

Sheet: /MCU/
File: MCU.kicad_sch

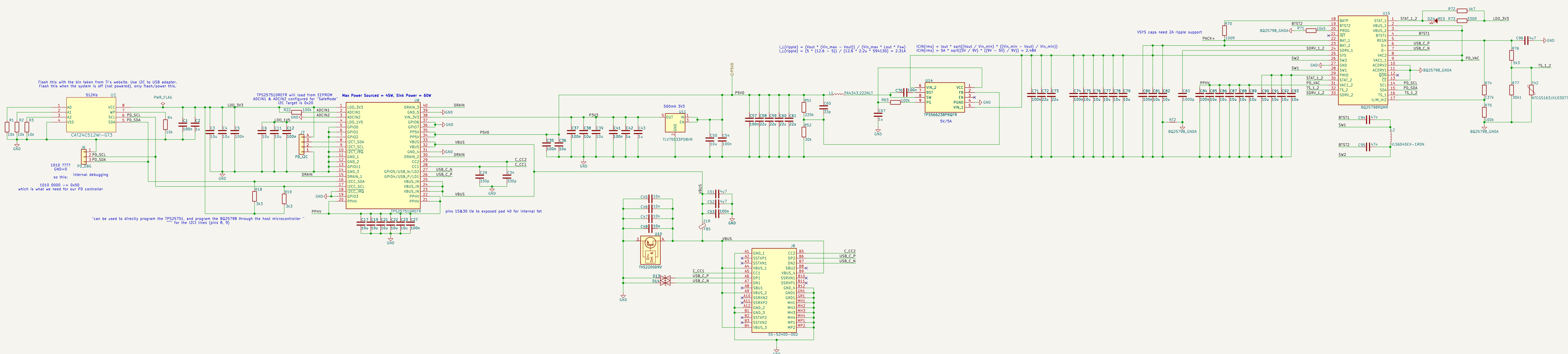
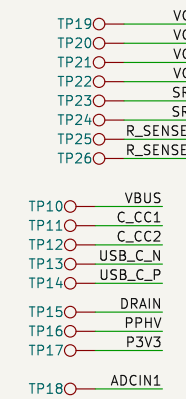
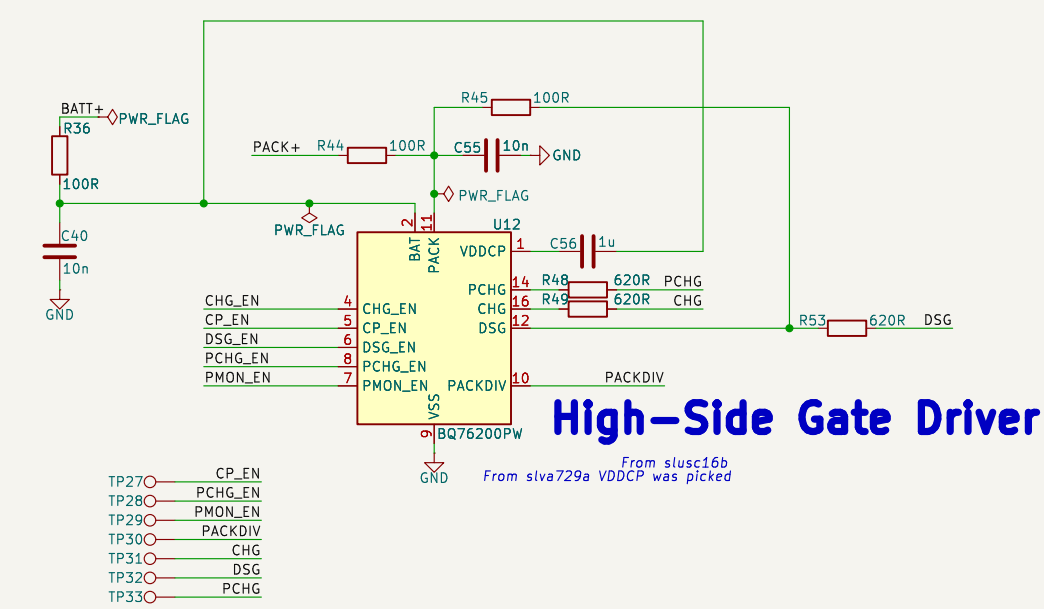
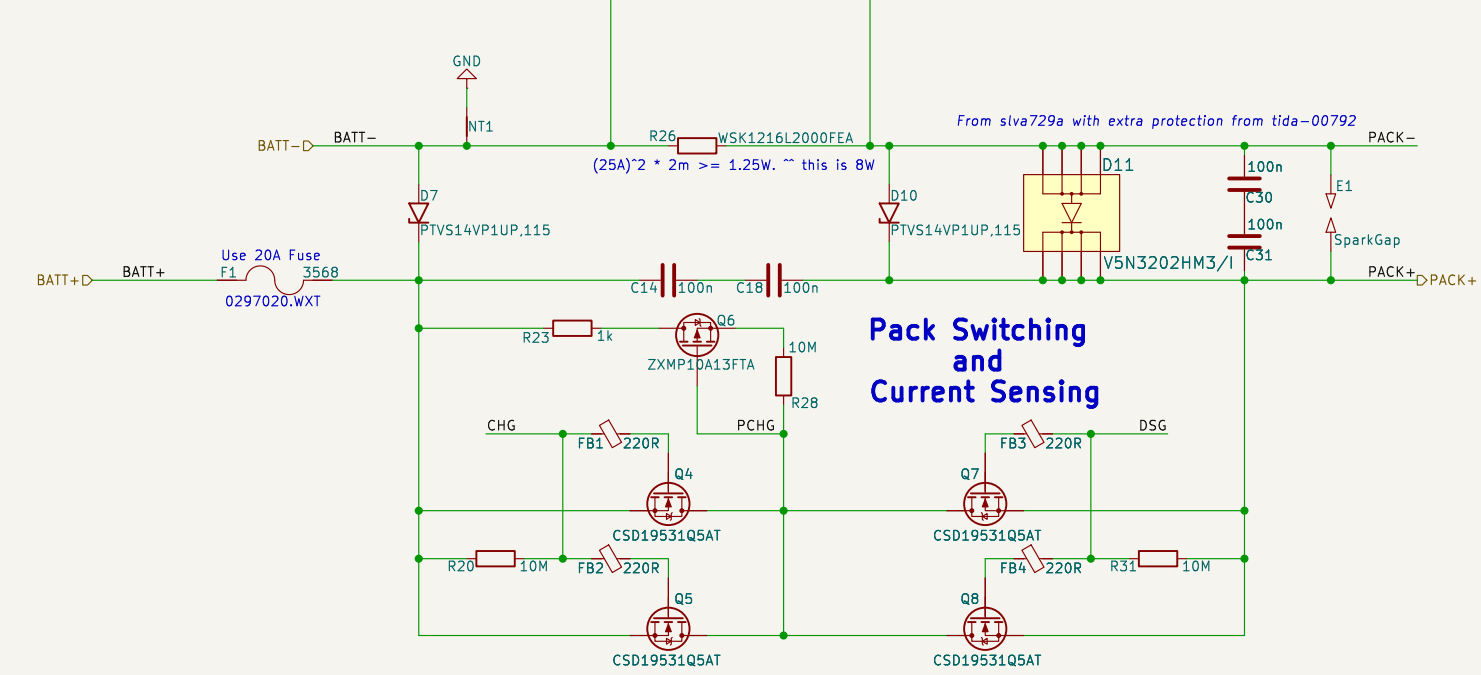
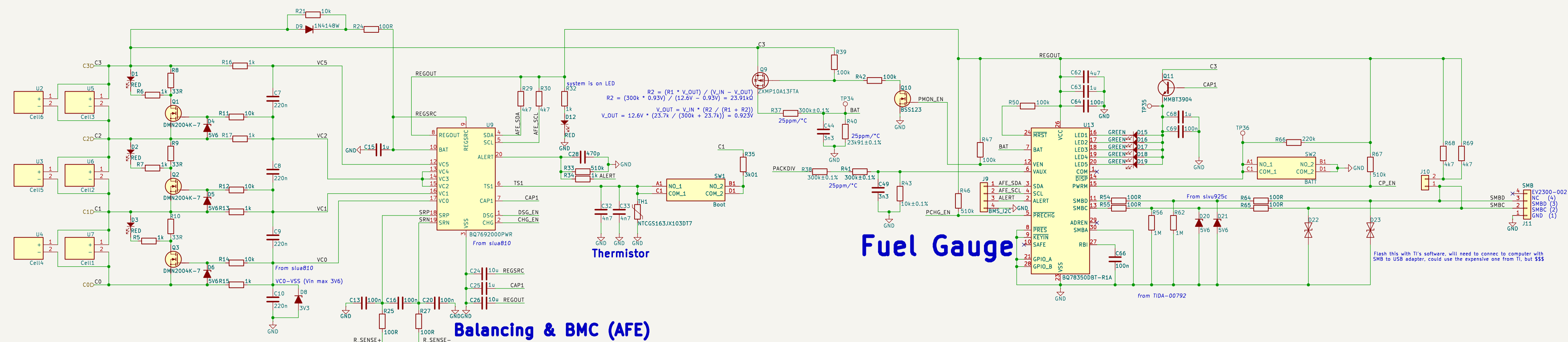
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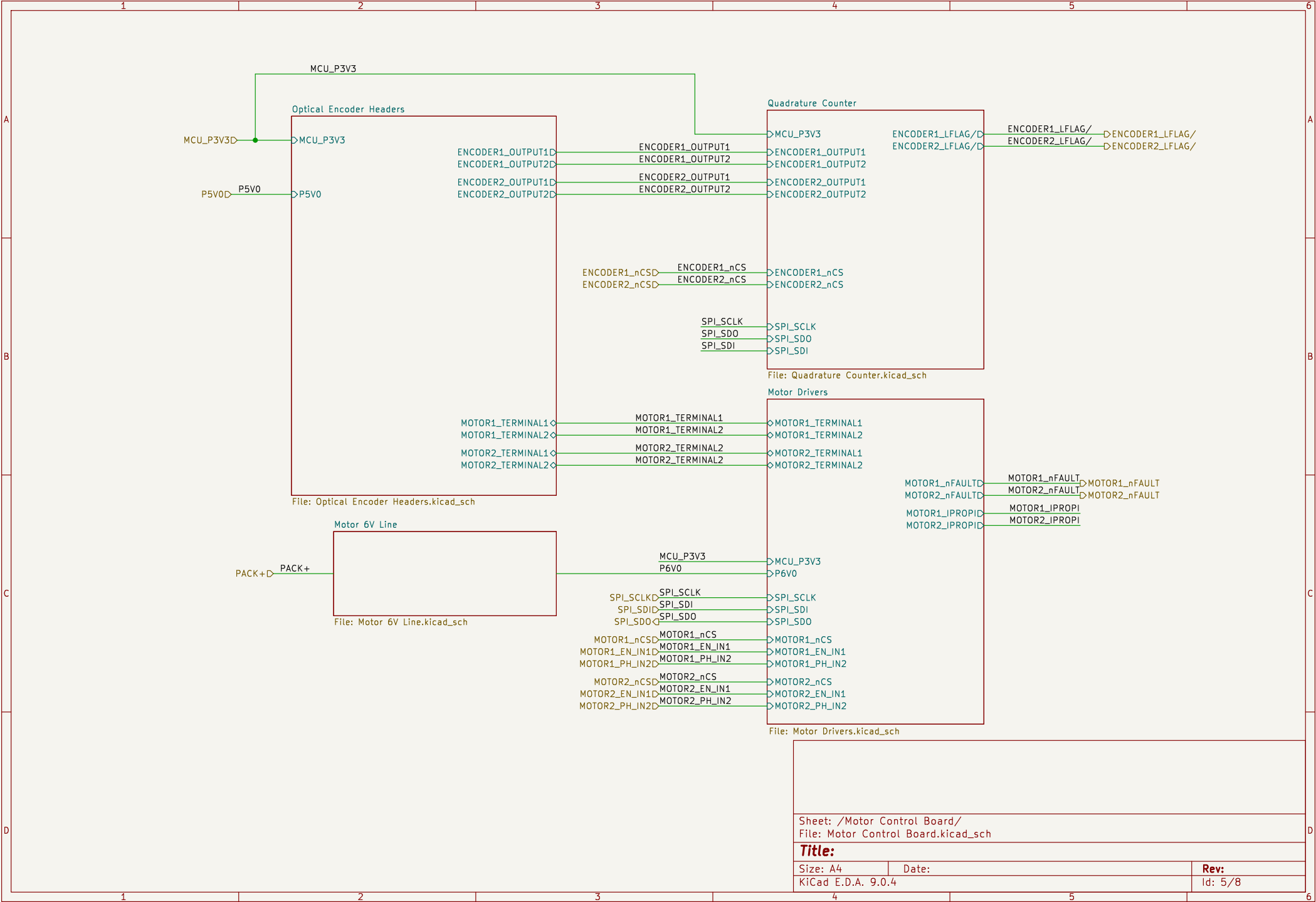
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KiCad E.D.A. 9.0.4

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BMS Protection Board for 3S Battery Pack
In/Out: min voltage: 9.6 V, nominal voltage: 11.1 V, max voltage: 12.6 V
Output: 20A continuous discharge current
Min Each Cell set to 3.2 V, Max Each Cell set to 4.2 V





Sheet: /Motor Control Board/
File: Motor Control Board.kicad_sch

Title:

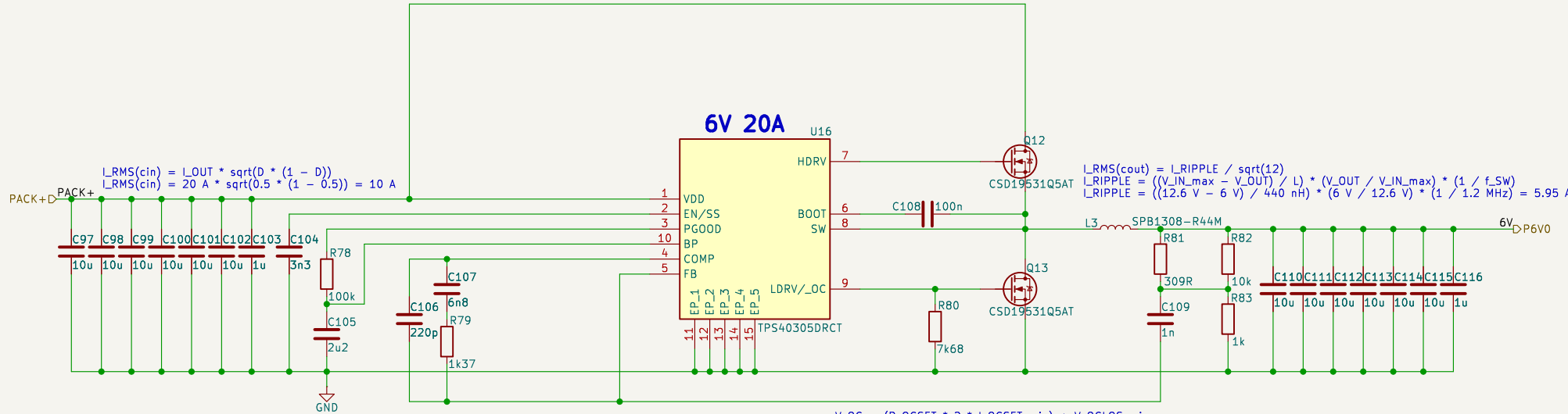
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$$V_{OC} = (R_{OCSET} \cdot 2 \cdot I_{OCSET_min}) + V_{OCLOS_min}$$

$$V_{OC} = (7.68 \text{ k}\Omega \cdot 2 \cdot 9.5 \text{ }\mu\text{A}) + (-8 \text{ mV})$$

$$V_{OC} = 137.9 \text{ mV}$$

$$I_{valley} = V_{OC} / R_{DS(on)}$$

$$I_{valley} = 137.9 \text{ mV} / 7.8 \text{ m}\Omega$$

$$I_{valley} = 17.68 \text{ A}$$

$$I_{SCP} = I_{valley} + (I_{RIPPLE} / 2)$$

$$I_{SCP} = 17.68 \text{ A} + (5.95 \text{ A} / 2)$$

$$I_{SCP} = 20.66 \text{ A}$$

Sheet: /Motor Control Board/Motor 6V Line/
File: Motor 6V Line.kicad_sch

Title:

Size: A4

Date:

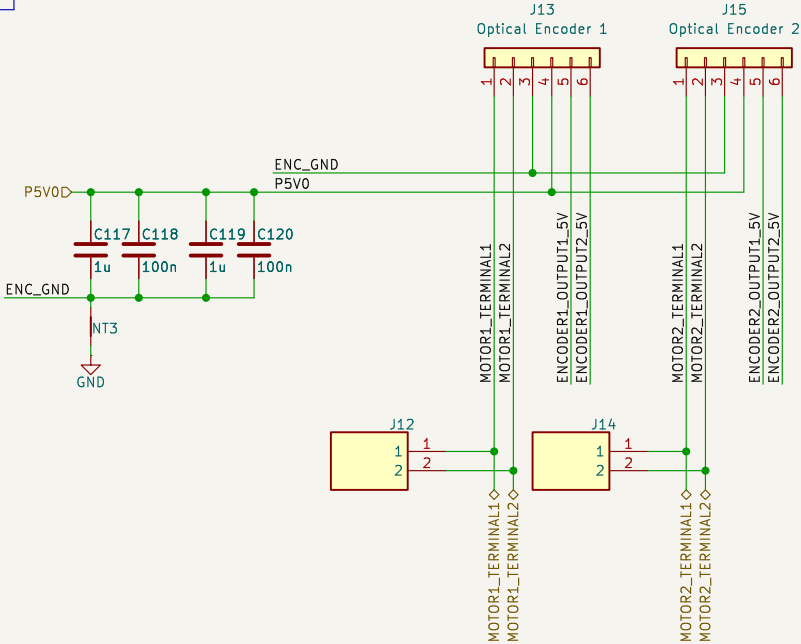
KiCad E.D.A. 9.0.4

Rev:

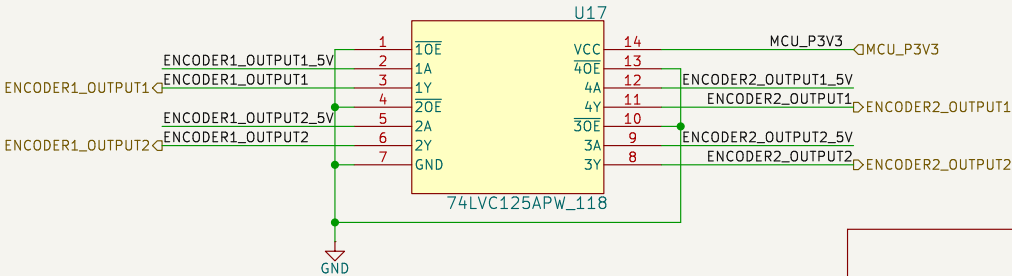
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(1) Red	motor power (connects to one motor terminal)
(2) Black	motor power (connects to the other motor terminal)
(3) Green	encoder GND
(4) Blue	encoder Vcc (3.5 – 20 V)
(5) Yellow	encoder A output
(6) White	encoder B output

- TP37○ ENC_GND
- TP38○ MOTOR1_TERMINAL1
- TP39○ MOTOR1_TERMINAL2
- TP40○ ENCODER1_OUTPUT1_5V
- TP41○ ENCODER1_OUTPUT2_5V
- TP42○ MOTOR2_TERMINAL1
- TP43○ MOTOR2_TERMINAL2
- TP44○ ENCODER2_OUTPUT1_5V
- TP45○ ENCODER2_OUTPUT2_5V
- TP46○ ENCODER1_OUTPUT1
- TP47○ ENCODER1_OUTPUT2
- TP48○ ENCODER2_OUTPUT1
- TP49○ ENCODER2_OUTPUT2



Input has to be 5V, output has to be 3V3



Sheet: /Motor Control Board/Optical Encoder Headers/
File: Optical Encoder Headers.kicad_sch

Title:

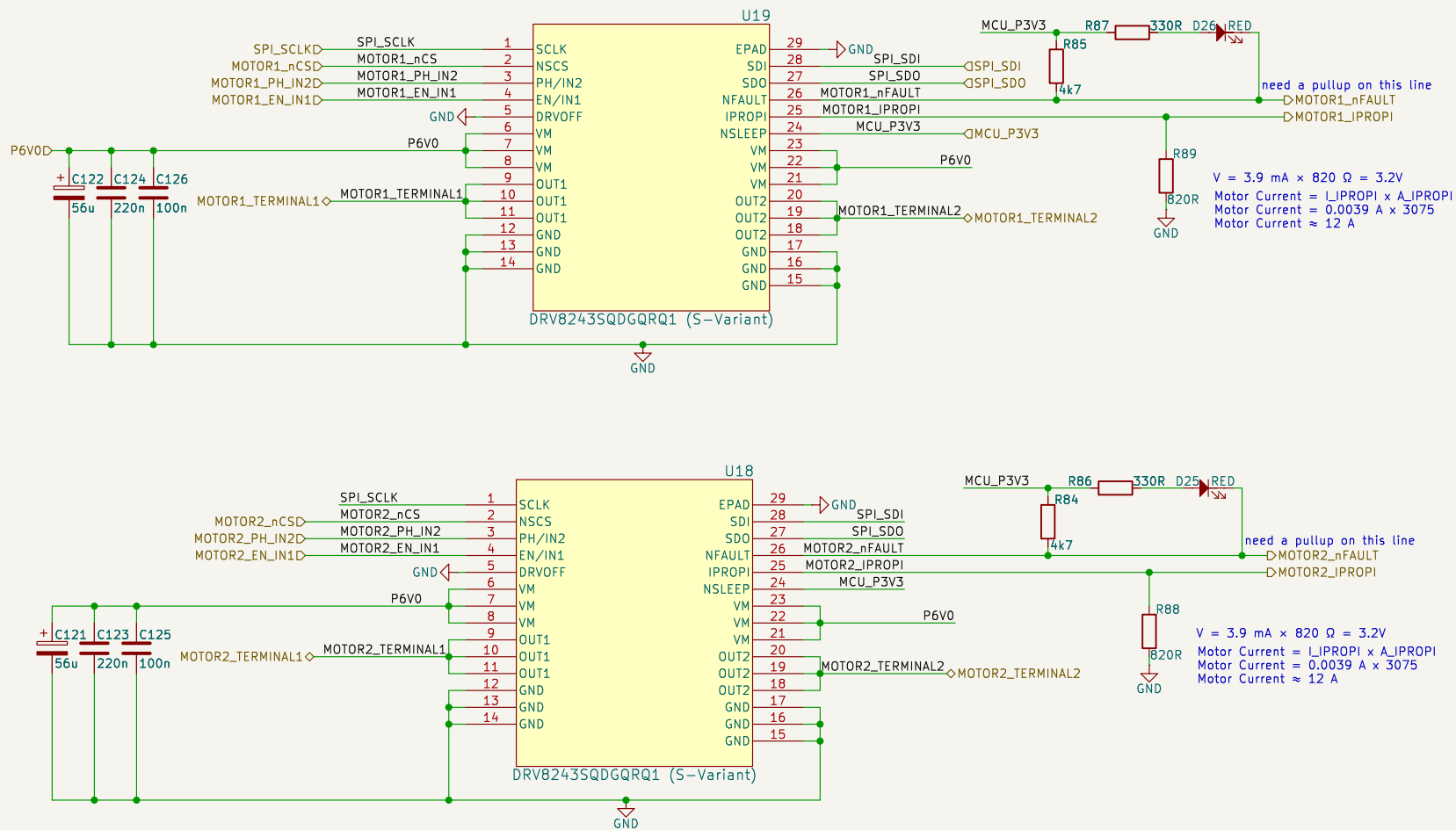
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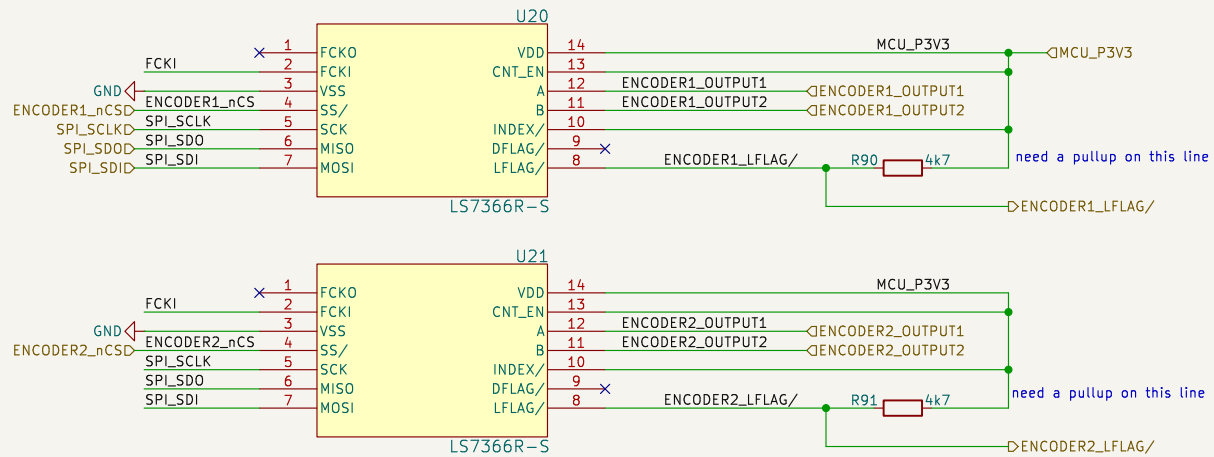
Sheet: /Motor Control Board/Motor Drivers/
 File: Motor Drivers.kicad_sch

Title:

Size: A4
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 Id: 8/8



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