Write SDN Controller

计算机网络 CS339

李子龙 518070910095 2021 年 11 月 4 日

目录

1	建立网络																		2
2	定时切换。																		3
3	使用双路																		5
4	断路备用																		7
Α	定时切换代码																		8
В	使用双路代码																		10

Ryu provides software components with well defined API's that make it easy for developers to create new network management and control applications.

1 建立网络

Set up the following network first:

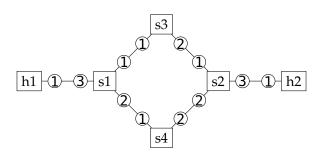


图 1: 网络拓扑

使用给出的示例代码。但是为了处理上的方便,将会指定链路连接的端口号。

Listing 1: loopnet.py

```
1 #!/usr/bin/python
   """Sample Code"""
   from mininet.topo import Topo
   from mininet.net import Mininet
  from mininet.node import OVSBridge, OVSSwitch, OVSKernelSwitch
  from mininet.node import CPULimitedHost
  from mininet.node import RemoteController
8 from mininet.link import TCLink
9 from mininet.util import dumpNodeConnections
  from mininet.log import setLogLevel, info
from mininet.cli import CLI
10
11
   from sys import argv
12
   def Test():
13
        "Create network and run simple performance test"
14
       net = Mininet( switch=OVSSwitch,host=CPULimitedHost, link=TCLink,
15
       autoStaticArp=False, controller=RemoteController)
16
        switch1 = net.addSwitch('s1')
        switch2 = net.addSwitch('s2')
17
        switch3 = net.addSwitch('s3')
18
19
        switch4 = net.addSwitch('s4')
       host1 = net.addHost('h1', cpu=.25)
host2 = net.addHost('h2', cpu=.25)
20
21
       net.addLink(host1, switch1, 1, 3, bw=10, delay='5ms', loss=0, use_htb=
22
       net.addLink(host2, switch2, 1, 3, bw=10, delay='5ms', loss=0, use_htb=
23
       net.addLink(switch1, switch3, 1, 1, bw=10, delay='5ms', loss=0, use_htb=
24
       net.addLink(switch1, switch4, 2, 1, bw=10, delay='5ms', loss=0, use_htb=
25
```

```
net.addLink(switch2, switch3, 1, 2, bw=10, delay='5ms', loss=0, use_htb=
       True)
       net.addLink(switch2, switch4, 2, 2, bw=10, delay='5ms', loss=0, use_htb=
27
       True)
        c1 = net.addController('c1', controller=RemoteController, ip="127.0.0.1",
28
        port=6653)
       net.build()
29
        c1.start()
30
        s1, s2, s3, s4 = net.getNodeByName('s1', 's2', 's3', 's4')
31
32
        s1.start([c1])
        s2.start([c1])
33
       s3.start([c1])
34
35
       s4.start([c1])
       net.start()
36
       info( "Dumping host connections\n" )
37
        dumpNodeConnections(net.hosts)
38
39
        h1, h2 = net.getNodeByName('h1', 'h2')
        CLI(net)
40
41
       net.stop()
   if __name__ == '__main__':
42
        # setLogLevel( 'debug' )
43
       setLogLevel('info')
44
45
       Test()
```

2 定时切换

Write an RYU controller that switches paths (h1-s1-s3-s2-h2 or h1-s1-s4-s2-h2) between h1 and h2 every 5 seconds.

查看修改流的定义函数。其中参数 hard_timeout 用于定义丢弃流前的最大秒数。

Listing 2: ../ryu/ryu/ofproto/ofproto_v1_3_parser.py

```
def __init__(self, datapath, cookie=0, cookie_mask=0, table_id=0,
2703
                       command=ofproto.OFPFC_ADD,
2704
2705
                       idle_timeout=0, hard_timeout=0,
                       priority=ofproto.OFP_DEFAULT_PRIORITY,
2706
                       buffer_id=ofproto.OFP_NO_BUFFER,
2707
                       out_port=0, out_group=0, flags=0,
2708
                       match=None,
2709
2710
                       instructions=None):
```

参数 flags 可以被指定为 OFPFF_SEND_FLOW_REM, 可以用于在丢弃流后发出事件用于相 关处理。

Flow-Removed: Inform the controller about the removal of a flow entry from a flow table. Flow-Removed messages are only sent for flow entries with the

OFPFF_SEND_FLOW_REM

flag set. They are generated as the result of a controller flow delete requests or the switch flow expiry process when one of the flow timeout is exceeded (see 5.5). [1]

Listing 3: ../ryu/ryu/ofproto/ofproto_v1_3.py

```
OFPFF_SEND_FLOW_REM = 1 << 0
                                     # Send flow removed message when flow
371
                                     # expires or is deleted.
372
```

处理丢弃事件, RYU 源码给出了例子:

Listing 4: ../ryu/ryu/ofproto/ofproto_v1_3_parser.py

```
@set_ev_cls(ofp_event.EventOFPFlowRemoved, MAIN_DISPATCHER)
2377
2378
             def flow_removed_handler(self, ev):
                 msq = ev.msg
2379
                  dp = msg.datapath
2380
2381
                 ofp = dp.ofproto
2382
                  if msg.reason == ofp.OFPRR_IDLE_TIMEOUT:
2383
                      reason = 'IDLE TIMEOUT
2384
                  elif msg.reason == ofp.OFPRR_HARD_TIMEOUT:
2385
                      reason = 'HARD TIMEOUT'
2386
                  elif msg.reason == ofp.OFPRR_DELETE:
2387
                      reason = 'DELETE
2388
                  elif msq.reason == ofp.OFPRR_GROUP_DELETE:
2389
                      reason = 'GROUP DELETE'
2390
2391
                  else:
                      reason = 'unknown'
2392
2393
2394
                  self.logger.debug('OFPFlowRemoved received:
                                      cookie=%d priority=%d reason=%s table_id=%d '
2395
                                      'duration_sec=%d duration_nsec=%d
2396
                                     'idle_timeout=%d hard_timeout=%d '
2397
                                      'packet_count=%d byte_count=%d match.fields=%s'
2398
2399
                                     msg.cookie, msg.priority, reason, msg.table_id,
                                     msg.duration_sec, msg.duration_nsec,
2400
2401
                                     msg.idle_timeout, msg.hard_timeout,
                                     msg.packet_count, msg.byte_count, msg.match)
2402
```

datapath.id 用于识别交换机,s1对应1号,s2对应2号,依次类推。

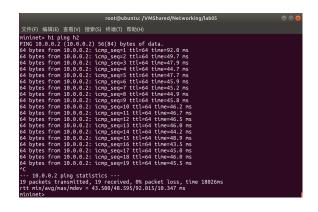
```
root@ubuntu: /VMShared/Networking/lab05
 文件(F) 编辑(E) 查看(V) 搜索(S) 终端(T) 帮助(H)
スパイプ 海地は) 宣信(ゲ) 接条(S) 終趣(J) 辞期(H)

**Croot@ubuntu:/VMShared/Networking/lab05# ryu-manager task2.py
loading app task2.py
loading app ryu.controller.ofp_handler
instantiating app task2.py of PeriodicSwtich
instantiating app ryu.controller.ofp_handler of OFPHandler
CONFIG switch id: 1
CONFIG switch id: 2
CONFIG switch id: 3
  ONFIG switch id: 3
ONFIG switch id: 4
```

图 2: 交换机编号

使用下面的命令可以可视化地观察流信息[2],并启动控制器。

ryu/ryu/app/gui_topology\$ ryu-manager --observe-links qui_topology.py ../../../lab05/task2.py



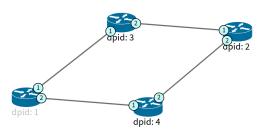


图 3: 测试连接

图 4: gui_topology 展示的拓扑结构

由图 4 可见,可以通过定时切换 s1 和 s2 的输出端口,来达到切换链路的功能。切换为 3 ightarrow 1 采用上面的链路,切换为 3 ightarrow 2 采用下面的链路。由于有两个流会超时,但是临近的两个 超时应当只改变一次端口状态,所以会设置一个状态变量用于避免不同步情况的设置延迟导致的 丢包,如图5所示。在图3中可见是能够 ping 通的。相关代码见附录 A。



图 5: 状态机

3 使用双路

Write an RYU controller that uses both paths to forward packets from h1 to h2.

select: Execute one bucket in the group. Packets are processed by a single bucket in the group, based on a switch-computed selection algorithm (e.g. hash on some user-configured tuple or simple round robin). All configuration and state for the selection algorithm is external to OpenFlow. The selection algorithm should implement equal load sharing and can optionally be based on bucket weights. When a port specified in a bucket in a select group goes down, the switch may restrict bucket selection

to the remaining set (those with forwarding actions to live ports) instead of dropping packets destined to that port. This behavior may reduce the disruption of a downed link or switch.[1]

代码见附录 B, 在使用组之前,需要先注册 OFPGT_SELECT 组。使用给出的示例代码发送 请求组信息。这里 watch_port 被设定为 OFPP_ANY,而 watch_group 被设定为 OFPQ_ALL [3], 定义如下:

Listing 5: ../ryu/ryu/ofproto/ofproto_v1_3.py

```
OFPP\_ANY = 0xffffffff
                                     # Not associated with a physical port.
110
    # All ones is used to indicate all queues in a port (for stats retrieval).
111
    OFPQ\_ALL = 0xffffffff
112
```

```
root@ubuntu: /VMShared/Networking/lab05
文件(F) 编辑(E) 查看(V) 搜索(S) 终端(T) 帮助(H)

000% loss) (10.00Mbit 5ms delay 0.00000% loss)

Dumping host connections hi hi-ethi:s1-eth3 hz h2-eth1:s2-eth3

**** Starting CLI: mininet> h1 ping h2

PING 10.0.0.2 (10.0.0.2) 56(84) bytes of data.
64 bytes from 10.0.0.2: icmp_seq=1 ttl=64 time=91.4 ms
64 bytes from 10.0.0.2: icmp_seq=2 ttl=64 time=42.8 ms
64 bytes from 10.0.0.2: icmp_seq=3 ttl=64 time=46.6 ms
64 bytes from 10.0.0.2: icmp_seq=5 ttl=64 time=46.6 ms
64 bytes from 10.0.0.2: icmp_seq=5 ttl=64 time=45.0 ms
64 bytes from 10.0.0.2: icmp_seq=5 ttl=64 time=45.7 ms
64 bytes from 10.0.0.2: icmp_seq=7 ttl=64 time=45.7 ms
64 bytes from 10.0.0.2: icmp_seq=8 ttl=64 time=47.8 ms

^C
       文件(F) 编辑(E) 查看(V) 搜索(S) 终端(T) 帮助(H)
  --- 10.0.0.2 ping statistics ---
8 packets transmitted, 8 received, 0% packet loss, time 7009ms
rtt min/avg/max/mdev = 42.865/51.769/91.479/15.084 ms
mininet>
```

图 6: 检查可达性

```
root@ubuntu: /VMShared/Networking/lab05
文件(F) 编辑(E) 查看(V) 搜索(S) 终端(T) 帮助(H)
mininet> dpctl dump-flows
cookie=0x0, duration=115.179s, table=0, n_packets=12, n_bytes=908, priority=10,in_port="s1-eth3" actions=group:1
cookie=0x0, duration=115.179s, table=0, n_packets=51, n_bytes=6076, priority=10,in_port="s1-eth1" actions=output:"s1-eth3"
cookie=0x0, duration=115.179s, table=0, n_packets=56, n_bytes=6310, priority=10,in_port="s1-eth2" actions=output:"s1-eth3"
cookie=0x0, duration=115.126s, table=0, n_packets=13, n_bytes=994, priority=10,in_port="s2-eth3" actions=group:1 cookie=0x0, duration=115.126s, table=0, n_packets=56, n_bytes=6382, priority=10,in_port="s2-eth1" actions=output:"s2-eth3" cookie=0x0, duration=115.126s, table=0, n_packets=51, n_bytes=6004, priority=10,in_port="s2-eth2" actions=output:"s2-eth3"
cookie=0x0, duration=115.038s, table=0, n_packets=32, n_bytes=3491, priority=10,in_port="s3-eth1" actions=output:"s3-eth2" cookie=0x0, duration=115.038s, table=0, n_packets=27, n_bytes=3185, priority=10,in_port="s3-eth2" actions=output:"s3-eth1"
 cookie=0x0, duration=114.985s, table=0, n_packets=27, n_bytes=3113, priority=10,in_port="s4-eth1" actions=output:"s4-eth2"
cookie=0x0, duration=114.985s, table=0, n_packets=32, n_bytes=3419, priority=10,in_port="s4-eth2" actions=output:"s4-eth1"
```

图 7: 流表

图 6 显示了其可达性正常。图 7 使用

```
dpctl dump-flows
```

显示流表信息,可以看到 s1 和 s2 对应的端口1和2负载是均衡的,说明了功能的正常实现。

4 断路备用

Write an RYU controller that uses the first path (h1-s1-s3-s2-h2) for routing packets from h1 to h2 and uses the second path for backup. Specifically, when the first path experiences a link failure, the network should automatically switch to the second path without causing packet drop. (hint: consider using OFPGT_FF (FF is short for "fast failover") to construct a group table)

fast failover: Execute the first live bucket. Each action bucket is associated with a specific port and/or group that controls its liveness. The buckets are evaluated in the order defined by the group, and the first bucket which is associated with a live port/group is selected. This group type enables the switch to change forwarding without requiring a round trip to the controller. If no buckets are live, packets are dropped. This group type must implement a *liveness mechanism* (see 6.5). [1]

参考文献

[1] Open Networking Foundation. OpenFlow switch specification[M/OL]. 2012. https://open networking.org/wp-content/uploads/2014/10/openflow-spec-v1.3.0.pdf.

- [2] 梵高的向日葵、. SDN(三) RYU控制器相关笔记[EB/OL]. 2020. https://blog.csdn.net/weix in_42094589/article/details/104160571.
- [3] 李呈. 基于RYU应用开发之负载均衡[EB/OL]. 2015. https://www.sdnlab.com/10211.html.

A 定时切换代码

Listing 6: task2.py

```
# 2. Write an RYU controller that switches paths (h1-s1-s3-s2-h2 or h1-s1-s4-
       s2-h2) between h1 and h2 every 5 seconds.
  from ryu.base import app_manager
3
4 from ryu.controller import ofp_event
from ryu.controller.handler import CONFIG_DISPATCHER, MAIN_DISPATCHER,
       set_ev_cls
  from ryu.lib import packet
   from ryu.lib.packet import ether_types, ethernet
8 from ryu.lib.packet import in_proto as inet
  from ryu.ofproto import ofproto_v1_3
10
11 pathport = 1
  pathstate = 1
12
   # 0 -> 1 -> 0 (change)
13
14
   class PeriodicSwtich(app_manager.RyuApp):
15
       OFP_VERSIONS = [ofproto_v1_3.0FP_VERSION]
16
17
       def __init__(self, *_args, **_kwargs):
18
19
           super(PeriodicSwtich, self).__init__(*_args, **_kwargs)
20
       @set_ev_cls(ofp_event.EventOFPSwitchFeatures, CONFIG_DISPATCHER)
21
       def switch_features_handler(self, ev):
22
           datapath = ev.msg.datapath
23
           ofproto = datapath.ofproto
25
           parser = datapath.ofproto_parser
           out_port = 1
26
27
28
           match = parser.OFPMatch(in_port=1, eth_type=ether_types.ETH_TYPE_IP,
       ipv4_src='10.0.0.1', ipv4_dst='10.0.0.2',ip_proto=inet.IPPROTO_UDP,
       udp_dst=5555)
           actions = [parser.OFPActionOutput(out_port)]
29
           self.add_flow(datapath, 0, match, actions)
30
31
       def add_flow(self, datapath, priority, match, actions, buffer_id=None):
32
33
           Default adding flow.
34
35
           ofproto = datapath.ofproto
36
           parser = datapath.ofproto_parser
37
38
           inst = [parser.OFPInstructionActions(ofproto.OFPIT_APPLY_ACTIONS,
39
```

```
actions)]
40
            if buffer_id:
41
                mod = parser.OFPFlowMod(datapath=datapath, buffer_id=buffer_id,
42
                                         priority=priority, match=match,
43
                                         instructions=inst)
44
            else:
45
                mod = parser.OFPFlowMod(datapath=datapath, priority=priority,
46
47
                                         match=match, instructions=inst)
            datapath.send_msq(mod)
48
49
       def add_flow_timeout(self, datapath, priority, match, actions, buffer_id=
50
       None):
51
           Add a flow that timeout in 5 sec.
52
53
            ofproto = datapath.ofproto
54
55
            parser = datapath.ofproto_parser
56
            inst = [parser.OFPInstructionActions(ofproto.OFPIT_APPLY_ACTIONS,
57
58
                                                   actions)]
            if buffer_id:
59
                mod = parser.OFPFlowMod(datapath=datapath, buffer_id=buffer_id,
60
61
                                         priority=priority, match=match,
                                         instructions=inst, hard_timeout=5, flags=
62
       ofproto.OFPFF_SEND_FLOW_REM)
            else:
63
                mod = parser.OFPFlowMod(datapath=datapath, priority=priority,
64
                                         match=match, instructions=inst,
65
       hard_timeout=5, flags=ofproto.OFPFF_SEND_FLOW_REM)
            datapath.send_msg(mod)
66
67
68
       @set_ev_cls(ofp_event.EventOFPSwitchFeatures, CONFIG_DISPATCHER)
       def switch_features_handler(self, ev):
69
            global pathport
70
71
            datapath = ev.msq.datapath
72
            ofproto = datapath.ofproto
73
74
            parser = datapath.ofproto_parser
75
            # Since the switches are added in order,
76
77
            # The id is appended in order as well.
            print('CONFIG switch id: '+ str(datapath.id))
78
79
            if datapath.id == 1 or datapath.id == 2:
80
                # forward flow h1 -> s1(s2)
81
                # input from port 3, output to the selected port.
82
                match = parser.OFPMatch(in_port=3)
83
                actions = [parser.OFPActionOutput(pathport)] #
84
                self.add_flow_timeout(datapath, 2, match, actions)
85
86
                # return flow s1(s2) -> h1
87
88
                # 2 possible flows: from port 1, from port 2.
                match = parser.OFPMatch(in_port=1)
89
                actions = [parser.OFPActionOutput(3)]
90
                self.add_flow(datapath, 2, match, actions)
91
                match = parser.OFPMatch(in_port=2)
```

```
actions = [parser.OFPActionOutput(3)]
93
                 self.add_flow(datapath, 2, match, actions)
94
            elif datapath.id == 3 or datapath.id == 4:
95
96
                 # s3 / s4
                match = parser.OFPMatch(in_port=1)
97
                 actions = [parser.OFPActionOutput(2)]
98
                 self.add_flow(datapath, 2, match, actions)
99
                match = parser.OFPMatch(in_port=2)
100
                 actions = [parser.OFPActionOutput(1)]
101
                 self.add_flow(datapath, 2, match, actions)
102
103
        @set_ev_cls(ofp_event.EventOFPFlowRemoved, MAIN_DISPATCHER)
104
        def flow_removed_handler(self, ev):
105
            global pathport, pathstate
106
107
108
            msg = ev.msg
            datapath = msg.datapath
109
            ofproto = datapath.ofproto
110
111
            parser = datapath.ofproto_parser
112
            if msq.reason == ofproto.OFPRR_HARD_TIMEOUT:
113
                 pathstate += 1
114
115
                 if pathstate == 2:
                     pathstate = 0
116
117
                     pathport = 2 if pathport==1 else 1
                     # change on pathport could only be invoked once in one round.
118
                     print('Swtich to port: ' + str(pathport))
119
                 print('OFPFlowRemoved received: ' + str(datapath.id))
120
121
                match = parser.OFPMatch(in_port=3)
                 actions = [parser.OFPActionOutput(pathport)]
122
                 self.add_flow_timeout(datapath, 2, match, actions)
123
```

使用双路代码

Listing 7: task3.py

```
# 3. Write an RYU controller that uses both paths to forward packets from h1
       to h2.
2
   from ryu.base import app_manager
   from ryu.controller import ofp_event
4
   from ryu.controller.handler import CONFIG_DISPATCHER, MAIN_DISPATCHER,
       set_ev_cls
   from ryu.lib import packet
   from ryu.lib.packet import ether_types, ethernet
   from ryu.lib.packet import in_proto as inet
8
   from ryu.ofproto import ofproto_v1_3
10
   class PeriodicSwtich(app_manager.RyuApp):
11
       OFP_VERSIONS = [ofproto_v1_3.0FP_VERSION]
12
13
       def __init__(self, *_args, **_kwargs):
14
           super(PeriodicSwtich, self).__init__(*_args, **_kwargs)
15
```

```
16
       @set_ev_cls(ofp_event.EventOFPSwitchFeatures, CONFIG_DISPATCHER)
17
       def switch_features_handler(self, ev):
18
19
            datapath = ev.msq.datapath
            ofproto = datapath.ofproto
20
            parser = datapath.ofproto_parser
21
22
            if datapath.id == 1 or datapath.id == 2:
23
                # s1 / s2
24
                # bucket group
                actions1 = [parser.OFPActionOutput(1)]
26
                actions2 = [parser.OFPActionOutput(2)]
27
                weight1 = 50
28
                weight2 = 50
29
                watch_port = ofproto_v1_3.0FPP_ANY
30
                watch_group = ofproto_v1_3.0FPQ_ALL
31
                buckets = [
32
                    parser.OFPBucket(weight1, watch_port, watch_group, actions1),
33
34
                    parser.OFPBucket(weight2, watch_port, watch_group, actions2)]
35
36
                group_id = 1
                req = parser.OFPGroupMod(datapath, ofproto.OFPGC_ADD, ofproto.
37
       OFPGT_SELECT, group_id, buckets)
38
                datapath.send_msg(req)
39
                match = parser.OFPMatch(in_port=3)
40
                self.add_flow_group(datapath, 10, match, group_id)
41
42
43
                \# return flow s1(s2) -> h1
                # 2 possible flows: from port 1, from port 2.
44
                match = parser.OFPMatch(in_port=1)
45
46
                actions = [parser.OFPActionOutput(3)]
                self.add_flow(datapath, 10, match, actions)
47
                match = parser.OFPMatch(in_port=2)
48
                actions = [parser.OFPActionOutput(3)]
49
                self.add_flow(datapath, 10, match, actions)
50
            elif datapath.id == 3 or datapath.id == 4:
51
                # s3 / s4
                match = parser.OFPMatch(in_port=1)
53
                actions = [parser.OFPActionOutput(2)]
54
                self.add_flow(datapath, 10, match, actions)
55
                match = parser.OFPMatch(in_port=2)
56
                actions = [parser.OFPActionOutput(1)]
57
                self.add_flow(datapath, 10, match, actions)
58
59
       def add_flow(self, datapath, priority, match, actions, buffer_id=None):
60
            ofproto = datapath.ofproto
61
62
            parser = datapath.ofproto_parser
63
            inst = [parser.OFPInstructionActions(ofproto.OFPIT_APPLY_ACTIONS,
64
65
                                                   actions)]
66
            if buffer_id:
                mod = parser.OFPFlowMod(datapath=datapath, buffer_id=buffer_id,
67
                                         priority=priority, match=match,
68
                                         instructions=inst)
69
70
            else:
```

```
mod = parser.OFPFlowMod(datapath=datapath, priority=priority,
71
                                        match=match, instructions=inst)
72
           datapath.send_msg(mod)
73
74
       def add_flow_group(self, datapath, priority, match, group_id):
75
           ofproto = datapath.ofproto
76
           parser = datapath.ofproto_parser
77
78
           actions = [parser.OFPActionGroup(group_id=group_id)]
79
           inst = [parser.OFPInstructionActions(ofproto.OFPIT_APPLY_ACTIONS,
80
       actions)]
           mod = parser.OFPFlowMod(datapath=datapath, priority=priority, match=
81
       match, instructions=inst)
           datapath.send_msg(mod)
82
```