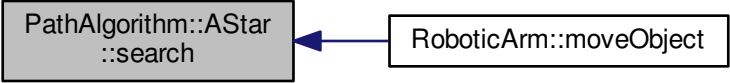


PathAlgorithm::AStar
::search

RoboticArm::moveObject



```
graph LR; A[RoboticArm::moveObject] --> B[PathAlgorithm::AStar::search];
```

The diagram consists of two rectangular boxes connected by a horizontal arrow. The box on the left is shaded gray and contains the text 'PathAlgorithm::AStar' on the top line and '::search' on the bottom line. The box on the right is white and contains the text 'RoboticArm::moveObject'. A blue arrow points from the right box to the left box, indicating a call or dependency.