

# Digital Signal Processing

## EE3900: Linear Systems and Signal Processing

Indian Institute of Technology Hyderabad

### Fourier Series

Lokesh Badisa  
AI21BTECH11001

12 Oct 2022

#### CONTENTS

<b>1</b>	<b>Periodic Function</b>	<b>1</b>
<b>2</b>	<b>Fourier Series</b>	<b>1</b>
<i>Abstract—This manual provides a simple introduction to Fourier Series</i>		

#### 1. PERIODIC FUNCTION

Let

$$x(t) = A_0 |\sin(2\pi f_0 t)| \quad (1.1)$$

##### 1.1 Plot $x(t)$ .

**Solution:**

```
wget https://raw.githubusercontent.com/
LokeshBadisa/EE3900-Linear-Systems-
and-Signal-Processing/main/charger/
codes/1.1.py
python3 1.1.py
```

##### 1.2 Show that $x(t)$ is periodic and find its period.

**Solution:** If a signal  $x(t)$  is periodic then

$$x(t + T) = x(t) \quad (1.2)$$

where  $T$  is known as fundamental period. Since  $|\sin\theta|$  function is periodic,  $x(t)$  is also periodic.

$$\text{Fundamental Period} = T = \frac{1}{2} \left( \frac{2\pi}{2\pi f_0} \right) \quad (1.3)$$

$$= \frac{1}{2f_0} \quad (1.4)$$

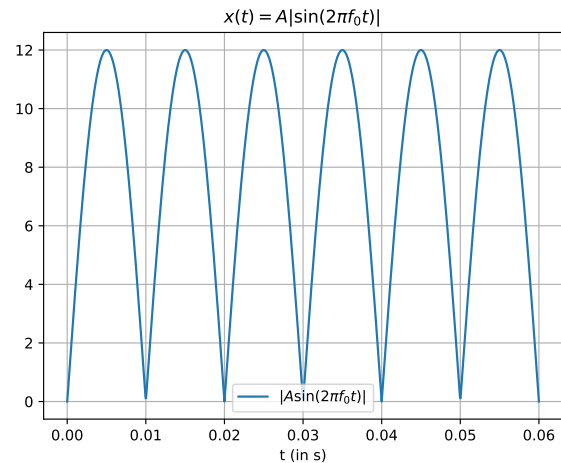


Fig. 1.1.

#### 2. FOURIER SERIES

Consider  $A_0 = 12$  and  $f_0 = 50$  for all numerical calculations.

##### 2.1 If

$$x(t) = \sum_{k=-\infty}^{\infty} c_k e^{j2\pi k f_0 t} \quad (2.1)$$

show that

$$c_k = f_0 \int_{-\frac{1}{2f_0}}^{\frac{1}{2f_0}} x(t) e^{-j2\pi k f_0 t} dt \quad (2.2)$$

**Solution:** From (2.1),

$$x(t) = \sum_{k=-\infty}^{\infty} c_k e^{j2\pi k f_0 t} \quad (2.3)$$

Multiply  $e^{-j2\pi l f_0 t}$  on both sides

$$x(t)e^{-j2\pi l f_0 t} = \sum_{k=-\infty}^{\infty} c_k e^{j2\pi k f_0 t} e^{-j2\pi l f_0 t} \quad (2.4)$$

Integrate on both sides with respect to 't' between  $-T$  to  $T$  where  $T$  is fundamental time period of  $x(t)$ .

Using (1.4),

$$T = \frac{1}{2f_0} \quad (2.5)$$

$$\int_{-\frac{1}{2f_0}}^{\frac{1}{2f_0}} x(t)e^{-j2\pi k f_0 t} dt = \int_{-\frac{1}{2f_0}}^{\frac{1}{2f_0}} \sum_{k=-\infty}^{\infty} c_k e^{j2\pi(k-l)f_0 t} dt \quad (2.6)$$

$$= \sum_{k=-\infty}^{\infty} c_k \int_{-\frac{1}{2f_0}}^{\frac{1}{2f_0}} e^{j2\pi(k-l)f_0 t} dt \quad (2.7)$$

The above integral:

$$\int_{-\frac{1}{2f_0}}^{\frac{1}{2f_0}} e^{j2\pi(k-l)f_0 t} dt = \begin{cases} 0 & k \neq l \\ \int_{-\frac{1}{2f_0}}^{\frac{1}{2f_0}} 1 dt & k = l \end{cases} \quad (2.8)$$

$$\therefore \int_{-\frac{1}{2f_0}}^{\frac{1}{2f_0}} x(t)e^{-j2\pi k f_0 t} dt = \left(\frac{1}{f_0}\right) c_k \quad (2.9)$$

$$\therefore c_k = f_0 \int_{-\frac{1}{2f_0}}^{\frac{1}{2f_0}} x(t)e^{-j2\pi k f_0 t} dt \quad (2.10)$$

2.2 Find  $c_k$  for (1.1)

**Solution:**  $c_k$  can be calculated even simpler by using

$$c_k = 2f_0 \int_0^{\frac{1}{2f_0}} x(t)e^{-j2\pi k f_0 t} dt \quad (2.11)$$

$x(t) = A_0 \sin(2\pi f_0 t)$  in 0 to  $\frac{1}{2f_0}$  region.  
Also,

$$\sin \theta = \frac{e^{j\theta} - e^{-j\theta}}{2j} \quad (2.12)$$

Using (2.12),

$$c_k = 2f_0 \int_0^{\frac{1}{2f_0}} A_0 \left( \frac{e^{j2\pi f_0 t} - e^{-j2\pi f_0 t}}{2j} \right) e^{-j2\pi k f_0 t} dt \quad (2.13)$$

$$= A_0 f_0 \int_0^{\frac{1}{2f_0}} \left( \frac{e^{j2\pi(1-k)f_0 t} - e^{j2\pi(-1-k)f_0 t}}{j} \right) dt \quad (2.14)$$

$$= A_0 f_0 \left[ \frac{e^{j2\pi(1-k)f_0 t}}{-2\pi(1-k)f_0} \Big|_0^{\frac{1}{2f_0}} - \frac{e^{j2\pi(-1-k)f_0 t}}{-2\pi(-1-k)f_0} \Big|_0^{\frac{1}{2f_0}} \right] \quad (2.15)$$

$$= A_0 \left[ \frac{e^{j\pi(1-k)} - 1}{2\pi(k-1)} - \frac{e^{-j\pi(1+k)} - 1}{2\pi(k+1)} \right] \quad (2.16)$$

$$= \begin{cases} \frac{2A_0}{\pi(1-k^2)} & k = \text{even} \\ 0 & k = \text{odd} \end{cases} \quad (2.17)$$

2.3 Verify (1.1) using python.

**Solution:**

```
wget https://raw.githubusercontent.com/
LokeshBadisa/EE3900-Linear-Systems-
and-Signal-Processing/main/charger/
codes/2.3.py
python3 2.3.py
```

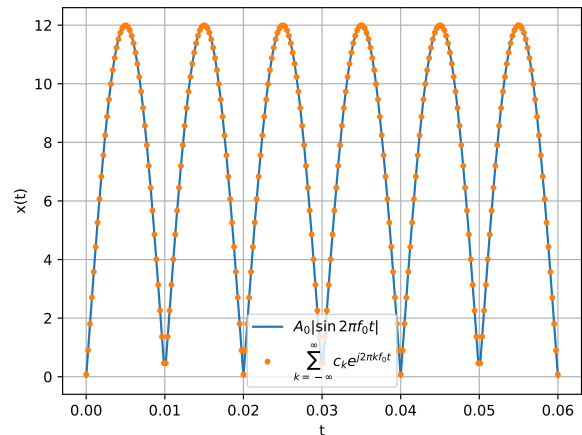


Fig. 2.3.

2.4 Show that

$$x(t) = \sum_{k=0}^{\infty} (a_k \cos 2\pi k f_0 t + b_k \sin 2\pi k f_0 t) \quad (2.18)$$

and obtain the formulae for  $a_k$  and  $b_k$ .

**Solution:** Using (2.1),

$$x(t) = \sum_{k=-\infty}^{\infty} c_k e^{j2\pi k f_0 t} \quad (2.19)$$

As,

$$e^{j2\pi k f_0 t} = \cos(2\pi k f_0 t) + j \sin(2\pi k f_0 t) \quad (2.20)$$

Substituting leads to

$$x(t) = \sum_{k=-\infty}^{\infty} c_k [\cos(2\pi k f_0 t) + j \sin(2\pi k f_0 t)] \quad (2.21)$$

$$= \sum_{k=-\infty}^{\infty} c_k \cos(2\pi k f_0 t) + j c_k \sin(2\pi k f_0 t) \quad (2.22)$$

$$= \sum_{k=-\infty}^{-1} [c_k \cos(2\pi k f_0 t) + j c_k \sin(2\pi k f_0 t)] + c_0 + \sum_{k=1}^{\infty} [c_k \cos(2\pi k f_0 t) + j c_k \sin(2\pi k f_0 t)] \quad (2.23)$$

$$= \sum_{k=1}^{\infty} [c_{-k} \cos(2\pi k f_0 t) - j c_{-k} \sin(2\pi k f_0 t)] + c_0 + \sum_{k=1}^{\infty} [c_k \cos(2\pi k f_0 t) + j c_k \sin(2\pi k f_0 t)] \quad (2.24)$$

$$= c_0 + \sum_{k=1}^{\infty} [(c_k + c_{-k}) \cos(2\pi k f_0 t) + j(c_k - c_{-k}) \sin(2\pi k f_0 t)] \quad (2.25)$$

Replacing  $(c_k + c_{-k}) \rightarrow a_k$  and  $j(c_k - c_{-k}) \rightarrow b_k$ ,

$$= c_0 + \sum_{k=1}^{\infty} (a_k \cos 2\pi k f_0 t + b_k \sin 2\pi k f_0 t) \quad (2.26)$$

$$= \sum_{k=0}^{\infty} (a_k \cos 2\pi k f_0 t + b_k \sin 2\pi k f_0 t) \quad (2.27)$$

$$\therefore a_k = \begin{cases} c_k + c_{-k} & k \neq 0 \\ c_0 & k = 0 \end{cases} \quad (2.28)$$

$$b_k = j(c_k - c_{-k}) \quad (2.29)$$

Using (2.2),

$$c_k = f_0 \int_{-\frac{1}{2f_0}}^{\frac{1}{2f_0}} x(t) e^{-j2\pi k f_0 t} dt \quad (2.30)$$

$$c_{-k} = f_0 \int_{-\frac{1}{2f_0}}^{\frac{1}{2f_0}} x(t) e^{j2\pi k f_0 t} dt \quad (2.31)$$

$$a_k = c_k + c_{-k} = f_0 \int_{-\frac{1}{2f_0}}^{\frac{1}{2f_0}} x(t) [e^{-j2\pi k f_0 t} + e^{j2\pi k f_0 t}] dt \quad (2.32)$$

$$= 2f_0 \int_{-\frac{1}{2f_0}}^{\frac{1}{2f_0}} x(t) \cos(2\pi k f_0 t) dt \quad (2.33)$$

Parallely,

$$b_k = -2jf_0 \int_{-\frac{1}{2f_0}}^{\frac{1}{2f_0}} x(t) \sin(2\pi k f_0 t) dt \quad (2.34)$$

2.5 Find  $a_k$  and  $b_k$  for (1.1)

**Solution:** Using (2.28) and (2.29) with (2.17),

$$a_k = c_k + c_{-k} = \begin{cases} \frac{4A_0}{\pi(1-k^2)} & k = \text{even} \\ \frac{2A_0}{\pi} & k = 0 \\ 0 & k = \text{odd} \end{cases} \quad (2.35)$$

$$b_k = j(c_k - c_{-k}) = 0 \quad (2.36)$$

2.6 Verify (2.18) using python.

**Solution:**

get <https://raw.githubusercontent.com/LokeshBadisa/EE3900-Linear-Systems-and-Signal-Processing/main/charger/python3/2.6.py>

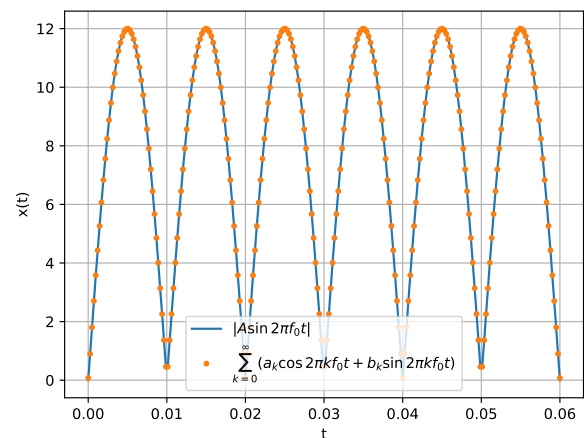


Fig. 2.6.