# Write SDN Controller

计算机网络 CS339

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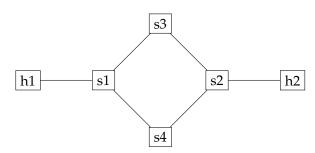
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Ryu provides software components with well defined API's that make it easy for developers to create new network management and control applications.

#### 1 建立网络

Set up the following network first:



使用给出的示例代码。但是为了处理上的方便,将会指定链路连接的端口号。

Listing 1: loopnet.py

```
#!/usr/bin/python
   """Sample Code"""
  from mininet.topo import Topo
4 from mininet.net import Mininet
5 from mininet.node import OVSBridge, OVSSwitch, OVSKernelSwitch
6 from mininet.node import CPULimitedHost
  from mininet.node import RemoteController
7
   from mininet.link import TCLink
8
   from mininet.util import dumpNodeConnections
9
   from mininet.log import setLogLevel, info
from mininet.cli import CLI
10
   from sys import argv
12
   def Test():
13
        "Create network and run simple performance test"
14
        net = Mininet( switch=OVSSwitch,host=CPULimitedHost, link=TCLink,
15
        autoStaticArp=False, controller=RemoteController)
        switch1 = net.addSwitch('s1')
switch2 = net.addSwitch('s2')
switch3 = net.addSwitch('s3')
16
17
18
        switch4 = net.addSwitch('s4')
19
        host1 = net.addHost('h1', cpu=.25)
host2 = net.addHost('h2', cpu=.25)
20
21
        net.addLink(host1, switch1, 1, 3, bw=10, delay='5ms', loss=0, use_htb=
22
        net.addLink(host2, switch2, 1, 3, bw=10, delay='5ms', loss=0, use_htb=
23
        True)
        net.addLink(switch1, switch3, 1, 1, bw=10, delay='5ms', loss=0, use_htb=
24
        net.addLink(switch1, switch4, 2, 1, bw=10, delay='5ms', loss=0, use_htb=
25
       True)
        net.addLink(switch2, switch3, 1, 2, bw=10, delay='5ms', loss=0, use_htb=
26
       True)
        net.addLink(switch2, switch4, 2, 2, bw=10, delay='5ms', loss=0, use_htb=
27
       True)
        c1 = net.addController('c1', controller=RemoteController, ip="127.0.0.1",
28
        port=6653)
        net.build()
29
```

```
30
        c1.start()
        s1, s2, s3, s4 = net.getNodeByName('s1', 's2', 's3', 's4')
31
        s1.start([c1])
32
33
        s2.start([c1])
        s3.start([c1])
34
        s4.start([c1])
35
        net.start()
36
        info( "Dumping host connections\n" )
37
        dumpNodeConnections(net.hosts)
38
        h1, h2 = net.getNodeByName('h1', 'h2')
39
        CLI(net)
40
        net.stop()
41
42
   if __name__ ==
                      _main__':
        # setLogLevel( 'debug'
43
        setLogLevel('info')
44
        Test()
45
```

#### 2 定时切换

Write an RYU controller that switches paths (h1-s1-s3-s2-h2 or h1-s1-s4-s2-h2) between h1 and h2 every 5 seconds.

查看修改流的定义函数。其中参数 hard\_timeout 用于定义丢弃流前的最大秒数。

Listing 2: ../ryu/ryu/ofproto/ofproto\_v1\_3\_parser.py

```
def __init__(self, datapath, cookie=0, cookie_mask=0, table_id=0,
2703
                       command=ofproto.OFPFC_ADD,
2704
                       idle_timeout=0, hard_timeout=0,
2705
                       priority=ofproto.OFP_DEFAULT_PRIORITY,
2706
                       buffer_id=ofproto.OFP_NO_BUFFER,
2707
2708
                       out_port=0, out_group=0, flags=0,
                       match=None,
2709
                       instructions=None):
2710
```

参数 flags 可以被指定为 OFPFF\_SEND\_FLOW\_REM, 可以用于在丢弃流后发出事件用于相 关处理。

**Flow-Removed**: Inform the controller about the removal of a flow entry from a flow table. Flow-Removed messages are only sent for flow entries with the

```
OFPFF_SEND_FLOW_REM
```

flag set. They are generated as the result of a controller flow delete requests or the switch flow expiry process when one of the flow timeout is exceeded (see 5.5). [1]

Listing 3: ../ryu/ryu/ofproto/ofproto\_v1\_3.py

```
OFPFF_SEND_FLOW_REM = 1 << 0
                                      # Send flow removed message when flow
371
                                     # expires or is deleted.
372
```

处理丢弃事件, RYU 源码给出了例子:

Listing 4: ../ryu/ryu/ofproto/ofproto\_v1\_3\_parser.py

```
@set_ev_cls(ofp_event.EventOFPFlowRemoved, MAIN_DISPATCHER)
2377
              def flow_removed_handler(self, ev):
2378
                  msg = ev.msg
2379
                  dp = msg.datapath
2380
                  ofp = dp.ofproto
2381
2382
                  if msg.reason == ofp.OFPRR_IDLE_TIMEOUT:
2383
                       reason = 'IDLE TIMEOUT
2384
                  elif msg.reason == ofp.OFPRR_HARD_TIMEOUT:
2385
                       reason = 'HARD TIMEOUT
2386
                  elif msg.reason == ofp.OFPRR_DELETE:
2387
                       reason = 'DELETE
2388
                  elif msg.reason == ofp.OFPRR_GROUP_DELETE:
2389
                       reason = 'GROUP DELETE
2390
2391
                  else:
                       reason = 'unknown'
2392
2393
                  self.logger.debug('OFPFlowRemoved received: '
2394
2395
                                        cookie=%d priority=%d reason=%s table_id=%d '
                                       'duration_sec=%d duration_nsec=%d
2396
                                       'idle_timeout=%d hard_timeout=%d '
2397
                                       'packet_count=%d byte_count=%d match.fields=%s'
2398
                                      msg.cookie, msg.priority, reason, msg.table_id,
2399
                                      msg.duration_sec, msg.duration_nsec,
msg.idle_timeout, msg.hard_timeout,
2400
2401
                                      msg.packet_count, msg.byte_count, msg.match)
2402
```

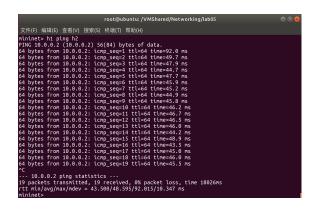
datapath.id 用于识别交换机,s1对应1号,s2对应2号,依次类推。



图 1: 交换机编号

使用下面的命令可以可视化地观察流信息[2],并启动控制器。

```
ryu/ryu/app/qui_topology$ ryu-manager --observe-links
qui_topology.py ../../../lab05/task2.py
```



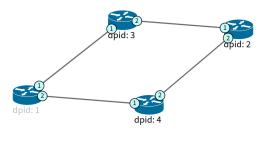


图 2: 测试连接

图 3: gui\_topology 展示的拓扑结构

由图 3 可见,可以通过定时切换 s1 和 s2 的输出端口,来达到切换链路的功能。切换为 3  $\rightarrow$  1 采用上面的链路,切换为 3  $\rightarrow$  2 采用下面的链路。由于有两个流会超时,但是临近的两个超时应当只改变一次端口状态,所以会设置一个状态变量用于避免不同步情况的设置延迟导致的丢包,如图 4 所示。在图 2 中可见是能够 ping 通的。相关代码见附录 A。



图 4: 状态机

## 3 使用双路

Write an RYU controller that uses both paths to forward packets from h1 to h2.

**select**: Execute one bucket in the group. Packets are processed by a single bucket in the group, based on a switch-computed selection algorithm (e.g. hash on some user-configured tuple or simple round robin). All configuration and state for the selection algorithm is external to OpenFlow. The selection algorithm should implement equal load sharing and can optionally be based on bucket weights. When a port specified in a bucket in a select group goes down, the switch may restrict bucket selection to the remaining set (those with forwarding actions to live ports) instead of dropping packets destined to that port. This behavior may reduce the disruption of a downed link or switch.<sup>[1]</sup>

Write an RYU controller that uses the first path (h1-s1-s3-s2-h2) for routing packets from h1 to h2 and uses the second path for backup. Specifically, when the first path experiences a link failure, the network should automatically switch to the second path without causing packet drop. (hint: consider using OFPGT\_FF (FF is short for "fast failover") to construct a group table)

fast failover: Execute the first live bucket. Each action bucket is associated with a specific port and/or group that controls its liveness. The buckets are evaluated in the order defined by the group, and the first bucket which is associated with a live port/group is selected. This group type enables the switch to change forwarding without requiring a round trip to the controller. If no buckets are live, packets are dropped. This group type must implement a liveness mechanism (see 6.5). [1]

## 参考文献

- [1] Open Networking Foundation. OpenFlow switch specification[M/OL]. 2012. https://open networking.org/wp-content/uploads/2014/10/openflow-spec-v1.3.0.pdf.
- [2] 梵高的向日葵、. SDN(三) RYU控制器相关笔记[EB/OL]. 2020. https://blog.csdn.net/weix in\_42094589/article/details/104160571.

### A 定时切换代码

#### Listing 5: task2.py

```
1 # 2. Write an RYU controller that switches paths (h1-s1-s3-s2-h2 or h1-s1-s4-
        s2-h2) between h1 and h2 every 5 seconds.
 3 from ryu.base import app_manager
 4 from ryu.controller import ofp_event
 5 from ryu.controller.handler import CONFIG_DISPATCHER, MAIN_DISPATCHER,
        set_ev_cls
 6 from ryu.lib import packet
 from ryu.lib.packet import ether_types, ethernet
from ryu.lib.packet import in_proto as inet
 9 from ryu.ofproto import ofproto_v1_3
pathport = 1
12 pathstate = 1
13 \# 0 -> 1 -> 0  (change)
15 class PeriodicSwtich(app_manager.RyuApp):
```

```
OFP_VERSIONS = [ofproto_v1_3.0FP_VERSION]
16
17
       def __init__(self, *_args, **_kwargs):
18
            super(PeriodicSwtich, self).__init__(*_args, **_kwargs)
19
20
       @set_ev_cls(ofp_event.EventOFPSwitchFeatures, CONFIG_DISPATCHER)
21
       def switch_features_handler(self, ev):
22
            datapath = ev.msq.datapath
23
            ofproto = datapath.ofproto
24
25
            parser = datapath.ofproto_parser
            out_port = 1
26
27
            match = parser.OFPMatch(in_port=1, eth_type=ether_types.ETH_TYPE_IP,
28
       ipv4\_src='10.0.0.1', ipv4\_dst='10.0.0.2', ip\_proto=inet.IPPROTO\_UDP,
       udp_dst=5555)
            actions = [parser.OFPActionOutput(out_port)]
29
            self.add_flow(datapath, 0, match, actions)
30
31
       def add_flow(self, datapath, priority, match, actions, buffer_id=None):
32
33
            Default adding flow.
34
35
            ofproto = datapath.ofproto
36
37
            parser = datapath.ofproto_parser
38
            inst = [parser.OFPInstructionActions(ofproto.OFPIT_APPLY_ACTIONS,
39
                                                   actions)]
40
            if buffer_id:
41
                mod = parser.OFPFlowMod(datapath=datapath, buffer_id=buffer_id,
42
                                         priority=priority, match=match,
43
                                         instructions=inst)
44
45
            else:
                mod = parser.OFPFlowMod(datapath=datapath, priority=priority,
46
                                         match=match, instructions=inst)
47
            datapath.send_msg(mod)
48
49
       def add_flow_timeout(self, datapath, priority, match, actions, buffer_id=
50
       None):
51
            Add a flow that timeout in 5 sec.
52
53
            ofproto = datapath.ofproto
54
            parser = datapath.ofproto_parser
55
56
            inst = [parser.OFPInstructionActions(ofproto.OFPIT_APPLY_ACTIONS,
57
                                                   actions)]
58
            if buffer_id:
59
                mod = parser.OFPFlowMod(datapath=datapath, buffer_id=buffer_id,
60
                                         priority=priority, match=match,
61
                                         instructions=inst, hard_timeout=5, flags=
62
       ofproto.OFPFF_SEND_FLOW_REM)
63
            else:
                mod = parser.OFPFlowMod(datapath=datapath, priority=priority,
64
                                         match=match, instructions=inst,
65
       hard_timeout=5, flags=ofproto.OFPFF_SEND_FLOW_REM)
66
            datapath.send_msg(mod)
```

```
67
        @set_ev_cls(ofp_event.EventOFPSwitchFeatures, CONFIG_DISPATCHER)
68
        def switch_features_handler(self, ev):
69
70
            global pathport
 71
             datapath = ev.msg.datapath
72
             ofproto = datapath.ofproto
 73
             parser = datapath.ofproto_parser
 74
 75
             # Since the switches are added in order,
 76
             # The id is appended in order as well.
 77
             print('CONFIG switch id: '+ str(datapath.id))
78
79
             if datapath.id == 1 or datapath.id == 2:
80
81
                 # forward flow h1 \rightarrow s1(s2)
                 # input from port 3, output to the selected port.
82
                 match = parser.OFPMatch(in_port=3)
83
                 actions = [parser.OFPActionOutput(pathport)] #
84
85
                 self.add_flow_timeout(datapath, 2, match, actions)
86
                 # return flow s1(s2) \rightarrow h1
87
                 # 2 possible flows: from port 1, from port 2.
88
                 match = parser.OFPMatch(in_port=1)
89
                 actions = [parser.OFPActionOutput(3)]
90
                 self.add_flow(datapath, 2, match, actions)
91
                 match = parser.OFPMatch(in_port=2)
92
                 actions = [parser.OFPActionOutput(3)]
93
                 self.add_flow(datapath, 2, match, actions)
94
95
             elif datapath.id == 3 or datapath.id == 4:
                 # s3 / s4
96
                 match = parser.OFPMatch(in_port=1)
97
98
                 actions = [parser.OFPActionOutput(2)]
                 self.add_flow(datapath, 2, match, actions)
99
                 match = parser.OFPMatch(in_port=2)
100
                 actions = [parser.OFPActionOutput(1)]
101
                 self.add_flow(datapath, 2, match, actions)
102
103
        @set_ev_cls(ofp_event.EventOFPFlowRemoved, MAIN_DISPATCHER)
104
        def flow_removed_handler(self, ev):
105
            global pathport, pathstate
106
107
            msg = ev.msg
108
             datapath = msg.datapath
109
             ofproto = datapath.ofproto
110
             parser = datapath.ofproto_parser
111
112
             if msg.reason == ofproto.OFPRR_HARD_TIMEOUT:
113
                 pathstate += 1
114
                 if pathstate == 2:
115
                     pathstate = 0
116
                     pathport = 2 if pathport==1 else 1
117
118
                     # change on pathport could only be invoked once in one round.
                     print('Swtich to port: ' + str(pathport))
119
                 print('OFPFlowRemoved received: ' + str(datapath.id))
120
                 match = parser.OFPMatch(in_port=3)
121
122
                 actions = [parser.OFPActionOutput(pathport)]
```