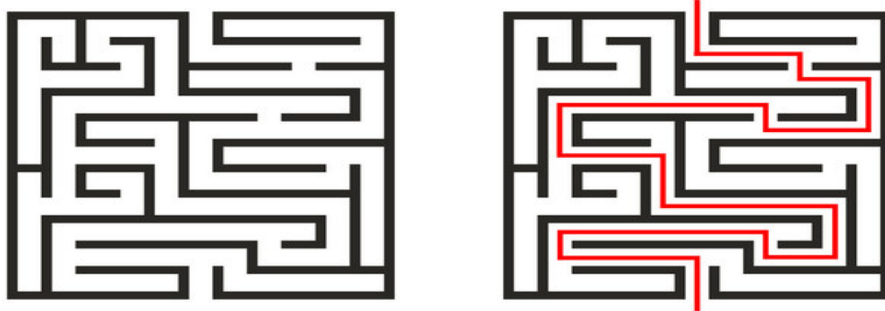


# Maze (Goal-based reflex agent)



Team:-

1-Loay Mohamed Fawzy

2-Mohamed Ashraf Al Emam

## Agent(PEAS)

P: Speed to reach the goal

E: roads

A: all directions (keyboard)

S: line sensor

## Environment(ODESA)

O : Fully observable

D : Deterministic

E : Sequential

S : Static

A : Single agent