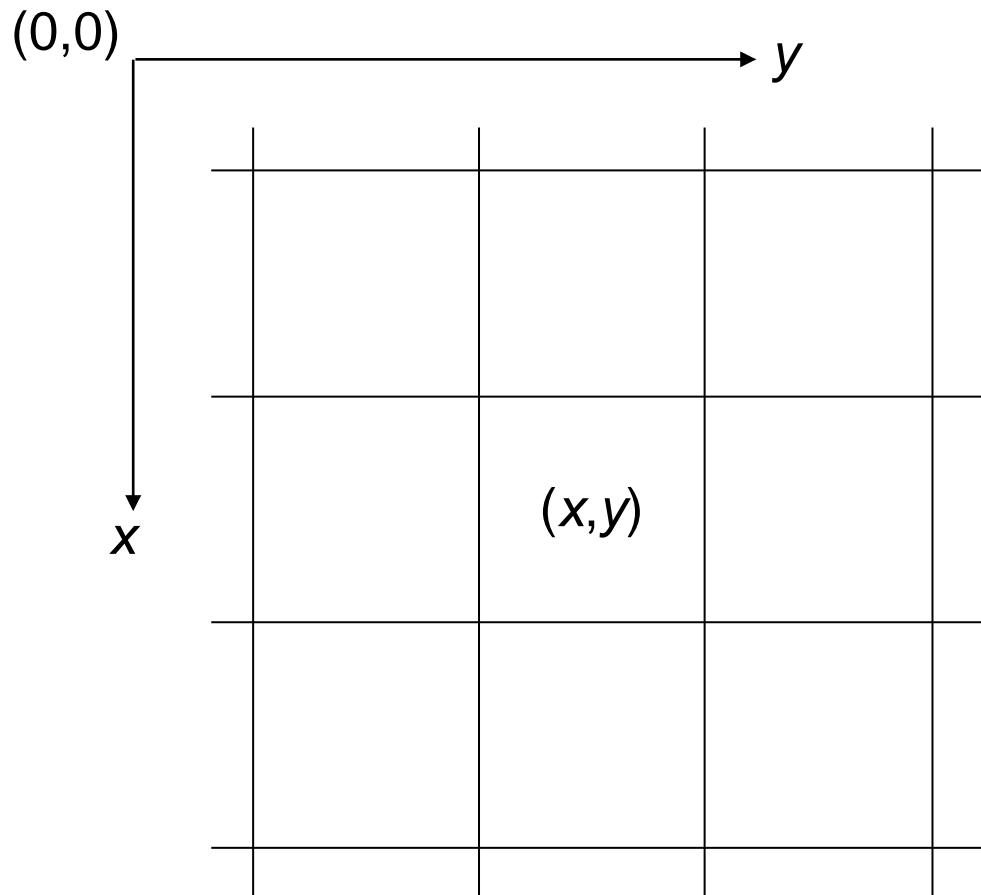


Objectives

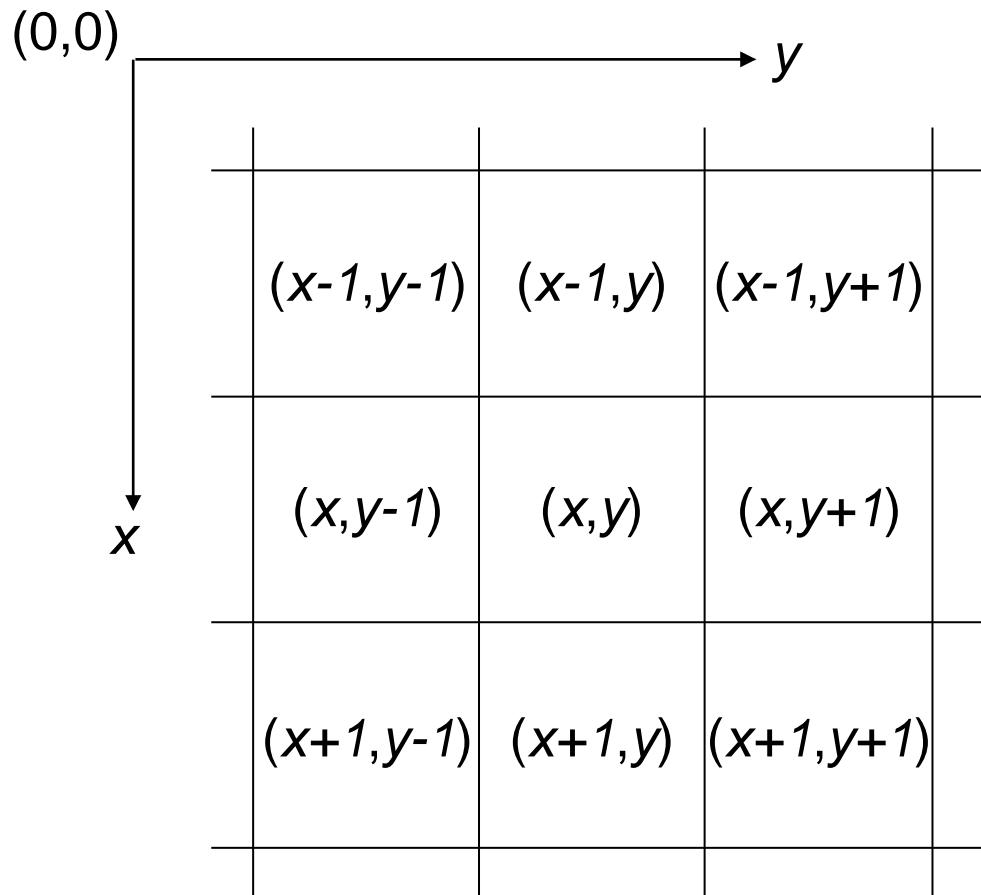
- We will learn the followings:
 - Pixel neighborhood
 - Adjacency
 - Connectivity
 - Distance measure

Basic Relationship of Pixels



Conventional indexing method

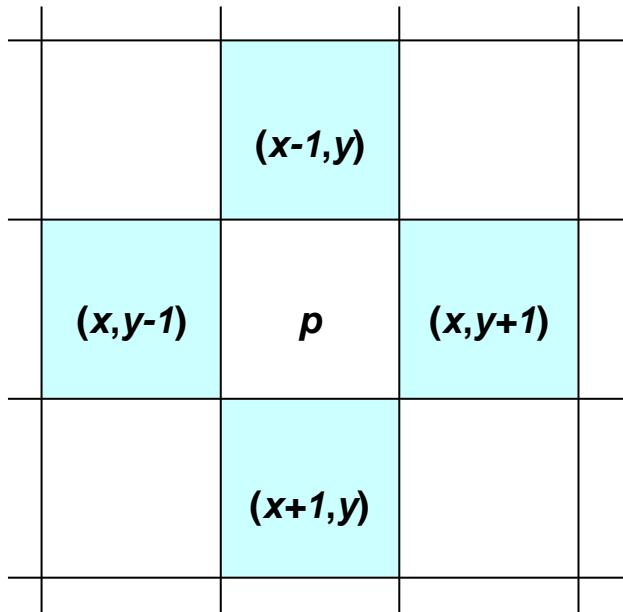
Basic Relationship of Pixels



Conventional indexing method

Neighbors of a Pixel

Neighborhood relation is used to find adjacent pixels. It is useful for analyzing regions.

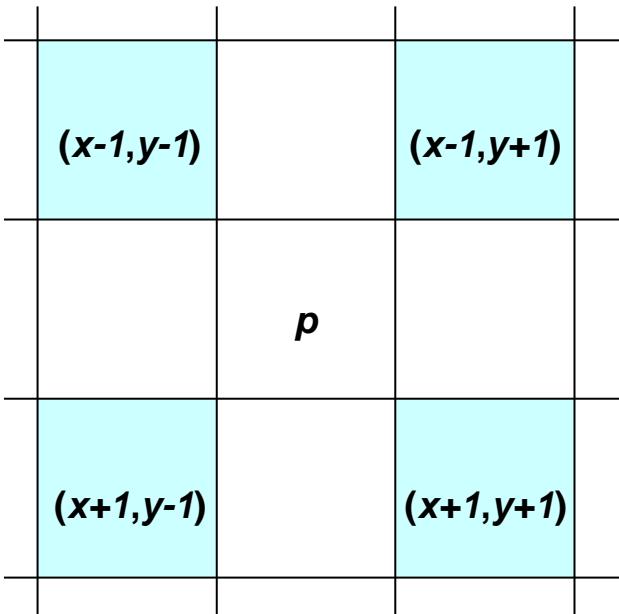


4-neighbors of p :

$$N_4(p) = \left\{ (x-1,y), (x+1,y), (x,y-1), (x,y+1) \right\}$$

4-neighborhood relation considers only vertical and horizontal neighbors.

Neighbors of a Pixel

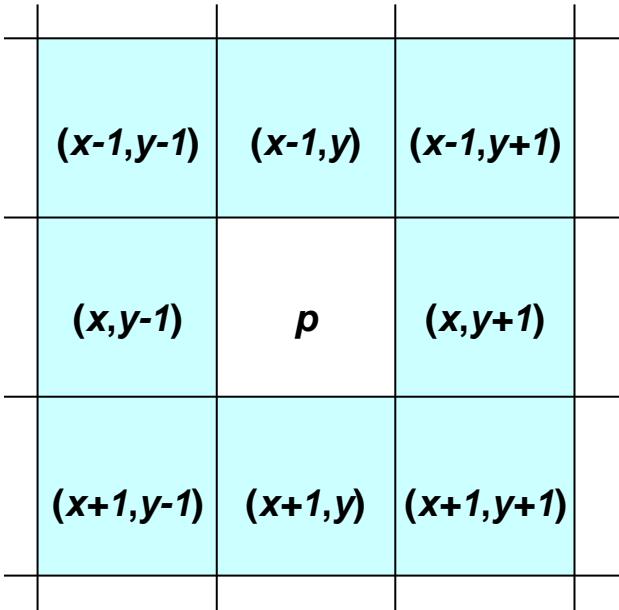


Diagonal neighbors of p :

$$N_D(p) = \left\{ (x-1,y-1), (x+1,y-1), (x-1,y+1), (x+1,y+1) \right\}$$

Diagonal -neighborhood relation considers only diagonal neighbor pixels.

Neighbors of a Pixel



8-neighbors of p :

$$N_8(p) = \left\{ (x-1,y-1), (x,y-1), (x+1,y-1), (x-1,y), (x+1,y), (x-1,y+1), (x,y+1), (x+1,y+1) \right\}$$

8-neighborhood relation considers all neighbor pixels.

Adjacency

Let V be the set of intensity values used to define adjacency

- **4-adjacency.** Two pixels p and q with values from V are 4-adjacent if q is in the set $N_4(p)$.
- **8-adjacency.** Two pixels p and q with values from V are 8-adjacent if q is in the set $N_8(p)$.
- **m-adjacency** (also called **mixed adjacency**). Two pixels p and q with values from V are m-adjacent if
 - a) q is in $N_4(p)$. or
 - b) q is in $N_D(p)$ and the set $N_4(p) \cap N_4(q)$. has no pixels whose values are from V

0	1	1	0	1	-1	0	1	-1
0	1	0	0	1	0	0	0	1
0	0	1	0	0	1	0	0	1

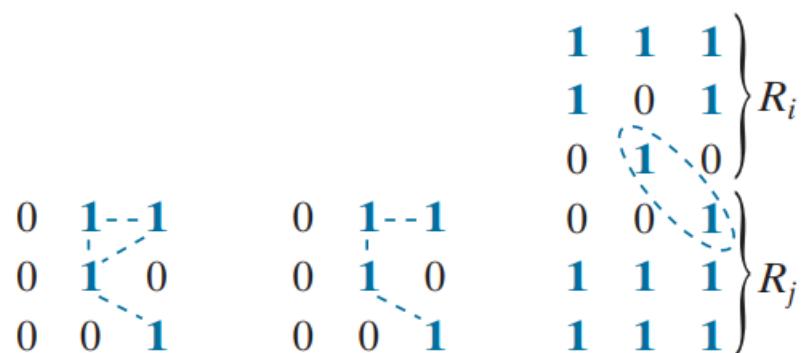
In a binary image, $V = \{1\}$ if we are referring to adjacency of pixels with value 1.

Path

A **digital path** (or curve) from pixel p with coordinates (x_0, y_0) to pixel q with coordinates (x_n, y_n) is a sequence of distinct pixels with coordinates

$$(x_0, y_0), (x_1, y_1), \dots, (x_n, y_n)$$

where points (x_0, y_0) and (x_{i-1}, y_{i-1}) are adjacent for $1 \leq i \leq n$. In this case, n is the length of the path. If $(x_0, y_0) = (x_n, y_n)$ the path is a **closed path**.



Connectivity

- Let S represent a subset of pixels in an image.
- Two pixels p and q are said to be connected in S if there exists a path between them consisting entirely of pixels in S .
- For any pixel p in S , the set of pixels that are connected to it in S is called a connected component of S .
- If it only has one component, and that component is connected, then S is called a connected set.

0	1	1	0	1	-	1	0	1	-	1
0	1	0	0	1	0	0	1	0	1	0
0	0	1	0	0	1	0	0	1	0	1

Region

- Let R represent a subset of pixels in an image.
- We call R a region of the image if R is a connected set.
- Two regions, R_i and R_j are said to be adjacent if their union forms a connected set.
- Regions that are not adjacent are said to be disjoint.
- We consider 4- and 8-adjacency when referring to regions.
- The type of adjacency used must be specified.

$\begin{matrix} 1 & 1 & 1 \\ 1 & 0 & 1 \\ 0 & 1 & 0 \end{matrix}$	$\left. \begin{matrix} 1 & 1 & 1 \\ 1 & 0 & 1 \\ 0 & 1 & 0 \end{matrix} \right\} R_i$	$\begin{matrix} 0 & 0 & 0 & 0 & 0 \\ 0 & 1 & 1 & 0 & 0 \\ 0 & 1 & 1 & 0 & 0 \\ 0 & 1 & 1 & 1 & 0 \\ 0 & 1 & 1 & 1 & 0 \end{matrix}$	$\begin{matrix} 0 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 1 & 0 \\ 0 & 1 & 0 \\ 0 & 1 & 0 \end{matrix}$
$\begin{matrix} 1 & 1 & 1 \\ 1 & 0 & 1 \\ 0 & 1 & 0 \end{matrix}$	$\left. \begin{matrix} 1 & 1 & 1 \\ 1 & 0 & 1 \\ 0 & 1 & 0 \end{matrix} \right\} R_j$	$\begin{matrix} 0 & 0 & 0 & 0 & 0 \\ 0 & 1 & 1 & 1 & 0 \\ 0 & 1 & 1 & 1 & 0 \\ 0 & 1 & 1 & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{matrix}$	$\begin{matrix} 0 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 1 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{matrix}$

Boundary

- The **boundary** of a region R is the set of pixels in R that are **adjacent** to pixels in the complement of R .
or
- The border of a region is the set of pixels in the region that have at least **one background neighbor**.
- we must specify the connectivity being used to define adjacency

$\begin{matrix} 1 & 1 & 1 \\ 1 & 0 & 1 \\ 0 & 1 & 0 \end{matrix}$	$\left. \begin{matrix} 1 & 1 & 1 \\ 1 & 0 & 1 \\ 0 & 1 & 0 \end{matrix} \right\} R_i$	$\begin{matrix} 0 & 0 & 0 & 0 & 0 \\ 0 & 1 & 1 & 0 & 0 \\ 0 & 1 & 1 & 0 & 0 \\ 0 & 1 & 1 & 1 & 0 \\ 0 & 1 & 1 & 1 & 0 \end{matrix}$	$\begin{matrix} 0 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 1 & 0 \\ 0 & 1 & 0 \\ 0 & 1 & 0 \end{matrix}$
$\begin{matrix} 1 & 1 & 1 \\ 1 & 0 & 1 \\ 1 & 1 & 1 \end{matrix}$	$\left. \begin{matrix} 1 & 1 & 1 \\ 1 & 0 & 1 \\ 1 & 1 & 1 \end{matrix} \right\} R_j$	$\begin{matrix} 0 & 0 & 0 & 0 & 0 \\ 0 & 1 & 1 & 1 & 0 \\ 0 & 1 & 1 & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{matrix}$	$\begin{matrix} 0 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{matrix}$

Distance

For pixel p , q , and z with coordinates (x,y) , (s,t) and (u,v) ,
 D is a ***distance function*** or ***metric*** if

- ◆ $D(p,q) \geq 0$ ($D(p,q) = 0$ if and only if $p = q$)
- ◆ $D(p,q) = D(q,p)$
- ◆ $D(p,z) \leq D(p,q) + D(q,z)$

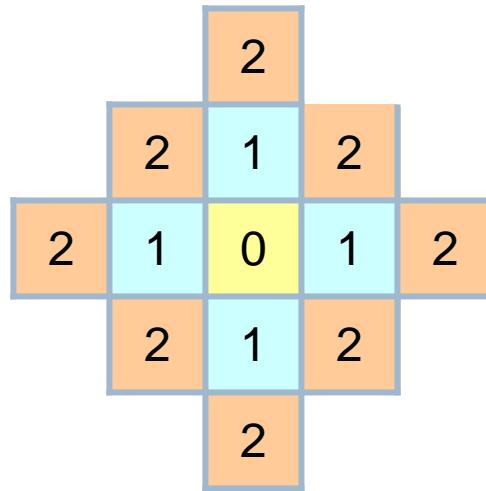
Example: Euclidean distance

$$D_e(p,q) = \sqrt{(x - s)^2 + (y - t)^2}$$

Distance

D_4 -distance (city-block distance) is defined as

$$D_4(p, q) = |x - s| + |y - t|$$



Pixels with $D_4(p) = 1$ is 4-neighbors of p .

Distance

D_8 -distance (*chessboard distance*) is defined as

$$D_8(p, q) = \max(|x - s|, |y - t|)$$

2	2	2	2	2
2	1	1	1	2
2	1	0	1	2
2	1	1	1	2
2	2	2	2	2

Pixels with $D_8(p) = 1$ are 8-neighbors of p .