

# Homework 4

PHYS209

Hikmat Gulaliyev

30.10.2023

**(1) Problem 1****(1.1)**

To solve  $\mathfrak{A}_a \cdot \mathfrak{L}_\Delta = \mathfrak{E}$  we can necessary substitutions and get:

$$\begin{aligned} \left( x \frac{d}{dx} - a \right) x^\Delta &= 0 \\ \frac{d}{dx} x^\Delta - a x^\Delta &= 0 \\ \Delta x x^{\Delta-1} &= a x^\Delta \end{aligned} \tag{1.1}$$

Giving us  $\Delta = a$

**(1.2)**

Considering definitions of  $\mathfrak{S}_a$ ,  $\mathfrak{S}_b$  and commutator operator, following can be achieved:

$$\begin{aligned} \left[ \mathfrak{S}_a, \mathfrak{S}_b \right] \cdot f &= \mathfrak{S}_a \cdot \left( \mathfrak{S}_b \cdot f \right) - \mathfrak{S}_b \cdot \left( \mathfrak{S}_a \cdot f \right) = \mathfrak{S}_a \cdot (f' - bf) - \mathfrak{S}_b \cdot (f' - af) = \\ &= (f' - bf)' - a(f' - bf) - (f' - af)' + b(f' - af) = \\ &= f'' - bf' - af + abf - f'' + af' + bf' - abf = x \rightarrow 0 \end{aligned} \tag{1.2}$$

Which proves and  $\left[ \mathfrak{S}_a, \mathfrak{S}_b \right] \cdot f = \mathfrak{E}$  therefore  $\mathfrak{S}_a$  and  $\mathfrak{S}_b$  commute.

**(1.3)**

To prove commutativity  $\mathfrak{A}_a$  and  $\mathfrak{A}_b$ , using their definitions:

$$\begin{aligned} \left[ \mathfrak{A}_a, \mathfrak{A}_b \right] \cdot f &= \mathfrak{A}_a(\mathfrak{A}_b \cdot f) - \mathfrak{A}_b(\mathfrak{A}_a \cdot f) = \mathfrak{A}_a \cdot \left( x \frac{d}{dx} - b \right) f - \mathfrak{A}_b \cdot \left( x \frac{d}{dx} - a \right) f = \\ &= x(xf' - bf)' - a(xf' - bf) - x(xf' - af)' + b(xf' - af) = \\ &= xf' + x^2 f'' - xbf' - axf' + abf - xf' - x^2 f'' + af'x + bxf' - abf' = x \rightarrow 0 \end{aligned} \tag{1.3}$$

Proving that  $[\mathfrak{A}_a, \mathfrak{A}_b] \cdot f = \mathfrak{A} \cdot f$  therefore  $\mathfrak{A}_a$  and  $\mathfrak{A}_b$  commute.

(1.4)

To check whether  $\mathfrak{A}_b$  and  $\mathfrak{A}_a$  commute, we can use their definitions:

$$\begin{aligned} \left[ \mathfrak{A}_a, \mathfrak{A}_b \right] \cdot f &= \mathfrak{A}_a \cdot (\mathfrak{A}_b \cdot f) - \mathfrak{A}_b \cdot \left( \mathfrak{A}_a \cdot f \right) = \mathfrak{A}_a \cdot (x f' - b f) - \mathfrak{A}_b \cdot (f' - a f) = \\ &= (x f' - b f)' - a(x f' - b f) - (f' - a f)' + b(f' - a f) = \\ &= f' + x f'' - b f' - a x f' + a b f - x f'' + a x f' + b f' - a b f = x \rightarrow f' \quad (1.4) \end{aligned}$$

Since commutator isn't equal to 0, these operators don't commute.

(1.5)

Since commutability of differential operator  $\mathfrak{A}$  is proved in previous sections, we can use it to solve given differential equation:

$$\mathfrak{A}_{a_1} \cdot \mathfrak{A}_{a_2} \cdot \dots \cdot \mathfrak{A}_{a_n} \cdot f = \mathfrak{A} \cdot f \quad (1.5)$$

We can find one solution as:

$$\begin{aligned} \left( x \frac{d}{dx} - a_1 \right) f &= 0 \\ x f' &= a_1 f \\ \frac{f'}{f} &= \frac{a_1}{x} \\ \ln(f) &= a_1 \ln(x) + C \\ f &= c_1 x^{a_1} \end{aligned} \quad (1.6)$$

Because of commutability, since we have  $n$  operators, we can find  $n$  solutions:

$$f = c_1 x^{a_1} + c_2 x^{a_2} + \dots + c_n x^{a_n} \quad (1.7)$$

**(2) Problem 2****(2.1)**

Given our differential equation:

$$\left( \frac{d^2}{dx^2} + \pi \tan(\pi x) \frac{d}{dx} + \pi^4 \cos(\pi x)^2 \right) f(x) = 0 \quad (2.8)$$

New substitution parameter  $u(x)$  can be defined as:

$$u(x) = \int \sqrt{q(x)} dx = \int \sqrt{\pi^4 \cos(\pi x)^2} dx = \int \pi^2 \cos(\pi x) dx = \pi |\sin(\pi x)| + C \quad (2.9)$$

However it doesn't matter if  $u(x) = \pi \sin(\pi x)$  or  $u(x) = -\pi \sin(\pi x)$  since  $\frac{q(x)}{u'(x)}$  can be chosen to be equal to -1 or 1.

For our differential equation to be rewritten as linear differential equation with constant coefficients, following condition must be satisfied:

$$\frac{q'(x) + 2p(x)q(x)}{2q(x)^{3/2}} = \text{const} \quad (2.10)$$

Substituting  $q(x)$  and  $p(x)$  with their values we get:

$$\frac{-2\pi^5 \cos(\pi x) \sin(\pi x) + 2\pi^5 \tan(\pi x) \cos(\pi x)^2}{2(\pi^2 \cos(\pi x))^3} = 0 \quad (2.11)$$

Since, condition 2.10 is satisfied.

**(2.2)**

To rewrite our differential equation as linear differential equation with constant coefficients, we need to find substitutions for  $\frac{d^2 f}{dx^2}$  and  $\frac{df}{dx}$ :

$$\frac{d^2 f}{dx^2} = u'' \frac{df}{du} + u' \frac{d^2 f}{du^2} \quad (2.12)$$

$$\frac{df}{dx} = u' \frac{df}{du} \quad (2.13)$$

**(2.3)**

Now using substitutions from previous section, we can rewrite our differential equation in terms of  $u$ :

$$\left( \frac{d^2}{du^2} + \frac{u'' + u'p(x)}{(u')^2} \frac{d}{du} + \frac{q(x)}{(u')^2} \right) f(x) = 0 \quad (2.14)$$

Where  $u''$  and  $u'$  are:

$$u' = \pi^2 \cos(\pi x) \quad (2.15)$$

$$u'' = -\pi^3 \sin(\pi x) \quad (2.16)$$

Making substitutions:

$$\left( \frac{d^2}{du^2} + \frac{-\pi^3 \sin(\pi x) + \pi^2 \cos(\pi x) \pi \tan(\pi x)}{\pi^4 \cos(\pi x)^2} \frac{d}{du} + \frac{\pi^4 \cos(\pi x)^2}{\pi^4 \cos(\pi x)^2} \right) f(x) = 0 \quad (2.17)$$

$$\left( \frac{d^2}{du^2} + 1 \right) f(x) = 0 \quad (2.18)$$

**(2.4)**

To solve this ordinary linear differential equation with constant coefficients, we need to find and solve its characteristic equation:

$$\begin{aligned} r^2 + 1 &= 0 \\ r_{1,2} &= \pm i \end{aligned} \quad (2.19)$$

Using roots of characteristic equation, we can find general solution of our differential equation:

$$f(u(x)) = c_1 e^{iu} + c_2 e^{-iu} = d_1 \cos(u) + d_2 \sin(u) \quad (2.20)$$

**(2.5)**

Writing our answer again in terms of  $x$ :

$$f(x) = d_1 \cos(\pi \sin(\pi x)) + d_2 \sin(\pi \sin(\pi x)) \quad (2.21)$$

**(2.6)**

Assuming given initial conditions  $f(x=0) = 12000212\sqrt{2}$  and  $f'(x=0) = 17101711\sqrt{2}\pi^2$  we can determine values of  $d_1$  and  $d_2$ :

$$\begin{aligned} f(x=0) &= d_1 = 12000212\sqrt{2} \\ f'(x=0) &= d_2\pi^2 = 17101711\sqrt{2}\pi^2 \end{aligned} \tag{2.22}$$

Giving us our final solution:

$$f(x) = 12000212\sqrt{2} \cos(\pi \sin(\pi x)) + 17101711\sqrt{2} \sin(\pi \sin(\pi x)) \tag{2.23}$$

Plugging in  $x = \frac{\arcsin(1/4)}{\pi}$  we get:

$$f\left(\frac{\arcsin(1/4)}{\pi}\right) = 29101923 \tag{2.24}$$