CID\_SEND 0x03**

set air conditioner arguments

Definition at line 85 of file panasonic.c.

**7.30.1.56 #define SET\_AIR\_ARG\_CONFIG\_OPT\_ALL 0x00**

Definition at line 87 of file panasonic.c.

**7.30.1.57 #define SET\_AIR\_ARG\_CONFIG\_OPT\_KEEP 0xff**

Definition at line 93 of file panasonic.c.

7.30.1.58 **#define SET\_AIR\_ARG\_CONFIG\_OPT\_MODE 0x02**

Definition at line 89 of file panasonic.c.

7.30.1.59 **#define SET\_AIR\_ARG\_CONFIG\_OPT\_SWITCH 0x01**

Definition at line 88 of file panasonic.c.

7.30.1.60 **#define SET\_AIR\_ARG\_CONFIG\_OPT\_TEMPERATURE 0x05**

Definition at line 92 of file panasonic.c.

7.30.1.61 **#define SET\_AIR\_ARG\_CONFIG\_OPT\_WIND\_DIRECTION 0x03**

Definition at line 90 of file panasonic.c.

7.30.1.62 **#define SET\_AIR\_ARG\_CONFIG\_OPT\_WIND\_RATE 0x04**

Definition at line 91 of file panasonic.c.

7.30.1.63 **#define SET\_AIR\_ARG\_OFF 0x01**

Definition at line 96 of file panasonic.c.

7.30.1.64 **#define SET\_AIR\_ARG\_ON 0x00**

Definition at line 95 of file panasonic.c.

7.30.1.65 **#define SET\_AIR\_ARG\_TELECONTROLLER\_MODE\_AUTO 0x00**

Definition at line 98 of file panasonic.c.

7.30.1.66 **#define SET\_AIR\_ARG\_TELECONTROLLER\_MODE\_COLD 0x03**

Definition at line 100 of file panasonic.c.

7.30.1.67 **#define SET\_AIR\_ARG\_TELECONTROLLER\_MODE\_DRY 0x02**

Definition at line 99 of file panasonic.c.

7.30.1.68 **#define SET\_AIR\_ARG\_TELECONTROLLER\_MODE\_HOT 0x04**

Definition at line 101 of file panasonic.c.

7.30.1.69 **#define SET\_AIR\_ARG\_TELECONTROLLER\_MODE\_WIND 0x06**

Definition at line 102 of file panasonic.c.

7.30.1.70 `#define SET_AIR_ARG_TEMPERATURE( x ) temperature_to_bin(x)`

Definition at line 115 of file panasonicnic.c.

7.30.1.71 `#define SET_AIR_ARG_WIND_DIRECTION_FOCUS 0x0e`

Definition at line 112 of file panasonicnic.c.

7.30.1.72 `#define SET_AIR_ARG_WIND_DIRECTION_HANDL (0x01 | 0x02 | 0x03 | 0x04 | 0x05)`

Definition at line 111 of file panasonicnic.c.

7.30.1.73 `#define SET_AIR_ARG_WIND_DIRECTION_WIDE 0x0f`

Definition at line 113 of file panasonicnic.c.

7.30.1.74 `#define SET_AIR_ARG_WIND_RATE_AUTO 0x0a`

Definition at line 108 of file panasonicnic.c.

7.30.1.75 `#define SET_AIR_ARG_WIND_RATE_HIGH 0x07`

Definition at line 106 of file panasonicnic.c.

7.30.1.76 `#define SET_AIR_ARG_WIND_RATE_LOW 0x03`

Definition at line 104 of file panasonicnic.c.

7.30.1.77 `#define SET_AIR_ARG_WIND_RATE_MIDDLE 0x05`

Definition at line 105 of file panasonicnic.c.

7.30.1.78 `#define SET_AIR_ARG_WIND_RATE_MOST 0x09`

Definition at line 107 of file panasonicnic.c.

7.30.1.79 `#define SET_AIR_ARG_WIND_RATE_MUTE 0x0b`

Definition at line 109 of file panasonicnic.c.

7.30.1.80 `#define SOI_RECEIVE 0x55`

Definition at line 122 of file panasonicnic.c.

7.30.1.81 `#define SOI_SEND 0xaa`

package protocol

Definition at line 121 of file panasonicnic.c.

### 7.30.1.82 #define UNKNOW\_ERROR -8

Definition at line 139 of file panasonicnic.c.

## 7.30.2 Function Documentation

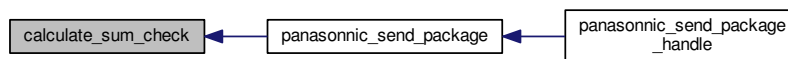
### 7.30.2.1 static unsigned char calculate\_sum\_check ( unsigned char \* *value*, int *length* ) [static]

static function declare

static function define

Definition at line 279 of file panasonicnic.c.

Here is the caller graph for this function:



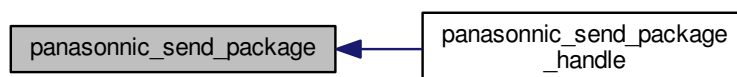
### 7.30.2.2 static int panasonicnic\_send\_package ( unsigned char \* *out*, int *out\_len*, unsigned char *addr*, unsigned char *msg\_cid*, const unsigned char \* *data*, int *data\_len* ) [static]

Definition at line 676 of file panasonicnic.c.

Here is the call graph for this function:



Here is the caller graph for this function:



## 7.30.3 Variable Documentation



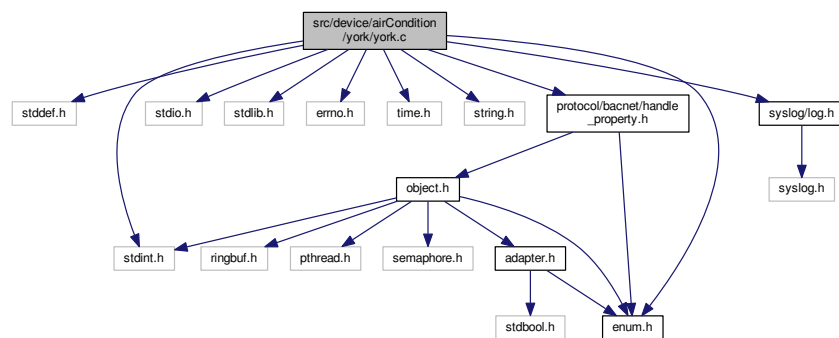
## 7.30.3.1 const unsigned char air\_command\_table[34][5]

Definition at line 218 of file panasonic.c.

## 7.31 src/device/airCondition/york/york.c File Reference

```
#include <stddef.h>
#include <stdint.h>
#include <stdio.h>
#include <stdlib.h>
#include <errno.h>
#include <time.h>
#include <string.h>
#include "protocol/bacnet/handle_property.h"
#include "enum.h"
#include "syslog/log.h"
```

Include dependency graph for york.c:



## Enumerations

- enum `york_air_conditioner_object` {
  - AI\_OUTDOOR\_TEMPERATURE, AI\_INDOOR\_TEMPERATURE, AI\_SET\_TEMPERATURE, AI\_INDOOR←\_HUMIDITY,
  - AI\_SET\_HUMIDITY, AI\_COMPRESSOR\_FREQUENCY, AI\_NET\_CLEAR\_TIME\_LEFT, BI\_ON\_OFF\_ST←\_ATUS,
  - BI\_ERROR\_RESET\_STATUS, BI\_NET\_CLEAR\_RESET\_STATUS, BI\_SLEEP\_STATUS, BI\_ELECTRIC←\_AL\_HEAT\_STATUS,
  - BI\_HEALTH\_AIR\_STATUS, BI\_HOT\_WATER\_STATUS, BI\_NEW\_AIR\_STATUS, BI\_FIX\_RUN\_STATUS,
  - BI\_SAVING\_STATUS, BI\_DEFROST, BI\_COMPRESSOR\_RUNNING\_STATUS, BI\_COOL\_ONLY\_STAT←\_US,
  - BI\_CENTRAL\_CONONLY\_STATUS, MI\_RESERVED, MI\_MODE, MI\_FAN,
  - MI\_SWING, MI\_VENTILATION, MI\_LOCAL\_SET, MI\_ERROR,
  - MI\_COMMUNICATION\_STATUS, MI\_INDOOR\_STYLE, AV\_SET\_TEMPERATURE, AV\_SET\_HUMIDUTY

## Functions

- int `get_air_york_write_args` (bacnet\_write\_args\_t \*args, unsigned int device\_id, int command, char \*value)
- int `get_air_york_read_args` (bacnet\_read\_args\_t \*args, unsigned int device\_id)

- get\_air\_york\_read\_args* The york air confition bacnet read interface
- int [get\\_air\\_york\\_instance](#) (unsigned char mac)  
*get\_air\_york\_instance* get the youk bacnet instance.

## Variables

- static const int [york\\_air\\_condition\\_object](#) [][][7]
- static const int [york\\_air\\_condition\\_read\\_property](#) [][][3]

## 7.31.1 Enumeration Type Documentation

### 7.31.1.1 enum york\_air\_conditioner\_object

#### Enumerator

***AI\_OUTDOOR\_TEMPERATURE***  
***AI\_INDOOR\_TEMPERATURE***  
***AI\_SET\_TEMPERATURE***  
***AI\_INDOOR\_HUMIDITY***  
***AI\_SET\_HUMIDITY***  
***AI\_COMPRESSOR\_FREQUENCY***  
***AI\_NET\_CLEAR\_TIME\_LEFT***  
***BI\_ON\_OFF\_STATUS***  
***BI\_ERROR\_RESET\_STATUS***  
***BI\_NET\_CLEAR\_RESET\_STATUS***  
***BI\_SLEEP\_STATUS***  
***BI\_ELECTRICAL\_HEAT\_STATUS***  
***BI\_HEALTH\_AIR\_STATUS***  
***BI\_HOT\_WATER\_STATUS***  
***BI\_NEW\_AIR\_STATUS***  
***BI\_FIX\_RUN\_STATUS***  
***BI\_SAVING\_STATUS***  
***BI\_DEFROST***  
***BI\_COMPRESSOR\_RUNNING\_STATUS***  
***BI\_COOL\_ONLY\_STATUS***  
***BI\_CENTRAL\_CONONLY\_STATUS***  
***MI\_RESERVED***  
***MI\_MODE***  
***MI\_FAN***  
***MI\_SWING***  
***MI\_VENTILATION***  
***MI\_LOCAL\_SET***  
***MI\_ERROR***  
***MI\_COMMUNICATION\_STATUS***  
***MI\_INDOOR\_STYLE***  
***AV\_SET\_TEMPERATURE***  
***AV\_SET\_HUMIDUTY***

Definition at line 21 of file york.c.

### 7.31.2 Function Documentation

7.31.2.1 `int get_air_york_write_args ( bacnet_write_args_t * args, unsigned int device_id, int command, char * value )`

Definition at line 161 of file york.c.

Here is the caller graph for this function:



### 7.31.3 Variable Documentation

7.31.3.1 `const int york_air_condition_object[][7] [static]`

Definition at line 61 of file york.c.

7.31.3.2 `const int york_air_condition_read_property[][3] [static]`

**Initial value:**

```

=
{
    {0, 0, 85},
    {0, 1, 85},
    {0, 2, 85},
    {0, 3, 85},
    {0, 4, 85},
    {0, 5, 85},
    {3, 1, 85},
}

```

Definition at line 140 of file york.c.

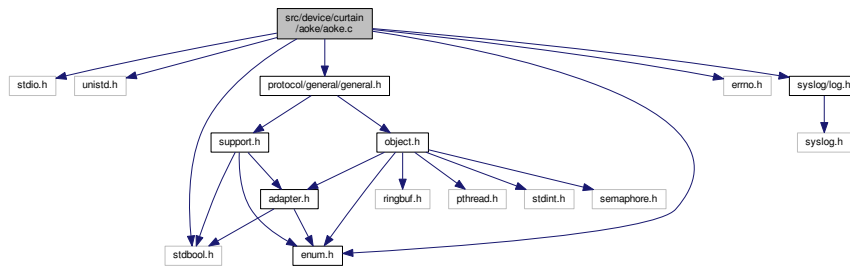
## 7.32 src/device/curtain/aoke/aoke.c File Reference

```

#include <stdio.h>
#include <unistd.h>
#include <stdbool.h>
#include <errno.h>
#include "enum.h"
#include "syslog/log.h"
#include "protocol/general/general.h"

```

Include dependency graph for aoke.c:



## Data Structures

- struct [rs485\\_curtain\\_ao\\_ke\\_send\\_package\\_t](#)

## Macros

- #define [RS485\\_CURTAIN\\_AO\\_KE\\_SI](#) 0x9a
- #define [RS485\\_CURTAIN\\_AO\\_KE\\_COMMAND\\_CONTROL](#) 0x0a
- #define [RS485\\_CURTAIN\\_AO\\_KE\\_COMMAND\\_POSTION](#) 0xdd
- #define [RS485\\_CURTAIN\\_AO\\_KE\\_COMMAND\\_SETTING](#) 0xd5
- #define [RS485\\_CURTAIN\\_AO\\_KE\\_COMMAND\\_GETTING](#) 0xcc
- #define [RS485\\_CURTAIN\\_AO\\_KE\\_COMMAND\\_ADDRING](#) 0xaa
- #define [RS485\\_CURTAIN\\_AO\\_KE\\_COMMAND\\_DELETE](#) 0xa6
- #define [RS485\\_CURTAIN\\_AO\\_KE\\_COMMAND\\_POINT](#) 0xda
- #define [RS485\\_CURTAIN\\_AO\\_KE\\_CONTROL\\_UP](#) 0xdd
- #define [RS485\\_CURTAIN\\_AO\\_KE\\_CONTROL\\_STOP](#) 0x0d
- #define [RS485\\_CURTAIN\\_AO\\_KE\\_CONTROL\\_DOWN](#) 0xee
- #define [RS485\\_CURTAIN\\_AO\\_KE\\_CONTROL\\_SET\\_ADDR](#) 0xaa
- #define [RS485\\_CURTAIN\\_AO\\_KE\\_CONTROL\\_DELETE\\_ADDR](#) 0xa6
- #define [RS485\\_CURTAIN\\_AO\\_KE\\_CONTROL\\_MIDDLE\\_1](#) 0x01
- #define [RS485\\_CURTAIN\\_AO\\_KE\\_CONTROL\\_MIDDLE\\_2](#) 0x02
- #define [RS485\\_CURTAIN\\_AO\\_KE\\_CONTROL\\_MIDDLE\\_3](#) 0x03
- #define [RS485\\_CURTAIN\\_AO\\_KE\\_CONTROL\\_MIDDLE\\_4](#) 0x04
- #define [RS485\\_CURTIAN\\_AO\\_KE\\_POSTION](#) 0x00
- #define [RS485\\_CURTIAN\\_AO\\_KE\\_SETTING\\_HANDLE](#) 0x01
- #define [RS485\\_CURTIAN\\_AO\\_KE\\_GETTING\\_STATUS](#) 0xcc
- #define [RS485\\_CURTAIN\\_AO\\_KE\\_ADDRING](#) 0xaa
- #define [RS485\\_CURTAIN\\_AO\\_KE\\_DELETE](#) 0xa6
- #define [RS485\\_CURTAIN\\_AO\\_KE\\_POINT\\_UP](#) 0xdd
- #define [RS485\\_CURTAIN\\_AO\\_KE\\_POINT\\_MIDDLE](#) 0xcc
- #define [RS485\\_CURTAIN\\_AO\\_KE\\_POINT\\_DOWN](#) 0xda
- #define [RS485\\_CURTAIN\\_AO\\_KE\\_POINT\\_SAVE](#) 0xaa
- #define [RS485\\_CURTAIN\\_AO\\_KE\\_POINT\\_DELETE](#) 0x00

## Functions

- static unsigned char [get\\_check](#) ([rs485\\_curtain\\_ao\\_ke\\_send\\_package\\_t](#) \*package)
- int [aoke\\_send\\_package\\_handle](#) (volatile void \*arg)  
*aoke\_send\_package\_handle aoke curtian package a send buffer*
- int [aoke\\_rcv\\_package\\_handle](#) (volatile void \*arg)  
*aoke\_rcv\_package\_handle aoke curtain process the receive package*

### 7.32.1 Macro Definition Documentation

#### 7.32.1.1 `#define RS485_CURTAIN_AO_KE_ADDRING 0xaa`

Definition at line 74 of file aoke.c.

#### 7.32.1.2 `#define RS485_CURTAIN_AO_KE_COMMAND_ADDRING 0xaa`

Definition at line 52 of file aoke.c.

#### 7.32.1.3 `#define RS485_CURTAIN_AO_KE_COMMAND_CONTROL 0x0a`

Definition at line 48 of file aoke.c.

#### 7.32.1.4 `#define RS485_CURTAIN_AO_KE_COMMAND_DELETE 0xa6`

Definition at line 53 of file aoke.c.

#### 7.32.1.5 `#define RS485_CURTAIN_AO_KE_COMMAND_GETTING 0xcc`

Definition at line 51 of file aoke.c.

#### 7.32.1.6 `#define RS485_CURTAIN_AO_KE_COMMAND_POINT 0xda`

Definition at line 54 of file aoke.c.

#### 7.32.1.7 `#define RS485_CURTAIN_AO_KE_COMMAND_POSTION 0xdd`

Definition at line 49 of file aoke.c.

#### 7.32.1.8 `#define RS485_CURTAIN_AO_KE_COMMAND_SETTING 0xd5`

Definition at line 50 of file aoke.c.

#### 7.32.1.9 `#define RS485_CURTAIN_AO_KE_CONTROL_DELETE_ADDR 0xa6`

Definition at line 61 of file aoke.c.

#### 7.32.1.10 `#define RS485_CURTAIN_AO_KE_CONTROL_DOWN 0xee`

Definition at line 59 of file aoke.c.

#### 7.32.1.11 `#define RS485_CURTAIN_AO_KE_CONTROL_MIDDLE_1 0x01`

Definition at line 62 of file aoke.c.

#### 7.32.1.12 `#define RS485_CURTAIN_AO_KE_CONTROL_MIDDLE_2 0x02`

Definition at line 63 of file aoke.c.

7.32.1.13 `#define RS485_CURTAIN_AO_KE_CONTROL_MIDDLE_3 0x03`

Definition at line 64 of file aoke.c.

7.32.1.14 `#define RS485_CURTAIN_AO_KE_CONTROL_MIDDLE_4 0x04`

Definition at line 65 of file aoke.c.

7.32.1.15 `#define RS485_CURTAIN_AO_KE_CONTROL_SET_ADDR 0xaa`

Definition at line 60 of file aoke.c.

7.32.1.16 `#define RS485_CURTAIN_AO_KE_CONTROL_STOP 0x0d`

Definition at line 58 of file aoke.c.

7.32.1.17 `#define RS485_CURTAIN_AO_KE_CONTROL_UP 0xdd`

Definition at line 57 of file aoke.c.

7.32.1.18 `#define RS485_CURTAIN_AO_KE_DELETE 0xa6`

Definition at line 76 of file aoke.c.

7.32.1.19 `#define RS485_CURTAIN_AO_KE_POINT_DELETE 0x00`

Definition at line 82 of file aoke.c.

7.32.1.20 `#define RS485_CURTAIN_AO_KE_POINT_DOWN 0xda`

Definition at line 80 of file aoke.c.

7.32.1.21 `#define RS485_CURTAIN_AO_KE_POINT_MIDDLE 0xcc`

Definition at line 79 of file aoke.c.

7.32.1.22 `#define RS485_CURTAIN_AO_KE_POINT_SAVE 0xaa`

Definition at line 81 of file aoke.c.

7.32.1.23 `#define RS485_CURTAIN_AO_KE_POINT_UP 0xdd`

Definition at line 78 of file aoke.c.

7.32.1.24 `#define RS485_CURTAIN_AO_KE_SI 0x9a`

ao\_ke curtain on RS485 baud rate : 9600 stop bit : 1 data bit : 8 parity bit : NULL

format:

```
|SI|ADDR0|ADDR1|ADDR2|CMD|DATA|CHECK|
```

Definition at line 45 of file aoke.c.

7.32.1.25 `#define RS485_CURTIAN_AO_KE_GETTING_STATUS 0xcc`

Definition at line 72 of file aoke.c.

7.32.1.26 `#define RS485_CURTIAN_AO_KE_POSTION 0x00`

Definition at line 68 of file aoke.c.

7.32.1.27 `#define RS485_CURTIAN_AO_KE_SETTING_HANDLE 0x01`

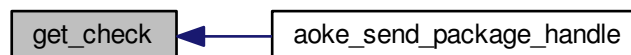
Definition at line 70 of file aoke.c.

## 7.32.2 Function Documentation

7.32.2.1 `static unsigned char get_check ( rs485_curtain_ao_ke_send_package_t* package ) [static]`

Definition at line 113 of file aoke.c.

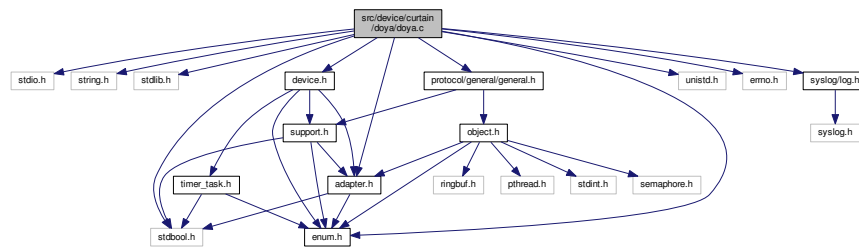
Here is the caller graph for this function:



## 7.33 src/device/curtain/doya/doya.c File Reference

```
#include <stdio.h>
#include <string.h>
#include <stdlib.h>
#include <stdbool.h>
#include <unistd.h>
#include <errno.h>
#include "enum.h"
#include "syslog/log.h"
#include "adapter.h"
#include "device.h"
#include "protocol/general/general.h"
```

Include dependency graph for doya.c:



## Data Structures

- struct [package](#)

## Macros

- `#define CURTAIN_COMMAND 0x03`
- `#define CURTAIN_READ 0x01`
- `#define CURTAIN_WRITE 0x02`
- `#define CURTAIN_COMMAND_OPEN 0x01`
- `#define CURTAIN_COMMAND_CLOSE 0x02`
- `#define CURTAIN_COMMAND_STOP 0x03`
- `#define CURTAIN_COMMAND_PERCENT 0x04`
- `#define CURTAIN_COMMAND_DELETE 0x07`
- `#define CURTAIN_COMMAND_REFACTORY 0x08`
- `#define CURTAIN_READ_WRITE_ADDR_LOW 0x00`
- `#define CURTAIN_READ_WRITE_ADDR_HIGH 0x01`
- `#define CURTAIN_READ_WRITE_ADDR 0x00`
- `#define CURTAIN_READ_WRITE_PERCENT 0x02`
- `#define CURTAIN_READ_WRITE_DIRECTION 0x03`
- `#define CURTAIN_READ_WRITE_HANDLE 0x04`
- `#define CURTAIN_READ_WRITE_SWITCH_PASSIVE 0x27`
- `#define CURTAIN_READ_WRITE_SWITCH_ACTIVE 0x28`
- `#define CURTAIN_READ_WRITE_VERSION 0xfe`
- `#define MOTOR_POSITIVE 0x00`
- `#define MOTOR_NEGATIVE 0x01`
- `#define HANDLE_ENABLE 0x00`
- `#define HANDLE_DISABLE 0x01`
- `#define SWITCH_PASSIVE_DOUBLE_REBOUND 0x01`
- `#define SWITCH_PASSIVE_DOUBLE_NO_REBOUND 0x02`
- `#define SWITCH_PASSIVE_ELECTRONIC_DC246 0x03`
- `#define SWITCH_PASSIVE_SINGLE_CYCLE 0x04`
- `#define SWITCH_ACTIVE_DOUBLE_LINE 0x00`
- `#define SWITCH_ACTIVE_SINGLE_LINE 0x01`

## Enumerations

- enum `command` {  
`COMMAND_OPEN, COMMAND_CLOSE, COMMAND_STOP, COMMAND_PERCENT,`  
`COMMAND_DELETE, COMMAND_REFACTORY, WO_ADDR, RO_PERCENT,`  
`RW_DIRECTION, RW_HANDLE, RW_SWITCH_PASSIVE, RW_SWITCH_ACTIVE,`  
`RO_VERSION` }



## Functions

- static int [rs485\\_send](#) (int port, void \*buffer, int len)
- static int [rs485\\_read](#) (int port, void \*buffer, int len)
- static void [modbus\\_crc16](#) (unsigned char result[2], const unsigned char \*pucFrame, int usLen)
- static int [send\\_package](#) (int port, const struct [package](#) \*package)
- int [receive\\_package](#) (int port, struct [package](#) \*package)
- int [open\\_curtain\\_no\\_reply](#) (int port, const unsigned char [addr](#)[2])
- int [close\\_curtain\\_no\\_reply](#) (int port, const unsigned char [addr](#)[2])
- int [stop\\_curtain\\_no\\_reply](#) (int port, const unsigned char [addr](#)[2])
- int [percent\\_curtain\\_no\\_reply](#) (int port, const unsigned char [addr](#)[2], unsigned char data)
- int [delete\\_track\\_curtain\\_no\\_reply](#) (int port, const unsigned char [addr](#)[2])
- int [refactory\\_curtain\\_no\\_reply](#) (int port, const unsigned char [addr](#)[2])
- int [set\\_addr\\_curtain\\_no\\_reply](#) (int port, const unsigned char [addr](#)[2], unsigned char set[2])
- int [set\\_direction\\_curtain\\_no\\_reply](#) (int port, const unsigned char [addr](#)[2], unsigned char same)
- int [set\\_handle\\_enable\\_curtain\\_no\\_reply](#) (int port, const unsigned char [addr](#)[2], unsigned char enable)
- int [set\\_switch\\_passive\\_curtain\\_no\\_reply](#) (int port, const unsigned char [addr](#)[2], unsigned char type)
- int [set\\_switch\\_active\\_curtain\\_no\\_reply](#) (int port, const unsigned char [addr](#)[2], unsigned char type)
- int [read\\_percent\\_curtain\\_no\\_reply](#) (int port, const unsigned char [addr](#)[2])
- int [read\\_version\\_curtain\\_no\\_reply](#) (int port, const unsigned char [addr](#)[2])
- static int [doya\\_send\\_package](#) (unsigned char \*send\_buffer, int buffer\_len, const struct [package](#) \*package)
- int [doya\\_send\\_package\\_handle](#) (volatile void \*arg)  
*doya\_send\_package\_handle The dooya curtain package a send buffer*
- int [doya\\_recv\\_package\\_handle](#) (volatile void \*arg)  
*doya\_recv\_package\_handle The dooya curtain process the receive data.*

## Variables

- static const unsigned char [crc\\_high](#) []
- static const unsigned char [crc\\_low](#) []

### 7.33.1 Macro Definition Documentation

#### 7.33.1.1 #define CURTAIN\_COMMAND 0x03

Definition at line 90 of file doya.c.

#### 7.33.1.2 #define CURTAIN\_COMMAND\_CLOSE 0x02

Definition at line 96 of file doya.c.

#### 7.33.1.3 #define CURTAIN\_COMMAND\_DELETE 0x07

Definition at line 99 of file doya.c.

#### 7.33.1.4 #define CURTAIN\_COMMAND\_OPEN 0x01

Definition at line 95 of file doya.c.

#### 7.33.1.5 #define CURTAIN\_COMMAND\_PERCENT 0x04

Definition at line 98 of file doya.c.

#### 7.33.1.6 `#define CURTAIN_COMMAND_REFACTORY 0x08`

Definition at line 100 of file doya.c.

#### 7.33.1.7 `#define CURTAIN_COMMAND_STOP 0x03`

Definition at line 97 of file doya.c.

#### 7.33.1.8 `#define CURTAIN_READ 0x01`

Definition at line 91 of file doya.c.

#### 7.33.1.9 `#define CURTAIN_READ_WRITE_ADDR 0x00`

Definition at line 105 of file doya.c.

#### 7.33.1.10 `#define CURTAIN_READ_WRITE_ADDR_HIGH 0x01`

Definition at line 104 of file doya.c.

#### 7.33.1.11 `#define CURTAIN_READ_WRITE_ADDR_LOW 0x00`

Definition at line 103 of file doya.c.

#### 7.33.1.12 `#define CURTAIN_READ_WRITE_DIRECTION 0x03`

Definition at line 107 of file doya.c.

#### 7.33.1.13 `#define CURTAIN_READ_WRITE_HANDLE 0x04`

Definition at line 108 of file doya.c.

#### 7.33.1.14 `#define CURTAIN_READ_WRITE_PERCENT 0x02`

Definition at line 106 of file doya.c.

#### 7.33.1.15 `#define CURTAIN_READ_WRITE_SWITCH_ACTIVE 0x28`

Definition at line 110 of file doya.c.

#### 7.33.1.16 `#define CURTAIN_READ_WRITE_SWITCH_PASSIVE 0x27`

Definition at line 109 of file doya.c.

#### 7.33.1.17 `#define CURTAIN_READ_WRITE_VERSION 0xfe`

Definition at line 111 of file doya.c.

**7.33.1.18 #define CURTAIN\_WRITE 0x02**

Definition at line 92 of file doya.c.

**7.33.1.19 #define HANDLE\_DISABLE 0x01**

Definition at line 118 of file doya.c.

**7.33.1.20 #define HANDLE\_ENABLE 0x00**

Definition at line 117 of file doya.c.

**7.33.1.21 #define MOTOR\_NEGATIVE 0x01**

Definition at line 115 of file doya.c.

**7.33.1.22 #define MOTOR\_POSITIVE 0x00**

Definition at line 114 of file doya.c.

**7.33.1.23 #define SWITCH\_ACTIVE\_DOUBLE\_LINE 0x00**

Definition at line 125 of file doya.c.

**7.33.1.24 #define SWITCH\_ACTIVE\_SINGLE\_LINE 0x01**

Definition at line 126 of file doya.c.

**7.33.1.25 #define SWITCH\_PASSIVE\_DOUBLE\_NO\_REBOUND 0x02**

Definition at line 121 of file doya.c.

**7.33.1.26 #define SWITCH\_PASSIVE\_DOUBLE\_REBOUND 0x01**

Definition at line 120 of file doya.c.

**7.33.1.27 #define SWITCH\_PASSIVE\_ELECTRONIC\_DC246 0x03**

Definition at line 122 of file doya.c.

**7.33.1.28 #define SWITCH\_PASSIVE\_SINGLE\_CYCLE 0x04**

Definition at line 123 of file doya.c.

**7.33.2 Enumeration Type Documentation****7.33.2.1 enum command**

du\_ya curtain on RS485 baud rate : 9600 stop bit : 1 data bit : 8 parity bit : NULL

## Enumerator

**COMMAND\_OPEN**  
**COMMAND\_CLOSE**  
**COMMAND\_STOP**  
**COMMAND\_PERCENT**  
**COMMAND\_DELETE**  
**COMMAND\_REFACTORY**  
**WO\_ADDR**  
**RO\_PERCENT**  
**RW\_DIRECTION**  
**RW\_HANDLE**  
**RW\_SWITCH\_PASSIVE**  
**RW\_SWITCH\_ACTIVE**  
**RO\_VERSION**

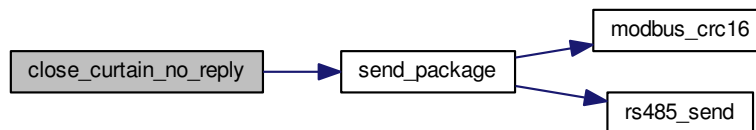
Definition at line 52 of file doya.c.

### 7.33.3 Function Documentation

#### 7.33.3.1 int close\_curtain\_no\_reply ( int *port*, const unsigned char *addr*[2] )

Definition at line 389 of file doya.c.

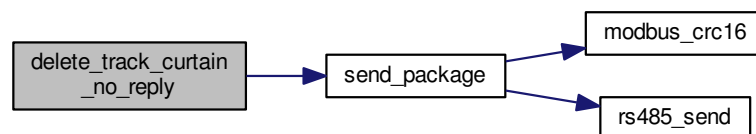
Here is the call graph for this function:



#### 7.33.3.2 int delete\_track\_curtain\_no\_reply ( int *port*, const unsigned char *addr*[2] )

Definition at line 442 of file doya.c.

Here is the call graph for this function:



7.33.3.3 `static int doya_send_package ( unsigned char * send_buffer, int buffer_len, const struct package * package )`  
`[static]`

Definition at line 607 of file doya.c.

Here is the call graph for this function:



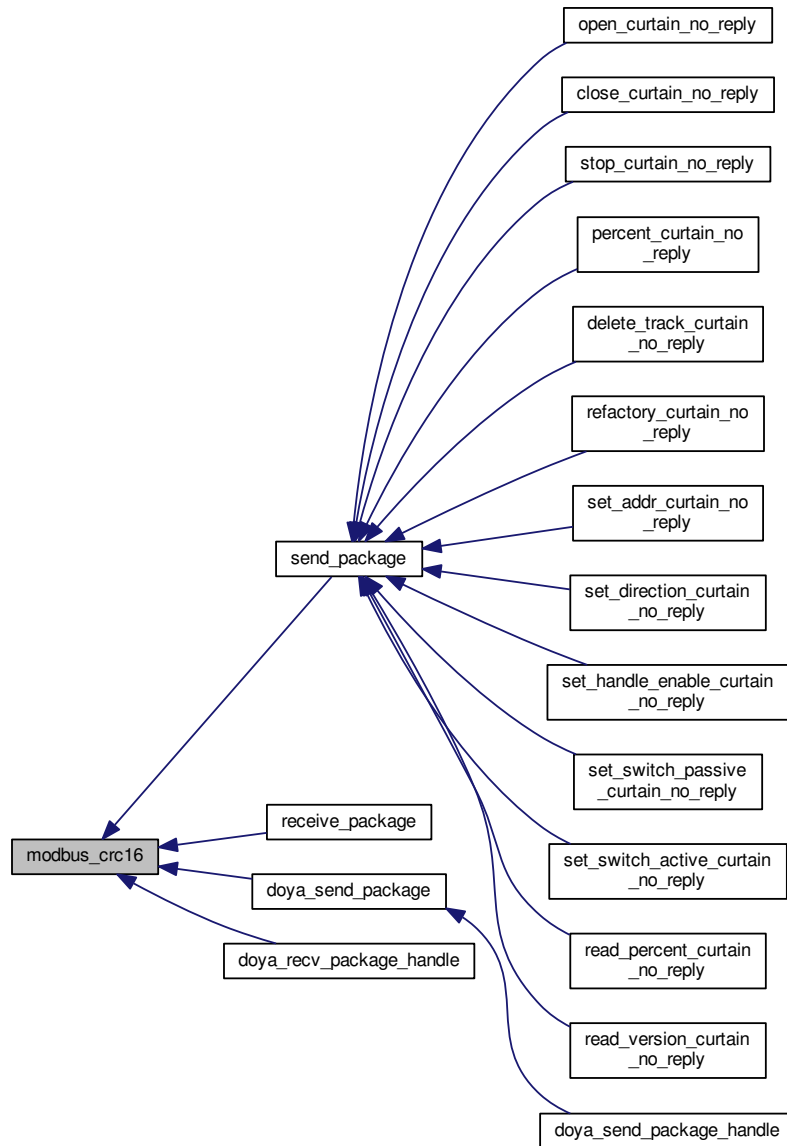
Here is the caller graph for this function:



7.33.3.4 `static void modbus_crc16 ( unsigned char result[2], const unsigned char * pucFrame, int usLen )` `[static]`

Definition at line 192 of file doya.c.

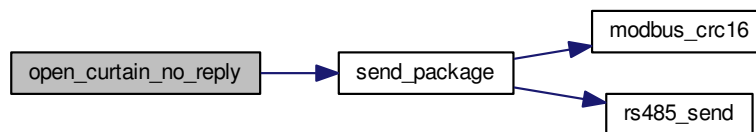
Here is the caller graph for this function:



### 7.33.3.5 int open\_curtain\_no\_reply ( int port, const unsigned char addr[2] )

Definition at line 372 of file doya.c.

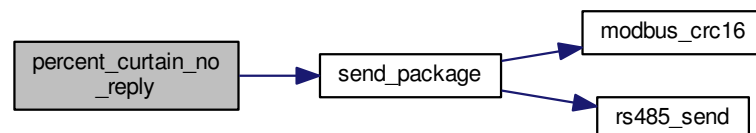
Here is the call graph for this function:



#### 7.33.3.6 `int percent_curtain_no_reply ( int port, const unsigned char addr[2], unsigned char data )`

Definition at line 423 of file doya.c.

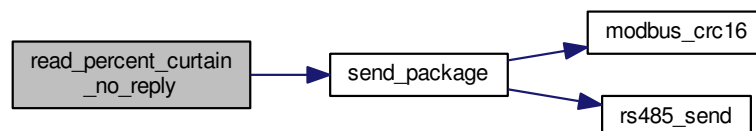
Here is the call graph for this function:



#### 7.33.3.7 `int read_percent_curtain_no_reply ( int port, const unsigned char addr[2] )`

Definition at line 572 of file doya.c.

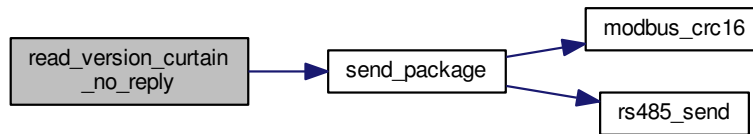
Here is the call graph for this function:



#### 7.33.3.8 `int read_version_curtain_no_reply ( int port, const unsigned char addr[2] )`

Definition at line 589 of file doya.c.

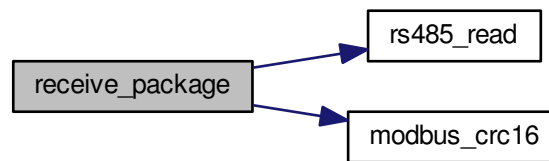
Here is the call graph for this function:



#### 7.33.3.9 `int receive_package ( int port, struct package * package )`

Definition at line 311 of file `doya.c`.

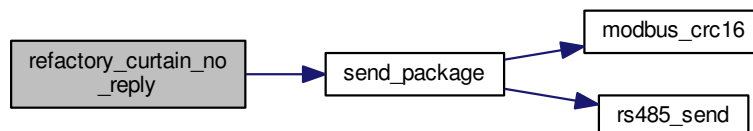
Here is the call graph for this function:



#### 7.33.3.10 `int refractory_curtain_no_reply ( int port, const unsigned char addr[2] )`

Definition at line 459 of file `doya.c`.

Here is the call graph for this function:



#### 7.33.3.11 `static int rs485_read ( int port, void * buffer, int len )` `[inline],[static]`

Definition at line 135 of file `doya.c`.



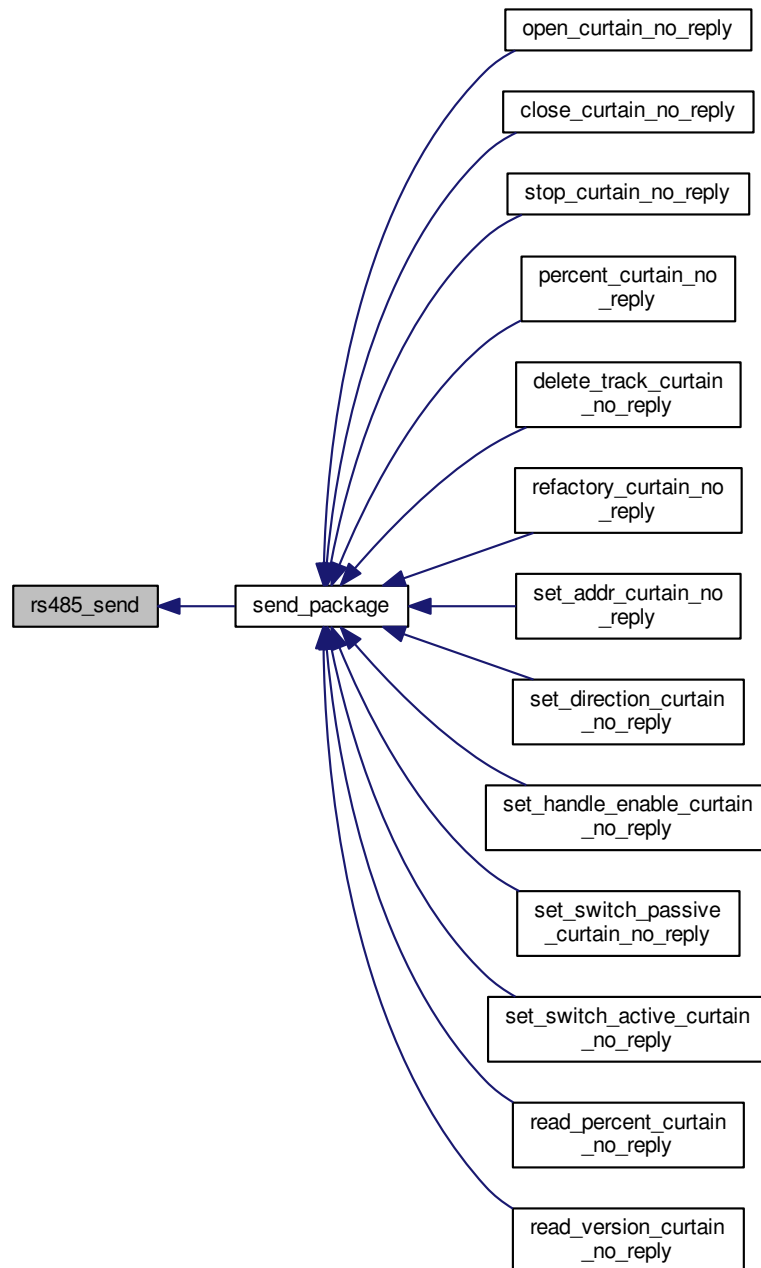
Here is the caller graph for this function:



7.33.3.12 `static int rs485_send ( int port, void * buffer, int len )` `[inline],[static]`

Definition at line 130 of file doya.c.

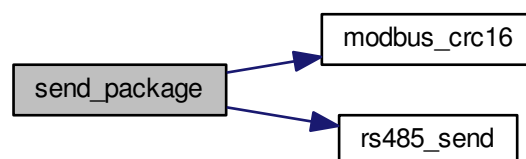
Here is the caller graph for this function:



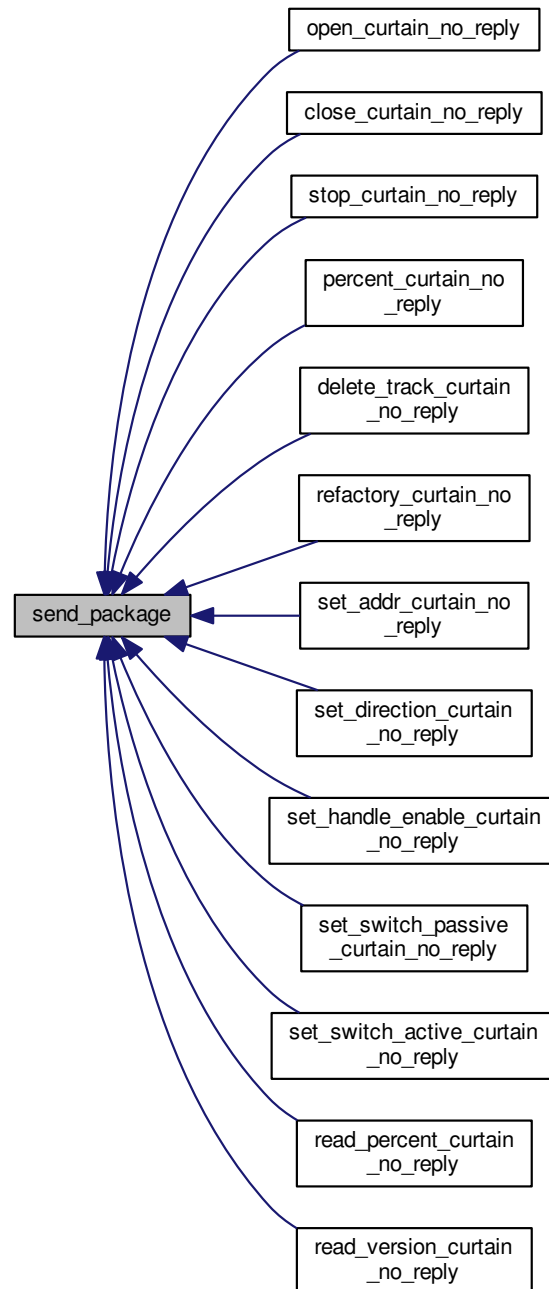
7.33.3.13 `static int send_package ( int port, const struct package * package )` `[static]`

Definition at line 228 of file doya.c.

Here is the call graph for this function:



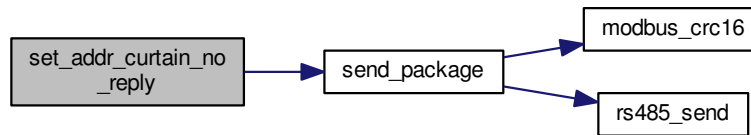
Here is the caller graph for this function:



7.33.3.14 `int set_addr_curtain_no_reply ( int port, const unsigned char addr[2], unsigned char set[2] )`

Definition at line 476 of file doya.c.

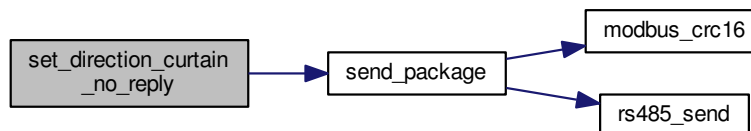
Here is the call graph for this function:



7.33.3.15 `int set_direction_curtain_no_reply ( int port, const unsigned char addr[2], unsigned char same )`

Definition at line 497 of file doya.c.

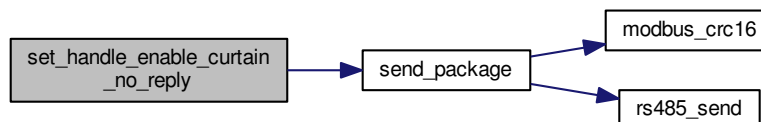
Here is the call graph for this function:



7.33.3.16 `int set_handle_enable_curtain_no_reply ( int port, const unsigned char addr[2], unsigned char enable )`

Definition at line 516 of file doya.c.

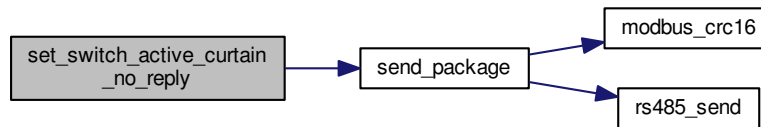
Here is the call graph for this function:



7.33.3.17 `int set_switch_active_curtain_no_reply ( int port, const unsigned char addr[2], unsigned char type )`

Definition at line 554 of file doya.c.

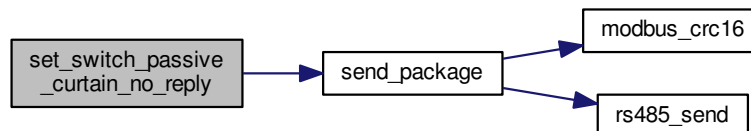
Here is the call graph for this function:



7.33.3.18 `int set_switch_passive_curtain_no_reply ( int port, const unsigned char addr[2], unsigned char type )`

Definition at line 535 of file doya.c.

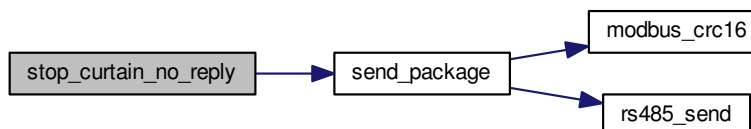
Here is the call graph for this function:



7.33.3.19 `int stop_curtain_no_reply ( int port, const unsigned char addr[2] )`

Definition at line 406 of file doya.c.

Here is the call graph for this function:



## 7.33.4 Variable Documentation

7.33.4.1 `const unsigned char crc_high[]` [static]

**Initial value:**

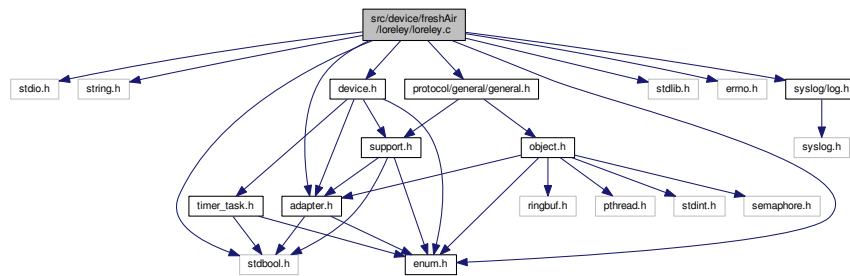
Definition at line 141 of file doya.c.

**Initial value:**

Definition at line 166 of file doya.c.

```
#include <stdio.h>
#include <string.h>
#include <stdbool.h>
#include <stdlib.h>
#include <errno.h>
#include "enum.h"
#include "syslog/log.h"
#include "adapter.h"
#include "device.h"
#include "protocol/general/general.h"
```

Include dependency graph for loreley.c:



## Macros

- #define [SOI\\_SEND](#) 0xaa
- #define [SOI\\_RECEIVE](#) 0x55
- #define [ADR\\_BROADCAST](#) 0xff
- #define [ADR\\_DEFAULT](#) 0x01
- #define [RTN\\_SEND](#) 0x60
- #define [RTN\\_RECEIVE\\_CMD\\_RIGHT](#) 0x01
- #define [RTN\\_RECEIVE\\_CHK\\_ERROR](#) 0x02
- #define [RTN\\_RECEIVE\\_CMD\\_INVALID](#) 0x03
- #define [EOI](#) 0x0d
- #define [RS485\\_NEW\\_TREND\\_SET\\_ADDR\\_CID](#) 0x20
- #define [RS485\\_NEW\\_TREND\\_GET\\_ADDR\\_CID](#) 0x21
- #define [RS485\\_NEW\\_TREND\\_GET\\_INFO\\_CID](#) 0x22
- #define [RS485\\_NEW\\_TREND\\_SET\\_ARG\\_CID](#) 0x23
- #define [RS485\\_NEW\\_TREND\\_RESTART\\_CID](#) 0x24
- #define [RS485\\_NEW\\_TREND\\_MODE\\_WAITING](#) 0x00
- #define [RS485\\_NEW\\_TREND\\_MODE\\_AUTOING](#) 0x01
- #define [RS485\\_NEW\\_TREND\\_MODE\\_OUT\\_CRC](#) 0x02
- #define [RS485\\_NEW\\_TREND\\_MODE\\_IN\\_CRC](#) 0x03
- #define [RS485\\_NEW\\_TREND\\_MODE\\_KILLING](#) 0x04
- #define [RS485\\_NEW\\_TREND\\_RUN\\_STATUS\\_OFF](#) 0x00
- #define [RS485\\_NEW\\_TREND\\_RUN\\_STATUS\\_ON](#) 0x01
- #define [RS485\\_NEW\\_TREND\\_STATUS\\_ERROR](#) 0x01
- #define [RS485\\_NEW\\_TREND\\_STATUS\\_NORMAL](#) 0x00
- #define [NEW\\_TREND\\_PACKAGE\\_MAX](#) 20

## Functions

- static unsigned char [calculate\\_sum\\_check](#) (unsigned char \*value, int length)
- static int [loreley\\_send\\_package](#) (unsigned char \*send\_buffer, int send\_buffer\_len, unsigned char [addr](#), unsigned char msg\_cid, const unsigned char \*data)
- int [loreley\\_send\\_package\\_handle](#) (volatile void \*arg)  
*loreley\_send\_package\_handle loreley fresh air package send a buffer*
- int [loreley\\_rcv\\_package\\_handle](#) (volatile void \*arg)  
*loreley\_rcv\_package\_handle loreley fresh air process the receive data.*

## Variables

- static const unsigned char [rs485\\_set\\_new\\_trend\\_table](#) [2][5]



### 7.34.1 Macro Definition Documentation

#### 7.34.1.1 `#define ADR_BROADCAST 0xff`

Definition at line 36 of file loreley.c.

#### 7.34.1.2 `#define ADR_DEFAULT 0x01`

Definition at line 37 of file loreley.c.

#### 7.34.1.3 `#define EOI 0x0d`

Definition at line 42 of file loreley.c.

#### 7.34.1.4 `#define NEW_TREND_PACKAGE_MAX 20`

Definition at line 66 of file loreley.c.

#### 7.34.1.5 `#define RS485_NEW_TREND_GET_ADDR_CID 0x21`

Definition at line 46 of file loreley.c.

#### 7.34.1.6 `#define RS485_NEW_TREND_GET_INFO_CID 0x22`

Definition at line 47 of file loreley.c.

#### 7.34.1.7 `#define RS485_NEW_TREND_MODE_AUTOING 0x01`

Definition at line 53 of file loreley.c.

#### 7.34.1.8 `#define RS485_NEW_TREND_MODE_IN_CRC 0x03`

Definition at line 55 of file loreley.c.

#### 7.34.1.9 `#define RS485_NEW_TREND_MODE_KILLING 0x04`

Definition at line 56 of file loreley.c.

#### 7.34.1.10 `#define RS485_NEW_TREND_MODE_OUT_CRC 0x02`

Definition at line 54 of file loreley.c.

#### 7.34.1.11 `#define RS485_NEW_TREND_MODE_WAITING 0x00`

Definition at line 52 of file loreley.c.

#### 7.34.1.12 `#define RS485_NEW_TREND_RESTART_CID 0x24`

Definition at line 49 of file loreley.c.

7.34.1.13 `#define RS485_NEW_TREND_RUN_STATUS_OFF 0x00`

Definition at line 58 of file loreley.c.

7.34.1.14 `#define RS485_NEW_TREND_RUN_STATUS_ON 0x01`

Definition at line 59 of file loreley.c.

7.34.1.15 `#define RS485_NEW_TREND_SET_ADDR_CID 0x20`

Definition at line 45 of file loreley.c.

7.34.1.16 `#define RS485_NEW_TREND_SET_ARG_CID 0x23`

Definition at line 48 of file loreley.c.

7.34.1.17 `#define RS485_NEW_TREND_STATUS_ERROR 0x01`

Definition at line 61 of file loreley.c.

7.34.1.18 `#define RS485_NEW_TREND_STATUS_NORMAL 0x00`

Definition at line 62 of file loreley.c.

7.34.1.19 `#define RTN_RECEIVE_CHK_ERROR 0x02`

Definition at line 40 of file loreley.c.

7.34.1.20 `#define RTN_RECEIVE_CMD_INVALID 0x03`

Definition at line 41 of file loreley.c.

7.34.1.21 `#define RTN_RECEIVE_CMD_RIGHT 0x01`

Definition at line 39 of file loreley.c.

7.34.1.22 `#define RTN_SEND 0x60`

Definition at line 38 of file loreley.c.

7.34.1.23 `#define SOI_RECEIVE 0x55`

Definition at line 35 of file loreley.c.

7.34.1.24 `#define SOI_SEND 0xaa`

package protocol

Definition at line 34 of file loreley.c.

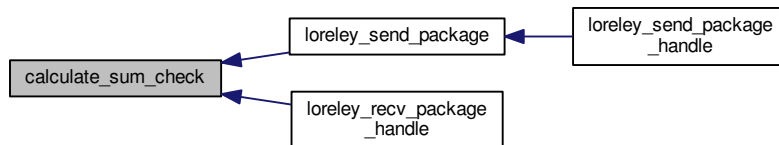
### 7.34.2 Function Documentation

#### 7.34.2.1 static unsigned char calculate\_sum\_check ( unsigned char \* *value*, int *length* ) [static]

static function define

Definition at line 77 of file loreley.c.

Here is the caller graph for this function:



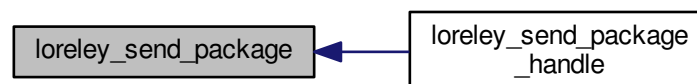
#### 7.34.2.2 static int loreley\_send\_package ( unsigned char \* *send\_buffer*, int *send\_buffer\_len*, unsigned char *addr*, unsigned char *msg\_cid*, const unsigned char \* *data* ) [static]

Definition at line 425 of file loreley.c.

Here is the call graph for this function:



Here is the caller graph for this function:



### 7.34.3 Variable Documentation

#### 7.34.3.1 const unsigned char rs485\_set\_new\_trend\_table[2][5] [static]

**Initial value:**

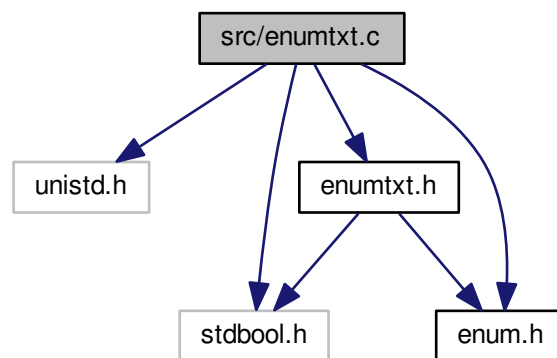
```
= {
{0x01, 0x01, 0x00, 0x00, 0x00},
{0x01, 0x00, 0x00, 0x00, 0x00}
}
```

Definition at line 69 of file loreley.c.

## 7.35 src/enumtxt.c File Reference

```
#include <unistd.h>
#include <stdbool.h>
#include "enumtxt.h"
#include "enum.h"
```

Include dependency graph for enumtxt.c:



## Functions

- char \* [get\\_enum\\_txt\\_service](#) (rs485\_service\_type\_enum type)  
*get\_enum\_txt\_service get enum rs485 service message type*
- char \* [get\\_enum\\_txt\\_rs485\\_device\\_type](#) (rs485\_device\_type\_enum type)  
*get\_enum\_txt\_rs485\_device\_type get enum rs485 device type*
- char \* [get\\_enum\\_txt\\_rs485\\_protocol\\_type](#) (rs485\_protocol\_type\_enum type)  
*get\_enum\_txt\_rs485\_protocol\_type get enum rs485 protocol type*
- char \* [get\\_enum\\_txt\\_device\\_method](#) (rs485\_device\_method\_enum type)  
*get\_enum\_txt\_device\_method get enum device method(command)*
- char \* [get\\_enum\\_txt\\_device\\_factory](#) (rs485\_factory\_name\_enum name)  
*get\_enum\_txt\_device\_factory get enum device factory name*
- char \* [get\\_enum\\_txt\\_bool](#) (bool status)  
*get\_enum\_txt\_bool get the string about bool value*

## 7.36 src/item\_config.c File Reference

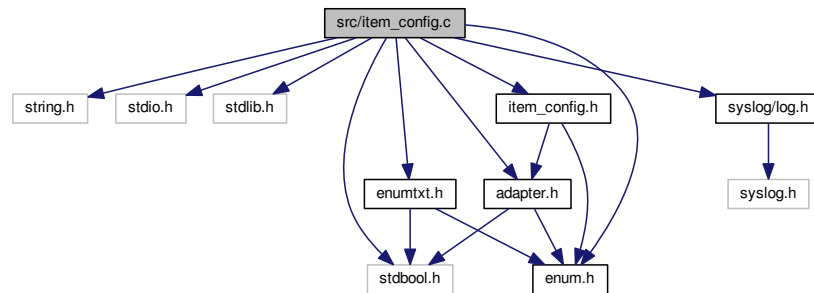
```
#include <string.h>
```

```

#include <stdio.h>
#include <stdlib.h>
#include <stdbool.h>
#include "item_config.h"
#include "enum.h"
#include "adapter.h"
#include "enumtxt.h"
#include "syslog/log.h"

```

Include dependency graph for item\_config.c:



## Macros

- `#define PANNO_S_ITEM_DEFAULT (1)`
- `#define PANNO_S_ITEM_WENRUDE (0)`
- `#define PANNO_S_ITEM_ARMANI (0)`
- `#define PANNO_S_ITEM_SHAOCHENGGUOJI (0)`

## Functions

- static void `_mount_device` (`adapter_t` \*adapter, int object\_id, `rs485_factory_name_enum` device, unsigned char addr)
- void `panno_s_item_config` (`adapter_t` \*adapter, `rs485_device_type_enum` device\_type, unsigned char device\_addr)

*panno\_s\_item\_config This function is offer the pannoS item config*

### 7.36.1 Macro Definition Documentation

#### 7.36.1.1 `#define PANNO_S_ITEM_ARMANI (0)`

Definition at line 42 of file item\_config.c.

#### 7.36.1.2 `#define PANNO_S_ITEM_DEFAULT (1)`

Definition at line 32 of file item\_config.c.

#### 7.36.1.3 `#define PANNO_S_ITEM_SHAOCHENGGUOJI (0)`

Definition at line 47 of file item\_config.c.

#### 7.36.1.4 #define PANNO\_S\_ITEM\_WENRUDE (0)

Definition at line 37 of file item\_config.c.

### 7.36.2 Function Documentation

#### 7.36.2.1 static void \_mount\_device ( adapter\_t \* adapter, int object\_id, rs485\_factory\_name\_enum device, unsigned char addr ) [static]

Definition at line 51 of file item\_config.c.

Here is the caller graph for this function:



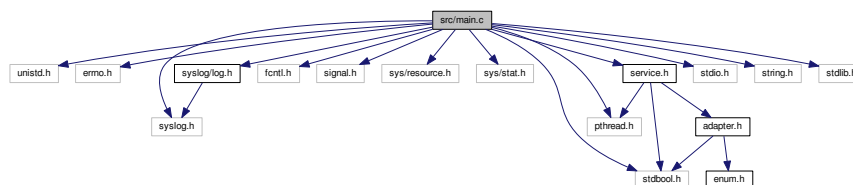
### 7.37 src/main.c File Reference

```

#include <unistd.h>
#include <errno.h>
#include <syslog.h>
#include <fcntl.h>
#include <signal.h>
#include <sys/resource.h>
#include <sys/stat.h>
#include <pthread.h>
#include <stdio.h>
#include <string.h>
#include <stdlib.h>
#include <stdbool.h>
#include "service.h"
#include "syslog/log.h"

```

Include dependency graph for main.c:



### Macros

- #define `LOCKFILE` `"/var/run/rs485.pid"`
- #define `LOCKMODE` `(S_IRUSR | S_IWUSR | S_IRGRP | S_IROTH)`

## Functions

- void \* [signal\\_handle\\_pthread](#) (void \*arg)
- void [daemonize](#) (const char \*cmd)
- static int [lockfile](#) (int fd)
- static int [already\\_running](#) (void)
- int [main](#) (int argc, char \*argv[])

## Variables

- static sigset\_t [mask](#)

### 7.37.1 Detailed Description

[www.enno.com](#)

Date

: Mar 14, 2016

Author

: chuanjiang.wong

Definition in file [main.c](#).

### 7.37.2 Macro Definition Documentation

7.37.2.1 `#define LOCKFILE "/var/run/rs485.pid"`

Definition at line 31 of file main.c.

7.37.2.2 `#define LOCKMODE (S_IRUSR | S_IWUSR | S_IRGRP | S_IROTH)`

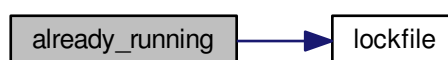
Definition at line 32 of file main.c.

### 7.37.3 Function Documentation

7.37.3.1 `static int already_running ( void ) [static]`

Definition at line 142 of file main.c.

Here is the call graph for this function:



### 7.37.3.2 void daemonize ( const char \* cmd )

Definition at line 69 of file main.c.

### 7.37.3.3 static int lockfile ( int fd ) [static]

Definition at line 129 of file main.c.

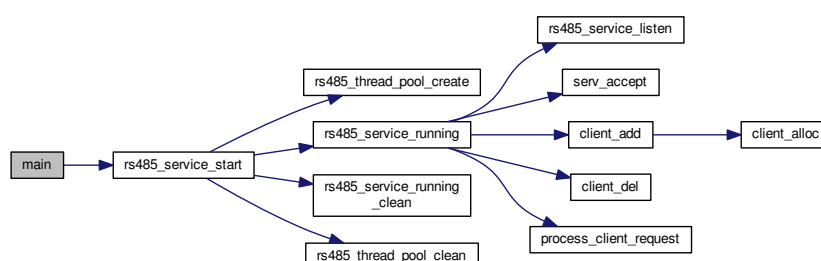
Here is the caller graph for this function:



### 7.37.3.4 int main ( int argc, char \* argv[] )

Definition at line 174 of file main.c.

Here is the call graph for this function:



### 7.37.3.5 void\* signal\_handle\_pthread ( void \* arg )

Definition at line 39 of file main.c.

## 7.37.4 Variable Documentation

### 7.37.4.1 sigset\_t mask [static]

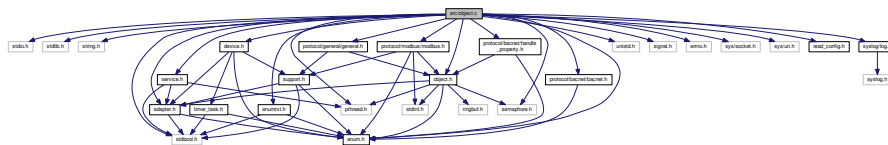
Definition at line 35 of file main.c.



## 7.38 src/object.c File Reference

```
#include <stdio.h>
#include <stdlib.h>
#include <string.h>
#include <stdbool.h>
#include <unistd.h>
#include <signal.h>
#include <errno.h>
#include <sys/socket.h>
#include <sys/un.h>
#include <pthread.h>
#include <semaphore.h>
#include "read_config.h"
#include "service.h"
#include "syslog/log.h"
#include "adapter.h"
#include "enum.h"
#include "object.h"
#include "protocol/general/general.h"
#include "protocol/bacnet/bacnet.h"
#include "protocol/bacnet/handle_property.h"
#include "protocol/modbus/modbus.h"
#include "device.h"
#include "enumtxt.h"
```

Include dependency graph for object.c:



### Macros

- `#define RS485_OBJECT_MAX_NUMBERS` (5)
- `#define RS485_WORK_QUEUE_DEPTH` (256)

### Functions

- `bool check_object_id` (int object\_id)  
*check\_object\_id check the object is legal*
- `static int find_available_object_id` (void)  
*find\_available\_object\_id Find a available object id from object table*
- `static bool object_is_used` (const `adapter_t` \*adapter)  
*object\_is\_used To determine whether the object id has been used*
- `static int work_thread_create` (`object_management_t` \*object)  
*work\_thread\_create create work thread*
- `static void work_thread_clean` (`object_management_t` \*object)  
*work\_thread\_clean clean the work thread*
- `static bool check_object_is_support` (`rs485_protocol_type_enum` object\_type)
- `int create_object` (const `adapter_t` \*adapter)  
*create\_object create a object by the adapter message*

- int [delete\\_object](#) (int object\_id)  
*delete\_object delete a rs485 object by object id*
- int [get\\_object\\_type](#) (int object\_id)  
*get\_object\_type get the object protocol type*
- int [get\\_object\\_mount\\_device](#) (int object\_id, int \*out\_id, int out\_id\_len)  
*get\_object\_mount\_device get the object mount device*
- int [object\\_mount\\_device\\_id](#) (int object\_id, int device\_id)  
*object\_mount\_device\_id add a device to his object*
- void [object\\_unmount\\_device\\_id](#) (int object\_id, int device\_id)  
*object\_unmount\_device\_id delete a device form his object*
- bool [check\\_object\\_numbers\\_have\\_idle](#) (int object\_id)  
*check\_object\_numbers\_have\_idle check object mount device is full ?*
- void \* [get\\_object\\_work\\_queue](#) (int object\_id)  
*get\_object\_work\_queue get the object of work queue*
- void \* [get\\_object\\_queue\\_sem](#) (int object\_id)  
*get\_object\_queue\_sem get the object of work queue semaphore*

## Variables

- static [object\\_management\\_t](#) \* [glb\\_object\\_manage](#) [[RS485\\_OBJECT\\_MAX\\_NUMBERS](#)] = { 0 }
- static struct ring\_buffer\_t [glb\\_work\\_queue](#) [[RS485\\_OBJECT\\_MAX\\_NUMBERS](#)]

## 7.38.1 Macro Definition Documentation

### 7.38.1.1 `#define RS485_OBJECT_MAX_NUMBERS (5)`

Definition at line 47 of file object.c.

### 7.38.1.2 `#define RS485_WORK_QUEUE_DEPTH (256)`

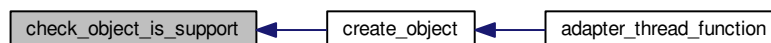
Definition at line 51 of file object.c.

## 7.38.2 Function Documentation

### 7.38.2.1 `static bool check_object_is_support ( rs485_protocol_type_enum object_type ) [static]`

Definition at line 311 of file object.c.

Here is the caller graph for this function:



### 7.38.3 Variable Documentation

#### 7.38.3.1 `object_management_t* glb_object_manage[RS485_OBJECT_MAX_NUMBERS] = {0}` [static]

define the RS485 object management table

Definition at line 56 of file object.c.

#### 7.38.3.2 `struct ring_buffer_t glb_work_queue[RS485_OBJECT_MAX_NUMBERS]` [static]

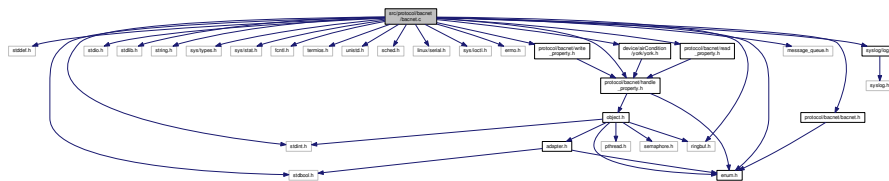
define the RS485 object ring buffer

Definition at line 59 of file object.c.

## 7.39 src/protocol/bacnet/bacnet.c File Reference

```
#include <stddef.h>
#include <stdint.h>
#include <stdbool.h>
#include <stdio.h>
#include <stdlib.h>
#include <string.h>
#include <sys/types.h>
#include <sys/stat.h>
#include <fcntl.h>
#include <termios.h>
#include <unistd.h>
#include <sched.h>
#include <linux/serial.h>
#include <sys/ioctl.h>
#include <errno.h>
#include "enum.h"
#include "protocol/bacnet/bacnet.h"
#include "protocol/bacnet/handle_property.h"
#include "protocol/bacnet/read_property.h"
#include "protocol/bacnet/write_property.h"
#include "message_queue.h"
#include "syslog/log.h"
#include "ringbuf.h"
#include "device/airCondition/york/york.h"
```

Include dependency graph for bacnet.c:



## Functions

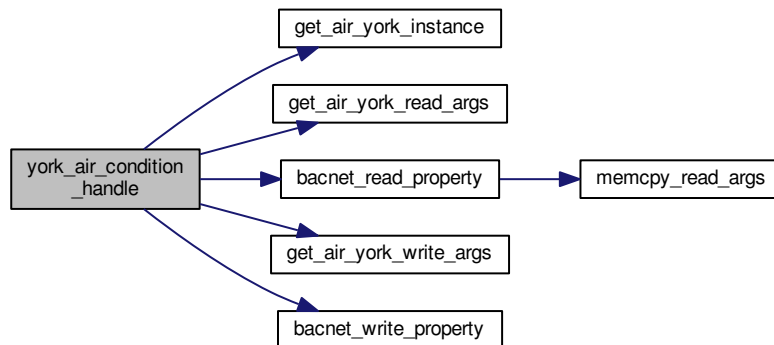
- static int [york\\_air\\_condition\\_handle](#) (const struct [bacnet](#) \*handle)
  - void \* [bacnet\\_work\\_thread\\_function](#) (void \*arg)
- bacnet\_work\_thread\_function* The bacnet work thread

### 7.39.1 Function Documentation

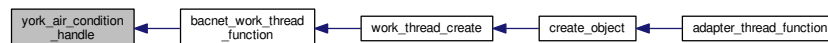
#### 7.39.1.1 `static int york_air_condition_handle ( const struct bacnet * handle )` `[static]`

Definition at line 51 of file bacnet.c.

Here is the call graph for this function:



Here is the caller graph for this function:

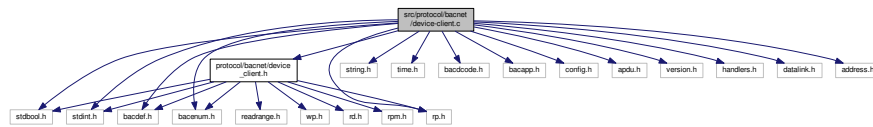


## 7.40 src/protocol/bacnet/device-client.c File Reference

```

#include <stdbool.h>
#include <stdint.h>
#include <string.h>
#include <time.h>
#include "bacdef.h"
#include "bacdcode.h"
#include "bacenum.h"
#include "bacapp.h"
#include "config.h"
#include "apdu.h"
#include "rp.h"
#include "version.h"
#include "handlers.h"
#include "datalink.h"
#include "address.h"
#include "protocol/bacnet/device_client.h"

```



- `bool Device_Object_Name_Copy (BACNET_OBJECT_TYPE object_type, uint32_t object_instance, BACNET_CHARACTER_STRING *object_name)`

## Variables

- static uint32\_t [Object\\_Instance\\_Number](#) = 260001
- static BACNET\_CHARACTER\_STRING [My\\_Object\\_Name](#)
- static BACNET\_DEVICE\_STATUS [System\\_Status](#) = STATUS\_OPERATIONAL
- static char \* [Vendor\\_Name](#) = BACNET\_VENDOR\_NAME
- static uint16\_t [Vendor\\_Identifier](#) = BACNET\_VENDOR\_ID
- static char \* [Model\\_Name](#) = "GNU"
- static char \* [Application\\_Software\\_Version](#) = "1.0"
- static char \* [Location](#) = "USA"
- static char \* [Description](#) = "command line [client](#)"
- static uint32\_t [Database\\_Revision](#) = 0
- static [object\\_functions\\_t](#) [Object\\_Table](#) []

### 7.40.1 Detailed Description

Lightweight base "class" for handling all BACnet objects belonging to a BACnet device, as well as Device-specific properties. This Device instance is designed to meet minimal functionality for simple clients.

Definition in file [device-client.c](#).

### 7.40.2 Function Documentation

#### 7.40.2.1 const char\* Device\_Application\_Software\_Version ( void )

Definition at line 362 of file device-client.c.

#### 7.40.2.2 unsigned Device\_Count ( void )

Definition at line 163 of file device-client.c.

#### 7.40.2.3 uint32\_t Device\_Database\_Revision ( void )

Definition at line 443 of file device-client.c.

#### 7.40.2.4 const char\* Device\_Description ( void )

Definition at line 383 of file device-client.c.

#### 7.40.2.5 const char\* Device\_Firmware\_Revision ( void )

Definition at line 356 of file device-client.c.

#### 7.40.2.6 void Device\_Inc\_Database\_Revision ( void )

Definition at line 460 of file device-client.c.

Here is the caller graph for this function:



#### 7.40.2.7 `uint32_t Device_Index_To_Instance ( unsigned index )`

Definition at line 169 of file `device-client.c`.

#### 7.40.2.8 `void Device_Init ( object_functions_t * object_table )`

Initialize the Device Object. Initialize the group of object helper functions for any supported Object. Initialize each of the Device Object child Object instances.

##### Parameters

|                     |                                                                                                                                                                                     |
|---------------------|-------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| <i>object_table</i> | [in,out] array of structure with object functions. Each Child Object must provide some implementation of each of these functions in order to properly support the default handlers. |
|---------------------|-------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|

Definition at line 895 of file `device-client.c`.

Here is the caller graph for this function:



#### 7.40.2.9 `const char* Device_Location ( void )`

Definition at line 404 of file `device-client.c`.

#### 7.40.2.10 `const char* Device_Model_Name ( void )`

Definition at line 335 of file `device-client.c`.

#### 7.40.2.11 `uint32_t Device_Object_Instance_Number ( void )`

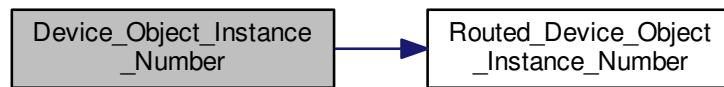
Return the Object Instance number for our (single) Device Object. This is a key function, widely invoked by the handler code, since it provides "our" (ie, local) address.

##### Returns

The Instance number used in the `BACNET_OBJECT_ID` for the Device.

Definition at line 184 of file `device-client.c`.

Here is the call graph for this function:



#### 7.40.2.12 unsigned Device\_Object\_List\_Count ( void )

Get the total count of objects supported by this Device Object.

##### Note

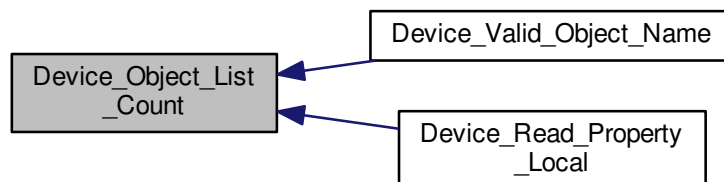
Since many network clients depend on the object list for discovery, it must be consistent!

##### Returns

The count of objects, for all supported Object types.

Definition at line 471 of file device-client.c.

Here is the caller graph for this function:



#### 7.40.2.13 bool Device\_Object\_List\_Identifier ( unsigned array\_index, int \* object\_type, uint32\_t \* instance )

Lookup the Object at the given array index in the Device's Object List. Even though we don't keep a single linear array of objects in the Device, this method acts as though we do and works through a virtual, concatenated array of all of our object type arrays.

##### Parameters



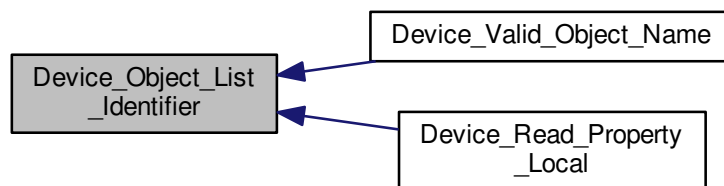
|                    |                                               |
|--------------------|-----------------------------------------------|
| <i>array_index</i> | [in] The desired array index (1 to N)         |
| <i>object_type</i> | [out] The object's type, if found.            |
| <i>instance</i>    | [out] The object's instance number, if found. |

**Returns**

True if found, else false.

Definition at line 499 of file device-client.c.

Here is the caller graph for this function:



**7.40.2.14** `bool Device_Object_Name ( uint32_t object_instance, BACNET_CHARACTER_STRING * object_name )`

Definition at line 215 of file device-client.c.

**7.40.2.15** `bool Device_Object_Name_Copy ( BACNET_OBJECT_TYPE object_type, uint32_t object_instance, BACNET_CHARACTER_STRING * object_name )`

Copy a child object's `object_name` value, given its ID.

**Parameters**

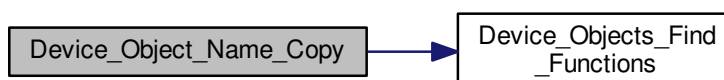
|                        |                                                      |
|------------------------|------------------------------------------------------|
| <i>object_type</i>     | [in] The BACNET_OBJECT_TYPE of the child Object.     |
| <i>object_instance</i> | [in] The object instance number of the child Object. |
| <i>object_name</i>     | [out] The Object Name found for this child Object.   |

**Returns**

True on success or else False if not found.

Definition at line 620 of file device-client.c.

Here is the call graph for this function:



7.40.2.16 `static struct object_functions* Device_Objects_Find_Functions ( BACNET_OBJECT_TYPE Object_Type )`  
`[static]`

Glue function to let the Device object, when called by a handler, lookup which Object type needs to be invoked.

#### Parameters

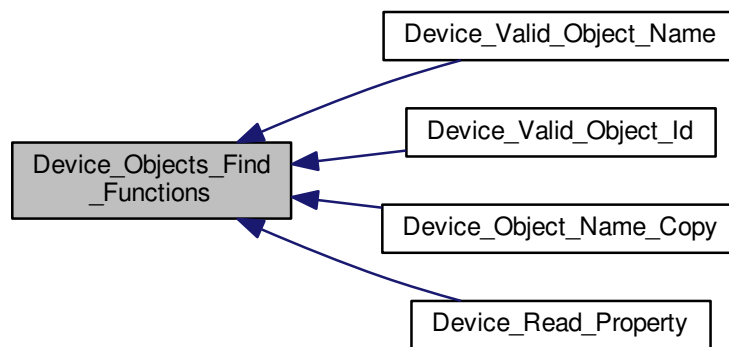
|                    |                                                             |
|--------------------|-------------------------------------------------------------|
| <i>Object_Type</i> | [in] The type of BACnet Object the handler wants to access. |
|--------------------|-------------------------------------------------------------|

#### Returns

Pointer to the group of object helper functions that implement this type of Object.

Definition at line 145 of file device-client.c.

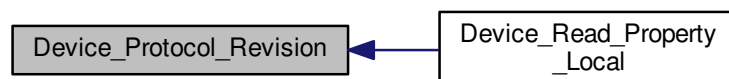
Here is the caller graph for this function:



7.40.2.17 `uint8_t Device_Protocol_Revision ( void )`

Definition at line 431 of file device-client.c.

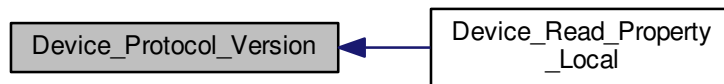
Here is the caller graph for this function:



7.40.2.18 `uint8_t Device_Protocol_Version ( void )`

Definition at line 425 of file device-client.c.

Here is the caller graph for this function:



#### 7.40.2.19 int Device\_Read\_Property ( BACNET\_READ\_PROPERTY\_DATA \* *rpdata* )

Looks up the requested Object and Property, and encodes its Value in an APDU.

If the Object or Property can't be found, sets the error class and code.

##### Parameters

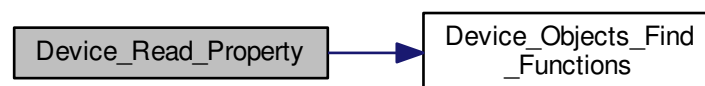
|               |                                                                                                    |
|---------------|----------------------------------------------------------------------------------------------------|
| <i>rpdata</i> | [in,out] Structure with the desired Object and Property info on entry, and APDU message on return. |
|---------------|----------------------------------------------------------------------------------------------------|

##### Returns

The length of the APDU on success, else BACNET\_STATUS\_ERROR

Definition at line 859 of file device-client.c.

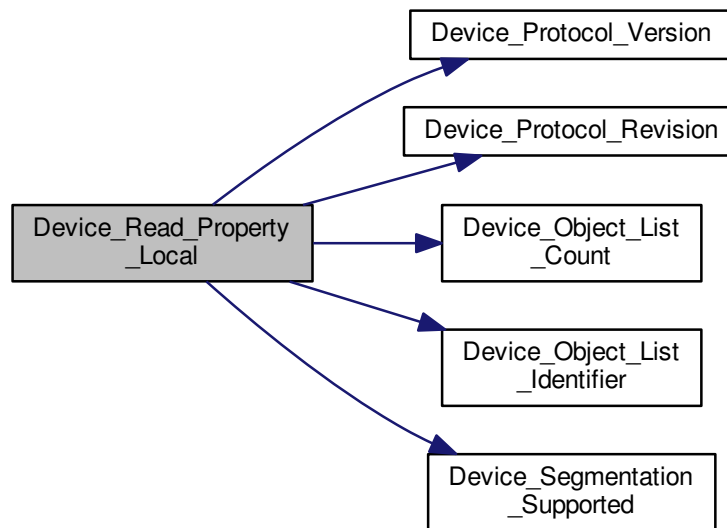
Here is the call graph for this function:



#### 7.40.2.20 int Device\_Read\_Property\_Local ( BACNET\_READ\_PROPERTY\_DATA \* *rpdata* )

Definition at line 638 of file device-client.c.

Here is the call graph for this function:



#### 7.40.2.21 BACNET\_SEGMENTATION Device\_Segmentation\_Supported ( void )

Definition at line 437 of file device-client.c.

Here is the caller graph for this function:



#### 7.40.2.22 bool Device\_Set\_Application\_Software\_Version ( const char \* name, size\_t length )

Definition at line 368 of file device-client.c.

#### 7.40.2.23 void Device\_Set\_Database\_Revision ( uint32\_t revision )

Definition at line 449 of file device-client.c.

**7.40.2.24** bool Device\_Set\_Description ( const char \* *name*, size\_t *length* )

Definition at line 389 of file device-client.c.

**7.40.2.25** bool Device\_Set\_Location ( const char \* *name*, size\_t *length* )

Definition at line 410 of file device-client.c.

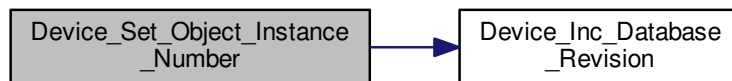
**7.40.2.26** bool Device\_Set\_Model\_Name ( const char \* *name*, size\_t *length* )

Definition at line 341 of file device-client.c.

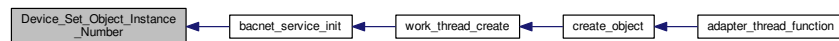
**7.40.2.27** bool Device\_Set\_Object\_Instance\_Number ( uint32\_t *object\_id* )

Definition at line 194 of file device-client.c.

Here is the call graph for this function:

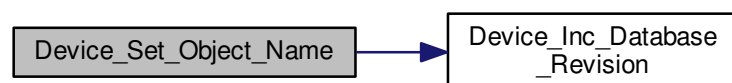


Here is the caller graph for this function:

**7.40.2.28** bool Device\_Set\_Object\_Name ( BACNET\_CHARACTER\_STRING \* *object\_name* )

Definition at line 228 of file device-client.c.

Here is the call graph for this function:



7.40.2.29 `int Device_Set_System_Status ( BACNET_DEVICE_STATUS status, bool local )`

Definition at line 248 of file device-client.c.

7.40.2.30 `void Device_Set_Vendor_Identifier ( uint16_t vendor_id )`

Definition at line 329 of file device-client.c.

7.40.2.31 `BACNET_DEVICE_STATUS Device_System_Status ( void )`

Definition at line 242 of file device-client.c.

7.40.2.32 `bool Device_Valid_Object_Id ( int object_type, uint32_t object_instance )`

Determine if we have an object of this type and instance number.

#### Parameters

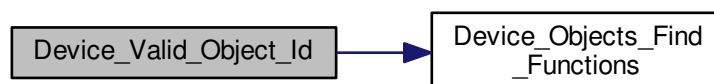
|                        |                                                  |
|------------------------|--------------------------------------------------|
| <i>object_type</i>     | [in] The desired BACNET_OBJECT_TYPE              |
| <i>object_instance</i> | [in] The object instance number to be looked up. |

#### Returns

True if found, else False if no such Object in this device.

Definition at line 599 of file device-client.c.

Here is the call graph for this function:



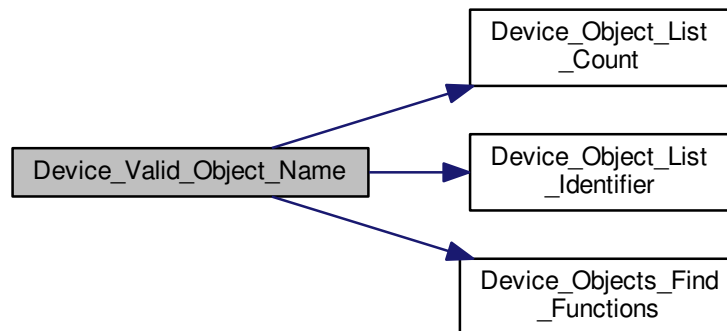
7.40.2.33 `bool Device_Valid_Object_Instance_Number ( uint32_t object_id )`

Definition at line 209 of file device-client.c.

7.40.2.34 `bool Device_Valid_Object_Name ( BACNET_CHARACTER_STRING * object_name1, int * object_type, uint32_t * object_instance )`

Definition at line 558 of file device-client.c.

Here is the call graph for this function:



#### 7.40.2.35 `uint16_t Device_Vendor_Identifier ( void )`

Returns the Vendor ID for this Device. See the assignments at <http://www.bacnet.org/VendorID/BACnet%20Vendor%20IDs.htm>

##### Returns

The Vendor ID of this Device.

Definition at line 323 of file device-client.c.

#### 7.40.2.36 `const char* Device_Vendor_Name ( void )`

Definition at line 313 of file device-client.c.

### 7.40.3 Variable Documentation

#### 7.40.3.1 `char* Application_Software_Version = "1.0" [static]`

Definition at line 60 of file device-client.c.

#### 7.40.3.2 `uint32_t Database_Revision = 0 [static]`

Definition at line 85 of file device-client.c.

#### 7.40.3.3 `char* Description = "command line client" [static]`

Definition at line 62 of file device-client.c.

#### 7.40.3.4 `char* Location = "USA" [static]`

Definition at line 61 of file device-client.c.

**7.40.3.5** `char* Model_Name = "GNU" [static]`

Definition at line 59 of file device-client.c.

**7.40.3.6** `BACNET_CHARACTER_STRING My_Object_Name [static]`

Definition at line 55 of file device-client.c.

**7.40.3.7** `uint32_t Object_Instance_Number = 260001 [static]`

Definition at line 54 of file device-client.c.

**7.40.3.8** `object_functions_t Object_Table[] [static]`

Definition at line 105 of file device-client.c.

**7.40.3.9** `BACNET_DEVICE_STATUS System_Status = STATUS_OPERATIONAL [static]`

Definition at line 56 of file device-client.c.

**7.40.3.10** `uint16_t Vendor_Identifier = BACNET_VENDOR_ID [static]`

Definition at line 58 of file device-client.c.

**7.40.3.11** `char* Vendor_Name = BACNET_VENDOR_NAME [static]`

Definition at line 57 of file device-client.c.



## 7.41 src/protocol/bacnet/handle\_property.c File Reference

```
#include <stddef.h>
#include <stdint.h>
#include <stdio.h>
#include <stdlib.h>
#include <errno.h>
#include <time.h>
#include "bacdef.h"
#include "config.h"
#include "bactext.h"
#include "bacerror.h"
#include "iam.h"
#include "arf.h"
#include "tsm.h"
#include "address.h"
#include "npdu.h"
#include "apdu.h"
#include "datalink.h"
#include "whois.h"
#include "rpm.h"
#include "filename.h"
#include "handlers.h"
#include "client.h"
#include "txbuf.h"
#include "dlenv.h"
#include <pthread.h>
#include "protocol/bacnet/handle_property.h"
#include "protocol/bacnet/read_property.h"
#include "protocol/bacnet/write_property.h"
#include "protocol/bacnet/device.h"
#include "adapter.h"
#include "syslog/log.h"
```

Include dependency graph for handle\_property.c:



### Macros

- #define [MAX\\_PROPERTY\\_VALUES](#) 64

### Functions

- void [My\\_Read\\_Property\\_Ack\\_Handler](#) (uint8\_t \*service\_request, uint16\_t service\_len, BACNET\_ADDRESS \*src, BACNET\_CONFIRMED\_SERVICE\_ACK\_DATA \*service\_data)
- void [MyWritePropertySimpleAckHandler](#) (BACNET\_ADDRESS \*src, uint8\_t invoke\_id)
- void [My\\_Read\\_Property\\_Multiple\\_Ack\\_Handler](#) (uint8\_t \*service\_request, uint16\_t service\_len, BACNET\_ADDRESS \*src, BACNET\_CONFIRMED\_SERVICE\_ACK\_DATA \*service\_data)
- static void [MyErrorHandler](#) (BACNET\_ADDRESS \*src, uint8\_t invoke\_id, BACNET\_ERROR\_CLASS error\_class, BACNET\_ERROR\_CODE error\_code)
- static void [MyAbortHandler](#) (BACNET\_ADDRESS \*src, uint8\_t invoke\_id, uint8\_t abort\_reason, bool server)

- static void [MyRejectHandler](#) (BACNET\_ADDRESS \*src, uint8\_t invoke\_id, uint8\_t reject\_reason)
- static void [Init\\_Service\\_Handlers](#) (void)
- static int [enno\\_dlenv\\_init](#) (const [object\\_management\\_t](#) \*object)
- int [bacnet\\_service\\_init](#) ([object\\_management\\_t](#) \*object)

*bacnet\_service\_init bacnet physics initialize.*

## Variables

- int [glb\\_config\\_bacnet\\_object\\_instance](#)

### 7.41.1 Macro Definition Documentation

#### 7.41.1.1 #define MAX\_PROPERTY\_VALUES 64

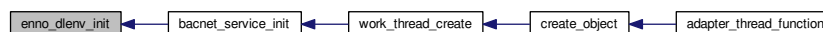
Definition at line 45 of file `handle_property.c`.

### 7.41.2 Function Documentation

#### 7.41.2.1 static int `enno_dlenv_init ( const object\_management\_t * object )` [static]

Definition at line 116 of file `handle_property.c`.

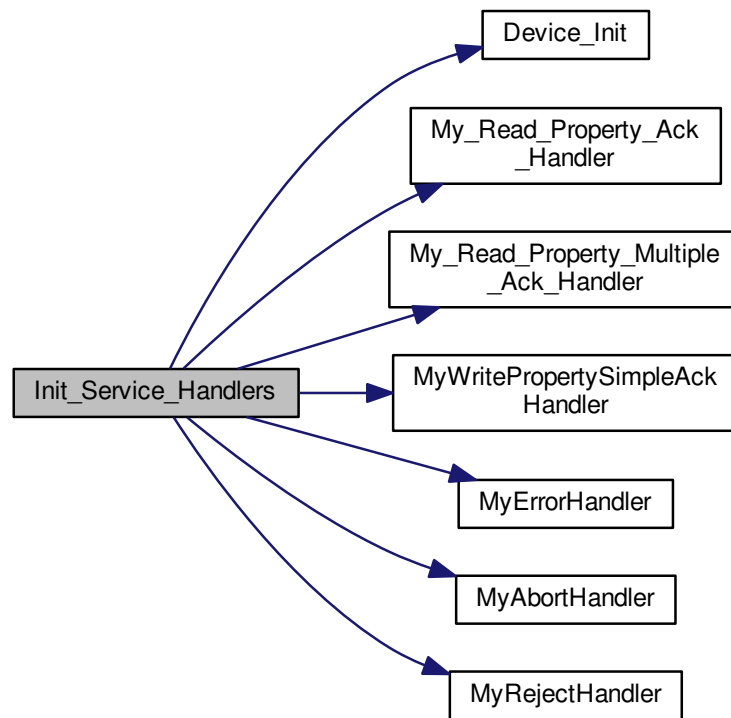
Here is the caller graph for this function:



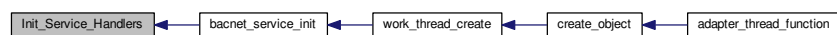
#### 7.41.2.2 static void `Init_Service_Handlers ( void )` [static]

Definition at line 85 of file `handle_property.c`.

Here is the call graph for this function:



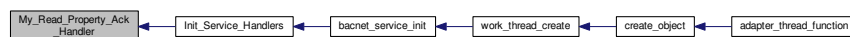
Here is the caller graph for this function:



**7.41.2.3** void `My_Read_Property_Ack_Handler` ( `uint8_t * service_request`, `uint16_t service_len`, `BACNET_ADDRESS * src`, `BACNET_CONFIRMED_SERVICE_ACK_DATA * service_data` )

Definition at line 48 of file `read_property.c`.

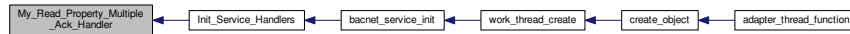
Here is the caller graph for this function:



7.41.2.4 `void My_Read_Property_Multiple_Ack_Handler ( uint8_t * service_request, uint16_t service_len, BACNET_ADDRESS * src, BACNET_CONFIRMED_SERVICE_ACK_DATA * service_data )`

Definition at line 82 of file `read_property.c`.

Here is the caller graph for this function:



7.41.2.5 `static void MyAbortHandler ( BACNET_ADDRESS * src, uint8_t invoke_id, uint8_t abort_reason, bool server )`  
[static]

Definition at line 71 of file `handle_property.c`.

Here is the caller graph for this function:



7.41.2.6 `static void MyErrorHandler ( BACNET_ADDRESS * src, uint8_t invoke_id, BACNET_ERROR_CLASS error_class, BACNET_ERROR_CODE error_code )` [static]

Definition at line 65 of file `handle_property.c`.

Here is the caller graph for this function:



7.41.2.7 `static void MyRejectHandler ( BACNET_ADDRESS * src, uint8_t invoke_id, uint8_t reject_reason )` [static]

Definition at line 78 of file `handle_property.c`.

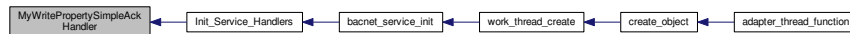
Here is the caller graph for this function:



7.41.2.8 `void MyWritePropertySimpleAckHandler ( BACNET_ADDRESS * src, uint8_t invoke_id )`

Definition at line 55 of file `write_property.c`.

Here is the caller graph for this function:



### 7.41.3 Variable Documentation

#### 7.41.3.1 int glb\_config\_bacnet\_object\_instance

Definition at line 35 of file read\_config.c.

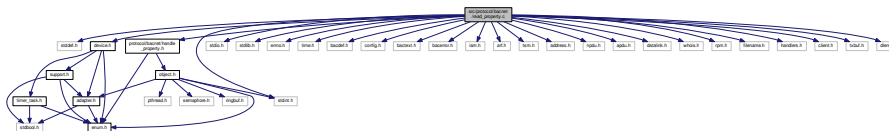
## 7.42 src/protocol/bacnet/read\_property.c File Reference

```

#include <stddef.h>
#include <stdint.h>
#include <stdio.h>
#include <stdlib.h>
#include <errno.h>
#include <time.h>
#include "bacdef.h"
#include "config.h"
#include "bactext.h"
#include "bacerror.h"
#include "iam.h"
#include "arf.h"
#include "tsm.h"
#include "address.h"
#include "npdu.h"
#include "apdu.h"
#include "device.h"
#include "datalink.h"
#include "whois.h"
#include "rpm.h"
#include "filename.h"
#include "handlers.h"
#include "client.h"
#include "txbuf.h"
#include "dlenv.h"
#include "protocol/bacnet/handle_property.h"

```

Include dependency graph for read\_property.c:



### Functions

- void [My\\_Read\\_Property\\_Ack\\_Handler](#) (uint8\_t \*service\_request, uint16\_t service\_len, BACNET\_ADDRESS \*src, BACNET\_CONFIRMED\_SERVICE\_ACK\_DATA \*service\_data)

- void [My\\_Read\\_Property\\_Multiple\\_Ack\\_Handler](#) (uint8\_t \*service\_request, uint16\_t service\_len, BACNET\_ADDRESS \*src, BACNET\_CONFIRMED\_SERVICE\_ACK\_DATA \*service\_data)
- static int [memcpy\\_read\\_args](#) (bacnet\_read\_args\_t \*args)
- int [bacnet\\_read\\_property](#) (bacnet\_read\_args\_t \*args)

## Variables

- static BACNET\_READ\_ACCESS\_DATA [read\\_access\\_data](#) [BACNET\_READ\_ARGS\_OBJECT\_MAX]
- static BACNET\_PROPERTY\_REFERENCE [read\\_access\\_data\\_property](#) [BACNET\_READ\_ARGS\_OBJECT\_MAX]
- static uint8\_t [Request\\_Invoke\\_ID](#) = 0
- static BACNET\_ADDRESS [Target\\_Address](#)

## 7.42.1 Function Documentation

### 7.42.1.1 int [bacnet\\_read\\_property](#) ( bacnet\_read\_args\_t \* args )

Definition at line 152 of file [read\\_property.c](#).

Here is the call graph for this function:



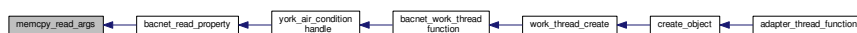
Here is the caller graph for this function:



### 7.42.1.2 static int [memcpy\\_read\\_args](#) ( bacnet\_read\_args\_t \* args ) [static]

Definition at line 115 of file [read\\_property.c](#).

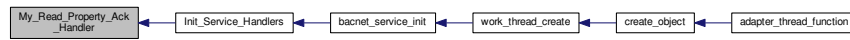
Here is the caller graph for this function:



7.42.1.3 void My\_Read\_Property\_Ack\_Handler ( uint8\_t \* *service\_request*, uint16\_t *service\_len*, BACNET\_ADDRESS \* *src*, BACNET\_CONFIRMED\_SERVICE\_ACK\_DATA \* *service\_data* )

Definition at line 48 of file read\_property.c.

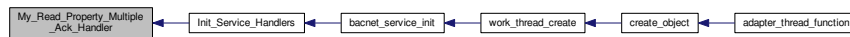
Here is the caller graph for this function:



7.42.1.4 void My\_Read\_Property\_Multiple\_Ack\_Handler ( uint8\_t \* *service\_request*, uint16\_t *service\_len*, BACNET\_ADDRESS \* *src*, BACNET\_CONFIRMED\_SERVICE\_ACK\_DATA \* *service\_data* )

Definition at line 82 of file read\_property.c.

Here is the caller graph for this function:



## 7.42.2 Variable Documentation

7.42.2.1 BACNET\_READ\_ACCESS\_DATA read\_access\_data[BACNET\_READ\_ARGS\_OBJECT\_MAX] [static]

Definition at line 39 of file read\_property.c.

7.42.2.2 BACNET\_PROPERTY\_REFERENCE read\_access\_data\_property[BACNET\_READ\_ARGS\_OBJECT\_MAX] [static]

Definition at line 40 of file read\_property.c.

7.42.2.3 uint8\_t Request\_Invoke\_ID = 0 [static]

Definition at line 44 of file read\_property.c.

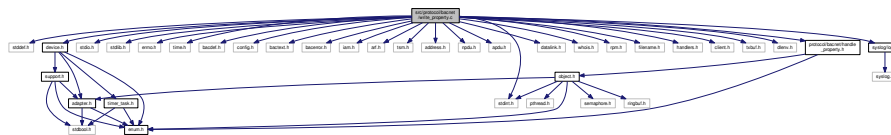
7.42.2.4 BACNET\_ADDRESS Target\_Address [static]

Definition at line 45 of file read\_property.c.

### 7.43 src/protocol/bacnet/write\_property.c File Reference

```
#include <stddef.h>
#include <stdint.h>
#include <stdio.h>
#include <stdlib.h>
#include <errno.h>
#include <time.h>
#include "bacdef.h"
#include "config.h"
#include "bactext.h"
#include "bacerror.h"
#include "iam.h"
#include "arf.h"
#include "tsm.h"
#include "address.h"
#include "npdu.h"
#include "apdu.h"
#include "device.h"
#include "datalink.h"
#include "whois.h"
#include "rpm.h"
#include "filename.h"
#include "handlers.h"
#include "client.h"
#include "txbuf.h"
#include "dlenv.h"
#include "protocol/bacnet/handle_property.h"
#include "syslog/log.h"
```

Include dependency graph for write\_property.c:



#### Macros

- #define [MAX\\_PROPERTY\\_VALUES](#) 64
- #define [RETRANSMISSION\\_TIMES](#) 3

#### Functions

- void [MyWritePropertySimpleAckHandler](#) (BACNET\_ADDRESS \*src, uint8\_t invoke\_id)
- int [bacnet\\_write\\_property](#) (const [bacnet\\_write\\_args\\_t](#) \*args)

#### Variables

- static uint8\_t [Rx\\_Buf](#) [MAX\_MPDU] = { 0 }
- static BACNET\_APPLICATION\_DATA\_VALUE [Target\\_Object\\_Property\\_Value](#) [MAX\_PROPERTY\_VALUES]
- static uint8\_t [Request\\_Invoke\\_ID](#) = 0
- static BACNET\_ADDRESS [Target\\_Address](#)
- static bool [Error\\_Detected](#) = false



### 7.43.1 Macro Definition Documentation

#### 7.43.1.1 `#define MAX_PROPERTY_VALUES 64`

Definition at line 40 of file write\_property.c.

#### 7.43.1.2 `#define RETRANSMISSION_TIMES 3`

Definition at line 44 of file write\_property.c.

### 7.43.2 Function Documentation

#### 7.43.2.1 `int bacnet_write_property ( const bacnet_write_args_t * args )`

500ms\*4, 2s

Definition at line 63 of file write\_property.c.

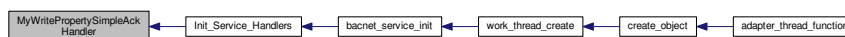
Here is the caller graph for this function:



#### 7.43.2.2 `void MyWritePropertySimpleAckHandler ( BACNET_ADDRESS * src, uint8_t invoke_id )`

Definition at line 55 of file write\_property.c.

Here is the caller graph for this function:



### 7.43.3 Variable Documentation

#### 7.43.3.1 `bool Error_Detected = false [static]`

Definition at line 53 of file write\_property.c.

#### 7.43.3.2 `uint8_t Request_Invoke_ID = 0 [static]`

Definition at line 51 of file write\_property.c.

#### 7.43.3.3 `uint8_t Rx_Buf[MAX_MPDU] = { 0 } [static]`

Definition at line 47 of file write\_property.c.

#### 7.43.3.4 BACNET\_ADDRESS Target\_Address [static]

Definition at line 52 of file write\_property.c.

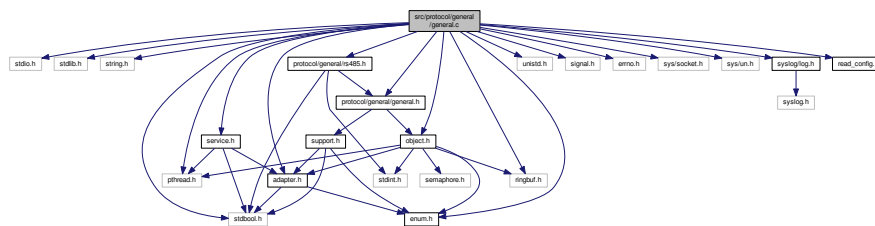
#### 7.43.3.5 BACNET\_APPLICATION\_DATA\_VALUE Target\_Object\_Property\_Value[MAX\_PROPERTY\_VALUES] [static]

Definition at line 49 of file write\_property.c.

## 7.44 src/protocol/general/general.c File Reference

```
#include <stdio.h>
#include <stdlib.h>
#include <string.h>
#include <stdbool.h>
#include <unistd.h>
#include <signal.h>
#include <errno.h>
#include <sys/socket.h>
#include <sys/un.h>
#include <pthread.h>
#include "service.h"
#include "syslog/log.h"
#include "adapter.h"
#include "enum.h"
#include "ringbuf.h"
#include "protocol/general/general.h"
#include "protocol/general/rs485.h"
#include "object.h"
#include "read_config.h"
```

Include dependency graph for general.c:



## Macros

- #define [BUS\\_MAX\\_RETRANSMISSION](#) (3)

## Functions

- int [general\\_service\\_init](#) ([object\\_management\\_t](#) \*object)  
*general\_service\_init* The general protocol(user defined) initialize
- void \* [general\\_work\\_thread\\_function](#) (void \*arg)  
*general\_work\_thread\_function* The general work thread function

### 7.44.1 Macro Definition Documentation

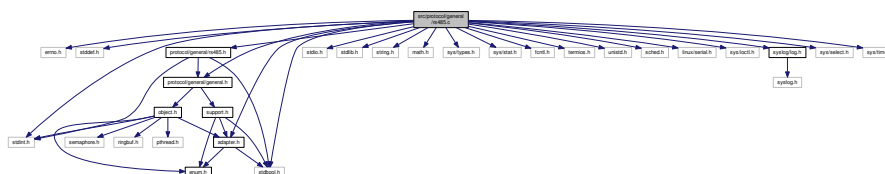
#### 7.44.1.1 #define BUS\_MAX\_RETRANSMISSION (3)

Definition at line 42 of file general.c.

## 7.45 src/protocol/general/rs485.c File Reference

```
#include <errno.h>
#include <stddef.h>
#include <stdint.h>
#include <stdbool.h>
#include <stdio.h>
#include <stdlib.h>
#include <string.h>
#include <math.h>
#include <sys/types.h>
#include <sys/stat.h>
#include <fcntl.h>
#include <termios.h>
#include <unistd.h>
#include <sched.h>
#include <linux/serial.h>
#include <sys/ioctl.h>
#include "adapter.h"
#include "protocol/general/general.h"
#include "protocol/general/rs485.h"
#include "syslog/log.h"
#include <sys/select.h>
#include <sys/time.h>
```

Include dependency graph for rs485.c:



### Macros

- #define [RS485\\_DEBUG](#) (1)
- #define [RS485MOD](#) 0
- #define [\\_POSIX\\_SOURCE](#) 1 /\* POSIX compliant source \*/

### Functions

- void [rs485\\_set\\_interface](#) (char \*ifname)  
*RS485\_Set\_Interface rs485 interface name.*
- const char \* [rs485\\_interface](#) (void)
- uint32\_t [rs485\\_get\\_baud\\_rate](#) (void)
- bool [rs485\\_set\\_baud\\_rate](#) (uint32\_t baud)  
*RS485\_Set\_Baud\_Rate set the rs485 buad rate.*

- int [rs485\\_send\\_handle\\_frame](#) (volatile struct [mstp\\_port\\_handle](#) \*mstp\_port)  
*rs485\_send\_handle\_frame rs485 bus package a send frame, and send the package to bus.*
- int [rs485\\_rcv\\_handle\\_frame](#) (volatile struct [mstp\\_port\\_handle](#) \*mstp\_port)  
*rs485\_rcv\_handle\_frame rs485 bus receive a frame, and call process these data.*
- void [rs485\\_cleanup](#) (void)  
*RS485\_Cleanup The rs485 initailize fail, have clean.*
- void [rs485\\_initialize](#) (void)  
*RS485\_Initialize.*

## Variables

- static int [RS485\\_Handle](#) = -1
- static unsigned int [RS485\\_Baud](#) = B38400
- static char \* [RS485\\_Port\\_Name](#) = "/dev/ttyS0"
- static struct termios [RS485\\_oldtio](#)
- static struct serial\_struct [RS485\\_oldserial](#)
- static bool [RS485\\_SpecBaud](#) = false

## 7.45.1 Macro Definition Documentation

### 7.45.1.1 `#define _POSIX_SOURCE 1 /* POSIX compliant source */`

Definition at line 82 of file rs485.c.

### 7.45.1.2 `#define RS485_DEBUG (1)`

Definition at line 49 of file rs485.c.

### 7.45.1.3 `#define RS485MOD 0`

Definition at line 72 of file rs485.c.

## 7.45.2 Function Documentation

### 7.45.2.1 `uint32_t rs485_get_baud_rate ( void )`

Definition at line 117 of file rs485.c.

### 7.45.2.2 `const char* rs485_interface ( void )`

Definition at line 105 of file rs485.c.

## 7.45.3 Variable Documentation

### 7.45.3.1 `unsigned int RS485_Baud = B38400 [static]`

Definition at line 63 of file rs485.c.

7.45.3.2 `int RS485_Handle = -1` `[static]`

Definition at line 60 of file rs485.c.

7.45.3.3 `struct serial_struct RS485_oldserial` `[static]`

Definition at line 77 of file rs485.c.

7.45.3.4 `struct termios RS485_oldtio` `[static]`

Definition at line 75 of file rs485.c.

7.45.3.5 `char* RS485_Port_Name = "/dev/ttyS0"` `[static]`

Definition at line 68 of file rs485.c.

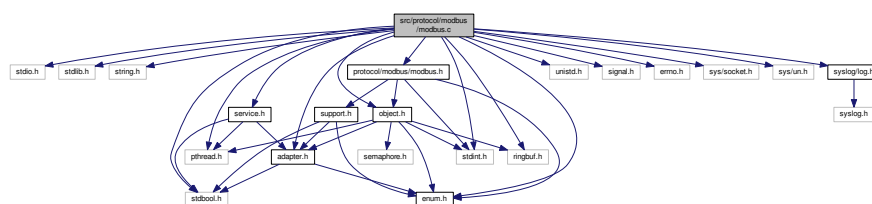
7.45.3.6 `bool RS485_SpecBaud = false` `[static]`

Definition at line 79 of file rs485.c.

## 7.46 src/protocol/modbus/modbus.c File Reference

```
#include <stdio.h>
#include <stdlib.h>
#include <string.h>
#include <stdbool.h>
#include <stdint.h>
#include <unistd.h>
#include <signal.h>
#include <errno.h>
#include <sys/socket.h>
#include <sys/un.h>
#include <pthread.h>
#include "service.h"
#include "syslog/log.h"
#include "adapter.h"
#include "enum.h"
#include "ringbuf.h"
#include "protocol/modbus/modbus.h"
#include "object.h"
```

Include dependency graph for modbus.c:



## Macros

- `#define RS485_MODBUS_MTU (512)`

## Functions

- `void * modbus_work_thread_function (void *arg)`  
*modbus\_work\_thread\_function The modbus work thread*
- `int modbus_service_init (object_management_t *object)`  
*modbus\_service\_init The modbus interface initialize.*
- `void modbus_service_deinit (object_management_t *object)`  
*modbus\_service\_deinit clean the modbus service, The haved called by thread have exit.*

### 7.46.1 Macro Definition Documentation

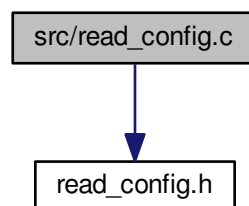
#### 7.46.1.1 `#define RS485_MODBUS_MTU (512)`

Definition at line 44 of file modbus.c.

## 7.47 src/read\_config.c File Reference

```
#include "read_config.h"
```

Include dependency graph for read\_config.c:



## Variables

- `int glb_config_general_work_queue_depth = 256`
- `int glb_config_general_work_package_mtu = 512`
- `int glb_config_bacnet_work_queue_depth = 128`
- `int glb_config_modbus_work_queue_depth = 256`
- `int glb_config_adapter_message_queue_depth = 32`
- `int glb_config_bacnet_object_instance = 10086`
- `int glb_config_client_max_numbers = 10`

### 7.47.1 Variable Documentation

#### 7.47.1.1 `int glb_config_adapter_message_queue_depth = 32`

Definition at line 32 of file `read_config.c`.

#### 7.47.1.2 `int glb_config_bacnet_object_instance = 10086`

Definition at line 35 of file `read_config.c`.

#### 7.47.1.3 `int glb_config_bacnet_work_queue_depth = 128`

Definition at line 26 of file `read_config.c`.

#### 7.47.1.4 `int glb_config_client_max_numbers = 10`

Definition at line 37 of file `read_config.c`.

#### 7.47.1.5 `int glb_config_general_work_package_mtu = 512`

Definition at line 23 of file `read_config.c`.

#### 7.47.1.6 `int glb_config_general_work_queue_depth = 256`

Definition at line 21 of file `read_config.c`.

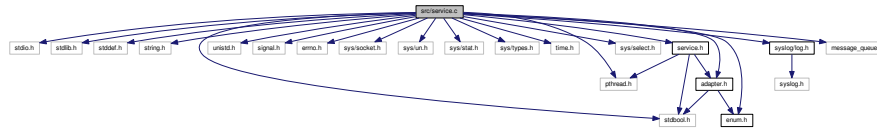
#### 7.47.1.7 `int glb_config_modbus_work_queue_depth = 256`

Definition at line 29 of file `read_config.c`.

## 7.48 src/service.c File Reference

```
#include <stdio.h>
#include <stdlib.h>
#include <stddef.h>
#include <string.h>
#include <stdbool.h>
#include <unistd.h>
#include <signal.h>
#include <errno.h>
#include <sys/socket.h>
#include <sys/un.h>
#include <sys/stat.h>
#include <sys/types.h>
#include <time.h>
#include <pthread.h>
#include <sys/select.h>
#include "service.h"
#include "syslog/log.h"
#include "adapter.h"
#include "enum.h"
#include "message_queue.h"
```

Include dependency graph for service.c:



## Data Structures

- struct [client\\_t](#)

## Macros

- #define [RECEIVE\\_BUFFER\\_LENGTH](#) (2048)
- #define [RS485\\_UNIX\\_DOMAIN\\_PATH](#) "/home/user/bin/rs485d/rs485\_unix\_domain\_service"
- #define [NALLOC](#) (10)

## Functions

- void \* [adapter\\_thread\\_function](#) (void \*arg)
- void \* [timer\\_task\\_thread\\_function](#) (void \*arg)
- static int [rs485\\_thread\\_pool\\_create](#) ([thread\\_pool\\_t](#) \*pool, int numbers)  
*rs485\_thread\_pool\_create create linux thread pool*
- static void [rs485\\_thread\\_pool\\_clean](#) (void)  
*rs485\_thread\_pool\_clean clean the linux thread have create*
- static int [rs485\\_service\\_listen](#) (int \*socket\_fd, const char \*unix\_domain\_path)  
*rs485\_service\_listen create a unix domain socket communicate, used to offer rs485 service*
- void [rs485\\_service\\_create\\_clean](#) (void)  
*rs485\_service\_create\_clean have clean the rs485 socket communicate*
- int [rs485\\_receive\\_from\\_client](#) (int clifd, void \*buffer, int buffer\_len)
- int [rs485\\_send\\_msg\\_to\\_client](#) (int clifd, void \*buffer, int buffer\_len)  
*rs485\_send\_msg\_to\_client send The message to a client*
- static int [process\\_client\\_request](#) (void \*buf, int nread, int clifd, int [UNUSED](#)(uid))
- int [send\\_msg\\_to\\_adapter](#) (const [adapter\\_t](#) \*adapter)  
*send\_msg\_to\_adapter send a message to self,*
- static void [client\\_alloc](#) (void)
- static int [client\\_add](#) (int fd, uid\_t uid)
- static void [client\\_del](#) (int fd)
- static int [serv\\_accept](#) (int listenfd, uid\_t \*uidptr)
- static int [rs485\\_service\\_running](#) (const char \*path)  
*rs485\_service\_running The rs485 service function, It's wait the client requests. It's block*
- static void [rs485\\_service\\_running\\_clean](#) (void)  
*rs485\_service\_running\_clean Have clean the service running*
- int [rs485\\_service\\_start](#) (void)  
*rs485\_service\_start The rs485 service start*



## Variables

- int [glb\\_config\\_adapter\\_message\\_queue\\_depth](#)
- int [glb\\_config\\_client\\_max\\_numbers](#)
- static char [receive\\_buffer](#) [RECEIVE\_BUFFER\_LENGTH]
- static int [socket\\_fd](#)
- static unsigned int [socket\\_len](#)
- static struct sockaddr\_un [addr](#)
- static char [unix\\_domain\\_path](#) [108] = {0}
- static struct message\_queue [adapter\\_message\\_queue](#)
- static pthread\_t [adapter\\_thread](#)
- static pthread\_t [timer\\_task\\_thread](#)
- static [thread\\_pool\\_t](#) [rs485\\_thread\\_pool](#) []
- static [client\\_t](#) \* [client](#) = NULL
- static int [client\\_size](#) = 0

### 7.48.1 Detailed Description

[www.ennio.com](#)

Date

: Mar 14, 2016

Author

: chuanjiang.wong

Definition in file [service.c](#).

### 7.48.2 Macro Definition Documentation

#### 7.48.2.1 `#define NALLOC (10)`

Definition at line 45 of file [service.c](#).

#### 7.48.2.2 `#define RECEIVE_BUFFER_LENGTH (2048)`

define the socket receive buffer length

Definition at line 38 of file [service.c](#).

#### 7.48.2.3 `#define RS485_UNIX_DOMAIN_PATH "/home/user/bin/rs485d/rs485_unix_domain_service"`

set the unix domain sinstalocket path

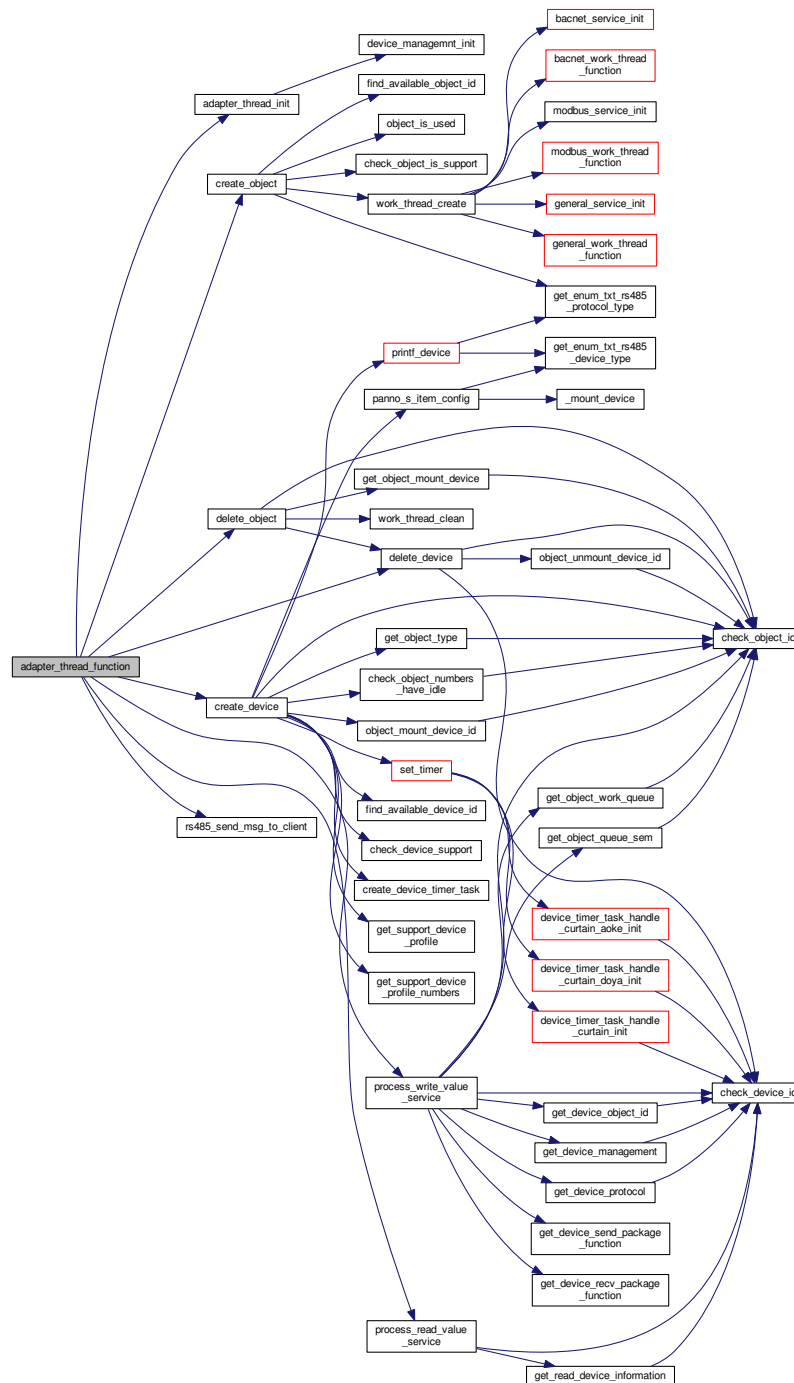
Definition at line 41 of file [service.c](#).

### 7.48.3 Function Documentation

#### 7.48.3.1 `void* adapter_thread_function ( void * arg )`

Definition at line 300 of file [adapter.c](#).

Here is the call graph for this function:



### 7.48.3.2 static int client\_add ( int fd, uid\_t uid ) [static]

Definition at line 315 of file service.c.

Here is the call graph for this function:



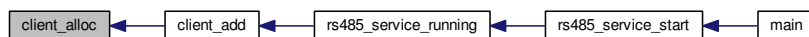
Here is the caller graph for this function:



#### 7.48.3.3 static void client\_alloc ( void ) [static]

Definition at line 292 of file service.c.

Here is the caller graph for this function:



#### 7.48.3.4 static void client\_del ( int fd ) [static]

Definition at line 340 of file service.c.

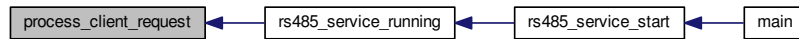
Here is the caller graph for this function:



#### 7.48.3.5 static int process\_client\_request ( void \* buf, int nread, int clifd, int UNUSEDuid ) [static]

Definition at line 252 of file service.c.

Here is the caller graph for this function:



7.48.3.6 `int rs485_receive_from_client ( int clifd, void * buffer, int buffer_len )`

Definition at line 241 of file `service.c`.

7.48.3.7 `static int rs485_service_listen ( int * socket_fd, const char * unix_domain_path )` `[static]`

`rs485_service_create` create a unix domain socket communicate, used to offer rs485 service

Parameters

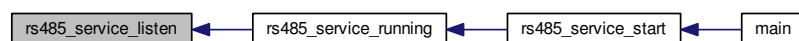
|     |                         |                                                 |
|-----|-------------------------|-------------------------------------------------|
| out | <i>socket_fd</i>        | : The socket id, have create it.                |
| in  | <i>unix_domain_path</i> | : The unix domain socket have bind a file path. |

Returns

0 is success, others is fail.

Definition at line 169 of file `service.c`.

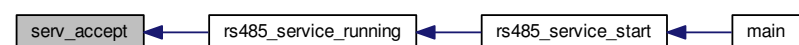
Here is the caller graph for this function:



7.48.3.8 `static int serv_accept ( int listenfd, uid_t * uidptr )` `[static]`

Definition at line 356 of file `service.c`.

Here is the caller graph for this function:



7.48.3.9 `void* timer_task_thread_function ( void * arg )`

#### 7.48.4 Variable Documentation

7.48.4.1 `struct message_queue adapter_message_queue` `[static]`

define the adapter message queue

Definition at line 79 of file service.c.

7.48.4.2 `pthread_t adapter_thread` `[static]`

define the adapter thread

Definition at line 81 of file service.c.

7.48.4.3 `struct sockaddr_un addr` `[static]`

define the unix domain socket struct

Definition at line 75 of file service.c.

7.48.4.4 `client_t* client = NULL` `[static]`

Definition at line 92 of file service.c.

7.48.4.5 `int client_size = 0` `[static]`

Definition at line 94 of file service.c.

7.48.4.6 `int glb_config_adapter_message_queue_depth`

Definition at line 32 of file read\_config.c.

7.48.4.7 `int glb_config_client_max_numbers`

Definition at line 37 of file read\_config.c.

7.48.4.8 `char receive_buffer[RECEIVE_BUFFER_LENGTH]` `[static]`

define the socket receive buffer

Definition at line 68 of file service.c.

7.48.4.9 `thread_pool_t rs485_thread_pool[]` `[static]`

#### Initial value:

```
=
{
    {&adapter_thread,      NULL,
      adapter_thread_function, &adapter_message_queue, false},
    {&timer_task_thread,  NULL,
      timer_task_thread_function, NULL, false},
}
```

define the rs485 service thread pool struct

Definition at line 85 of file service.c.

**7.48.4.10** `int socket_fd` `[static]`

define the socket id

Definition at line 70 of file service.c.

**7.48.4.11** `unsigned int socket_len` `[static]`

define the unix domain socket length

Definition at line 73 of file service.c.

**7.48.4.12** `pthread_t timer_task_thread` `[static]`

define the timer task thread

Definition at line 83 of file service.c.

**7.48.4.13** `char unix_domain_path[108] = {0}` `[static]`

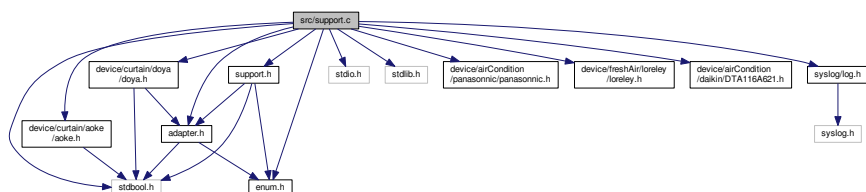
define the unix domain socket path variable , It's max length is 108

Definition at line 77 of file service.c.

## 7.49 src/support.c File Reference

```
#include <stdbool.h>
#include <stdio.h>
#include <stdlib.h>
#include "enum.h"
#include "adapter.h"
#include "support.h"
#include "device/airCondition/panasonic/panasonic.h"
#include "device/curtain/doya/doya.h"
#include "device/curtain/aoke/aoke.h"
#include "device/freshAir/loreley/loreley.h"
#include "device/airCondition/daikin/DTA116A621.h"
#include "syslog/log.h"
```

Include dependency graph for support.c:



## Functions

- bool [check\\_device\\_support](#) (const [adapter\\_t](#) \*adaptper)  
*check\_device\_support* check the device have supported by rs485 service
- struct [device\\_profile](#) \* [get\\_support\\_device\\_profile](#) ([rs485\\_factory\\_name\\_enum](#) name)  
*get\_support\_device\_profile* Get the device profile, The struct [device\\_profile](#)
- int [get\\_support\\_device\\_profile\\_numbers](#) ([rs485\\_factory\\_name\\_enum](#) name)  
*get\_support\_device\_profile\_numbers* Get the device profile have support how many command.
- method\_send [get\\_device\\_send\\_package\\_function](#) (const struct [device\\_profile](#) \*profile, int profile\_numbers, int command)  
*get\_device\_send\_package\_function* Get the device profile send package callback function
- method\_rcv [get\\_device\\_rcv\\_package\\_function](#) (const struct [device\\_profile](#) \*profile, int profile\_numbers, int command)  
*get\_device\_rcv\_package\_function* Get the device profile receive package callback function

## Variables

- static struct [device\\_profile](#) [air\\_condition\\_panasonic](#) []  
*device\_profile* The panasonic air condition device profile
- static struct [device\\_profile](#) [curtain\\_doya](#) []
- static struct [device\\_profile](#) [curtain\\_aoke](#) []
- static struct [device\\_profile](#) [fresh\\_air\\_loreley](#) []
- static struct [device\\_profile](#) [air\\_condition\\_daikin\\_dta116a621](#) []

### 7.49.1 Variable Documentation

#### 7.49.1.1 struct [device\\_profile](#) [air\\_condition\\_daikin\\_dta116a621](#)[] [static]

Definition at line 110 of file support.c.

#### 7.49.1.2 struct [device\\_profile](#) [air\\_condition\\_panasonic](#)[] [static]

[device\\_profile](#) The panasonic air condition device profile

Definition at line 40 of file support.c.

#### 7.49.1.3 struct [device\\_profile](#) [curtain\\_aoke](#)[] [static]

**Initial value:**

```
=
{
    {3,      RS485_CURTAIN_OPEN,
      aoke_send_package_handle,
      aoke_rcv_package_handle},
    {3,      RS485_CURTAIN_CLOSE,
      aoke_send_package_handle,
      aoke_rcv_package_handle},
    {3,      RS485_CURTAIN_SET_PERCENT,
      aoke_send_package_handle,
      aoke_rcv_package_handle},
    {3,      RS485_CURTAIN_GET_DEVICE_INFO,
      aoke_send_package_handle,
      aoke_rcv_package_handle},
}
```

Definition at line 94 of file support.c.

#### 7.49.1.4 struct device\_profile curtain\_doya[] [static]

##### Initial value:

```
=
{
    {2,      RS485_DOYA_CURTAIN_OPEN,
      doya_send_package_handle,
      doya_rcv_package_handle},
    {2,      RS485_DOYA_CURTAIN_CLOSE,
      doya_send_package_handle,
      doya_rcv_package_handle},
    {2,      RS485_DOYA_CURTAIN_SET_PERCENT,
      doya_send_package_handle,
      doya_rcv_package_handle},
    {2,      RS485_DOYA_CURTAIN_GET_DEVICE_INFO,
      doya_send_package_handle,
      doya_rcv_package_handle},
}
```

Definition at line 85 of file support.c.

#### 7.49.1.5 struct device\_profile fresh\_air\_loreley[] [static]

##### Initial value:

```
=
{
    {1,      RS485_FRESH_AIR_AUTO_ON,
      loreley_send_package_handle,
      loreley_rcv_package_handle},
    {1,      RS485_FRESH_AIR_AUTO_OFF,
      loreley_send_package_handle,
      loreley_rcv_package_handle},
    {1,      RS485_FRESH_AIR_GET_DEVICE_INFO,
      loreley_send_package_handle,
      loreley_rcv_package_handle},
}
```

Definition at line 102 of file support.c.

## 7.50 src/syslog/log.c File Reference

### 7.50.1 Detailed Description

www.enno.com

#### Date

: Mar 15, 2016

#### Author

: wong

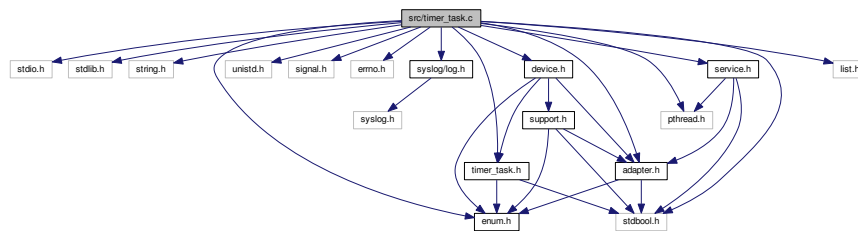
Definition in file [log.c](#).



## 7.51 src/timer\_task.c File Reference

```
#include <stdio.h>
#include <stdlib.h>
#include <string.h>
#include <stdbool.h>
#include <unistd.h>
#include <signal.h>
#include <errno.h>
#include <pthread.h>
#include "timer_task.h"
#include "syslog/log.h"
#include "enum.h"
#include "device.h"
#include "adapter.h"
#include "service.h"
#include "list.h"
```

Include dependency graph for timer\_task.c:



### Macros

- `#define SYSTEM_TIMER_TICK_SECOND (10)`

### Functions

- `static int timer_task_init (void)`  
*timer\_task\_init timer task initial*
- `void * timer_task_thread_function (void *UNUSED(arg))`
- `int create_device_timer_task (timer_task_t *task)`  
*create\_deivce\_timer\_task create a device timer task , The timer task min tick is 10 second*
- `int delete_device_timer_task (timer_task_t *task)`  
*delete\_device\_timer\_task delete a device timer task from The timer list.*
- `int device_timer_task_handle_demo (int device_id, int command)`  
*device\_timer\_task\_handle\_demo timer task handle fucntion demo*
- `int device_timer_task_handle_curtain_init (int device_id, int UNUSED(command))`
- `int device_timer_task_handle_curtain_aoke_init (int device_id, int UNUSED(command))`
- `int device_timer_task_handle_curtain_doya_init (int device_id, int UNUSED(command))`

### Variables

- `static list_t * timer_task_list = NULL`
- `static list_iterator_t * timer_task_list_iterator = NULL`
- `static int timer_task_thread_status = TIMER_TASK_THREAD_STATUS_START`
- `static pthread_mutex_t timer_task_lock`

### 7.51.1 Detailed Description

www.enno.com

Date

: Mar 14, 2016

Author

: chuanjiang.wong

Definition in file [timer\\_task.c](#).

### 7.51.2 Macro Definition Documentation

#### 7.51.2.1 #define SYSTEM\_TIMER\_TICK\_SECOND (10)

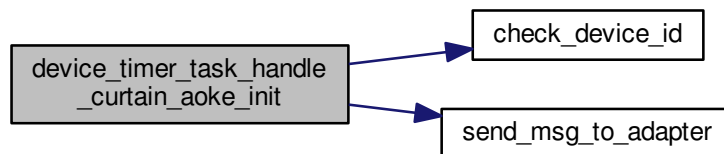
Definition at line 34 of file timer\_task.c.

### 7.51.3 Function Documentation

#### 7.51.3.1 int device\_timer\_task\_handle\_curtain\_aoke\_init ( int device\_id, int UNUSEDcommand )

Definition at line 273 of file timer\_task.c.

Here is the call graph for this function:



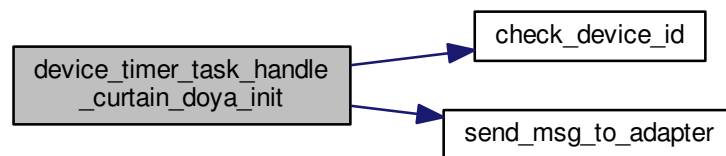
Here is the caller graph for this function:



#### 7.51.3.2 int device\_timer\_task\_handle\_curtain\_doya\_init ( int device\_id, int UNUSEDcommand )

Definition at line 303 of file timer\_task.c.

Here is the call graph for this function:



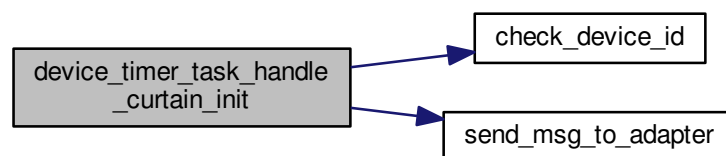
Here is the caller graph for this function:



### 7.51.3.3 int device\_timer\_task\_handle\_curtain\_init ( int device\_id, int UNUSEDcommand )

Definition at line 243 of file timer\_task.c.

Here is the call graph for this function:



Here is the caller graph for this function:



#### 7.51.3.4 `static int timer_task_init ( void ) [static]`

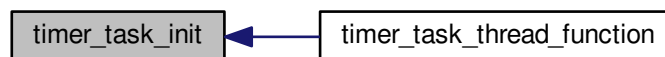
timer\_task\_init timer task initial

##### Returns

, 0 is success, others is fail.

Definition at line 58 of file timer\_task.c.

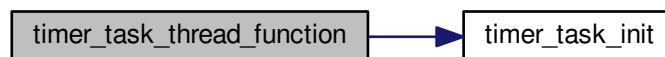
Here is the caller graph for this function:



#### 7.51.3.5 `void* timer_task_thread_function ( void * UNUSEDarg )`

Definition at line 90 of file timer\_task.c.

Here is the call graph for this function:



### 7.51.4 Variable Documentation

#### 7.51.4.1 `list_t* timer_task_list = NULL [static]`

define the timer managemnt list

Definition at line 39 of file timer\_task.c.

#### 7.51.4.2 `list_iterator_t* timer_task_list_iterator = NULL [static]`

define the list iterate

Definition at line 41 of file timer\_task.c.

#### 7.51.4.3 `pthread_mutex_t timer_task_lock [static]`

define a mutex to used to add and delete list data

Definition at line 45 of file timer\_task.c.

7.51.4.4 `int timer_task_thread_status = TIMER_TASK_THREAD_STATUS_START` `[static]`

define the timer thread status

Definition at line 43 of file timer\_task.c.

# Index

- ADAPTER\_THREAD\_STATUS\_INIT
  - enum.h, [153](#)
- ADAPTER\_THREAD\_STATUS\_RUNNING
  - enum.h, [153](#)
- ADAPTER\_THREAD\_STATUS\_START
  - enum.h, [153](#)
- ADAPTER\_THREAD\_STATUS\_STOP
  - enum.h, [153](#)
- ADAPTER\_THREAD\_STATUS\_UNKNOWN
  - enum.h, [153](#)
- AI\_COMPRESSOR\_FREQUENCY
  - york.c, [218](#)
- AI\_INDOOR\_HUMIDITY
  - york.c, [218](#)
- AI\_INDOOR\_TEMPERATURE
  - york.c, [218](#)
- AI\_NET\_CLEAR\_TIME\_LEFT
  - york.c, [218](#)
- AI\_OUTDOOR\_TEMPERATURE
  - york.c, [218](#)
- AI\_SET\_HUMIDITY
  - york.c, [218](#)
- AI\_SET\_TEMPERATURE
  - york.c, [218](#)
- AV\_SET\_HUMIDITY
  - york.c, [218](#)
- AV\_SET\_TEMPERATURE
  - york.c, [218](#)
- Adapter management, [19](#)
  - arg
    - bacnet, [104](#)
- BI\_CENTRAL\_CONONLY\_STATUS
  - york.c, [218](#)
- BI\_COMPRESSOR\_RUNNING\_STATUS
  - york.c, [218](#)
- BI\_COOL\_ONLY\_STATUS
  - york.c, [218](#)
- BI\_DEFROST
  - york.c, [218](#)
- BI\_ELECTRICAL\_HEAT\_STATUS
  - york.c, [218](#)
- BI\_ERROR\_RESET\_STATUS
  - york.c, [218](#)
- BI\_FIX\_RUN\_STATUS
  - york.c, [218](#)
- BI\_HEALTH\_AIR\_STATUS
  - york.c, [218](#)
- BI\_HOT\_WATER\_STATUS
  - york.c, [218](#)
- BI\_NET\_CLEAR\_RESET\_STATUS
  - york.c, [218](#)
- BI\_NEW\_AIR\_STATUS
  - york.c, [218](#)
- BI\_ON\_OFF\_STATUS
  - york.c, [218](#)
- BI\_SAVING\_STATUS
  - york.c, [218](#)
- BI\_SLEEP\_STATUS
  - york.c, [218](#)
- bacnet, [103](#)
  - arg, [104](#)
  - command, [104](#)
  - value, [104](#)
- COMMAND\_CLOSE
  - doya.c, [228](#)
- COMMAND\_DELETE
  - doya.c, [228](#)
- COMMAND\_OPEN
  - doya.c, [228](#)
- COMMAND\_PERCENT
  - doya.c, [228](#)
- COMMAND\_REFACTORY
  - doya.c, [228](#)
- COMMAND\_STOP
  - doya.c, [228](#)
- cmd
  - package, [131](#)
- command
  - bacnet, [104](#)
  - package, [131](#)
- Curtain, [17](#)
- data
  - package, [131](#)
- Device, [15](#)
- Device management, [40](#)
- Device register management, [94](#)
- doya.c
  - COMMAND\_CLOSE, [228](#)
  - COMMAND\_DELETE, [228](#)
  - COMMAND\_OPEN, [228](#)
  - COMMAND\_PERCENT, [228](#)
  - COMMAND\_REFACTORY, [228](#)
  - COMMAND\_STOP, [228](#)
  - RO\_PERCENT, [228](#)
  - RO\_VERSION, [228](#)
  - RW\_DIRECTION, [228](#)
  - RW\_HANDLE, [228](#)

RW\_SWITCH\_ACTIVE, 228  
 RW\_SWITCH\_PASSIVE, 228  
 WO\_ADDR, 228

## enum.h

ADAPTER\_THREAD\_STATUS\_INIT, 153  
 ADAPTER\_THREAD\_STATUS\_RUNNING, 153  
 ADAPTER\_THREAD\_STATUS\_START, 153  
 ADAPTER\_THREAD\_STATUS\_STOP, 153  
 ADAPTER\_THREAD\_STATUS\_UNKNOWN, 153  
 MODBUS\_FUNCTION\_CODE\_DO\_NOTHING, 153  
 MODBUS\_FUNCTION\_CODE\_READ\_MULTIPLE\_COILS, 153  
 MODBUS\_FUNCTION\_CODE\_READ\_MULTIPLE\_REGISTERS, 153  
 MODBUS\_FUNCTION\_CODE\_READ\_SINGLE\_COIL, 153  
 MODBUS\_FUNCTION\_CODE\_READ\_SINGLE\_REGISTER, 153  
 MODBUS\_FUNCTION\_CODE\_WRITE\_MULTIPLE\_COILS, 153  
 MODBUS\_FUNCTION\_CODE\_WRITE\_MULTIPLE\_REGISTERS, 153  
 MODBUS\_FUNCTION\_CODE\_WRITE\_SINGLE\_COIL, 153  
 MODBUS\_FUNCTION\_CODE\_WRITE\_SINGLE\_REGISTER, 153  
 OBJECT\_THREAD\_STATUS\_INIT, 153  
 OBJECT\_THREAD\_STATUS\_RUNNING, 153  
 OBJECT\_THREAD\_STATUS\_START, 153  
 OBJECT\_THREAD\_STATUS\_STOP, 153  
 OBJECT\_THREAD\_STATUS\_UNKNOWN, 153  
 RS485\_AIR\_FAN, 154  
 RS485\_AIR\_FAN\_AUTO, 154  
 RS485\_AIR\_FAN\_HIGH, 154  
 RS485\_AIR\_FAN\_LOW, 154  
 RS485\_AIR\_FAN\_MIDDLE, 154  
 RS485\_AIR\_GET\_DEVICE\_INFO, 154  
 RS485\_AIR\_MODE, 154  
 RS485\_AIR\_MODE\_AUTOING, 154  
 RS485\_AIR\_MODE\_COOLING, 154  
 RS485\_AIR\_MODE\_DRYING, 154  
 RS485\_AIR\_MODE\_FANING, 154  
 RS485\_AIR\_MODE\_HEATING, 154  
 RS485\_AIR\_OFF, 154  
 RS485\_AIR\_ON, 154  
 RS485\_AIR\_RESTART, 154  
 RS485\_AIR\_SET\_TEMP, 153  
 RS485\_AIR\_SET\_TEMP\_18, 153  
 RS485\_AIR\_SET\_TEMP\_19, 153  
 RS485\_AIR\_SET\_TEMP\_20, 153  
 RS485\_AIR\_SET\_TEMP\_21, 153  
 RS485\_AIR\_SET\_TEMP\_22, 153  
 RS485\_AIR\_SET\_TEMP\_23, 153  
 RS485\_AIR\_SET\_TEMP\_24, 154  
 RS485\_AIR\_SET\_TEMP\_25, 154  
 RS485\_AIR\_SET\_TEMP\_26, 154  
 RS485\_AIR\_SET\_TEMP\_27, 154  
 RS485\_AIR\_SET\_TEMP\_28, 154  
 RS485\_AIR\_SET\_TEMP\_29, 154  
 RS485\_AIR\_SET\_TEMP\_30, 154  
 RS485\_AIR\_SWING, 154  
 RS485\_AIR\_SWING\_AUTO, 154  
 RS485\_AIR\_SWING\_LEFT\_RIGHT, 154  
 RS485\_AIR\_SWING\_UP\_DOWN, 154  
 RS485\_AIR\_SWING\_UP\_DOWN\_LEFT\_RIGHT, 154  
 RS485\_AIR\_SWITCH, 154  
 RS485\_AOKE\_CURTAIN\_CLOSE, 158  
 RS485\_AOKE\_CURTAIN\_GET\_DEVICE\_INFO, 158  
 RS485\_AOKE\_CURTAIN\_OPEN, 158  
 RS485\_AOKE\_CURTAIN\_RESET, 158  
 RS485\_AOKE\_CURTAIN\_SET\_PERCENT, 158  
 RS485\_CURTAIN, 154  
 RS485\_CURTAIN\_CLOSE, 154  
 RS485\_CURTAIN\_GET\_DEVICE\_INFO, 154  
 RS485\_CURTAIN\_OPEN, 154  
 RS485\_CURTAIN\_RESET, 154  
 RS485\_CURTAIN\_SET\_PERCENT, 154  
 RS485\_DEVICE\_TYPE\_AIR\_CONDITION, 155  
 RS485\_DEVICE\_TYPE\_CURTAIN, 155  
 RS485\_DEVICE\_TYPE\_FRESH\_AIR, 155  
 RS485\_DEVICE\_TYPE\_UNKNOWN, 155  
 RS485\_DOYA\_CURTAIN\_CLOSE, 158  
 RS485\_DOYA\_CURTAIN\_GET\_DEVICE\_INFO, 158  
 RS485\_DOYA\_CURTAIN\_OPEN, 158  
 RS485\_DOYA\_CURTAIN\_RESET, 158  
 RS485\_DOYA\_CURTAIN\_SET\_PERCENT, 158  
 RS485\_FACTORY\_AOKE, 155  
 RS485\_FACTORY\_DAIKIN\_DTA116A621, 155  
 RS485\_FACTORY\_DOYA, 155  
 RS485\_FACTORY\_LORELEY, 155  
 RS485\_FACTORY\_PANASONNIC, 155  
 RS485\_FACTORY\_UNKNOWN, 155  
 RS485\_FACTORY\_YORK, 155  
 RS485\_FRESH\_AIR, 154  
 RS485\_FRESH\_AIR\_AUTO\_OFF, 154  
 RS485\_FRESH\_AIR\_AUTO\_ON, 154  
 RS485\_FRESH\_AIR\_GET\_DEVICE\_INFO, 154  
 RS485\_FRESH\_AIR\_RESET, 154  
 RS485\_LORELEY\_FRESH\_AIR\_AUTO\_OFF, 158  
 RS485\_LORELEY\_FRESH\_AIR\_AUTO\_ON, 158  
 RS485\_LORELEY\_FRESH\_AIR\_GET\_DEVICE\_INFO, 158  
 RS485\_LORELEY\_FRESH\_AIR\_RESET, 158  
 RS485\_PANASONNIC\_AIR\_FAN\_AUTO, 156  
 RS485\_PANASONNIC\_AIR\_FAN\_HIGH, 156  
 RS485\_PANASONNIC\_AIR\_FAN\_LOW, 156  
 RS485\_PANASONNIC\_AIR\_FAN\_MIDDLE, 156  
 RS485\_PANASONNIC\_AIR\_FAN\_MOST, 156  
 RS485\_PANASONNIC\_AIR\_FAN\_MUTE, 156  
 RS485\_PANASONNIC\_AIR\_GET\_DEVICE\_INFO, 156

- RS485\_PANASONNIC\_AIR\_MODE\_AUTOING, [156](#)
- RS485\_PANASONNIC\_AIR\_MODE\_COOLING, [156](#)
- RS485\_PANASONNIC\_AIR\_MODE\_DRYING, [156](#)
- RS485\_PANASONNIC\_AIR\_MODE\_FANING, [156](#)
- RS485\_PANASONNIC\_AIR\_MODE\_HEATING, [156](#)
- RS485\_PANASONNIC\_AIR\_OFF, [156](#)
- RS485\_PANASONNIC\_AIR\_ON, [156](#)
- RS485\_PANASONNIC\_AIR\_RESET, [156](#)
- RS485\_PANASONNIC\_AIR\_SET\_TEMP\_16, [155](#)
- RS485\_PANASONNIC\_AIR\_SET\_TEMP\_17, [155](#)
- RS485\_PANASONNIC\_AIR\_SET\_TEMP\_18, [155](#)
- RS485\_PANASONNIC\_AIR\_SET\_TEMP\_19, [155](#)
- RS485\_PANASONNIC\_AIR\_SET\_TEMP\_20, [155](#)
- RS485\_PANASONNIC\_AIR\_SET\_TEMP\_21, [155](#)
- RS485\_PANASONNIC\_AIR\_SET\_TEMP\_22, [155](#)
- RS485\_PANASONNIC\_AIR\_SET\_TEMP\_23, [155](#)
- RS485\_PANASONNIC\_AIR\_SET\_TEMP\_24, [155](#)
- RS485\_PANASONNIC\_AIR\_SET\_TEMP\_25, [155](#)
- RS485\_PANASONNIC\_AIR\_SET\_TEMP\_26, [155](#)
- RS485\_PANASONNIC\_AIR\_SET\_TEMP\_27, [155](#)
- RS485\_PANASONNIC\_AIR\_SET\_TEMP\_28, [155](#)
- RS485\_PANASONNIC\_AIR\_SET\_TEMP\_29, [155](#)
- RS485\_PANASONNIC\_AIR\_SET\_TEMP\_30, [155](#)
- RS485\_PANASONNIC\_AIR\_SWING\_AUTO, [155](#)
- RS485\_PANASONNIC\_AIR\_SWING\_HAND1, [156](#)
- RS485\_PANASONNIC\_AIR\_SWING\_HAND2, [156](#)
- RS485\_PANASONNIC\_AIR\_SWING\_HAND3, [156](#)
- RS485\_PANASONNIC\_AIR\_SWING\_HAND4, [156](#)
- RS485\_PANASONNIC\_AIR\_SWING\_HAND5, [156](#)
- RS485\_PROTOCOL\_TYPE\_BACNET, [158](#)
- RS485\_PROTOCOL\_TYPE\_GENERAL, [158](#)
- RS485\_PROTOCOL\_TYPE\_MODBUS, [158](#)
- RS485\_PROTOCOL\_TYPE\_UNKNOWN, [158](#)
- RS485\_YORK\_AIR\_CENTRAL\_CONTROL\_ON↵LY\_NO, [157](#)
- RS485\_YORK\_AIR\_CENTRAL\_CONTROL\_ON↵LY\_YES, [157](#)
- RS485\_YORK\_AIR\_COOL\_ONLY\_NO, [157](#)
- RS485\_YORK\_AIR\_COOL\_ONLY\_YES, [157](#)
- RS485\_YORK\_AIR\_DEFROST\_NO, [157](#)
- RS485\_YORK\_AIR\_DEFROST\_YES, [157](#)
- RS485\_YORK\_AIR\_ELECTRICAL\_HEAT\_NO, [157](#)
- RS485\_YORK\_AIR\_ELECTRICAL\_HEAT\_YES, [157](#)
- RS485\_YORK\_AIR\_ERR\_RESET\_NO, [157](#)
- RS485\_YORK\_AIR\_ERR\_RESET\_YES, [157](#)
- RS485\_YORK\_AIR\_FAN\_AUTO, [157](#)
- RS485\_YORK\_AIR\_FAN\_HIGH, [157](#)
- RS485\_YORK\_AIR\_FAN\_LOW, [157](#)
- RS485\_YORK\_AIR\_FAN\_MIDDLE, [157](#)
- RS485\_YORK\_AIR\_FIX\_RUN\_NO, [157](#)
- RS485\_YORK\_AIR\_FIX\_RUN\_YES, [157](#)
- RS485\_YORK\_AIR\_GET\_DEVICE\_INFO, [157](#)
- RS485\_YORK\_AIR\_HEALTH\_AIR\_NO, [157](#)
- RS485\_YORK\_AIR\_HEALTH\_AIR\_YES, [157](#)
- RS485\_YORK\_AIR\_HOME\_LEFT\_NO, [157](#)
- RS485\_YORK\_AIR\_HOME\_LEFT\_YES, [157](#)
- RS485\_YORK\_AIR\_HOT\_WATER\_NO, [157](#)
- RS485\_YORK\_AIR\_HOT\_WATER\_YES, [157](#)
- RS485\_YORK\_AIR\_MODE\_AUTOING, [157](#)
- RS485\_YORK\_AIR\_MODE\_COOLING, [157](#)
- RS485\_YORK\_AIR\_MODE\_DRYING, [157](#)
- RS485\_YORK\_AIR\_MODE\_FANING, [157](#)
- RS485\_YORK\_AIR\_MODE\_HEATING, [157](#)
- RS485\_YORK\_AIR\_NET\_RESET\_NO, [157](#)
- RS485\_YORK\_AIR\_NET\_RESET\_YES, [157](#)
- RS485\_YORK\_AIR\_OFF, [157](#)
- RS485\_YORK\_AIR\_ON, [157](#)
- RS485\_YORK\_AIR\_SAVING\_NO, [157](#)
- RS485\_YORK\_AIR\_SAVING\_YES, [157](#)
- RS485\_YORK\_AIR\_SET\_HUMIDITY, [156](#)
- RS485\_YORK\_AIR\_SET\_TEMP\_18, [156](#)
- RS485\_YORK\_AIR\_SET\_TEMP\_19, [156](#)
- RS485\_YORK\_AIR\_SET\_TEMP\_20, [156](#)
- RS485\_YORK\_AIR\_SET\_TEMP\_21, [156](#)
- RS485\_YORK\_AIR\_SET\_TEMP\_22, [156](#)
- RS485\_YORK\_AIR\_SET\_TEMP\_23, [156](#)
- RS485\_YORK\_AIR\_SET\_TEMP\_24, [156](#)
- RS485\_YORK\_AIR\_SET\_TEMP\_25, [156](#)
- RS485\_YORK\_AIR\_SET\_TEMP\_26, [156](#)
- RS485\_YORK\_AIR\_SET\_TEMP\_27, [156](#)
- RS485\_YORK\_AIR\_SET\_TEMP\_28, [156](#)
- RS485\_YORK\_AIR\_SET\_TEMP\_29, [156](#)
- RS485\_YORK\_AIR\_SET\_TEMP\_30, [156](#)
- RS485\_YORK\_AIR\_SET\_TEMP\_31, [156](#)
- RS485\_YORK\_AIR\_SET\_TEMP\_32, [156](#)
- RS485\_YORK\_AIR\_SLEEP\_NO, [157](#)
- RS485\_YORK\_AIR\_SLEEP\_YES, [157](#)
- RS485\_YORK\_AIR\_SWING\_AUTO, [156](#)
- RS485\_YORK\_AIR\_SWING\_LEFT\_RIGHT, [157](#)
- RS485\_YORK\_AIR\_SWING\_UP\_DOWN, [156](#)
- RS485\_YORK\_AIR\_SWING\_UP\_DOWN\_LEFT↵RIGHT, [157](#)
- SERVICE\_CREATE\_RS485\_OBJECT, [159](#)
- SERVICE\_DELETE\_RS485\_OBJECT, [159](#)
- SERVICE\_MOUNT\_DEVICE\_TO\_OBJECT, [159](#)
- SERVICE\_READ\_VALUE\_FROM\_DEVICE, [159](#)
- SERVICE\_SYSTEM\_UPDATE\_START, [159](#)
- SERVICE\_SYSTEM\_UPDATE\_STOP, [159](#)
- SERVICE\_UNKNOWN, [159](#)
- SERVICE\_UNMOUNT\_DEVICE\_FROM\_OBJE↵CT, [159](#)
- SERVICE\_WRITE\_VALUE\_TO\_DEVICE, [159](#)
- TIMER\_TASK\_THREAD\_STATUS\_ADDING, [159](#)
- TIMER\_TASK\_THREAD\_STATUS\_DELETEING, [159](#)
- TIMER\_TASK\_THREAD\_STATUS\_INIT, [159](#)
- TIMER\_TASK\_THREAD\_STATUS\_RUNNING, [159](#)
- TIMER\_TASK\_THREAD\_STATUS\_START, [159](#)
- TIMER\_TASK\_THREAD\_STATUS\_STOP, [159](#)



- TIMER\_TASK\_THREAD\_STATUS\_UNKNOWN, 159
- General, 14
- General interface, 79
- Item management, 58
- MI\_COMMUNICATION\_STATUS
  - york.c, 218
- MI\_ERROR
  - york.c, 218
- MI\_FAN
  - york.c, 218
- MI\_INDOOR\_STYLE
  - york.c, 218
- MI\_LOCAL\_SET
  - york.c, 218
- MI\_MODE
  - york.c, 218
- MI\_RESERVED
  - york.c, 218
- MI\_SWING
  - york.c, 218
- MI\_VENTILATION
  - york.c, 218
- MODBUS\_FUNCTION\_CODE\_DO\_NOTHING
  - enum.h, 153
- MODBUS\_FUNCTION\_CODE\_READ\_MULTIPLE\_COILS
  - enum.h, 153
- MODBUS\_FUNCTION\_CODE\_READ\_MULTIPLE\_REGISTERS
  - enum.h, 153
- MODBUS\_FUNCTION\_CODE\_READ\_SIGNLE\_COIL
  - enum.h, 153
- MODBUS\_FUNCTION\_CODE\_READ\_SIGNLE\_REGISTER
  - enum.h, 153
- MODBUS\_FUNCTION\_CODE\_WRITE\_MULTIPLE\_COILS
  - enum.h, 153
- MODBUS\_FUNCTION\_CODE\_WRITE\_MULTIPLE\_REGISTERS
  - enum.h, 153
- MODBUS\_FUNCTION\_CODE\_WRITE\_SIGNLE\_COIL
  - enum.h, 153
- MODBUS\_FUNCTION\_CODE\_WRITE\_SIGNLE\_REGISTER
  - enum.h, 153
- Management, 9
- Modbus, 13
- OBJECT\_THREAD\_STATUS\_INIT
  - enum.h, 153
- OBJECT\_THREAD\_STATUS\_RUNNING
  - enum.h, 153
- OBJECT\_THREAD\_STATUS\_START
  - enum.h, 153
- OBJECT\_THREAD\_STATUS\_STOP
  - enum.h, 153
- OBJECT\_THREAD\_STATUS\_UNKNOWN
  - enum.h, 153
- Object management, 60
- package, 130
  - cmd, 131
  - command, 131
  - data, 131
- Protocol, 11
- RO\_PERCENT
  - doya.c, 228
- RO\_VERSION
  - doya.c, 228
- RS485\_AIR\_FAN
  - enum.h, 154
- RS485\_AIR\_FAN\_AUTO
  - enum.h, 154
- RS485\_AIR\_FAN\_HIGH
  - enum.h, 154
- RS485\_AIR\_FAN\_LOW
  - enum.h, 154
- RS485\_AIR\_FAN\_MIDDLE
  - enum.h, 154
- RS485\_AIR\_GET\_DEVICE\_INFO
  - enum.h, 154
- RS485\_AIR\_MODE
  - enum.h, 154
- RS485\_AIR\_MODE\_AUTOING
  - enum.h, 154
- RS485\_AIR\_MODE\_COOLING
  - enum.h, 154
- RS485\_AIR\_MODE\_DRYING
  - enum.h, 154
- RS485\_AIR\_MODE\_FANING
  - enum.h, 154
- RS485\_AIR\_MODE\_HEATING
  - enum.h, 154
- RS485\_AIR\_OFF
  - enum.h, 154
- RS485\_AIR\_ON
  - enum.h, 154
- RS485\_AIR\_RESTART
  - enum.h, 154
- RS485\_AIR\_SET\_TEMP
  - enum.h, 153
- RS485\_AIR\_SET\_TEMP\_18
  - enum.h, 153
- RS485\_AIR\_SET\_TEMP\_19
  - enum.h, 153
- RS485\_AIR\_SET\_TEMP\_20
  - enum.h, 153
- RS485\_AIR\_SET\_TEMP\_21
  - enum.h, 153
- RS485\_AIR\_SET\_TEMP\_22
  - enum.h, 153

RS485\_AIR\_SET\_TEMP\_23  
enum.h, [153](#)

RS485\_AIR\_SET\_TEMP\_24  
enum.h, [154](#)

RS485\_AIR\_SET\_TEMP\_25  
enum.h, [154](#)

RS485\_AIR\_SET\_TEMP\_26  
enum.h, [154](#)

RS485\_AIR\_SET\_TEMP\_27  
enum.h, [154](#)

RS485\_AIR\_SET\_TEMP\_28  
enum.h, [154](#)

RS485\_AIR\_SET\_TEMP\_29  
enum.h, [154](#)

RS485\_AIR\_SET\_TEMP\_30  
enum.h, [154](#)

RS485\_AIR\_SWING  
enum.h, [154](#)

RS485\_AIR\_SWING\_AUTO  
enum.h, [154](#)

RS485\_AIR\_SWING\_LEFT\_RIGHT  
enum.h, [154](#)

RS485\_AIR\_SWING\_UP\_DOWN  
enum.h, [154](#)

RS485\_AIR\_SWING\_UP\_DOWN\_LEFT\_RIGHT  
enum.h, [154](#)

RS485\_AIR\_SWITCH  
enum.h, [154](#)

RS485\_AOKE\_CURTAIN\_CLOSE  
enum.h, [158](#)

RS485\_AOKE\_CURTAIN\_GET\_DEVICE\_INFO  
enum.h, [158](#)

RS485\_AOKE\_CURTAIN\_OPEN  
enum.h, [158](#)

RS485\_AOKE\_CURTAIN\_RESET  
enum.h, [158](#)

RS485\_AOKE\_CURTAIN\_SET\_PERCENT  
enum.h, [158](#)

RS485\_CURTAIN  
enum.h, [154](#)

RS485\_CURTAIN\_CLOSE  
enum.h, [154](#)

RS485\_CURTAIN\_GET\_DEVICE\_INFO  
enum.h, [154](#)

RS485\_CURTAIN\_OPEN  
enum.h, [154](#)

RS485\_CURTAIN\_RESET  
enum.h, [154](#)

RS485\_CURTAIN\_SET\_PERCENT  
enum.h, [154](#)

RS485\_DEVICE\_TYPE\_AIR\_CONDITION  
enum.h, [155](#)

RS485\_DEVICE\_TYPE\_CURTAIN  
enum.h, [155](#)

RS485\_DEVICE\_TYPE\_FRESH\_AIR  
enum.h, [155](#)

RS485\_DEVICE\_TYPE\_UNKNOWN  
enum.h, [155](#)

RS485\_DOYA\_CURTAIN\_CLOSE  
enum.h, [158](#)

RS485\_DOYA\_CURTAIN\_GET\_DEVICE\_INFO  
enum.h, [158](#)

RS485\_DOYA\_CURTAIN\_OPEN  
enum.h, [158](#)

RS485\_DOYA\_CURTAIN\_RESET  
enum.h, [158](#)

RS485\_DOYA\_CURTAIN\_SET\_PERCENT  
enum.h, [158](#)

RS485\_FACTORY\_AOKE  
enum.h, [155](#)

RS485\_FACTORY\_DAIKIN\_DTA116A621  
enum.h, [155](#)

RS485\_FACTORY\_DOYA  
enum.h, [155](#)

RS485\_FACTORY\_LORELEY  
enum.h, [155](#)

RS485\_FACTORY\_PANASONNIC  
enum.h, [155](#)

RS485\_FACTORY\_UNKNOWN  
enum.h, [155](#)

RS485\_FACTORY\_YORK  
enum.h, [155](#)

RS485\_FRESH\_AIR  
enum.h, [154](#)

RS485\_FRESH\_AIR\_AUTO\_OFF  
enum.h, [154](#)

RS485\_FRESH\_AIR\_AUTO\_ON  
enum.h, [154](#)

RS485\_FRESH\_AIR\_GET\_DEVICE\_INFO  
enum.h, [154](#)

RS485\_FRESH\_AIR\_RESET  
enum.h, [154](#)

RS485\_LORELEY\_FRESH\_AIR\_AUTO\_OFF  
enum.h, [158](#)

RS485\_LORELEY\_FRESH\_AIR\_AUTO\_ON  
enum.h, [158](#)

RS485\_LORELEY\_FRESH\_AIR\_GET\_DEVICE\_INFO  
enum.h, [158](#)

RS485\_LORELEY\_FRESH\_AIR\_RESET  
enum.h, [158](#)

RS485\_PANASONNIC\_AIR\_FAN\_AUTO  
enum.h, [156](#)

RS485\_PANASONNIC\_AIR\_FAN\_HIGH  
enum.h, [156](#)

RS485\_PANASONNIC\_AIR\_FAN\_LOW  
enum.h, [156](#)

RS485\_PANASONNIC\_AIR\_FAN\_MIDDLE  
enum.h, [156](#)

RS485\_PANASONNIC\_AIR\_FAN\_MOST  
enum.h, [156](#)

RS485\_PANASONNIC\_AIR\_FAN\_MUTE  
enum.h, [156](#)

RS485\_PANASONNIC\_AIR\_GET\_DEVICE\_INFO  
enum.h, [156](#)

RS485\_PANASONNIC\_AIR\_MODE\_AUTOING  
enum.h, [156](#)

- RS485\_PANASONNIC\_AIR\_MODE\_COOLING  
enum.h, [156](#)
- RS485\_PANASONNIC\_AIR\_MODE\_DRYING  
enum.h, [156](#)
- RS485\_PANASONNIC\_AIR\_MODE\_FANING  
enum.h, [156](#)
- RS485\_PANASONNIC\_AIR\_MODE\_HEATING  
enum.h, [156](#)
- RS485\_PANASONNIC\_AIR\_OFF  
enum.h, [156](#)
- RS485\_PANASONNIC\_AIR\_ON  
enum.h, [156](#)
- RS485\_PANASONNIC\_AIR\_RESET  
enum.h, [156](#)
- RS485\_PANASONNIC\_AIR\_SET\_TEMP\_16  
enum.h, [155](#)
- RS485\_PANASONNIC\_AIR\_SET\_TEMP\_17  
enum.h, [155](#)
- RS485\_PANASONNIC\_AIR\_SET\_TEMP\_18  
enum.h, [155](#)
- RS485\_PANASONNIC\_AIR\_SET\_TEMP\_19  
enum.h, [155](#)
- RS485\_PANASONNIC\_AIR\_SET\_TEMP\_20  
enum.h, [155](#)
- RS485\_PANASONNIC\_AIR\_SET\_TEMP\_21  
enum.h, [155](#)
- RS485\_PANASONNIC\_AIR\_SET\_TEMP\_22  
enum.h, [155](#)
- RS485\_PANASONNIC\_AIR\_SET\_TEMP\_23  
enum.h, [155](#)
- RS485\_PANASONNIC\_AIR\_SET\_TEMP\_24  
enum.h, [155](#)
- RS485\_PANASONNIC\_AIR\_SET\_TEMP\_25  
enum.h, [155](#)
- RS485\_PANASONNIC\_AIR\_SET\_TEMP\_26  
enum.h, [155](#)
- RS485\_PANASONNIC\_AIR\_SET\_TEMP\_27  
enum.h, [155](#)
- RS485\_PANASONNIC\_AIR\_SET\_TEMP\_28  
enum.h, [155](#)
- RS485\_PANASONNIC\_AIR\_SET\_TEMP\_29  
enum.h, [155](#)
- RS485\_PANASONNIC\_AIR\_SET\_TEMP\_30  
enum.h, [155](#)
- RS485\_PANASONNIC\_AIR\_SWING\_AUTO  
enum.h, [155](#)
- RS485\_PANASONNIC\_AIR\_SWING\_HAND1  
enum.h, [156](#)
- RS485\_PANASONNIC\_AIR\_SWING\_HAND2  
enum.h, [156](#)
- RS485\_PANASONNIC\_AIR\_SWING\_HAND3  
enum.h, [156](#)
- RS485\_PANASONNIC\_AIR\_SWING\_HAND4  
enum.h, [156](#)
- RS485\_PANASONNIC\_AIR\_SWING\_HAND5  
enum.h, [156](#)
- RS485\_PROTOCOL\_TYPE\_BACNET  
enum.h, [158](#)
- RS485\_PROTOCOL\_TYPE\_GENERAL  
enum.h, [158](#)
- RS485\_PROTOCOL\_TYPE\_MODBUS  
enum.h, [158](#)
- RS485\_PROTOCOL\_TYPE\_UNKNOWN  
enum.h, [158](#)
- RS485\_YORK\_AIR\_CENTRAL\_CONTROL\_ONLY\_↔  
NO  
enum.h, [157](#)
- RS485\_YORK\_AIR\_CENTRAL\_CONTROL\_ONLY\_Y↔  
ES  
enum.h, [157](#)
- RS485\_YORK\_AIR\_COOL\_ONLY\_NO  
enum.h, [157](#)
- RS485\_YORK\_AIR\_COOL\_ONLY\_YES  
enum.h, [157](#)
- RS485\_YORK\_AIR\_DEFROST\_NO  
enum.h, [157](#)
- RS485\_YORK\_AIR\_DEFROST\_YES  
enum.h, [157](#)
- RS485\_YORK\_AIR\_ELECTRICAL\_HEAT\_NO  
enum.h, [157](#)
- RS485\_YORK\_AIR\_ELECTRICAL\_HEAT\_YES  
enum.h, [157](#)
- RS485\_YORK\_AIR\_ERR\_RESET\_NO  
enum.h, [157](#)
- RS485\_YORK\_AIR\_ERR\_RESET\_YES  
enum.h, [157](#)
- RS485\_YORK\_AIR\_FAN\_AUTO  
enum.h, [157](#)
- RS485\_YORK\_AIR\_FAN\_HIGH  
enum.h, [157](#)
- RS485\_YORK\_AIR\_FAN\_LOW  
enum.h, [157](#)
- RS485\_YORK\_AIR\_FAN\_MIDDLE  
enum.h, [157](#)
- RS485\_YORK\_AIR\_FIX\_RUN\_NO  
enum.h, [157](#)
- RS485\_YORK\_AIR\_FIX\_RUN\_YES  
enum.h, [157](#)
- RS485\_YORK\_AIR\_GET\_DEVICE\_INFO  
enum.h, [157](#)
- RS485\_YORK\_AIR\_HEALTH\_AIR\_NO  
enum.h, [157](#)
- RS485\_YORK\_AIR\_HEALTH\_AIR\_YES  
enum.h, [157](#)
- RS485\_YORK\_AIR\_HOME\_LEFT\_NO  
enum.h, [157](#)
- RS485\_YORK\_AIR\_HOME\_LEFT\_YES  
enum.h, [157](#)
- RS485\_YORK\_AIR\_HOT\_WATER\_NO  
enum.h, [157](#)
- RS485\_YORK\_AIR\_HOT\_WATER\_YES  
enum.h, [157](#)
- RS485\_YORK\_AIR\_MODE\_AUTOING  
enum.h, [157](#)
- RS485\_YORK\_AIR\_MODE\_COOLING  
enum.h, [157](#)

- RS485\_YORK\_AIR\_MODE\_DRYING  
enum.h, [157](#)
- RS485\_YORK\_AIR\_MODE\_FANING  
enum.h, [157](#)
- RS485\_YORK\_AIR\_MODE\_HEATING  
enum.h, [157](#)
- RS485\_YORK\_AIR\_NET\_RESET\_NO  
enum.h, [157](#)
- RS485\_YORK\_AIR\_NET\_RESET\_YES  
enum.h, [157](#)
- RS485\_YORK\_AIR\_OFF  
enum.h, [157](#)
- RS485\_YORK\_AIR\_ON  
enum.h, [157](#)
- RS485\_YORK\_AIR\_SAVING\_NO  
enum.h, [157](#)
- RS485\_YORK\_AIR\_SAVING\_YES  
enum.h, [157](#)
- RS485\_YORK\_AIR\_SET\_HUMIDITY  
enum.h, [156](#)
- RS485\_YORK\_AIR\_SET\_TEMP\_18  
enum.h, [156](#)
- RS485\_YORK\_AIR\_SET\_TEMP\_19  
enum.h, [156](#)
- RS485\_YORK\_AIR\_SET\_TEMP\_20  
enum.h, [156](#)
- RS485\_YORK\_AIR\_SET\_TEMP\_21  
enum.h, [156](#)
- RS485\_YORK\_AIR\_SET\_TEMP\_22  
enum.h, [156](#)
- RS485\_YORK\_AIR\_SET\_TEMP\_23  
enum.h, [156](#)
- RS485\_YORK\_AIR\_SET\_TEMP\_24  
enum.h, [156](#)
- RS485\_YORK\_AIR\_SET\_TEMP\_25  
enum.h, [156](#)
- RS485\_YORK\_AIR\_SET\_TEMP\_26  
enum.h, [156](#)
- RS485\_YORK\_AIR\_SET\_TEMP\_27  
enum.h, [156](#)
- RS485\_YORK\_AIR\_SET\_TEMP\_28  
enum.h, [156](#)
- RS485\_YORK\_AIR\_SET\_TEMP\_29  
enum.h, [156](#)
- RS485\_YORK\_AIR\_SET\_TEMP\_30  
enum.h, [156](#)
- RS485\_YORK\_AIR\_SET\_TEMP\_31  
enum.h, [156](#)
- RS485\_YORK\_AIR\_SET\_TEMP\_32  
enum.h, [156](#)
- RS485\_YORK\_AIR\_SLEEP\_NO  
enum.h, [157](#)
- RS485\_YORK\_AIR\_SLEEP\_YES  
enum.h, [157](#)
- RS485\_YORK\_AIR\_SWING\_AUTO  
enum.h, [156](#)
- RS485\_YORK\_AIR\_SWING\_LEFT\_RIGHT  
enum.h, [157](#)
- RS485\_YORK\_AIR\_SWING\_UP\_DOWN  
enum.h, [156](#)
- RS485\_YORK\_AIR\_SWING\_UP\_DOWN\_LEFT\_RIGHT  
enum.h, [157](#)
- RW\_DIRECTION  
doya.c, [228](#)
- RW\_HANDLE  
doya.c, [228](#)
- RW\_SWITCH\_ACTIVE  
doya.c, [228](#)
- RW\_SWITCH\_PASSIVE  
doya.c, [228](#)
- SERVICE\_CREATE\_RS485\_OBJECT  
enum.h, [159](#)
- SERVICE\_DELETE\_RS485\_OBJECT  
enum.h, [159](#)
- SERVICE\_MOUNT\_DEVICE\_TO\_OBJECT  
enum.h, [159](#)
- SERVICE\_READ\_VALUE\_FROM\_DEVICE  
enum.h, [159](#)
- SERVICE\_SYSTEM\_UPDATE\_START  
enum.h, [159](#)
- SERVICE\_SYSTEM\_UPDATE\_STOP  
enum.h, [159](#)
- SERVICE\_UNKNOWN  
enum.h, [159](#)
- SERVICE\_UNMOUNT\_DEVICE\_FROM\_OBJECT  
enum.h, [159](#)
- SERVICE\_WRITE\_VALUE\_TO\_DEVICE  
enum.h, [159](#)
- Service management, [89](#)
- String management, [55](#)
- TIMER\_TASK\_THREAD\_STATUS\_ADDING  
enum.h, [159](#)
- TIMER\_TASK\_THREAD\_STATUS\_DELETEING  
enum.h, [159](#)
- TIMER\_TASK\_THREAD\_STATUS\_INIT  
enum.h, [159](#)
- TIMER\_TASK\_THREAD\_STATUS\_RUNNING  
enum.h, [159](#)
- TIMER\_TASK\_THREAD\_STATUS\_START  
enum.h, [159](#)
- TIMER\_TASK\_THREAD\_STATUS\_STOP  
enum.h, [159](#)
- TIMER\_TASK\_THREAD\_STATUS\_UNKNOWN  
enum.h, [159](#)
- Timer management, [98](#)
- value  
bacnet, [104](#)
- WO\_ADDR  
doya.c, [228](#)
- york.c  
AI\_COMPRESSOR\_FREQUENCY, [218](#)

AI\_INDOOR\_HUMIDITY, 218  
AI\_INDOOR\_TEMPERATURE, 218  
AI\_NET\_CLEAR\_TIME\_LEFT, 218  
AI\_OUTDOOR\_TEMPERATURE, 218  
AI\_SET\_HUMIDITY, 218  
AI\_SET\_TEMPERATURE, 218  
AV\_SET\_HUMIDITY, 218  
AV\_SET\_TEMPERATURE, 218  
BI\_CENTRAL\_CONONLY\_STATUS, 218  
BI\_COMPRESSOR\_RUNNING\_STATUS, 218  
BI\_COOL\_ONLY\_STATUS, 218  
BI\_DEFROST, 218  
BI\_ELECTRICAL\_HEAT\_STATUS, 218  
BI\_ERROR\_RESET\_STATUS, 218  
BI\_FIX\_RUN\_STATUS, 218  
BI\_HEALTH\_AIR\_STATUS, 218  
BI\_HOT\_WATER\_STATUS, 218  
BI\_NET\_CLEAR\_RESET\_STATUS, 218  
BI\_NEW\_AIR\_STATUS, 218  
BI\_ON\_OFF\_STATUS, 218  
BI\_SAVING\_STATUS, 218  
BI\_SLEEP\_STATUS, 218  
MI\_COMMUNICATION\_STATUS, 218  
MI\_ERROR, 218  
MI\_FAN, 218  
MI\_INDOOR\_STYLE, 218  
MI\_LOCAL\_SET, 218  
MI\_MODE, 218  
MI\_RESERVED, 218  
MI\_SWING, 218  
MI\_VENTILATION, 218