操作系统(D)

项目 8

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设计虚拟内存管理器

1. 起步

首先将测试用的地址写入 trial.txt, 以测试 addext 内存地址分析模块的正确性。

Listing 1: src/trial.txt

```
1
256
32768
32769
128
65534
33153
```

```
logcreative@ubuntu: /mnt/hgfs/VMShared/linux/OS/Project/Projec...
Logcreative@ubuntu:/mnt/hgfs/VMShared/linux/OS/Project/Project8/src$ ./vmm trial.txt
                Page number:
Input:
                                          Offset:
           1
                                1
                                          Offset:
         256
                Page number:
                                0
Input:
Input: 32768
                Page number:
                                          Offset:
                                                    0
                Page number:
                                0
                                                    0
Input:
           0
                                          Offset:
Input: 32769
                Page number:
                                          Offset:
Input:
                Page number:
          0
                                          Offset:
Input:
         128
                Page number: 128
                                          Offset: 128
Input: 65534
                Page number: 254
                                          Offset: 254
Input:
                Page number:
                                0
                                          Offset:
                Page number: 129
Input: 33153
                                          Offset: 129
logcreative@ubuntu:/mnt/hgfs/VMShared/linux/OS/Project/Project8/src$
```

定义地址结构和地址提取器如下:

Listing 2: src/addext.h

```
#include <stdlib.h>

typedef struct address
{
   int number;
   int offset;
} add;
```

```
add addext(int _rline);
int getAdd(add _addin);
```

Listing 3: src/addext.c

```
#include "addext.h"

add addext(int _rline) {
    add add_;
    _rline = _rline & 0x0000FFFF;
    add_.number = (_rline & 0x0000FF00) >> 8;
    add_.offset = _rline & 0x000000FF;
    return add_;
}

int getAdd(add _addin) {
    return (_addin.number << 8) + _addin.offset;
}</pre>
```

2. 处理页面错误

接着, 先不考虑 TLB, 只使用页表。将输出结果与正确参考比较, 结论是正确:

首先对输入流分析,在 main 函数里的情形如下:

```
while(fgets(addline, MAXLINE, addfile)!=NULL){
   int rline = atoi(addline);
   add viradd = addext(rline);
   add phyadd = getPhyAdd(viradd);
   fprintf(stdout, "Virtual address: %d Physical address: %d Value: %d\n",
        getAdd(viradd), getAdd(phyadd), getValue(phyadd));
}
```

获取值是直接从内存中获得对应位置的值:

```
int getValue(add _phyadd) {
    return mem[_phyadd.number][_phyadd.offset];
}
```

其中 mem 是用 char 存储的:

Listing 4: src/memory.h

```
#ifndef MEMORY
#define MEMORY 1

#include <stdio.h>

#define MEMSIZE 256

#define FRAMESIZE 256

char mem[MEMSIZE][FRAMESIZE];

int read_frame(int page_number);

#endif
```

当前只使用页表是不需要考虑 TLB 的获取物理地址的函数如下:

```
add getPhyAdd(add _inadd) {
    add phyadd;

if (!page_table[_inadd.number][1])
    handle_pagefault(_inadd.number);

phyadd.number = page_table[_inadd.number][0];
phyadd.offset = _inadd.offset;
return phyadd;
}
```

一旦有页面错误就会触发对应的函数,将内容存放到内存中去:

```
void handle_pagefault(int page_number) {
   int frame_number = read_frame(page_number);
   page_table[page_number][0] = frame_number;
   page_table[page_number][1] = 1;
}
```

由于现在的内存充足,帧码直接用静态变量 frame_number 递增存储。

```
int read_frame(int page_number) {
    static int frame_number = 0;

FILE* backstore;
    if ((backstore = fopen("BACKING_STORE.bin", "rb")) == NULL) {
        fprintf(stderr, "Empty file storage!\n");
        return -1;
    }

    int frame_number_ = frame_number++;
    long pos = page_number * FRAMESIZE;
    fseek(backstore, pos, SEEK_SET);
    fread(mem[frame_number_], sizeof(char), FRAMESIZE, backstore);
    fclose(backstore);

    return frame_number_;
}
```

这里使用了二进制文件读取的方式复制到内存中去。

3. 使用 TLB

使用 test.sh 脚本进行相同的测试后,结果仍然是一致的。

Listing 5: src/test.sh

```
make
./vmm addresses.txt > test.txt
diff test.txt correct.txt -s
```

首先,输入流分析被重定向到 TLB 对应的接口。

```
add getPhyAdd(add _inadd) {
   add phyadd;

   phyadd.number = tlb_search(_inadd.number);
   phyadd.offset = _inadd.offset;

   return phyadd;
}
```

TLB 由 16 个内存块组成。

Listing 6: src/tlb.h

```
#ifndef TLB_GUARD
#define TLB_GUARD 1

#include "pagetab.h"
#include "lru.h"

#define TLBSIZE 16

// TLB[i][2] - isOccupied:
// 0 - empty
// 1 - occupied
int TLB[TLBSIZE][3];

int tlb_search(int page_number);

#endif // !TLB_GUARD
```

而最主要的 tlb_search 函数首先会尝试 TLB 命中,接着如果是 TLB 未命中,就看需不需要触发页面缺失,然后看是否由空余 TLB 空间用于存储到 TLB 中。如果 TLB 满,就会使用 LRU 算法进行 TLB 置换。

Listing 7: src/tlb.c

```
#include "tlb.h"
int tlb_search(int page_number) {
   static struct used_node* tlb_head = NULL;
   static struct used_node* tlb_tail = NULL;
   int result = -1;
   for (int i = 0; i < TLBSIZE; ++i) {</pre>
       if (TLB[i][2]
                            // is occupied
           && TLB[i][0] == page_number) {
          result = i:
           break;
       }
   }
   if (result >= 0) {
                            // TLB hit
       search_pop(&tlb_head, &tlb_tail, page_number);
       push(&tlb_head, &tlb_tail, page_number);
       return TLB[result][1];
   }
   else {
                             // TLB miss
       if (!page_table[page_number][1]) // page fault
           handle_pagefault(page_number);
       int frame_number = page_table[page_number][0];
       int hole = -1;
       for (int i = 0; i < TLBSIZE; ++i)</pre>
           if (!TLB[i][2]) { // is empty
              hole = i;
              break;
           }
       if (hole >= 0) {
           TLB[hole][0] = page_number;
           TLB[hole][1] = frame_number;
          TLB[hole][2] = 1;
          push(&tlb_head, &tlb_tail, page_number);
       } else {
                             // full TLB
           // LRU Algorithm
           int least_used = bottom_pop(&tlb_head, &tlb_tail);
           int least_used_index = 0;
           for (; TLB[least_used_index][0] != least_used; ++least_used_index);
           TLB[least_used_index][0] = page_number;
           TLB[least_used_index][1] = frame_number;
           push(&tlb_head, &tlb_tail, page_number);
       }
       return frame_number;
```

```
}
}
```

对于 TLB 使用状态使用了双向链表式栈存储,记录头 tlb_head 和尾 tlb_tail。对应的 LRU 操作具有如下定义:

Listing 8: src/lru.h

```
#ifndef LRU
#define LRU 1

#include <stdlib.h>

struct used_node {
    int page_number;
    struct used_node* prev;
    struct used_node* next;
};

void search_pop(struct used_node** head, struct used_node** tail, int page_number);

void push(struct used_node** head, struct used_node** tail, int page_number);

int bottom_pop(struct used_node** head, struct used_node** tail);

#endif
```

- search_pop 将会寻找对应的栈节点,并移除。
- push 入栈操作。
- bottom_pop 栈底出栈。

Listing 9: src/lru.c

```
#include "lru.h"
void search_pop(struct used_node** head, struct used_node** tail, int page_number) {
   struct used_node* tmp = *head;
   while (tmp && tmp->page_number != page_number)
       tmp = tmp->next;
   if (!tmp) return;
   if (*head == *tail) {
       *head = *tail = NULL;
       return;
   if (tmp == *head) {
       tmp->next->prev = tmp->prev;
       *head = tmp->next;
   else if (tmp == *tail) {
       tmp->prev->next = tmp->next;
       *tail = tmp->prev;
   }
   else {
```

```
tmp->next->prev = tmp->prev;
       tmp->prev->next = tmp->next;
   }
   free(tmp);
}
void push(struct used_node** head, struct used_node** tail, int page_number) {
   struct used_node* new_node = (struct used_node*)malloc(sizeof(struct used_node));
   new_node->page_number = page_number;
   new_node->prev = NULL;
   new_node->next = NULL;
   if (!*head) {
       *head = *tail = new_node;
       return;
   }
   new_node->next = *head;
   (*head)->prev = new_node;
   *head = new_node;
}
int bottom_pop(struct used_node** head, struct used_node** tail) {
   if (!*tail) return -1;
   int bottom = (*tail)->page_number;
   if (*head == *tail) {
       *head = *tail = NULL;
      return bottom;
   *tail = (*tail)->prev;
   free((*tail)->next);
   (*tail)->next = NULL;
   return bottom;
}
```