Write SDN Controller
计算机网络 CS339

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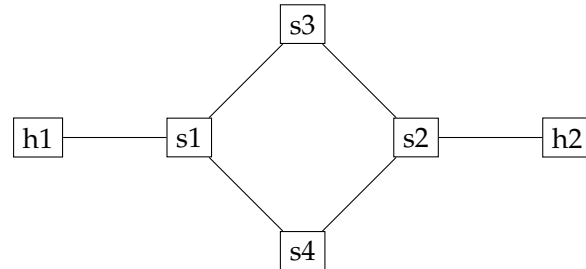
目录

Ryu provides software components with well defined API's that make it easy for developers to create new network management and control applications.

1 建立网络

Set up the following network first:

使用给出的示例代码。

Listing 1: `loopnet.py`

```python
#!/usr/bin/python
"""Sample Code"""
from mininet.topo import Topo
from mininet.net import Mininet
from mininet.node import OVSBridge, OVSSwitch, OVSKernelSwitch
from mininet.node import CPULimitedHost
from mininet.node import RemoteController
from mininet.link import TCLink
from mininet.util import dumpNodeConnections
from mininet.log import setLogLevel, info
from mininet.cli import CLI
from sys import argv
def Test():
    "Create network and run simple performance test"
    net = Mininet( switch=OVSSwitch,host=CPULimitedHost, link=TCLink,
    autoStaticArp=False, controller=RemoteController)
    switch1 = net.addSwitch('s1')
    switch2 = net.addSwitch('s2')
    switch3 = net.addSwitch('s3')
    switch4 = net.addSwitch('s4')
    host1 = net.addHost('h1', cpu=.25)
    host2 = net.addHost('h2', cpu=.25)
    net.addLink(host1, switch1, bw=10, delay='5ms', loss=0, use_htb=True)
    net.addLink(host2, switch2, bw=10, delay='5ms', loss=0, use_htb=True)
    net.addLink(switch1, switch3, bw=10, delay='5ms', loss=0, use_htb=True)
    net.addLink(switch1, switch4, bw=10, delay='5ms', loss=0, use_htb=True)
    net.addLink(switch2, switch3, bw=10, delay='5ms', loss=0, use_htb=True)
    net.addLink(switch2, switch4, bw=10, delay='5ms', loss=0, use_htb=True)
    c1 = net.addController('c1', controller=RemoteController, ip="127.0.0.1",
     port=6653)
    net.build()
    c1.start()
    s1, s2, s3, s4 = net.getNodeByName('s1', 's2', 's3', 's4')
    s1.start([c1])
    s2.start([c1])
    s3.start([c1])
    s4.start([c1])
```

```
36      net.start()
37      info( "Dumping host connections\n" )
38      dumpNodeConnections(net.hosts)
39      h1, h2 = net.getNodeByName('h1', 'h2')
40      CLI(net)
41      net.stop()
42  if __name__ == '__main__':
43      # setLogLevel( 'debug' )
44      setLogLevel('info')
45      Test()
```

2 定时切换

Write an RYU controller that switches paths (h1-s1-s3-s2-h2 or h1-s1-s4-s2-h2) between h1 and h2 every 5 seconds.

查看修改流的定义函数。其中参数 `hard_timeout` 用于定义丢弃流前的最大秒数。

Listing 2: `../ryu/ryu/ofproto/ofproto_v1_3_parser.py`

```
2703    def __init__(self, datapath, cookie=0, cookie_mask=0, table_id=0,
2704                  command=ofproto.OFPFC_ADD,
2705                  idle_timeout=0, hard_timeout=0,
2706                  priority=ofproto.OFP_DEFAULT_PRIORITY,
2707                  buffer_id=ofproto.OFP_NO_BUFFER,
2708                  out_port=0, out_group=0, flags=0,
2709                  match=None,
2710                  instructions=None):
```

参数 `flags` 可以被指定为 `OFPFF_SEND_FLOW_REM`，可以用于在丢弃流后发出事件用于相关处理。

> **Flow-Removed**: Inform the controller about the removal of a flow entry from a flow table. Flow-Removed messages are only sent for flow entries with the
>
> OFPFF_SEND_FLOW_REM
>
> flag set. They are generated as the result of a controller flow delete requests or the switch flow expiry process when one of the flow timeout is exceeded (see 5.5).[1]

Listing 3: `../ryu/ryu/ofproto/ofproto_v1_3.py`

```
371  OFPFF_SEND_FLOW_REM = 1 << 0     # Send flow removed message when flow
372                                   # expires or is deleted.
```

处理丢弃事件，RYU 源码给出了例子：

Listing 4: ../ryu/ryu/ofproto/ofproto_v1_3_parser.py

```python
2377        @set_ev_cls(ofp_event.EventOFPFlowRemoved, MAIN_DISPATCHER)
2378        def flow_removed_handler(self, ev):
2379            msg = ev.msg
2380            dp = msg.datapath
2381            ofp = dp.ofproto
2382
2383            if msg.reason == ofp.OFPRR_IDLE_TIMEOUT:
2384                reason = 'IDLE TIMEOUT'
2385            elif msg.reason == ofp.OFPRR_HARD_TIMEOUT:
2386                reason = 'HARD TIMEOUT'
2387            elif msg.reason == ofp.OFPRR_DELETE:
2388                reason = 'DELETE'
2389            elif msg.reason == ofp.OFPRR_GROUP_DELETE:
2390                reason = 'GROUP DELETE'
2391            else:
2392                reason = 'unknown'
2393
2394            self.logger.debug('OFPFlowRemoved received: '
2395                              'cookie=%d priority=%d reason=%s table_id=%d '
2396                              'duration_sec=%d duration_nsec=%d '
2397                              'idle_timeout=%d hard_timeout=%d '
2398                              'packet_count=%d byte_count=%d match.fields=%s'
     ,
2399                              msg.cookie, msg.priority, reason, msg.table_id,
2400                              msg.duration_sec, msg.duration_nsec,
2401                              msg.idle_timeout, msg.hard_timeout,
2402                              msg.packet_count, msg.byte_count, msg.match)
```

datapath.id 用于识别交换机，s1对应1号，s2对应2号，依次类推。

图 1: 交换机编号

使用下面的命令可以可视化地观察流信息[2]，并启动控制器。

```
ryu/ryu/app/gui_topology$ ryu-manager --observe-links
gui_topology.py ../../../../lab05/task2.py
```
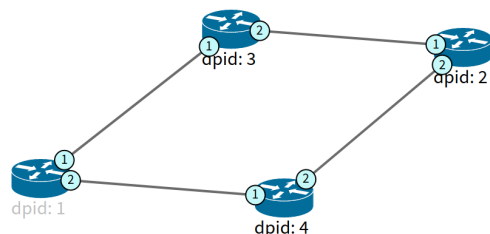
图 2: 测试连接

图 3: `gui_topology` 展示的拓扑结构

由图 3 可见，可以通过定时切换 `s1` 和 `s2` 的输出端口，来达到切换链路的功能。切换为 3 → 1 采用上面的链路，切换为 3 → 2 采用下面的链路。由于有两个流会超时，但是临近的两个超时应当只改变一次端口状态，所以会设置一个状态变量用于避免不同步情况的设置延迟导致的丢包，如图 4 所示。在图 2 中可见是能够 `ping` 通的。相关代码见附录 A。
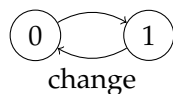

图 4: 状态机

3 使用双路

Write an RYU controller that uses both paths to forward packets from h1 to h2.

select: Execute one bucket in the group. Packets are processed by a single bucket in the group, based on a switch-computed selection algorithm (e.g. hash on some user-configured tuple or simple round robin). All configuration and state for the selection algorithm is external to OpenFlow. The selection algorithm should implement equal load sharing and can optionally be based on bucket weights. When a port specified in a bucket in a select group goes down, the switch may restrict bucket selection to the remaining set (those with forwarding actions to live ports) instead of dropping packets destined to that port. This behavior may reduce the disruption of a downed link or switch.[1]

4

Write an RYU controller that uses the first path (h1-s1-s3-s2-h2) for routing packets from h1 to h2 and uses the second path for backup. Specifically, when the first path experiences a link failure, the network should automatically switch to the second path without causing packet drop. (hint: consider using OFPGT_FF (FF is short for "fast failover") to construct a group table)

> **fast failover**: Execute the first live bucket. Each action bucket is associated with a specific port and/or group that controls its liveness. The buckets are evaluated in the order defined by the group, and the first bucket which is associated with a live port/group is selected. This group type enables the switch to change forwarding without requiring a round trip to the controller. If no buckets are live, packets are dropped. This group type must implement a *liveness mechanism*(see 6.5).[1]

参考文献

[1] Open Networking Foundation. OpenFlow switch specification[M/OL]. 2012. https://open networking.org/wp-content/uploads/2014/10/openflow-spec-v1.3.0.pdf.

[2] 梵高的向日葵、. SDN(三) RYU控制器相关笔记[EB/OL]. 2020. https://blog.csdn.net/weix in_42094589/article/details/104160571.

A 定时切换代码

Listing 5: `task2.py`

```python
1  # 2. Write an RYU controller that switches paths (h1-s1-s3-s2-h2 or h1-s1-s4-
       s2-h2) between h1 and h2 every 5 seconds.
2
3  from ryu.base import app_manager
4  from ryu.controller import ofp_event
5  from ryu.controller.handler import CONFIG_DISPATCHER, MAIN_DISPATCHER,
       set_ev_cls
6  from ryu.lib import packet
7  from ryu.lib.packet import ether_types, ethernet
8  from ryu.lib.packet import in_proto as inet
9  from ryu.ofproto import ofproto_v1_3
10
11 pathport = 1
12 pathstate = 1
13 # 0 -> 1 -> 0 (change)
14
15 class PeriodicSwtich(app_manager.RyuApp):
```

```
16          OFP_VERSIONS = [ofproto_v1_3.OFP_VERSION]
17
18          def __init__(self, *_args, **_kwargs):
19              super(PeriodicSwtich, self).__init__(*_args, **_kwargs)
20
21          @set_ev_cls(ofp_event.EventOFPSwitchFeatures, CONFIG_DISPATCHER)
22          def switch_features_handler(self, ev):
23              datapath = ev.msg.datapath
24              ofproto = datapath.ofproto
25              parser = datapath.ofproto_parser
26              out_port = 1
27
28              match = parser.OFPMatch(in_port=1, eth_type=ether_types.ETH_TYPE_IP,
            ipv4_src='10.0.0.1', ipv4_dst='10.0.0.2',ip_proto=inet.IPPROTO_UDP,
            udp_dst=5555)
29              actions = [parser.OFPActionOutput(out_port)]
30              self.add_flow(datapath, 0, match, actions)
31
32          def add_flow(self, datapath, priority, match, actions, buffer_id=None):
33              """
34              Default adding flow.
35              """
36              ofproto = datapath.ofproto
37              parser = datapath.ofproto_parser
38
39              inst = [parser.OFPInstructionActions(ofproto.OFPIT_APPLY_ACTIONS,
40                                                   actions)]
41              if buffer_id:
42                  mod = parser.OFPFlowMod(datapath=datapath, buffer_id=buffer_id,
43                                          priority=priority, match=match,
44                                          instructions=inst)
45              else:
46                  mod = parser.OFPFlowMod(datapath=datapath, priority=priority,
47                                          match=match, instructions=inst)
48              datapath.send_msg(mod)
49
50          def add_flow_timeout(self, datapath, priority, match, actions, buffer_id=
            None):
51              """
52              Add a flow that timeout in 5 sec.
53              """
54              ofproto = datapath.ofproto
55              parser = datapath.ofproto_parser
56
57              inst = [parser.OFPInstructionActions(ofproto.OFPIT_APPLY_ACTIONS,
58                                                   actions)]
59              if buffer_id:
60                  mod = parser.OFPFlowMod(datapath=datapath, buffer_id=buffer_id,
61                                          priority=priority, match=match,
62                                          instructions=inst, hard_timeout=5, flags=
            ofproto.OFPFF_SEND_FLOW_REM)
63              else:
64                  mod = parser.OFPFlowMod(datapath=datapath, priority=priority,
65                                          match=match, instructions=inst,
            hard_timeout=5, flags=ofproto.OFPFF_SEND_FLOW_REM)
66              datapath.send_msg(mod)
```

```python
67
68      @set_ev_cls(ofp_event.EventOFPSwitchFeatures, CONFIG_DISPATCHER)
69      def switch_features_handler(self, ev):
70          global pathport
71
72          datapath = ev.msg.datapath
73          ofproto = datapath.ofproto
74          parser = datapath.ofproto_parser
75
76          # Since the switches are added in order,
77          # The id is appended in order as well.
78          print('CONFIG switch id: '+ str(datapath.id))
79
80          if datapath.id == 1 or datapath.id == 2:
81              # forward flow h1 -> s1(s2)
82              # input from port 3, output to the selected port.
83              match = parser.OFPMatch(in_port=3)
84              actions = [parser.OFPActionOutput(pathport)] #
85              self.add_flow_timeout(datapath, 2, match, actions)
86
87              # return flow s1(s2) -> h1
88              # 2 possible flows: from port 1, from port 2.
89              match = parser.OFPMatch(in_port=1)
90              actions = [parser.OFPActionOutput(3)]
91              self.add_flow(datapath, 2, match, actions)
92              match = parser.OFPMatch(in_port=2)
93              actions = [parser.OFPActionOutput(3)]
94              self.add_flow(datapath, 2, match, actions)
95          elif datapath.id == 3 or datapath.id == 4:
96              # s3 / s4
97              match = parser.OFPMatch(in_port=1)
98              actions = [parser.OFPActionOutput(2)]
99              self.add_flow(datapath, 2, match, actions)
100             match = parser.OFPMatch(in_port=2)
101             actions = [parser.OFPActionOutput(1)]
102             self.add_flow(datapath, 2, match, actions)
103
104     @set_ev_cls(ofp_event.EventOFPFlowRemoved, MAIN_DISPATCHER)
105     def flow_removed_handler(self, ev):
106         global pathport, pathstate
107
108         msg = ev.msg
109         datapath = msg.datapath
110         ofproto = datapath.ofproto
111         parser = datapath.ofproto_parser
112
113         if msg.reason == ofproto.OFPRR_HARD_TIMEOUT:
114             pathstate += 1
115             if pathstate == 2:
116                 pathstate = 0
117                 pathport = 2 if pathport==1 else 1
118                 # change on pathport could only be invoked once in one round.
119                 print('Swtich to port: ' + str(pathport))
120             print('OFPFlowRemoved received: ' + str(datapath.id))
121             match = parser.OFPMatch(in_port=3)
122             actions = [parser.OFPActionOutput(pathport)]
```

```
123        self.add_flow_timeout(datapath, 2, match, actions)
```