1) Fic sixtemal
$$\begin{cases} x_1^2 = \frac{1}{4}x_1 + \frac{1}{4}x_2 \\ x_2^2 = -\frac{3}{4}x_1 + \ln t \end{cases}$$
 (2)

a) Jorieti forma nutriciala a esistemului.

b) Artisto ca prin solubaria de valiabila $t = e^t$ se obtine un sistema cu coeficient constanti pertru partia liviara.

e) Astir minosi solutia generala poutru sistemul de la 6), que, pentru sistemul initial obstruinosi solutia generala si solutia care rerifica $(x_1, x_2) = 1$

a) $x' = Acti \cdot x + b(t)$
 $\begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \begin{pmatrix} t & t \\ t & -1 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} + \begin{pmatrix} 0 \\ 0 \\ t \end{pmatrix}$

(lher-curs 8) Isaca sistemul livial rangen are $A(t) = 1$. printe -0 solvimbore she variabila en durina sistem cu coeficiati constant, atunci se aplica metoda en valori proprio, reveind opin coupta solvimbori de mariabila.

 $A(t) = \frac{1}{4} \cdot \begin{pmatrix} 1 & 2 \\ -2 & -3 \end{pmatrix} = \frac{1}{4} \cdot 8$, $\frac{1}{2} \cdot (t) = \begin{pmatrix} 0 \\ 1 & t \end{pmatrix}$
 $\frac{1}{2} \cdot (x_1 - 3) = \frac{1}{4} \cdot 8$, $\frac{1}{2} \cdot (t) = \begin{pmatrix} 0 \\ 1 & t \end{pmatrix}$
 $\frac{1}{2} \cdot (x_1 - 3) = \frac{1}{4} \cdot 8$, $\frac{1}{2} \cdot (t) = \begin{pmatrix} 0 \\ 1 & t \end{pmatrix}$
 $\frac{1}{2} \cdot (x_1 - 3) = \frac{1}{4} \cdot 8$, $\frac{1}{2} \cdot (x_1 - 3) = \begin{pmatrix} 0 \\ 1 & t \end{pmatrix}$
 $\frac{1}{2} \cdot (x_1 - 3) = \frac{1}{4} \cdot 8$, $\frac{1}{2} \cdot (x_1 - 3) = \begin{pmatrix} 0 \\ 1 & t \end{pmatrix}$
 $\frac{1}{2} \cdot (x_1 - 3) = \frac{1}{4} \cdot 8$, $\frac{1}{2} \cdot (x_1 - 3) = \begin{pmatrix} 0 \\ 1 & t \end{pmatrix}$
 $\frac{1}{2} \cdot (x_1 - 3) = \frac{1}{4} \cdot 8$, $\frac{1}{2} \cdot (x_1 - 3) = \begin{pmatrix} 0 \\ 1 & t \end{pmatrix}$
 $\frac{1}{2} \cdot (x_1 - 3) = \frac{1}{4} \cdot 8$, $\frac{1}{2} \cdot (x_1 - 3) = \begin{pmatrix} 0 \\ 1 & t \end{pmatrix}$
 $\frac{1}{2} \cdot (x_1 - 3) = \begin{pmatrix} 0 \\ 1 & t \end{pmatrix}$
 $\frac{1}{2} \cdot (x_1 - 3) = \begin{pmatrix} 0 \\ 1 & t \end{pmatrix}$
 $\frac{1}{2} \cdot (x_1 - 3) = \begin{pmatrix} 0 \\ 1 & t \end{pmatrix}$
 $\frac{1}{2} \cdot (x_1 - 3) = \begin{pmatrix} 0 \\ 1 & t \end{pmatrix}$
 $\frac{1}{2} \cdot (x_1 - 3) = \begin{pmatrix} 0 \\ 1 & t \end{pmatrix}$
 $\frac{1}{2} \cdot (x_1 - 3) = \begin{pmatrix} 0 \\ 1 & t \end{pmatrix}$
 $\frac{1}{2} \cdot (x_1 - 3) = \begin{pmatrix} 0 \\ 1 & t \end{pmatrix}$
 $\frac{1}{2} \cdot (x_1 - 3) = \begin{pmatrix} 0 \\ 1 & t \end{pmatrix}$
 $\frac{1}{2} \cdot (x_1 - 3) = \begin{pmatrix} 0 \\ 1 & t \end{pmatrix}$
 $\frac{1}{2} \cdot (x_1 - 3) = \begin{pmatrix} 0 \\ 1 & t \end{pmatrix}$
 $\frac{1}{2} \cdot (x_1 - 3) = \begin{pmatrix} 0 \\ 1 & t \end{pmatrix}$
 $\frac{1}{2} \cdot (x_1 - 3) = \begin{pmatrix} 0 \\ 1 & t \end{pmatrix}$
 $\frac{1}{2} \cdot (x_1 - 3) = \begin{pmatrix} 0 \\ 1 & t \end{pmatrix}$
 $\frac{1}{2} \cdot (x_1 - 3) = \begin{pmatrix} 0 \\ 1 & t \end{pmatrix}$
 $\frac{1}{2} \cdot (x_1 - 3) = \begin{pmatrix} 0 \\ 1 & t \end{pmatrix}$
 $\frac{1}{2} \cdot (x_1 - 3) = \begin{pmatrix} 0 \\ 1 & t \end{pmatrix}$
 $\frac{1}{2} \cdot (x_1 - 3) = \begin{pmatrix} 0 \\ 1 & t \end{pmatrix}$

t = e =) s = het

s(t) = lnt =) s'(t) = 1

x'ch = (y sch)) = g'(sch). s'(t) = y'(s). \frac{1}{4} = \frac{1}{4}. y'(s)

x(t)= y(1(t))

Scanned with CamScanner

Siteral device:
$$\frac{1}{2} = \frac{1}{2} = \frac{1}{2} = \frac{1}{2} + \frac{1}{2} = \frac{1}{2}$$

Scanned with CamScanner

$$\Rightarrow \begin{pmatrix} (1+2s)e^{-3} & 2se^{-3} \\ (1-2s)e^{-3} & (1-2s)e^{-3} \end{pmatrix} \cdot \begin{pmatrix} c_1^2 \\ c_2^2 \end{pmatrix} = \begin{pmatrix} c_1 \\ c_2 \end{pmatrix} = \begin{pmatrix} (1+2s)e^{-3} \\ (1+2s)e^{-3} \\ c_1^2 + (1-2s)e^{-3}c_2^2 + 2e^{-3}c_2^2 = 2e^{-3} \end{pmatrix} = \begin{pmatrix} (1+2s)e^{-3} \\ (1+2s)e^{-3} \\ c_1^2 + (1-2s)e^{-3}c_2^2 + 2e^{-3}c_2^2 = 2e^{-3} \\ \end{pmatrix} = \begin{pmatrix} (1+2s)e^{-3} \\ (1+2s)e^{-3} \\ c_1^2 + (1-2s)e^{-3}c_2^2 + 2e^{-3}c_2^2 = 2e^{-3} \\ \end{pmatrix} = \begin{pmatrix} (1+2s)e^{-3} \\ c_1^2 + c_2^2 \\ c_2^2 + c_2^2 \\ c_3^2 + c_3^2 + c_3^2 + c_3^2 + c_3^2 \\ \end{pmatrix} = \begin{pmatrix} (1+2s)e^{-3} \\ c_1^2 + c_2^2 \\ c_3^2 + c_3^2 + c_3^2 \\ \end{pmatrix} = \begin{pmatrix} (1+2s)e^{-3} \\ c_1^2 + c_3^2 \\ \end{pmatrix} = \begin{pmatrix} (1+2s)e^{-3} \\ c_1^2 + c_3^2 \\ \end{pmatrix} = \begin{pmatrix} (1+2s)e^{-3} \\ c_1^2 + c_3^2 \\ \end{pmatrix} = \begin{pmatrix} (1+2s)e^{-3} \\ c_1^2 + c_3^2 \\ \end{pmatrix} = \begin{pmatrix} (1+2s)e^{-3} \\ c_1^2 + c_3^2 \\ \end{pmatrix} = \begin{pmatrix} (1+2s)e^{-3} \\ c_1^2 + c_3^2 \\ \end{pmatrix} = \begin{pmatrix} (1+2s)e^{-3} \\ c_1^2 + c_3^2 \\ \end{pmatrix} = \begin{pmatrix} (1+2s)e^{-3} \\ c_1^2 + c_3^2 \\ \end{pmatrix} = \begin{pmatrix} (1+2s)e^{-3} \\ c_1^2 + c_3^2 \\ \end{pmatrix} = \begin{pmatrix} (1+2s)e^{-3} \\ c_1^2 + c_3^2 \\ \end{pmatrix} = \begin{pmatrix} (1+2s)e^{-3} \\ c_1^2 + c_3^2 \\ \end{pmatrix} = \begin{pmatrix} (1+2s)e^{-3} \\ c_1^2 + c_3^2 \\ \end{pmatrix} = \begin{pmatrix} (1+2s)e^{-3} \\ c_1^2 + c_3^2 \\ \end{pmatrix} = \begin{pmatrix} (1+2s)e^{-3} \\ c_1^2 + c_3^2 \\ \end{pmatrix} = \begin{pmatrix} (1+2s)e^{-3} \\ c_1^2 + c_3^2 \\ \end{pmatrix} = \begin{pmatrix} (1+2s)e^{-3} \\ c_1^2 + c_3^2 \\ \end{pmatrix} = \begin{pmatrix} (1+2s)e^{-3} \\ c_1^2 + c_3^2 \\ \end{pmatrix} = \begin{pmatrix} (1+2s)e^{-3} \\ c_1^2 + c_3^2 \\ \end{pmatrix} = \begin{pmatrix} (1+2s)e^{-3} \\ c_1^2 + c_3^2 \\ \end{pmatrix} = \begin{pmatrix} (1+2s)e^{-3} \\ c_1^2 + c_3^2 \\ \end{pmatrix} = \begin{pmatrix} (1+2s)e^{-3} \\ c_1^2 + c_2^2 \\ \end{pmatrix} = \begin{pmatrix} (1+2s)e^{-3} \\ c_1^2 + c_2^2 \\ \end{pmatrix} = \begin{pmatrix} (1+2s)e^{-3} \\ c_1^2 + c_2^2 \\ \end{pmatrix} = \begin{pmatrix} (1+2s)e^{-3} \\ c_1^2 + c_2^2 \\ \end{pmatrix} = \begin{pmatrix} (1+2s)e^{-3} \\ c_1^2 + c_2^2 \\ \end{pmatrix} = \begin{pmatrix} (1+2s)e^{-3} \\ c_1^2 + c_2^2 \\ \end{pmatrix} = \begin{pmatrix} (1+2s)e^{-3} \\ c_1^2 + c_2^2 \\ \end{pmatrix} = \begin{pmatrix} (1+2s)e^{-3} \\ c_1^2 + c_2^2 \\ \end{pmatrix} = \begin{pmatrix} (1+2s)e^{-3} \\ c_1^2 + c_2^2 \\ \end{pmatrix} = \begin{pmatrix} (1+2s)e^{-3} \\ c_1^2 + c_2^2 \\ \end{pmatrix} = \begin{pmatrix} (1+2s)e^{-3} \\ c_1^2 + c_2^2 \\ \end{pmatrix} = \begin{pmatrix} (1+2s)e^{-3} \\ c_1^2 + c_2^2 \\ \end{pmatrix} = \begin{pmatrix} (1+2s)e^{-3} \\ c_1^2 + c_2^2 \\ \end{pmatrix} = \begin{pmatrix} (1+2s)e^{-3} \\ c_1^2 + c_2^2 \\ \end{pmatrix} = \begin{pmatrix} (1+2s)e^{-3} \\ c_1^2 + c_2^2 \\ \end{pmatrix} = \begin{pmatrix} (1+2s)e^{-3} \\ c_1^2 + c_2^2 \\ \end{pmatrix} = \begin{pmatrix} (1+2s)e^{-3} \\ c_1^2 + c_2^2 \\ \end{pmatrix} = \begin{pmatrix} (1+2s)e^{-3} \\ c_1^2 + c_2^2 \\ \end{pmatrix} = \begin{pmatrix} (1+2s)e^{-3} \\ c_1^2 + c_2^2 + c_2^2 \\ \end{pmatrix} = \begin{pmatrix} (1+2s)e^{-3} \\ \end{pmatrix} = \begin{pmatrix} (1+2s)e^{-3} \\ \end{pmatrix} = \begin{pmatrix} (1+2s)e^{-3} \\ \end{pmatrix} = \begin{pmatrix} (1+2s)e^{-$$

$$f(3) = 1443 \qquad f(3) = 4 \qquad f(3) = 4 \qquad g(3) = \int \frac{e^{23}}{e^{-1}} ds = \frac{e^{23}}{4} \qquad g(3) = \int \frac{e^{23}}{e^{-1}} ds = \frac{e^{23}}{4} \qquad g(3) = \int \frac{e^{23}}{e^{-1}} ds = \frac{e^{23}}{4} \qquad g(3) = \frac{e^{23}}{e^{-1}} - \frac{e^{14}}{e^{-1}} + \int \frac{e^{23}}{e^{-1}} ds = \frac{e^{23}}{e^{-1}} + \int \frac{e^{23}}{e^{-1}}$$

$$e^{-ht} = (e^{ht})^{-1} = t^{-1} = \frac{1}{t}$$

$$=) \times (t) = \frac{1}{t} (2ht^{-2}) + ((1+2ht)^{-1} + 2ht^{-1} + (k_1)^{-1} + k_2 + k_3) + (k_1) + k_1 + k_2 + k_3$$

$$\begin{cases} X_1(t) = 2 \\ X_2(t) = 1 \end{cases} = X(1) = \begin{pmatrix} 1 \\ 1 \end{pmatrix}$$

$$X(t) = \frac{1}{t} \cdot \begin{pmatrix} -2 \\ 1 \end{pmatrix} + \begin{pmatrix} 1 \\ 0 \end{pmatrix} \cdot \begin{pmatrix} k_1 \\ k_2 \end{pmatrix} = \begin{pmatrix} -\frac{1}{t} + k_1 \\ \frac{1}{t} \end{pmatrix} + \begin{pmatrix} k_1 \\ k_2 \end{pmatrix} = \begin{pmatrix} -\frac{1}{t} + k_1 \\ \frac{1}{t} \end{pmatrix} = \begin{pmatrix} 2 \\ 1 \end{pmatrix}$$

$$X(t) = \frac{1}{t} \cdot \begin{pmatrix} 2ht^{-2} \\ 1 \end{pmatrix} + \begin{pmatrix} (h+2ht) \cdot \frac{1}{t} \\ -ht^{-1} \end{pmatrix} + \begin{pmatrix} \frac{5}{t} \\ \frac{3}{t} \end{pmatrix}$$

$$X(t) = \frac{1}{t} \cdot \begin{pmatrix} 2ht^{-2} \\ 1 \end{pmatrix} + \begin{pmatrix} (h+2ht) \cdot \frac{1}{t} \\ -ht^{-1} \end{pmatrix} + \begin{pmatrix} \frac{5}{t} \\ -ht^{-1} \end{pmatrix} = \begin{pmatrix} \frac{5}{t} \\ \frac{3}{t} \end{pmatrix}$$