

## **Cross Compiling Ubuntu Kernel & Prophesee device drivers**

Detail Document - 02 for Kria-App

## **Ubuntu Kernel Corss Compilation Steps:**

This document is on how to cross-compile ubuntu kernel in Host PC. For updating the Prophesee camera driver and camera operation inside Kria-Ubuntu, we have to re-build the Kria-Ubuntu kernel with the necessary support for custom camera driver.

Steps for cross compiling linux kernel from source as mentioned here: Rebuilding+the+Certified+Ubuntu+for+Xilinx+Devices+20.04+LTS+Kernel+from+Source

Above link is used for `Ubuntu 20.04 LTS`: focal , which was changed to `jammy` corresponding to `Ubuntu 22.04`

So terminal command used:

```
echo "deb-src http://archive.ubuntu.com/ubuntu jammy main" | sudo tee -a
/etc/apt/sources.list.d/jammy.list

sudo apt-get update

sudo apt-get build-dep linux

sudo apt-get install git fakeroot libncurses-dev gcc-aarch64-linux-gnu
linux-tools-common

git clone
https://git.launchpad.net/~canonical-kernel/ubuntu/+source/linux-xilinx-zyn
qmp/+git/jammy
```

This will create 'jammy' folder containing linux kernel source code...

Next selected the kernel branch as currently running in kria board:

```
cd jammy
git tag
```



```
git checkout Ubuntu-xilinx-zynqmp-5.15.0-1027.31

export ARCH=arm64
export $(dpkg-architecture -aarm64)
export CROSS_COMPILE=aarch64-linux-gnu-
```

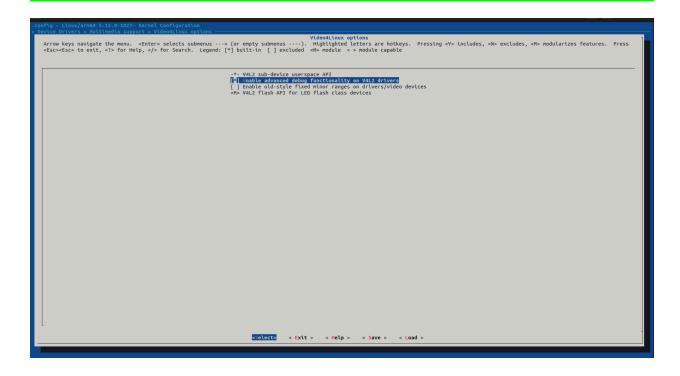
Next configure the kernel by running following commands:

fakeroot debian/rules clean fakeroot debian/rules editconfigs do\_enforce\_all=false

Update the cross compiled linux kernel with CONFIG\_VIDEO\_ADV\_DEBUG config enabled:

```
Symbol: VIDEO_ADV_DEBUG [=y]
Type : bool
Defined at drivers/media/v4l2-core/Kconfig:28
  Prompt: Enable advanced debug functionality on V4L2 drivers
  Depends on: MEDIA_SUPPORT [=y]
  Visible if: MEDIA_SUPPORT [=y] && VIDEO_DEV [=y]
  Location:
    -> Device Drivers
    -> Multimedia support (MEDIA_SUPPORT [=y])
(2)    -> Video4Linux options
```





fakeroot debian/rules clean fakeroot debian/rules binary

Note:

Error during build:

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mkdir

/home/logictronix03/ubuntu\_workspace/jammy\_custom/jammy/debian/linux-libc-dev/usr/include/aarch64-linux-gnu

mkdir: cannot create directory

'/home/logictronix03/ubuntu\_workspace/jammy\_custom/jammy/debian/linux-libc-dev/usr/include/aarch64-linux-gnu': File exists

make: \*\*\* [debian/rules.d/2-binary-arch.mk:569: install-arch-headers] Error 1

Soln:

Remove the aarch64-linux-gnu directory using rm -rf command:

rm -rf

/home/logictronix03/ubuntu\_workspace/jammy\_custom/jammy/debian/linux-libc-dev/usr/include/aarch64-linux-gnu

After build is complete \*.deb files are found outside ubuntu kernel folder `jammy` folder:



```
logictronkx03(ojcktronkx03:-/ubuntu_workspace/jammy_custom$ is *deb
linux-buildinfo-5.15.0-027.xillinx-zynqnp_5.15.0-1027.3i_arm64.deb
linux-headers-5.15.0-1027.xillinx-zynqnp_5.15.0-1027.3i_arm64.deb
linux-headers-5.15.0-1027.xillinx-zynqnp_5.15.0-1027.3i_arm64.deb
linux-kilinx-zynqnp-headers-5.15.0-1027.3i_all.deb
linux-kilinx-zynqnp-headers-5.15.0-1027.3i_all.deb
linux-kilinx-zynqnp-headers-5.15.0-1027.3i_all.deb
linux-kilinx-zynqnp-tools-common_5.15.0-1027.3i_all.deb
linux-kilinx-zynqnp-tools-common_5.15.0-1027.3i_all.deb
```

Also kernel build directory is found at : `jammy/debian/build/build-xilinx-zynqmp/` which is needed to cross compile the device drivers.

After build is completed, copy the \*.deb file to Kria target board.

Install the kernel files by running following command:

```
sudo dpkg -i *.deb
...

Then reboot the system:
...
sudo reboot
```



## **Cross Compiling Prophesee device drivers:**

Prophesee device driver consist of following drivers:

- Prophesee ccam5 sensor driver:
  - Sensor driver repository : <a href="https://github.com/prophesee-ai/linux-sensor-drivers">https://github.com/prophesee-ai/linux-sensor-drivers</a>
- Prophesee video drivers
  - for processing event data from sensor and v4l2 compatible video device.
  - Video driver repository : <a href="https://github.com/prophesee-ai/zyng-video-drivers">https://github.com/prophesee-ai/zyng-video-drivers</a>

Get the drivers using git commands:

```
git clone https://github.com/prophesee-ai/linux-sensor-drivers
git clone https://github.com/prophesee-ai/zynq-video-drivers
```

First setup the KERNEL\_SRC and arm64 environment variable to linux kernel build directory:

```
export KERNEL_SRC=<path of
workspace>/jammy/debian/build/build-xilinx-zynqmp/
export ARCH=arm64
  export $(dpkg-architecture -aarm64)
  export CROSS_COMPILE=aarch64-linux-gnu-
```

Building Prophese device drivers:

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```
cd linux-sensor-drivers
make
```

Here is the log of the device driver build:

```
logictronix03glogictronix03:-/ubuntu_workspace/linux-sensor-drivers make
make - C /home/logictronix03/ubuntu_workspace/jammy_custom/jammy/debian/build/build-xilinx-zynqmp/ M=/home/logictronix03/ubuntu_workspace/jammy_custom/jammy/debian/build/build-xilinx-zynqmp'

CC [M] /home/logictronix03/ubuntu_workspace/jammy_custom/jammy/debian/build/build-xilinx-zynqmp'

CC [M] /home/logictronix03/ubuntu_workspace/linux-sensor-drivers/mox636.o

MODPDST /home/logictronix03/ubuntu_workspace/linux-sensor-drivers/mox636.nod.o

LD [M] /home/logictronix03/ubuntu_workspace/linux-sensor-drivers/inx636.ko

BTF [M] /home/logictronix03/ubuntu_workspace/linux-sensor-drivers/inx636.ko

BTF [M] /home/logictronix03/ubuntu_workspace/linux-sensor-drivers/inx636.ko

COPYING inx636.c inx636.ko inx636.mod inx636.mod.c inx636.mod.o inx636.o Makefile modules.order Module.symvers psee-format.h sony,inx636.yaml

logictronix03:/ubuntu_workspace/linux-sensor-drivers/six66.o Makefile modules.order Module.symvers psee-format.h sony,inx636.yaml

logictronix03:/ubuntu_workspace/linux-sensor-drivers/six66.o Makefile modules.order Module.symvers psee-format.h sony,inx636.yaml
```

Above build creates kernel driver: 'imx636.ko'



Next building video drivers:

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cd zynq-video-driver

make

Above build fails with undeclared media bus type error:

```
Logictronix83/bounts.com/sas-/instructions/sas-/sas-/instructions/sas-/sas-/instructions/sas-/sas-/instructions/sas-/sas-/instructions/sas-/sas-/instructions/sas-/instructions/sas-/instructions/sas-/instructions/sas-/instructions/sas-/instructions/sas-/instructions/sas-/instructions/sas-/instructions/sas-/instructions/sas-/instructions/sas-/instructions/sas-/instructions/sas-/instructions/sas-/instructions/sas-/instructions/sas-/instructions/sas-/instructions/sas-/instructions/sas-/instructions/sas-/instructions/sas-/instructions/sas-/instructions/sas-/instructions/sas-/instructions/sas-/instructions/sas-/instructions/sas-/instructions/sas-/instructions/sas-/instructions/sas-/instructions/sas-/instructions/sas-/instructions/sas-/instructions/sas-/instructions/sas-/instructions/sas-/instructions/sas-/instructions/sas-/instructions/sas-/instructions/sas-/instructions/sas-/instructions/sas-/instructions/sas-/instructions/sas-/instructions/sas-/instructions/sas-/instructions/sas-/instructions/sas-/instructions/sas-/instructions/sas-/instructions/sas-/instructions/sas-/instructions/sas-/instructions/sas-/instructions/sas-/instructions/sas-/instructions/sas-/instructions/sas-/instructions/sas-/instructions/sas-/instructions/sas-/instructions/sas-/instructions/sas-/instructions/sas-/instructions/sas-/instructions/sas-/instructions/sas-/instructions/sas-/instructions/sas-/instructions/sas-/instructions/sas-/instructions/sas-/instructions/sas-/instructions/sas-/instructions/sas-/instructions/sas-/instructions/sas-/instructions/sas-/instructions/sas-/instructions/sas-/instructions/sas-/instructions/sas-/instructions/sas-/instructions/sas-/instructions/sas-/instructions/sas-/instructions/sas-/instructions/sas-/instructions/sas-/instructions/sas-/instructions/sas-/instructions/sas-/instructions/sas-/instructions/sas-/instructions/sas-/instructions/sas-/instructions/sas-/instructions/sas-/instructions/sas-/instructions/sas-/instructions/sas-/instructions/sas-/instructions/sas-/instructions/sas-/instructions/sas-/instruction
```

It can be solved by adding 'psee-format.h' header in 'psee-tkeep-handler.c' file:

```
#include <linux/device.h>
#include <linux/module.h>
#include <linux/of.h>
#include <linux/platform_device.h>
#include <linux/clk.h>
#include <media/v4l2-async.h>
#include <media/v4l2-subdev.h>
#include "psee-format.h"
#define PAD_SINK 0
#define PAD_SOURCE 1
#define REG VERSION
                                     (0x0)
#define REG_CONTROL
                                     (0x4)
#define BIT_ENABLE
#define BIT_BYPASS
#define BIT_CLEAR
                                     BIT(0)
                                        T(1)
                                     BIT(2)
#define REG_CONFIG
                                    (0x8)
```

Then running 'make' command driver is compiled and build:



After Prophesee Video driver build, following linux driver modules are created:

- psee-csi2rxss.ko
- psee-streamer.ko
- psee-tkeep-handler.ko
- psee-video.ko

To use the Prophesee drivers, copy all the \*.ko file to Kria Ubuntu /lib/modules/5.15.0-1027-xilinx-zynqmp/ folder.