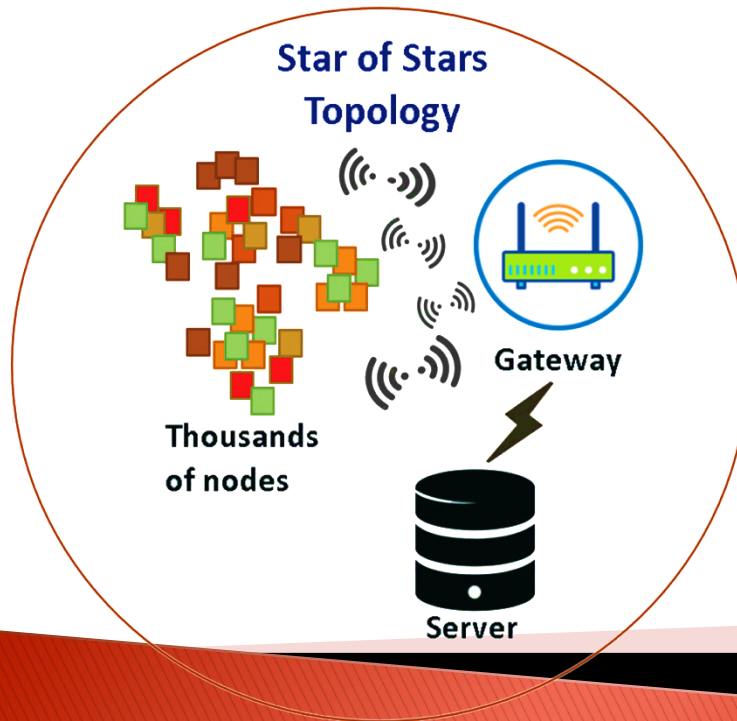
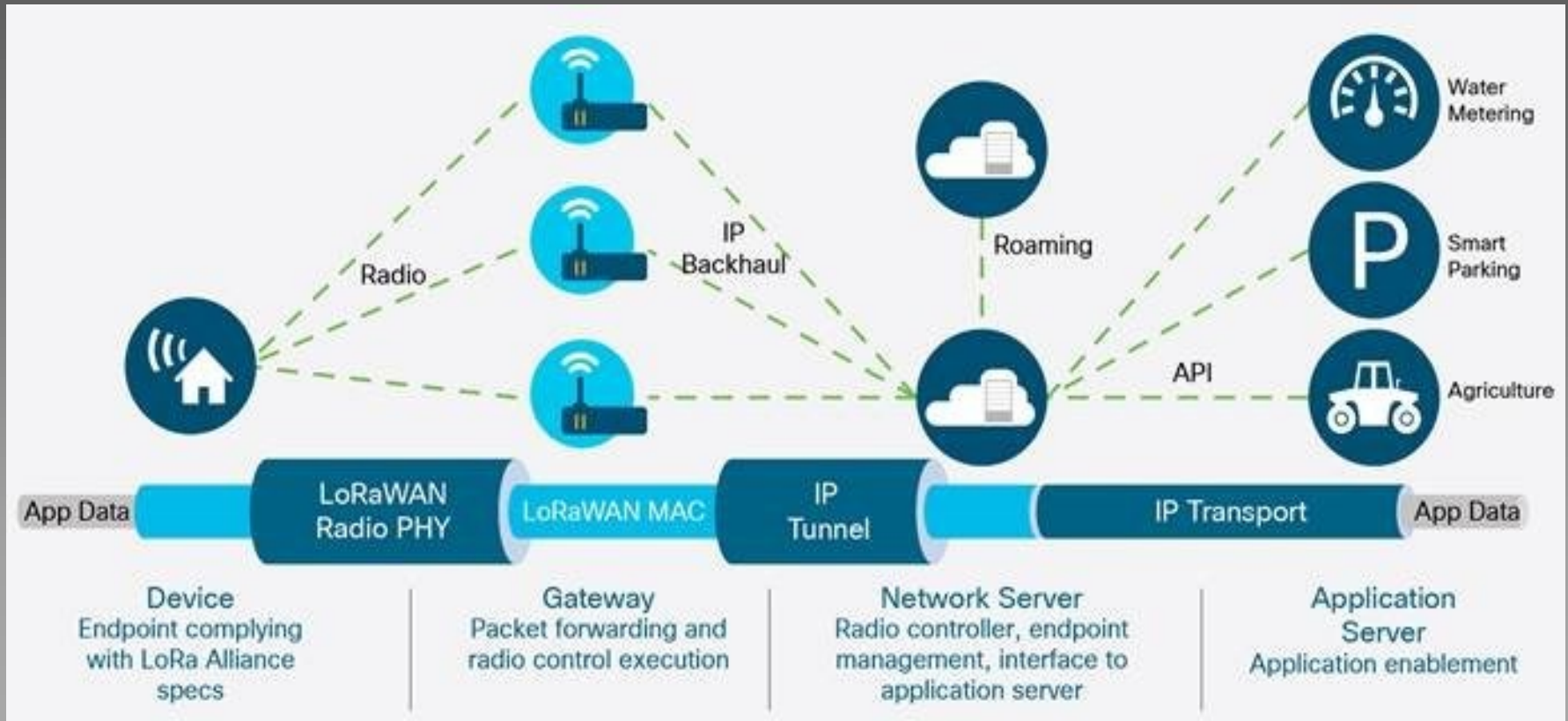


Building a Simple LoRaWAN Network



<https://github.com/LoRaWAN-workshop/tutorial>

LoRaWAN 1.0.3

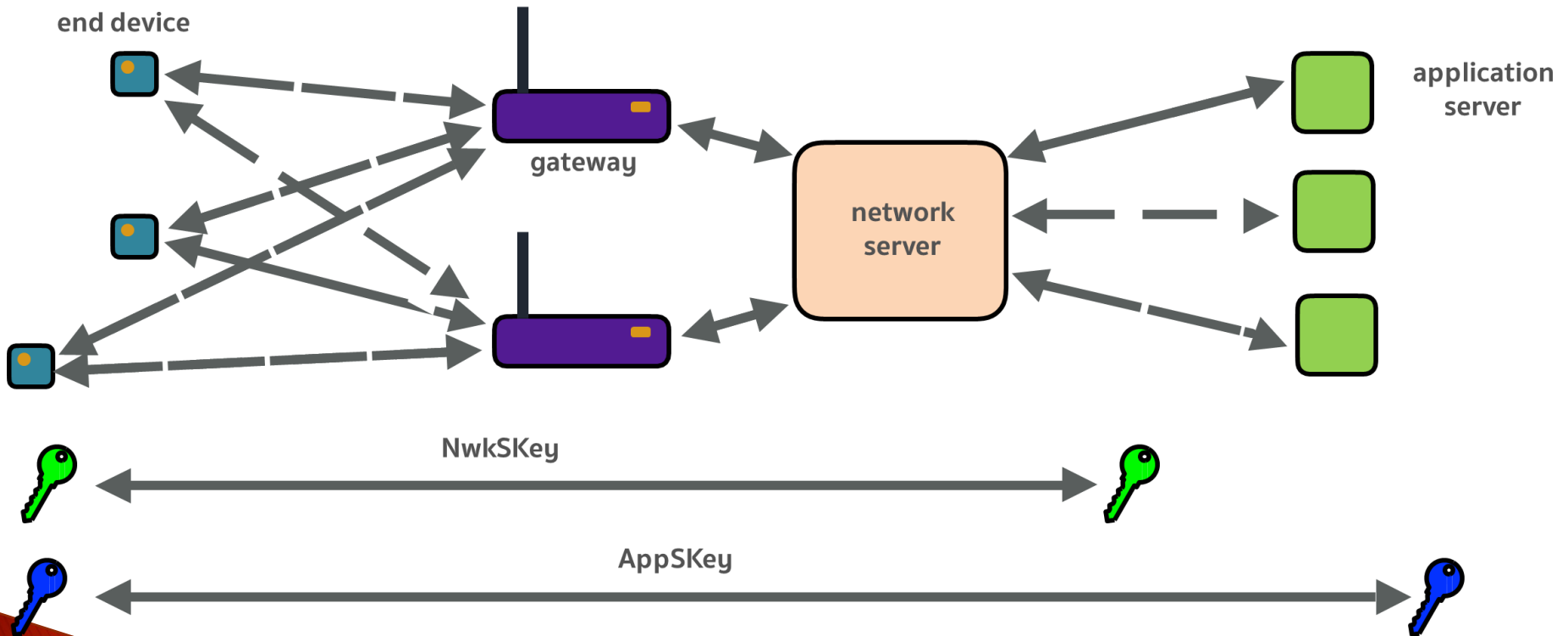
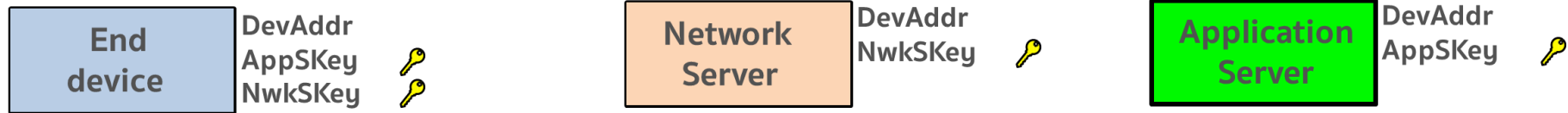


Network Encryption

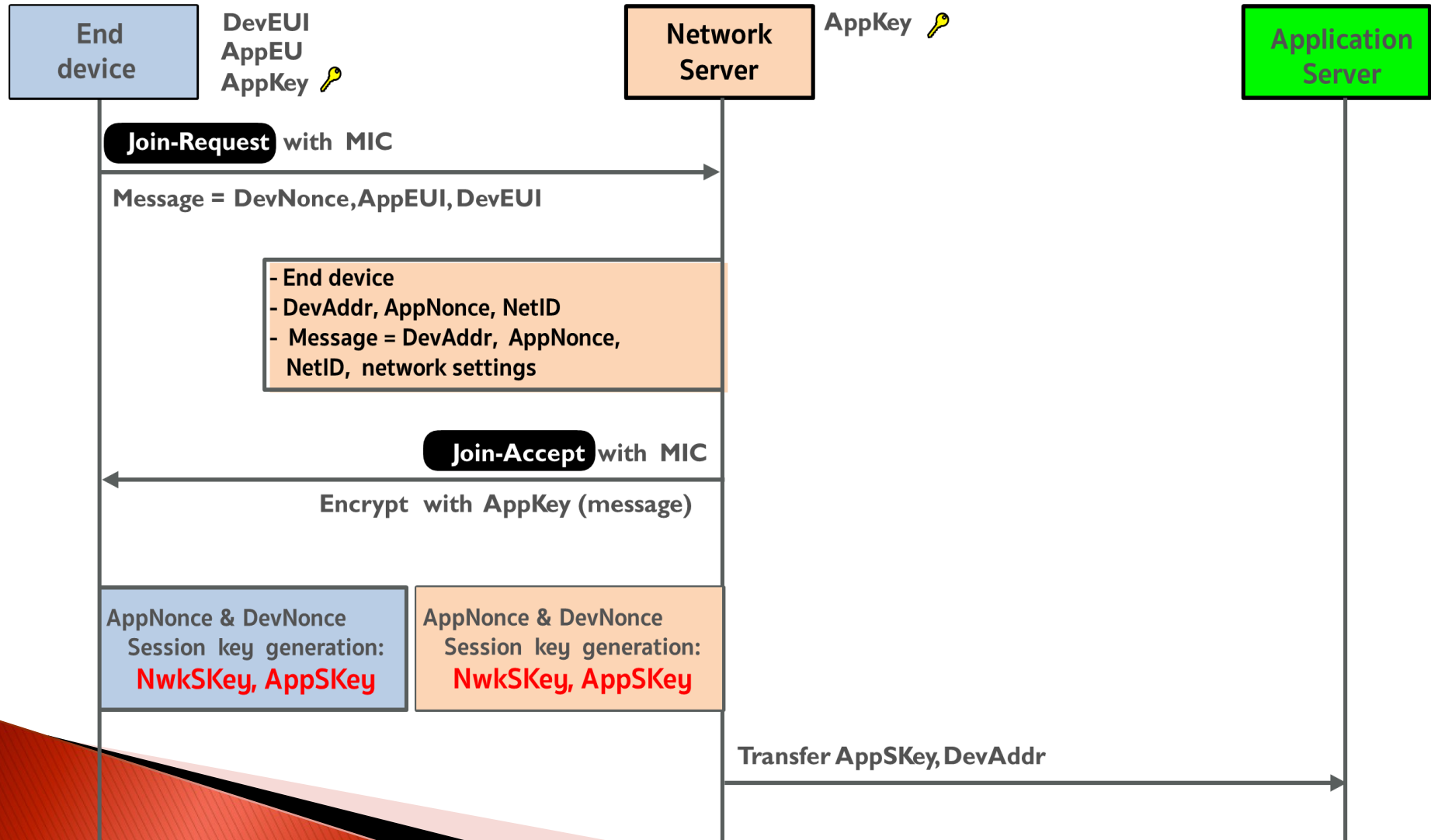
Application Encryption

Data

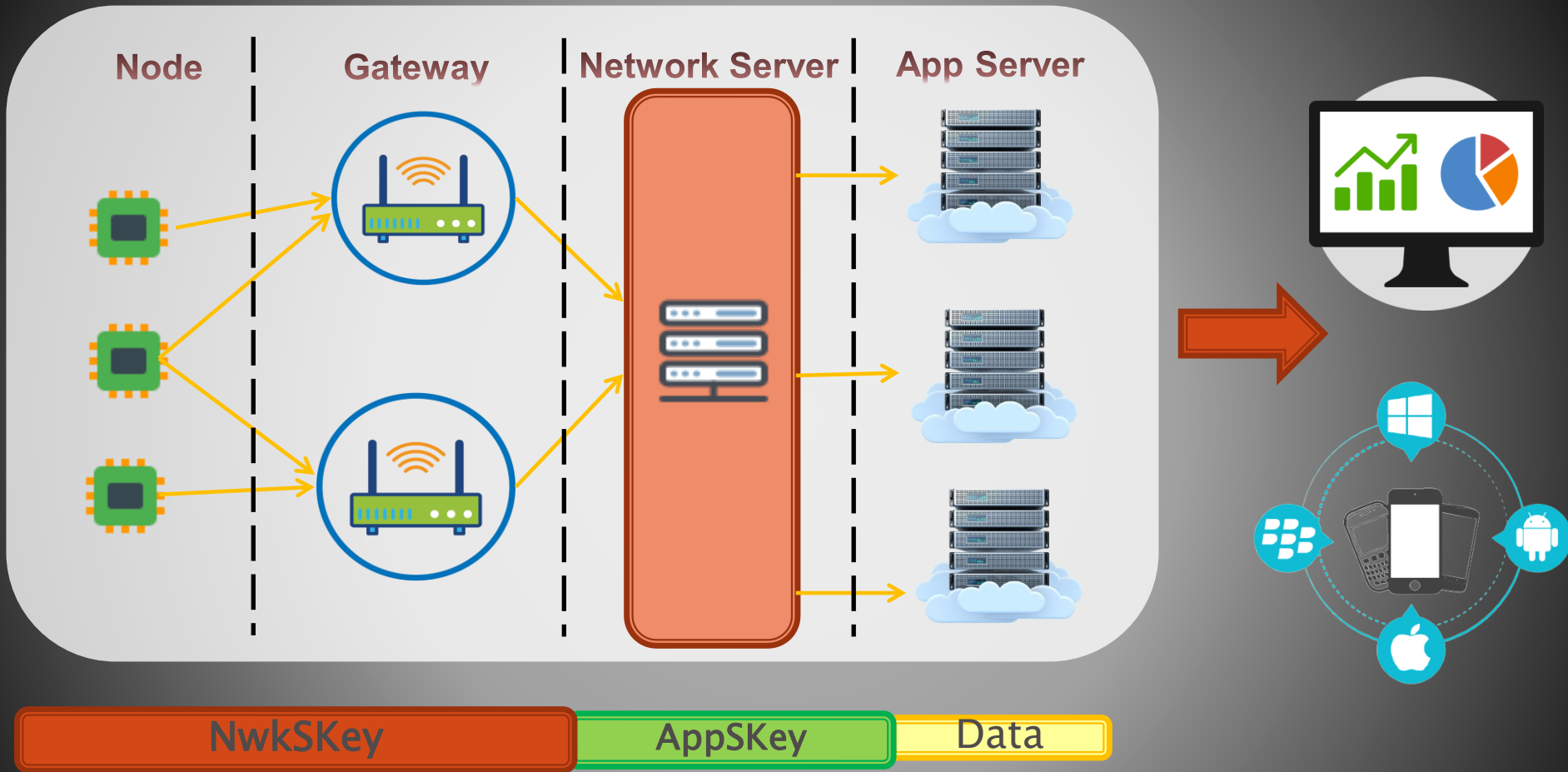
ABP (Activation-By-Personalization)



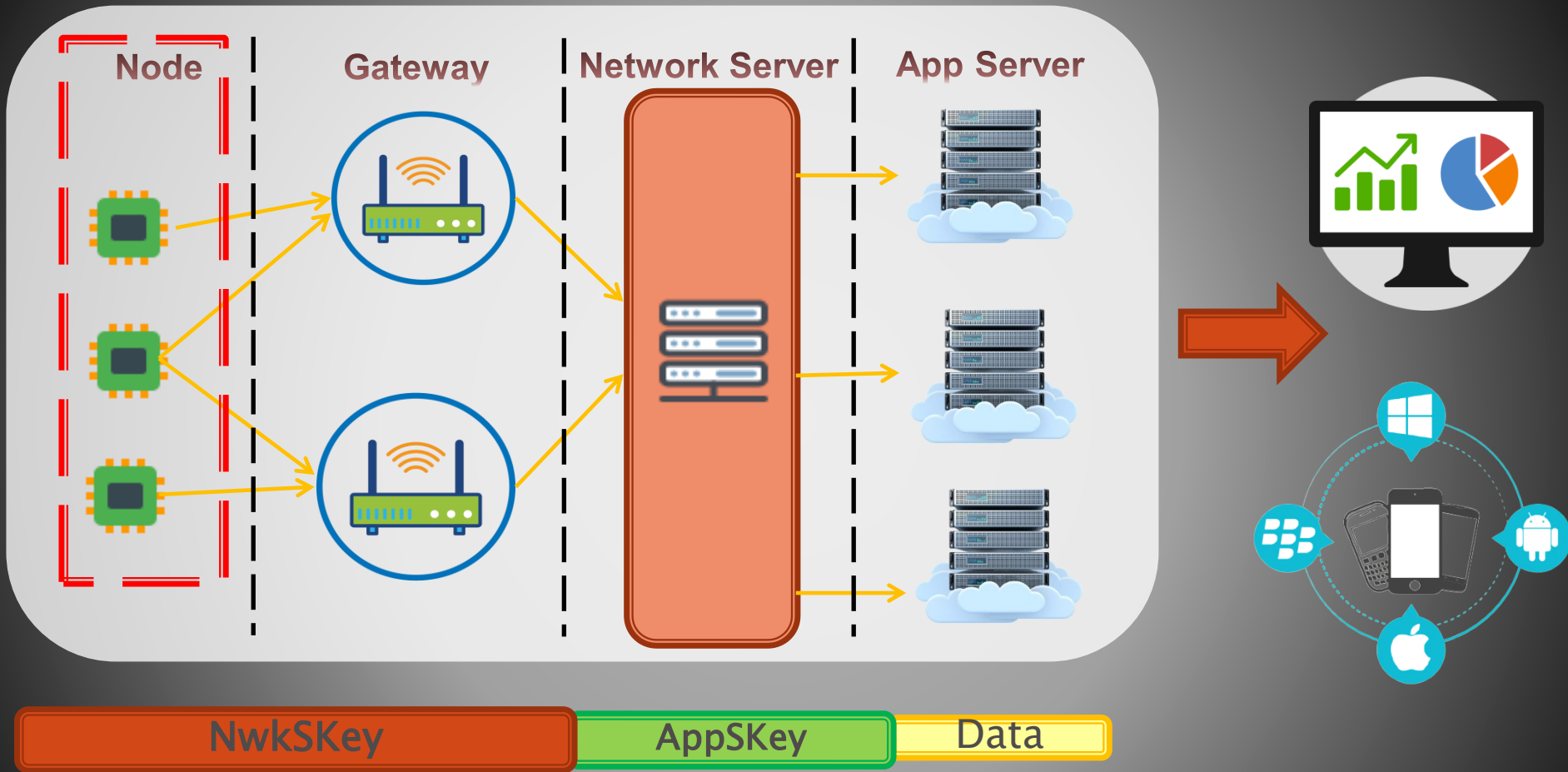
OTAA(Over-The-Air Activation)



LoRaWAN 1.0.3



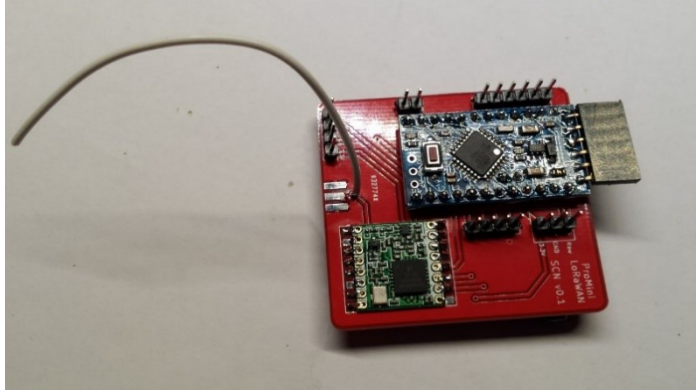
LoRaWAN 1.0.3



Examples of LoRaWAN Node



LoRa Shield + Arduino



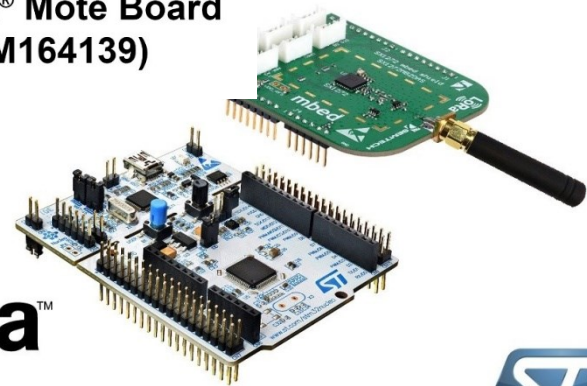
DIY LoRa Shield + Arduino



RN2903 LoRa® Mote Board
(Part # DM164139)

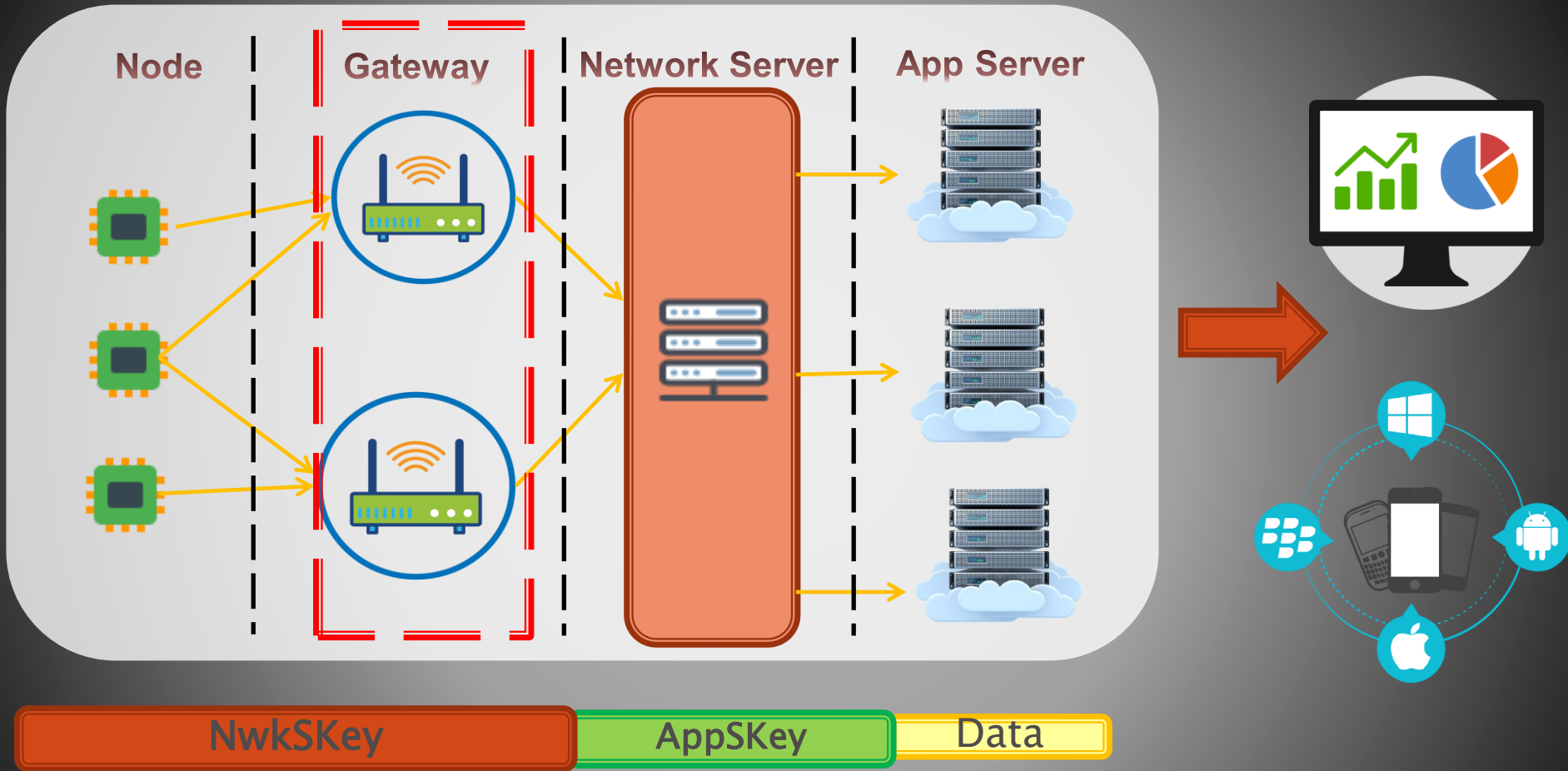


STM32 Nucleo-64 board+LoRa



LMIC : <https://github.com/matthijskooijman/arduino-lmic-v1.5>

LoRaWAN 1.0.3



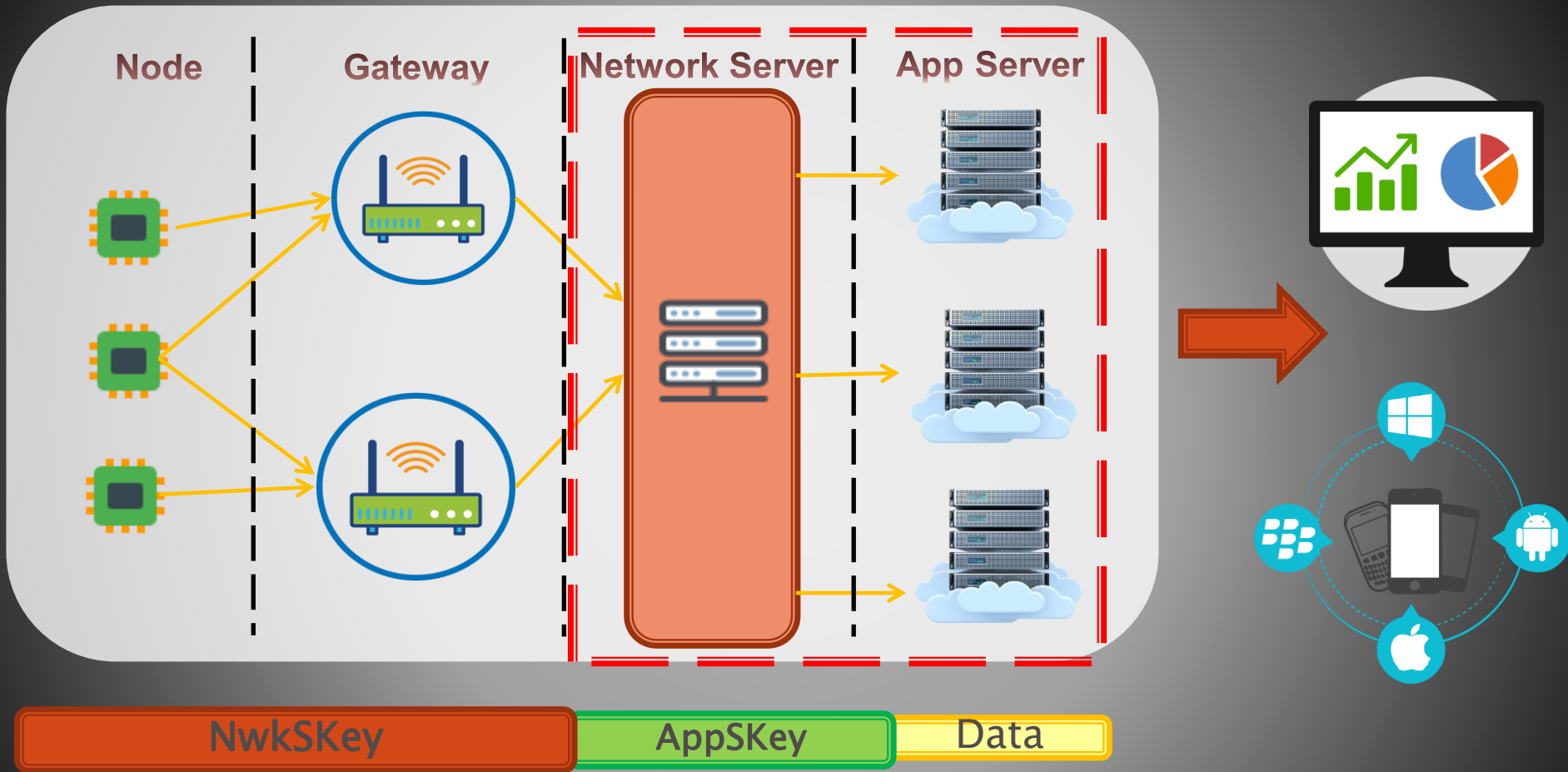
Examples of LoRaWAN Gateway

Gateway with Packet forwarder module



<https://github.com/ttn-zh/ic880a-gateway/wiki>

LoRaWAN 1.0.3



Examples of LoRaWAN Server

Private:



Public

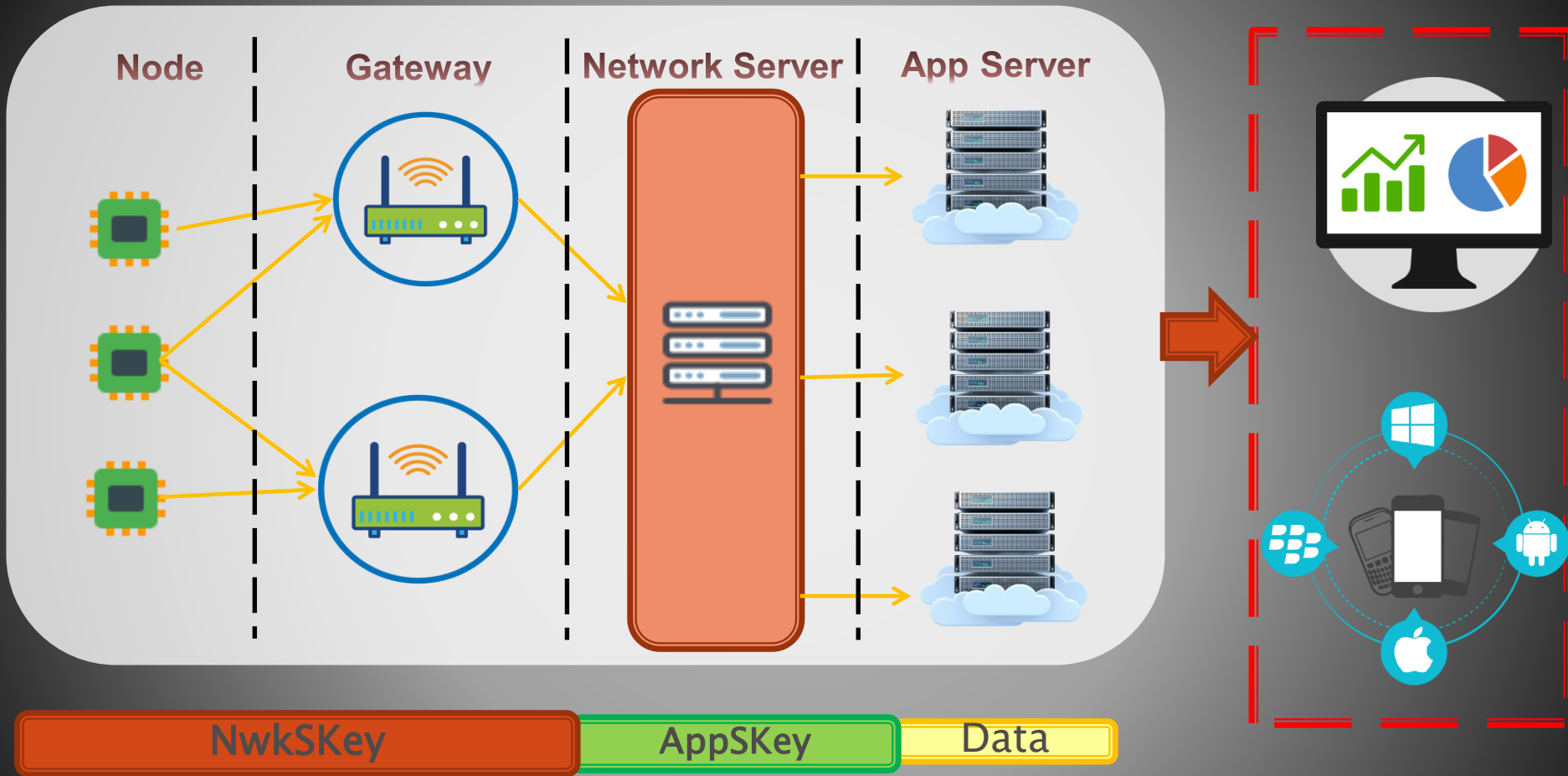


Activity

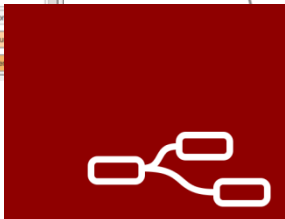
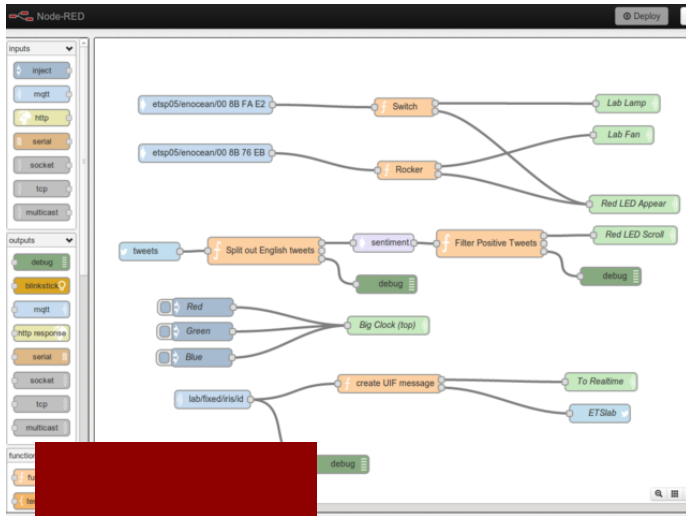


LORIO T

LoRaWAN 1.0.3



Example of Dashboards



Node-RED



Tago 

 **ubidots**


```
#define ASM_VMX_VMREAD_RDX_RAX 0, 0x0f, 0x7b, 0xd0

static __always_inline unsigned long vmcs_read(unsigned long field)
{
    unsigned long value;

    asm volatile (
        _lex_clear(ASM_VMX_VMREAD_RDX_RAX, "x0")
        : "=a"(value) : "d"(field) : "cc");

    return value;
}

#include <stdio.h>
int main(int argc, char **argv) {
    int src = 0;
    int dst;
    __asm__ volatile (
        "lscnt %1, %0\n"
        : "=y"(dst)
        : "y"(src)
        : "cc");
}
```

Procedures >>

Our LoRaWAN Server



Website:

<https://www.thethingsnetwork.org/>

Username: LoRaWAN-workshop

Password: 654321

Connect Gateway with



Website:

<https://www.thethingsnetwork.org/>

Username: LoRaWAN-workshop

Password: 654321

Gateway EUI (MAC Address):

7276FF004501022D

Develop Node

- ▶ Hardware
 - ❖ Arduino Uno with RFM95
- ▶ Software
 - ❖ LMIC Library
- ▶ Compiler
 - ❖ Arduino IDE

Develop Node

- ▶ Hardware

- ❖ Arduino Uno with RFM95

- ▶ Software

- ❖ LMIC Library

- <https://github.com/LoRaWAN-workshop/tutorial>

- ▶ Compiler

- ❖ Arduino IDE



Register Node with



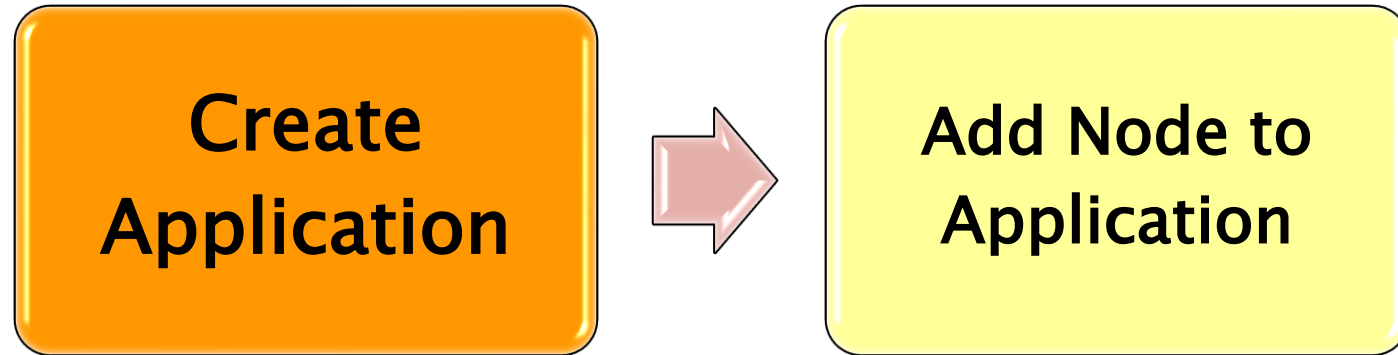
Website:

<https://www.thethingsnetwork.org/>

Username: LoRaWAN-workshop

Password: 654321

Register Node with



Let's Change some Parameters

- ▶ SF

`LMIC_setDrTxpow(DR_SFx, 14);`

❖ DR_SF7 – DR_SF12

- ▶ Unconfirmed/Confirmed

`LMIC_setTxData2(1, mydata, sizeof(mydata)-1, x);`

❖ Unconfirmed = 0, Confirmed = 1

AS923

Data Rate	Settings	Bit Rate (bit/s)	Max MAC Payload Length (byte)
0	SF12/BW125kHz	250	59
1	SF11/BW125 kHz	440	59
2	SF10/BW125 kHz	980	59
3	SF9/BW125 kHz	1760	123
4	SF8/BW125 kHz	3125	230
5	SF7/BW125 kHz	5470	250
6	SF7/BW250 kHz	11000	250

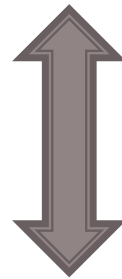
Duration

- ▶ Maximum period = $\text{Airtime} / \text{dutycycle}$

Integration with Dashboard



THE THINGS
NETWORK



Cayenne
myDevices



Cayenne is a **solution for building IoT applications** based on known platforms

- Arduino
- Raspberry pi
- ESP8266
- Serial devices
- Wifi
- **Lora devices**
- Mqtt client API

CayenneLPP

<http://mydevices.com/cayenne/docs/lora/#lora-cayenne-low-power-payload>



Requirement:

1. Node with CayenneLPP Class

<https://www.thethingsnetwork.org/docs/devices/arduino/api/cayennelpp.html>

2. Integrate Application on TTN with Cayenne (Integration Page)

3. Sign up and Create Dashboard at Cayenne

LoRa -> The Things Network -> Cayenne LPP



Cayenne

myDevices

```
uint8_t addDigitalInput(uint8_t channel, uint8_t value);
uint8_t addDigitalOutput(uint8_t channel, uint8_t value);

uint8_t addAnalogInput(uint8_t channel, float value);
uint8_t addAnalogOutput(uint8_t channel, float value);

uint8_t addLuminosity(uint8_t channel, uint16_t lux);
uint8_t addPresence(uint8_t channel, uint8_t value);
uint8_t addTemperature(uint8_t channel, float celsius);
uint8_t addRelativeHumidity(uint8_t channel, float rh);
uint8_t addAccelerometer(uint8_t channel, float x, float y, float z);
uint8_t addBarometricPressure(uint8_t channel, float hpa);
uint8_t addGyrometer(uint8_t channel, float x, float y, float z);
uint8_t addGPS(uint8_t channel, float latitude, float longitude, float meters);
```




Device with 2 temperature sensors

Payload (Hex)	03 67 01 10 05 67 00 FF	
Data Channel	Type	Value
03 ⇒ 3	67 ⇒ Temperature	0110 = 272 ⇒ 27.2°C
05 ⇒ 5	67 ⇒ Temperature	00FF = 255 ⇒ 25.5°C

Type	IPSO	LPP	Hex	Data Size	Data Resolution per bit
Digital Input	3200	0	0	1	1
Digital Output	3201	1	1	1	1
Analog Input	3202	2	2	2	0.01 Signed
Analog Output	3203	3	3	2	0.01 Signed
Illuminance Sensor	3301	101	65	2	1 Lux Unsigned MSB
Presence Sensor	3302	102	66	1	1
Temperature Sensor	3303	103	67	2	0.1 °C Signed MSB
Humidity Sensor	3304	104	68	1	0.5 % Unsigned
Accelerometer	3313	113	71	6	0.001 G Signed MSB per axis
Barometer	3315	115	73	2	0.1 hPa Unsigned MSB
Gyrometer	3334	134	86	6	0.01 °/s Signed MSB per axis
GPS Location	3336	136	88	9	Latitude : 0.0001 ° Signed MSB
					Longitude : 0.0001 ° Signed MSB
					Altitude : 0.01 meter Signed MSB

Q&A

Workshop Evaluation



<https://qrgo.page.link/UFwtj>

THANK YOU

