

MapCoder: Multi-Agent Code Generation for Competitive Problem Solving

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Abstract

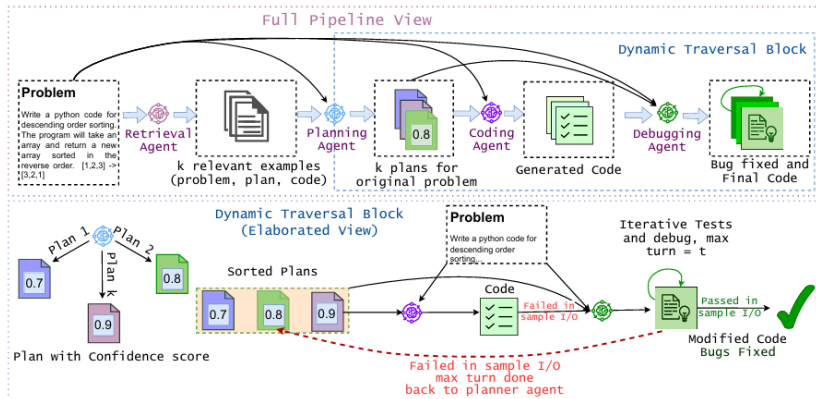
- LLMs have limited ability for coding
 - Code generation is harder than just NLP
- New framework MapCoder, which has 4 stages
 - Retrieval, Planning, Coding, Debugging
 - It is open source

Previous works

- Chain-of-Thought
 - Pseudo code-based generation
 - Fail to pass test cases, No bug fixing
- Retrieval-based approach
 - Leverage relevant problems and solutions
 - Fail to pass test cases, No bug fixing
- Self-reflection
 - Iteratively evaluates generated code against test case
 - Only leverage the problem description itself in a zero-shot manner

Multi Agent Prompting Code

- Retrieval agent
 - Generates relevant examples itself
- Dynamic Traversal Block
 - Plans and considers the confidence of the generated plans
 - Code generation and debugging



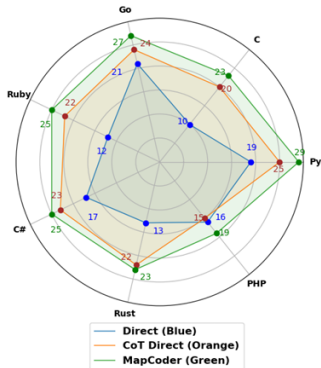
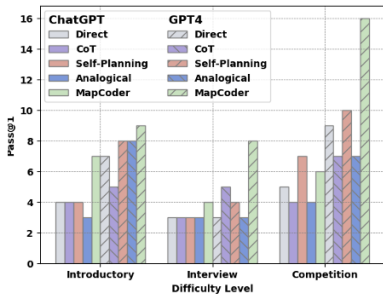
Experiment

- 5 basic-level benchmark + 3 contest-level benchmark
- GPT-3.5-Turbo and GPT-4 as foundation models
- Various prompting baselines including MapCoder

LLM	Approach	Simple Problems					Contest-Level Problems		
		HumanEval	HumanEval ET	EvalPlus	MBPP	MBPP ET	APPS	xCodeEval	CodeContest
ChatGPT	Direct	48.1%	37.2%	66.5%	49.8%	37.7%	8.0%	17.9%	5.5%
	CoT	68.9%	55.5%	65.2%	54.5%	39.6%	7.3%	23.6%	6.1%
	Self-Planning	60.3%	46.2%	-	55.7%	41.9%	9.3%	18.9%	6.1%
	Analogical	63.4%	50.6%	59.1%	70.5%	46.1%	6.7%	15.1%	7.3%
	Reflexion	67.1%	49.4%	62.2%	73.0%	47.4%	-	-	-
	Self-collaboration	74.4%	56.1%	-	68.2%	49.5%	-	-	-
	MapCoder	80.5% ↑ 67.3%	70.1% ↑ 88.5%	71.3% ↑ 7.3%	78.3% ↑ 57.3%	54.4% ↑ 44.3%	11.3% ↑ 41.3%	27.4% ↑ 52.6%	12.7% ↑ 132.8%
GPT4	Direct	80.1%	73.8%	81.7%	81.1%	54.7%	12.7%	32.1%	12.1%
	CoT	89.0%	61.6%	-	82.4%	56.2%	11.3%	36.8%	5.5%
	Self-Planning	85.4%	62.2%	-	75.8%	50.4%	14.7%	34.0%	10.9%
	Analogical	66.5%	48.8%	62.2%	58.4%	40.3%	12.0%	26.4%	10.9%
	Reflexion	91.0%	78.7%	81.7%	78.3%	51.9%	-	-	-
	MapCoder	93.9% ↑ 17.2%	82.9% ↑ 12.4%	83.5% ↑ 2.2%	83.1% ↑ 2.5%	57.7% ↑ 5.5%	22.0% ↑ 73.7%	45.3% ↑ 41.2%	28.5% ↑ 135.1%

Experiment Results

- Performance gain on varying difficulty levels
- Performance gain on different programming languages



Ablation study

- Removed each agent
 - Showed that every agent has its role in the pipeline
 - Debugging Agent has the most significant impact

Retrieval Agent	Planning Agent	Debugging Agent	Pass@1	Performance Drop
✗	✗	✓	68.0%	15.0%
✗	✓	✓	76.0%	5.0%
✗	✓	✗	52.0%	35.0%
✓	✗	✓	70.0%	12.5%
✓	✓	✗	66.0%	17.5%
✓	✗	✗	62.0%	22.5%
✓	✓	✓	80.0%	-

Conclusion

- MapCoder outperformed many SOTA approaches
 - Performance gain on varying difficulty levels
 - Performance gain on different programming languages
- Limitation
 - It generates a large number of tokens
 - Challenging in resource-constrained environment