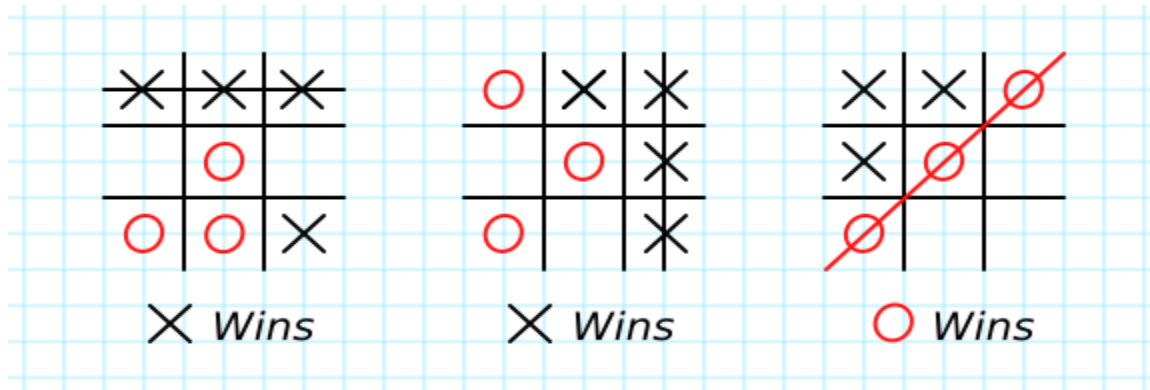


# Tic-tac-toe

Goal-based reflex agent)



Team:-

1-Loay Mohamed Fawzy

2-Mohamed Ashraf Al Emam

## Agent(PEAS)

P: reach win situation

E: available positions

A: board squares

S: numpad

## Environment(ODESA)

O : Fully observable

D : Strategic

E : Sequential

S : Static

A : Multi agent