

# LOGAN E. BEAVER

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## OBJECTIVE

To obtain a full time position as a graduate research assistant at a top tier institution with the intent of obtaining a Ph.D. in robotics. A position that utilizes my current robotics and computer science background and allows me to advance the state of the art in robotics by making novel contributions to the field.

## EDUCATION

May 2015 **Milwaukee School of Engineering**, B.S., Mechanical Engineering: GPA: 3.304 Milwaukee, WI

## RESEARCH EXPERIENCE

**Joy Global Inc., Surface Mining**, Robotics Research Co-Op May 2014-Present

- Implemented SLAM using LIDAR data as part of a proof of concept object detection algorithm
- Designed and implemented an automated calibration procedure for a mining shovel collision avoidance system
- Developed an optimized particle filter algorithm for use in multiple products currently under development

**Milwaukee School of Engineering**, Capstone Research Project 2014-Present

- Leading a four person senior design team in the development of a pneumatically driven walking robot
- Derived the forward and inverse kinematics of the robot for design verification and analysis

## PROJECT EXPERIENCE

**Milwaukee School of Engineering Game Development Crew**, President 2014-Present

- Partnered with Time Warner Cable and Discovery World to lead the first ever *Science of Videogames* exhibit for STEMfest and the Connect a Million Minds initiative
- Created a custom OpenGL graphical pipeline for use in current 3D Java applications
- Utilized behavior trees to develop a dynamic artificial intelligence baseline for all projects

**Ludum Dare**, Online Game Jam 2013

- Led a four person team to construct a complete game within a 72 hour timespan
- Rapidly prototyped and iterated game architecture and mechanics from scratch

**Milwaukee School of Engineering**, Notable Class Projects 2012-2013

- Modeled the flight path of the first three stages of a Saturn V rocket through earth's atmosphere
- Developed and analyzed a stochastic model of a wholesale club checkout line to improve its efficiency
- Integrated stepper motors with user input to control the position of a solar cell in 2D space
- Developed a state machine architecture to allow a robot arm to track the position of a solar cell

## AWARDS

- **Who's Who Among Students in American Universities and Colleges**, Nominee 2015
- **Milwaukee School of Engineering Dean's List** 2011-2014
  - Awarded quarterly to Milwaukee School of Engineering students for outstanding academic achievement

## PROGRAMMING SKILLS

- Expert at using Java and MATLAB for large projects
- Proficient with LabVIEW from multiple projects at Joy Global, Inc.
- Experienced with complex data structures such as Lists, Trees, Maps, Queues, Stacks, and Threads
- Some experience with C#/Python scripting through the Unity game engine and miscellaneous projects
- Minor experience with header files, pointers, and memory management in C/C++