# Mastering Embedded System Online Diploma

**High-Pressure-Detector** 

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#### 1-Case Study:

- A pressure controller informs the crew of a cabin with an alarm when the pressure exceeds 20 bars in the cabin.
- The alarm duration equals 60 seconds.

#### **Assumptions:**

- The controller set up and shutdown procedures are not modeled.
- The controller maintenance is not modeled.
- The pressure sensor never fails.
- The alarm never fails.
- The controller never faces power cut.

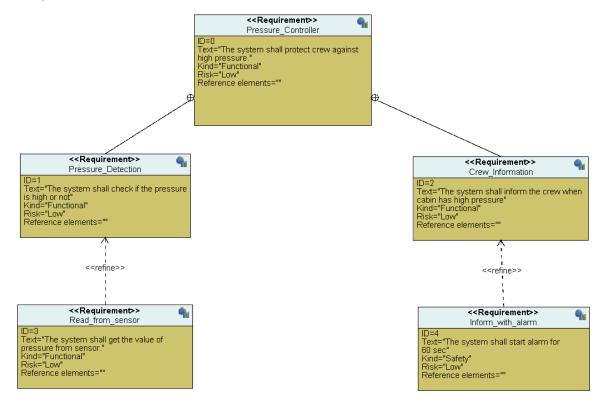
#### 2-Method:

• The system was designed using the Waterfall model.

#### The Waterfall Model

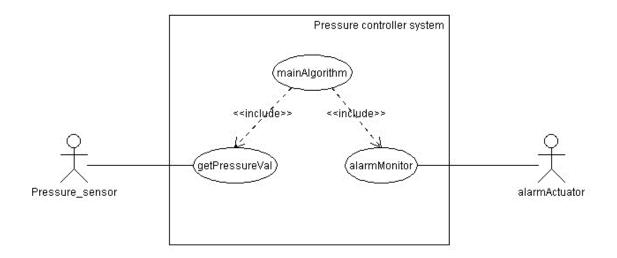


## 3-Requirements:

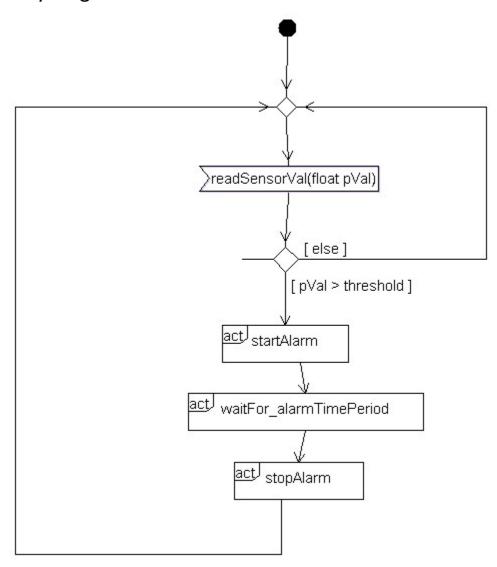


# 4-System Analysis:

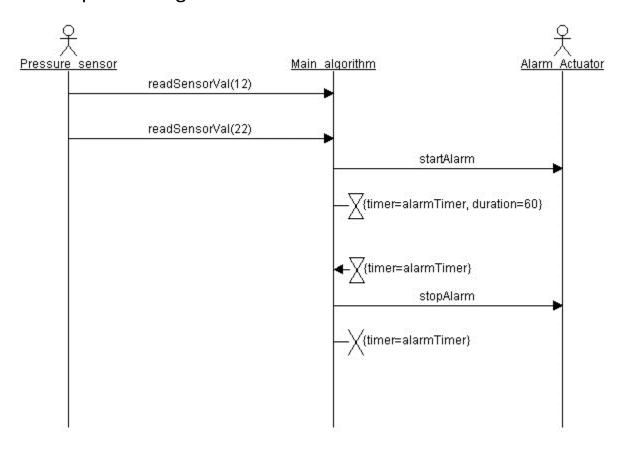
• Use case diagram:



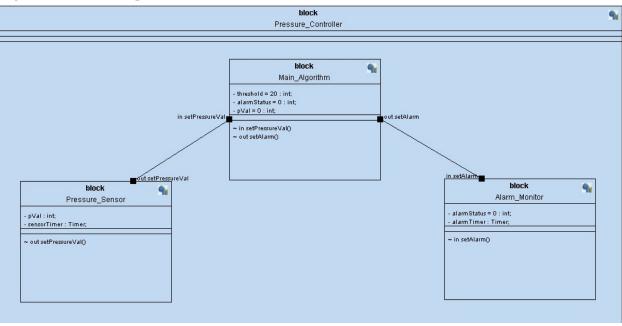
## • Activity diagram:



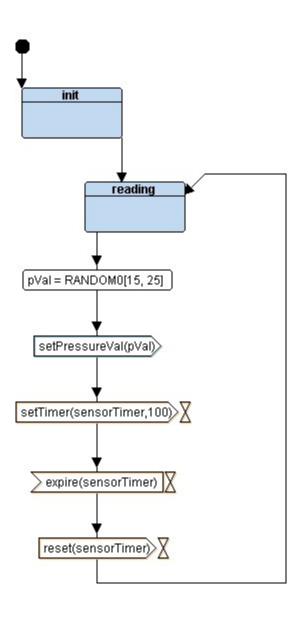
## • Sequence diagram:



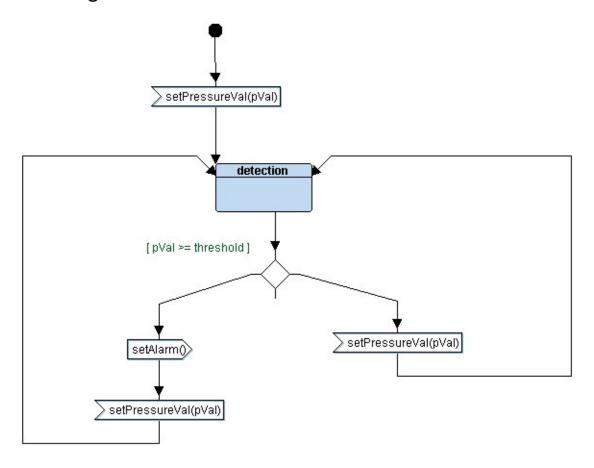
# 5- System Design:



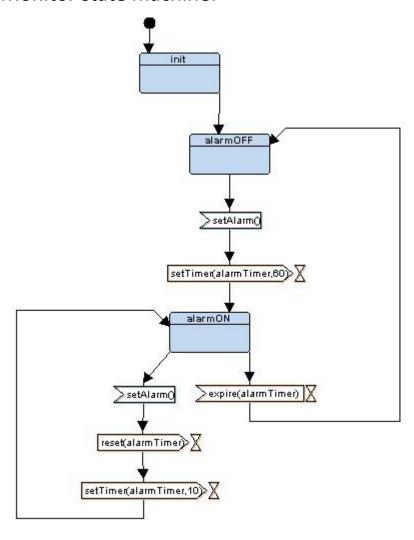
• Pressure sensor state machine:



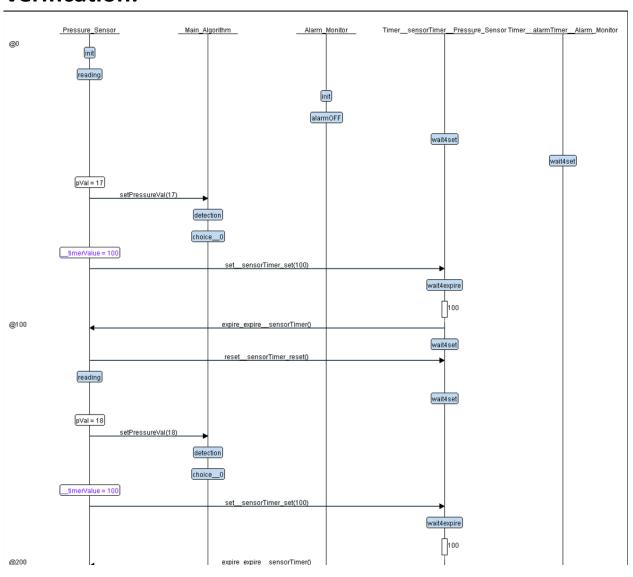
• Main Algorithm state machine:

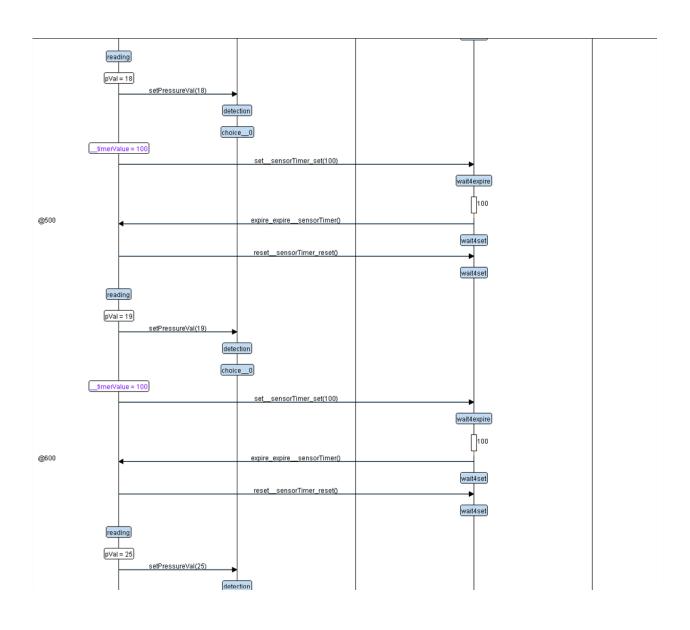


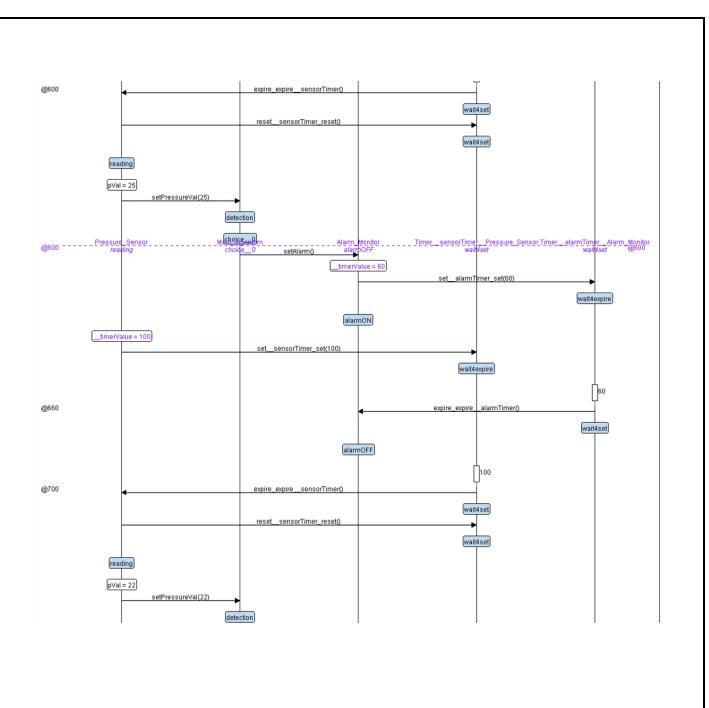
• Alarm Monitor state machine:



# **Verification:**

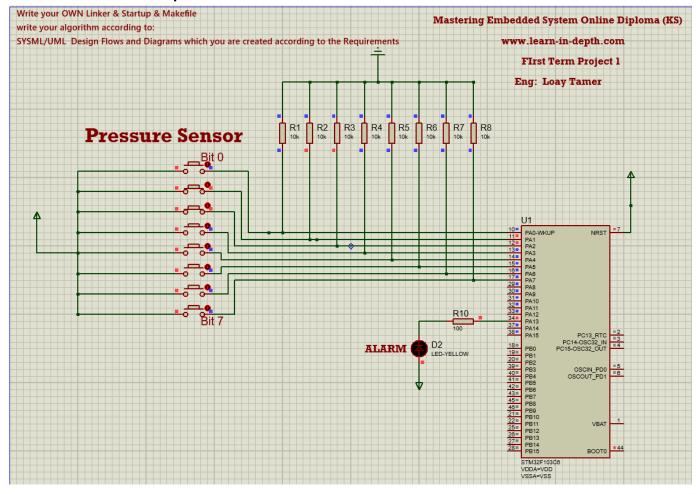




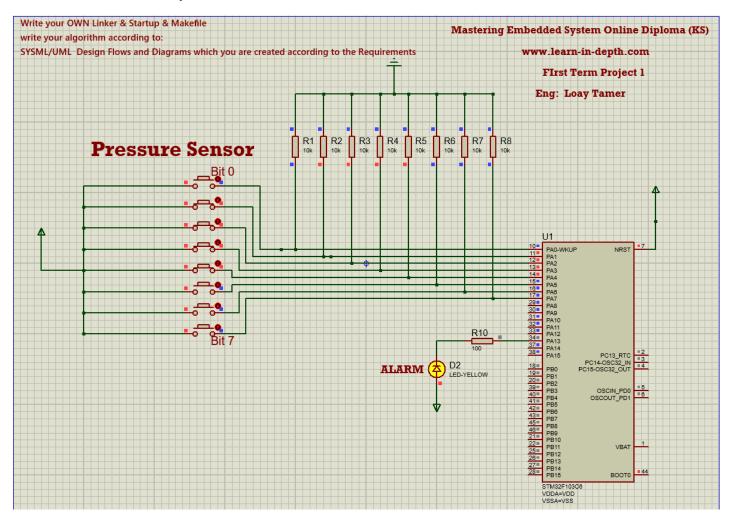


#### **Proteus simulation:**

• Case 1: pressure value = 6 < threshold



## • Case 2: pressure value = 30 < threshold



## **Symbols:**

```
$ make symbols
arm-none-eabi-nm.exe *.o
alarm_monitor.o:
000000a0 T alarm_monitor_init
00000004 c alarm_monitor_state
00000001 c alarm_monitor_state_id
00000000 B alarm_state
00000080 T setAlarm
0000002c T ST_alarm_OFF
00000000 T ST_alarm_ON
driver.o:
00000000 T Delay
00000024 T getPressureVal
0000008c T GPIO_INITIALIZATION
0000003c T Set_Alarm_actuator
main.o:
        U alarm_monitor_state
00000001 c alarm_monitor_state_id
        U Delav
        U getPressureVal
        U GPIO_INITIALIZATION
00000040 T main
        U pController_state
00000001 c pressure_controller_state_id
        U pSensor_state
00000001 c pSensor_state_id
        U Set Alarm actuator
        U setPressureVal
00000000 T setup
        U ST_alarm_OFF
        U ST_pressure_detection
        U ST_pSensor_reading
pressure_controller.o:
00000000 B pc_pval
00000004 C pController_state
00000001 c pressure_controller_state_id
        U return_pval
        U setAlarm
00000000 T ST_pressure_detection
00000000 D threshold
```

```
pressure_sensor.o:
00000080 T pressure_sensor_init
00000004 C pSensor_state
00000001 c pSensor_state_id
00000000 в pval
00000068 T return_pVal
00000004 B sensor_timer
00000048 T setPressureVal
00000000 т sт_psensor_reading
startup.o:
         U _E_bss
         U _E_data
         U _E_text
         U _S_bss
         U _S_data
         U _stack_top
000000b0 W Bus_Fault
000000b0 T Default_Handler
000000b0 w H_fault_Handler
         U main
000000b0 w mm_fault_Handler
000000b0 w NMI_Handler
00000000 T Reset_Handler
000000b0 W Usage_Fault_Handler
00000000 D vectors
```