

ODE :- $y: [a, b] \rightarrow \mathbb{R}$ is smooth.

$F(x, y, y', y'') = 0$ is an ode. (2nd Order).

$$F: [a, b] \times \mathbb{R} \times \mathbb{R} \times \mathbb{R} \rightarrow \mathbb{R}$$

$$\textcircled{i} \quad F(x, y, y', y'') = y''$$

$$\textcircled{ii} \quad F(x, y, y', y'') = xy^2 + y' + y''$$

PDE :- $u: \Omega \subset \mathbb{R}^2 \rightarrow \mathbb{R}$ is smooth.

$Du(x, y) = \nabla u(x, y)$ = Total Derivative of u at (x, y) .

$$= (u_x(x, y), u_y(x, y))$$

Assumption :- u is smooth $\Rightarrow u, u_x, u_y, u_{xx}, u_{yy}, u_{xy}$ are defined and are continuous.

$F(x, y, u, u_x, u_y, u_{xx}, u_{yy}, u_{xy}) = 0$ (F is smooth), (2nd Order PDE in two variables provided F is not independent of the last 3 variable (either)).

$$\text{Ex: } \textcircled{i} \quad F(\dots) = u_{xx} + u_{yy} \quad \Delta u = 0$$

$$\textcircled{ii} \quad F(\dots) = u_x + u_y$$

Given a PDE $F(x_1, u, u_x, u_y, u_{xx}, u_{xy}, u_{yy}) = 0 \quad \text{--- } ①$

Defn :- $u \in C^2(\Omega)$ is said to be a soln of ① if u satisfies ① for all $(x_1, y) \in \Omega$

Ex :- $\underline{u_{xx} = 0 \text{ in } \Omega}$ $\underline{u(x, y) \in C^2(\Omega)}$

$$\underline{u(x_1, y) = 0}$$

$$\underline{u_{xx}(x_1, y) = 0}$$

Well Posedness of PDE :- We call a PDE ① is well posed if

- ① \exists at least one soln. (Existence of soln)
- ② The soln has to be unique (Uniqueness of soln)
- ③ For small change in data the solution change is also small (Perturbation)

Classification of PDE :- (2nd Order ; 2 variable)

Linear PDE :- $a u_{xx} + b u_{xy} + c u_{yy} + d u_x + e u_y + f u + g = 0 \text{ in } \Omega$

Here, a, b, c, \dots, g are smooth fns in Ω

Ex 1 :- $u_{xx} + u_{yy} = 0$ Ex 2 :- $x u_{xx} + u_{yy} = 0$

$$L[u] = a u_{xx} + b u_{xy} + c u_{yy} + d u_x + e u_y + f u.$$

$$\underline{L[\tilde{c}u_1 + u_2]} = \tilde{c} L[u_1] + L[u_2]; \quad \tilde{c} \text{ is a constant}$$

Should hold for linearity of L .

Let us assume, $\exists u_1, u_2, \dots, u_n \in C^2(\Omega)$ solving

$$u = \sum_{n=1}^{\infty} \tilde{c}_n u_n$$

Hence, $u \in C^2(\Omega)$ and

$$L[u] = \sum_{n=1}^{\infty} \tilde{c}_n L[u_n] \quad \left[L[u_n] = 0 \quad \forall n \right]$$

Hence, u solves $\boxed{(III)}$ (Principle of Superposition).

Let us come back to $\boxed{(I)}$ $Lu = g$ — $\boxed{(II)}$

Let us assume $\exists v$ solving $\boxed{(II)}$

$$\begin{aligned} L[u] &= 0 \\ \Rightarrow L[u+v] &= L[u] + L[v] = 0 + g = g \end{aligned}$$

$$\checkmark \quad \boxed{(III)} \quad L[u_n] = 0 \quad \forall n \in \mathbb{N}$$

$$\begin{array}{l} \cancel{L[u] + g = 0} \xrightarrow{\textcircled{II}} \\ \boxed{g = 0} \end{array}$$

Semilinear :-

$$a u_{xx} + b u_{xy} + c u_{yy} + \underbrace{F(u_x, u_y, u, x, y)}_{} = 0$$

where a, b, c and F are smooth.
 $a, b, c \dots$ funs of (x, y)

Ex :- ① $u_{xx} + u_{yy} + u_x^2 + u_y^2 = 0$

② $u_{xx} + \sin u = 0$

③ $u_{xx} + u_y = 0$

$$a(x, y, u, u_x, u_y) u_{xx} + b(x, y, u, u_x, u_y) u_{xy} + c(x, y, u, u_x, u_y) u_{yy} + F(u_x, u_y, u, x, y) = 0.$$

Quasilinear :- $a(x, y, u, u_x, u_y) u_{xx} + b(x, y, u, u_x, u_y) u_{xy} + c(x, y, u, u_x, u_y) u_{yy} + F(u_x, u_y, u, x, y) = 0.$

Ex 1 :- ① $u^2 u_{xx} + u_{yy} = 0$

② $u_x u_{xx} + e^u = 0$

③ $u_{xx}^2 + 2 = 0 \times$ not a quasilinear

Nonlinear :- $F(u_{xx}, u_{xy}, u_x, u_y, u, x, y) = 0$.

① $\det(D^2 u) = 0$

$$u: \mathbb{R}^2 \rightarrow \mathbb{R}$$

$$D^2 u = \begin{pmatrix} u_{xx} & u_{xy} \\ u_{yx} & u_{yy} \end{pmatrix}$$

$u_{xx} + u_y = 0 \rightarrow$ Burger's Eqn