Image_Generation

October 20, 2022

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[]: import tensorflow as tf
     from tensorflow import keras
     from keras import datasets, layers, models, losses, Model
     from keras.models import load model
     import matplotlib.pyplot as plt
     %matplotlib inline
     from matplotlib.axis import Axis
     import numpy as np
     import random
     import PIL
     from PIL import Image
[]: # Load data, we only need the training images.
     from keras.datasets.mnist import load_data
     (X_train, _), (_, _) = load_data()
     print('Train Shape: ', X_train.shape)
     print(X_train[0].shape)
[]: # Reshape the images for the CNN.
     X_train = tf.expand_dims(X_train, axis=3)
     print('Train Shape: ', X_train.shape)
     print(X_train[0].shape)
[]: # Standardize the pixel values
     X_train = X_train.numpy().astype('float32') / 255.0
[]: # Construct the discriminator.
     input_img = keras.Input(shape=(256,256, 1))
     conv1 = layers.Conv2D(16, (7,7), (2,2), padding='same',
                                   activation=layers.LeakyReLU(alpha=0.2))(input_img)
     drop1 = layers.Dropout(rate=0.30)(conv1)
     conv2 = layers.Conv2D(32, (5,5), (2,2), padding='same',
                                   activation=layers.LeakyReLU(alpha=0.2))(drop1)
     drop2 = layers.Dropout(rate=0.35)(conv2)
     conv3 = layers.Conv2D(64, (5,5), (2,2), padding='same',
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[]: D.summary()

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[]: # Construct the generator.
     random_input = keras.Input(shape=200)
     Dense1 = layers.Dense(units = 32*32*32)(random_input)
     B_Norm1 = layers.BatchNormalization()(Dense1)
     Relu1 = layers.Activation('relu')(B_Norm1)
     Reshape1 = layers.Reshape((32,32,32))(Relu1)
     Drop1 = layers.Dropout(0.35)(Reshape1)
     Up1 = layers.UpSampling2D((2, 2))(Drop1)
     DeConv1 = layers.Conv2DTranspose(filters=32, kernel_size=(7, 7), strides=1,__
      →padding='same')(Up1)
     B_Norm2 = layers.BatchNormalization()(DeConv1)
     Relu2 = layers.Activation('relu')(B_Norm2)
     Up2 = layers.UpSampling2D((2, 2))(Relu2)
     DeConv2 = layers.Conv2DTranspose(filters=16, kernel_size=(7, 7), strides=1, ____
      →padding='same')(Up2)
     B_Norm3 = layers.BatchNormalization()(DeConv2)
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Relu3 = layers.Activation('relu')(B_Norm3)
     Up3 = layers.UpSampling2D((2, 2))(Relu3)
     DeConv3 = layers.Conv2DTranspose(filters=8, kernel_size=(7, 7), strides=1, ___
      →padding='same')(Up3)
     B_Norm4 = layers.BatchNormalization()(DeConv3)
     Relu4 = layers.Activation('relu')(B_Norm4)
     output_img = layers.Conv2DTranspose(filters=1, kernel_size=(5, 5), strides=1,__
      →padding='same',
      ⇔activation='sigmoid')(Relu4)
     G = keras.Model(inputs=random_input, outputs=output_img)
[]: G.summary()
[]: # Join the discriminator and generator, forming the final GAN model.
     latent_input = keras.Input(shape=200)
     gen = G
     disc = D
     img = gen(latent_input)
     disc.trainable = False
     score = disc(img)
     GAN = keras.Model(inputs = latent_input, outputs=score)
     GAN.compile(loss='binary_crossentropy', optimizer=keras.optimizers.
      →Adam(learning_rate=0.0004), metrics=['accuracy'])
[]: GAN.summary()
[]: # Function retrieves a random sample of real images from the training data.
     def getRealSamples(batchSizeIn):
         indices = random.sample(range(X_train.shape[0]), k=int(batchSizeIn))
         X_real = X_train[indices]
         y_real = np.ones((int(batchSizeIn), 1))
         return X_real, y_real
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[]: # Function returns a sample of latent points from a normal distribution.
     def getLatentSamples(num_samples):
         latent = np.random.normal(size=(200*int(num_samples)))
         latent = np.reshape(latent, (int(num_samples), 200))
         labels = np.ones((int(num_samples), 1))
         return latent, labels
[]: # Function imputs latent data into the generator and returns the fake image
     ⇔samples outputted
     # by the generator.
     def getFakeSamples(num_samples, Gin):
         num_samples = int(num_samples)
         latent_input, _ = getLatentSamples(num_samples)
         output_img = Gin.predict(latent_input)
         output_labels = np.zeros((num_samples, 1))
         return output_img, output_labels
[]: # Function plots a sample of 16 'predicted' images from the trained generator.
     def pred_plot(Gin):
         x, _ = getLatentSamples(1)
         gen_images = Gin.predict(x)
         plt.figure(figsize=(6, 6))
         for i in range(1):
             ax = plt.subplot()
             plt.imshow(gen_images.reshape((256,256,1)), cmap='gray')
             ax.get_xaxis().set_visible(False)
             ax.get_yaxis().set_visible(False)
         plt.show()
[]: # Function plots the networks loss values with respect to epoch.
     def loss plot(dLossIn, gLossIn):
         fig, ax = plt.subplots(figsize=(12, 8))
         ax.plot(dLossIn, label='Discriminator Loss')
         ax.plot(gLossIn, label='GAN (generator) Loss')
         ax.legend()
         ax.set_xlim(xmin=-5, xmax=305)
         ax.set_ylim(ymin=-0.2, ymax=1.2)
         plt.xlabel('Epoch')
         plt.ylabel('Loss value')
         plt.title("Loss value vs Epoch for Generator and Discriminator")
         plt.show()
[]: | # Lists to store the models loss values at the end of each epoch
     dLoss = list()
     gLoss = list()
     img = Image.open("C:\\Users\\ltnoo\\Desktop\\final.jpg")
     img.load()
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img = img.convert(mode='L')
     img = np.asarray(img).reshape(256,256,1)
     img = img.astype("float32") / 255.0
     # Function trains the GAN (generator) model.
     def trainGAN(G, D, GAN, num_epochs, batchSize):
         d_loss = float()
         g_loss = float()
         batches_per_epoch = 128
         for epoch in range(num_epochs):
             for batch in range(batches_per_epoch):
                 #X_real, y_real = getRealSamples(batchSize / 2)
                 X_real, y_real = [img] * int(batchSize / 2), np.ones((int(batchSize_
      4/2), 1))
                 X_fake, y_fake = getFakeSamples(batchSize / 2, G)
                 X_combined, y_combined = np.vstack((X_real, X_fake)), np.
      ⇔vstack((y_real, y_fake))
                 d_loss, _ = D.train_on_batch(X_combined, y_combined)
                 X_latent, y_latent = getLatentSamples(batchSize)
                 g_loss, _ = GAN.train_on_batch(X_latent, y_latent)
                 if (batch % 64 == 0) | (batch == 0):
                     print('Epoch %d: , %d/%d, d_loss = %.3f, g_loss = %.3f' %_
      \hookrightarrow (epoch+1, batch+1,
                                                                 batches_per_epoch,_
      ⇔d_loss, g_loss))
             #dLoss.append(d_loss)
             #qLoss.append(q_loss)
             if (epoch % 2 == 0) | (epoch == 0):
                 pred_plot(G)
                 #filename = 'generator_model_%03d.h5' % (epoch + 1)
                 #GAN.save(filename)
                 G.save('Generator.h5')
[]: trainGAN(load_model('Generator.h5'), D, GAN, 13, 128)
[]: g = load_model('Generator.h5')
     g.compile()
[]: x, _ = getLatentSamples(1)
     pred = g.predict(x)
     pred = pred.reshape((256,256,1))
    1/1 [======= ] - 6s 6s/step
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[]: (256, 256, 1)

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[]: original_img = Image.open("train_img.JPG")
    converted = original_img.convert(mode="1")
    fig, ax = plt.subplots(1,2,figsize=(7,7))
    ax[0].imshow(pred, cmap='gray')
    ax[1].imshow(converted, cmap='gray')
    plt.show()
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